

# 6.5 The Riemann-Stieltjes Integral

## 1. Motivation

The Riemann-Stieltjes integral unifies discrete summations and continuous integrals into a single mathematical framework.

- **Example (Moment of Inertia  $I$ ):**

- **Discrete:** System of  $n$  masses  $m_i$  at distance  $r_i$ :  $I = \sum r_i^2 m_i$ .
- **Continuous:** Wire of length  $l$  with density  $\rho(x)$ :  $I = \int_0^l x^2 \rho(x) dx$ .
- **Unified:** Using mass distribution  $m(x)$ , both become  $I = \int x^2 dm(x)$ .

## 2. Definition

Let  $\alpha$  be a **monotone increasing** function on  $[a, b]$  and  $f$  be bounded.

For a partition  $\mathcal{P} = \{x_0, \dots, x_n\}$ , define  $\Delta\alpha_i = \alpha(x_i) - \alpha(x_{i-1})$ . Note that  $\Delta\alpha_i \geq 0$ .

- **Upper Sum:**  $\mathcal{U}(\mathcal{P}, f, \alpha) = \sum_{i=1}^n M_i \Delta\alpha_i$ , where  $M_i = \sup_{[x_{i-1}, x_i]} f$ .
- **Lower Sum:**  $\mathcal{L}(\mathcal{P}, f, \alpha) = \sum_{i=1}^n m_i \Delta\alpha_i$ , where  $m_i = \inf_{[x_{i-1}, x_i]} f$ .

### Integrability:

$f$  is Riemann-Stieltjes integrable with respect to  $\alpha$  ( $f \in \mathcal{R}(\alpha)$ ) if the lower and upper integrals meet:

$$\sup_{\mathcal{P}} \mathcal{L}(\mathcal{P}, f, \alpha) = \inf_{\mathcal{P}} \mathcal{U}(\mathcal{P}, f, \alpha) = \int_a^b f d\alpha$$

If  $\alpha(x) = x$ , this reduces to the standard Riemann integral.

## 3. Conditions for Existence

- **Cauchy Criterion (Theorem 6.5.5):**  $f \in \mathcal{R}(\alpha) \iff \forall \epsilon > 0, \exists \mathcal{P}$  such that  $\mathcal{U}(\mathcal{P}, f, \alpha) - \mathcal{L}(\mathcal{P}, f, \alpha) < \epsilon$ .
- **Theorem 6.5.6:** Integrability is guaranteed if:
  - i.  $f$  is **continuous** (proof relies on uniform continuity).
  - ii.  $f$  is **monotone** and  $\alpha$  is **continuous**.

## 4. Key Properties

If  $f, g \in \mathcal{R}(\alpha)$  and  $c \in \mathbb{R}$ :

1. **Linearity:**  $\int (f + g)d\alpha = \int fd\alpha + \int gd\alpha$  and  $\int cfd\alpha = c \int fd\alpha$ .
2. **Additivity of  $\alpha$ :**  $\int fd(\alpha_1 + \alpha_2) = \int fd\alpha_1 + \int fd\alpha_2$ .
3. **Interval Additivity:**  $\int_a^b = \int_a^c + \int_c^b$ .
4. **Order:**  $f \leq g \implies \int fd\alpha \leq \int gd\alpha$ .
5. **Boundedness:**  $|\int fd\alpha| \leq \int |f|d\alpha \leq M[\alpha(b) - \alpha(a)]$ .

## 5. Calculation Methods & Major Theorems

### A. The Unit Jump Function (Discrete Case)

Let  $I_c(x)$  be the unit jump at  $c$  (0 if  $x < c$ , 1 if  $x \geq c$ ).

