

SMART PARKING SYSTEM (SPS)

Mohammed Almalki
Yahya Alyoubi
Mohammed Alajmi

Jamilah Alharbi
Ghaliah Maher
Ghadeer Alghamdi

Supervised by: Dr.Mejdal AlQahtani



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PROBLEM DEFINITION



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PROJECT



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CV BASED ON
DEEP LEARNING



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FUTURE WORK



استراتيجية تطوير
مدينة الرياض

أعلن سمو ولي العهد خلال مشاركته في الدورة الرابعة لمبادرة مستقبل الاستثمار عن خطط المملكة في إعلان إستراتيجية تطوير مدينة الرياض كجزء من خططها للتنوع مصادر الدخل ونمو الاقتصاد.

من تصريحات سمهو

▶ نستهدف أن تكون الرياض من أكبر عشر مدن اقتصادية في العالم، اليوم هي رقم أربعين، من أكبر أربعين اقتصاد في العالم كمدينة، نستهدف في الرياض أن نصل من 7.5 مليون نسمة إلى ما بين 15 و 20 مليون نسمة في 2030.

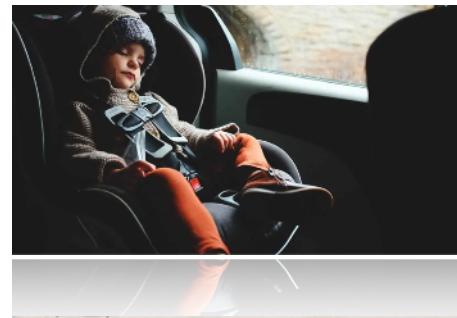
MOTIVATION



01

PROBLEM DEFINITION

- Parking violations.
- Illegal Parking .
- One in two parking.
- Crowding in exit.



02 OBJECTIVE OF PROJECT

SMART PARKING SYSTEM



CV BASED ON DEEP
LEARNING

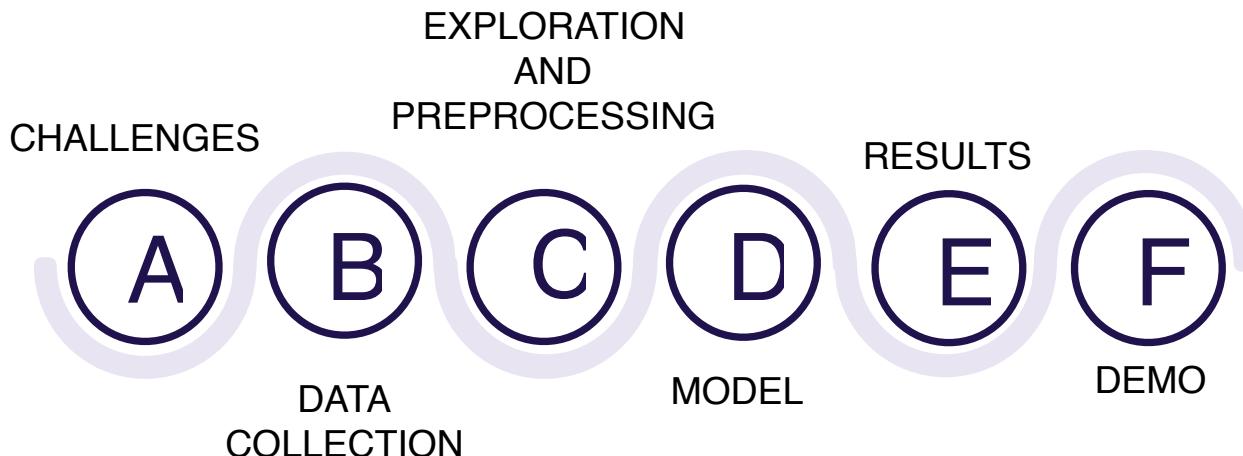


ARABIC
CHATBOT Q/A



03

ARABIC CHATBOT (NLP)



Challenges A

Errors in text.

Morphological Processing and the Dialects

Domain-specific language.

Low-resource languages.

DATA COLLECTION

B

SURVEYS.

