1. Description

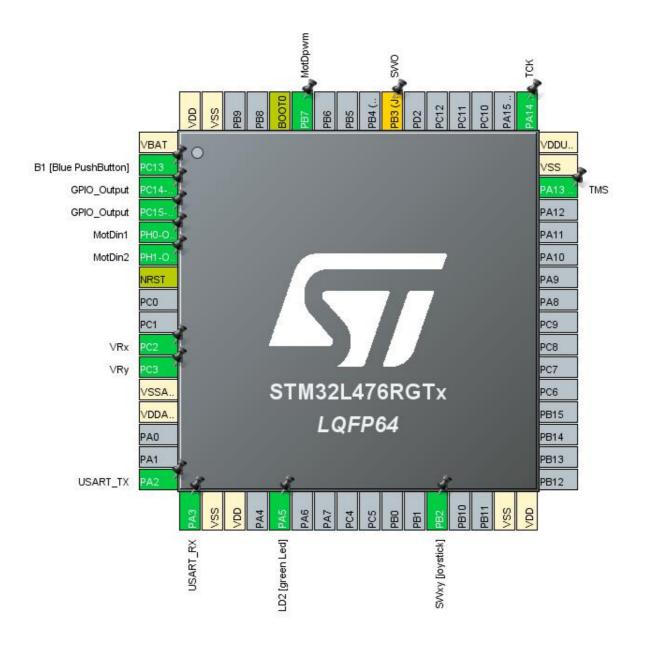
1.1. Project

Project Name	yRobot
Board Name	NUCLEO-L476RG
Generated with:	STM32CubeMX 5.6.0
Date	09/21/2020

1.2. MCU

MCU Series	STM32L4
MCU Line	STM32L4x6
MCU name	STM32L476RGTx
MCU Package	LQFP64
MCU Pin number	64

