

# Systems and Networking – Unit I

B.Sc. in Applied Computer Science and Artificial Intelligence

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Synchronization as a solution to the critical section problem

# Part III: Process Synchronization

# The Need for Synchronization: Example

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Time	Bob	Carla
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5:20pm		Arrive home
5:25pm	Arrive at the grocery	Look in the fridge → No milk!

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5:50pm		Buy milk
6:05pm		Arrive home, put the milk in the fridge

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5:25pm	Arrive at the grocery	Look in the fridge → No milk!
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5:45pm	Arrive home, put the milk in the fridge	Arrive at the grocery
5:50pm		Buy milk
6:05pm		Arrive home, put the milk in the fridge
6:05pm	Oh f*%#k!	Oh f*%#k!

# The Need for Synchronization: Example

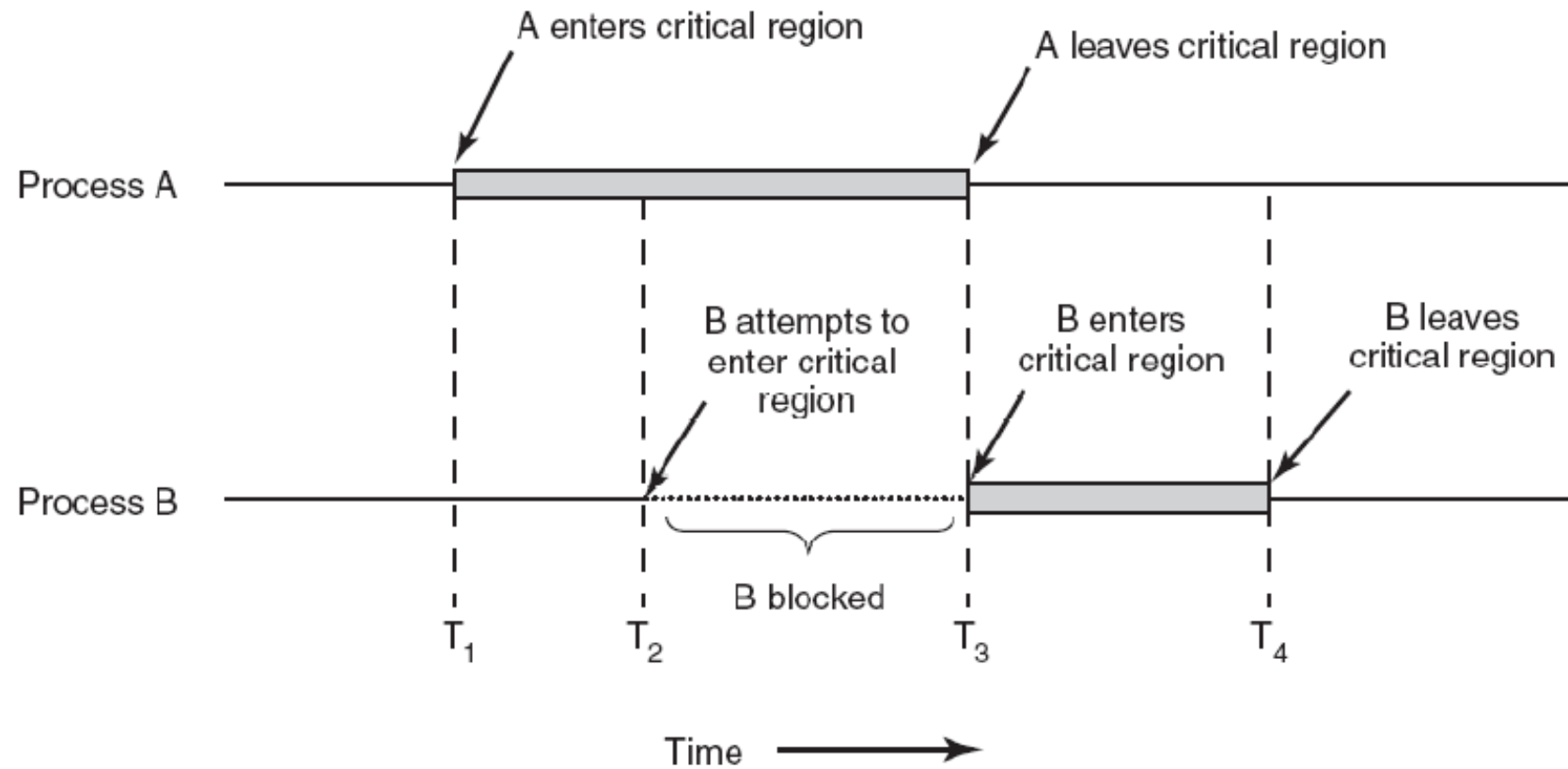
- In the example, **Bob** and **Carla** represents 2 processes/threads
- Theoretically, they should cooperate to achieve a common task (e.g., buying some milk)
- In practice, though, they might incur in unpleasant situations (e.g., buying too much milk!)

