



GEBZE TECHNICAL UNIVERSITY
ENGINEERING FACULTY
ELECTRONICS ENGINEERING

ELEC 334

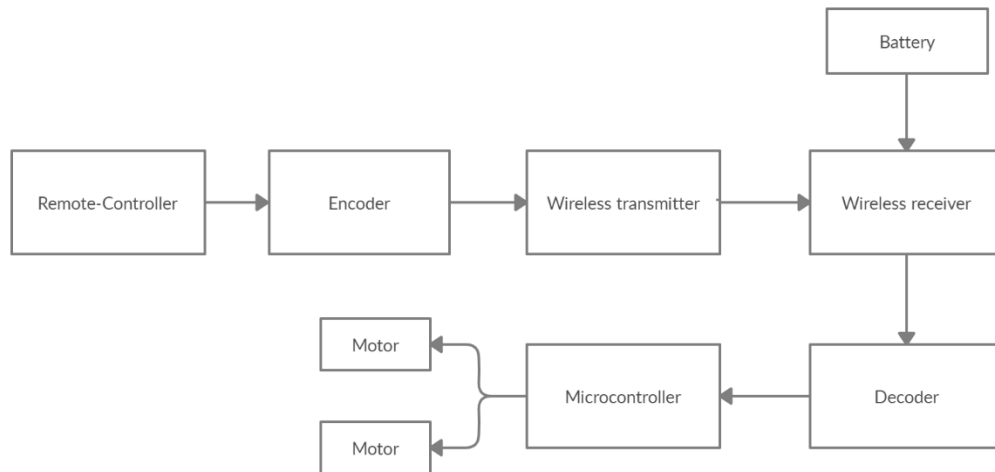
MICROPROCESSORS

HW1

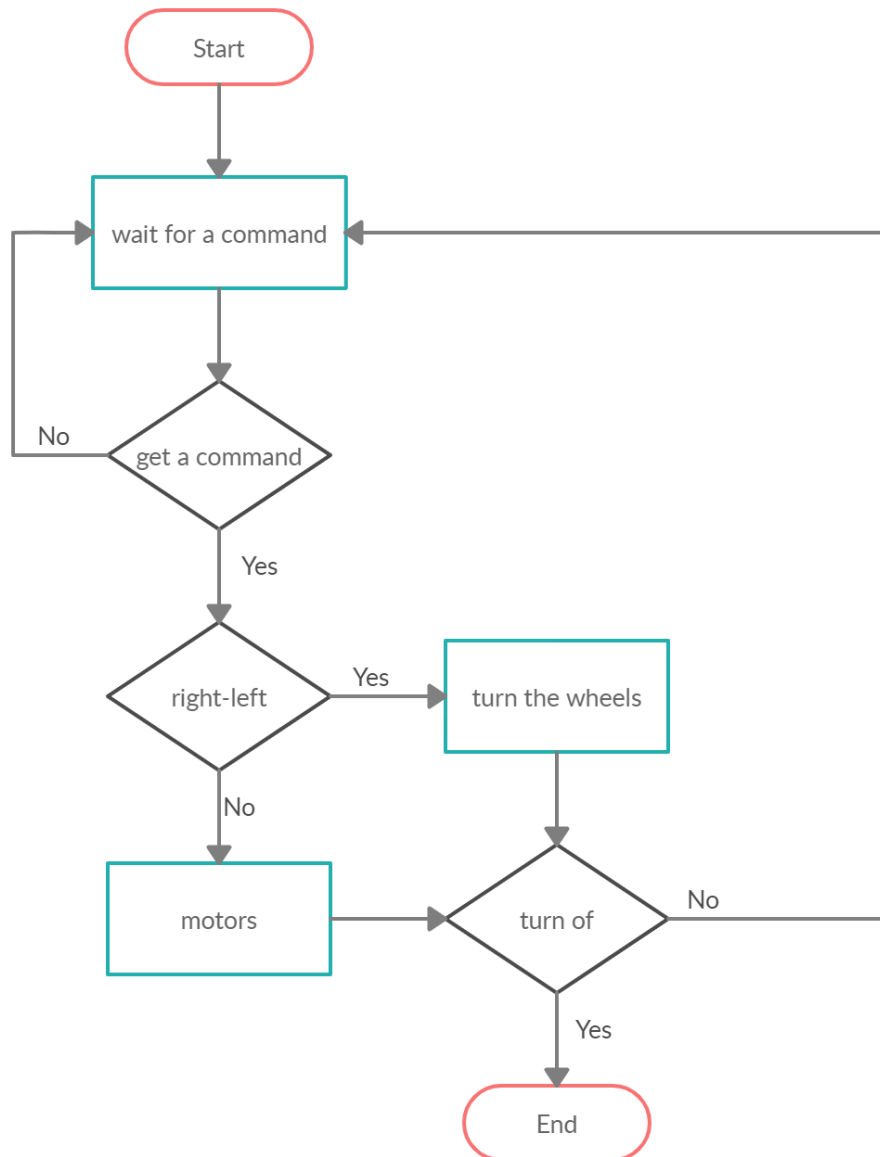
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Problem 1.

