Systems and Networking I

Applied Computer Science and Artificial Intelligence 2023–2024



Gabriele Tolomei

Dipartimento di Informatica Sapienza Università di Roma tolomei@di.uniroma1.it

Recap from Last Lecture

- Synchronization primitives:
 - Locks
 - Semaphores
 - Monitors

Recap from Last Lecture

- Synchronization primitives:
 - Locks
 - Semaphores
 - Monitors
- 2 fundamental synchronization problems:
 - Producers-Consumers
 - Readers-Writers

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- 5 philosophers sitting at a round table

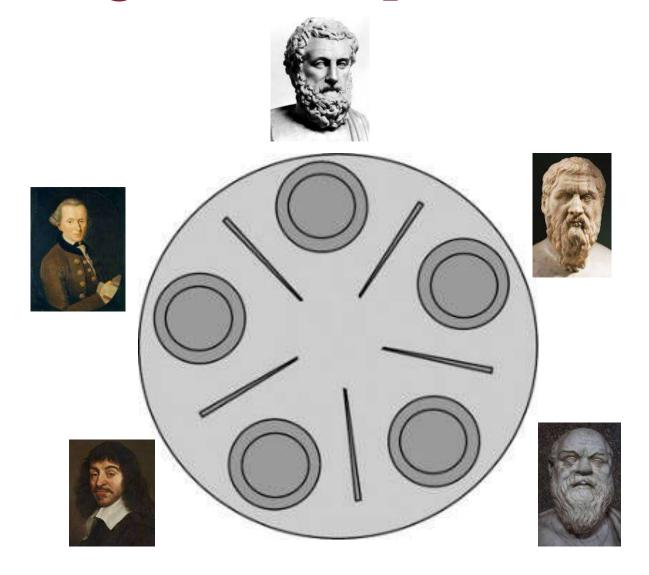
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- 2 things philosophers are good at \odot :
 - Eating
 - Thinking

• Thinking means do nothing (just kidding, but you get the idea!)

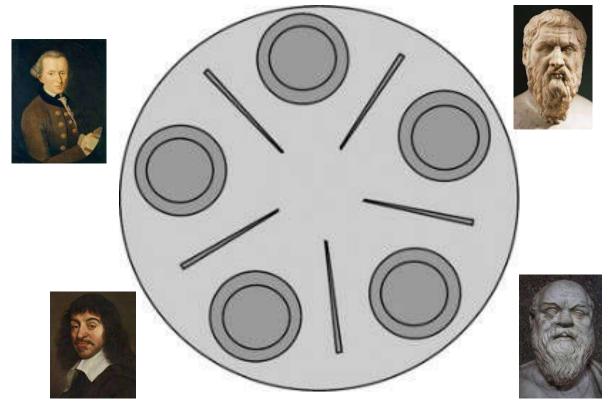
- Thinking means do nothing (just kidding, but you get the idea!)
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 - Try to pick up the two closest chopsticks (the left and the right ones)
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- After eating, put down both chopsticks and go back thinking!





How to make them not starving?



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Very inefficient! Only one philosopher at a time can eat

We still want some concurrency here ©

The Dining Philosophers: Solution 1

```
Semaphore chopsticks[5];
while(True) {
   chopsticks[i].wait();  // wait on the left chopstick
   chopsticks[(i+1)%5].wait(); // wait on the right chopstick
   eat();
   chopsticks[i].siqnal(); // siqnal on the left chopstick
   chopsticks[(i+1)%5].signal(); // signal on the right chopstick
   think();
```

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   think();
```

Is this solution correct?

No! Deadlock if all philosophers take the left chopstick

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Testing if either one of the two neighbors of a given philosopher is currently eating (condition variables)

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Idea: Before picking one chopstick be sure also the second one is available, otherwise wait for the neighbor to finish

Testing if either one of the two neighbors of a given philosopher is currently eating (condition variables)

Never gonna pick a single chopstick!

```
class Philosopher {
    enum Status {
        THINKING,
        HUNGRY,
        EATING
    }
    Status state;

    public Philosopher() {
        this.state = THINKING;
    }
}
```

```
void canEat(int i) {
    State state = this.philosophers[i].state;
    State left = this.philosophers[[(i-1)%5].state;
    State right = this.philosophers[[(i+1)%5].state;
    if(left != EATING && right != EATING && state == HUNGRY) {
        this.philosophers[i].state = EATING;
        this.philosophers[i].notify();
    }
}
```

```
class DiningPhilosophers {
    Philosopher[5] philosophers;

    public DiningPhilosopers() {
        for(int i=0; i < 5; ++i) {
            this.philosophers[i] = new Philosopher();
        }
    }
}
// continue implementation ------>
```

```
void synchronized pickup(int i) {
    this.philosophers[i].state = HUNGRY;
    canEat(i);
    while(this.philosophers[i].state != EATING) {
        this.philosophers[i].wait();
    }
}

void synchronized putdown(int i) {
    this.philosophers[i].state = THINKING;
    canEat((i - 1) % 5); // left neighbour
    canEat((i + 1) % 5); // right neighbour
}
```

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 - Producer-Consumer
 - Audio/Video player embedded in a web browser: shared data buffer
 - + network and render threads
 - Reader-Writer
 - DB system of a bank: read vs. update account balances
 - Dining Philosophers
 - Lock on multiple resources: e.g., travel reservation (hotel, airline, car rental databases)

Our Journey

- What is deadlock?
- Conditions for deadlock to happen
- Deadlock detection
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"When two trains approach each other at a crossing, both shall come to a full stop and neither shall start up again until the other has gone."

Kansas legislation early 1900's

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```
Thread A

printer.wait();
disk.wait();

// copy from disk to printer

printer.signal();
disk.signal();
```

```
Thread B

disk.wait();
printer.wait();

// copy from disk to printer
printer.signal();
disk.signal();
```

Intuitively, a condition where two or more threads are waiting for an event that can only be generated by the very same threads

```
Thread A

A starts first

printer.wait();

disk.wait();

// copy from disk to printer

printer.signal();
disk.signal();
```

```
Thread B

disk.wait();
printer.wait();

// copy from disk to printer

printer.signal();
disk.signal();
```

Intuitively, a condition where two or more threads are waiting for an event that can only be generated by the very same threads

```
Thread A

printer.wait(); Acquires printer and context switch
disk.wait();

// copy from disk to printer

printer.signal();
disk.signal();
```

```
Thread B

disk.wait();
printer.wait();

// copy from disk to printer

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Thread B

disk.wait(); Acquires disk and printer.wait(); context switch

// copy from disk to printer

printer.signal(); disk.signal();
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```
Thread B

disk.wait();
printer.wait();

// copy from disk to printer

printer.signal();
disk.signal();
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A waits B to release the disk

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```
Thread B

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printer.wait();

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printer.signal();
disk.signal();
```

B waits A to release the printer

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- Deadlock avoidance (online): runtime support checks resource requests made by threads to avoid deadlocks

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- Related terms but each one refers to a specific situation
- Starvation occurs when a thread waits indefinitely for some resource but other threads are actually making progress using that resource
- The main difference with deadlock is that the system is not completely stuck!

