

ODE.

$$\frac{dX_t}{dt} = u_t(X_t) \quad \text{or} \quad dX_t = u_t(X_t) dt.$$

입자적      입자적  
순간속도      운동방정식의  
                    물질 -

Flow       $X_t = \psi_t(x_0)$

" $t$ 로 흘러온 ODE"

← 같은 시기 초기부여 "

Picard-Lindelof Thm.

$$u_t = -\theta z$$

$$\psi_t(x_0) = \exp(-\theta t) \cdot x_0$$

풀실       $u_t$  가  cią기 부드러워짐       $\Rightarrow$  모든  $x_0$ 에 대해

① 연속으로 미가  
② 미분 가능

ODE는  유계  외부   $\psi_t \frac{d}{dt}$  가진다.

복잡한  $u_t$ 에 대해서  
 $\psi_t$  구하기 위함 수치해석을 활용하는 것.

① 오일러 방법      ② 노선 방법

- $X_{t+h} = X_t + h u_t(X_t)$
- $X_{t+h} = X_t + h \left( \frac{u_t(X_t) + u_{t+h}(X'_t)}{2} \right)$

## Flow Model

$$\text{ 초기 } p_{\text{init}} \rightarrow p_{\text{data}}$$

①  $X_0 \sim p_{\text{init}} = N(0, I)$

② define ODE  $\Rightarrow \frac{d}{dt} X_t = u_t(X_t)$  (Neural Net)

③ solve ODE  $\Rightarrow X_1$

④ train NN  $\Rightarrow X_1 \sim p_{\text{data}}$

---

언제나 확률

$\Rightarrow$  확률적인 경우

SDE의 특징

①  $W_0 = 0$

$W_{t+h} = W_t + \sqrt{h} \varepsilon_t$

②  $W_t - W_s \sim N(0, (t-s)I)$

$\sim N(0, I)$

언제나 같은 시간 구간의

연속량은 가로 축

---

ODE :  $X_0 \xrightarrow{\text{deterministic}} X_1$

$$X_{t+h} = X_t + h u_t(X_t)$$

$$dX_t = u_t(X_t) dt.$$

SDE :  $X_0 \xrightarrow{\text{stochastic}} X_1$

$$X_{t+h} = X_t + h u_t(X_t) + \sigma_t \cdot (W_{t+h} - W_t)$$

$$\approx \sqrt{h} \cdot \sigma_t \cdot \varepsilon_t$$

$$dX_t = u_t(X_t) dt + \sigma_t \cdot dW_t$$

SDE에는  $\frac{dX_t}{dt} = f(X_t, t)$   $\frac{dW_t}{dt}$  if  $t \in \mathbb{R}$

- ① 연속으로 되어 있음
- ②  $\sum_{t=1}^n \frac{dW_t}{dt} = 0$

$X_0 = x_0$   
init cond

$dX_t = u(X_t) dt + \sigma_t dW_t$ .

drift diffusion

$$\begin{cases} \text{ODE} : dX_t = f(X_t, t) dt \\ \text{SDE} : dX_t = f(X_t, t) dt + g(t) dW_t \end{cases}$$

solution path  $\{X_t\}_{t=0}^T \implies$  prob. distribution  $\{p_t\}_{t=0}^T$

• càdlàg } right-continuous  
              }  $\exists$  left limit.

$$X_t = X_0 + \int_0^t f(X_s, s) ds + \int_0^t g(X_s, s) dW_s$$

$$\int_0^t g(X_{s-}, s) dW_s = \sum_{k=0}^{t/\Delta t} g(X_{k\Delta t}, \underbrace{\varepsilon_k}_{\text{small}}) \sqrt{\Delta t} \cdot \underbrace{Z_k}_{\sim N(0, I)} \quad (\Delta t \rightarrow 0)$$

$$= \Delta W_k$$

(example) OU process

$$dX_t = -\theta \cdot X_t dt + \sigma dW_t$$

$$X_\infty \sim N(0, \frac{\sigma^2}{2\theta})$$

How to simulate SDE

< Euler-Maruyama Method >

$$X_{t+h} = X_t + h u_t(X_t) + \sqrt{h} \cdot \sigma_t \underbrace{Z_h}_{\sim N(0, I)}$$

Diffusion 2차원  
2차원 확률 과정

$X_0 \sim \text{Pinit}$

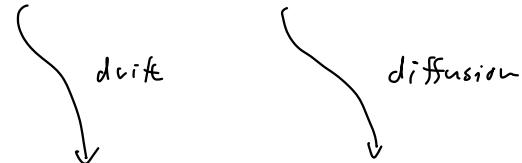
$$dX_t = u_t(X_t) dt + \sigma_t dW_t$$

$$\Rightarrow X_t \sim P_{\text{distr}}$$

Fokker-Planck Equation

(SDE)

$$dX_t = f(x, t) dt + g(t) dW_t$$



$$\partial_t P_t(x) = -\partial_x (f(x, t) P_t(x)) + \frac{\partial^2}{2} \partial_x^2 (P_t(x)) \quad \text{and} \quad X_t \sim P_t$$

