

# Systems and Networking – Unit I

B.Sc. in Applied Computer Science and Artificial Intelligence  
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- All modern operating systems provide features enabling a process to contain **multiple threads** of control
- We introduce many concepts associated with multi-threaded computer systems
- We look at a number of issues related to multi-threaded programming and its effect on the design of operating systems

# Threads: Overview

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- Traditional (heavyweight) processes have a single thread of control
  - There is only one program counter, and one sequence of instructions that can be carried out at any given time
- Multi-threaded applications have multiple threads within a single process, each having their own program counter, stack, and set of registers
  - But sharing common code, data, and certain structures, such as open files



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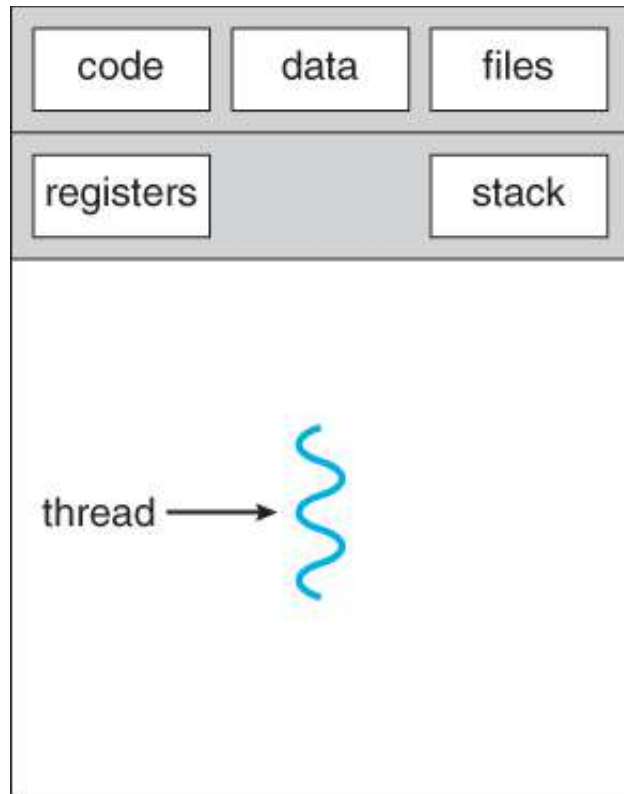
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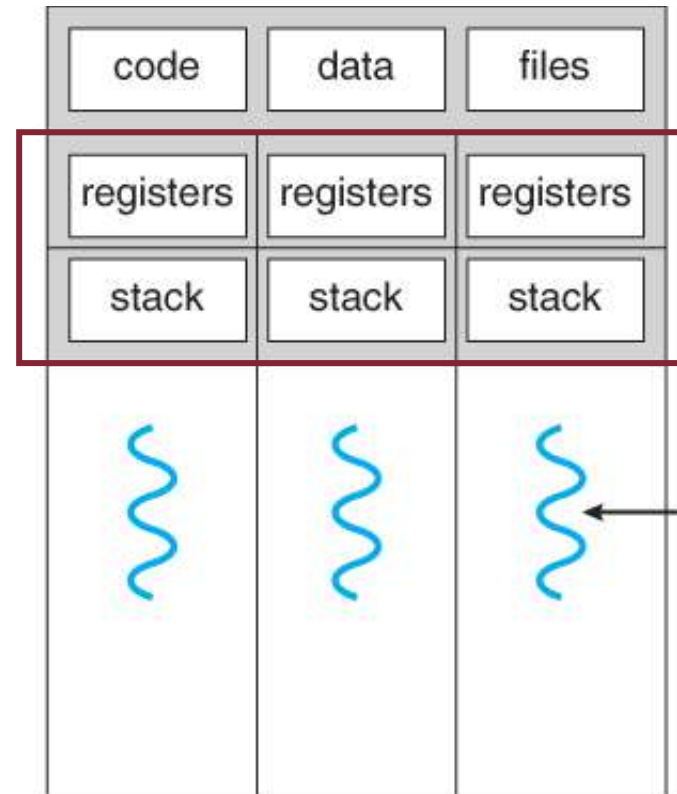
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- A thread is bound to a specific process
- Each process may have several threads of control within it
  - The process' address space is shared among all its threads
  - No system calls are required for threads to cooperate with each other
  - Simpler than message passing and shared memory

# Single- vs. Multi-Threaded Process



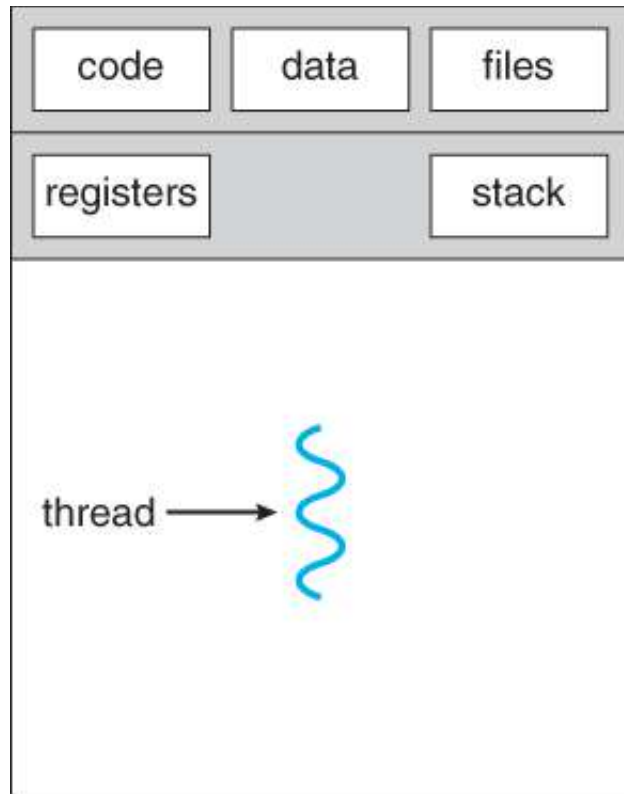
single-threaded process



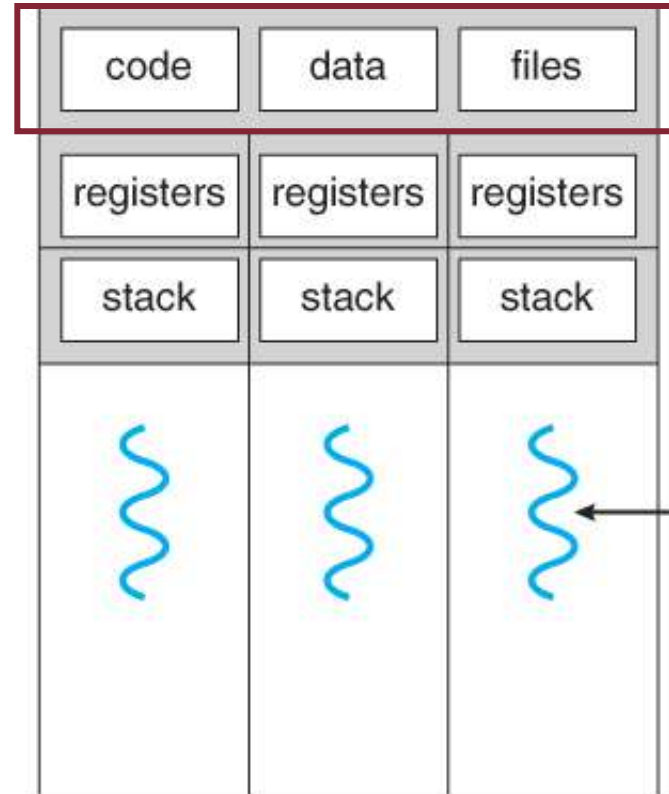
multithreaded process

Each thread has its own independent set of registers and "state"

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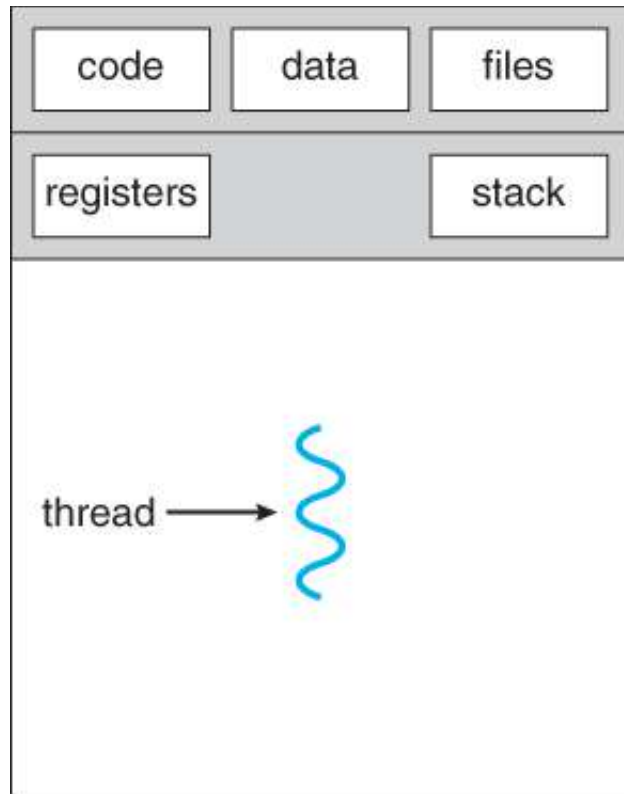
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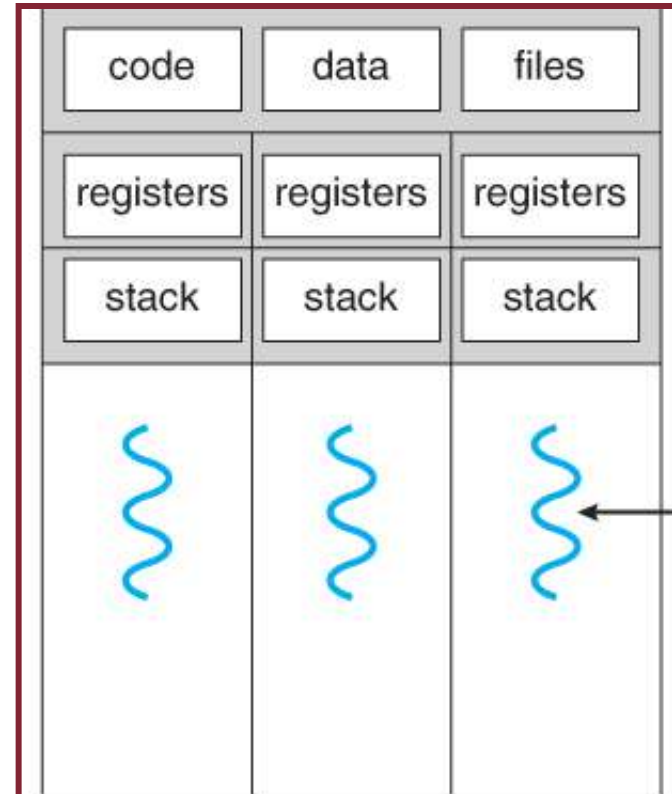
multithreaded process

All the threads of a process share the same code and "global" resources

# Single- vs. Multi-Threaded Process



single-threaded process



multithreaded process

Since all the threads live in the same address space, communication between them is easier than communication between processes

# Threads: Motivation

- Threads are very useful in modern programming whenever a process has multiple tasks to perform independently of the others



