



Elektrobit



UDACITY

Functional Safety Concept Lane Assistance

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Document history

Date	Version	Editor	Description
03-04-2019	1.0	Akshat Yadav	Initial document

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Purpose of the Functional Safety Concept

The purpose of the functional safety concept is to identify system level requirements and allocate these requirements to high level system diagrams for the functional safety project. Technical safety requirements will be derived from these safety concepts.

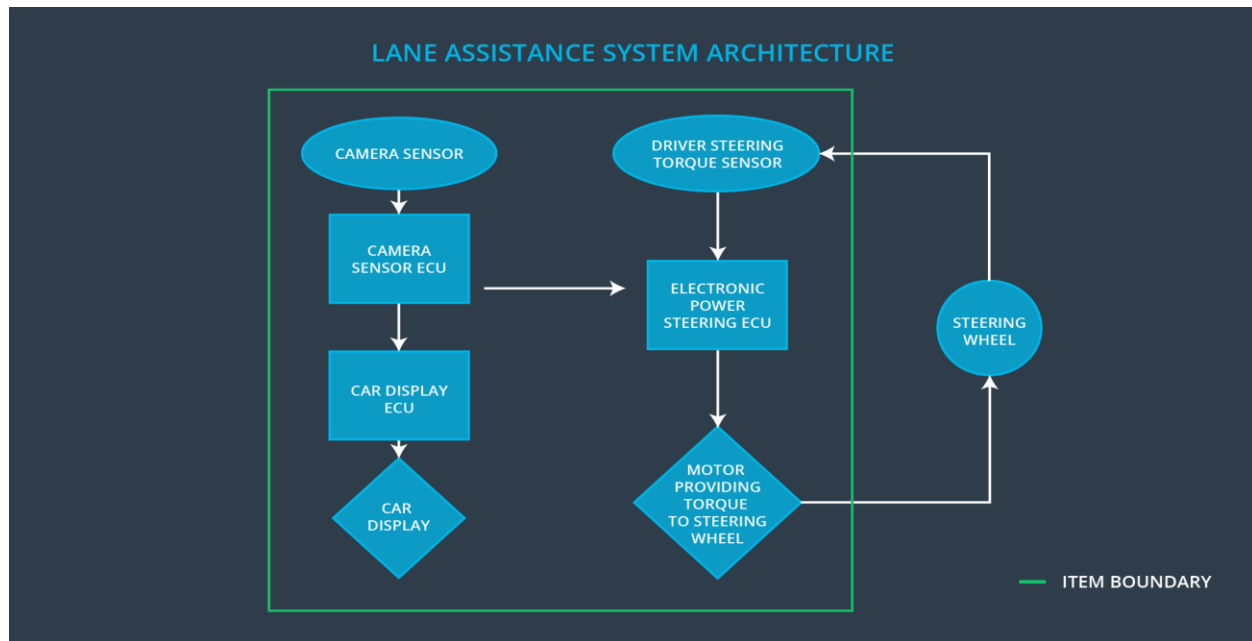
Inputs to the Functional Safety Concept

Safety goals from the Hazard Analysis and Risk Assessment

ID	Safety Goal
Safety_Goal_01	The oscillating steering torque from the Lane Departure Warning function shall be limited.
Safety_Goal_02	The Lane Keeping Assistance function shall be time limited, and additional steering torque shall end after a given time interval so the driver cannot misuse the system for autonomous driving.
Safety_Goal_03	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.
Safety_Goal_04	The Lane Keeping Assistance function shall be deactivated when the camera sensor stop working.

Preliminary Architecture

The following figure shows the Lane Assistance item architecture:



Description of architecture elements

Element	Description
Camera Sensor	Sensor responsible for capturing vehicle driving condition including detectable lane lines.
Camera Sensor ECU	Responsible for detecting lane lines and determining when the vehicle leaves the lane by mistake.
Car Display	Provide feedback to the driver displaying warnings and the Lane Departure Assistance status.
Car Display ECU	Responsible for displaying warning of lane departures, Lane Keeping Assistance (LKA) & Lane Departure Warning (LDW) activation and deactivations on the Car Display
Driver Steering Torque Sensor	Measure the torque applied to the steering wheel by the driver.
Electronic Power Steering ECU	Responsible for measuring the torque provided by the driver and adding appropriate amount of torque based on a LKA system torque request, and vibrates the steering wheel when the driver drifts away from center by mistake (LDW).
Motor	Actuator responsible for applying requested torque by the Electronic Power Steering ECU for either the LKA or the LDW functions to the steering column

Functional Safety Concept

The functional safety concept consists of:

- Functional safety analysis
- Functional safety requirements
- Functional safety architecture
- Warning and degradation concept

Functional Safety Analysis

Malfunction ID	Main Function of the Item Related to Safety Goal Violations	Guidewords (NO, WRONG, EARLY, LATE, MORE, LESS)	Resulting Malfunction
Malfunction_01	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The Lane Departure Warning function applies an oscillating torque with very high torque amplitude (above limit)
Malfunction_02	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The Lane Departure Warning function applies an oscillating torque with very high torque frequency (above limit)
Malfunction_03	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	NO	The Lane Keeping Assistance function is not limited in time duration which lead to misuse as an autonomous driving function.
Malfunction_04	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.	WRONG	The Lane Departure Warning start acting randomly when the camera sensor is not working.

