

# Assignment 1 – Programming Raspberry Pi to Read/Write Sensors and Actuators

Controlling LED with a switch, an LDR sensor, and a DHT sensor

# Outline

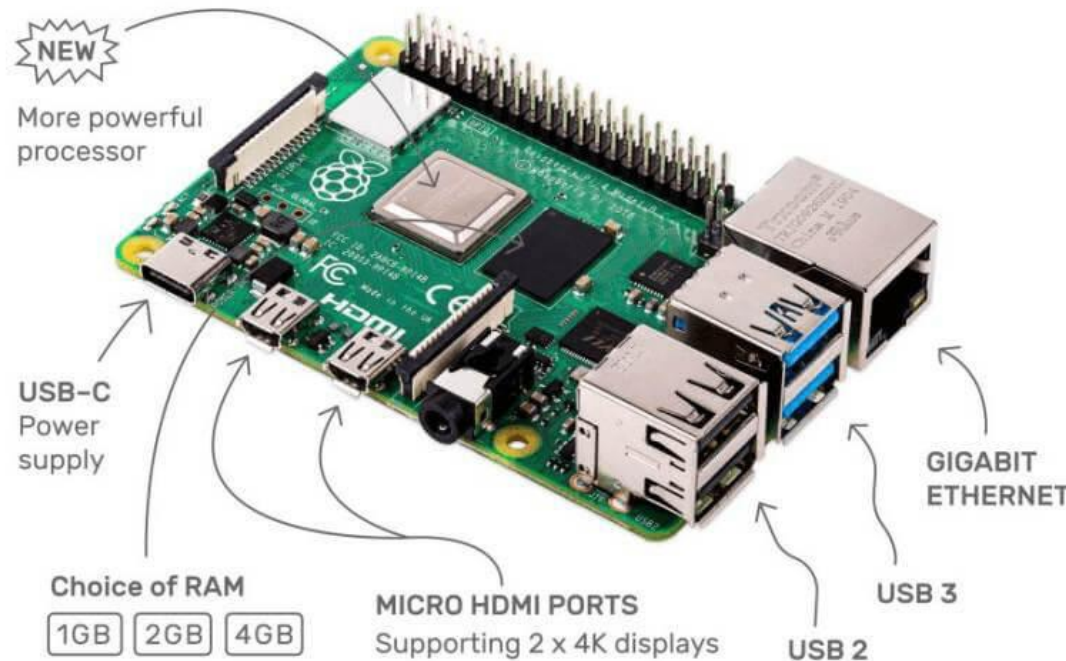
- Objectives
- Basic Raspberry Pi
- OS installation
- A simple IoT application
  - Controlling LED
    - With Raspberry Pi
    - With Switch
    - With Light Sensor (LDR)
    - With Temperature and Humidity Sensor (DHT)
- Assignment 1 - Specification

# Objectives

- Get to know Raspberry Pi
- Capable to install the Raspbian operating system
- Connecting sensors and actuators to Raspberry Pi
- Writing the code to run the sensors and actuators

# Basic Raspberry Pi – What is a Raspberry Pi?

A low cost, credit-card sized computer



<b>Processor:</b>	Broadcom BCM2711, quad-core Cortex-A72 (ARM v8) 64-bit SoC @ 1.5GHz
<b>Memory:</b>	2GB, 4GB or 8GB LPDDR4 (depending on model)
<b>Connectivity:</b>	2.4 GHz and 5.0 GHz IEEE 802.11b/g/n/ac wireless LAN, Bluetooth 5.0, BLE Gigabit Ethernet 2 × USB 3.0 ports 2 × USB 2.0 ports.
<b>GPIO:</b>	Standard 40-pin GPIO header (fully backwards-compatible with previous boards)

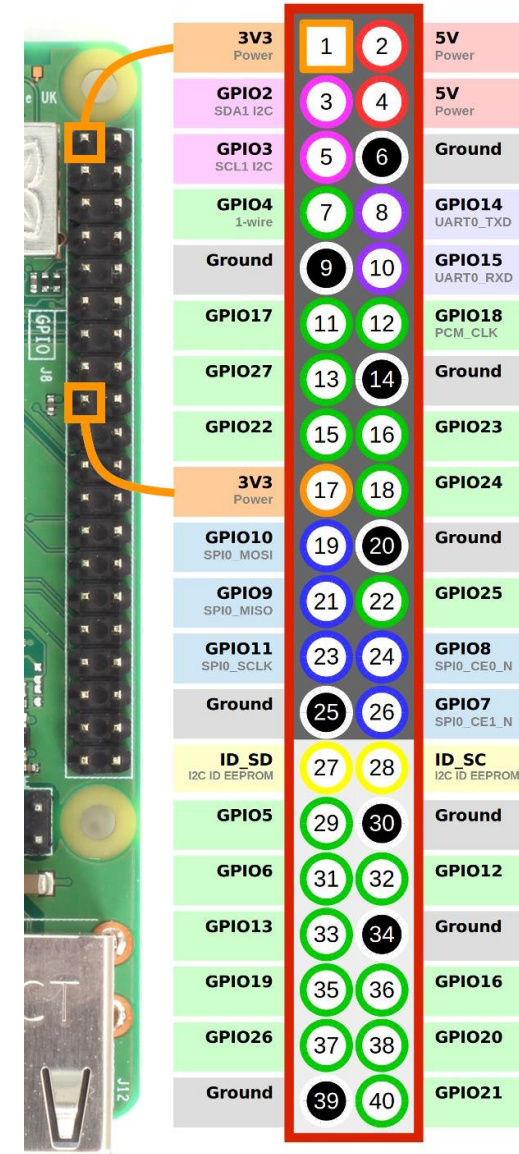
# Basic Raspberry Pi – GPIO Pins

- GPIO: a physical interface between the Raspberry Pi and the outside world
- To monitor and control the sensors and actuators
- 5 parts of GPIO pins:

Raspberry Pi A+ / B+ and Raspberry Pi 2/3/4 pin numbers

● GPIO ● Ground ● 3.3v ● 5v ○ ID EEPROM  
Advanced use only

- GPIO: Input/output pins
- Ground: Zero volts
- 3.3v: These pins provide 3.3V power
- 5v: These pins provide 5V power
- ID EEPROM: Advanced use only

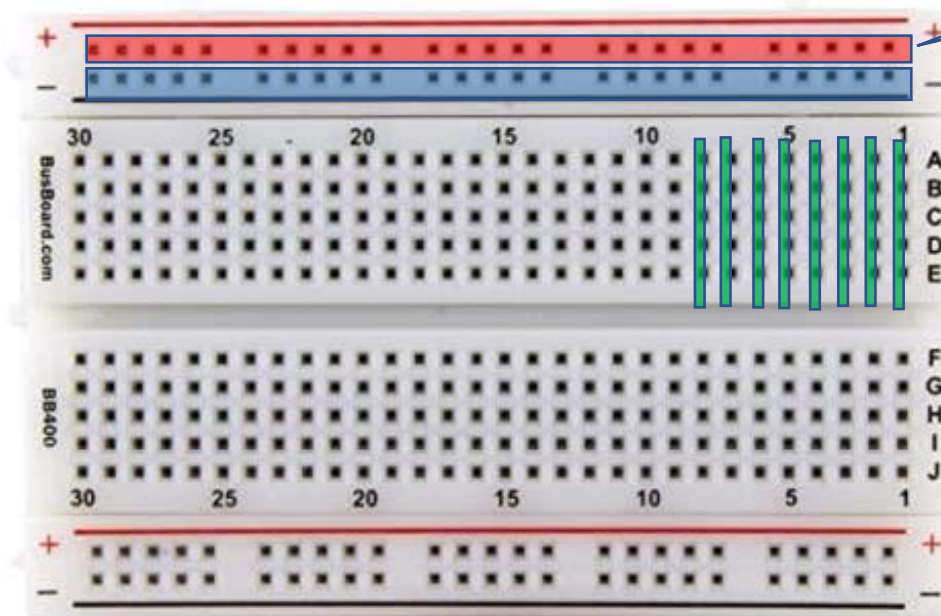


# Basic Raspberry Pi – Connecting Raspberry Pi

- Using micro HDMI ports
  - Connect the Micro HDMI into LCD Monitor
- Using network
  - By wire/wireless
  - Connect by using SSH or VNC