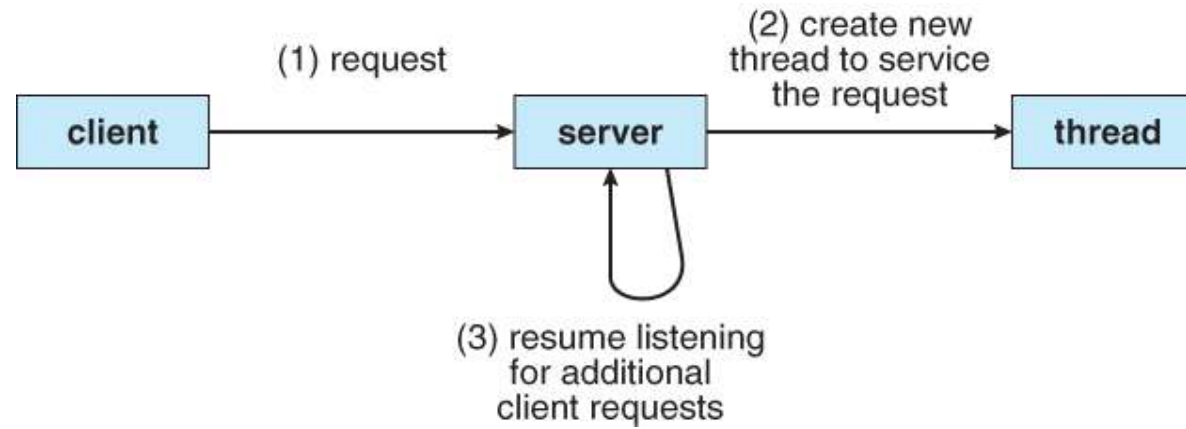
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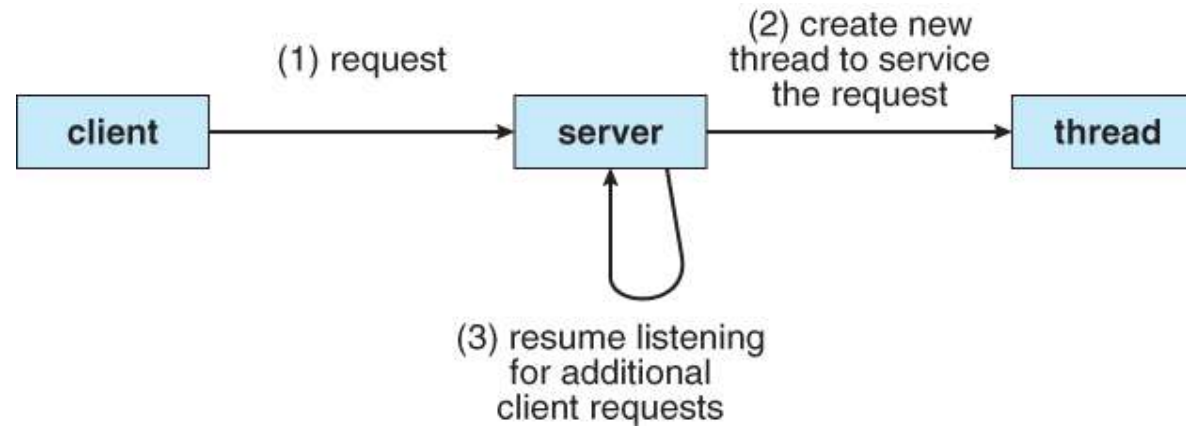
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- **Example: word processor**
  - a thread may check spelling and grammar while another thread handles user input (keystrokes), and a third does periodic backups of the file being edited

# Multi-threaded Web Server

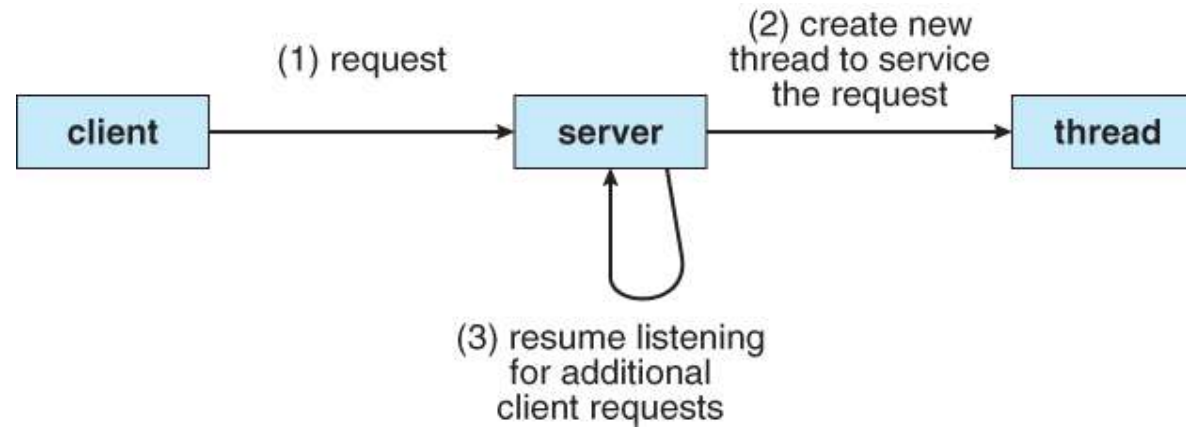


# Multi-threaded Web Server



Multiple threads allow for multiple requests to be satisfied simultaneously, without having to serve requests sequentially or to fork off separate processes for every incoming request

# Multi-threaded Web Server



What if the server process spawns off a new process for each incoming request rather than a thread?

# Multiple Processes vs. Multiple Threads

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- There are at least **2 reasons** why this is not the best choice:
  - Inter-thread communication is significantly quicker than inter-process one
  - Context-switches between threads is a lot faster than between processes

# Threads: Benefits

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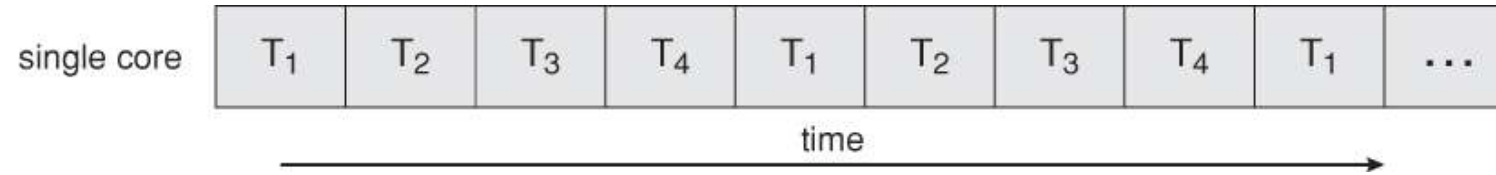
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  - **Economy** → creating and managing threads (and context switches between them) is much faster than performing the same tasks for processes
  - **Scalability** (multi-processor architectures) → A single threaded process can only run on one CPU, whereas a multi-threaded process may be split amongst all available processors/cores

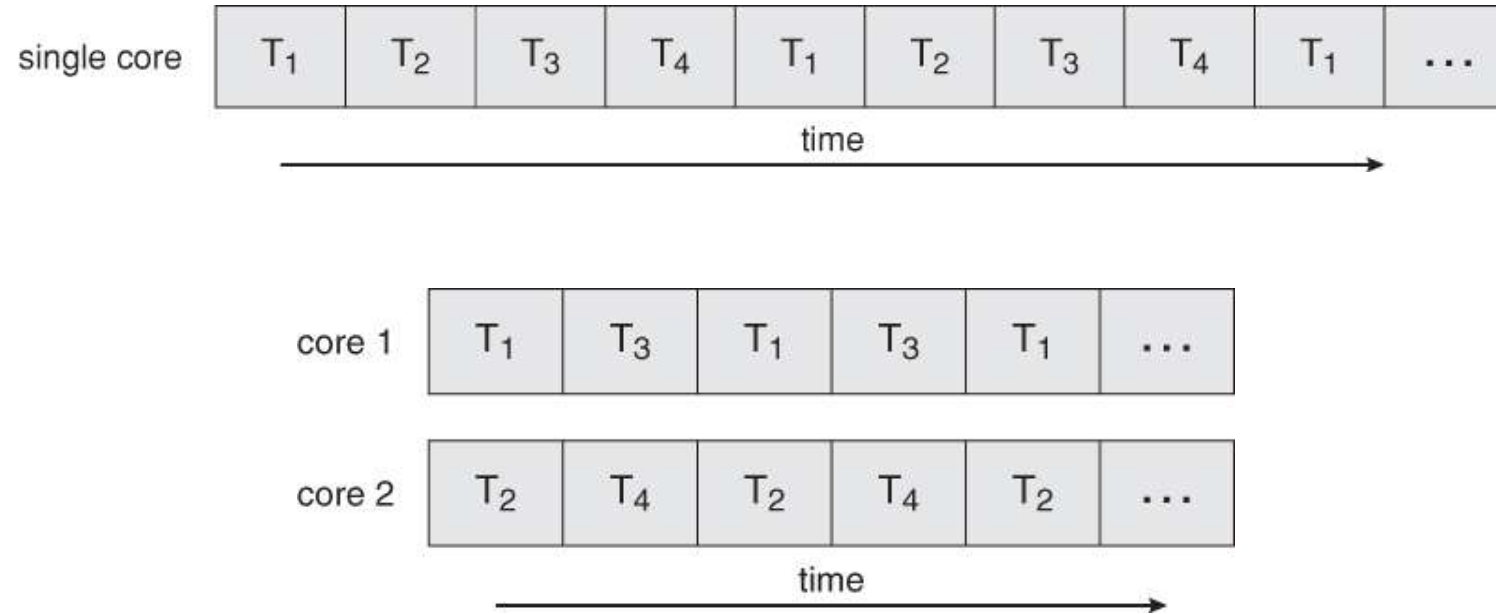
# Multi-core Programming

- A recent trend in computer architecture is to produce chips with multiple cores, or CPUs on a single chip
- A multi-threaded application running on a traditional single-core chip would have to interleave the threads
- On a multi-core chip, however, threads could be spread across the available cores, allowing **true parallel processing!**