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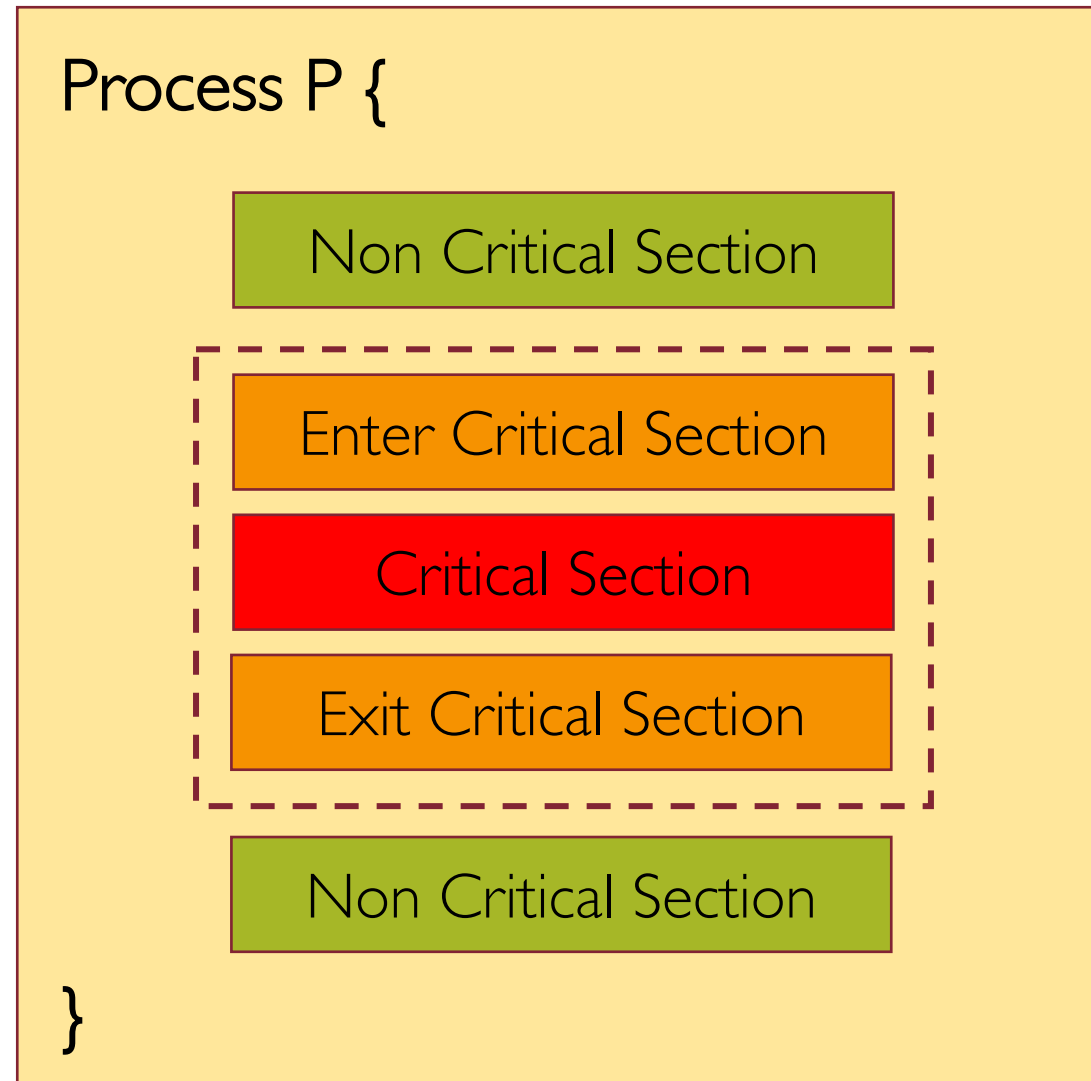
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What kind of mechanisms do we need in order to get independent yet cooperating processes to communicate and have a consistent view of the "world" (i.e., computational state)?