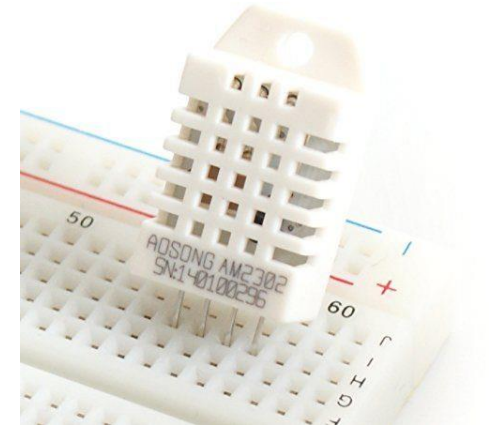
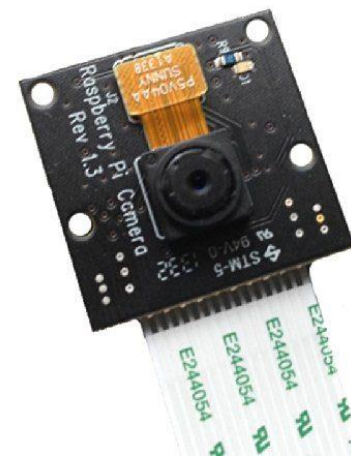
# Basic Raspberry Pi – Breadboard

- 3 parts of breadboard:
  - The red line or positive: commonly used for Power
  - The blue line or negative: commonly used for Ground
  - The main part in the middle: to put and assemble your sensors or actuators



# Basic Raspberry Pi – Sensors

- What are sensors
  - Add almost-human sensing capabilities
  - Take real-world events
  - Convert them to analogue or digital signals
  - Read by Raspberry Pi





# Basic Raspberry Pi – Sensors

- Sensor categories
  - Temperature / Humidity / Air Pressure / Gas
  - Motion Sensors
  - Navigation Modules
  - Wireless / Infrared (IR) / Bluetooth
  - Analogue Sensors
  - Current Supply
  - Other Modules, Components and Sensors

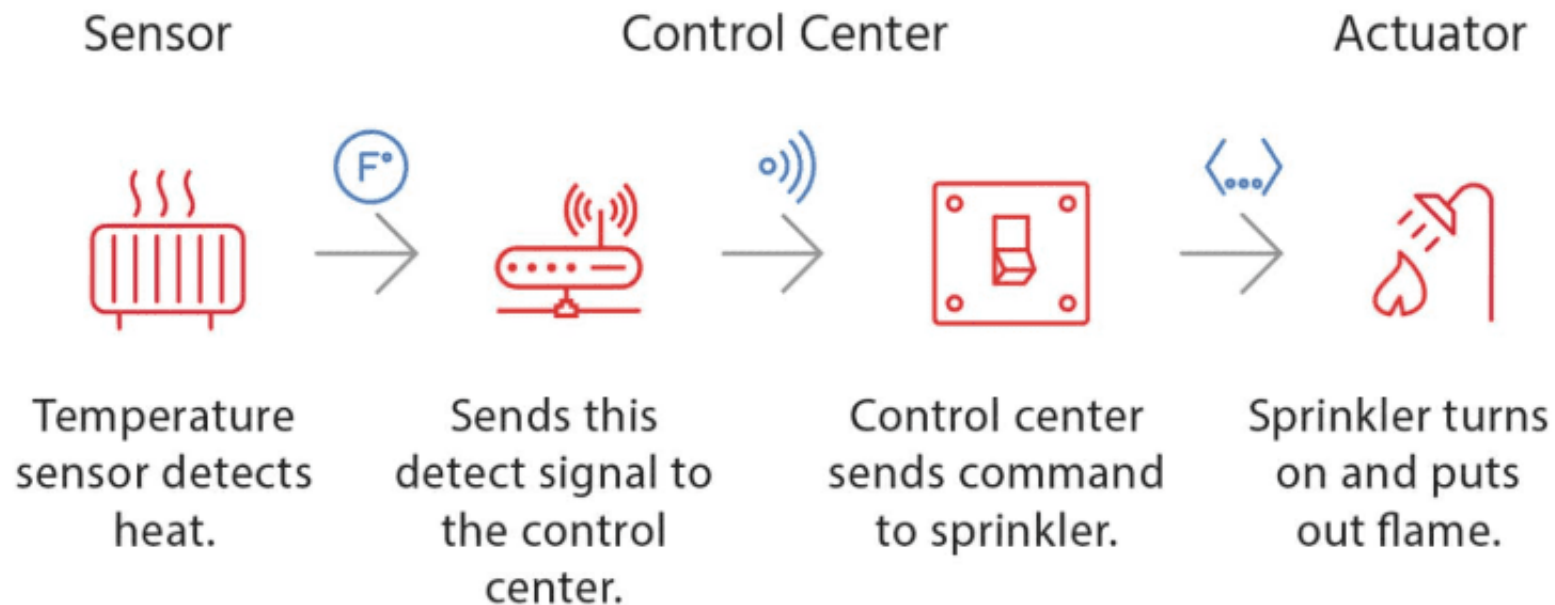
# Basic Raspberry Pi – Actuators

- What are actuators
  - Convert an electrical signal into a corresponding physical quantity
    - Example: movement, force, sound etc.
  - Controlled by Raspberry Pi



# Basic Raspberry Pi – Sensors vs Actuators

- Difference in sensors and actuators
  - Sensors: read and get the information from sensors
  - Actuators: write and control some tools based on the previous information



# Basic Raspberry Pi – Sensors and Actuators

## How to get it ?

- Borrow from us
  - We have a limited number of sensors and actuators
- Buy it by yourself
  - Save the receipt and reimburse to us
  - The limit of amount to reimburse : 1,000 NTD per team
  - The receipts should show the following title or number
    - 抬頭：國立陽明交通大學
    - 統編：**87557573**

# Basic Raspberry Pi – Sensors and Actuators

## Our Collections of IoT Equipments

Item	Total	Note	Item	Total	Note
<b>Mandatory Components</b>			<b>Sensors</b>		
Raspberry Pi	37	Tiny computer that can be used as the main IoT system	Mic	1	Capturing any sound
Power Supply	37	To supply power to Raspberry Pi	RFID Reader	2	A device used to gather information from an RFID tag
SD Card	37	OS and storage holder	RFID Tags	3	RFID tags are a type of tracking system
SD Card Reader	13	Converter from SD Card to micro SD	Push ON button	17	Switching device, closed circuit when pushed, open circuit when unpushed
<b>Sensors</b>			Switch	7	ON/OFF Switch
BME680	1	Measures the temperature & humidity	Keypad	2	Record number that is inputed
DHT 11	28		<b>Actuators</b>		
HW484	1	Sound Detector	Display	8	To display any information given
FC22	1	Gas Leakage Detection	Number Display	10	To display number information
IR-08H	2	Object Detection	Buzzer	20	To give ring sound
MH Flying Fish	1		Fan	9	Small fan to cool small area
SR04	8	Measure the Distance	LED	50	To provide lighting
LDR	61	Measures the Light Intensity	<b>Other Components</b>		
PIR	20	Motion Detection	Bread Board	19	To help developing IoT environment
Water Sensor	1	Detect the presence of water	Relay	5	Controls the opening and closing of the circuit
Soil Sensor	3	Measure the amount of water in the soil	Potentiometer	2	Measures the distance or displacement of an object in a linear
Rain Sensor	1	Switching device when rain is detected	Capacitor	50	Device that stores electrical energy in an electric field
Touch Sensor	1	When touch is closed switch, untouch is open switch	Resistor	50	Limit the flow of electric current
Raspberry Pi Cam	5	Capturing any activities	Battery	10	To give power

# Basic Raspberry Pi – Sensors and Actuators

- Where to buy the sensors and actuators?



# OS Installation – Things you need at first

Make sure you already get all of them below:

- Raspberry Pi 4 Model B
- USB type-C power supply
- microSD card

Something you also need:

- card reader (for microSD)
- network cable (Ethernet RJ45)
- laptop or PC

# OS Installation – Download the OS

- Download Raspbian from here:

<https://www.raspberrypi.org/downloads/raspbian/>

- Choose the version you like and unzip the .zip file
- Here, we choose **Raspberry Pi OS (32-bit) with desktop and recommended software** since we have 32GB SD card



# OS Installation – Tools to Flash the OS (1)

- Right now pi 4b only supports booting from SD card, so we need to download a tool to flash OS image to SD card
- Rufus (Windows only) or balenaEtcher (Windows / macOS / Linux)
- Flash .img file into your SD card  
(You need an SD card reader to help you complete this step.)

