Tutorial on How to Fit Latent Factor Models

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This tutorial describes how you can fit latent factor models (e.g., [1, 2, 3]) using the open source package developed in Yahoo! Labs.

```
Stable repository: https://github.com/yahoo/Latent-Factor-Models
Development repository: https://github.com/beechung/Latent-Factor-Models
```

1 Preparation

Before you can use this code to fit any model, you need to install R (with R version $\geq 2.10.1$) and compile the C/C++ code in this package.

1.1 Install R

Before installing R, please make sure that you have C/C++ and Fortran compilers (e.g., gcc and gfortran) installed on your machine.

To install R, go to http://www.r-project.org/. Click CRAN on the left panel. Pick a CRAN mirror. Then, install R from the R source code. The fact that you are able to build R from source would ensure that you can compile the C/C++ code in this package.

Alternatively, you can install R using linux's package management software. In this case, please install r-base, r-base-core, r-base-dev, r-recommended.

After installing R, enter R by simply typing R and install the following R packages: Matrix, glmnet and randomForest. Note that the R packages glmnet and randomForest are not required unless you want to use them in the regression priors of the model (the parameter reg.algo in control of fit.bst). To install these R packages, use the following commands in R.

```
> install.packages("Matrix");
> install.packages("glmnet");
> install.packages("randomForest");
```

Make sure that you can run R by simply typing R. Otherwise, please use alias to point R to your R executable file. This is required for make to work properly.

1.2 Be Familiar with R

This tutorial assumes that you are familiar with R, at least comfortable calling R functions, reading R code. If not, please read http://cran.r-project.org/doc/manuals/R-intro.pdf.

1.3 Compile C/C++ Code

This is extremely simple. Just type make in the top-level directory (i.e., the directory that contains LICENSE, README, Makefile, Makevars, etc.).

2 Bias-Smoothed Tensor Model

In this section, we demonstrate how to fit the bias-smoothed tensor (BST) model [2], which includes the regression-based latent factor model (RLFM) [1] and regular matrix factorization models as special cases. In fact, the BST model presented here is more general than the model presented in [2]. It also provides the ability to use non-linear regression priors as described in [3]. The R script of this section can be found in src/R/examples/tutorial-BST.R.

2.1 Model

We first specify the model in its most general form and then describe special cases. Let y_{ijkpq} denote the response (e.g., rating) that source node i (e.g., user i) gives destination node j (e.g., item j) in context (k, p, q), where the context is specified by a three dimensional vector:

- Edge context k specifies the context when the response occurs on the edge from node i to node j; e.g., the rating on the edge from user i to item j was given when i saw j on web page k.
- Source context p specifies the context (or mode) of the source node i when this node gives the response; e.g., p represents the category of item j, meaning that user i are in different modes when rating items in different categories. Notice that, in this example, p represents an item category, instead of the user segment that i belongs to; if it was the latter case, the user ID would completely determine the context, thus making this context information unnecessary.
- Destination context q specifies the context (or mode) of the destination node j when this node receives the response; e.g., q represents the user segment that user i belongs to, meaning that the response that an item receives depends on the segment that the user belongs to.

Notice that the context (k, p, q) is assumed to be given and each individual response is assumed to occur in a single context. Also note that when modeling a problem, we may not always need all the three components in the three dimensional context vector. Some examples will be given later. It is important to

note that, in the current implementation, the total number of source contexts and the total number of destination contexts cannot be too large (around $2 \sim 100$). However, the total number of edge contexts can be large.

Because i always denotes a source node (e.g., a user), j always denotes a destination node (e.g., an item) and k always denotes an edge context, we slightly abuse our notation by using \mathbf{x}_i to denote the feature vector of source node i, \mathbf{x}_j to denote the feature vector of destination node j, \mathbf{x}_k to denote the feature vector of edge context k, and \mathbf{x}_{ijk} to denote the feature vector associated with the occasion when i gives j the response in context k (e.g., the time of day, day of week of the response). Notice that we do not consider features for source and destination contexts because the number of such contexts are expected to be small; since each such context would have a relatively large number of observations, it usually does not need a feature-based regression prior.