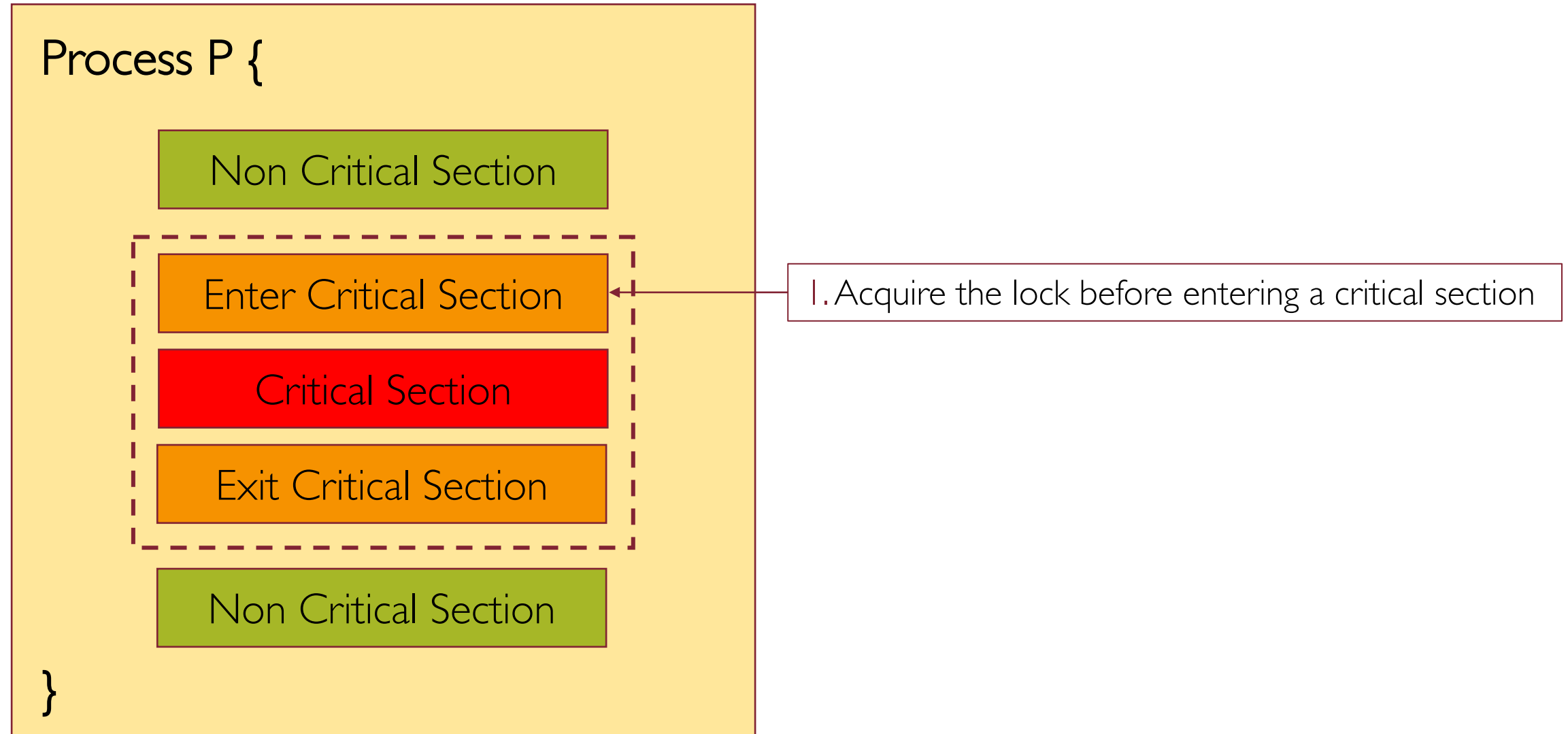
# The Critical Section Problem



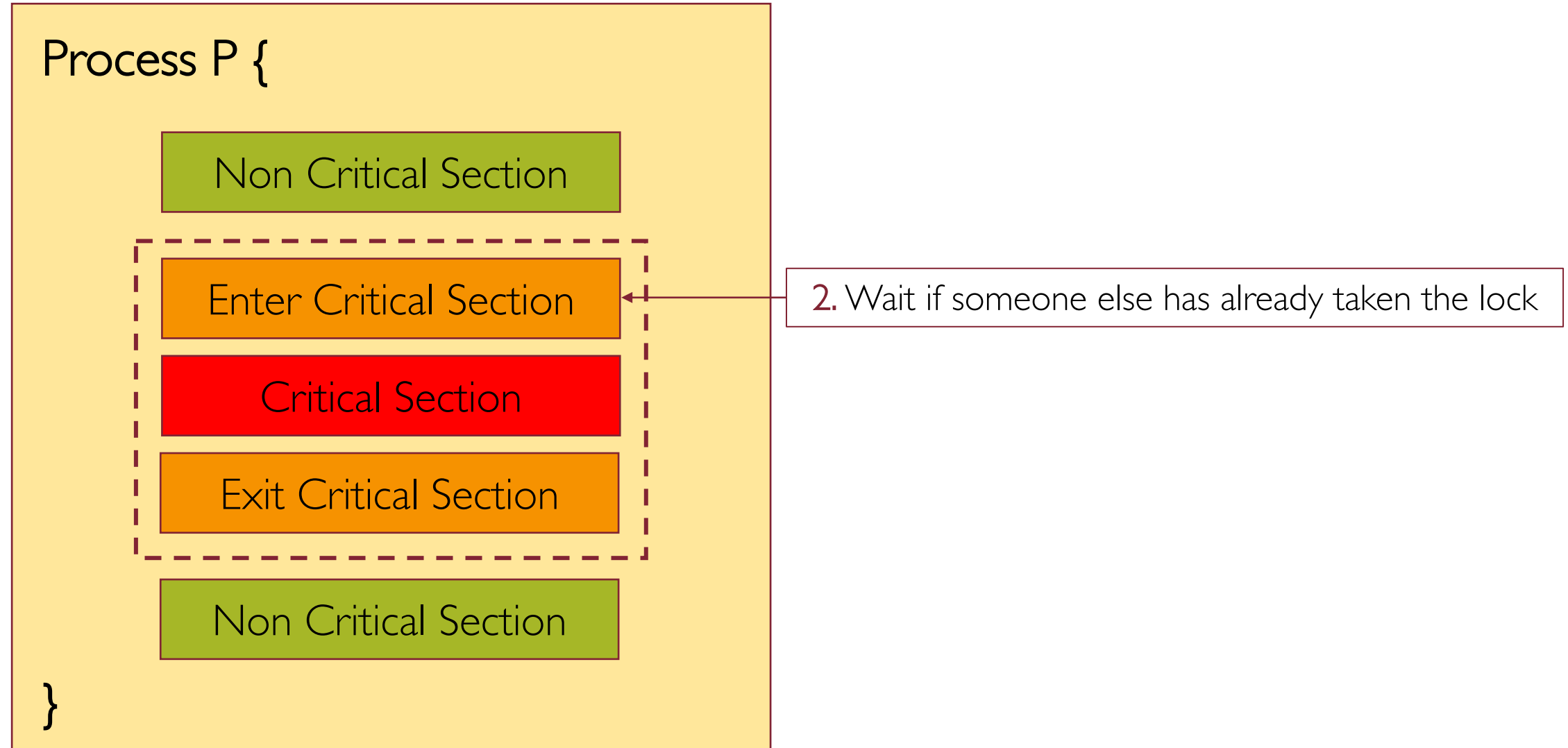
# The Anatomy of a Critical Section



# Locking Critical Section

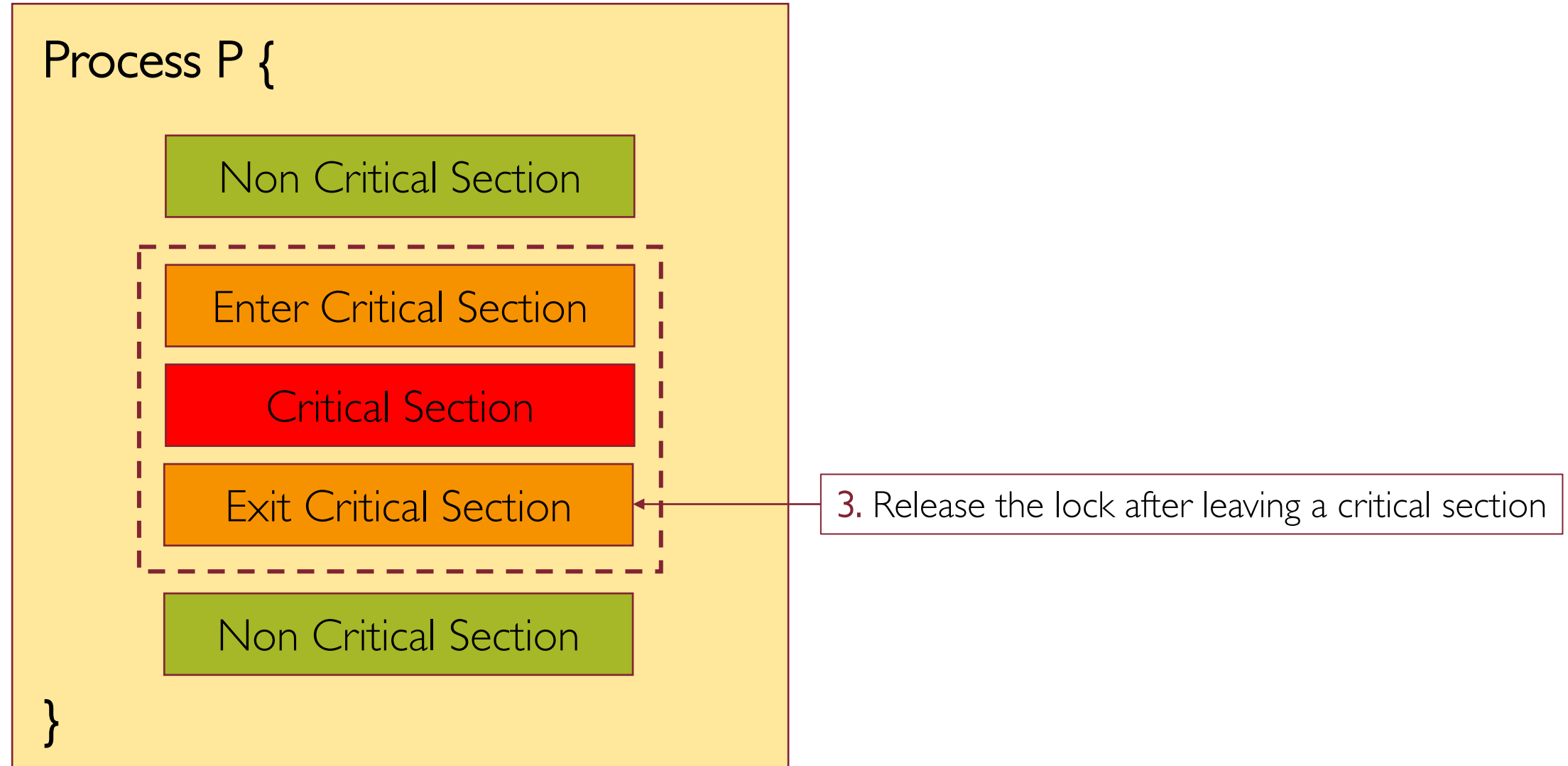


# Locking Critical Section

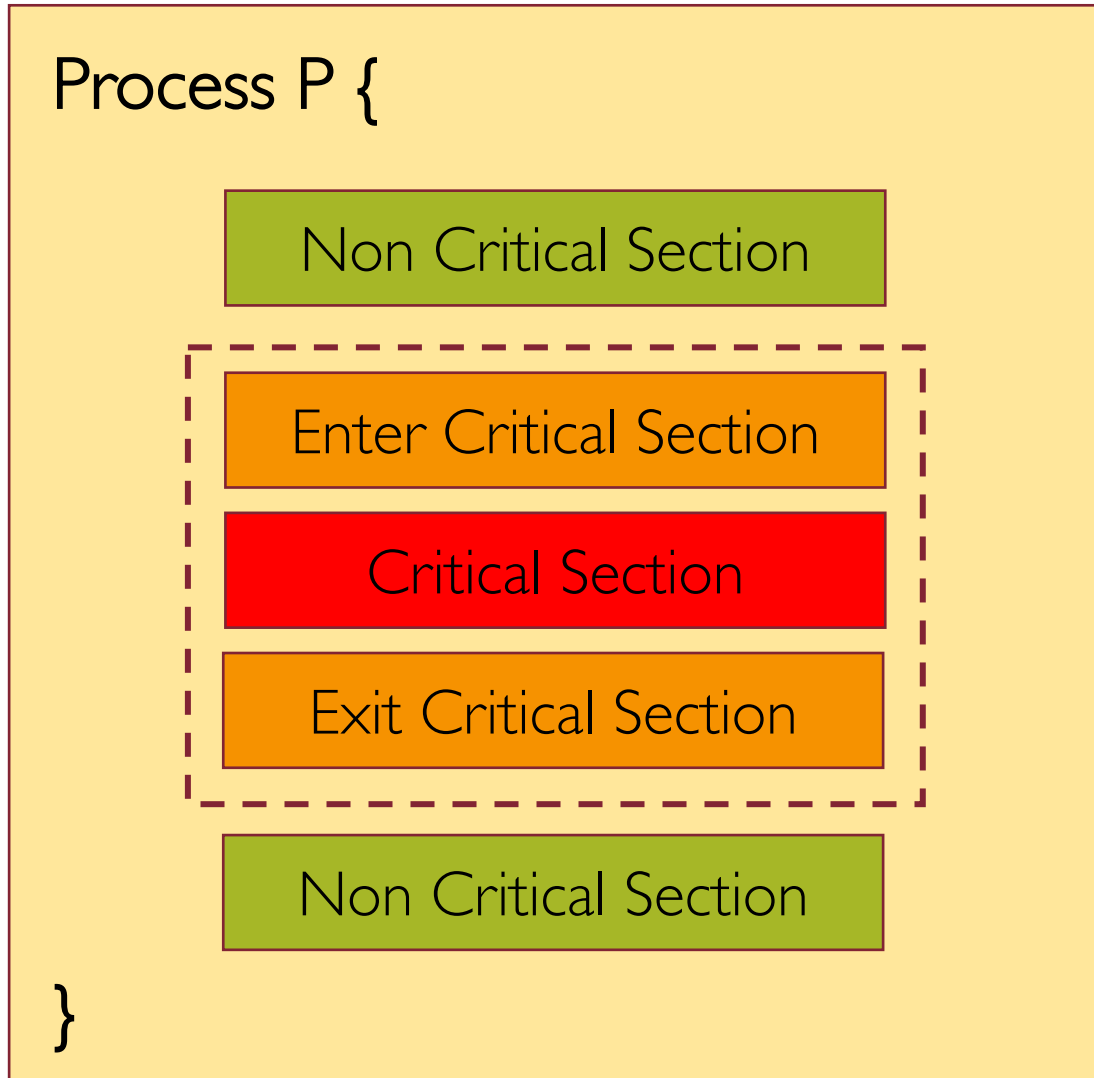




# Locking Critical Section



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All synchronization involves waiting!

# Synchronization: Goals

- Any synchronization solution to the critical section problem must satisfy 3 properties:
  - **Mutual Exclusion** → only one process/thread can be in its critical section at a time!

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  - **Mutual Exclusion** → only one process/thread can be in its critical section at a time!
  - **Liveness** → If no process is in its critical section, and one or more want to execute it then any one of these must be able to get into its critical section
  - **Bounded Waiting** → A process requesting entry into its critical section will get a turn eventually, and there is a limit on how many others get to go first

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- In the milk example:
  - Ensuring **mutual exclusion** means no more milk than what is needed will be bought (i.e., only one between **Bob** and **Carla** will buy milk if needed)

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  - Ensuring **liveness** means that someone should buy some milk (i.e., the option where both **Bob** and **Carla** do not do anything is surely safe but undesirable)
  - Ensuring **bounding waiting** means that eventually **Bob** and **Carla** will enter their critical section