# OS Installation - Tools to Flash the OS (2)



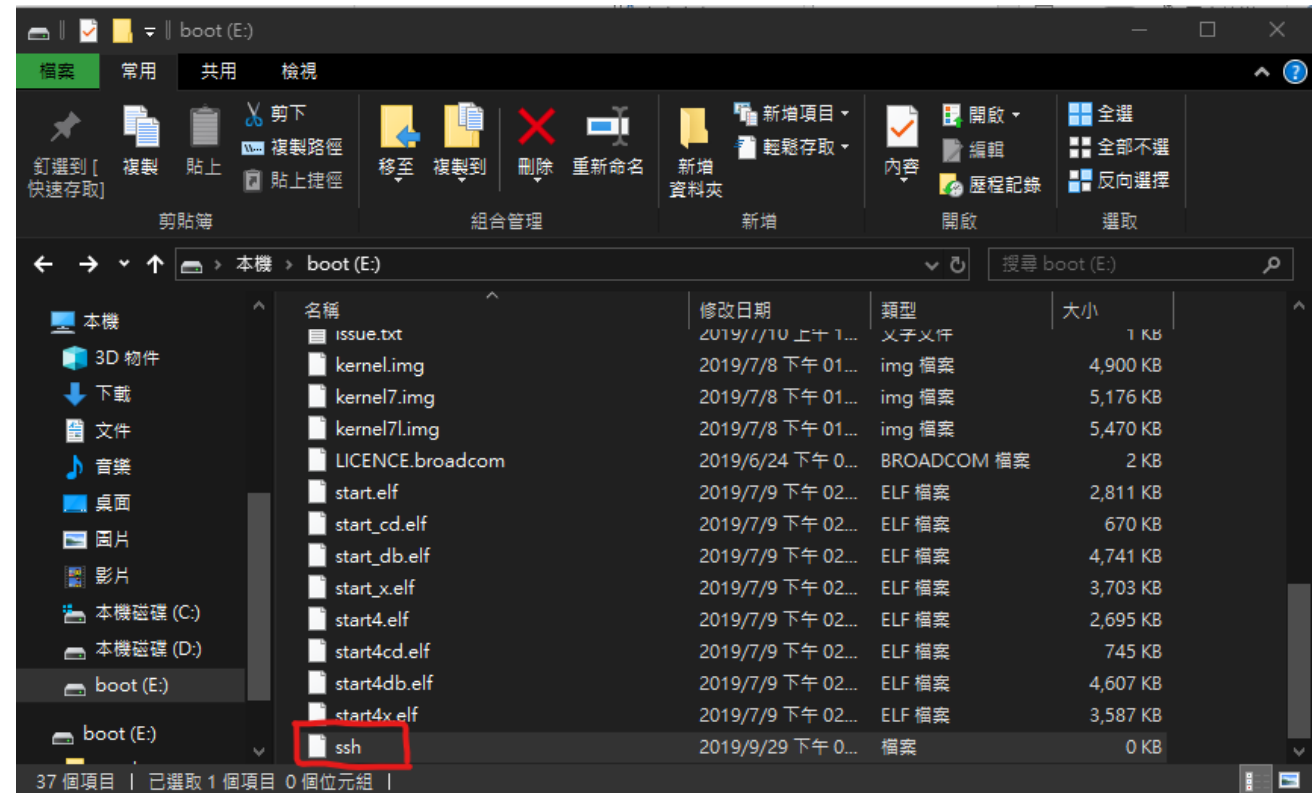
# OS Installation – SSH (1)

- After process completes, add a **new raw file** called “ssh” into the “boot” disk.

Check:

Plug the microSD card into pi 4b, and connect type-C power cable and network cable.

If green light is twinkling under the left corner of network cable slot, that means your pi 4b is using SSH now!!



# OS Installation – SSH (2)

- There is a built-in tool for ssh in Windows 10. But if you cannot find it, you need to download PuTTY [here](#).
- Use ssh command  
“ssh [pi@raspberrypi.local](#)”  
default password: raspberry

```
C:\Users\chenj>ssh pi@raspberrypi.local
pi@raspberrypi.local's password:
Linux raspberrypi 4.19.57-v7l+ #1244 SMP Thu Jul 4 18:48:07 BST 2019 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Sat Sep 28 21:50:49 2019

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set a new password.

pi@raspberrypi:~ $
```

# OS Installation – Enable VNC server

- `sudo raspi-config`

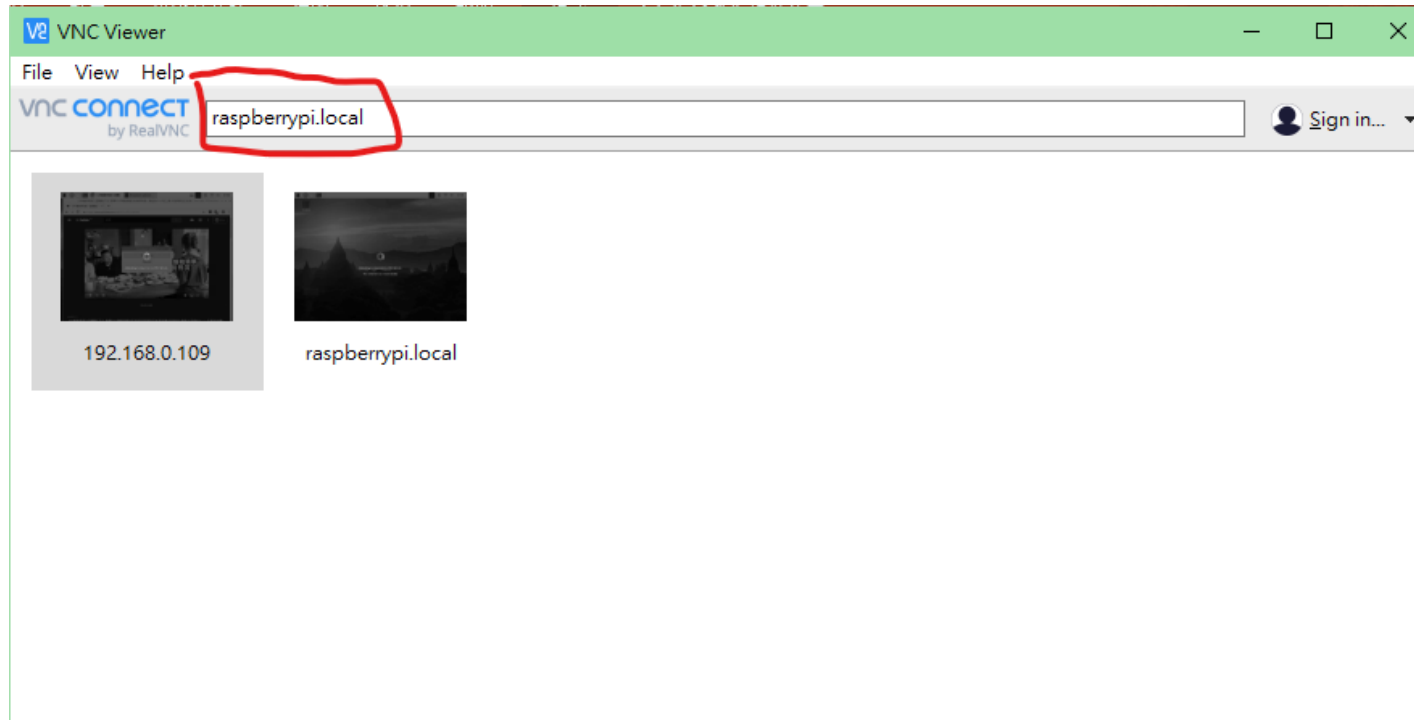
**Step 1. Choose 5 Interfacing Options -> P3 VNC -> Yes(是)**

**Step 2. Choose 7 Advanced Options -> A5 Resolution -> choose one other than Default**

**You need to reboot the system after the setting!**

# OS Installation – VNC client

- UltraVNC (Windows only) or RealVNC (Windows / macOS / Linux)
- Connect to the VNC Server “raspberrypi.local”





垃圾桶



# OS Installation - Notes

After you configure WiFi connection on Pi 4b, you can use VNC connect to Pi 4b without network cable.

Use command **ifconfig** to find what is the ip address on wlan.