2. Pinout Configuration



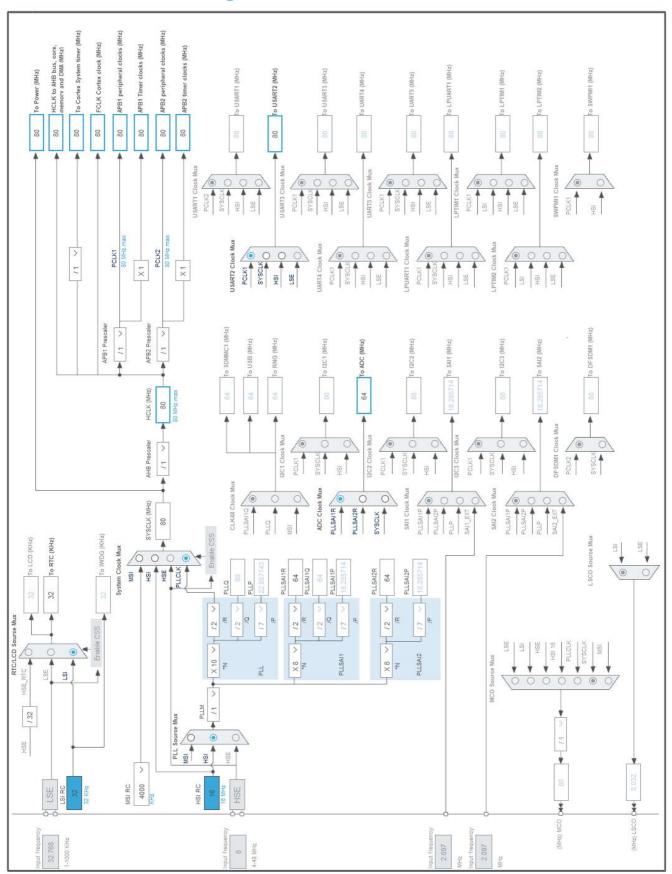
3. Pins Configuration

Pin Number	Pin Name	Pin Type	Alternate	Label	
LQFP64	(function after		Function(s)		
	reset)				
1	VBAT	Power			
2	PC13	I/O	GPIO_EXTI13	B1 [Blue PushButton]	
3	PC14-OSC32_IN (PC14) *	I/O	GPIO_Output		
4	PC15-OSC32_OUT (PC15) *	I/O	GPIO_Output		
5	PH0-OSC_IN (PH0) *	I/O	GPIO_Output	MotDin1	
6	PH1-OSC_OUT (PH1) *	I/O	GPIO_Output	MotDin2	
7	NRST	Reset			
10	PC2	I/O	ADC1_IN3	VRx	
11	PC3	I/O	ADC1_IN4	VRy	
12	VSSA/VREF-	Power			
13	VDDA/VREF+	Power			
16	PA2	I/O	USART2_TX	USART_TX	
17	PA3	I/O	USART2_RX	USART_RX	
18	VSS	Power			
19	VDD	Power			
21	PA5 *	I/O	GPIO_Output	LD2 [green Led]	
28	PB2	I/O	GPIO_EXTI2	SWxy [joystick]	
31	VSS	Power			
32	VDD	Power			
46	PA13 (JTMS-SWDIO)	I/O	SYS_JTMS-SWDIO	TMS	
47	VSS	Power			
48	VDDUSB	Power			
49	PA14 (JTCK-SWCLK)	I/O	SYS_JTCK-SWCLK	TCK	
55	PB3 (JTDO-TRACESWO) **	I/O	SYS_JTDO-SWO	SWO	
59	PB7	I/O	TIM4_CH2	MotDpwm	
60	BOOT0	Boot			
63	VSS	Power			
64	VDD	Power			

^{*} The pin is affected with an I/O function

^{**} The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



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5. Software Project

5.1. Project Settings

Name	Value	
Project Name	yRobot	
Project Folder	D:\GitDepots\yRobot	
Toolchain / IDE	TrueSTUDIO	
Firmware Package Name and Version	STM32Cube FW_L4 V1.15.1	

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	Yes
consumption)	

6. Power Consumption Calculator report

6.1. Microcontroller Selection

Series	STM32L4
Line	STM32L4x6
мси	STM32L476RGTx
Datasheet	025976_Rev4

6.2. Parameter Selection

Temperature	25
IVAA	3.0

6.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

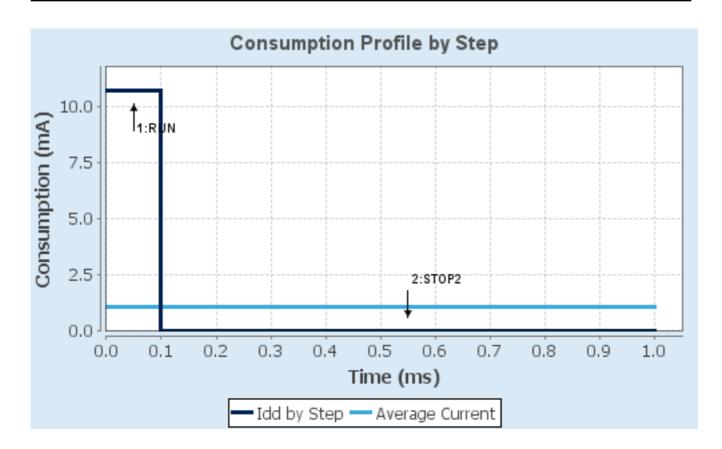
6.4. Sequence

Step	Step1	Step2	
Mode	RUN	STOP2	
Vdd	3.0	3.0	
Voltage Source	Battery	Battery	
Range	Range1-High	NoRange	
Fetch Type	SRAM2	n/a	
CPU Frequency	80 MHz	0 Hz	
Clock Configuration	HSE PLL	ALL CLOCKS OFF	
Clock Source Frequency	4 MHz	0 Hz	
Peripherals			
Additional Cons.	0 mA	0 mA	
Average Current	10.7 mA	1.18 μΑ	
Duration	0.1 ms	0.9 ms	
DMIPS	100.0	0.0	
Ta Max	103.56	105	
Category	In DS Table	In DS Table	

6.5. RESULTS

Sequence Time	1 ms	Average Current	1.07 mA
Battery Life	4 months, 10	Average DMIPS	100.0 DMIPS
	days. 3 hours		

6.6. Chart



7. IPs and Middleware Configuration 7.1. ADC1

IN3: IN3 Single-ended IN4: IN4 Single-ended

7.1.1. Parameter Settings:

ADCs_Common_Settings:

Mode Independent mode

ADC_Settings:

Clock Prescaler Asynchronous clock mode divided by 1

Resolution ADC 12-bit resolution
Data Alignment Right alignment

Scan Conversion Mode Enabled

Continuous Conversion Mode Discontinuous Conversion Mode Enabled *

Number Of Discontinuous Conversions

DMA Continuous Requests Enabled *

End Of Conversion Selection End of sequence of conversion *

Overrun behaviour Overrun data preserved

Low Power Auto Wait Disabled

ADC_Regular_ConversionMode:

