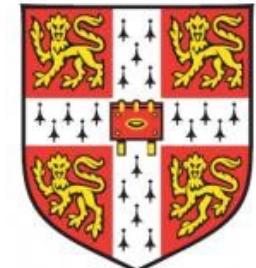
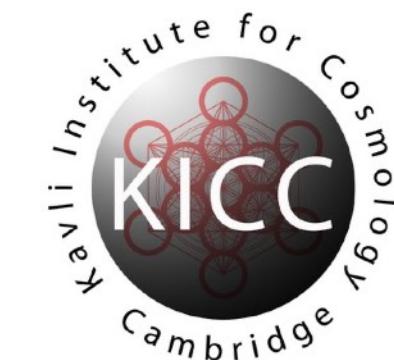


# Simulation Based Inference

## Astro Data Science Discussion group

David Yallup - 28/02/24

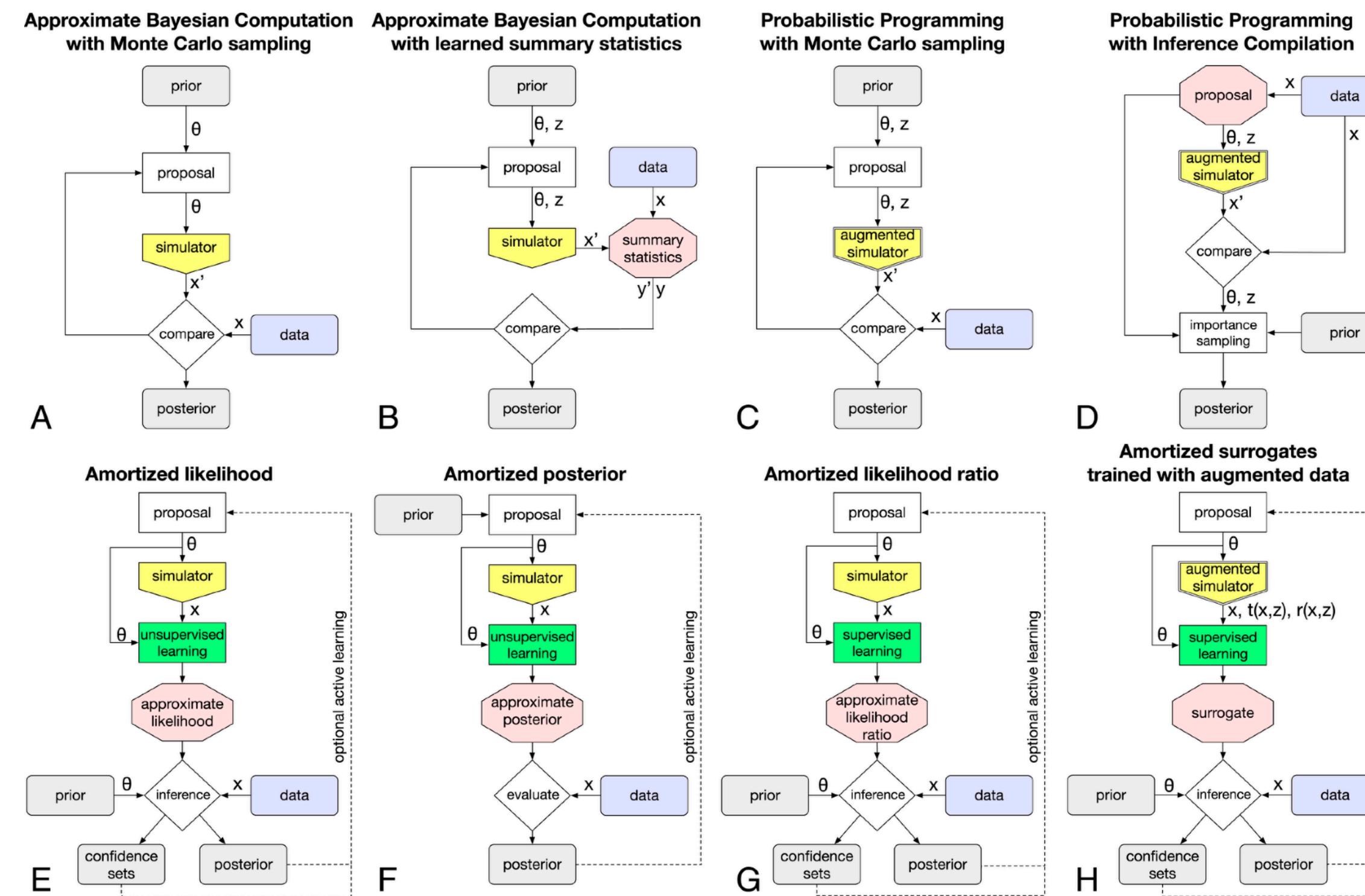


UNIVERSITY  
OF  
CAMBRIDGE

# Building a mindmap of SBI

Rather than analyse parameters (of models), analyse mock data (from models)

- NLE
- NPE
- NRE



Either using **classifiers** to distinguish between two piles of mock data, or using invertible **density estimators** to learn distributions over piles of mock data

## Neural Posterior Estimation: amortized (NPE) and sequential (SNPE)

- [SNPE\\_A](#) (including amortized single-round NPE) from Papamakarios G and Murray I [\*Fast  \$\varepsilon\$ -free Inference of Simulation Models with Bayesian Conditional Density Estimation\*](#) (NeurIPS 2016).
- [SNPE\\_C](#) or [APT](#) from Greenberg D, Nonnenmacher M, and Macke J [\*Automatic Posterior Transformation for likelihood-free inference\*](#) (ICML 2019).
- [TSNPE](#) from Deistler M, Goncalves P, and Macke J [\*Truncated proposals for scalable and hassle-free simulation-based inference\*](#) (NeurIPS 2022).

[<https://github.com/sbi-dev/sbi>]

SBI Package `sbi`

Seems to be generally touted  
as one stop shop for all SBI  
needs

## Neural Likelihood Estimation: amortized (NLE) and sequential (SNLE)

- [SNLE\\_A](#) or just [SNL](#) from Papamakarios G, Sterrat DC and Murray I [\*Sequential Neural Likelihood\*](#) (AISTATS 2019).

## Neural Ratio Estimation: amortized (NRE) and sequential (SNRE)

- [\(S\)NRE\\_A](#) or [AALR](#) from Hermans J, Begy V, and Louppe G. [\*Likelihood-free Inference with Amortized Approximate Likelihood Ratios\*](#) (ICML 2020).