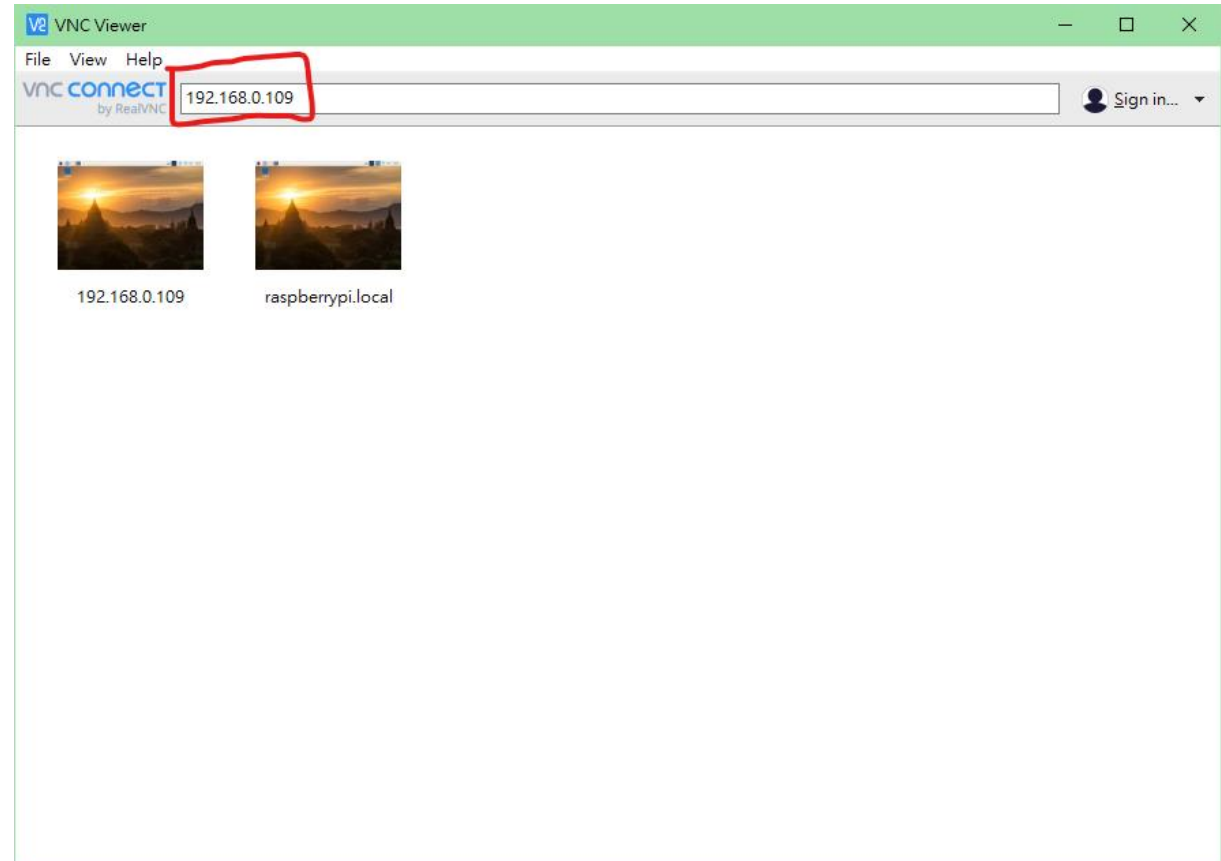


# OS Installation - Notes

```
pi@raspberrypi:~ $ ifconfig
eth0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 169.254.98.144 netmask 255.255.0.0 broadcast 169.254.255.255
    inet6 fe80::1b0b:8f29:bb0b:9fc2 prefixlen 64 scopeid 0x20<link>
    ether dc:a6:32:11:24:19 txqueuelen 1000 (Ethernet)
    RX packets 2722 bytes 303582 (296.4 KiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 3195 bytes 2441752 (2.3 MiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

lo: flags=73<UP,LOOPBACK,RUNNING> mtu 65536
    inet 127.0.0.1 netmask 255.0.0.0
    inet6 ::1 prefixlen 128 scopeid 0x10<host>
    loop txqueuelen 1000 (Local Loopback)
    RX packets 17 bytes 1004 (1004.0 B)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 17 bytes 1004 (1004.0 B)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

wlan0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 192.168.0.109 netmask 255.255.255.0 broadcast 192.168.0.255
    inet6 fe80::b914:d332:250f:226c prefixlen 64 scopeid 0x20<link>
    ether dc:a6:32:11:24:1a txqueuelen 1000 (Ethernet)
    RX packets 1451 bytes 255163 (249.1 KiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 110 bytes 11534 (11.2 KiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
```



# OS Installation - Notes

If you re-install the Raspberry Pi again, maybe you will encounter some problem when you use SSH command.

Try to delete the “known\_hosts” file or just delete the line related to “raspberrypi.local” in the known\_hosts and use ssh command again!

# OS Installation - Notes

```
C:\Users\chenj>ssh pi@raspberrypi.local
@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
@      WARNING: POSSIBLE DNS SPOOFING DETECTED!      @
@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
The ECDSA host key for raspberrypi.local has changed,
and the key for the corresponding IP address fe80::1b0b:8f29:bb0b:9fc2%7
is unknown. This could either mean that
DNS SPOOFING is happening or the IP address for the host
and its host key have changed at the same time.
@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
@      WARNING: REMOTE HOST IDENTIFICATION HAS CHANGED!      @
@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
IT IS POSSIBLE THAT SOMEONE IS DOING SOMETHING NASTY!
Someone could be eavesdropping on you right now (man-in-the-middle attack)!
It is also possible that a host key has just been changed.
The fingerprint for the ECDSA key sent by the remote host is
SHA256:XgkT5//45sRrCkA2An2Jy/4g4w3HHDiWRYao4YbJTCo.
Please contact your system administrator.
Add correct host key in C:\\Users\\chenj\\.ssh\\known_hosts to get rid of this message.
Offending ECDSA key in C:\\Users\\chenj\\.ssh\\known_hosts:11
ECDSA host key for raspberrypi.local has changed and you have requested strict checking.
Host key verification failed.

C:\Users\chenj>rmdir /S .ssh
.ssh, 您確定要執行嗎 (Y/N)? Y
```

The screenshot shows a terminal window with the vim editor open. The title bar indicates the file being edited is `known_hosts (~/.ssh) - VIM`. The first line of the file is highlighted with a red box:

```
raspberrypi.local,fe80::1b0b:8f29:bb0b:9fc2%7 ecdsa-sha2-nistp256 AAAAE2VjZHNhLXNoYTItbmlzdHAyNTYAAAAIbmlzdHAyNTYAAABBBNfEMKUrPo7rdLuobyowUB1AqkKUuQjV4wzQzWmgA5KATGYTSIhGYQx1Tjw0kd6N4jzqYvfd3VPNNwQRrx1rjE=
```

The rest of the file contains several empty lines, indicated by tilde (~) characters. The status bar at the bottom shows the current position is line 1, column 1, and the file size is 208C.

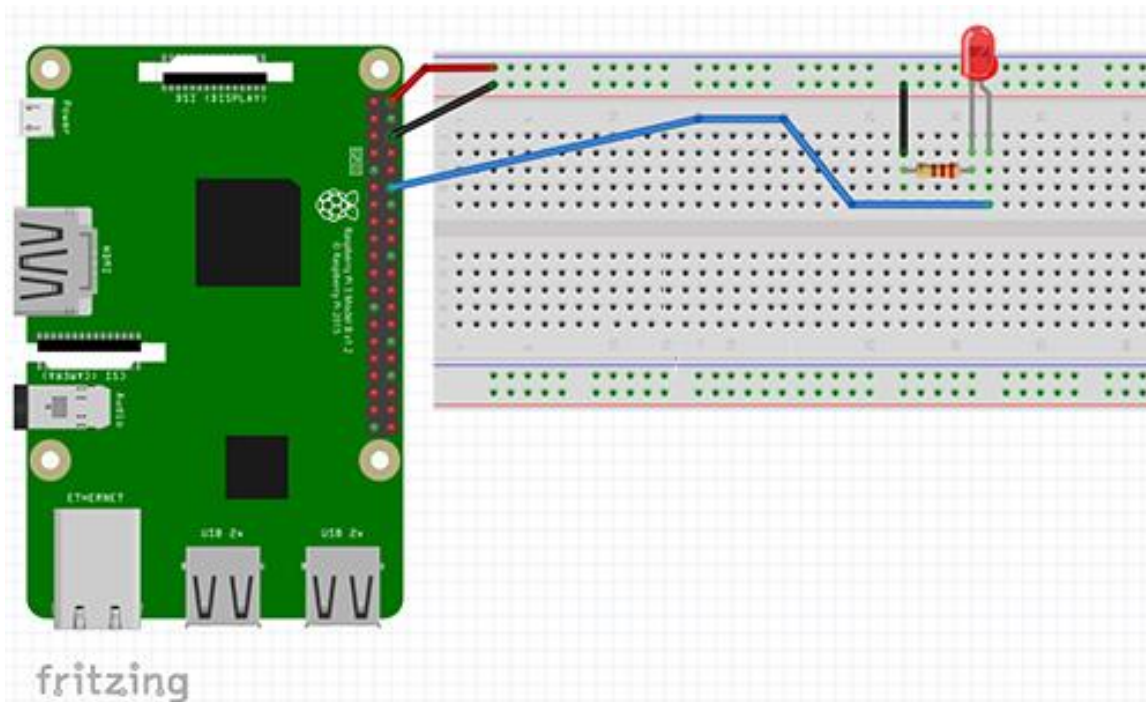
# A Simple IoT Application

Controlling LED with a switch, an LDR sensor, and a DHT sensor

# Controlling LED with Raspberry Pi

Components :