Malfunction_05	The Lane Keeping Assistance function shall be deactivated when the camera sensor stop working.	WRONG	The Lane Keeping Assistance start acting randomly when the camera sensor is not working.
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Functional Safety Requirements

Lane Departure Warning (LDW) Requirements:

ID	Functional Safety Requirement	A S I L	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below MAX_Torque_Amplitude	C	50 ms	Set vibration torque amplitude to zero
Functional Safety Requirement 01-02	The lane keeping item shall ensure that the lane departure oscillating torque frequency is below MAX_Torque_Frequency	C	50 ms	Set vibration torque frequency to zero.
Functional Safety Requirement 01-03	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.	C	10 ms	Function is deactivated.

Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 01-01	Validate Max_Torque_Amplitude chosen is high enough to be detected by a driver while low enough not to cause loss of steering	Verify the system does turn off if the Lane Departure Warning exceeded Max_Torque_Amplitude.

Functional Safety Requirement 01-02	Validate Max_Torque_Frequency chosen is adequate to be detected by the driver and not cause the loss of steering.	Verify the system does turn off if the Lane Departure Warning exceeded Max_Torque_Frequency.
Functional Safety Requirement 01-03	Validate Lane Departure Warning is off when the camera sensor is not working.	Verify the Lane Departure Warning is never on when the camera sensor is not working.

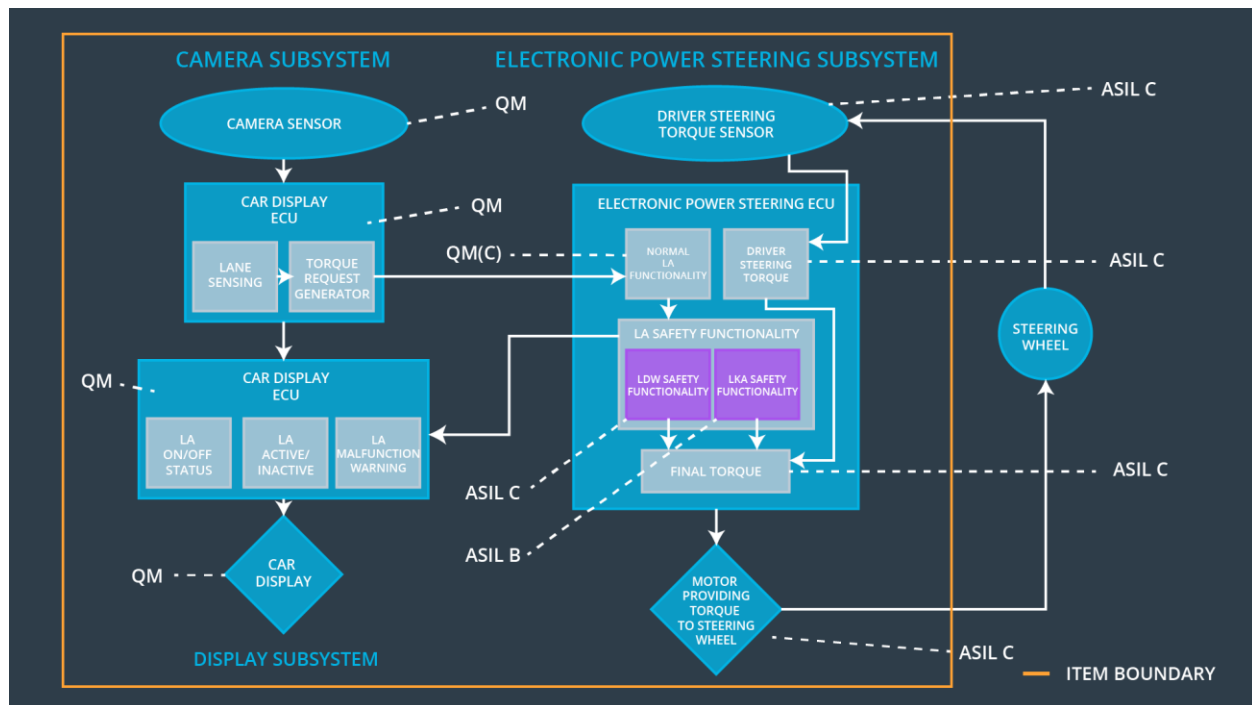
Lane Keeping Assistance (LKA) Requirements:

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max_Duration	B	500 ms	Lane Keeping Assistance torque is zero.
Functional Safety Requirement 02-02	The Lane Keeping assistance shall be deactivated when the electronic power steering ECU detects the camera sensor is not working.	C	10 ms	Function is deactivated.

Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 02-01	Validate the Max_Duration chosen not allow the driver to use the car as self-driving car.	Verify the system does deactivate if the Lane Keeping Assistance torque application exceeded Max_Duration.
Functional Safety Requirement 02-02	Validate the Lane Keeping assistance shall be deactivated when the camera sensor stop working.	Verify the system does deactivate the Lane Keeping Assistance if the camera sensor is not working.

Refinement of the System Architecture



Allocation of Functional Safety Requirements to Architecture Elements

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The Lane Departure Warning item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude.	X		
Functional Safety Requirement 01-02	The Lane Departure Warning item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency.	X		

Functional Safety Requirement 01-03	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.	X		
Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the Lane Keeping Assistance torque is applied only Max_Duration.	X		
Functional Safety Requirement 02-02	The Lane Keeping assistance shall be deactivated when the electronic power steering ECU detects the camera sensor is not working.	X		

Warning and Degradation Concept

ID	Degradation Mode	Trigger for Degradation Mode	Safe State invoked?	Driver Warning
WDC-01	Turn off Lane Departure Warning functionality	Malfunction_01, Malfunction_02, Malfunction_04	Yes	Lane Departure Warning Malfunction Warning on Car Display
WDC-02	Turn off Lane Keeping Assistance functionality	Malfunction_03, Malfunction_05	Yes	Lane Keeping Assistance Malfunction Warning on Car Display