Response model: For numeric response, we use the Gaussian response model; for binary response, we use the logistic response model.

$$y_{ijkpq} \sim \mathcal{N}(\mu_{ijkpq}, \sigma_y^2) \text{ or } y_{ijkpq} \sim Bernoulli((1 + \exp(-\mu_{ijkpq}))^{-1}),$$

where $\mu_{ijkpq} = \mathbf{x}'_{ijk}\mathbf{b} + \alpha_{ip} + \beta_{jq} + \gamma_k + \langle \mathbf{u}_i, \mathbf{v}_j, \mathbf{w}_k \rangle$. Note that $\langle \mathbf{u}_i, \mathbf{v}_j, \mathbf{w}_k \rangle = \sum_{\ell} \mathbf{u}_i[\ell] \mathbf{v}_j[\ell] \mathbf{w}_k[\ell]$ is a form of the tensor product of three vectors $\mathbf{u}_i, \mathbf{v}_j$ and \mathbf{w}_k , where $\mathbf{u}_i[\ell]$ denotes the ℓ th element in vector \mathbf{u}_i . For ease of exposition, we use the following notation to represent both the Gaussian and logistic models.

$$y_{ijkpq} \sim \boldsymbol{x}'_{ijk}\boldsymbol{b} + \alpha_{ip} + \beta_{jq} + \gamma_k + \langle \boldsymbol{u}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle,$$
 (1)

where \boldsymbol{b} is the regression coefficient vector on feature vector \boldsymbol{x}_{ijk} ; α_{ip} is the latent factor of source node i in source context p; β_{jq} is the latent factor of destination node j in destination context q; γ_k is the latent factor of edge context k; \boldsymbol{u}_i , \boldsymbol{v}_j and \boldsymbol{w}_k are the latent factor vectors of source node i, destination node j and edge context k, respectively. Note that these latent factors and regression coefficients will be learned from data.

Regression Priors: The priors of the latent factors are specified in the following:

$$\alpha_{ip} \sim \mathcal{N}(\mathbf{g}_p(\mathbf{x}_i) + q_p \alpha_i, \ \sigma_{\alpha,p}^2), \quad \alpha_i \sim \mathcal{N}(0,1)$$
 (2)

$$\beta_{jq} \sim \mathcal{N}(\boldsymbol{d}_q(\boldsymbol{x}_j) + r_q \beta_j, \ \sigma_{\beta,q}^2), \quad \beta_j \sim \mathcal{N}(0,1)$$
 (3)

$$\gamma_k \sim \mathcal{N}(\boldsymbol{h}(\boldsymbol{x}_k), \, \sigma_{\gamma}^2 I),$$
 (4)

$$\boldsymbol{u}_i \sim \mathcal{N}(G(\boldsymbol{x}_i), \, \sigma_u^2 I), \quad \boldsymbol{v}_j \sim \mathcal{N}(D(\boldsymbol{x}_j), \, \sigma_v^2 I), \quad \boldsymbol{w}_k \sim \mathcal{N}(H(\boldsymbol{x}_k), \, \sigma_w^2 I), \quad (5)$$

where q_p and r_q are regression coefficients; $g_p(\cdot)$, $d_q(\cdot)$, $h(\cdot)$, $G(\cdot)$, $D(\cdot)$ and $H(\cdot)$ are regression functions that can either be linear regression coefficient vectors/matrices, or non-linear regression functions such as random forests. These regression functions will be learned from data and provide the ability to make predictions for users or items that do not appear in training data. The factors of these new users or items will be predicted based on their features through regression.

2.2 Data Format

We introduce the input data format through the following toy dataset. You can put your own data in the same format to fit the model to your data. This toy dataset is in the following directory:

```
test-data/multicontext_model/simulated-mtx-uvw-10K
```

Please read the README file there to better understand this dataset, which was created by running the following R script. Please do not rerun this R script.

```
src/unit-test/multicontext_model/create-simulated-data-1.R
```

This is a simulated dataset; i.e., the response values y_{ijkpq} are generated according to a known ground-truth model. To see the ground-truth, run the following commands in R.

```
> load("test-data/multicontext_model/simulated-mtx-uvw-10K/ground-truth.RData");
> str(factor);
> str(param);
```

Observation Data: The observation data, also called response data, is in obs-train.txt and obs-test.txt. Each file has six columns:

- 1. src_id : Source node ID (e.g., user i).
- 2. dst_id : Destination node ID (e.g., item j).
- 3. $src_context$: Source context ID (e.g., source context p). This is an optional column.
- 4. $dst_context$: Destination context ID (e.g., destination context q). This is an optional column.
- 5. ctx_id : Edge context ID (e.g., edge context k). This is an optional column.
- 6. y: Response (e.g., the rating that user i gives item j in context (k, p, q)).