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 - No Preemption → a thread can only release a resource voluntarily;
 neither another thread nor the OS can force it to release the resource
 - Circular Wait \rightarrow a set of waiting threads t_1 , ..., t_n where t_i is waiting on $t_{(i+1)\%n}$

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• We define a directed graph G=(V, E) where:

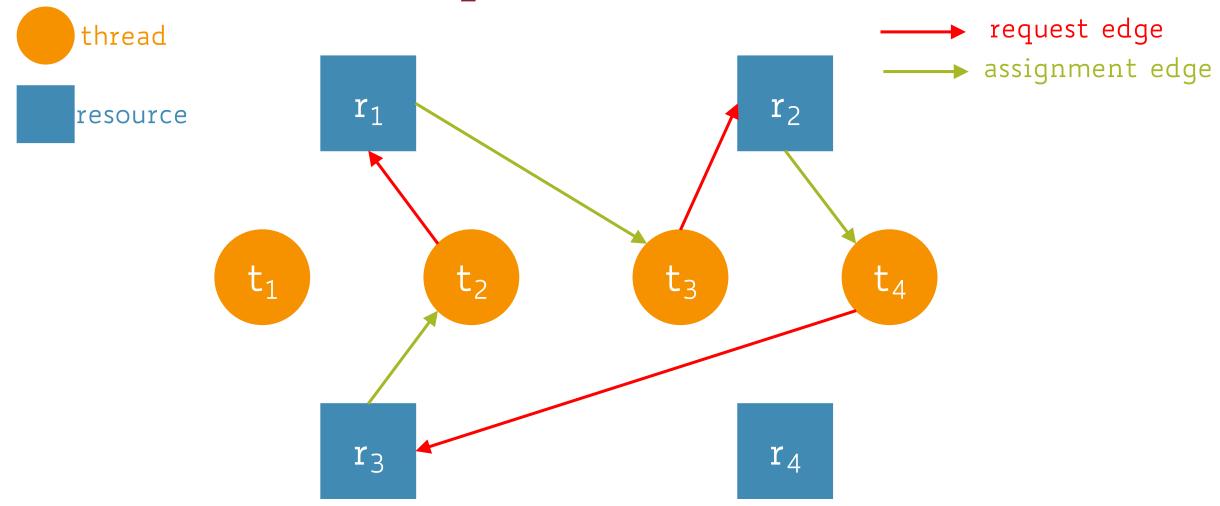
- We define a directed graph G=(V, E) where:
 - V is the set of vertices representing both resources $\{r_1, ..., r_m\}$ and threads $\{t_1, ..., t_n\}$

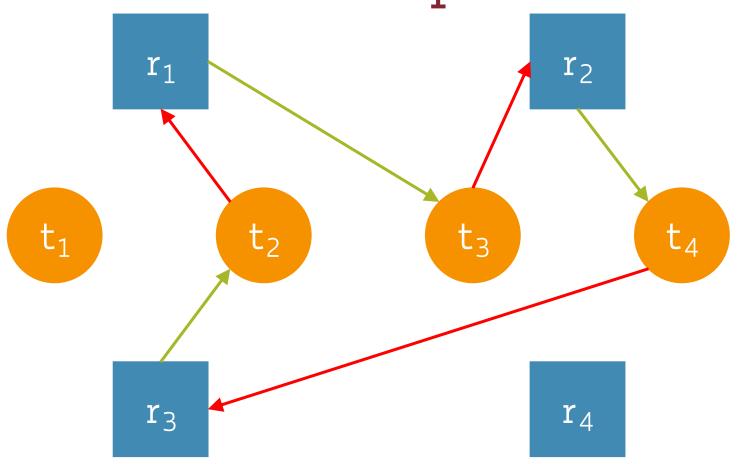
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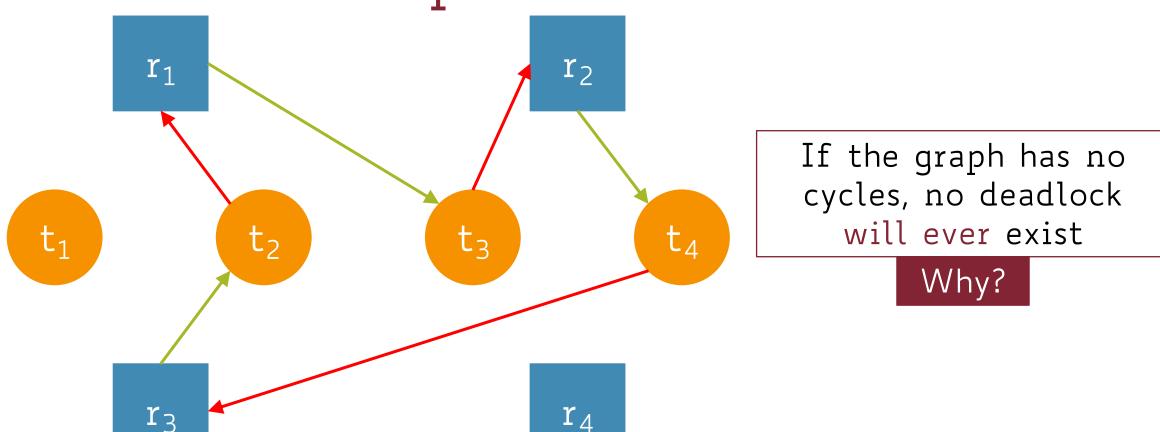
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 - Assignment Edge ightarrow a directed edge (r_j, t_i) indicates that the OS has allocated r_i to t_i



