

DSP Basics - Prof Ryan Robucci - This notebook introduces some basic code processes required in the field of DSP

A good reference for getting started with numpy and plotting

<https://www.labri.fr/perso/nrougier/teaching/matplotlib/>
(<https://www.labri.fr/perso/nrougier/teaching/matplotlib/>)

(This is a documentation cell, note I can use latex: ω)

The cell below contains the function zplane which is not commonly included with python packages

To use it your own code you can download the file

- <https://bitbucket.org/cfelton/examples/raw/f3383e14f18a57852e17c10ee4cd316fbfafbf85/snippet>
(<https://bitbucket.org/cfelton/examples/raw/f3383e14f18a57852e17c10ee4cd316fbfafbf85/snippet>)

Then use the following import in your python code:

- `from plot_zplane import zplane`




```

In [1]: #
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#
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#

# The following is derived from the slides presented by
# Alexander Kain for CS506/606 "Special Topics: Speech Signal Processing"
# CSLU / OHSU, Spring Term 2011.
#
# 2017/03/04 Ryan Robucci - changed plot radius to expand to 10% beyond largest

import numpy as np
import matplotlib.pyplot as plt
from matplotlib import patches
from matplotlib.figure import Figure
from matplotlib import rcParams

def zplane(b,a,filename=None):
    """Plot the complex z-plane given a transfer function.
    """

    # get a figure/plot
    ax = plt.subplot(111)

    # create the unit circle
    uc = patches.Circle((0,0), radius=1, fill=False,
                        color='black', ls='dashed')
    ax.add_patch(uc)

    # The coefficients are less than 1, normalize the coefficients
    if np.max(b) > 1:
        kn = np.max(b)
        b = b/float(kn)
    else:
        kn = 1

    if np.max(a) > 1:
        kd = np.max(a)
        a = a/float(kd)
    else:
        kd = 1

    # Get the poles and zeros
    p = np.roots(a)
    z = np.roots(b)

```

```

k = kn/float(kd)

# Plot the zeros and set marker properties
t1 = plt.plot(z.real, z.imag, 'go', ms=10)
plt.setp( t1, markersize=10.0, markeredgewidth=1.0,
          markeredgewidth=1.0, markeredgewidth=1.0, markerfacecolor='g')

# Plot the poles and set marker properties
t2 = plt.plot(p.real, p.imag, 'rx', ms=10)
plt.setp( t2, markersize=12.0, markeredgewidth=3.0,
          markeredgewidth=3.0, markeredgewidth=3.0, markerfacecolor='r')

ax.spines['left'].set_position('center')
ax.spines['bottom'].set_position('center')
ax.spines['right'].set_visible(False)
ax.spines['top'].set_visible(False)

# set the ticks
#RWR: the following has been modified to fit larger-magnitude roots and mar
r = 1.1*max(1.5/1.1,np.abs(np.concatenate((p.real,p.imag,z.real,z.imag))).n
plt.axis('scaled');
if r<1.6:
    ticks = [-1, -.5, .5, 1];
elif r<5:
    ticks = [-2,-1, -.5, .5, 1,2];
elif r<10:
    ticks = [-5,-2,-1,1,2,5];
elif r<20:
    ticks = [-10,-1,1,10];
else:
    rlog = np.ceil(np.log10(r))
    ticks = np.arange(-(10**rlog),(10**rlog)+1,10**(rlog-1)*2);

plt.xticks(ticks);
plt.yticks(ticks)
plt.axis([-r, r, -r, r])

if filename is None:
    plt.show()
else:
    plt.savefig(filename)

return z, p, k

```

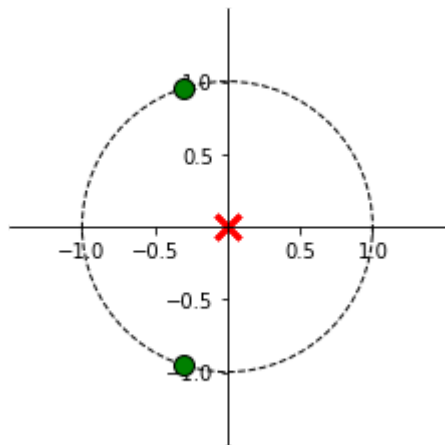
$$\mathcal{Z}^{-1}\{1 + z^{-1} + z^{-2} + z^{-3}\} = \delta[n] + 2\delta[n-1] + 2\delta[n-2] + \delta[n-3]$$

```
In [13]: import numpy as np
#          z^-2 + 0.618z^-1+1
# H(z)= -----
#          2.618
b = np.array([1,0.618,1])
b=b/sum(b)
a = np.array([1, 0, 0])
```

```
In [36]: [z,p,g] = signal.tf2zpk(b, a)
print('P:',p)
print('Z:',z)
print('G:',g)
[b,a] = signal.zpk2tf(z, p*10, g)
print('b:',b)
print('a:',a)
```

```
P: [0. 0.]
Z: [-0.309+0.95106204j -0.309-0.95106204j]
G: 0.38197097020626436
b: [0.38197097 0.23605806 0.38197097]
a: [1. 0. 0.]
```

```
In [37]: zplane(b,a)
plt.show()
```



```
In [15]: from scipy import signal #https://docs.scipy.org/doc/scipy-0.18.1/reference/sig
```