Enable Regular Conversions Enable
Enable Regular Oversampling Disable
Number Of Conversion 2 *

External Trigger Conversion Source Timer 1 Trigger Out event *

External Trigger Conversion Edge Trigger detection on the rising edge

Rank

Channel 3

Sampling Time 6.5 Cycles *

Offset Number No offset

<u>Rank</u> 2 *

Channel 4 *
Sampling Time 6.5 Cycles *

Offset Number No offset

ADC_Injected_ConversionMode:

Enable Injected Conversions Disable

Analog Watchdog 1:

Enable Analog WatchDog1 Mode false

Analog Watchdog 2:

Enable Analog WatchDog2 Mode false

Analog Watchdog 3:

Enable Analog WatchDog3 Mode false

7.2. GPIO

7.3. RTC

mode: Activate Clock Source

mode: Activate Calendar
Alarm A: Internal Alarm A
7.3.1. Parameter Settings:

General:

Hour Format Hourformat 24

Asynchronous Predivider value 127 Synchronous Predivider value 255

Calendar Time:

Data Format BCD data format

Hours 12 *
Minutes 0
Seconds 0

Day Light Saving: value of hour adjustment Daylightsaving None

Store Operation Storeoperation Set *

Calendar Date:

Week Day Saturday *
Month August *

Date 1
Year 20 *

Alarm A:

 Hours
 12 *

 Minutes
 12 *

 Seconds
 1 *

 Sub Seconds
 0

Alarm Mask Date Week day

Alarm Mask Hours

Enable *

Alarm Mask Minutes Enable *

Alarm Mask Seconds Disable

Alarm Sub Second Mask All Alarm SS fields are masked.

Alarm Date Week Day Sel Date
Alarm Date 1

7.4. SYS

Debug: Serial Wire

Timebase Source: TIM6

7.5. TIM1

Clock Source : Internal Clock

7.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 19999 *

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 1999 *

Internal Clock Division (CKD)

No Division

Repetition Counter (RCR - 8 bits value) 0

auto-reload preload Enable *

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Update Event *

Trigger Event Selection TRGO2 Reset (UG bit from TIMx_EGR)

7.6. TIM4

Channel2: PWM Generation CH2

7.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 8000-1 *

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 100-1 *

Internal Clock Division (CKD)

No Division

auto-reload preload Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx_EGR)

Clear Input:

Clear Input Source Disable

PWM Generation Channel 2:

Mode PWM mode 1

Pulse (16 bits value) 5 *

Output compare preload Enable

Fast Mode Disable

CH Polarity High

7.7. USART2

Mode: Asynchronous

7.7.1. Parameter Settings:

Basic Parameters:

Baud Rate 921600 *

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

Advanced Features:

Auto Baudrate Disable TX Pin Active Level Inversion Disable **RX Pin Active Level Inversion** Disable **Data Inversion** Disable TX and RX Pins Swapping Disable Overrun Enable DMA on RX Error Enable MSB First Disable

7.8. FREERTOS

Interface: CMSIS_V2

7.8.1. Config parameters:

API:

FreeRTOS API CMSIS v2

Versions:

FreeRTOS version 10.2.1 CMSIS-RTOS version 2.00

MPU/FPU:

ENABLE_MPU Disabled ENABLE_FPU Disabled

Kernel settings:

USE_PREEMPTION Enabled

CPU_CLOCK_HZ SystemCoreClock

TICK_RATE_HZ

MAX_PRIORITIES

56

MINIMAL_STACK_SIZE

MAX_TASK_NAME_LEN

USE_16_BIT_TICKS

IDLE_SHOULD_YIELD

USE_MUTEXES

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USE_MUTEXES Enabled
USE_RECURSIVE_MUTEXES Enabled
USE_COUNTING_SEMAPHORES Enabled
QUEUE_REGISTRY_SIZE 8

USE_TICKLESS_IDLE Built in functionality enabled *

USE_TASK_NOTIFICATIONS Enabled

RECORD_STACK_HIGH_ADDRESS Enabled *

Memory management settings:

Memory Allocation Dynamic / Static

TOTAL_HEAP_SIZE 27000 *
Memory Management scheme heap_4

Hook function related definitions:

USE_IDLE_HOOK Enabled *
USE_TICK_HOOK Disabled
USE_MALLOC_FAILED_HOOK Disabled

USE_DAEMON_TASK_STARTUP_HOOK Enabled * CHECK_FOR_STACK_OVERFLOW Option2 *

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS Enabled * Enabled USE_TRACE_FACILITY USE_STATS_FORMATTING_FUNCTIONS Enabled *