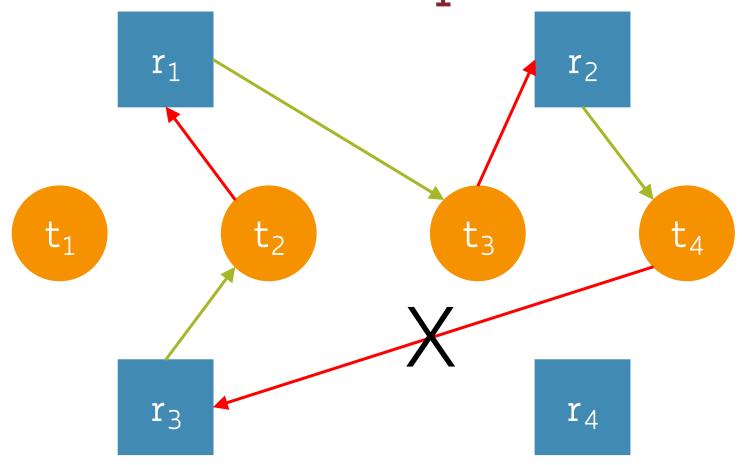


If the graph has no cycles, no deadlock will ever exist



Deadlock Detection: Resource

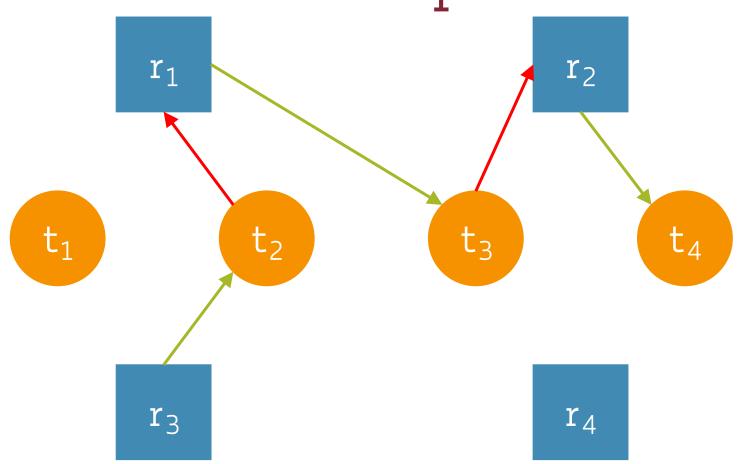
Allocation Graph



Suppose we remove the edge (t_4, r_3) so as to remove the cycle

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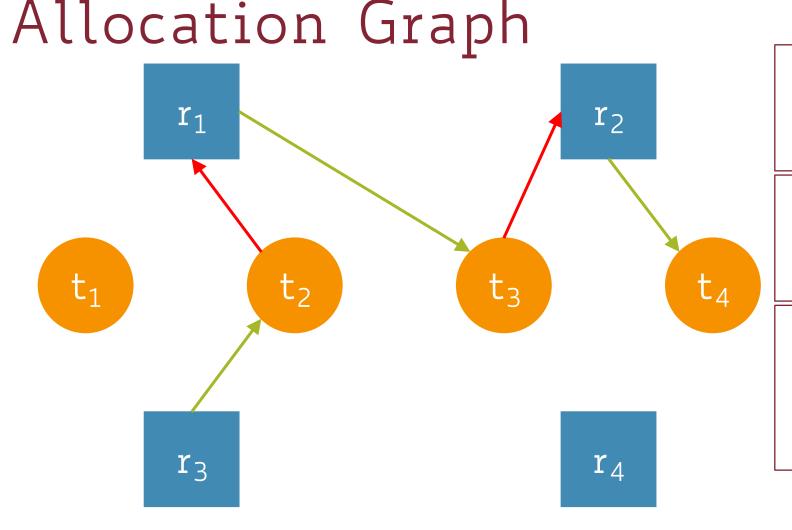
Allocation Graph



Suppose we remove the edge (t₄, r₃) so as to remove the cycle

No deadlock can occur as t₄ is not waiting on anything...

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Therefore, t₄ can run and eventually will release r₂, which wakes up t₃

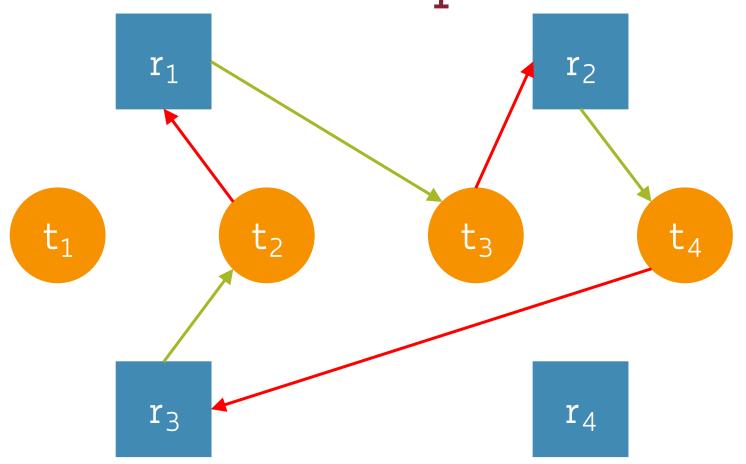
 r_1 r_2 t_4 t_2 t_3 r_4 **r**₃

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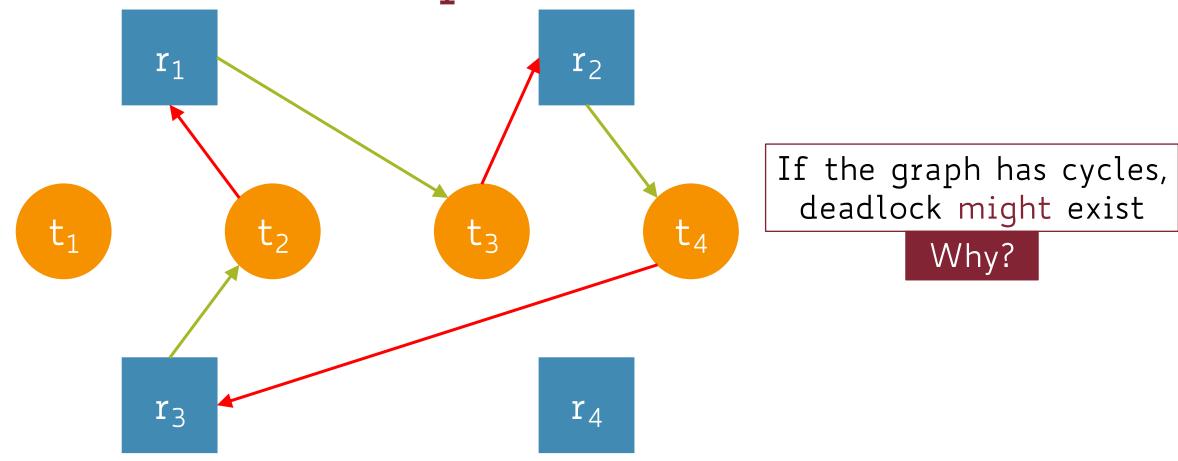
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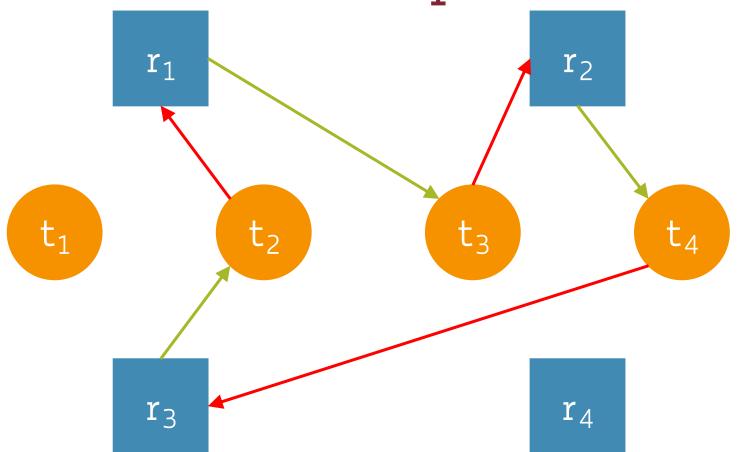
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And so on and so forth...