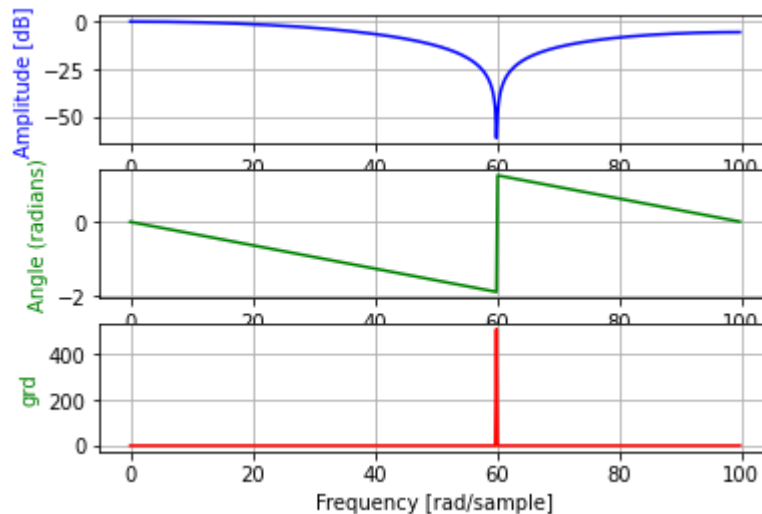
```
In [28]: w, H = signal.freqz(b,a)
fs=200
ww=(fs*w)/(2*np.pi)
```

```

In [29]: import matplotlib.pyplot as plt
plt.subplot(311)
plt.plot(w, 20 * np.log10(np.abs(H)), 'b')
plt.ylabel('Amplitude [dB]', color='b')
plt.xlabel('Frequency [rad/sample]')
plt.grid(True)
plt.axis('tight')
plt.subplot(312)
angles = np.unwrap(np.angle(H))
plt.plot(w, angles, 'g')
plt.ylabel('Angle (radians)', color='g')
plt.xlabel('Frequency [rad/sample]')
plt.grid(True)
plt.axis('tight')

plt.subplot(313)
grd = np.diff(angles)/np.diff(w)
grd_temp=np.append(grd,0)
plt.plot(w, grd_temp, 'r')
plt.ylabel('grd', color='g')
plt.xlabel('Frequency [rad/sample]')
plt.grid(True)
plt.axis('tight')
plt.show()

```



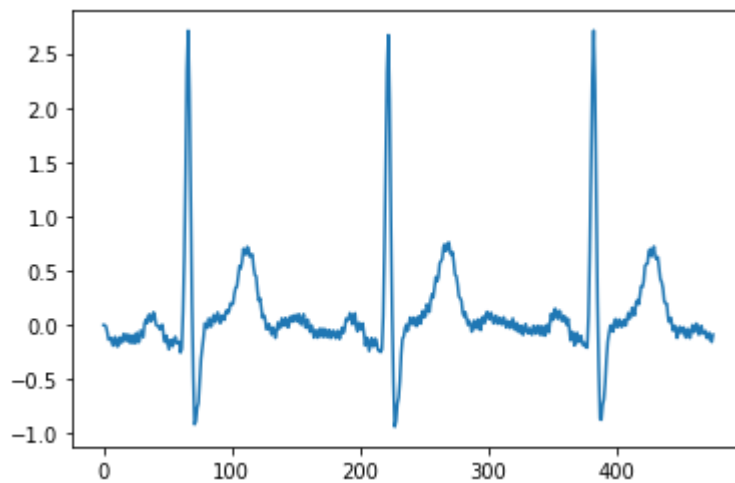
```

In [45]: ecg = np.genfromtxt('ecg2x60.dat')

```

```
In [47]: plt.plot(ecg)
```

```
Out[47]: [<matplotlib.lines.Line2D at 0x20eb25d9d60>]
```



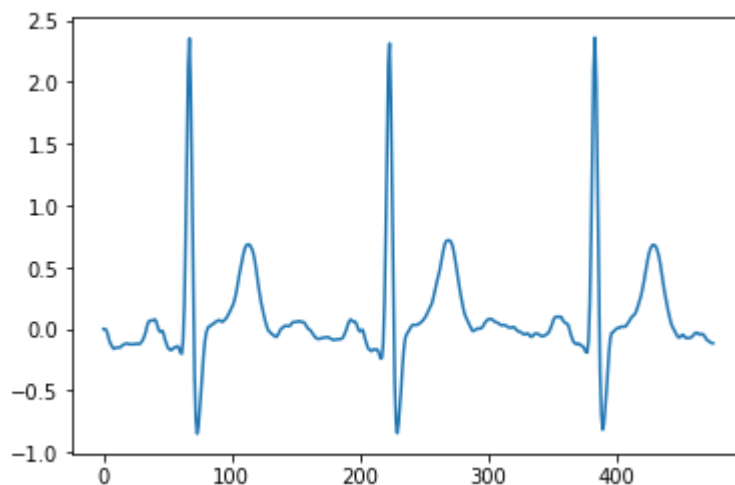
Note the "group" or "range" of frequencies with a localized, generalized linear delay