Note that all of the above IDs can be numbers or character strings. To read obs-train.txt, run the following commands in R.

```
> input.dir = "test-data/multicontext_model/simulated-mtx-uvw-10K"
> obs.train = read.table(paste(input.dir,"/obs-train.txt",sep=""),
    sep="\t", header=FALSE, as.is=TRUE);
> names(obs.train) = c("src_id", "dst_id", "src_context",
    "dst_context", "ctx_id", "y");
```

It is important to note that the **column names** of an observation table have to be exactly **src_id**, **dst_id**, **src_context**, **dst_context**, **ctx_id** and **y**. The model fitting code looks for these column names to setup internal data structures (instead of the order of columns; i.e., **src_id** does not need to be

the first column), and it does not recognize other columns names. Also, note that src_context, dst_context and ctx_id are optional columns. When these columns are missing, a reduced model without context-specific factors will be fitted. For example, an observation table with only 3 columns: src_id, dst_id, and y will setup the fitting procedure to fit the RLFM model introduced in [1]; i.e.,

$$y_{ij} \sim \boldsymbol{x}'_{ij}\boldsymbol{b} + \alpha_i + \beta_j + \boldsymbol{u}'_i\boldsymbol{v}_j,$$

since k, p and q are missing.

Source, Destination and Context Features: The feature vectors of source nodes (x_i) , destination nodes (x_j) and edge contexts (x_k) are in

```
type-feature-user.txt,
type-feature-item.txt,
type-feature-ctxt.txt,
```

where type = "dense" for the dense format and type = "sparse" for the sparse format.

For the dense format, take dense-feature-user.txt for example. The first column is src_id (the src_id column in the observation table refers to this column to get the feature vector of the source node for each observation). It is important to note that, after reading this table into R, the name of the first column has to be set to src_id exactly. The rest of the columns specify the feature values and the column names can be arbitrary.

For the sparse format, take sparse-feature-user.txt for example. It has three columns:

- 1. src_id: Source node ID
- 2. index: Feature index (starting from 1, not 0)
- 3. value: Feature value

It is important to note that, after reading this table into R, the **column names** have to be set to **src_id**, **index** and **value** exactly. The following example shows the correspondence between the sparse and dense formats.

```
sparse-feature-user.txt
                            dense-feature-user.txt
SPARSE FORMAT
                       <=> DENSE FORMAT
src_id index
               value
                            src_id feature_1 feature_2 feature_3
    15
           2 - 0.978
                                15
                                             0
                                                   -0.978
                                                               0.031
    15
           3
               0.031
```

Observation Features: The features vectors of training and test observations (x_{ijk}) are in

```
type-feature-obs-train.txt,
type-feature-obs-test.txt,
```

where type = "dense" for the dense format and type = "sparse" for the sparse format.

For the dense format, take dense-feature-obs-train.txt for example. The *n*th line specifies the feature vector of observation on the *n*th line of obs-train.txt. Since there is a line-by-line correspondence, there is no need to have an ID column. Each column in this file represents a feature and the column names can be arbitrary.

For the sparse format, take sparse-feature-obs-train.txt for example. It has three columns:

- 1. obs_id: Line number in obs-train.txt (starting from 1, not 0)
- 2. index: Feature index (starting from 1, not 0)
- 3. value: Feature value

It is important to note that, after reading this table into R, the **column names** have to be set to **src_id**, **index** and **value** exactly. An example is presented in the following.

2.3 Model Fitting

In this section, we describe how to fit the BST model to the toy dataset using this package without deep understanding of the fitting procedure. Before you run the sample code, please make sure you are in the top-level directory (i.e. by using Linux command 1s, you should be able to see files LICENSE and README).

2.3.1 Step 1: Read Data

We fist read training and test observation tables (named as obs.train and obs.test in the following R script), their corresponding observation feature tables (named as x_obs.train and x_obs.test), the source feature table (x_src), the destination feature table (x_dst) and the edge context feature table (x_ctx) from the corresponding files. Note that if you replace these tables with your data, you must not change the column names. If you remove some optional columns, you must make sure that you remove the corresponding column names correctly. Assuming we use the dense format of the feature files, a sample R script is in the following.

2.3.2 Step **2**: Fit Model(s)

We start fitting the model by loading the function fit.bst in src/R/BST.R.

```
> source("src/R/BST.R");
```

Then, we can fit a simple latent factor model without any feature using the following command.