# Single- vs. Multi-core Programming

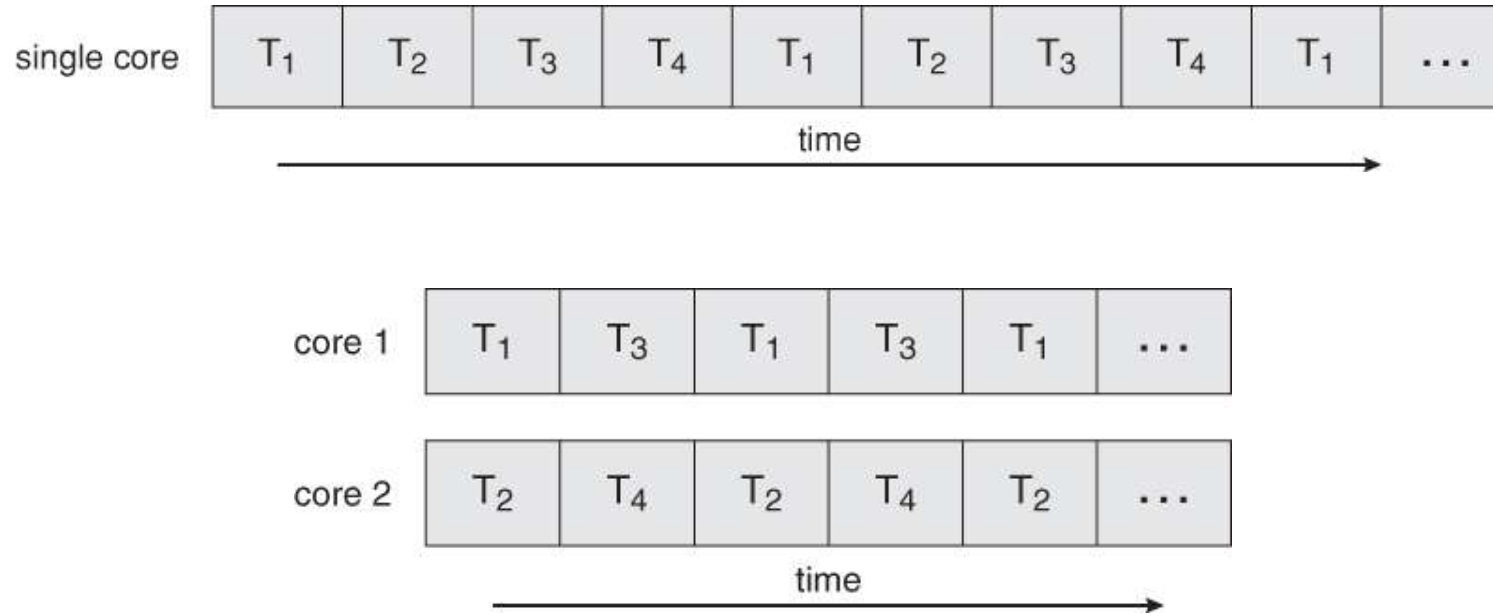


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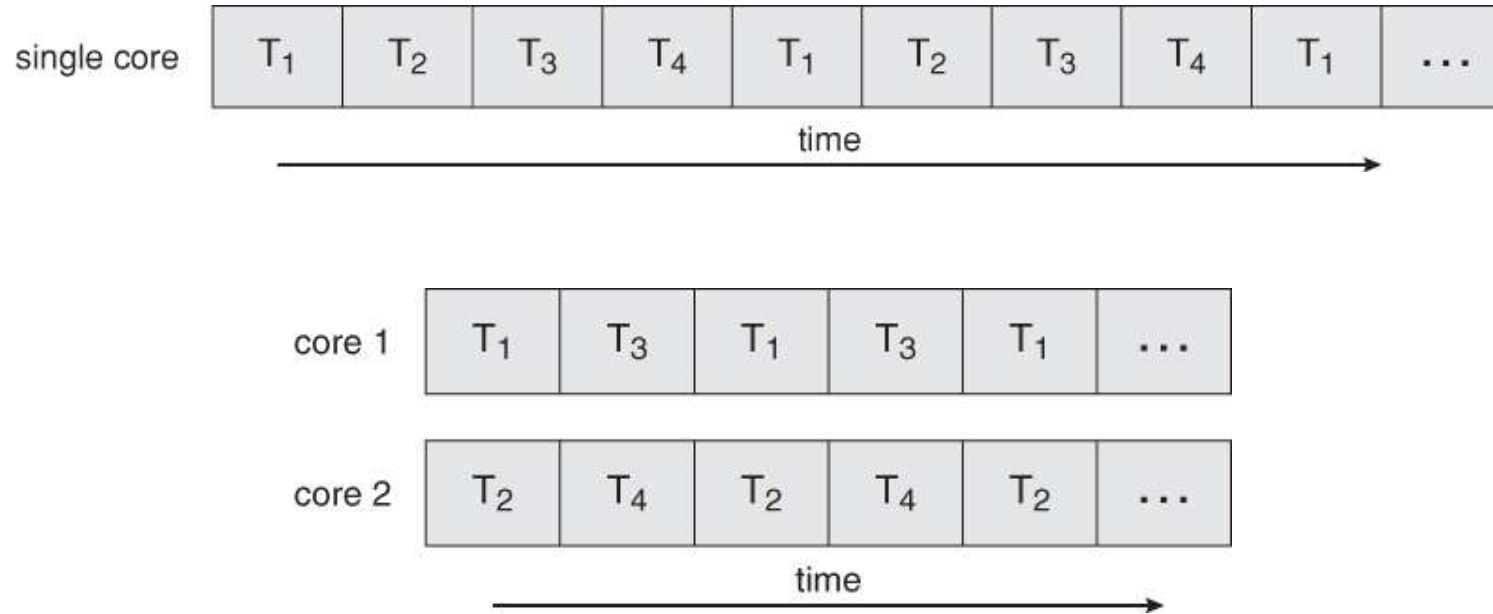


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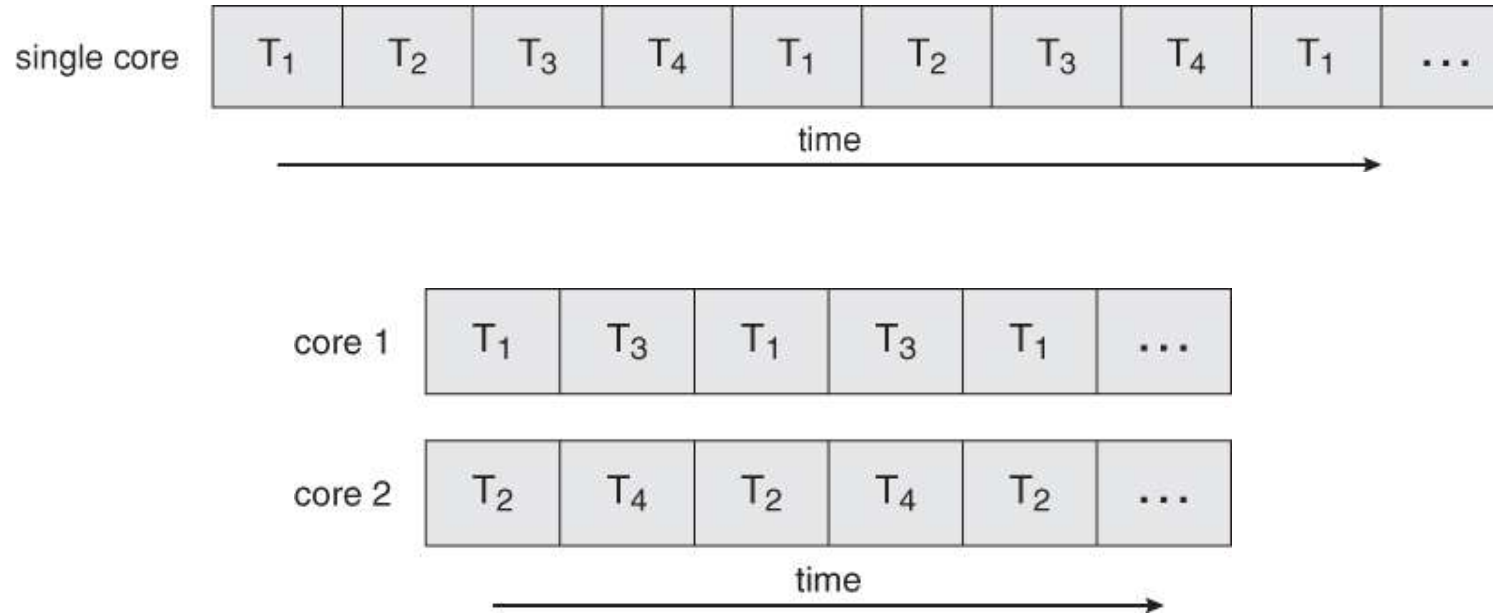
Multi-core chips require new OS scheduling algorithms to make better use of the multiple cores available

# Single- vs. Multi-core Programming



CPU's have been developed to support more simultaneous threads per core in hardware (e.g., Intel's **hyper-threading**)

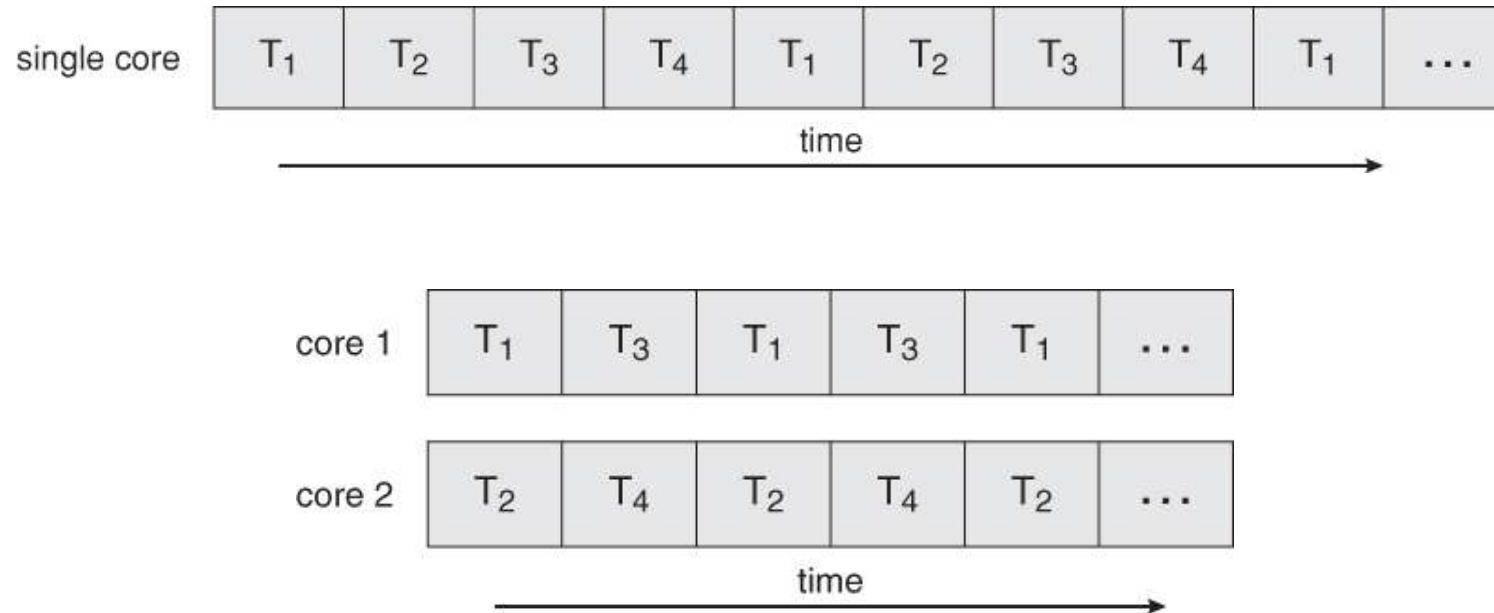
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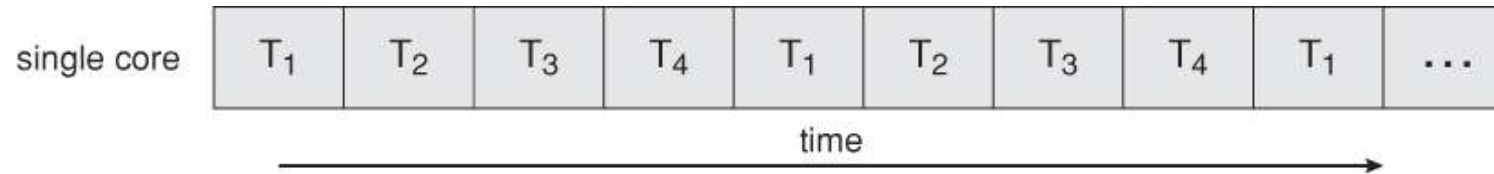
## Hyper-threading

Each physical core appears as **two** processors to the OS, allowing **concurrent** scheduling of **two processes per core**

# Single- vs. Multi-core Programming

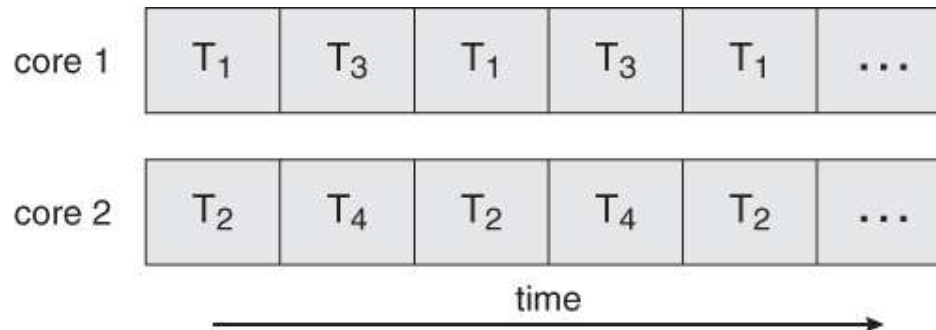


# Single- vs. Multi-core Programming



Concurrency

VS.