What group delay does it correspond to?

```
In [48]: filtered_ecg = signal.lfilter(b,a,ecg)
```

```
In [49]: plt.plot(filtered_ecg)
```

```
Out[49]: [<matplotlib.lines.Line2D at 0x20eb23fe670>]
```

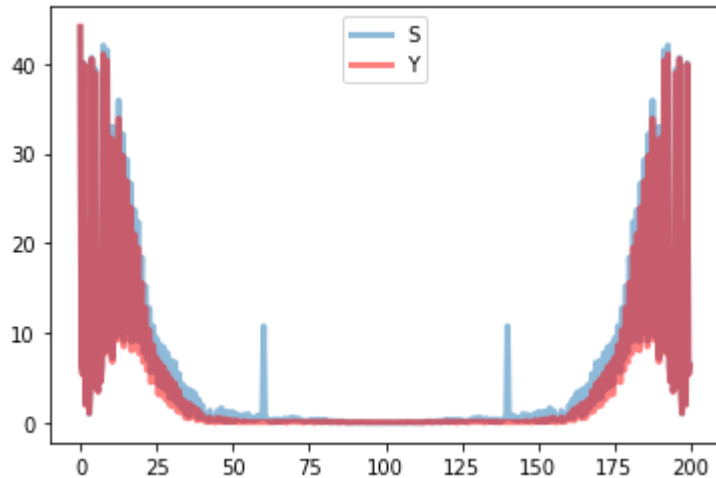


```
In [50]: import numpy as np
S = np.fft.fft(ecg) # https://docs.scipy.org/doc/numpy/reference/routines.fft.html
Y = np.fft.fft(filtered_ecg)
```

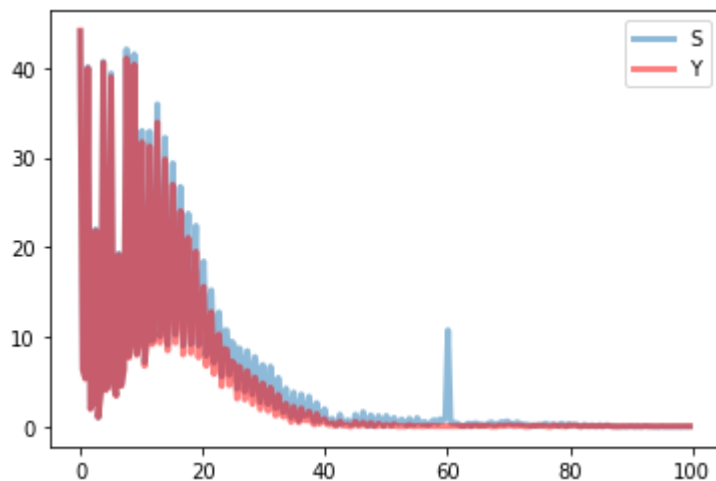
```
In [58]: len(omega)
```

```
Out[58]: 476
```

```
In [65]: dF = fs/476;
f = np.arange(-fs/2,(fs/2),dF);
plt.plot(f+fs/2,np.abs(S), label = 'S',linewidth=3,alpha=.5) # in matlab extra
plt.plot(f+fs/2,np.abs(Y), label = 'Y',linewidth=3,alpha=.5,color='r')
plt.legend()
plt.axis('tight')
plt.show()
```



```
In [59]: omega = 2 * np.pi * np.arange(len(S))/len(S)
omega=(omega*fs)/(2 * np.pi)
plt.plot(omega[0:int(476/2)],np.abs(S[0:int(476/2)]), label = 'S',linewidth=3,a
plt.plot(omega[0:int(476/2)],np.abs(Y[0:int(476/2)]), label = 'Y',linewidth=3,a
plt.legend()
plt.axis('tight')
plt.show()
```



```
In [68]: Eecg=np.sum(ecg**2)
Eecg
```

Out[68]: 94.49460053477425


```
In [69]: Efiltecg=np.sum(filtered_ecg**2)
Efiltecg
```

```
Out[69]: 83.42150042053937
```

```
In [77]: snr=np.log(Eecg/Efiltecg)
```

```
In [78]: snr
```

```
Out[78]: 0.12463662072142397
```

Next, we rerun the magnitude plot earlier to verify that the gain at the input frequency is a little above 4×

We expect a 1.5 sample group delay, based on the center of mass of the impulse response or the derivative of the phase response