Or, we can fit a model using all the features.

In the above examples, we basically put all the loaded data as input to the fitting function, specify the output directory prefix as /tmp/bst/quick-start, and fit a model (with name uvw3 or uvw3-F). Note that the model name can be arbitrary, and the final output directory for model uvw3 is in $/\text{tmp/bst/quick-start_uvw3}$. This model has 3 factors per node (i.e., u_i , v_j and w_k are 3-dimensional vectors) and is fitted using 10 EM iterations. If you do not have test data, you can simply omit input parameters obs.test and x_obs.test when calling fit.bst. More options and control parameters will be introduced in Section 2.3.5.

2.3.3 Step 3: Check the Output

The two main output files in an output directory are summary and model.last.

Summary File: It records a number of statistics for each EM iteration. To read a summary file, use the following R command.

> read.table("/tmp/bst/quick-start_uvw3-F/summary", header=TRUE);

Explanation of the columns is in the following:

- Iter specifies the iteration number.
- nSteps records the number of Gibbs samples drawn in the E-step of that iteration.
- CDlogL, TestLoss, LossInTrain and TestRMSE record the complete data log likelihood, loss on the test data, loss on the training data and RMSE (root mean squared error) on the test data for the model at the end of that iteration. For the Gaussian response model, the loss is defined as RMSE. For the logistic response model, the loss is defined as negative average log likelihood per observation.
- TimeEStep, TimeMStep and TimeTest record the numbers of seconds used to compute the E-step, M-step and predictions on test data in that iteration.

Sanity Check:

- Check CDlogL to see whether it increases sharply during the first few iterations and then oscillates at the end.
- Check TestLoss to see whether it converges. If not, more EM iterations are needed.
- Check TestLoss and LossInTrain to see whether the model overfits the data; i.e., TestLoss goes up, while LossInTrain goes down. If so, try to simplify the model by reducing the number of factors and parameters.

You can monitor the summary file when the code is running. When you see TestLoss converges, kill the running process.

Model Files: The fitted models are saved in model.last and model.minTestLoss, which are R data binary files. To load the models, run the following command.

```
> load("/tmp/bst/quick-start_uvw3-F/model.last");
> str(factor);
> str(param);
> str(data.train);
```

After we load the model, the fitted prior parameters are in object param and the fitted latent factors are in object factor. Also, the object data.train contains the ID mappings (see Appendix A.2 for details) that are needed when we need to apply this model to a new test dataset. Notice that data.train does not contain actual data, but just meta information. You do not need to understand these objects to use this model to predict the response of new test data.

Object factor is a list of factors. For example, $\alpha_{ip} = \texttt{factor\$alpha[i,p]}$, the $\texttt{src_id}$ of source node index i is data.train\$IDs\$SrcIDs[i], and the $\texttt{src_context}$ of source context index p is data.train\$IDs\$SrcContexts[p]. As another example, $\boldsymbol{w}_k = \texttt{factor\$w[k,]}$ and the $\texttt{ctx_id}$ of edge context index k is data.train\$IDs\$CtxIDs[k].

Object param is a list of prior parameters. For example, $\sigma_{\alpha,p}^2 = \text{param}var_alpha[p]$. The format of the regression function parameters (b, g, d, h, G, D and H) depends on the regression model. See the following file for details.

src/R/model/Notation-multicontext.txt

2.3.4 Step 4: Make Predictions

Once Step 2 finishes, we have the predicted values of the response variable y for the test data, since we have the test data as input to the fitting function. Check file prediction inside the output directory (In our example, $\t^{tmp/bst/quick-start_uvw3-F/prediction}$ is the file name). The file has two columns:

- 1. y: The ground-truth response y
- 2. pred_y: The predicted response y

Please note that the predicted values of y for model uvw3-F can also be found at ans\$pred.y[["uvw3-F"]]. If you did not specify obs.test and x.obs.test when calling function fit.bst, then there would be no prediction file.

To make predictions for new test data, first read the new data (similar to Step 1) and then call predict.bst.

Note that obs.test is the test observation tables, and x_obs.test, x_src, x_dst and x_ctx are the feature tables. You need to make sure that the test data uses the same set of features as those used in training (i.e., the column names of a feature table in the training data must be the same as those in the test data). This prediction function does not perform sanity checks for feature consistency. Some strange errors may occur if the training and test features are inconsistent. It is also important to note that, in the current implementation, x_src, x_dst and x_ctx must also include all of the source nodes, destination nodes and edge contexts that appear in the training data.