Co-routine related definitions:

USE_CO_ROUTINES Disabled MAX_CO_ROUTINE_PRIORITIES 2

Software timer definitions:

USE_TIMERS Enabled TIMER_TASK_PRIORITY TIMER_QUEUE_LENGTH 10 TIMER_TASK_STACK_DEPTH

Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY 15 LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY

Added with 10.2.1 support:

MESSAGE_BUFFER_LENGTH_TYPE size_t USE_POSIX_ERRNO Disabled

7.8.2. Include parameters:

Include definitions:

vTaskPrioritySet uxTaskPriorityGet Enabled vTaskDelete Enabled vTaskCleanUpResources Enabled * Enabled vTaskSuspend vTaskDelayUntil Enabled Enabled vTaskDelay xTaskGetSchedulerState Enabled xTaskResumeFromISR Enabled xQueueGetMutexHolder Enabled xSemaphoreGetMutexHolder Disabled pcTaskGetTaskName Enabled * Enabled uxTaskGetStackHighWaterMarkxTaskGetCurrentTaskHandle Enabled * Enabled eTaskGetState xEventGroupSetBitFromISR Disabled

Enabled

xTimerPendFunctionCallEnabledxTaskAbortDelayDisabledxTaskGetHandleEnabled *uxTaskGetStackHighWaterMark2Disabled

7.8.3. Advanced settings:

Newlib settings (see parameter description first):

USE_NEWLIB_REENTRANT Disabled

Project settings (see parameter description first):

Use FW pack heap file Enabled

^{*} User modified value

8. System Configuration

8.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PC2	ADC1_IN3	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	VRx
	PC3	ADC1_IN4	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	VRy
SYS	PA13 (JTMS- SWDIO)	SYS_JTMS- SWDIO	n/a	n/a	n/a	TMS
	PA14 (JTCK- SWCLK)	SYS_JTCK- SWCLK	n/a	n/a	n/a	тск
TIM4	PB7	TIM4_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MotDpwm
USART2	PA2	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	USART_TX
	PA3	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	USART_RX
Single Mapped Signals	PB3 (JTDO- TRACESWO)	SYS_JTDO- SWO	n/a	n/a	n/a	SWO
GPIO	PC13	GPIO_EXTI13	External Interrupt	No pull-up and no pull-down	n/a	B1 [Blue PushButton]
			Mode with Falling			
			edge trigger detection			
	PC14- OSC32_IN (PC14)	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PC15- OSC32_OU T (PC15)	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PH0- OSC_IN (PH0)	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MotDin1
	PH1- OSC_OUT (PH1)	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MotDin2
	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD2 [green Led]
	PB2	GPIO_EXTI2	External Interrupt	Pull-up *	n/a	SWxy [joystick]
			Mode with Falling			
			edge trigger detection			

yRobot Projec
Configuration Repor

8.2. DMA configuration

DMA request	Stream	Direction	Priority
ADC1	DMA1_Channel1	Peripheral To Memory	Medium *

ADC1: DMA1_Channel1 DMA request Settings:

Mode: Circular *

Peripheral Increment: Disable

Memory Increment: Enable *

Peripheral Data Width: Word *

Memory Data Width: Word *

8.3. NVIC configuration

			0.151.1
Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Prefetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
EXTI line2 interrupt	true	5	0
DMA1 channel1 global interrupt	true	5	0
ADC1 and ADC2 interrupts	true	5	0
TIM1 trigger and commutation interrupts and TIM17 global interrupt	true	5	0
USART2 global interrupt	true	5	0
EXTI line[15:10] interrupts	true	5	0
RTC alarm interrupt through EXTI line 18	true	5	0
TIM6 global interrupt, DAC channel1 and channel2 underrun error interrupts	true	0	0
PVD/PVM1/PVM2/PVM3/PVM4 interrupts through EXTI lines 16/35/36/37/38	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
TIM1 break interrupt and TIM15 global interrupt	unused		
TIM1 update interrupt and TIM16 global interrupt	unused		
TIM1 capture compare interrupt	unused		
TIM4 global interrupt	unused		
FPU global interrupt	unused		

^{*} User modified value

9. Predefined Views - Category view: Current



10. Software Pack Report

10.1. Software Pack selected

Vendor	Name	Version	Component
STMicroelectronic	FreeRTOS	0.0.1	Class : RTOS
s			Group : Core
			Version : 10.2.0