- LED
- A Resistor (Orange, Orange, Brown, Gold)



```
import RPi.GPIO as GPIO
import time
```

```
GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
```

```
ledPin = 12
```

```
GPIO.setup(ledPin, GPIO.OUT)
```

```
for i in range(100):
    print("LED turning on.")
    GPIO.output(ledPin, GPIO.HIGH)
    time.sleep(1)
    print("LED turning off.")
    GPIO.output(ledPin, GPIO.LOW)
    time.sleep(1)
```

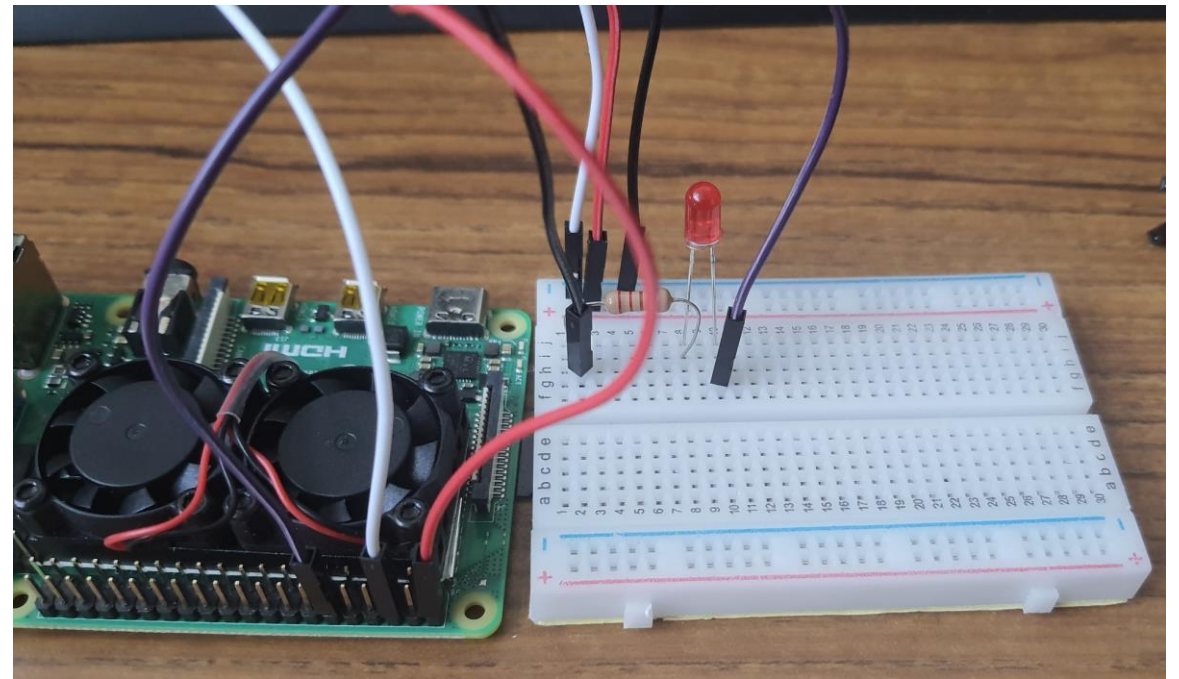
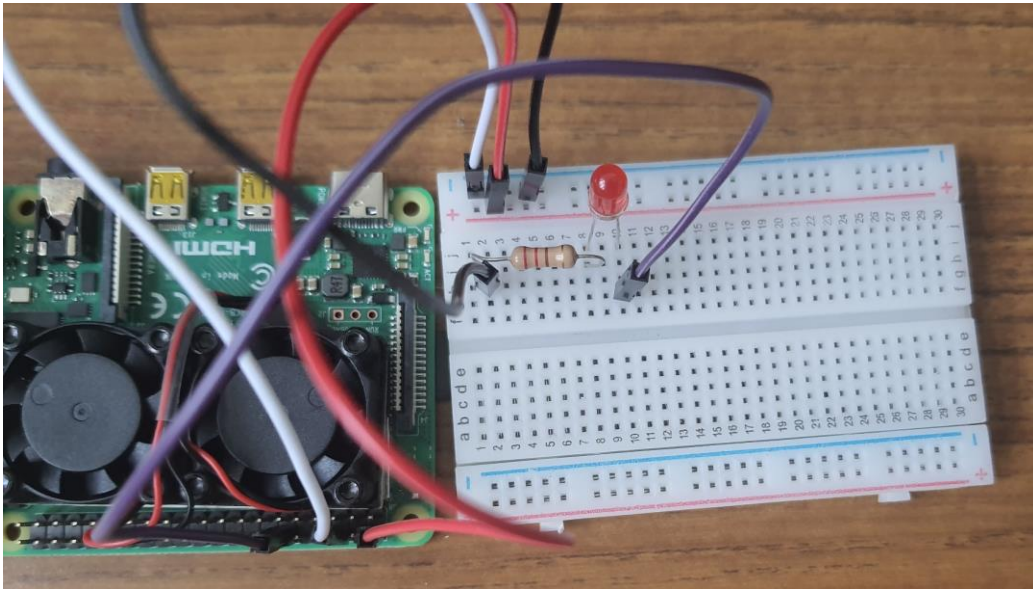
There are two different models of GPIO.setmode (pin numbering)

- GPIO.BOARD : using board numbering system (ex: pin 12)
- GPIO.BCM : using BCM numbers (ex : GPIO 18)

# Controlling LED with Raspberry Pi

Demo video:

<https://youtu.be/77u4gbw1fVw>

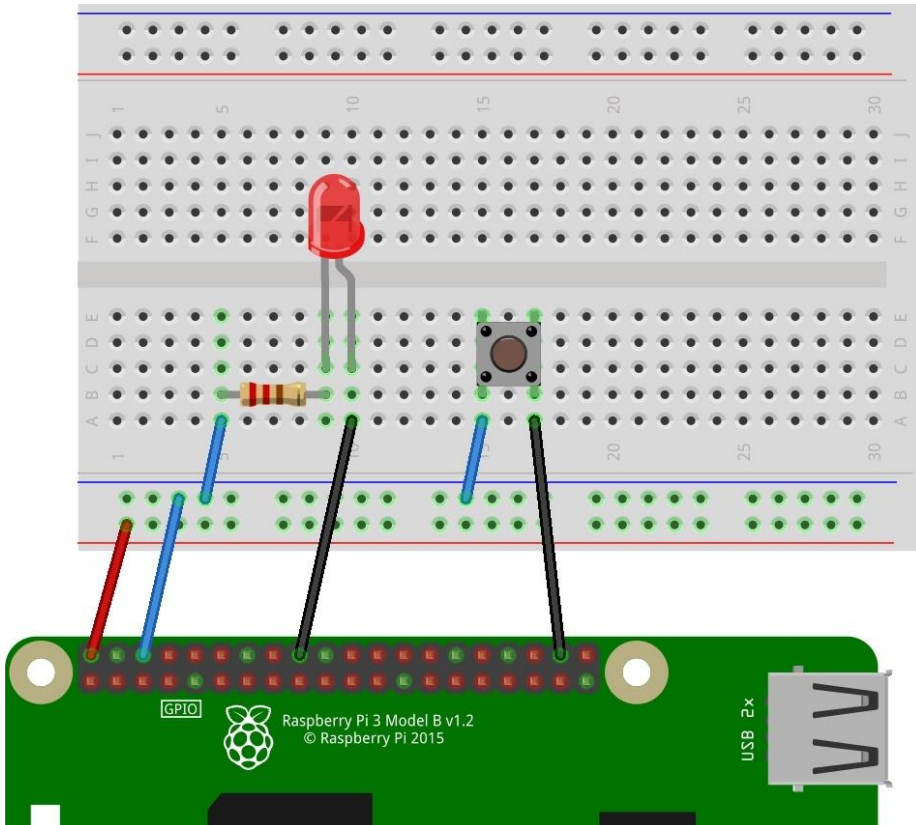




# Controlling LED with Switch

Components :

- LED
- Switch
- 1 Resistors (Orange, Orange, Brown, Gold)



```
import RPi.GPIO as GPIO
import time
```

```
GPIO.setmode(GPIO.BCM)
```