2.3.5 Details of fit.bst

Fit Multiple Models in One Call: You are able to fit multiple models by calling fit.bst once. The following is an example.

Here, we fit two models: uvw1 and uvw2 by setting the model.name and nFactors as vectors of length=2; in this example, model uvw1 uses 1 factor, and model uvw2 uses 2 factors. They are both fitted using 10 EM iterations. Unfortunately, for fair comparison between sibling models we do not allow nIter to be different among different models. The model files, summary files and prediction files for the two models are in /tmp/bst/quick-start_uvw1 and /tmp/bst/quick-start_uvw2.

Basic parameters: The basic input parameters of function fit.bst are documented in the following:

- code.dir is the top-level directory of the location where this package was installed. If you are already in this directory, the default which is the empty string can be used.
- obs.train, obs.test, x_obs.train, x_obs.test, x_src, x_dst, x_ctx are the training and data. Please check Section 2.2 for details. Note that only obs.train is required to run this code; everything else is optional depending on the problem that you have. Note that if obs.test, x_src, x_dst and x_ctx are specified, then x_src, x_dst and x_ctx must also contain the features of the source nodes, destination nodes and edge contexts that appear only in the test data.
- out.dir is the output directory prefix. The final output directory is out.dir_model.name.
- model.name is a vector of the names of the models to be fitted. It can be an arbitrary string or a vector of strings. Default is "model".
- nFactors specifies the number of factors per node (i.e., the number of dimensions of vector v_j ; note that u_i and w_k have the same number of dimensions). It can be either a scalar or a vector of numbers with length equal to the number of models.
- nIter specifies the number of EM iterations. All the models are fitted using the same number of iterations.
- nSamplesPerIter specifies the number of Gibbs samples drawn in each Estep of an single EM iteration. It can be either a scalar which means every EM iteration uses the same nSamplesPerIter, or it can be a vector with length equal to nIter specifying the Gibbs samples for each EM iteration (in this case, each iteration has its own value of nSamplesPerIter). Note that all models use the same nSamplesPerIter.

- is.logistic specifies whether we want to use logistic link function for our models on binary response data. Default is FALSE. It can be either a boolean value that is shared by all models, or a vector of boolean values with length equal to the number of models.
- src.dst.same specifies whether you want the model to have a single factor vector per node (ignoring the difference between source nodes and destination nodes). For example, if source nodes represent users and destination nodes represents items, src.dst.same should be set to FALSE because it does not make sense to use a single factor vector for both the *i*th user and the *i*th item. However, if both source and destination nodes represent users (e.g., users rate other users) and src_id = A refers to the same user A as dst_id = A, then src.dst.same can be set to TRUE. In this case, the following model will be fitted.

$$y_{ijkpq} \sim \boldsymbol{x}'_{ijk}\boldsymbol{b} + \alpha_{ip} + \beta_{jq} + \gamma_k + \langle \boldsymbol{v}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle,$$
 (6)

Comparing the above model to the original model specified in Equation 1, note the difference between $\langle \boldsymbol{v}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle$ and $\langle \boldsymbol{u}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle$. Of course, in the case where both source nodes and destination nodes represent users, you can still set src.dst.same=FALSE to fit the original model. The default of src.dst.same is FALSE.

 control has a list of more advanced parameters that will be introduced later.

Advanced parameters: control=fit.bst.control(...) contains the following advanced parameters:

- rm.self.link: Whether to remove self-edges. If src.dst.same=TRUE, you can choose to remove observations with src_id = dst_id by setting rm.self.link=FALSE. Otherwise, rm.self.link should be set to FALSE. The default of rm.self.link is FALSE.
- add.intercept: Whether you want to add an intercept to each feature matrix. If add.intercept=TRUE, a column of all 1s will be added to every feature matrix. The default of add.intercept is TRUE.
- has.gamma specifies whether to include γ_k in the model specified in Equation 1 or not. If has.gamma=FALSE, γ_k will be disabled or removed from the model. By default, has.gamma is set as FALSE unless the training response data obs.train does not have any source or destination context, but has edge context.
- reg.algo and reg.control specify how the regression priors will to be fitted. If they are set to NULL (default), R's basic linear regression function lm will be used to fit the prior regression coefficients g, d, h, G, D and H. Currently, we only support two other algorithms "GLMNet" and

"RandomForest". Currently, reg.algo can only take one of the following three: NULL, "GLMNet" and "RandomForest" (both are strings). Notice that if "RandomForest" is used, the regression priors become nonlinear; see [3] for more information.

