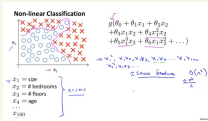


Need of NN:

- Consider a classification problem (binary) that is not linear.
- We use polynomial logistic regression for drawing a decision boundary.
- From the fig. it can be seen that a poly. decision boundary can be found.
- * - But what if $p > 2$, like $p = 100$
 - The no. of parameters will be more than 100 (4150 considering interaction with degree = 2)
 - This will cause overfitting.

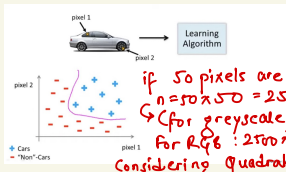
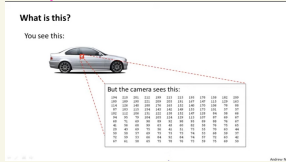


+ NN is majorly used in "Computer Vision:"

+ An object is viewed as a matrix of **pixel intensity values** and trained using these matrices.

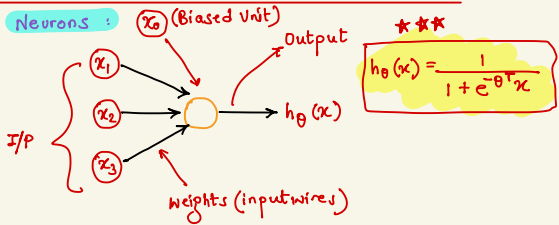
+ Learning Algorithm (CV):

- Pixels with same intensity are fed to the model. (Positive for cars, negative for other objects)
- Then the separation (decision) boundary is found for classification.



if 50 pixels are consi.
 $n = 50 \times 50 = 2500$ features
 (for greyscale)
 for RGB: $2500 \times 3 = 7500$
 considering quadratic features: 3 million!!

Neurons:



Sigmoid / Activation function:

$$g(z) = \frac{1}{1 + e^{-z}}$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{bmatrix}$$

θ weights (parameters) like $\theta_0, \theta_1, \dots, \theta_p$

Forward propagation: Vectorized implementation



$$a_1^{(2)} = g(\theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \theta_{12}^{(1)} x_2 + \theta_{13}^{(1)} x_3)$$

$$a_2^{(2)} = g(\theta_{20}^{(1)} x_0 + \theta_{21}^{(1)} x_1 + \theta_{22}^{(1)} x_2 + \theta_{23}^{(1)} x_3)$$

$$a_3^{(2)} = g(\theta_{30}^{(1)} x_0 + \theta_{31}^{(1)} x_1 + \theta_{32}^{(1)} x_2 + \theta_{33}^{(1)} x_3)$$

$$h_\theta(x) = g(\theta_{10}^{(2)} a_0^{(2)} + \theta_{11}^{(2)} a_1^{(2)} + \theta_{12}^{(2)} a_2^{(2)} + \theta_{13}^{(2)} a_3^{(2)})$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$z^{(2)} = \theta^{(1)} x \quad (2D) \quad *$$

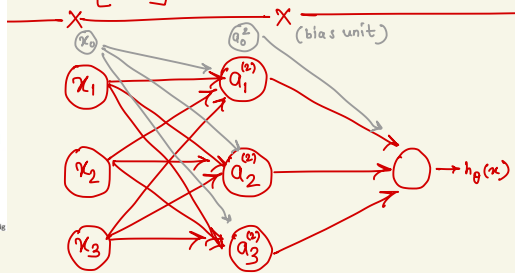
$$\text{and } a^{(2)} = g(z^{(2)}) \quad (3D)$$

$$\text{Add } a_0^{(2)} = 1$$

$$\Rightarrow a^{(2)} = 4D *$$

$$z^{(3)} = \theta^{(2)} a^{(2)}$$

$$h_\theta(x) = a^{(3)} = g(z^{(3)})$$



Layer 1 (input layer) Layer 2 (hidden layer) Layer 3 (output layer)

Neural Network

$\rightarrow a_i^{(j)}$ = "activation" of unit i in layer j

$\rightarrow \theta^{(j)}$ = matrix of weights controlling function mapping from layer j to layer $j+1$

$$a_1^{(2)} = g(\theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \theta_{12}^{(1)} x_2 + \theta_{13}^{(1)} x_3)$$

$$a_2^{(2)} = g(\theta_{20}^{(1)} x_0 + \theta_{21}^{(1)} x_1 + \theta_{22}^{(1)} x_2 + \theta_{23}^{(1)} x_3)$$

$$a_3^{(2)} = g(\theta_{30}^{(1)} x_0 + \theta_{31}^{(1)} x_1 + \theta_{32}^{(1)} x_2 + \theta_{33}^{(1)} x_3)$$

$$h_\theta(x) = a_1^{(3)} = g(\theta_{10}^{(2)} a_0^{(2)} + \theta_{11}^{(2)} a_1^{(2)} + \theta_{12}^{(2)} a_2^{(2)} + \theta_{13}^{(2)} a_3^{(2)})$$

$$\theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \theta_{12}^{(1)} x_2 + \theta_{13}^{(1)} x_3 = z_1^{(1)} \Rightarrow a_1^{(1)} = g(z_1^{(1)})$$

$$\Rightarrow \text{Similarly, } a_2^{(2)} = g(z_2^{(2)})$$

$$a_3^{(2)} = g(z_3^{(2)})$$

"Forward Propagation"