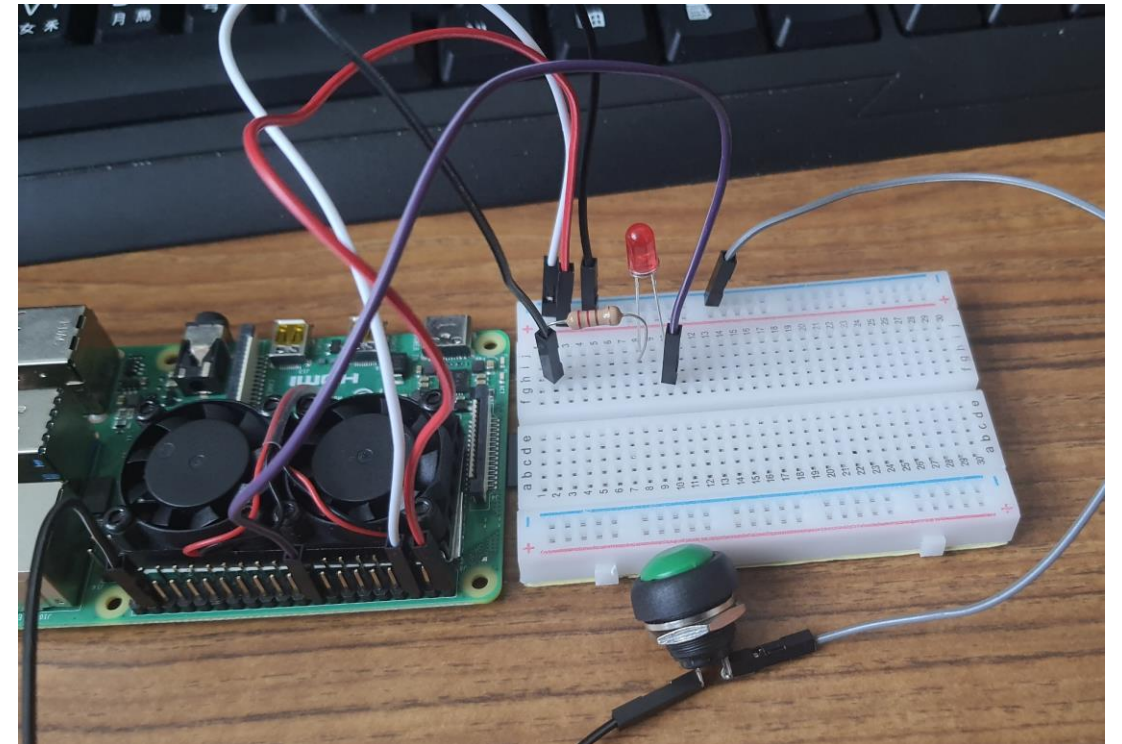
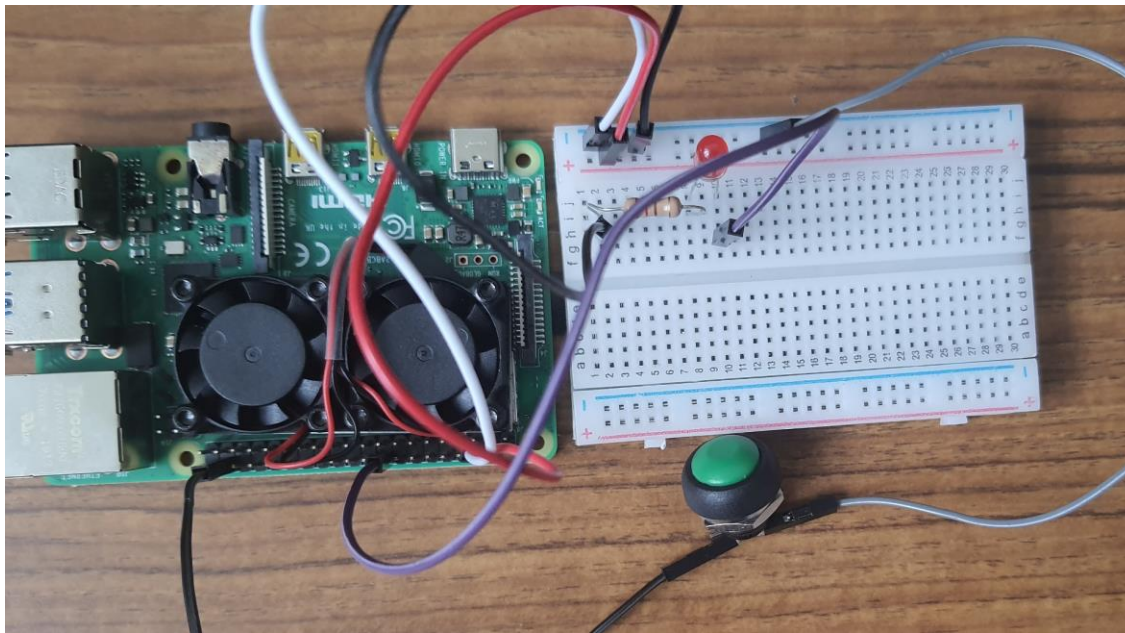
```
GPIO.setup(20, GPIO.IN, pull_up_down=GPIO.PUD_UP)#Button to GPIO20
GPIO.setup(24, GPIO.OUT) #LED to GPIO24
```

```
try:
    while True:
        button_state = GPIO.input(20)
        if button_state == False:
            GPIO.output(24, True)
            print('Button Pressed...')
            time.sleep(0.2)
        else:
            GPIO.output(24, False)
except:
    GPIO.cleanup()
```

# Controlling LED with Switch

Demo video:

<https://youtu.be/M9R75bi-ahA>

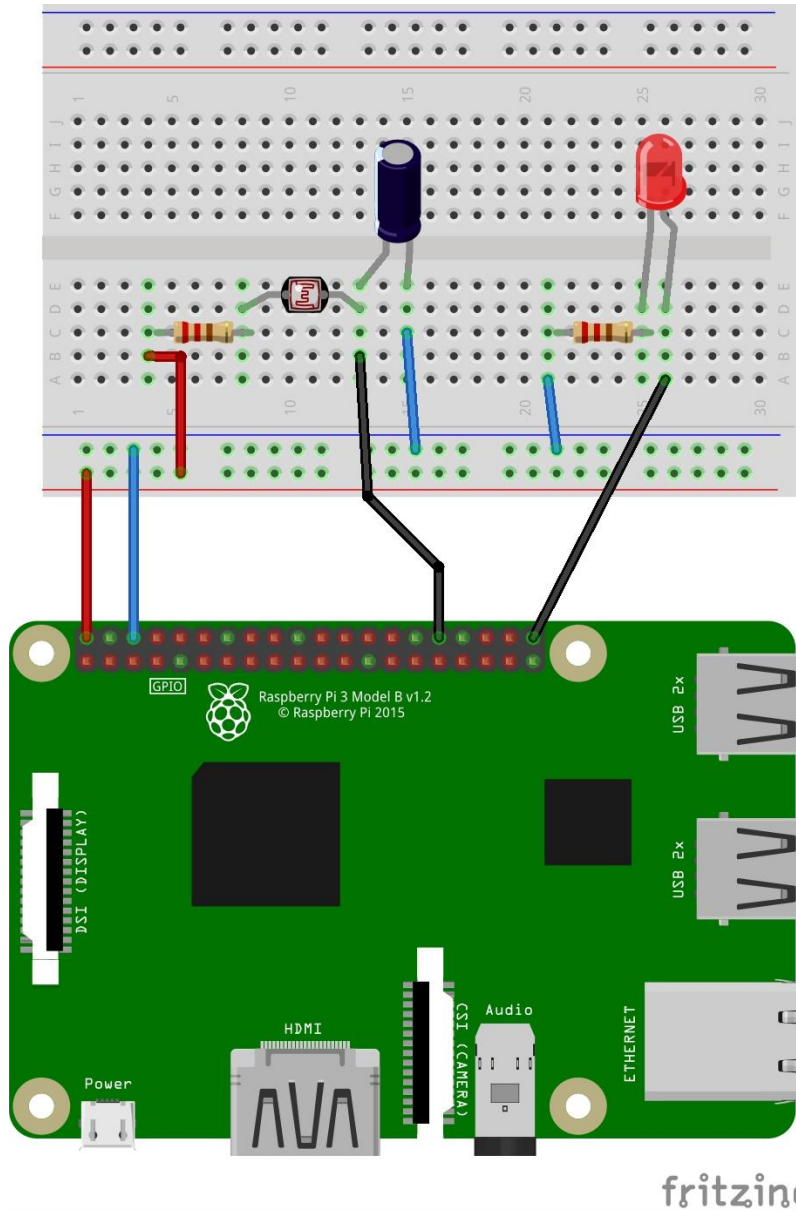




# Controlling LED with LDR Sensor

## Components :

- LED
- LDR (Light Dependent Resistor)
- Capacitor 1 $\mu$ F
- 2 Resistors (Orange, Orange, Brown, Gold)



```
import RPi.GPIO as GPIO
import time
```

```
GPIO.setmode(GPIO.BCM)
ldr_threshold = 30000
LDR_PIN = 12
LIGHT_PIN = 21
```

```
def readLDR(PIN):
    reading=0
    GPIO.setup(PIN, GPIO.OUT)
    GPIO.output(PIN, False)
    time.sleep(0.1)
    GPIO.setup(PIN, GPIO.IN)
    while (GPIO.input(PIN)==False):
        reading=reading+1
    return reading
```

```
def switchOnLight(PIN):
    GPIO.setup(PIN, GPIO.OUT)
    GPIO.output(PIN, True)
```