- nBurnin is the number of burn-in samples per E-step. The default is 10% of nSamplesPerIter.
- init.params is a list of the initial values of all the variance component parameters at the beginning of the first EM iteration. The default value of init.params is

where var_alpha specifies the initial value of σ_{α}^2 and so on. When var_y=NULL, the initial value of σ_y^2 is set to the sample variance of the response in the training data. relative.to.var_y specifies whether the specification of var_alpha and so on should be relative to var_y. For example, if relative.to.var_y=TRUE, var_y=NULL and var_alpha=0.1, then the initial value of σ_{α}^2 will be set to 0.1 times the sample variance of the response.

• random.seed is the random seed for the model fitting procedure.

2.3.6 Special Case Models

Original BST Model: The original BST model defined in [2] can be fitted by setting src.dst.same=TRUE, has.gamma=FALSE, rm.self.link=TRUE and setting all the context columns to be the same in the input data.

This setting gives the following model:

$$y_{ijk} \sim \boldsymbol{x}'_{ijk}\boldsymbol{b} + \alpha_{ik} + \beta_{jk} + \langle \boldsymbol{v}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle$$

Notice that since all the context columns are the same, there is no need for using a three dimensional context vector (k, p, q); instead, it is sufficient to just use k to index the context in the above equation.

RLFM: The RLFM model defined in [1] can be fitteing by removing all of the context columns.

Notice that x_ctx is also removed. This setting gives the following model:

$$y_{ij} \sim \boldsymbol{x}'_{ij}\boldsymbol{b} + \alpha_i + \beta_j + \boldsymbol{u}'_i\boldsymbol{v}_j$$

Notice that removing the context-related columns in an observation table disables the context-specific factors in the model.

References

- D. Agarwal and B.-C. Chen. Regression-based latent factor models. In KDD, 2009.
- [2] B.-C. Chen, J. Guo, B. Tseng, and J. Yang. User reputation in a comment rating environment. In *KDD*, 2011.
- [3] L. Zhang, D. Agarwal, and B. Chen. Generalizing matrix factorization through flexible regression priors. In *RecSys*, 2011.

A BST Model Fitting Details

In this section, we provide more details of how BST models are fitted. In fact, we will fit BST models without using the wrapper function fit.bst; hence, it may give insights on how to use this package in your problem settings. All the R code written in this section can be found in Appendix Example 1 in src/R/examples/tutorial-BST.R. For succinctness, we ignore some R commands in the following description.

A.1 Read Data

Read all the data sets in the same way as described in Section 2.3.1.

A.2 Index Data

Index the training and test data. Functions indexData and indexTestData (defined in rc/R/model/multicontext_model_utils.R) convert the input data tables into the right data structure. In particular, they replace the original IDs (src_id, dst_id, src_context, dst_context and ctx_id) by consecutive index numbers, and convert feature tables (data frames) into feature matrices.

```
data.train = indexData(
    obs=obs.train, src.dst.same=FALSE, rm.self.link=FALSE,
    x_obs=x_obs.train, x_src=x_src, x_dst=x_dst, x_ctx=x_ctx,
    add.intercept=TRUE
);
data.test = indexTestData(
    data.train=data.train, obs=obs.test,
    x_obs=x_obs.test, x_src=x_src, x_dst=x_dst, x_ctx=x_ctx
);
```

We then describe some input parameters to function indexData.

- src.dst.same: Whether source nodes and destination nodes refer to the same set of entities. For example, if source nodes represent users and destination nodes represents items, src.dst.same should be set to FALSE. However, if both source and destination nodes represent users (e.g., users rate other users) and src_id = A refers to the same user A as dst_id = A, the src.dst.same should be set to TRUE.
- rm.self.link: Whether to remove self-edges. If src.dst.same=TRUE, you can choose to remove observations with src_id = dst_id by setting rm.self.link=FALSE. Otherwise, rm.self.link should be set to FALSE
- add.intercept: Whether you want to add an intercept to each feature matrix. If add.intercept=TRUE, a column of all 1s will be added to every feature matrix.