Parallelism

# Types of Parallelism

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  - **Data parallelism:** divides the data up amongst multiple cores (threads), and performs the same task on each chunk of the data
  - **Task parallelism:** divides the different tasks to be performed among the different cores and performs them simultaneously
- In practice, no program is ever divided up solely by one or the other of these, but instead by some sort of hybrid combination

# Classifying OSs



address space



thread

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address space



thread

single thread

---

multiple threads

# Classifying OSs



address space



thread

single address space  
(uniprogramming)

multiple address spaces  
(multiprogramming)

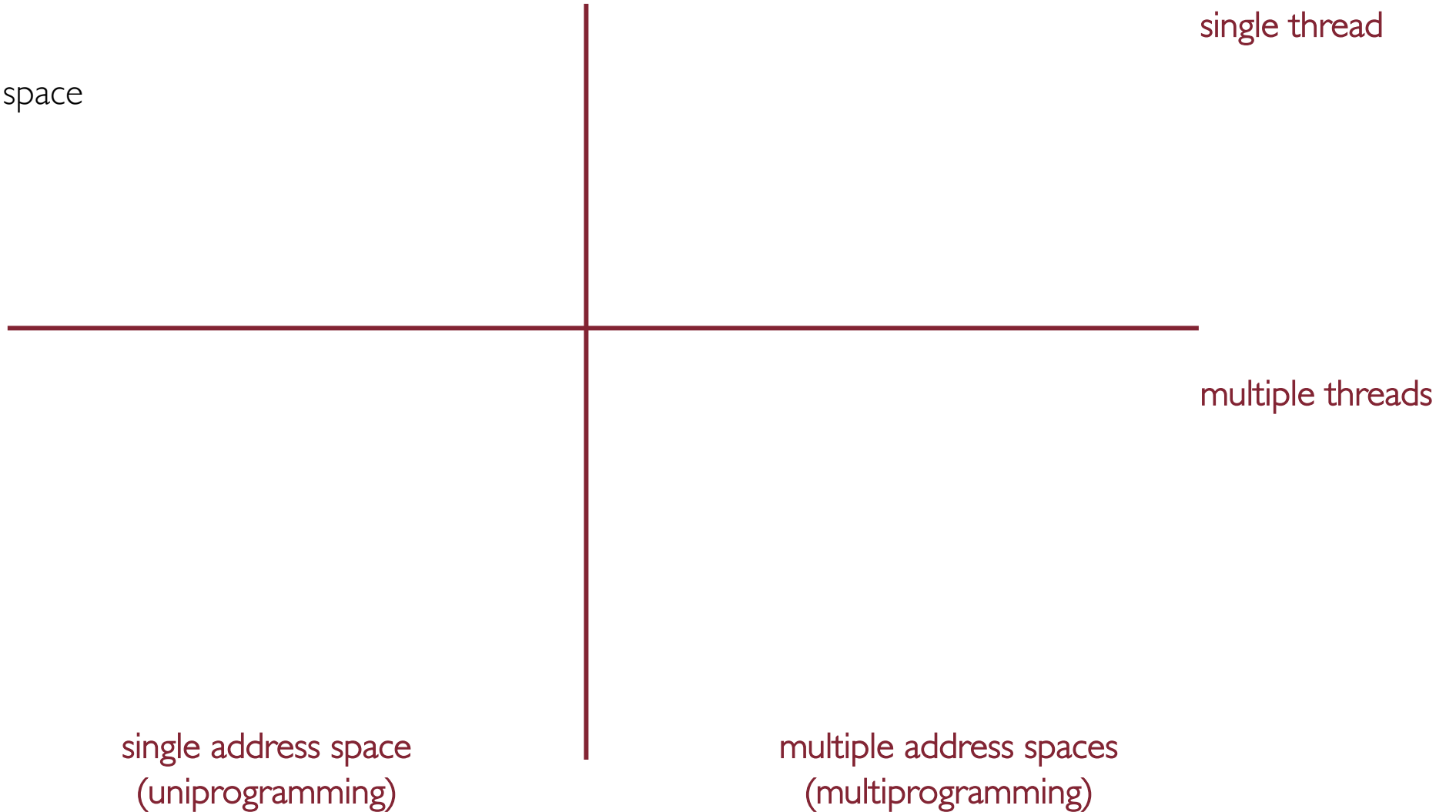
# Classifying OSs



address space



thread



# Classifying OSs



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thread



MS-DOS

single thread

single address space  
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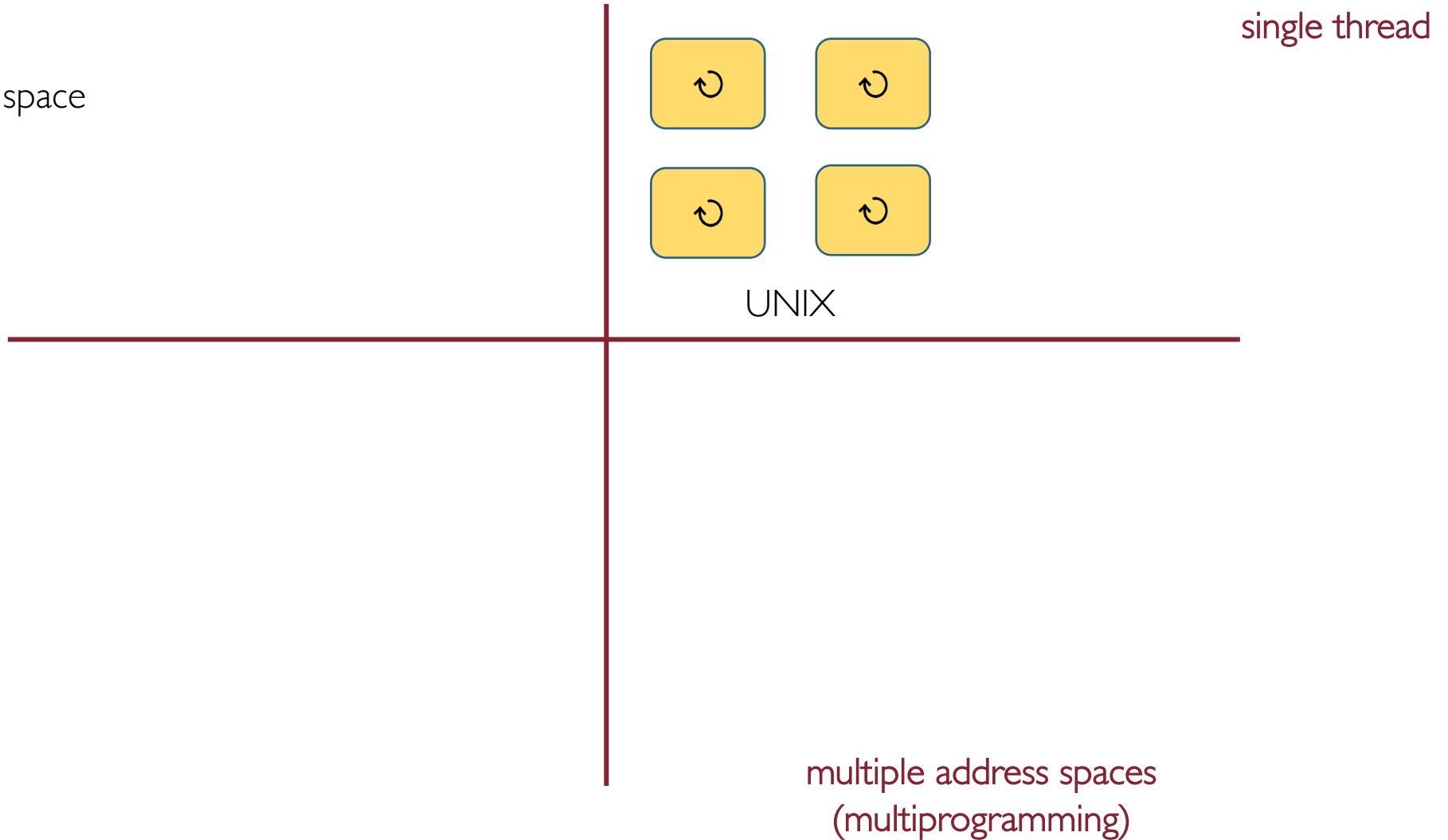
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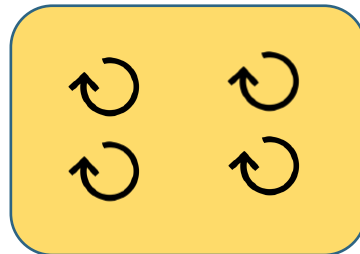
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thread



Xerox Pilot

single address space  
(uniprogramming)

multiple threads



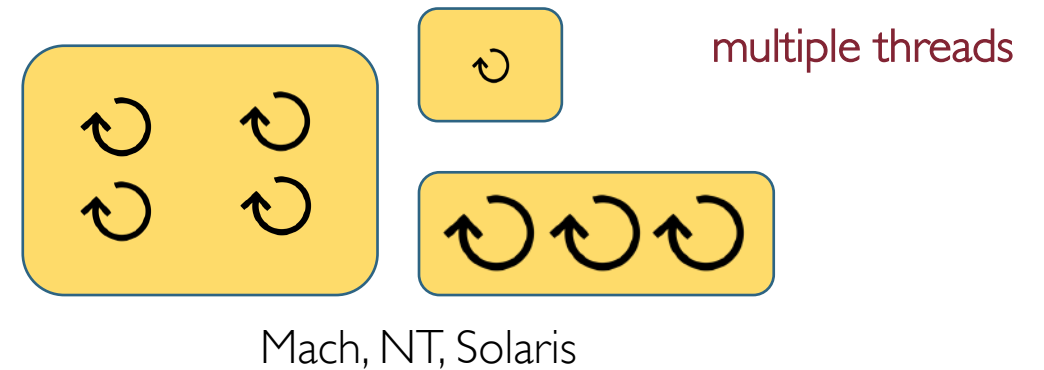
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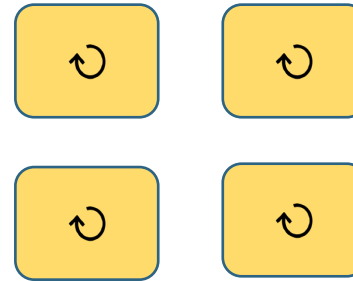
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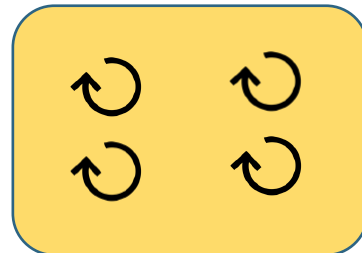


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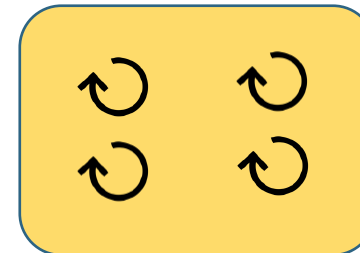


UNIX

single thread



Xerox Pilot



Mach, NT, Solaris

multiple threads

single address space  
(uniprogramming)

multiple address spaces  
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# Multi-threading: Support and Management

- Support for (multiple) threads can be provided in 2 ways:
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- User threads
  - managed in user space by a user-level thread library, without OS intervention

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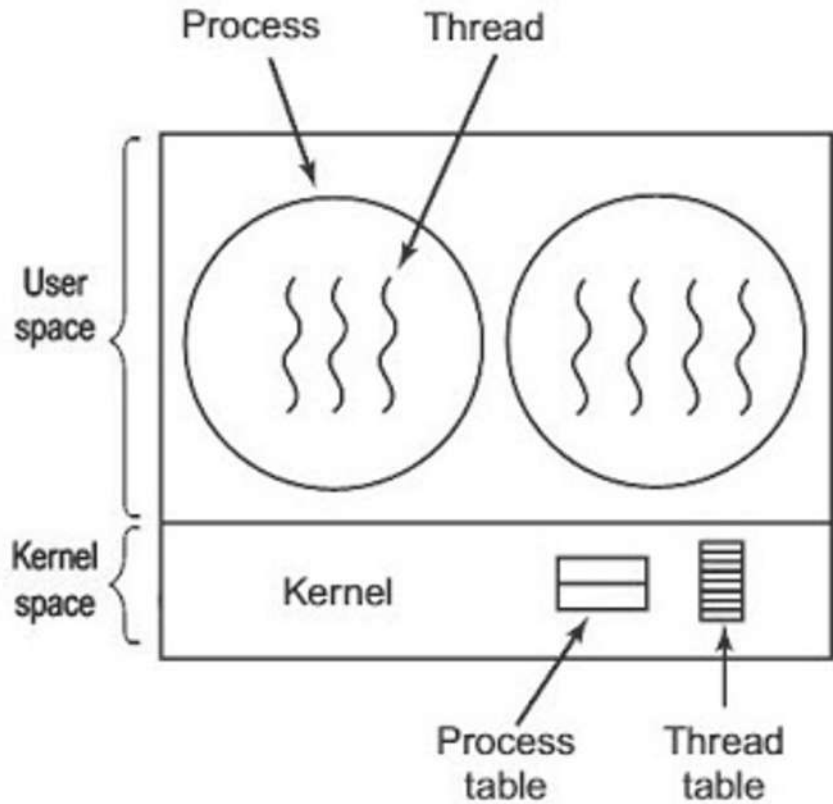
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- The smallest unit of execution that can be scheduled by the OS
- The OS is responsible for supporting and managing all threads
- One Process Control Block (PCB) for each process, one Thread Control Block (TCB) for each thread
- The OS usually provides system calls to create and manage threads from user space