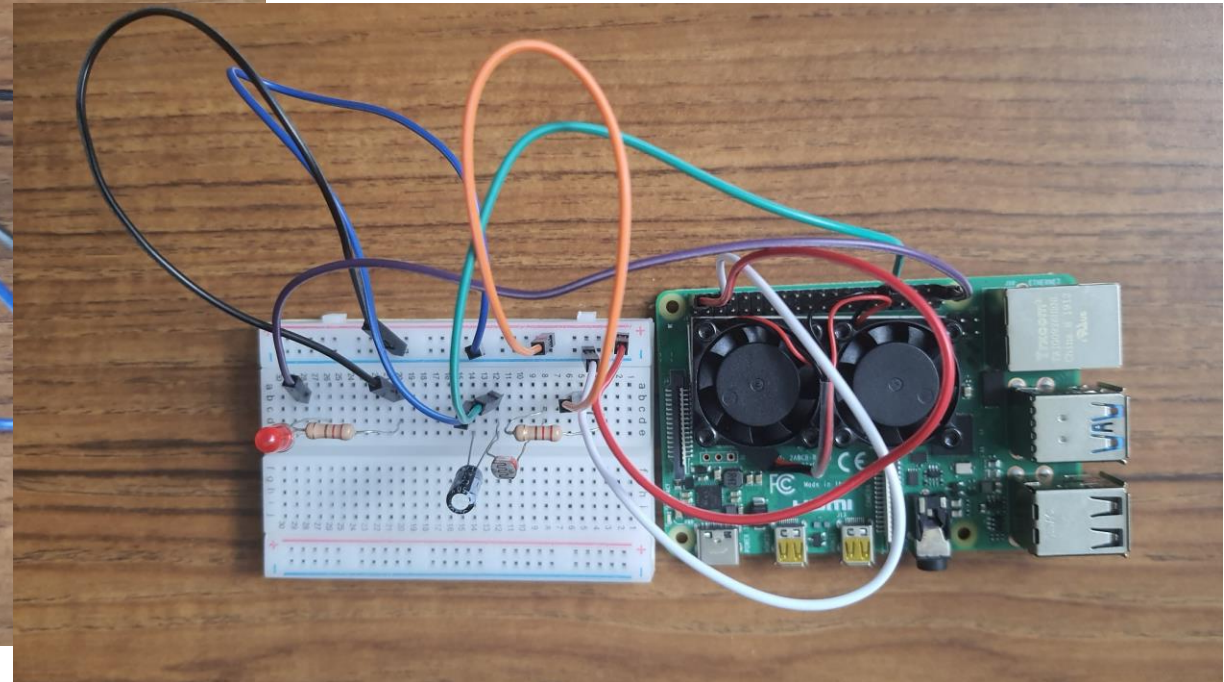
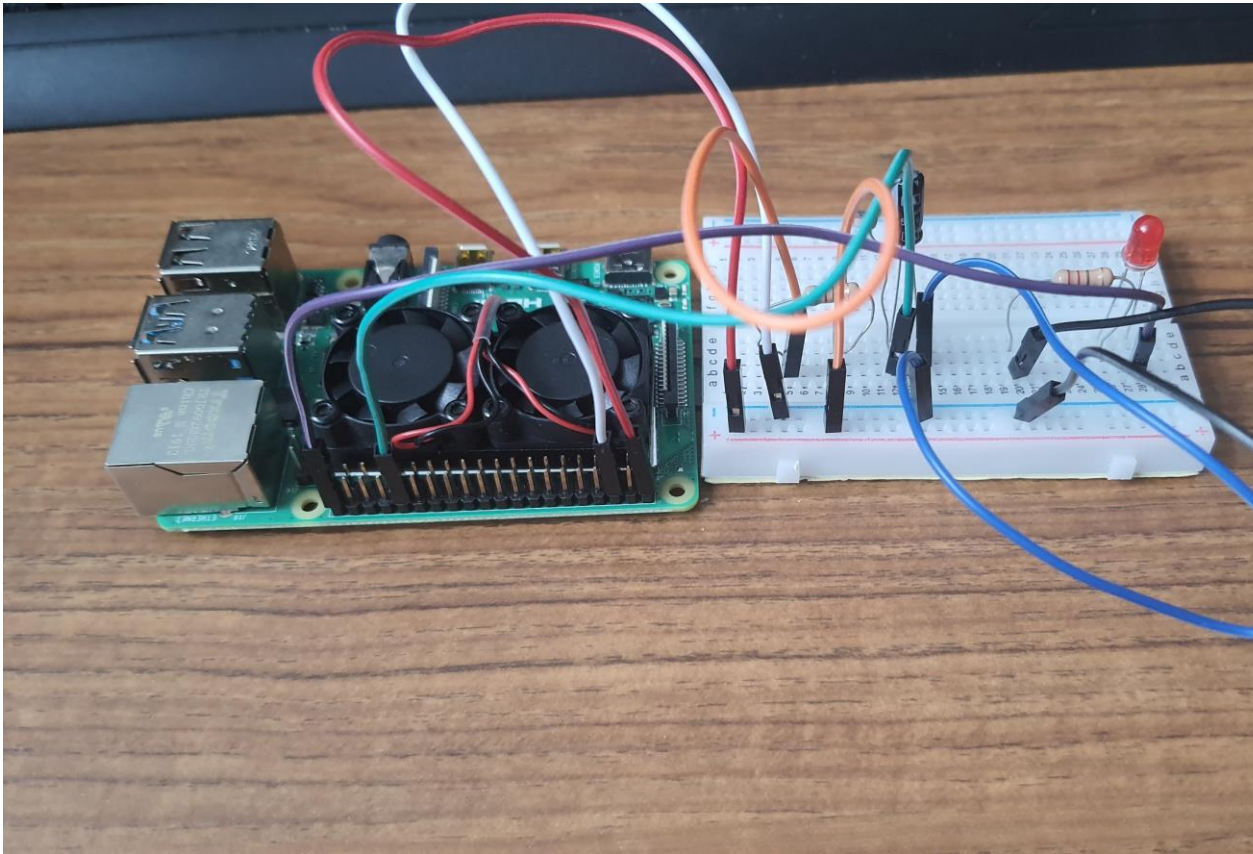
```
def switchOffLight(PIN):
    GPIO.setup(PIN, GPIO.OUT)
    GPIO.output(PIN, False)
```

```
while True:
    try:
        ldr_reading = readLDR(LDR_PIN)
        print(ldr_reading)
        if ldr_reading > ldr_threshold:
            switchOnLight(LIGHT_PIN)
        else:
            switchOffLight(LIGHT_PIN)
        time.sleep(1)
    except KeyboardInterrupt:33
        exit()
```

# Controlling LED with LDR Sensor

Demo video:

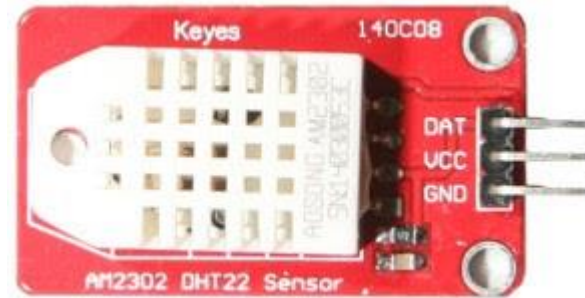
<https://youtu.be/uyhHY2IFaq4>



# Controlling LED with DHT Sensor

- Components :

- DHT11 or DHT22 Sensor
  - VCC (+)
  - GND (-)
  - DAT (data)



- Install some libraries

- `sudo apt-get update`
- `sudo apt-get upgrade`
- `sudo apt-get install python3-dev python3-pip`
- `sudo python3 -m pip install --upgrade pip setuptools wheel`
- `sudo pip3 install Adafruit_DHT`