Because data.train is passed into indexTestData, the above parameters do not need to be passed into indexTestData and the parameter setting used to create the test data will be the same as the setting used to create the training data.

The output of indexData and indexTestData primarily consists of the following three components:

- obs: This is the observation table (data frame) with the new numeric index IDs. The columns are: src.id, dst.id, src.context, dst.context, edge.context and y, where src.id corresponds to src_id, etc., and edge.context corresponds to ctx_id.
- IDs: This list of vectors contains the mapping from new numeric index IDs to the original IDs.
- feature: This is a list of four feature matrices. x_obs , x_src , x_dst and x_cctx correspond to x_{ijk} , x_i , x_j and x_k , respectively.

For example, assume the *m*th row of data.train\$obs is

```
src.id dst.id src.context dst.context edge.context y i j p q k y_{ijkpq}
```

Then, we have the following correspondence:

- data.train\$IDs\$SrcIDs[i] is the original source node ID of this observation. Similarly, DstIDs[j], SrcContexts[p], DstContexts[q] and CtxIDs[k] are the original IDs of the destination node, source context, destination context, edge context of this observation.
- data.train\$feature\$x_obs[m,] is the observation feature vector of this observation. Similarly, x_src[i,], x_dst[j,] and x_ctx[k,] are the feature vectors of the source node, destination node and edge context of this observation.

A.3 Model Setting

Fit the model(s). We first specify the settings of the models to be fitted.

```
setting = data.frame(
                 = c("uvw1", "uvw2"),
   name
                      1,
   nFactors
                = c(
                                 2).
                 = c( TRUE,
   has.u
                              TRUE),
                = c( FALSE, FALSE),
   has.gamma
   nLocalFactors = c( 0,
                                 0),
   is.logistic = c( FALSE, FALSE)
);
```

In the above example, we specify two models to be fitted.

- name specifies the name of the model, which should be unique.
- nFactors specifies the number of interaction factors per node; i.e., the number of dimensions of v_j , which is the same as the numbers of dimensions of u_i and w_k . If you want to disable or remove $\langle u_i, v_j, w_k \rangle$ from the model specified in Eq 1, set nFactors = 0.
- has.u specifies whether to use $\langle u_i, v_j, w_k \rangle$ in the model specified in Eq 1 or replace this term by $\langle v_i, v_j, w_k \rangle$ (more examples will be given later). Notice that the latter does not have factor vector u_i ; thus, it corresponds to has.u=FALSE. It is important to note that if has.u=FALSE, you must set src.dst.same=TRUE when calling indexData in Step 2.
- has.gamma specifies whether to include γ_k in the model specified in Eq 1 or not. If has.gamm=FALSE, γ_k will be disabled or removed from the model.
- nLocalFactors should be set to 0 for most cases. Do not set it to other numbers unless you know what you are doing.
- is.logistic specifies whether to use the logistic response model or not. If is.logistic=FALSE, the Gaussian response model will be used.

In the following, we demonstrate a few different example settings and their corresponding models.

• The original BST model defined in [2]: Set has.u=FALSE, has.gamma=FALSE, and set all the context columns to be the same in the input data; i.e., before Step 2, set the input observation tables obs.train and obs.test so that the following holds.

```
obs.train$src_context = obs.train$dst_context = obs.train$ctx_id
obs.test$src_context = obs.test$dst_context = obs.test$ctx_id
```

This setting gives the following model:

$$y_{ijk} \sim \boldsymbol{x}'_{ijk}\boldsymbol{b} + \alpha_{ik} + \beta_{jk} + \langle \boldsymbol{v}_i, \boldsymbol{v}_j, \boldsymbol{w}_k \rangle$$

Notice that since all the context columns are the same, there is no need for using a three dimensional context vector (k,p,q); instead, it is sufficient to just use k to index the context in the above equation. Also note that you must set $\mathtt{src.dst.same=TRUE}$ when calling $\mathtt{indexData}$ in Step 2.

• The RLFM model defined in [1]: Set has.u=TRUE, has.gamma=FALSE, and before Step 2, set:

```
obs.train$src_context = obs.train$dst_context = obs.train$ctx_id = NULL;
obs.test$src_context = obs.test$dst_context = obs.test$ctx_id = NULL;
x_ctx = NULL;
```

This setting gives the following model:

$$y_{ij} \sim \boldsymbol{x}'_{ij}\boldsymbol{b} + \alpha_i + \beta_j + \boldsymbol{u}'_i\boldsymbol{v}_j$$

Notice that setting the context-related objects to NULL disables the context-specific factors in the model.