Web scraping from articles and writing data all collected in Excel File.

	text
0	هذا شخص وافق خلف سيراتي
1	هذا شخص متوقف خلف سيراتي
2	في احد موقف ورا سيراتي
3	فيه واحد موقف ورا سيراتي
4	فيه واحد وافق وراي
...	...
607	ما هو مبلغ مخالفاتي
608	وجدت مخالفات جديدة وأوّل الاستفسار عن وقت حدوثها
609	هل على مخالفات
610	ما هي فواتيرني
611	هل لي ان اعرف نوع المخالفة
612	rows x 1 columns

EXPLORATION AND PR-EPROCESSING

- 1- Remove number and punctuation.
 - 2- Create stop word dictionary “prepositions and pronouns” and then remove them all from the dataset.
 - 3- Replace the word "وري" by the word "خلفي"
 - 4- Normalize the following from Camel tool:
 - All "أ، إ، ا" with "ا"
 - All "ى" to "ي"
 - 5- Stemming from Farasah library.
 - 6- Part of speech (P.O.S) using Camel tool model CAMeL-Lab/bert-base-arabiccamelbert-mix-pos-glf

لقيت سياري مصدمه <<(لقيت) تصنف ك فعل

MODEL D

BERT_for_Arabic_Topic_Modeling_ACLing2021

Model	HuggingFace Model Name	Size (MB/Params)	Pre-Segmentation	DataSet (Sentences/Size/nWords)
AraBERTv0.2-base	bert-base-arabertv02	543MB / 136M	No	200M / 77GB / 8.6B
AraBERTv0.2-large	bert-large-arabertv02	1.38G 371M	No	200M / 77GB / 8.6B
AraBERTv2-base	bert-base-arabertv2	543MB 136M	Yes	200M / 77GB / 8.6B
AraBERTv2-large	bert-large-arabertv2	1.38G 371M	Yes	200M / 77GB / 8.6B
AraBERTv0.1-base	bert-base-arabertv01	543MB 136M	No	77M / 23GB / 2.7B
AraBERTv1-base	bert-base-arabert	543MB 136M	Yes	77M / 23GB / 2.7B

MaartenGr / BERTTopic Public Watch 26

<> Code Issues 18 Pull requests 3 Actions Projects Wiki Security Insights

master 9 branches 21 tags Go to file Add file Code

MaartenGr v0.9.4 (#335) cd98fc8 15 days ago 45 commits

- berttopic v0.9.4 (#335) 15 days ago
- docs v0.9.4 (#335) 15 days ago
- images v0.9.4 (#335) 15 days ago
- notebooks v0.4.0 (#22) 12 months ago
- tests v0.9.4 (#335) 15 days ago
- .gitattributes Add gitattributes to update frequent languages 16 months ago
- .gitignore Init commit 16 months ago
- LICENSE v0.1.0 16 months ago
- Makefile v0.2.0 16 months ago
- README.md v0.9.4 (#335) 15 days ago
- mkdocs.yml v0.9.4 (#335) 15 days ago

MODEL D

BERT_for_Arabic_Topic_Modeling_ACLing2021

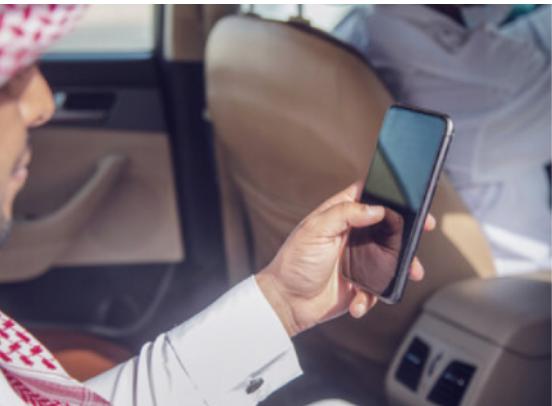
Topic Word Scores





RESULTS

E



COHERENCE

0.376

0.584

1.000

MODEL NAME

LDA (Latent Dirichlet Allocation).

NMF (Non-negative Matrix Factorizatin)

BERT_for_Arabic_Topic_Modeling_ACLing2021

DEMO

F

Interactive Arabic Chatbot



CV OF DEEP LEARNING



01

PROBLEM DEFINITION

Parking Violations Detection:

1- By line parking detection

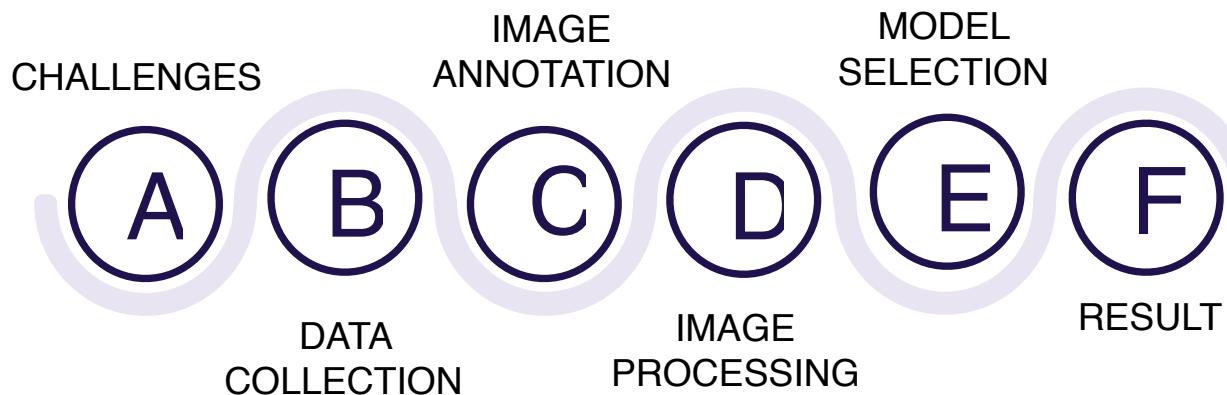
2- Object tracking based on limited and object movement

- Occupied parking.
- Available parking.
- Disabled parking.
- Parked in wrong space.
- One in two parking.



04

CV BASED ON DEEP LEARNING



Challenges C

Data collection.

Selection of the best weight.

Data-intensive computing.

Real time detection.

FIRST APPROACH

Object detection with (Drone)



Object detection with (Drone)



We used Yolov5 model (last version of yolo)

Epoch	gpu_mem	cls	total	targets
4999/4999	1.05G	00556	0.2554	1312
	Class		P	R
	all		0.986	0.604
	space-acc		1	0.902
	space-empty		0.958	0.911
	wrong-parcking		1	0

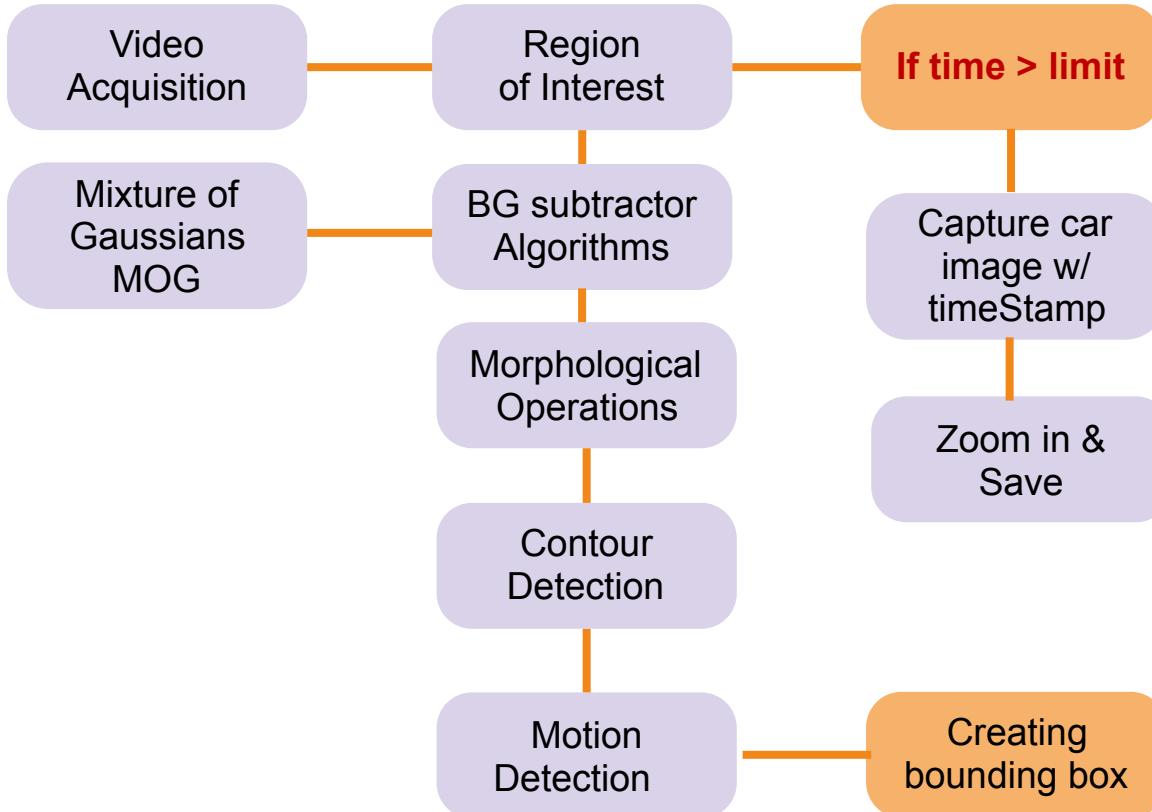
Result



SECOND APPROACH

Real time detection and object tracking .