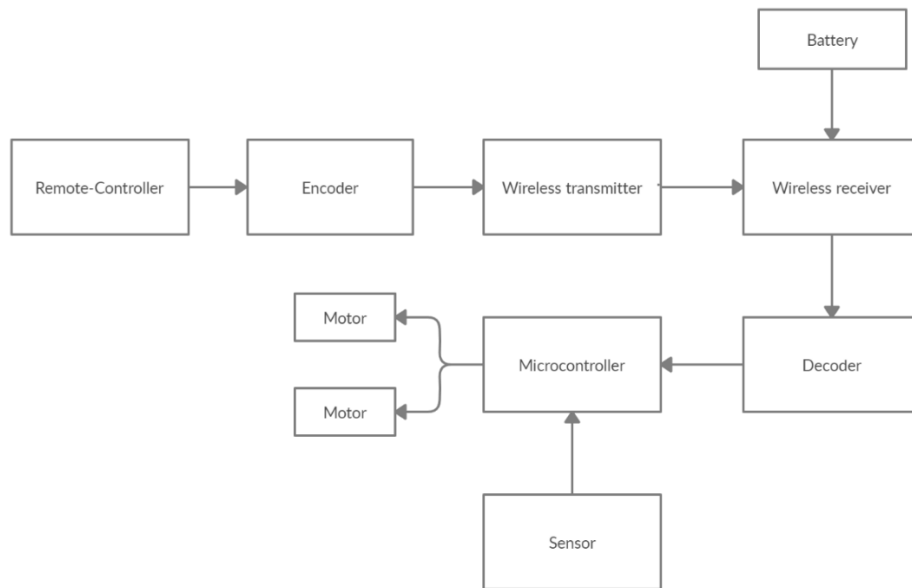
The block diagram of a remote-controlled 2-motor 3-wheel robot:



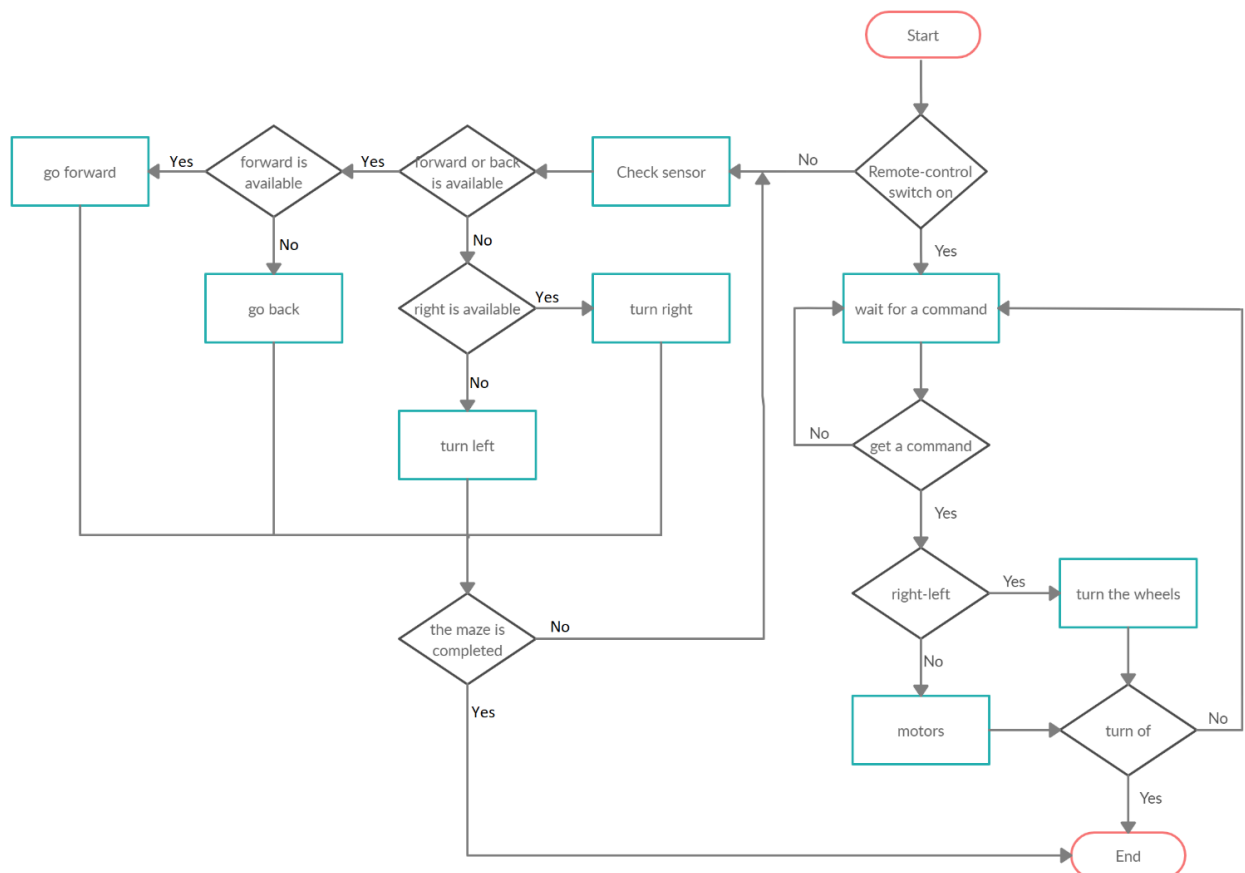
The flowchart of a remote-controlled 2-motor 3-wheel robot:



Problem 2. The block diagram of an autonomous robot which can be used with remote-control functional by using a switch.



The flowchart of an autonomous robot which can be used with remote-control functional by using a switch.:



The sensor might be a radar sensor, which sends out radio waves that detect objects and speed in relation to the vehicle in real time, or a lidar sensor, which uses lasers instead of radio waves, in this problem.

Problem 3. The C code of the logger function that will remember all the locations the robot travelled and counts the number of steps until the robot finishes its move.

```
#include<stdio.h>
#include<stdlib.h>
#include<time.h>

#define SIZE 100

typedef struct Position{ // The position of the robot in the maze
    int num;
    char let;
} Position;

typedef struct Queue{ // The data structure that keeps the all the previous moves.
    struct Queue *next; // next position
    struct Position* pos; // current position
    int size;
} Queue;

void logger(struct Position moves[], int size);
struct Position* random_moves(struct Position moves[], int size);
struct Queue* createQueue(struct Position* p);
void push(struct Position* next_p, struct Queue* current);
void print_moves(struct Queue* head, int size);

int main(){
    srand((unsigned)time(NULL)); // srand() makes use of the computer's internal clock to control the
    choice of the seed, by this way random values always change

    int size = rand() % 50 + 1; // assigns random size values for moves array with a top limit which is 50
    so we can check easily.
    struct Position moves[size]; // random_moves
    random_moves(moves, size);

    /* // to check if the print_moves function works true
    int i;
        for(i=0; i<size; i++){
            printf("%c%d-", moves[i].let, moves[i].num);
        }
    printf("\n");
    */

    logger(moves, size);

    return 0;
}

void logger(struct Position moves[], int size){

    struct Position* first_p = (struct Position*)malloc(sizeof(struct Position));
    first_p->let = moves[0].let;
    first_p->num = moves[0].num;
    struct Queue* queue = createQueue(first_p); // assigns first position to queue

    struct Queue* head = queue; // keeps head of the queue in order to not lose head

    int i;
    for(i=1; i<size; i++){
        struct Position* p = (struct Position*)malloc(sizeof(struct Position));
        p->let = moves[i].let;
        p->num = moves[i].num;

        push(p, queue);
    }
}
```

```

        queue = queue->next;
        queue -> next = NULL; // clears next for the next loops for any problems
    }

    print_moves(head, size);
}

void print_moves(struct Queue* head, int size){
    printf("Path followed:\n");
    int i;
    for(i=0; i<size; i++){
        printf("%c%d", head->pos->let, head->pos->num);
        if(i != size-1){
            printf(", ");
        }
        head = head->next;
    }
    printf("\nTotal moves: %d", size);
}

struct Queue* createQueue(struct Position* p){
    struct Queue* queue = (struct Queue*)malloc(sizeof(struct Queue));
    queue->size = SIZE;
    queue->next = NULL;
    queue->pos = p;
    return queue;
}

void push(struct Position* next_p, struct Queue* current){
    current->next = (struct Queue*)malloc(sizeof(struct Queue));
    current->next->pos = next_p;
}

struct Position* random_moves(struct Position moves[], int size){
    int i;
    char letters[8] = {'A', 'B', 'C', 'D', 'E', 'F', 'G', 'H'};

    for(i=0; i<size; i++){
        moves[i].num = rand() % 8 + 1; // numbers star from 1 to 8 so we need to add 1 to not get 0
        int l = rand() % 8; // gets random value between 0 to 7.
        moves[i].let = letters[l]; // gets a random letter from letters array, l used as an index.
        (letters[0] = A, letters[5] = F etc.)
    }

    return moves;
}

```