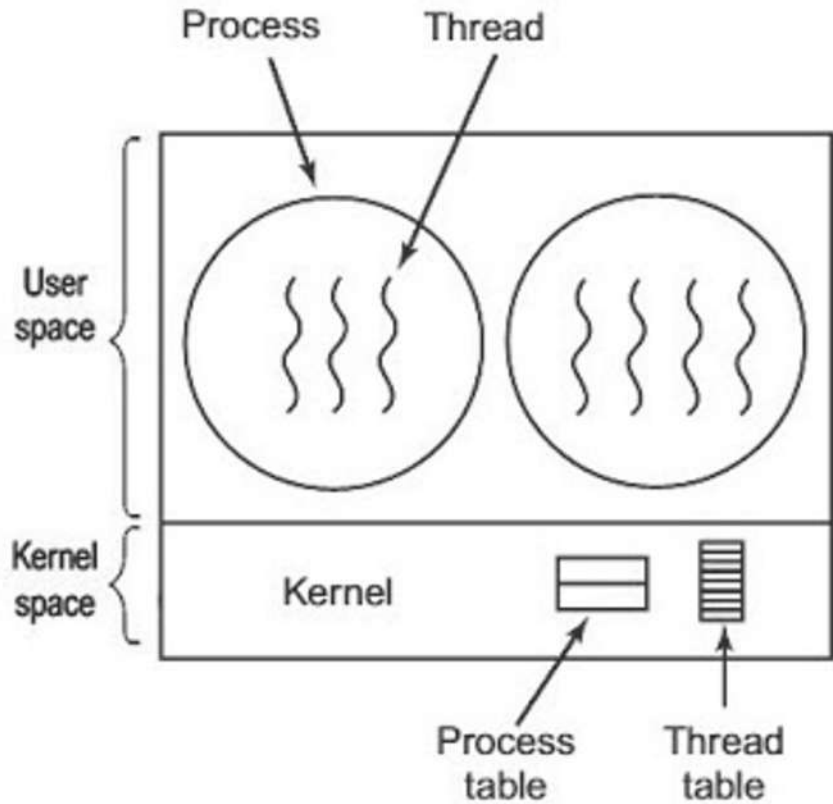
# Kernel Threads: PROs



- PROs

- The kernel has full knowledge of all threads
- Scheduler may decide to give more CPU time to a process having a large number of threads
- Good for applications that frequently block
- Switching between threads is faster than switching between processes

# Kernel Threads: CONs



- CONs

- Significant overhead and increase in kernel complexity
- Slow and inefficient (need kernel invocations)
- Context switching, although lighter, is managed by the kernel

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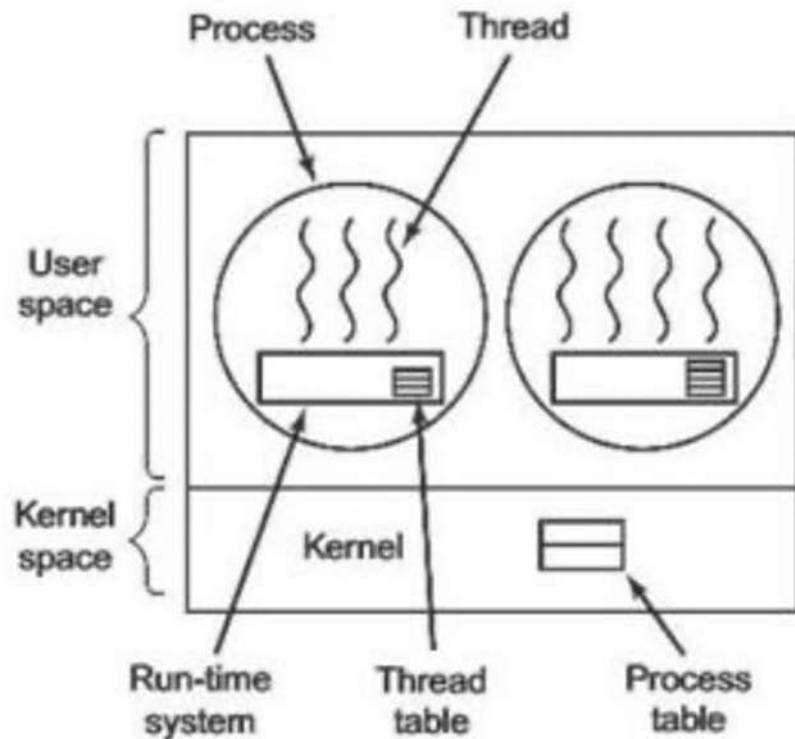
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- Ideally, thread operations should be as fast as a function call

# User Threads: PROs

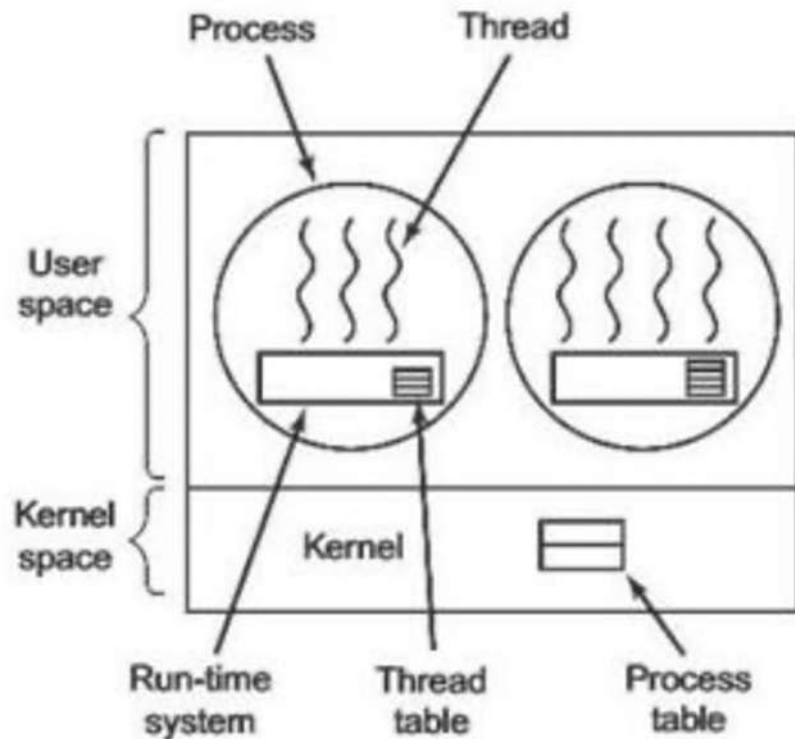


- PROs

- Really fast and lightweight
- Scheduling policies are more flexible
- Can be implemented in OSs that do not support threading
- No system calls involved, just user-space function calls
- No actual context switch



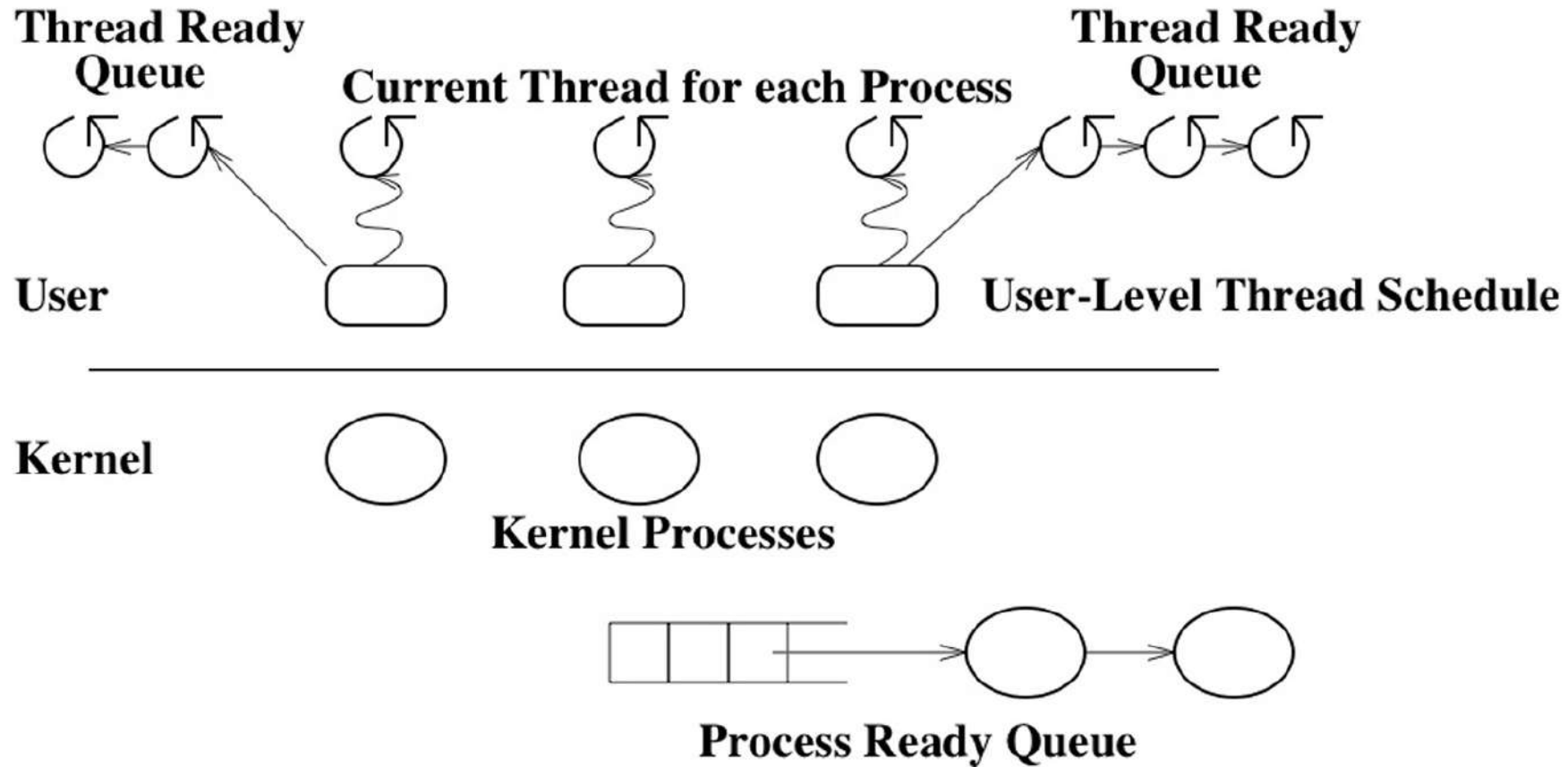
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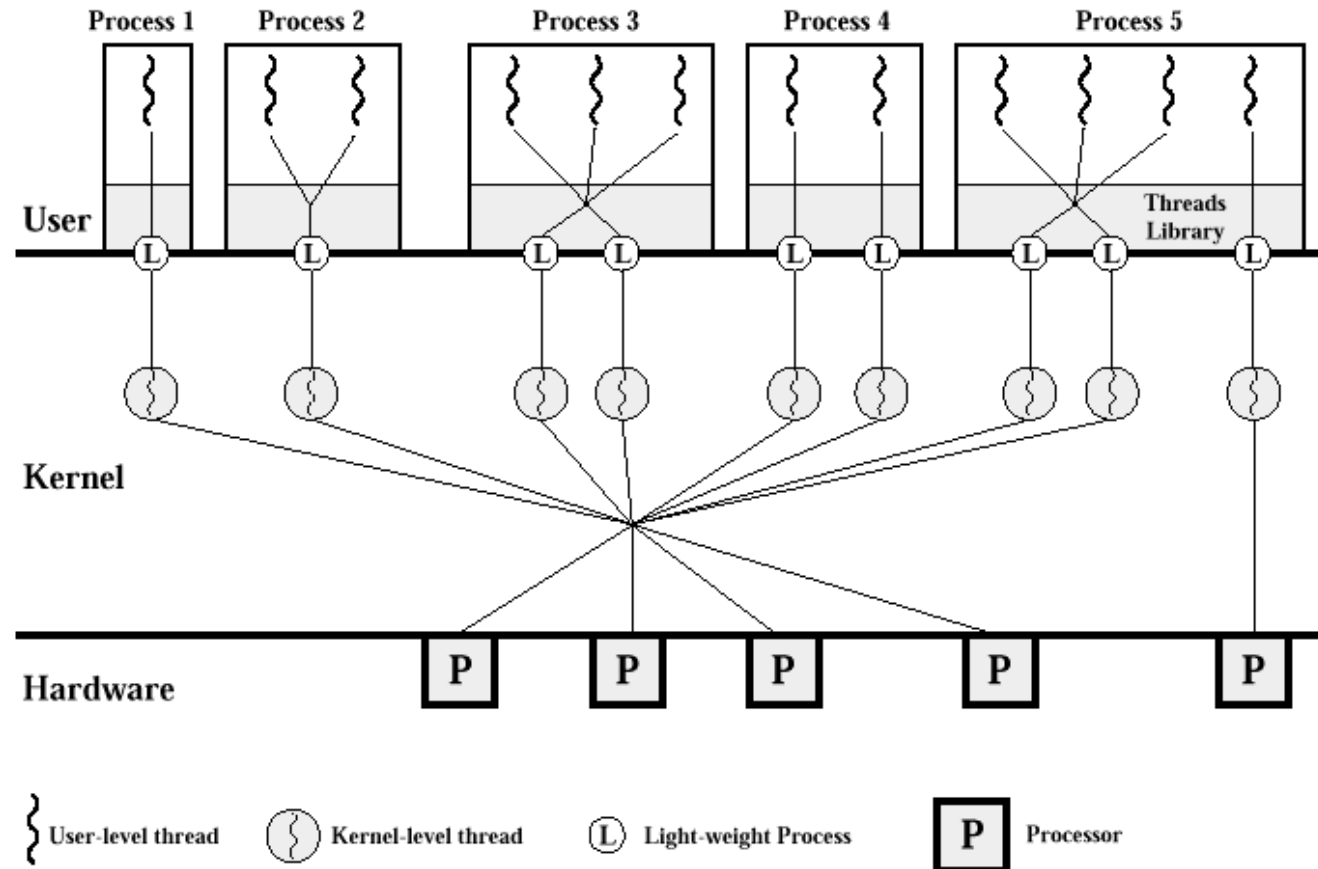
- CONs

