

Nexus Robotics Q4 2025 Product Report

Company Overview

Nexus Robotics, founded in 2019 by Dr. Sarah Chen in Austin, Texas, specializes in autonomous warehouse robots. The company has 847 employees across 12 global offices. In Q4 2025, Nexus achieved \$124.5 million in revenue, representing a 34% year-over-year growth. The flagship product, the NX-7 Navigator, captured 28% market share in the North American warehouse automation sector.

NX-7 Navigator Specifications

The NX-7 Navigator is a fully autonomous mobile robot designed for warehouse logistics. It uses LiDAR-based navigation with a proprietary PathSense AI system that achieves 99.7% obstacle avoidance accuracy. The robot can operate continuously for 16 hours on a single charge and supports payloads up to 500 kg.

Specification	Value	Notes
Maximum Payload	500 kg	Tested at 23°C
Battery Life	16 hours	Under standard load
Navigation Accuracy	±2 cm	Using PathSense AI
Maximum Speed	2.5 m/s	Empty, flat surface
Operating Temperature	-10°C to 45°C	Indoor use only
Weight (empty)	185 kg	Includes battery
Dimensions (LxWxH)	120x80x45 cm	Collapsed position

Regional Sales Performance

Q4 2025 sales were led by the North American market, which contributed \$67.2 million (54% of total). Europe generated \$31.1 million (25%), while Asia-Pacific accounted for \$26.2 million (21%). The company deployed 1,247 NX-7 units during the quarter, with Amazon being the largest customer at 312 units. Other major customers included DHL (186 units) and FedEx (143 units).

Region	Revenue	Units Sold	Growth YoY
North America	\$67.2M	673	+38%
Europe	\$31.1M	298	+29%

Asia-Pacific	\$26.2M	276	+41%
Total	\$124.5M	1,247	+34%

2026 Outlook

Nexus Robotics plans to launch the NX-8 Navigator in March 2026, featuring extended 24-hour battery life and 750 kg payload capacity. The company projects Q1 2026 revenue of \$145 million, driven by expansion into the Latin American market and a new partnership with Walmart for 500 units. R&D; investment will increase to \$18 million, focusing on computer vision improvements and fleet coordination algorithms.