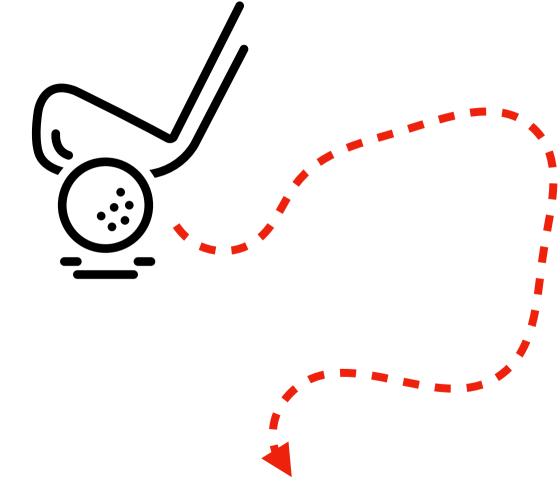




observed path

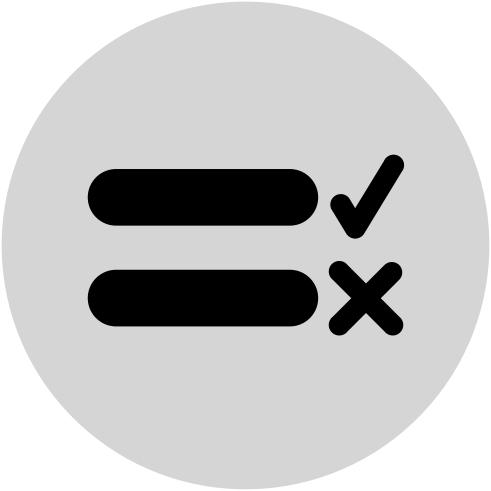
instantaneous rule

global principle



min action

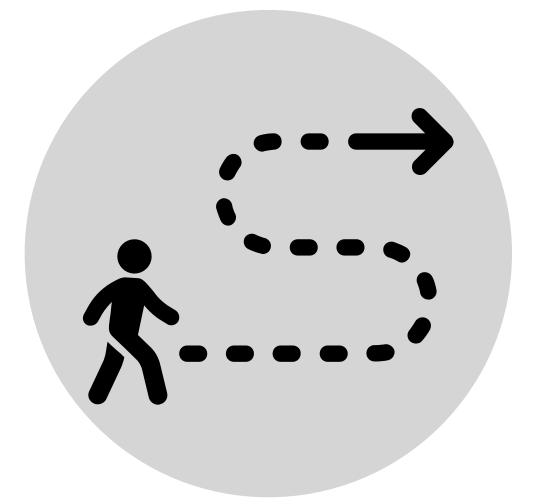


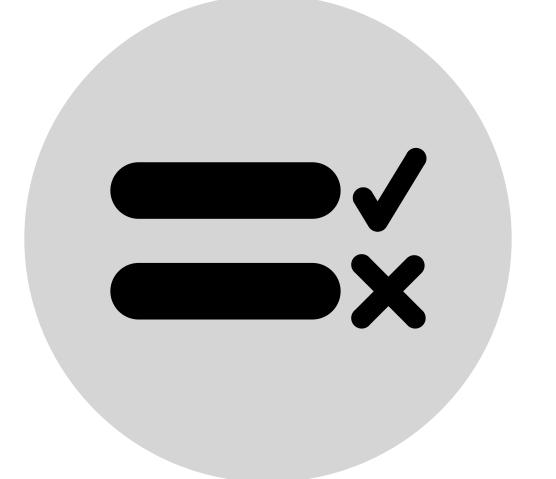


observed path

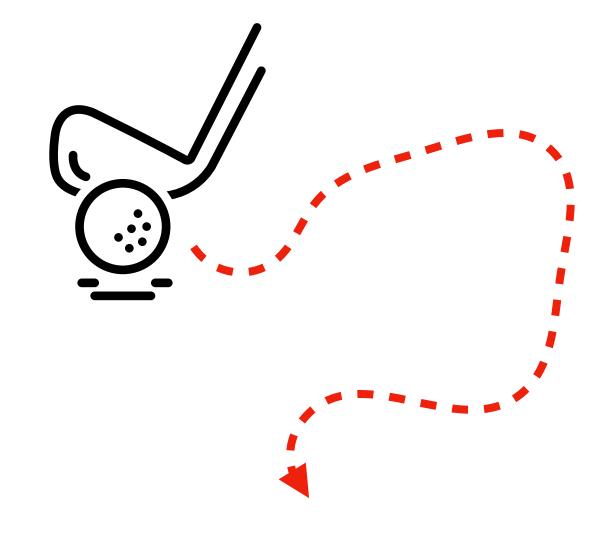


global principle













observed path



global principle