- No true concurrency of multi-threaded processes
- Poor scheduling decisions
- Lack of coordination between kernel and threads
  - A process with 100 threads competes for a time slice with a process with just 1 thread
- Requires non-blocking system calls, otherwise all threads within a process have to wait

# User Threads



# Hybrid Management: Lightweight Processes



# Multi-threading Models

- In a specific implementation, user threads must be mapped to kernel threads in one of the following ways:
  - Many-to-One
  - One-to-One
  - Many-to-Many
  - Two-level

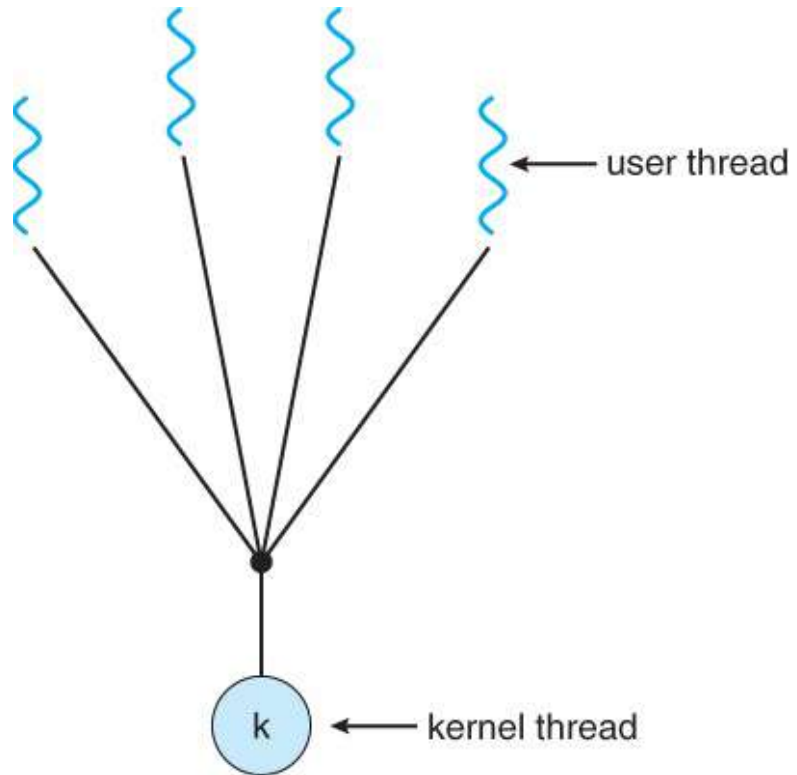
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## Remember:

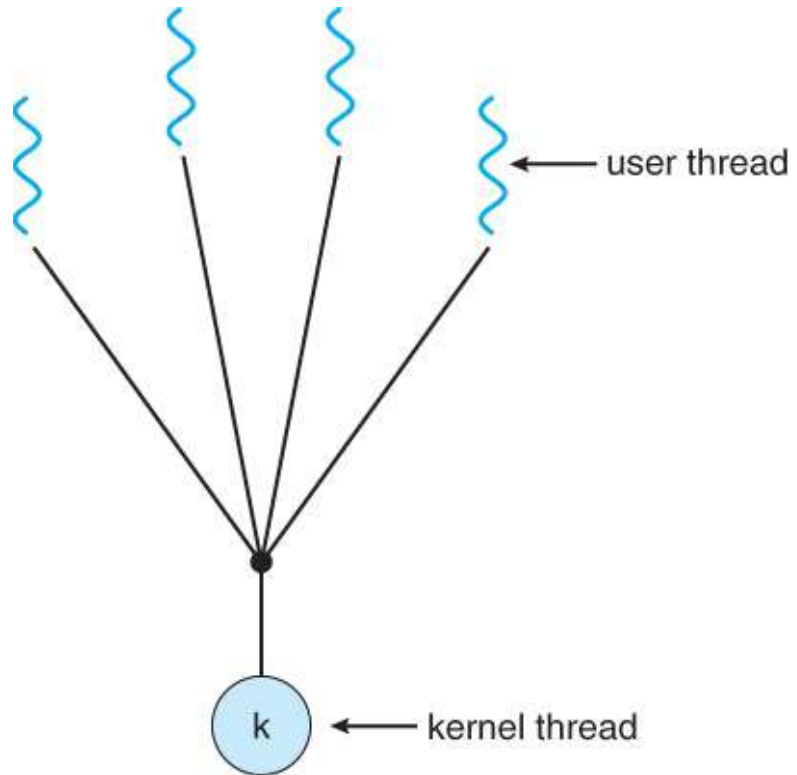
A kernel thread is the unit of execution that is scheduled by the OS to run on the CPU (similar to single-threaded process)

# Many-to-One Model



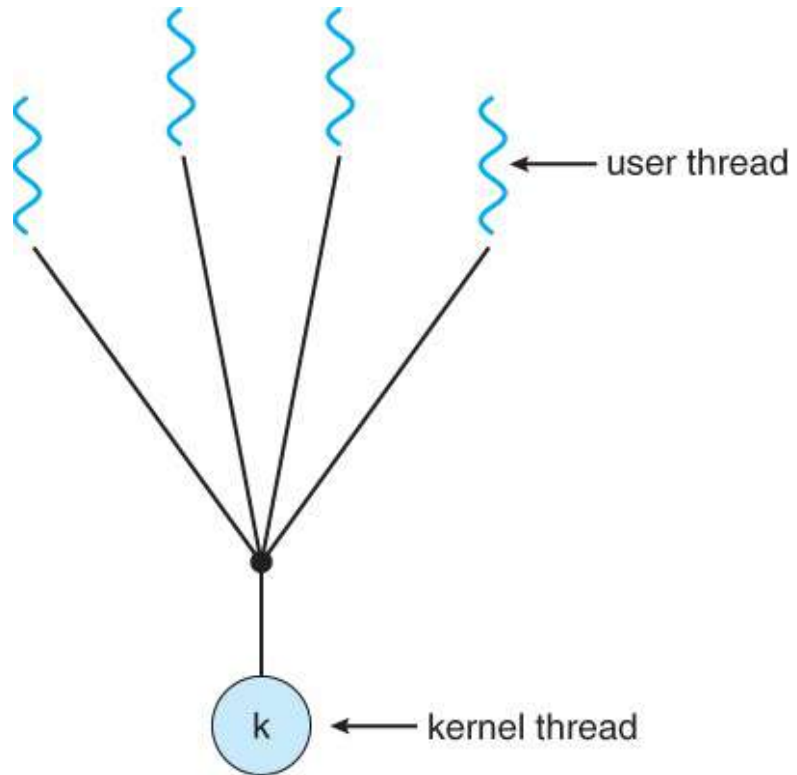
- Many user threads are all mapped onto a single kernel thread
- The process can only run one user thread at a time because there is only one kernel thread associated with it
- As single kernel thread can operate on a single CPU, multi-user-thread processes cannot be split across multiple CPUs
- If a blocking system call is made, the entire process blocks, even if other user threads would be able to continue

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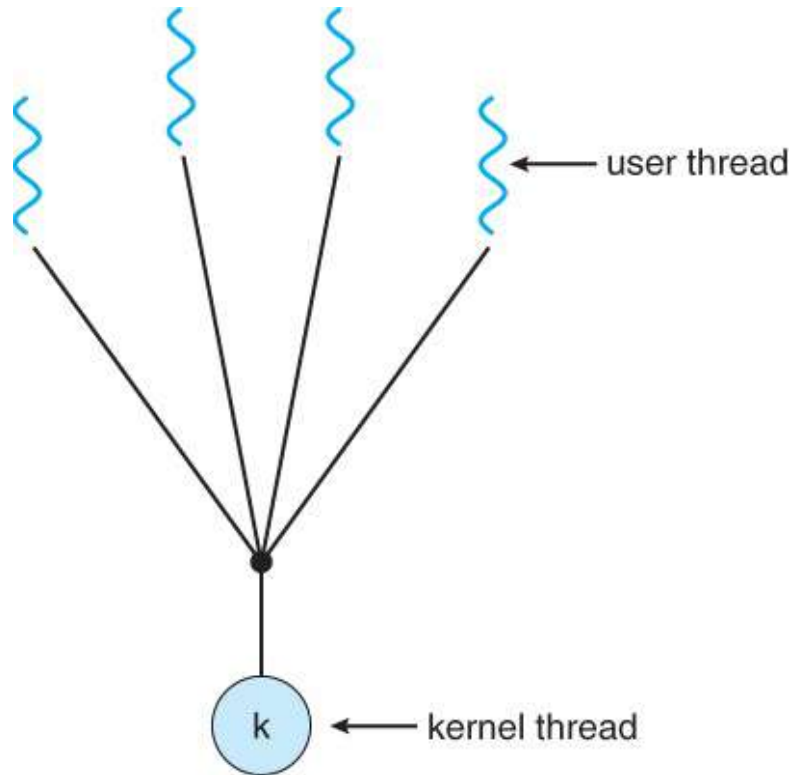
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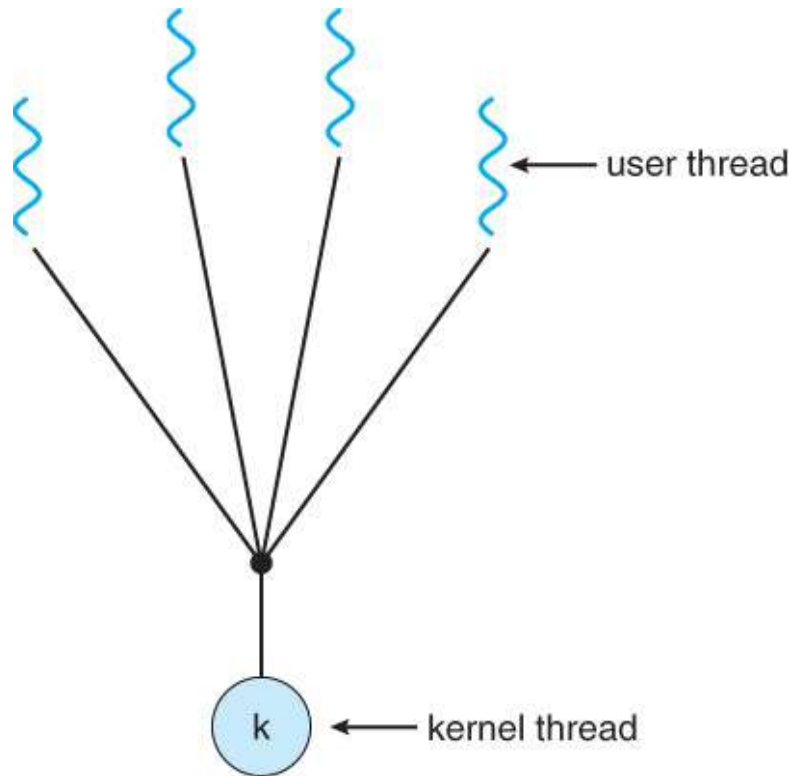