If the graph has cycles, deadlock might exist

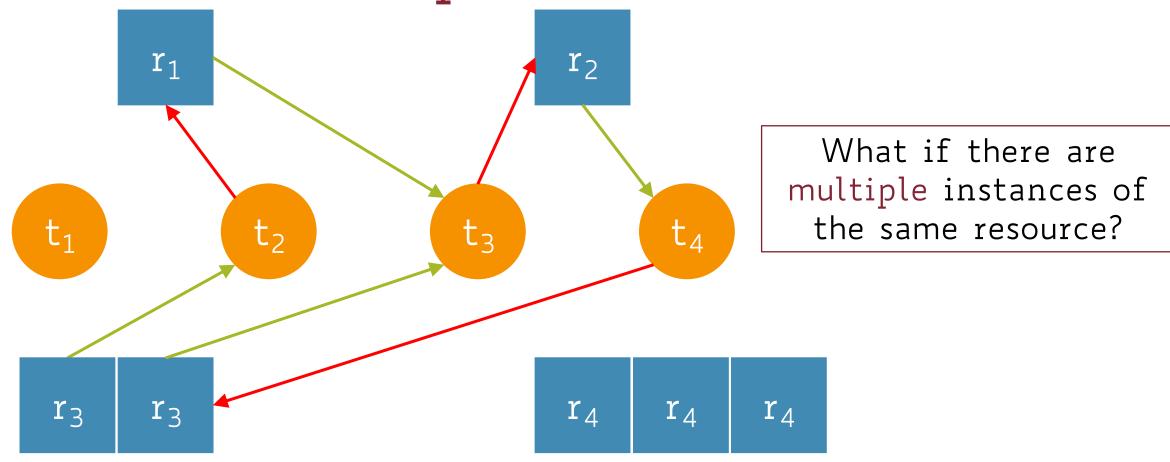




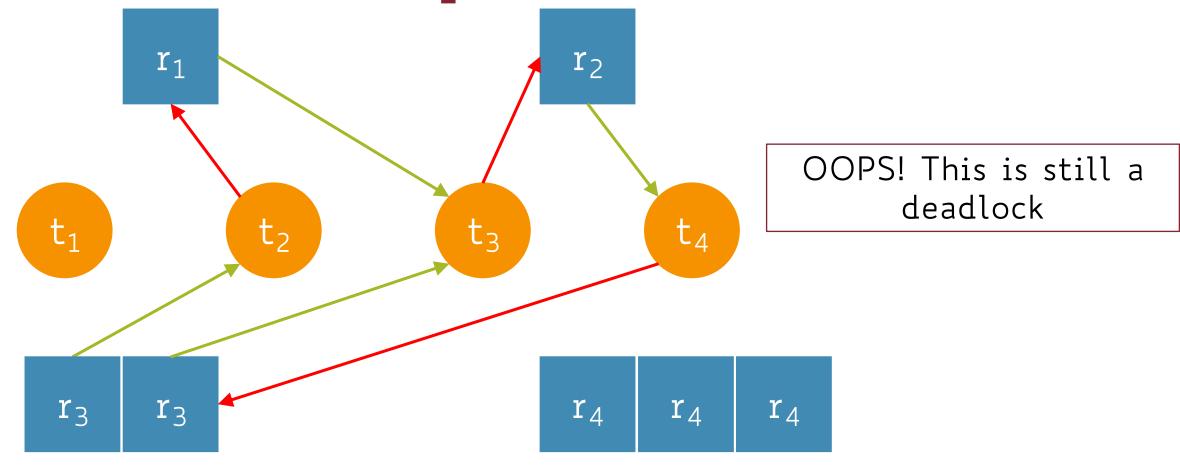
If the graph has cycles, deadlock might exist

We are assuming the multiplicity of each resource is 1 (i.e., one r_1 , one r_2 , etc.)

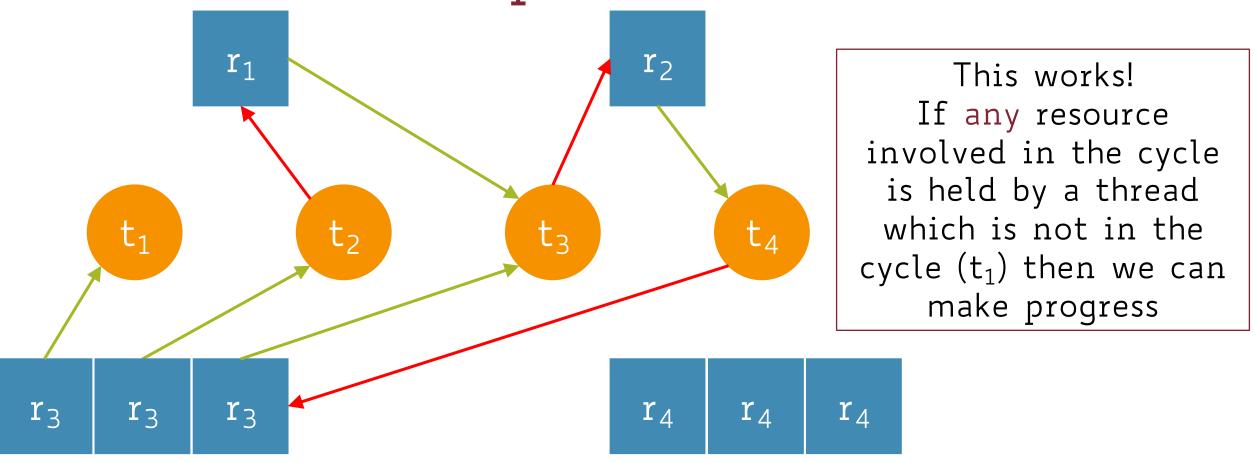
Deadlock Detection: Resource Allocation Graph



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- We would like to be more precise than that...

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- Known algorithms based on $depth-first\ search\ (DFS)$ take O(|V|+|E|) time
- $O(|V|+|E|) \sim O(|V|^2)$ as $|E| = O(|V|^2)$ for dense graphs, and |V| = #threads + #resources

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 - Before granting a resource \rightarrow each granted request will take $O(|V|^2)$
 - When a request cannot be fulfilled \rightarrow each failed request will take $O(|V|^2)$
 - On a regular schedule or when the CPU is under-utilized

Our Journey

- What is deadlock?
- Conditions for deadlock to happen
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- Ensure that *at least one* of the 4 necessary conditions doesn't hold
 - Mutual Exclusion → make all resources sharable
 - Not all can be shared
 - E.g., disks, printers, etc.