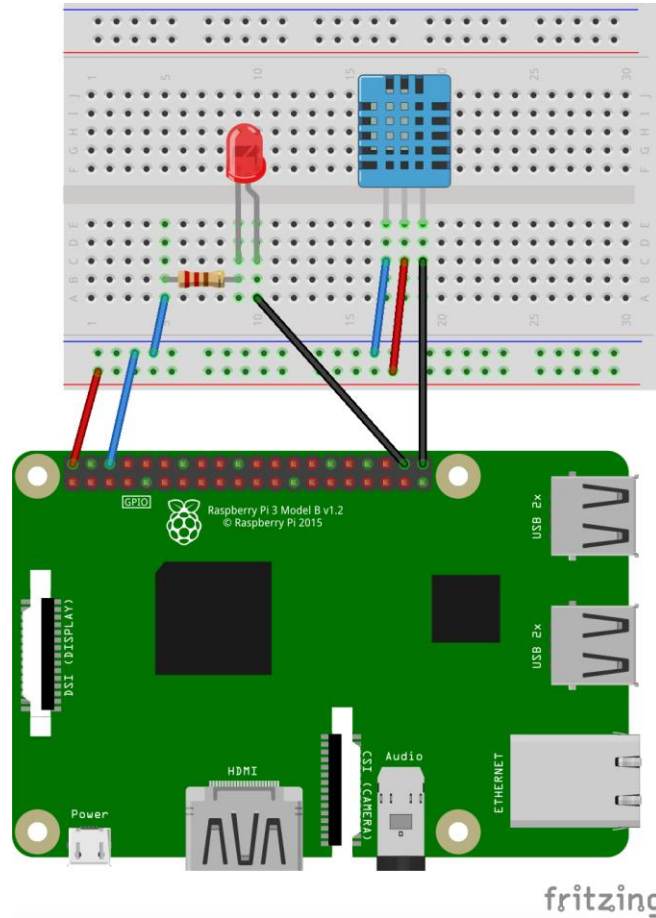
# Controlling LED with DHT Sensor

The circuit:

DAT : to GPIO

VCC : to Power

GND : to Ground



```
import Adafruit_DHT
import RPi.GPIO as GPIO
import time
```

```
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
DHT_SENSOR = Adafruit_DHT.DHT11
DHT_PIN = 21
```

```
humidity_threshold = 65
LIGHT_PIN = 20
```

```
def switchOnLight(PIN):
    GPIO.setup(PIN, GPIO.OUT)
    GPIO.output(PIN, True)
```

```
def switchOffLight(PIN):
    GPIO.setup(PIN, GPIO.OUT)
    GPIO.output(PIN, False)
```

```
while True:
    try:
        humidity, temperature = Adafruit_DHT.read_retry(DHT_SENSOR, DHT_PIN)
        if humidity is not None and temperature is not None:
            print("Temp={0:0.1f}*C Humidity={1:0.1f}%".format(temperature, humidity))
        else:
            print("Failed to retrieve data from humidity sensor")

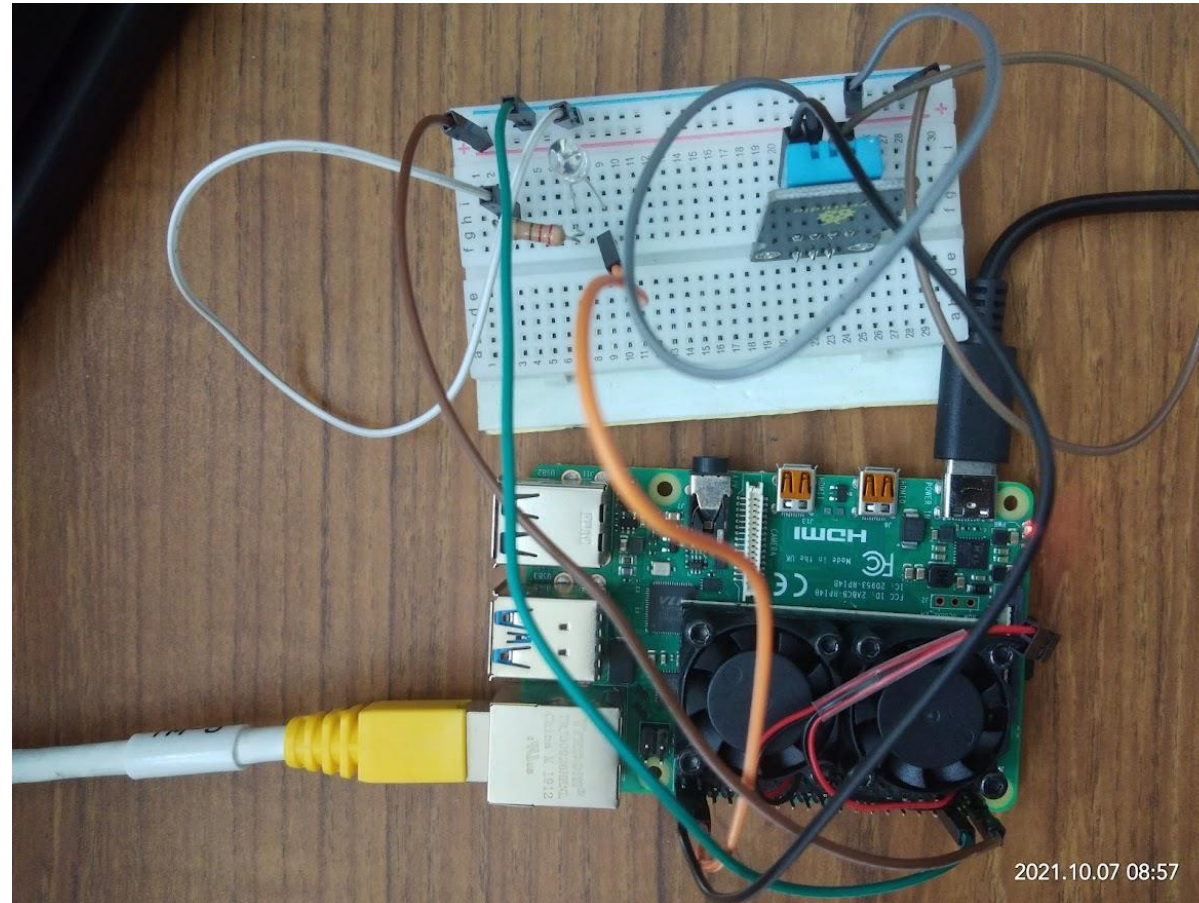
        if humidity > humidity_threshold:
            switchOnLight(LIGHT_PIN)
            print("SWITCH ON LIGHT")
        else:
            switchOffLight(LIGHT_PIN)

        time.sleep(1)
    except KeyboardInterrupt:
        exit()
```

# Controlling LED with DHT Sensor

Demo video:

<https://youtu.be/0fJ5V0zgsNo>



# Controlling LED with DHT Sensor

## Troubleshoot

- If you find an error like this one:

```
pi@raspberrypi:~/Documents $ python3 temperature.py
Traceback (most recent call last):
  File "temperature.py", line 8, in <module>
    humidity, temperature = Adafruit_DHT.read_retry(DHT_SENSOR, DHT_PIN)
  File "/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/common.py", line 94,
in read_retry
    humidity, temperature = read(sensor, pin, platform)
  File "/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/common.py", line 80,
in read
    platform = get_platform()
  File "/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/common.py", line 60,
in get_platform
    from . import Beaglebone_Black
  File "/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/Beaglebone_Black.py",
, line 24, in <module>
    from . import Beaglebone_Black_Driver as driver
ImportError: cannot import name 'Beaglebone_Black_Driver' from 'Adafruit_DHT' (/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/__init__.py)
```

# Controlling LED with DHT Sensor

## Troubleshoot

- After system updates, the hardware name in the /proc/cpuinfo on raspberry pi4 has been changed.

So, it is necessary to edit a `platform_detect.py` in `/usr/local/lib/python3.7/dist-packages/Adafruit_DHT/` directory. All you need it is add next few strings in `def pi_version():` function:



Code: **Select all**

```
elif match.group(1) == 'BCM2711':  
    return 3
```

# Assignment 1 - Specification

- Objectives:
  - Connect and read data from sensors
  - Connect and write data to control actuators
- Upload to E3 before 10/27 23:59PM
  - Assignment 1 – deliverables
    - Report (2-4 pages) in PDF and use the template that we provide
      - Explain the objective
      - Explain your source code and the detail of how your script can read and write your sensors and actuators, respectively
      - Link to a 3-minute demo video on YouTube
    - Source code
  - 1-page project proposal in PDF
    - Topic, objective, and sensors/actuators
    - Specs for Assignments 1, 2, and 3 (grow your IoT application instead of changing it for each assignment: Assignment 2 needs to store data to the cloud, while Assignment 3 needs to have two devices and run a program in the cloud)
  - Zip the above 3 files into one compressed file and upload
- Q&A? Post on E3 discussion board



# Assignment 1 - Specification

- Note for Assignment 1:
  - You must use different combinations of sensors and actuators than the ones we present
    - If using the same combinations, your maximum score is only 65.
  - The report can be written in Chinese or English, but the video must be delivered in English.
  - In video, explain how you assemble your sensors and actuators, how you connect it, and also explain your source code, and show the results.
  - Upload your video to YouTube and put the link into your report. Don't upload your video to E3.
  - In your report, make sure you have a diagram of connected sensors and actuators on your board (you can refer the diagram on page 29 and you can use "Fritzing" to draw it).

Enjoy it.