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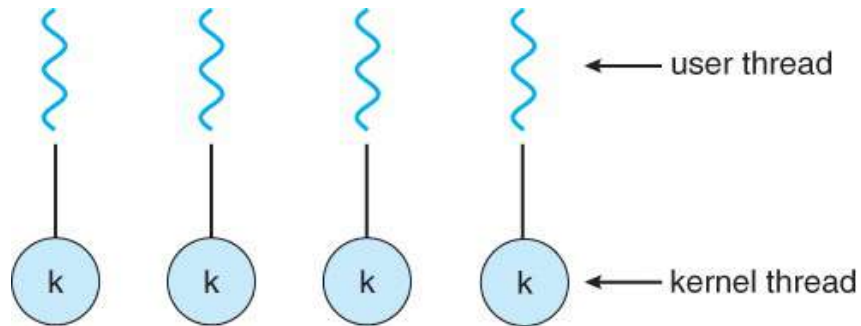
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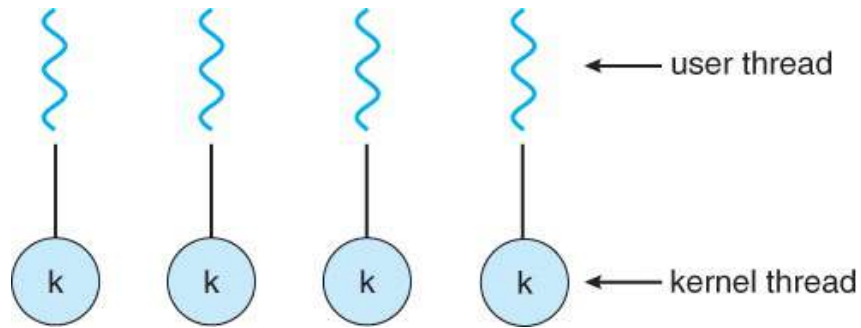
pure user-level

# One-to-One Model



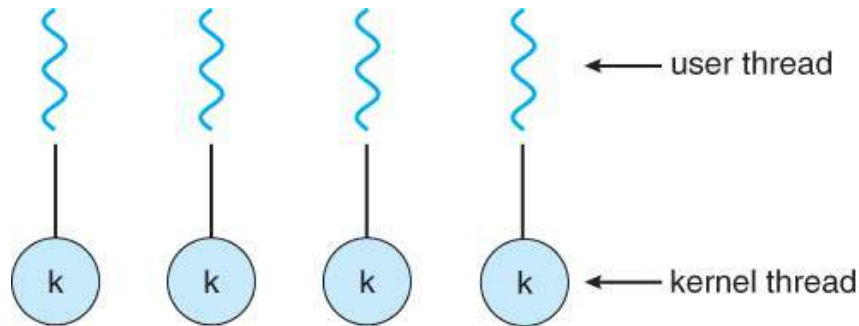
- A separate kernel thread to handle each user thread
- Overcomes the limitations of blocking system calls and splitting of processes across multiple CPUs
- The overhead of managing the one-to-one model is more significant and may slow down the system
- Most implementations of this model place a limit on how many threads can be created

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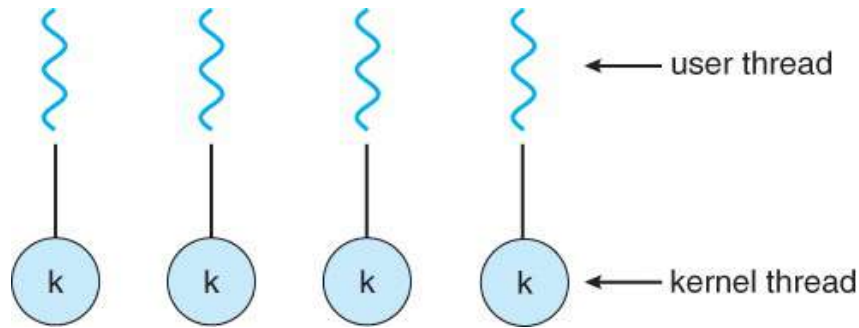
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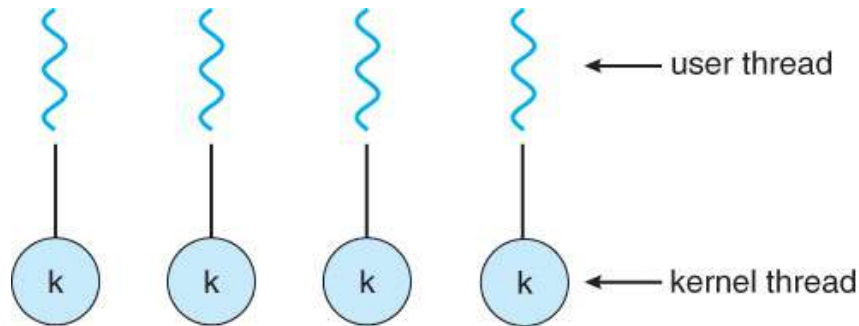
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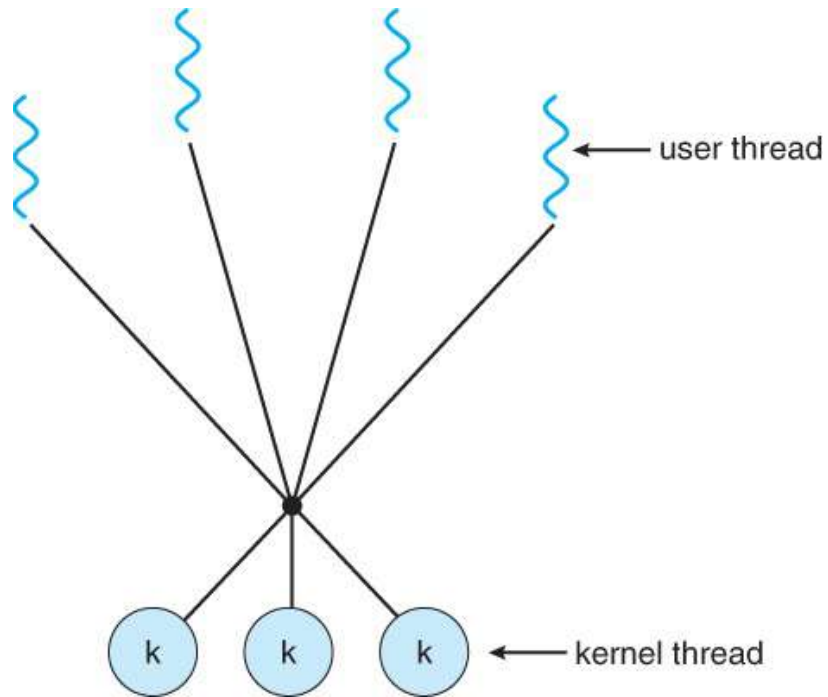
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pure kernel-level

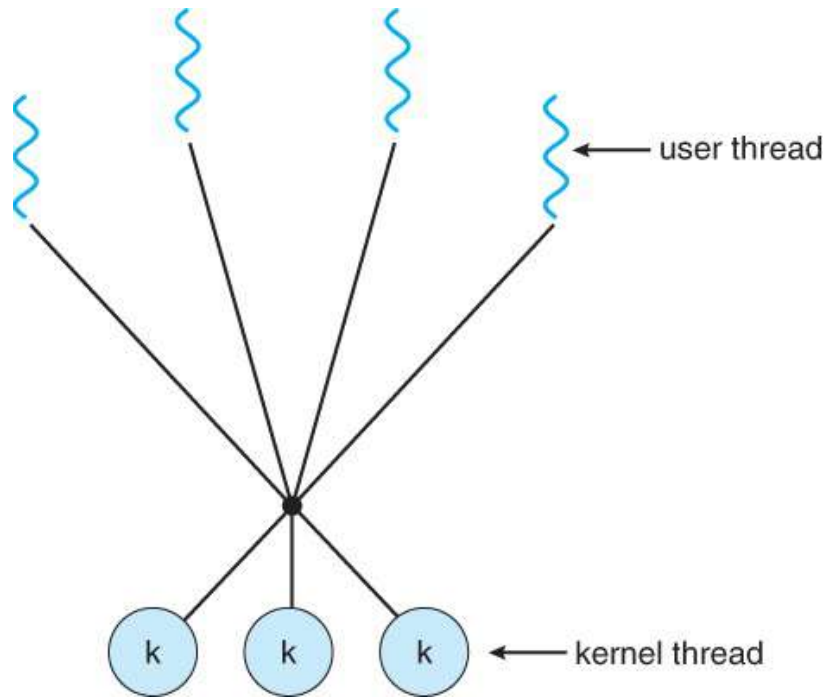
# Many-to-Many Model



- Multiplexes any number of user threads onto an equal or smaller number of kernel threads
- Users have no restrictions on the number of threads created
- Processes can be split across multiple processors
- Blocking kernel system calls do not block the entire process