- Ensure that *at least one* of the 4 necessary conditions doesn't hold
 - Hold and Wait → a thread cannot hold one resource when it requests another
 - Enforce requests to be made all at once
 - Hard to predict all the resources a thread will need

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- Ensure that *at least one* of the 4 necessary conditions doesn't hold
 - No Preemption → if a thread requests a resource that cannot be allocated to it, the OS preempts (releases) all the resources that the thread is already holding
 - Not all resources can be easily preempted (e.g., printers)

- Ensure that *at least one* of the 4 necessary conditions doesn't hold
 - Circular Wait → impose an ordering (i.e., numbering) on resources and enforce to request them in such order
 - Hard to establish such an order

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Deadlock Avoidance: Resource Reservation

Each thread provides information about the maximum number of resources it might need during execution

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m_i = maximum number of resources that thread i might request c_i = current number of resources that thread i is holding C = \sum_{i=1}^{n} c_i = total number of resources currently allocated R = maximum number of resources overall available
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Any thread sequence is safe if for each thread it holds that:

$$\underbrace{m_i - c_i}_{\text{resources } t_i \text{ might still request}} \leq \underbrace{R - C}_{\text{resources currently available}} + \underbrace{\sum_{j=1}^{i} c_j}_{\text{resources currently allocated up to } t_i, j < i}$$

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- This policy ensures no circular-wait condition exists

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t_1	4	3	1
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Is the current state safe?

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The current state is safe: there exists a sequence of threads (t_1, t_2, t_3) where each one gets the maximum number of resources without waiting

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 t_2 can use the current allocation, plus t_1 's resources and 1 drive left (4 drives)

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 t_3 can use the current allocation, plus t_1 's & t_2 's resources and 1 drive left (8 drives)

Thread	m_{i}	c _i	m_i – c_i
t ₁	4	3	1
t_2	8	4	4
t ₃	12	5	7

Suppose t₃ requests one more drive, then now there are no more available drives

Thread	m _i	c _i	m_i – c_i
t_1	4	3	1
t ₂	8	4	4
t ₃	12	5	7

Suppose t₃ requests one more drive, then now there are no more available drives

Theoretically, everything might still work (e.g., t₁ may never request another drive)

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t ₂	8	4	4
t ₃	12	5	7

Suppose t₃ requests one more drive, then now there are no more available drives

Theoretically, everything might still work (e.g., t₁ may never request another drive)

However, t₃ must wait because allocating that extra drive would lead to an unsafe state, which in turn might lead to deadlock

• An extension of the original resource allocation graph

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- Edges can now be of 3 types:
 - Request Edge \rightarrow a directed edge (t_i, r_j) indicates that t_i has requested r_j , but not yet acquired
 - Claim (dotted) Edge \rightarrow a directed edge (t_i, r_j) indicates that t_i might request r_j in the future
 - Assignment Edge \rightarrow a directed edge (r_j, t_i) indicates that the OS has allocated r_j to t_i

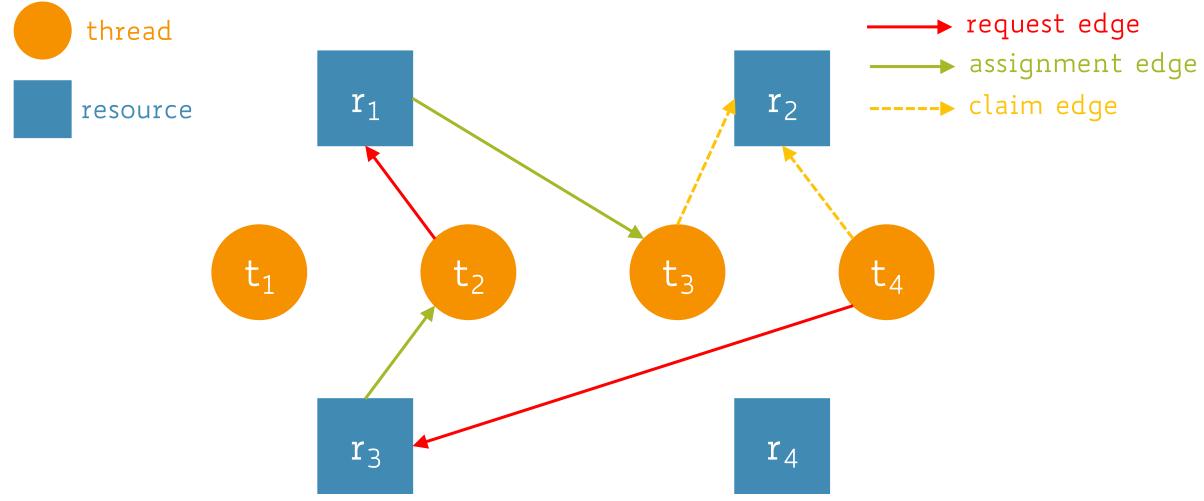
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 - Assignment Edge \rightarrow a directed edge (r_j, t_i) indicates that the OS has allocated r_j to t_i
- Satisfying a request means converting a claim into an assignment edge

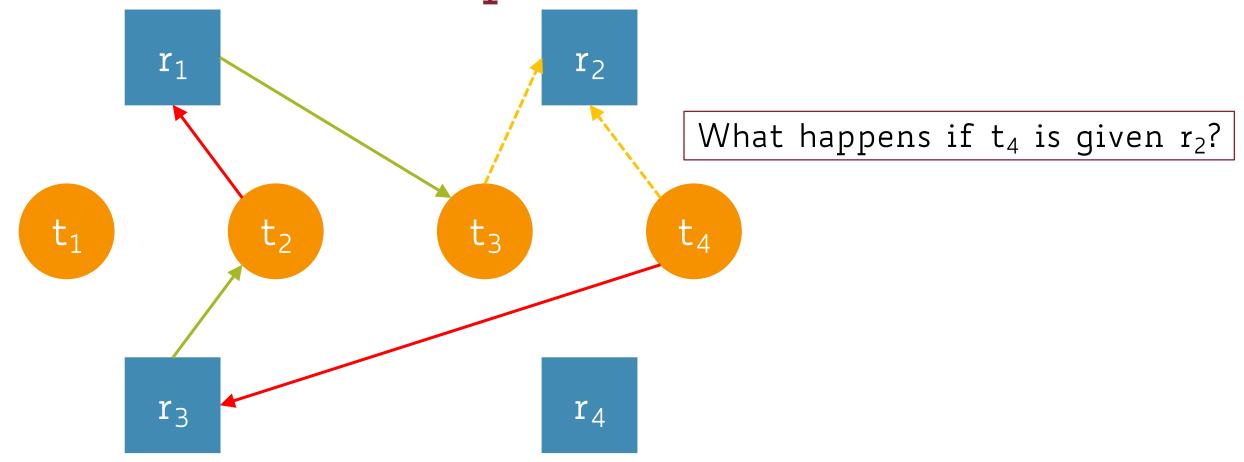
• A cycle in this extended RAG indicates an unsafe state