# Too Much Milk: Solution I

Use a **note**

```
# Thread Bob

if (!milk and !note):
    leave_note()
    buy_milk()
    remove_note()
```

```
# Thread Carla

if (!milk and !note):
    leave_note()
    buy_milk()
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Does this solution work?

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Does this solution work **regardless of the scheduling?**

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    buy_milk()
    remove_note()
```

Does this solution work **regardless of the scheduling?**

No! mutual exclusion can be violated

# Too Much Milk: Solution 2

Use 2 (labeled) notes

```
# Thread Bob

leave_note(Bob)

if (!note(Carla)) :
    if (!milk):
        buy_milk()

remove_note()
```

```
# Thread Carla

leave_note(Carla)

if (!note(Bob)) :
    if (!milk):
        buy_milk()

remove_note()
```

# Too Much Milk: Solution 2

Use **2** (labeled) notes

```
# Thread Bob

leave_note(Bob)

if (!note(Carla)) :
    if (!milk):
        buy_milk()

remove_note()
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```
# Thread Carla

leave_note(Carla)

if (!note(Bob)) :
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        buy_milk()

remove_note()
```

Does this solution work **regardless of the scheduling?**

# Too Much Milk: Solution 2

Use 2 (labeled) notes

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# Thread Bob

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if (!note(Carla)) :
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remove_note()
```

```
# Thread Carla

leave_note(Carla)

if (!note(Bob)) :
    if (!milk):
        buy_milk()

remove_note()
```

Does this solution work **regardless of the scheduling?**

No! Liveness property can be violated

# Too Much Milk: Solution 3

Use **2** (labeled) notes... more cleverly

```
# Thread Bob

leave_note(Bob)

while (note(Carla)) :
    do_nothing()
if (!milk):
    buy_milk()

remove_note()
```

```
# Thread Carla

leave_note(Carla)

if (!note(Bob)) :
    if (!milk):
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remove_note()
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Does this solution work regardless of the scheduling?

Yes!

# Too Much Milk: Solution 3

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Y: →

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Case 1: no note from Bob

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Thread Bob must be  
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Carla will buy milk only if  
needed

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remove_note()
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Case 2: Bob has left a note

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remove_note()
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So has Carla, therefore Bob  
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So has Carla, therefore Bob will be waiting (loop)



Carla will remove his note and Bob will buy milk if needed

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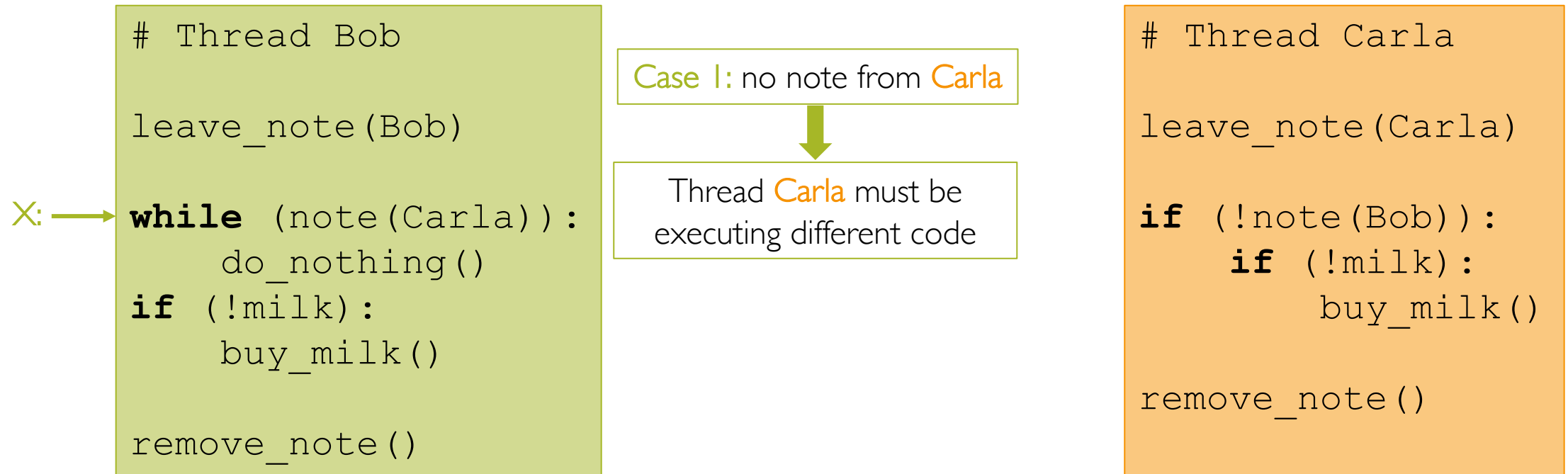
X: →