① 극한 정의의

시작 확률

$$\partial_t E[\phi(X_t)] = \lim_{\Delta t \rightarrow 0} \frac{E[\phi(X_{t+\Delta t})] - E[\phi(X_t)]}{\Delta t}$$

② 정의 - 미분 - 확장

$$X_{t+\Delta t} \approx X_t + \Delta X_t$$

근사

$$\approx X_t + f \Delta t + g \sqrt{\Delta t} Z$$

③ 정의 - 근사

$$\phi(X_{t+\Delta t}) \approx \phi(X_t)$$

$$+ \phi'(X_t) \cdot (f \Delta t + g \sqrt{\Delta t} Z)$$

$\Delta t$ 에 대입 고려

$$+ \frac{1}{2} \phi''(X_t) \cdot (g^2 \Delta t \cdot Z^2 + \dots)$$

④ 기대값

$$E[\phi(X_{t+\Delta t})] - E[\phi(X_t)]$$

$$\approx E \left[ \phi'(X_t) \cdot (f \Delta t + g \sqrt{\Delta t} \cdot Z) \right] \quad E[Z] = 0$$

$$+ \frac{1}{2} \phi''(X_t) (g^2 \Delta t \cdot Z^2) \quad E[Z^2] = 1$$

$$\approx \Delta t \cdot E[\phi'(X_t) f + \frac{1}{2} \phi''(X_t) g^2]$$

$$\textcircled{5} \quad \text{한계값} \quad \partial_t E[\phi(X_t)] \approx E[\phi'(X_t) \cdot f(X_t, t) + \frac{1}{2} \phi''(X_t) g^2(t)]$$

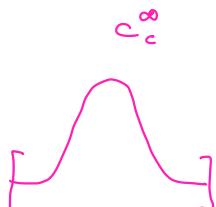
### ⑦ 누운책은 .

assume  $\phi, f$  sufficiently smooth

de decay sufficiently quickly at  $|x| \rightarrow \infty$

$$\phi \in C_c^\infty(\mathbb{R})$$

$$\int_{\mathbb{R}} \phi'(x) f(x) dx = \left[ \phi(x) f(x) \right]_{-\infty}^{\infty} - \int_{\mathbb{R}} \phi(x) f'(x) dx$$



$$\forall \phi \in C_c^\infty \quad \int \phi(x) \left( \partial_x p_t + \partial_x(f p_t) - \frac{\partial^2}{2} \partial_x^2 (f p_t) \right) dx = 0$$

$$\text{다른 험로의 예는...} \quad \partial_t p_+ = -\nabla_x \cdot (f_{p_+}) + \frac{1}{2} + \nu (g^T (\nabla_x^2 p_+) g)$$

out process

$$\cdot dx_t = -\beta x_t dt + \sigma dW_t$$

$$\cdot x_t = e^{-\beta t} x_0 + \sigma e^{-\beta t} \int_0^t e^{\beta s} dW_s$$

$$\cdot x_t | x_0 \sim N\left(e^{-\beta t} x_0, \frac{\sigma^2}{2\beta} \cdot (1 - e^{-2\beta t})\right)$$

---

stationary distribution  $N(0, \frac{\sigma^2}{2\beta})$

$$\cdot E[x_t] = E[E[x_t | x_0]]$$

$$= E[e^{-\beta t} \cancel{x_0}] = 0$$

$$\cdot \text{Var}[x_t] = E[\text{Var}(x_t | x_0)] + \text{Var}(E[x_t | x_0])$$

$$= \left[ \frac{\sigma^2}{2\beta} \cdot (1 - e^{-2\beta t}) \right] + (e^{-\beta t})^2 \cdot \frac{\sigma^2}{2\beta}$$

$$= \dots = \frac{\sigma^2}{2\beta}$$

$$\cdot p_t(x_t) = \frac{1}{\sqrt{\pi \sigma^2 / \beta}} \exp\left(-\frac{\beta}{\sigma^2} \cdot (x_t)^2\right)$$

image corruption with OU

$$\text{output} \quad \text{input} \quad X_T | X_0 \sim N \left( e^{-\beta t} X_0, \frac{\sigma^2}{2\beta} (1 - e^{-2\beta t}) \cdot I \right)$$

$$\sim N(0, \frac{\sigma^2}{2\beta}) \quad \text{if} \quad T \approx \infty$$

---

in ODE,

$$\begin{cases} X(0) \\ \frac{dX}{dt}(t) = f(X(t), t) \end{cases}$$

$$\text{i.e. } X_{k+1} = X_k + \Delta t \cdot f(X_k, k\Delta t)$$

hence  $X_k = X_{k+1} - \Delta t \cdot f(X_{k+1}, k\Delta t)$

what about SDE?