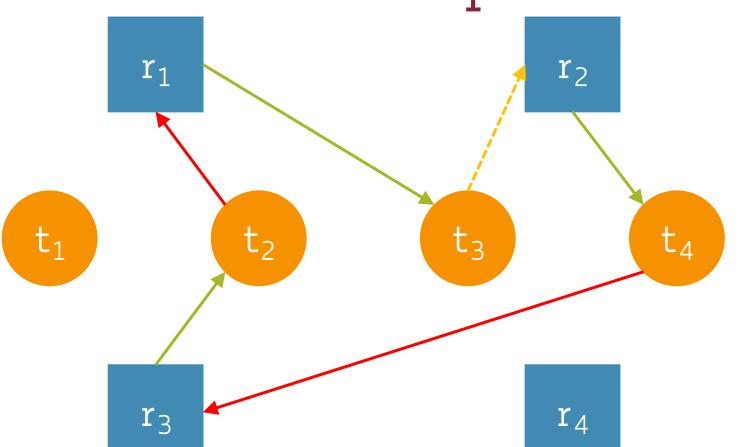
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- In other words, the claim edge is converted into a request edge and the thread will wait

- A cycle in this extended RAG indicates an unsafe state
- If the allocation results in an unsafe state, this will be denied even if the resource is actually available
- In other words, the claim edge is converted into a request edge and the thread will wait
- NOTE: This solution does not work when there are multiple instances of the *same* resource

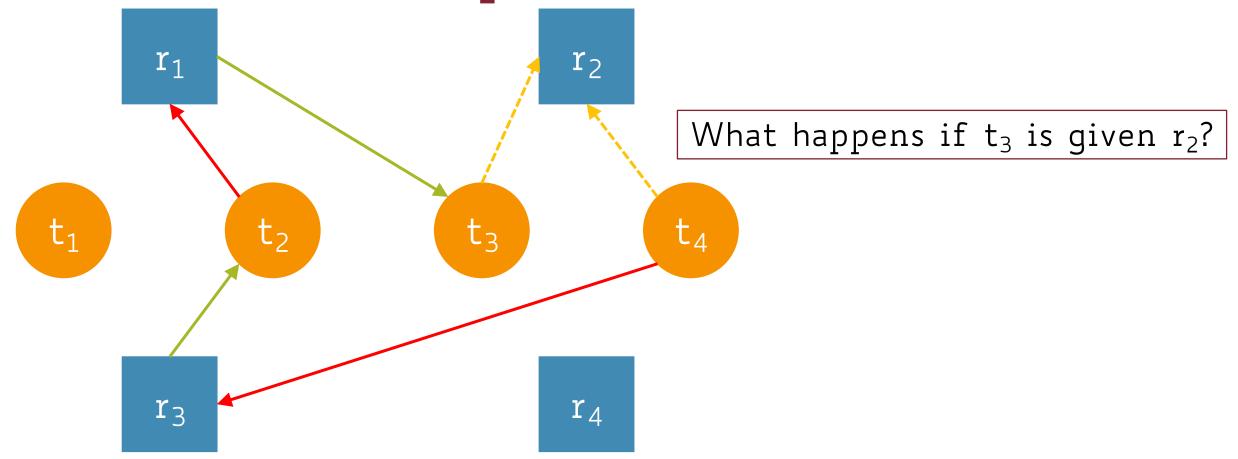


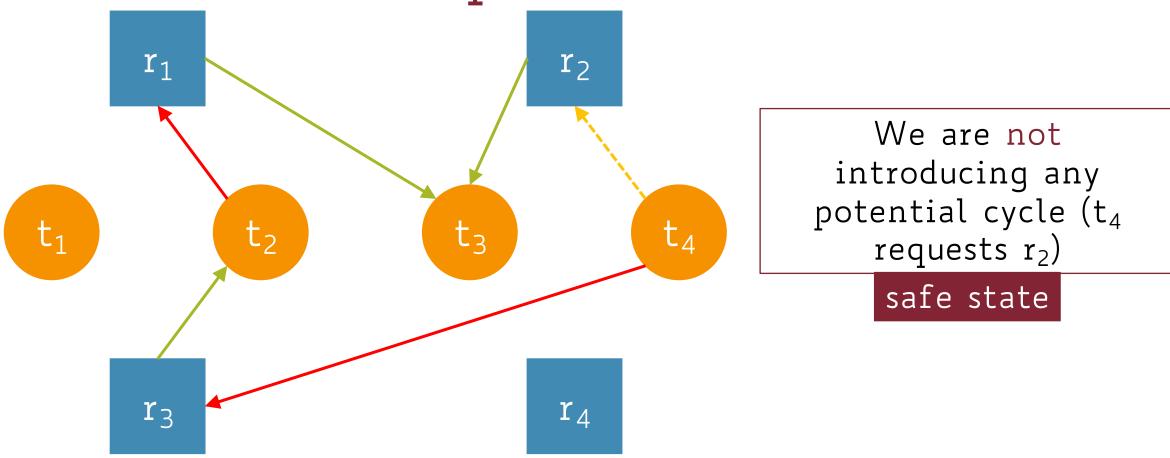


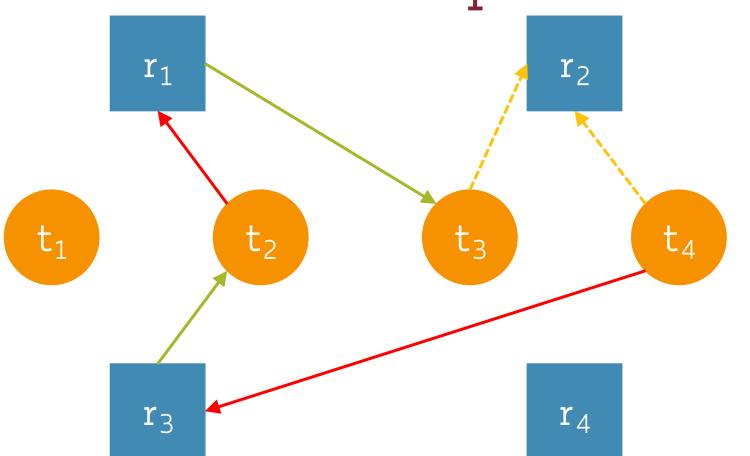


We are introducing a potential cycle (t₃ requests r₂), which in turn might cause deadlock

unsafe state







Start from a safe state

Invariant

Accept a request iff we move from a safe state to another

Banker's Algorithm

- Handles multiple instances of the same resource
- Forces threads to provide information on what resource they might need, in advance
- The resources requested must not exceed the total available in the system
- The algorithm allocates resources to a requesting thread if the allocation leaves the system in a safe state, otherwise the thread waits

Banker's Algorithm: Data Structures

- n = number of threads; m = number of resource types
- available[1..m]: m-dimensional vector
 - available[j] = k means there are k resources of type j available
- max[1..n, 1..m]: n x m matrix
 - max[i, j] = k means thread i may require at most k resources of type j
- allocation[1..n, 1..m]: n x m matrix
 - allocation[i, j] = k means thread i has allocated k resources of type j
- need[1..n, 1..m]: n x m matrix
 - need[i, j] = max[i, j] allocation[i, j] = k means thread i may need k more resources of type j to complete its task