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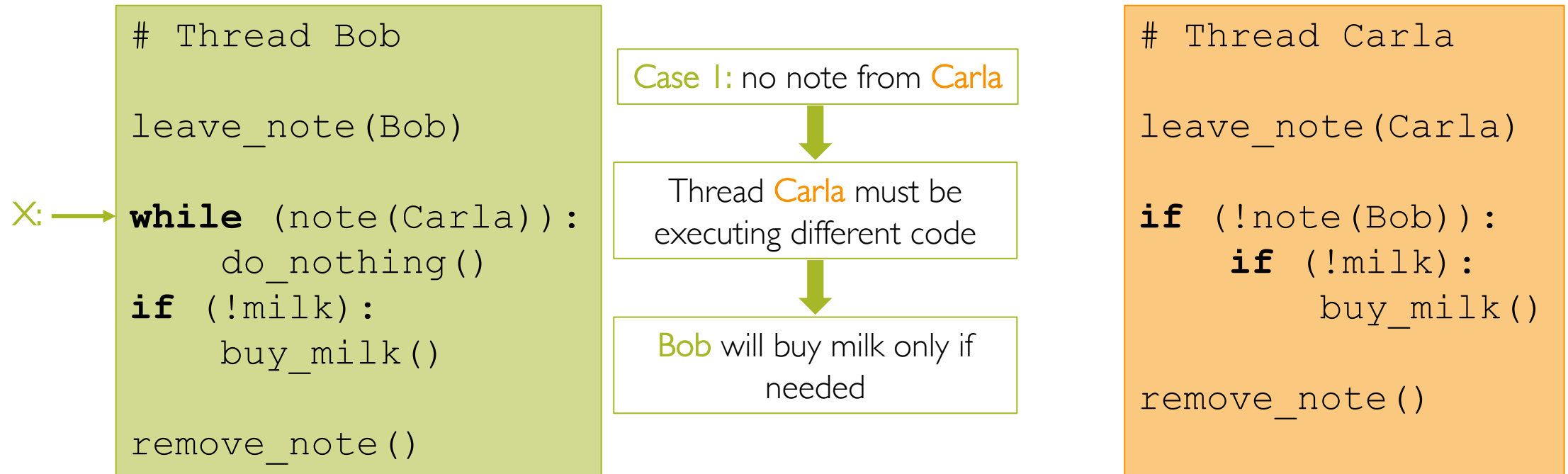
Case I: no note from Carla

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Case 2: Carla has left a note

```
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    if (!milk):  
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remove_note()
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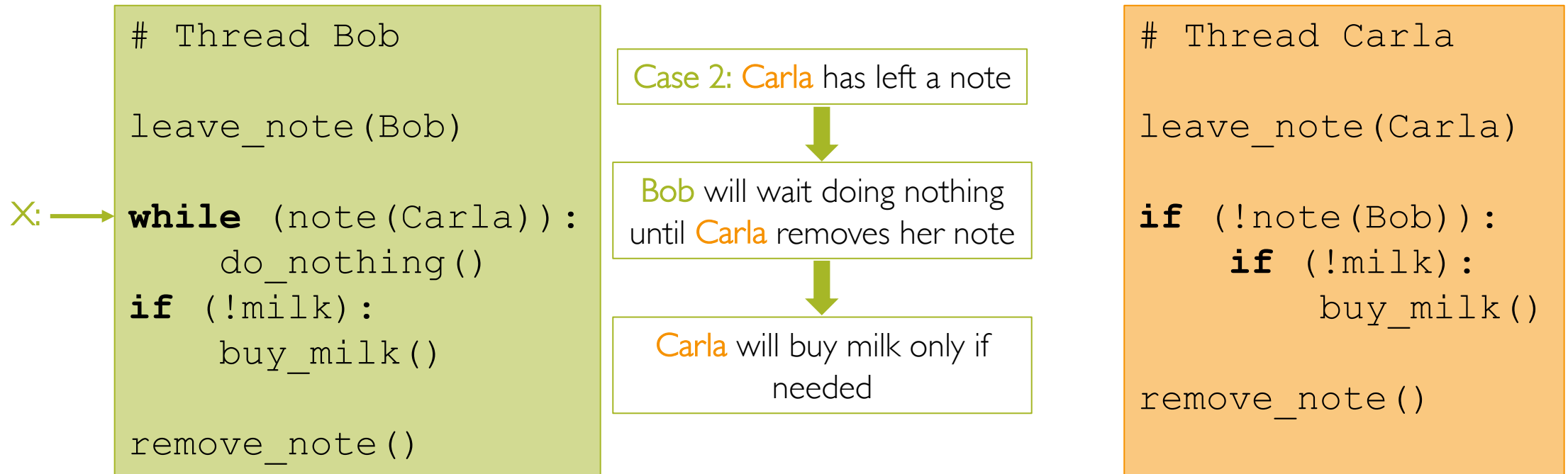
Case 2: Carla has left a note



Bob will wait doing nothing  
until Carla removes her note

```
# Thread Carla  
leave_note(Carla)  
  
if (!note(Bob)) :  
    if (!milk):  
        buy_milk()  
  
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This solution assumes loads and stores being atomic (i.e., non-interruptable)

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- **Locks** → At each time, only one process holds a lock, executes its critical section, and finally releases the lock
- **Semaphores** → A generalization of locks
- **Monitors** → To connect shared data to synchronization primitives

Require some HW support and waiting

# Locks

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- Rules for using a lock:
  - Always acquire the lock **before** accessing shared data
  - Always release the lock **after** finishing with shared data
  - Lock must be **initially free**
- Only one process/thread can acquire the lock, others will wait!