$$X_t = A_t + b_t \quad \text{and}$$

$$\begin{aligned} \textcircled{1} \quad & \text{정의} \quad A_t = e^{-\beta t} X_0 \\ \textcircled{2} \quad & \text{정의} \quad b_t = \underbrace{\sigma \cdot e^{-\beta t}}_{=: Y_t} \cdot \underbrace{\int_s^t e^{\beta s} dW_s}_{=: Z_t} \end{aligned}$$

Step ① 계산 미술.

$$dA_t = \frac{dA_t}{dt} \cdot dt = (-\beta \cdot e^{-\beta t} X_0) dt$$

$$dY_t = \frac{dY_t}{dt} \cdot dt = (-\beta \cdot \sigma \cdot e^{-\beta t}) dt$$

$$dZ_t = d\left(\int_s^t e^{\beta s} dW_s\right) = e^{\beta t} \cdot dW_t$$


---

Step ② 0으로 Riemann의 정의

$$(i) \quad d(Y_t Z_t) = Y_t dZ_t + Z_t dY_t + dY_t dZ_t.$$

$$(ii) \quad dt \cdot dt = 0 \quad \text{hence}$$

$$dt \cdot dW_t = 0 \quad dY_t \cdot dZ_t = (-\beta \cdot \sigma \cdot e^{-\beta t} dt) \cdot (e^{\beta t} \cdot dW_t) = 0$$

$$dW_t \cdot dW_t = dt$$


---

Step ③ 결론.

$$\begin{aligned} dX_t &= \left( (-\beta \cdot e^{-\beta t} X_0) dt + (-\beta \cdot \sigma \cdot e^{-\beta t}) dt \cdot \int_s^t e^{\beta s} dW_s \right) \Rightarrow -\beta X_0 dt \\ &\quad + \left( + \sigma \cdot e^{-\beta t} \cdot e^{\beta t} \cdot dW_t \right) \Rightarrow \sigma dW_t. \end{aligned}$$

$$\Delta(YZ) = (Y + \Delta Y)(Z + \Delta Z) - YZ$$

$$= Y\Delta Z + Z\Delta Y + \text{circled } \Delta Y \Delta Z.$$

(설명)

(이제)

$$\Delta Y \approx Y'(t) \cdot \Delta t$$

$$\Delta Z \approx Z'(t) \cdot \Delta t$$

$$\Delta Y \Delta Z \approx Y'(t) Z'(t) \cdot (\Delta t)^2$$

$$\begin{cases} dY = a \cdot dt + b \cdot dW_t \\ dZ = c \cdot dt + d \cdot dW_t \end{cases}$$

작은.

$$dY dZ = a \cdot c (dt \cdot dt) + ad (dt \cdot dW_t) + bc (dW_t \cdot dt) + bd (dW_t \cdot dW_t)$$

정한!

$$X_t = e^{-\beta t} \cdot X_0 + \sigma \cdot e^{-\beta t} \cdot \int_0^t e^{\beta s} dW_s$$

$$\textcircled{1} \quad E[X_t] = E[e^{-\beta t} \cdot X_0] + E[\sigma \cdot e^{-\beta t} \cdot \int_0^t e^{\beta s} dW_s]$$

$$= e^{-\beta t} \cdot E[X_0]$$

$$\textcircled{2} \quad \text{Var}[X_t] = e^{-2\beta t} \cdot \text{Var}(X_0) + \sigma^2 \cdot e^{-2\beta t} \cdot \text{Var}\left(\int_0^t e^{\beta s} dW_s\right)$$

$$= E\left[\int_0^t e^{2\beta s} ds\right]$$

이제  
정답

$$= e^{-2\beta t} \cdot \text{Var}(X_0) + \sigma^2 \cdot e^{-2\beta t} \cdot \int_0^t e^{2\beta s} ds$$

$$= \frac{1}{2\beta} \cdot (e^{2\beta t} - 1)$$

$$= \frac{\sigma^2}{2\beta} (1 - e^{-2\beta t})$$

• 1주 풀이

$$\mathbb{E} \left[ \left( \int_0^t f(s) dW_s \right)^2 \right] = \mathbb{E} \left[ \int_0^t (f(s))^2 ds \right]$$

(pt)  $\mathbb{E} \left[ \left( \sum_i f(t_i) \cdot \Delta B_i \right)^2 \right]$

$$= \mathbb{E} \left[ \underbrace{\sum_i (f(t_i))^2 \cdot (\Delta B_i)^2}_{= \Delta t i} + \underbrace{\sum_{i \neq j} f(t_i) f(t_j) \Delta B_i \Delta B_j}_{\mathbb{E}[\Delta B_i] \cdot \mathbb{E}[\Delta B_j]} \right]$$

---