Banker's Algorithm: Idea

- The algorithm is divided in 2 tasks:
 - isSafeState → given the current status of allocation of resources, tests if this is a safe state
 - resourceRequest → given a thread and its resource request decides if such a request can be satisfied

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Banker's Algorithm: Idea

- The algorithm is divided in 2 tasks:
 - isSafeState → given the current status of allocation of resources, tests if this is a safe state
 - resourceRequest → given a thread and its resource request decides if such a request can be satisfied
- A request can be satisfied iff this leads to a safe state!
- In other words, the second tasks uses the output of the first one in order to make a decision

Banker's Algorithm: isSafeState

1. Let work and finish be vectors of length m and n, respectively

```
Initialize: work = available; finish[i] = false; for all i
```

2. Find an i such that:

```
finish[i] = false && need[i] ≤ work

If no such i exists, go to step 4.
```

3. Assume thread i executes:

```
work = work + allocation[i]; finish[i] = true; go to step 2.
```

4. If finish[i] == true for all i, the system is in a safe state

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Banker's Algorithm: requestResource

Input: i (thread) and request an m-dimensional vector of requests

- 1. If request > need[i] raise an error as thread i is attempting to request more resources that it claimed, otherwise go to step 2.
- 2. If request > available thread i must wait since resources are not available, otherwise go to step 3.
- 3. Even if resources are available, test if this allocation will
 lead to a safe state by simulating it
 available -= request; allocation[i] += request; need[i] -= request;
 isSafeState() ? OK : rollback() and wait()

A snapshot of the current state of the system

					RES	SOUR	CES			
			MAX		ALL	OCAT	ION	AVAILABLE		
		А	В	С	Α	В	С	Α	В	С
T H	To	0	0	1	0	0	1			
R	T ₁	1	7	5	1	0	0			
E A	T ₂	2	3	5	1	3	5			
D S	T ₃	0	6	5	0	6	3			
	Total				2	9	9	1	5	2

Q1: How many resources of type A, B, and C are there overall?

					RES	SOUR	CES			
			MAX		ALL	OCAT	ION	AV	AILAE	BLE
		Α	В	С	Α	В	С	Α	В	С
T H	T _O	0	0	1	0	0	1			
R	T ₁	1	7	5	1	0	0			
E A	T ₂	2	3	5	1	3	5			
D S	T ₃	0	6	5	0	6	3			
	Total				2	9	9	1	5	2

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					RES	SOUR	CES			
			MAX		ALL	OCAT	ION	AVAILABLE		
		Α	В	С	Α	В	С	Α	В	С
T H	To	0	0	1	0	0	1			
R	T ₁	1	7	5	1	0	0			
E A	T ₂	2	3	5	1	3	5			
D S	T ₃	0	6	5	0	6	3			
	Total				2	9	9	1	5	2

Q2: What is the content of the NEED matrix?

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE	NEED		
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1						
R	T ₁	1	7	5	1	0	0						
E A	T ₂	2	3	5	1	3	5						
D S	T ₃	0	6	5	0	6	3						
	Total				2	9	9	1	5	2			

Q2: What is the content of the NEED matrix?

NEED[i, j] = MAX[i, j] - ALLOCATION[i, j]

					RES	OUR	CES						
			MAX		ALL	OCAT	ION	AV	'AILAE	BLE	NEED		
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1						
R	T ₁	1	7	5	1	0	0						
E A	T ₂	2	3	5	1	3	5						
E A D S	T ₃	0	6	5	0	6	3						
	Total				2	9	9	1	5	2			

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NEED[i, j] = MAX[i, j] - ALLOCATION[i, j]

					RES	SOUR	CES						
		MAX ALLOCATION AVAILABLE								BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				O-O =		
R	T ₁	1	7	5	1	0	0						
E A	T ₂	2	3	5	1	3	5						
D S	T ₃	0	6	5	0	6	3						
	Total				2	9	9	1	5	2			

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NEED[i, j] = MAX[i, j] - ALLOCATION[i, j]

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE	NEED		
		А	В	С	А	В	С	Α	В	С	А	В	С
T H	To	0	0	1	0	0	1				0	O-O = O	
R	T ₁	1	7	5	1	0	0						
E A	T ₂	2	3	5	1	3	5						
D S	T ₃	0	6	5	0	6	3						
	Total				2	9	9	1	5	2			

Q2: What is the content of the NEED matrix?

NEED[i, j] = MAX[i, j] - ALLOCATION[i, j]

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	'AILAE	3LE	NEED		
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	1-1 = O
R	T ₁	1	7	5	1	0	0						
E A	T ₂	2	3	5	1	3	5						
D S	T ₃	0	6	5	0	6	3						
	Total				2	9	9	1	5	2			

Q2: What is the content of the NEED matrix?

NEED[i, j] = MAX[i, j] - ALLOCATION[i, j]

				RES										
		MAX			ALL	ALLOCATION			AVAILABLE			NEED		
		А	В	С	Α	В	С	Α	В	С	А	В	С	
T H	To	0	0	1	0	0	1				0	0	0	
R	T ₁	1	7	5	1	0	0				0	7	5	
E A	T ₂	2	3	5	1	3	5				1	0	0	
D S	T ₃	0	6	5	0	6	3				0	0	2	
	Total				2	9	9	1	5	2				

Q3: Is the system in a safe state? Why?

		RESOURCES											
		MAX			ALLOCATION			AVAILABLE			NEED		
		Α	А В С		Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R T ₁	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

Let's start with To

			RESOURCES										
		MAX			ALLOCATION			AVAILABLE			NEED		
		АВС		Α	В	С	Α	В	С	А	В	С	
$ \begin{array}{c} T \\ H \\ R \\ R \\ E \\ A \\ D \\ S \\ \end{array} $ $ \begin{array}{c} T_0 \\ T_1 \\ T_2 \\ T_3 \end{array} $	T _O	0	0	1	0	0	1				0	0	0
	T ₁	1	7	5	1	0	0				0	7	5
	T ₂	2	3	5	1	3	5				1	0	0
	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

Eventually, To finishes and releases all its resources

			MAX		ALLOCATION			AVAILABLE			NEED		
		А	В	С	Α	В	С	Α	В	С	А	В	С
$ \begin{array}{c} T \\ H \\ R \\ R \\ E \\ A \\ D \\ S \end{array} $ $ \begin{array}{c} T_0 \\ T_1 \\ T_2 \\ T_3 \end{array} $	To	0	0	1	0	0	1				0	0	0
	T ₁	1	7	5	1	0	0				0	7	5
	T ₂	2	3	5	1	3	5				1	0	0
	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

 T_1 can't execute as it still might NEED (0, 7, 5) and AVAILABLE = (1, 5, 3)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	A B CO O 1			В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	_	-				-	_	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	8	1	5	3			

 T_2 can execute as it still might NEED (1, 0, 0) and AVAILABLE = (1, 5, 3)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	A B CO O 1			В	С	Α	В	С	А	В	С
T H	To	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	8	1	5	3			