- If  $f$  is continuous at  $c$  ( $a < c \leq b$ ), then:

$$\int_a^b fdI_c = f(c)$$

- **Proof Idea:** For any partition where  $c \in (x_{k-1}, x_k]$ , only  $\Delta\alpha_k = 1$  (others are 0). The sums squeeze  $f(c)$  due to continuity.
- **General Series (Theorem 6.5.11):** If  $\alpha(x) = \sum_{n=1}^{\infty} c_n I(x - s_n)$  (a step function with jumps at  $s_n$ ):

$$\int_a^b fd\alpha = \sum_{n=1}^{\infty} c_n f(s_n)$$

### B. The Differentiable $\alpha$ (Continuous Case)

- **Theorem 6.5.12:** If  $\alpha$  is differentiable and  $\alpha' \in \mathcal{R}[a, b]$ :

$$\int_a^b f(x)d\alpha(x) = \int_a^b f(x)\alpha'(x)dx$$

- **Proof Idea:** Uses Mean Value Theorem.  $\Delta\alpha_i = \alpha'(t_i)\Delta x_i$ . The Riemann-Stieltjes sum transforms into a Riemann sum for  $f\alpha'$ .

## C. Integration by Parts (Theorem 6.5.10)

$$\int_a^b \alpha d\beta = \alpha(b)\beta(b) - \alpha(a)\beta(a) - \int_a^b \beta d\alpha$$

- **Proof Idea:** Uses the identity for partition sums:  $\sum \alpha_i \Delta\beta_i = \alpha\beta - \sum \beta_i \Delta\alpha_i$  (Abel's transformation logic).

## D. Mean Value Theorem (Theorem 6.5.9)

If  $f$  is continuous,  $\exists c \in [a, b]$  such that:

$$\int_a^b f d\alpha = f(c)[\alpha(b) - \alpha(a)]$$

## 6. Illustrative Examples

### Example 6.5.4 (Integrability check)

1. **Jump Function:** If  $f$  is continuous at  $c$ ,  $\int f dI_c = f(c)$ .
2. **Dirichlet Function:**  $f(x) = 1$  if  $x \in \mathbb{Q}$ , 0 if irrational. This is **not** integrable w.r.t any non-constant  $\alpha$  because upper sums use  $M_i = 1$  and lower sums use  $m_i = 0$ .

### Example 6.5.13 (Computational Examples)

1. **Step Function:**  $\int_0^2 e^x d[x]$ .
  - $[x]$  has jumps of size 1 at  $x = 1$  and  $x = 2$ .
  - Result:  $e^1 + e^2$ .
2. **Smooth  $\alpha$ :**  $\int_0^1 \sin(\pi x) d(x^2)$ .
  - Convert using  $\alpha'(x) = 2x$ .
  - Integral becomes  $2 \int_0^1 x \sin(\pi x) dx = \frac{1}{\pi}$ .
3. **Mixed:**  $\int_0^3 [x] d(e^{2x})$ .
  - Use Theorem 6.5.12 (convert  $d(e^{2x})$  to  $2e^{2x} dx$ ).
  - Split integral based on values of  $[x]$ : 0 on  $[0, 1)$ , 1 on  $[1, 2)$ , 2 on  $[2, 3]$ .
  - Result:  $2e^6 - e^4 - e^2$ .

## 7. Riemann-Stieltjes Sums & Limits

A Riemann-Stieltjes sum is  $S(\mathcal{P}, f, \alpha) = \sum f(t_i) \Delta\alpha_i$  where  $t_i \in [x_{i-1}, x_i]$ .

- **Warning:** Unlike standard calculus, knowing the limit of sums exists does **not** imply  $f \in \mathcal{R}(\alpha)$  in all cases, nor does integrability always imply the limit of sums equals the integral for *any* choice of

tags  $t_i$  if  $f$  and  $\alpha$  share discontinuities.

- **Theorem:** If  $f$  is continuous, then  $\lim_{\|\mathcal{P}\| \rightarrow 0} S(\mathcal{P}, f, \alpha) = \int f d\alpha$ .

### Example 6.5.15 (Failure of Sums)

- $f(x) = 0$  on  $[0, 1]$ ,  $1$  on  $(1, 2]$  (jump at  $1$ ).
- $\alpha(x) = 0$  on  $(0, 1)$ ,  $1$  on  $[1, 2]$  (jump at  $1$ ).
- $f$  is left-continuous  $\implies$  Integrable.  $\int f d\alpha = 0$ .
- However, choosing tags  $t_k$  differently at the discontinuity point  $x = 1$  yields different sum limits ( $0$  or  $1$ ). Thus, the limit of sums **does not exist** even though the integral is defined.