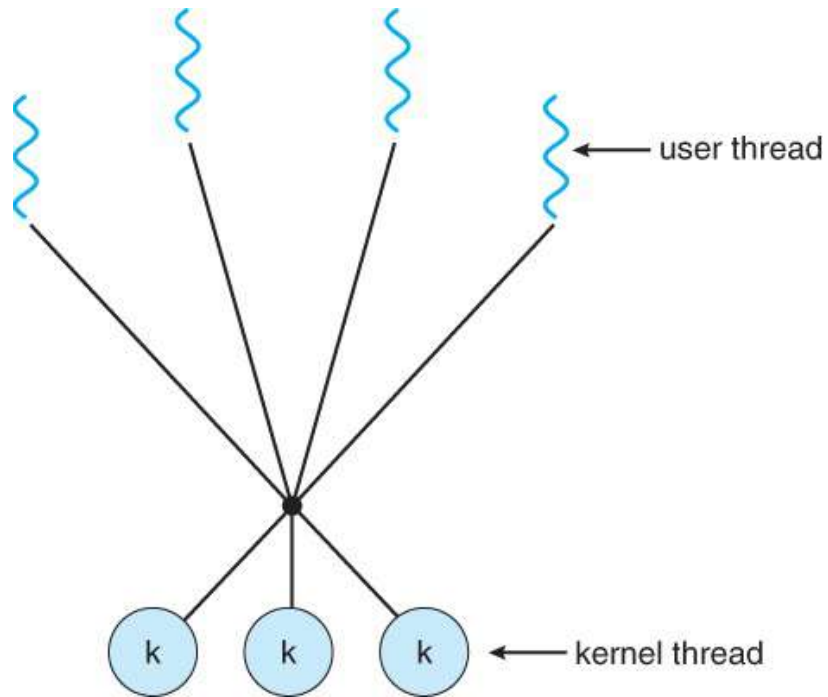


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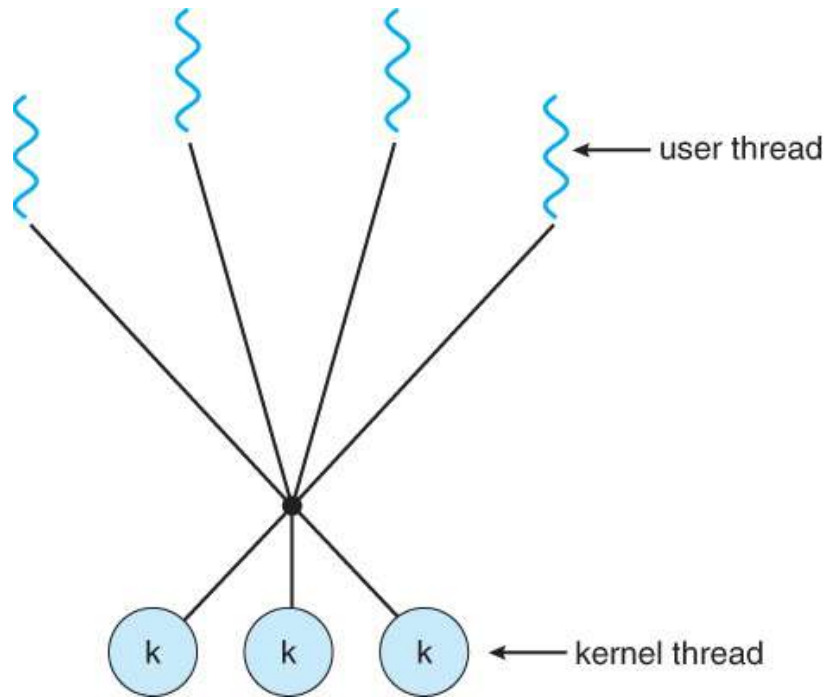
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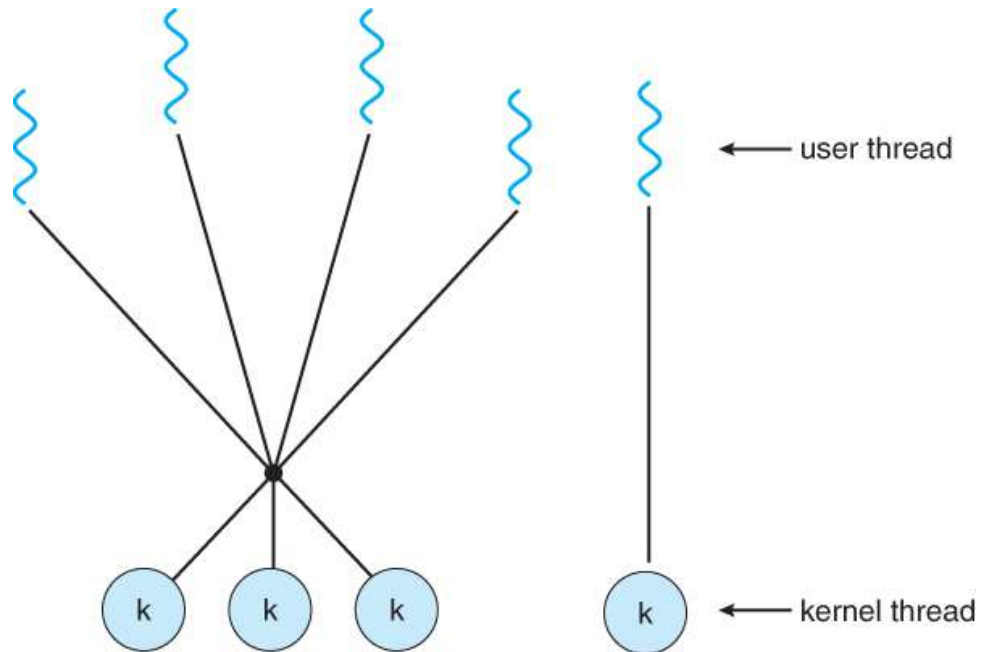
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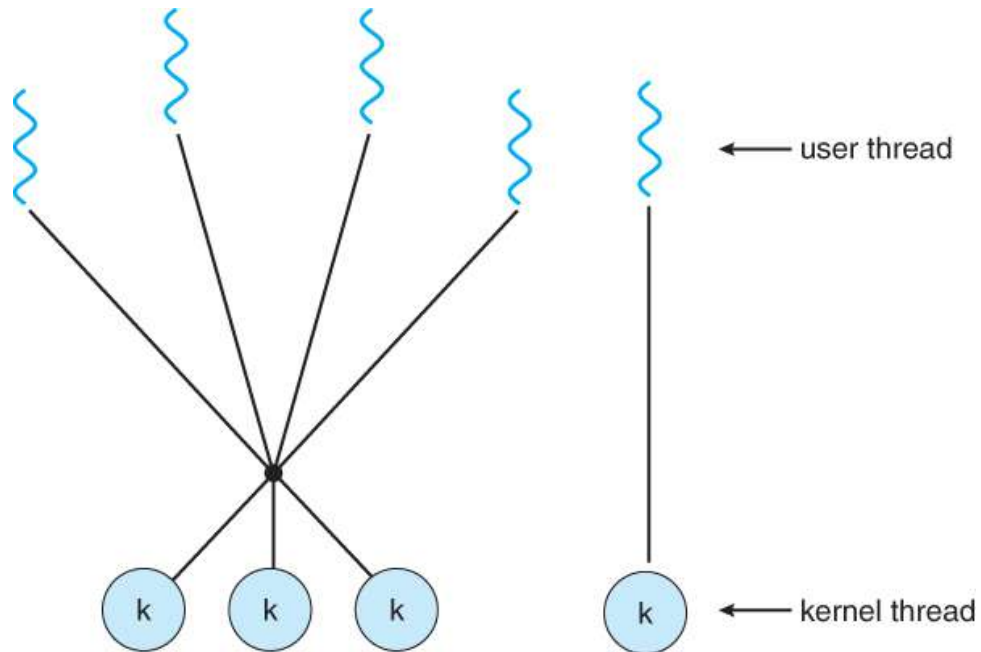
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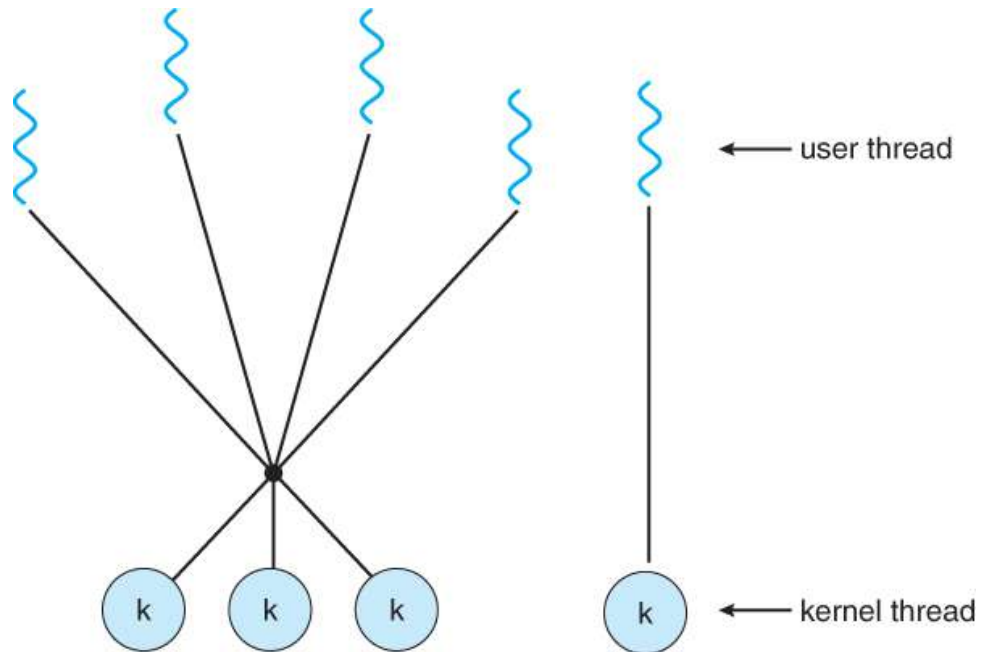
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- Provides programmers with an API for creating and managing threads
- 2 primary ways of implementing it:
  - **user space** → API functions implemented entirely in user space (function calls)
  - **kernel space** → implemented in kernel space within a kernel that supports threads (system calls)

# Thread Libraries: Examples

- There are 3 main thread libraries in use today:
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  - **POSIX Pthreads** → may be provided as either a user or kernel library, as an extension to the POSIX standard
  - **Win32 threads** → provided as a kernel-level library on Windows systems
  - **Java threads** → the implementation of threads is based upon whatever OS and hardware the JVM is running on, e.g., either Pthreads or Win32 threads

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- One thread can wait for the others to rejoin before continuing



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Compute the sum of the first  $N$  integers on a separate thread

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#include <pthread.h>
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int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */

int main(int argc, char *argv[])
{
    pthread_t tid; /* the thread identifier */
    pthread_attr_t attr; /* set of thread attributes */

    if (argc != 2) {
        fprintf(stderr, "usage: a.out <integer value>\n");
        return -1;
    }
    if (atoi(argv[1]) < 0) {
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    }

    /* get the default attributes */
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    /* wait for the thread to exit */
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}

/* The thread will begin control in this function */
void *runner(void *param)
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    int i, upper = atoi(param);
    sum = 0;

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Figure 4.6 Multithreaded C program using the Pthreads API.

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  - Extending the **Thread** class
  - Implementing the **Runnable** Interface
- Both solutions require to override the **run()** method
- Note that Java doesn't support multiple inheritance!
  - If your class extends the **Thread** class, it cannot extend any other class
  - In such a situation, implementing **Runnable** is preferable



# Java Threads: Single-Threaded Web Server

```
1 public class SingleThreadedServer implements Runnable {
2
3     protected int      serverPort    = 8080;
4     protected ServerSocket serverSocket = null;
5     protected boolean   isStopped    = false;
6
7     public SingleThreadedServer(int port){
8         this.serverPort = port;
9     }
10
11     public void run() {
12
13         try {
14             this.serverSocket = new ServerSocket(this.serverPort);
15         }
16         catch (IOException e) {
17             throw new RuntimeException("Cannot open port " + this.serverPort, e);
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42     private void processClientRequest(Socket clientSocket) throws Exception {
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This is the simplest (although not optimal)  
**single-threaded** implementation of a Java web server

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This is not a good idea as clients can connect to the server only when this is inside the `serverSocket.accept()` method call

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The risk of clients being denied access to the server because the listening thread is outside the `accept()` call is minimized



# Java Threads: Multi-Threaded Web Server

```
1 public class WorkerRunnable implements Runnable{
2
3     protected Socket clientSocket = null;
4     protected String serverText = null;
5
6     public WorkerRunnable(Socket clientSocket, String serverText) {
7         this.clientSocket = clientSocket;
8         this.serverText = serverText;
9     }
10
11     public void run() {
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- Solution → use a **thread pool**

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- Those threads are placed in the "pool" waiting for some work to do
- When the web server gets a request it awakens a thread from the pool
- The worker thread processes the request and goes back to the pool once terminated
- If no threads are available in the pool the server simply waits for one

# Thread Pools: Benefits

- Servicing a request with an existing thread is faster than waiting to create a thread
- A thread pool limits the number of threads that exist at any one point
- Separating the task to be performed from the mechanics of creating the task allows us to use different strategies for running the task
  - For example, the task could be scheduled to execute after a time delay or to execute periodically

# Threading Issues: **fork ()** and **exec ()**

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# Threading Issues: **fork()** and **exec()**

- **Q:** *If one thread forks, is the entire process copied, or is the new process single-threaded?*
- **A1:** System dependent
- **A2:** If the new process execs right away, there is no need to copy all the other threads, otherwise the entire process should be copied

# Threading Issues: **fork ()** and **exec ()**

- **Q:** *If one thread forks, is the entire process copied, or is the new process single-threaded?*
- **A1:** System dependent
- **A2:** If the new process execs right away, there is no need to copy all the other threads, otherwise the entire process should be copied
- **A3:** Many versions of UNIX provide multiple versions of the fork call for this purpose



# Threading Issues: Signal Handling

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# Threading Issues: Signal Handling

- **Q:** *When a multi-threaded process receives a signal, to what thread should that signal be delivered?*
- **A:** There are 4 major options:
  - Deliver the signal to the thread to which the signal applies
  - Deliver the signal to every thread in the process
  - Deliver the signal to certain threads in the process
  - Assign a specific thread to receive all signals in a process

# Threading Issues: Signal Handling (UNIX)

- UNIX allows individual threads to indicate which signals they are accepting and which they are ignoring
- Provides 2 separate system calls for delivering signals to process/threads, respectively:
  - `kill(pid, signal)`
  - `pthread_kill(tid, signal)`

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  - on systems implementing many-to-one and many-to-many threads
- **System Contention Scope (SCS)**
  - involves the system scheduler scheduling kernel threads to run on one or more CPUs
  - on systems implementing one-to-one threads

# Thread Scheduling: Activation

- Many implementations of threads provide a virtual processor as an interface between user thread and the kernel thread (many-to-many or two-tier)
- This virtual processor is known as a **Lightweight Process (LWP)**
- There is a one-to-one correspondence between LWPs and kernel threads
- The number of kernel threads available may change dynamically
- The application (user-level thread library) maps user threads onto available LWPs
- Kernel threads are scheduled onto the real processor(s) by the OS

# Thread Scheduling: Activation

- The kernel communicates to the user-level thread library when certain events occur (e.g., a thread is blocking) via an **upcall**
- The upcall is handled in the thread library by an **upcall handler**
- The upcall also provides a new LWP for the upcall handler to run on, which it can then use to reschedule the user thread that is about to become blocked
- The OS will also issue upcalls when a thread unblocks, so the thread library can make appropriate adjustments
- If the kernel thread blocks then the LWP blocks, which blocks the user thread



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- **Thread** vs. **Process**:
  - common vs. separate address spaces → **quicker communication**
  - lightweight vs. heavyweight → **faster context switching**
- **User-** vs. **Kernel-level** threads
- Scheduling algorithms operates (almost) transparently with threads