 T_2 can execute as it still might NEED (1, 0, 0) and AVAILABLE = (1, 5, 3)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	3LE		NEED	
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	2	3	5				0	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				3	9	8	0	5	3			

T₂ eventually finishes and releases all its resources

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	T ₀	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				1	6	3	2	8	8			

 T_3 can execute as it still might NEED (0, 0, 2) and AVAILABLE = (2, 8, 8)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	3LE		NEED	
		А				В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	-	-	-				-	_	-
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				1	6	3	2	8	8			

 T_3 can execute as it still might NEED (0, 0, 2) and AVAILABLE = (2, 3, 6)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	/AILAB	3LE		NEED	
		А	В	С	Α	В	С	А	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	0	6	5				0	0	0
	Total				1	6	5	2	8	6			

T₃ eventually finishes and releases all its resources

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	'AILAE	3LE		NEED	
		А	A B C O 1			В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	-	-	_				-	-	-
D S	T ₃	0	6	5	-	-	-				-	-	-
	Total				1	0	0	2	14	11			

 T_1 can now execute since NEED (0, 7, 5) and AVAILABLE = (2, 14, 11)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	A B C O 0 1			В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	_	-
R	T_1	1	7	5	1	7	5				0	0	0
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	-	-	-				-	-	-
	Total				1	7	5	2	7	6			

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We have found a sequence of execution T_0 , T_2 , T_3 , T_1 which leads to safe state!

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	-	_	-				-	-	-
R	T ₁	1	7	5	-	-	-				-	-	-
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	-	_	-				-	_	-
	Total				-	_	-	3	14	11			

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Q4: If T_1 issues a REQUEST (0, 5, 2), can this be granted immediately?

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	'AILAE	BLE		NEED	
		А	A B C 0 1			В	С	Α	В	С	А	В	С
T H	То	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

We have to ask ourselves: 1. if the request can be satisfied; 2. if it will lead to a safe state

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

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To answer 1. check if: a. REQUEST <= NEED and b. REQUEST <= AVAILABLE

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	A B C O 0 1			В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

1.a. REQUEST <= NEED?

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	То	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

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1.a. REQUEST <= NEED? YES! (0, 5, 2) <= (0, 7, 5)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	A B C O 1			В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

1.b. REQUEST <= AVAILABLE?

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	То	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

1.b. REQUEST <= AVAILABLE? YES! (0, 5, 2) <= (1, 5, 2)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	В	С	Α	В	С	А	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

To answer 2. we simulate the request is granted and see if we are still in a safe state

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	0	0				0	7	5
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	9	9	1	5	2			

To answer 2. we simulate the request is granted and see if we are still in a safe state

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	'AILAE	3LE		NEED	
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	14	11	1	0	0			

Let's start with T₀

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	В	С	А	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	0	0	1				0	0	0
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	14	11	1	0	0			

Eventually, To finishes and releases all its resources

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	14	10	1	0	1			

 T_1 can't execute as it still might NEED (0, 2, 3) and AVAILABLE = (1, 0, 1)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	3LE		NEED	
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	_	-				-	-	-
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	14	10	1	0	1			

 T_2 can execute as it still might NEED (1, 0, 0) and AVAILABLE = (1, 0, 1)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	3LE		NEED	
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	To	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	1	3	5				1	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				2	14	10	1	0	1			

 T_2 can execute as it still might NEED (1, 0, 0) and AVAILABLE = (1, 0, 1)

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	В	С	Α	В	С	А	В	С	А	В	С
T H	To	0	0	1	-	_	-				-	-	-
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	2	3	5				0	0	0
D S	T ₃	0	6	5	0	6	3				0	0	2
	Total				3	14	10	0	0	1			

T₂ eventually finishes and releases all its resources

					RES	SOUR	CES						
			MAX		ALL	OCAT	ION	AV	AILAE	BLE		NEED	
		А	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	-	_				-	-	-
R	T ₁	1	7	5	1	5	2				0	2	3
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	Ο	6	3				0	0	2
	Total				1	11	5	2	3	6			

 T_3 can execute as it still might NEED (0, 0, 2) and AVAILABLE = (2, 3, 6)

		RESOURCES												
			MAX			ALLOCATION			AVAILABLE			NEED		
		А	В	С	Α	В	С	А	В	С	А	В	С	
T H	To	0	0	1	-	-	-				-	-	-	
R	T ₁	1	7	5	1	5	2				0	2	3	
E A	T ₂	2	3	5	_	-	_				-	-	-	
D S	T ₃	0	6	5	0	6	3				0	0	2	
	Total				1	11	5	2	3	6				

 T_3 can execute as it still might NEED (0, 0, 2) and AVAILABLE = (2, 3, 6)

			RESOURCES											
			MAX			ALLOCATION			AVAILABLE			NEED		
		А	В	С	А	В	С	А	В	С	А	В	С	
T H	T _O	0	0	1	-	-	-				-	-	_	
R	T ₁	1	7	5	1	5	2				0	2	3	
E A	T ₂	2	3	5	-	-	-				-	-	-	
D S	T ₃	0	6	5	0	6	5				0	0	0	
	Total				1	11	7	2	3	4				

T₃ eventually finishes and releases all its resources

					RES	RESOURCES								
			MAX			ALLOCATION			AVAILABLE			NEED		
		А	В	С	Α	В	С	Α	В	С	А	В	С	
T H	T _O	0	0	1	-	-	-				-	-	-	
R	T ₁	1	7	5	1	5	2				0	2	3	
E A	T ₂	2	3	5	-	-	_				_	-	-	
D S	T ₃	0	6	5	-	-	-				-	-	-	
	Total				1	5	2	2	9	9				

 T_1 can now execute since NEED (0, 2, 3) and AVAILABLE = (2, 9, 9)

		RESOURCES											
		MAX		ALLOCATION			AVAILABLE			NEED			
		Α	В	С	Α	В	С	Α	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	1	7	5				0	0	0
E A	T ₂	2	3	5	_	-	-				-	-	-
D S	T ₃	0	6	5	_	_	-				-	-	-
	Total				1	7	5	2	7	6			

We have found a sequence of execution T_0 , T_2 , T_3 , T_1 which leads to safe state!

	RESOURCES												
		MAX		ALLOCATION			AVAILABLE			NEED			
		Α	В	С	Α	В	С	А	В	С	А	В	С
T H	T _O	0	0	1	-	-	-				-	-	-
R	T ₁	1	7	5	-	-	-				-	-	-
E A	T ₂	2	3	5	-	-	-				-	-	-
D S	T ₃	0	6	5	_	_	_				-	-	-
	Total				-	-	-	3	14	11			

 Deadlock → a situation in which a set of threads/processes cannot proceed because each one requires resources held by another

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- Detection and Recovery → recognize deadlock after it has occurred and break it
- Prevention → design resource allocation strategies which guarantee at least one of the 4 necessary deadlock conditions never holds
- Avoidance > runtime checks to avoid deadlock online

In practice, most OSs don't do anything and leave it all to applications