# Too Much Milk: Solution Using Locks

Use **lock** primitives

```
# Thread Bob

Lock.acquire()

if (!milk):
    buy_milk()

Lock.release()
```

```
# Thread Carla

Lock.acquire()

if (!milk):
    buy_milk()

Lock.release()
```



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**Q:** How do we make **acquire()** and **release()** atomic?

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Low-level atomic operations (HW)	disabling interrupts, atomic instructions (test&set)

# HW Support for Synchronization

Implementing high-level synchronization primitives requires low-level hardware support

High-level atomic operations (SW)	<b>lock</b> , monitor, semaphore, send/receive
Low-level atomic operations (HW)	<b>disabling interrupts</b> , atomic instructions (test&set)

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- The CPU scheduler takes control due to **2** possible situations:
  - **internal events** → the current thread voluntarily relinquishes control of the CPU (e.g., via an I/O system call)
  - **external events** → interrupts (e.g., time slice) cause the scheduler to take over the currently running thread

# Implementing Locks: Disabling Interrupts

- If we think about it, the reason why we care of synchronization is because context switches may occur unexpectedly
- The CPU scheduler takes control due to **2** possible situations:
  - **internal events** → the current thread voluntarily relinquishes control of the CPU (e.g., via an I/O system call)
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We want to prevent the CPU scheduler to take control while an **acquire()** operation is ongoing

# Implementing Locks: Disabling Interrupts

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  - **external event** → disabling interrupts (i.e., telling the HW to delay the handling of any external event until the current thread is done with the critical section)

We cover all the possible cases where the current thread might loose control of the CPU, either voluntarily (due to internal events) or involuntarily (due to external events)

# Implementing Locks: Disabling Interrupts

```
Class Lock {  
    public void acquire(Thread t);  
    public void release();  
    private int value; // 0=FREE, 1=BUSY  
    private Queue q;  
  
    Lock() {  
        // lock is initially FREE  
        this.value = 0;  
        this.q = null;  
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```

```
public void acquire(Thread t) {  
    disable_interrupts();  
    if(this.value) { // lock is held by someone  
        q.push(t); // add t to waiting queue  
        t.sleep(); // put t to sleep  
    }  
    else {  
        this.value = 1;  
    }  
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```
public void release() {  
    disable_interrupts();  
    if(!q.is_empty()) {  
        t = q.pop(); // extract a waiting thread from q  
        push_onto_ready_queue(t); // put t on ready queue  
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We need both **acquire** and **release** being implemented as system calls

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Why?

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# HW Support for Synchronization

Implementing high-level synchronization primitives requires low-level hardware support

High-level atomic operations (SW)	<b>lock</b> , monitor, semaphore, send/receive
Low-level atomic operations (HW)	disabling interrupts, <b>atomic instructions (test&amp;set)</b>

# Implementing Locks: Atomic Instructions

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  - On a uniprocessor → straightforward to implement adding a new instruction
  - On a multiprocessor → the processor issuing the instruction must also be able to invalidate any copies of the value other processes may have in their cache
- Examples:
  - **test&set** (most architectures) → reads a value, writes **1** back to memory
  - **exchange** (x86) → swaps values between register and memory

# Implementing Locks: test&set

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Class Lock {  
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    public void release();  
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public void acquire() {  
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        // while busy do nothing  
    }  
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**Case 1:** if lock is free (value = 0) test&set (value) will read 0, set it to 1 and return 0

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**Case 1:** if lock is free (`value = 0`) `test&set(value)` will read 0, set it to 1 and return 0

The lock is now busy, the boolean expression in the while guard is false and **acquire** terminates

# Implementing Locks: test&set

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Class Lock {  
    public void acquire();  
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public void acquire() {  
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**Case 2:** if lock is busy (value = 1) test&set (value) will read 1, set it to 1 and return 1

# Implementing Locks: `test&set`

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Class Lock {  
    public void acquire();  
    public void release();  
    private int value;  
  
    Lock () {  
        // lock is initially free  
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    }  
}
```

```
public void acquire() {  
    while(test&set(this.value) == 1) {  
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}
```

```
public void release() {  
    this.value = 0;  
}
```

**Case 2:** if lock is busy (`value = 1`) `test&set (value)` will read 1, set it to 1 and return 1

The lock is still busy, the boolean expression in the while guard is true and **acquire** continues to loop until **release** executes

# Atomic Instructions: Any Issue?

```
public void acquire() {  
    while(test&set(this.value) == 1) {  
        // while busy do nothing  
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```

- What's wrong with the above implementation?

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who is going to take the  
lock once released?

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  - **unfeasible** with multiprocessor architectures
- 2 main problems with atomic instructions:
  - **busy waiting**
  - **unfairness** as there is no queue where threads wait for the lock to be released

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```
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    }
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        q.push(t);
        t.sleep_and_reset_guard_to_0();
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    else {
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    }
    else {
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    }
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```

No, but we can minimize busy-waiting time by atomically checking the lock value and giving up the CPU if the lock is busy

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We can't totally get rid of busy-waiting but we can make it independent on how long is the critical section delimited by **acquire** and **release**



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