A.4 Modeling Fitting

Run the model fitting procedure.

```
out.dir = "/tmp/unit-test/simulated-mtx-uvw-10K";
ans = run.multicontext(
   data.train=data.train, # training data
   data.test=data.test, # test data (optional)
   setting=setting, # setting specified in Step 3
                    # number of Gibbs samples in each E-step
   nSamples=200,
   nBurnIn=20,
                    # number of burn-in samples for the Gibbs sampler
   nIter=10,
                    # number of EM iterations
   reg.algo=NULL, # regression algorithm; see below
   reg.control=NULL, # control parameters for the regression algorithm
   out.level=1,
                       # see below
   out.dir=out.dir,
                       # output directory
   out.overwrite=TRUE, # whether to overwrite the output directory
   # initialization parameters (the default setting usually works)
    var_alpha=1, var_beta=1, var_gamma=1,
```

```
var_v=1, var_u=1, var_w=1, var_y=NULL,
relative.to.var_y=FALSE, var_alpha_global=1, var_beta_global=1,
# others
verbose=1, # overall verbose level: larger -> more messages
verbose.M=2, # verbose level of the M-step
rnd.seed.init=0, rnd.seed.fit=1 # random seeds
);
```

Most input parameters to run.multicontext are described in the above code piece. We make the following additional notes:

- nSamples, nBurnIn and nIter determine how long the procedure will run. In the above example, the procedure runs 10 EM iterations. In each iteration, it draws 220 Gibbs samples, where the first 20 samples are burnin samples (which are thrown away) and the rest 200 samples are used to compute the Monte Carlo means in the E-step of this iteration. In our experience, 10-20 EM iterations with 100-200 samples per iteration are usually sufficient.
- reg.algo and reg.control specify how the regression priors will to be fitted. If they are set to NULL, R's basic linear regression function 1m will be used to fit the prior regression coefficients g, d, h, G, D and H. Currently, we only support two other algorithms GLMNet and RandomForest. Notice that if RandomForest is used, the regression priors become nonlinear; see [3] for more information.
- out.level and out.dir specify what and where the fitting procedure will output. If out.level > 0, each model specified in setting (i.e., each row in the setting table) will be output to a separate directory. The output directory name of the *m*th model is

```
paste(out.dir, "_", setting$name[m], sep="")
```

In this example, the output directories of the two models specified in the setting table are:

```
/tmp/unit-test/simulated-mtx-uvw-10K_uvw1
/tmp/unit-test/simulated-mtx-uvw-10K_uvw2
```

If out.level=1, the fitted models are stored in files model.last and model.minTestLoss in the output directories, where model.last contains the model obtained at the end of the last EM iteration and model.minTestLoss contains the model at the end of the EM iteration that gives the minimum loss on the test observation. model.minTestLoss exists only when test.obs is not NULL. If the fitting procedure stops (e.g., the machine reboots) before it finishes all the EM iteration, the latest fitted models will still be saved in these two files. If out.level=2, the model at the end of the mth EM iteration will be saved in model.m for each m. We describe how to read the output in Section 2.3.3.

A.5 Prediction

To make predictions, use the following function.

```
pred = predict.multicontext(
    model=list(factor=factor, param=param),
    obs=data.test$obs, feature=data.test$feature, is.logistic=FALSE
);
```

Now, pred\$pred.y contains the predicted response for data.test\$obs. Notice that the test data data.test was created by calling indexTestData in Step 2 of Section A. If you have new test data, you can use the following command to index the new test data.

```
data.test = indexTestData(
    data.train=data.train, obs=obs.test,
    x_obs=x_obs.test, x_src=x_src, x_dst=x_dst, x_ctx=x_ctx
);
```

where obs.test, x_obs.test, x_src, x_dst and x_ctx contain new data in the same format as described in Step 2 of Section A.

A.6 Other Examples

In src/R/examples/tutorial-BST.R, we also provide a number of additional examples.

- Example 2: In this example, we demonstrate how to fit the same models as those in Example 1 with sparse features and the glmnet algorithm.
- Example 3: In this example, we demonstrate how to add more EM iterations to an already fitted model.
- Example 4: In this example, we demonstrate how to fit RLFM models with sparse features and the glmnet algorithm. Note that RLFM models do not fit this toy dataset well.