Parking Violation Workflow

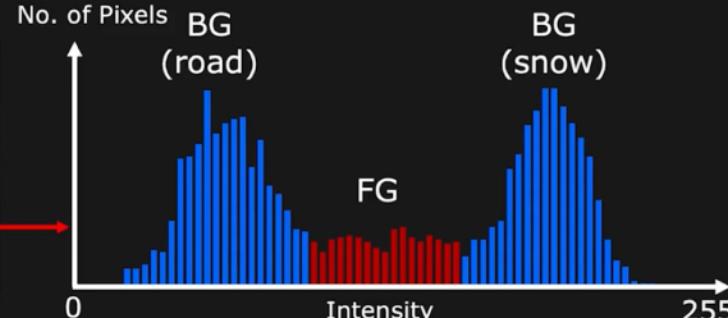


Mixture of Gaussians MOG

Intensity distribution at each pixel over time:



Input video sequence



Intensity histogram for a pixel over time

Intensity variations due to static scene (**road**), noise (**snow**),
and occasional moving objects (**vehicles**).



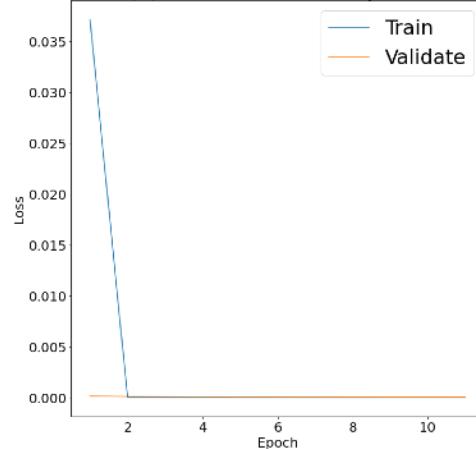
THIRD APPROACH

Combining two models.

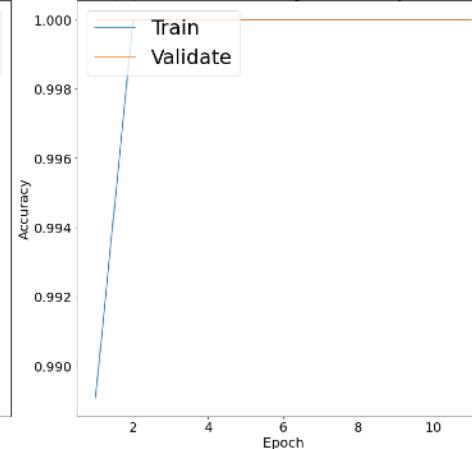
RESNET50



(A) Model Loss Across Epochs



(B) Model Accuracy Across Epochs

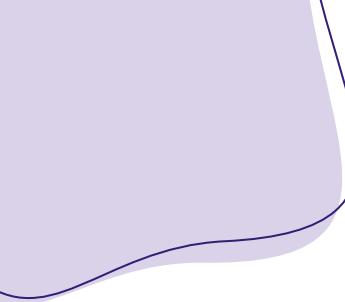


RESNET50 – Before Updating

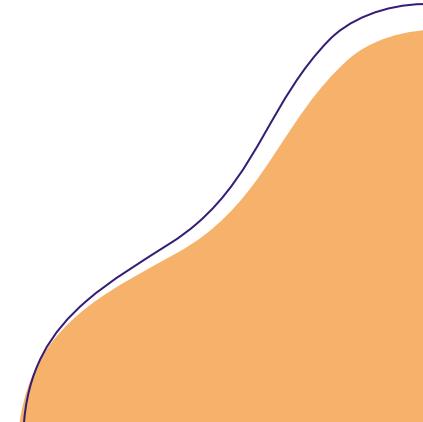


Combine 2 Models (RESNET50 and YOLOv5)





THE BENEFIT OF THE COMBINATION

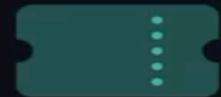
- YOLOv5 is the best model for detection and tracking object.
 - Resnet50 is best in classification.
 - This combination enhance the accuracy and add more speed in processing.
 - Applicable to use on so many other features.
- 

الموافق >

القسائم السابقة

مبالغ مستحقة

مخالفات



لا يوجد مخالفات



FUTURE WORK



01

Integrate the system with Tawakkalna.



توكالنا
Tawakkalna



02

Using callbot



03

Detect the car plate so it will be known when car accident happened.

THANK YOU...

