**INPUT/OUTPUT**

* RPi.GPIO (<https://sourceforge.net/p/raspberry-gpio-python/wiki/BasicUsage/>)
* GPIOZERO (<https://gpiozero.readthedocs.io/en/stable/>) (Optional)
* WiringPI ([GPIO Programming on the Raspberry Pi: Python Libraries | by Sebastian | Geek Culture | Medium](https://medium.com/geekculture/gpio-programming-on-the-raspberry-pi-python-libraries-e12af7e0a812)) (Optional)

**DC & Stepper Motor**

* CircuitPython (<https://docs.circuitpython.org/projects/motorkit/en/latest/index.html)v>

**Camera**

* PiCamera (<https://picamera.readthedocs.io/en/release-1.13/>)
* Thermal Camera
  + Requirements:
    - Requires **cv2** and **numpy**
  + PyLepton (<https://github.com/groupgets/pylepton>)

**Distance sensor**

* <https://learn.adafruit.com/adafruit-vl53l0x-micro-lidar-distance-sensor-breakout/python-circuitpython>