- [\(S\)NRE\\_B](#) or [SRE](#) from Durkan C, Murray I, and Papamakarios G. [\*On Contrastive Learning for Likelihood-free Inference\*](#) (ICML 2020).
- [BNRE](#) from Delaunoy A, Hermans J, Rozet F, Wehenkel A, and Louppe G. [\*Towards Reliable Simulation-Based Inference with Balanced Neural Ratio Estimation\*](#) (NeurIPS 2022).
- [\(S\)NRE\\_C](#) or [NRE-C](#) from Miller BK, Weniger C, Forré P. [\*Contrastive Neural Ratio Estimation\*](#) (NeurIPS 2022).

These slides: [bit.ly/ras-sbi-disc](https://bit.ly/ras-sbi-disc)  
Q&A: [bit.ly/ras-sbi-qs](https://bit.ly/ras-sbi-qs)

## Structure

- Why SBI?
- What are the limits?
- (When) Will SBI replace Likelihood-based?

[https://ras.ac.uk/events-and-meetings/  
ras-meetings/simulation-based-  
inference-astrophysics](https://ras.ac.uk/events-and-meetings/ras-meetings/simulation-based-inference-astrophysics)

These slides: [bit.ly/ras-sbi-disc](https://bit.ly/ras-sbi-disc)  
Q&A: [bit.ly/ras-sbi-qs](https://bit.ly/ras-sbi-qs)

## What are the limits?

- When not to use it?
- What is still missing from SBI frameworks?
- Is it only a matter of building trust in SBI techniques?
- Simulations are key, but what about compression?
- Are the emerging SBI methods multi-purpose enough that we now only need to worry about how we perform our simulations?

Thanks to organisers of RAS SBI meeting:  
Alessio Spurio Mancini  
Ian Harrison  
Will Hartley

Watch out for community document summarising  
meeting and SBI outlook.

*I know no other discipline where half of the principle equation is so widely ignored*

**John Skilling**

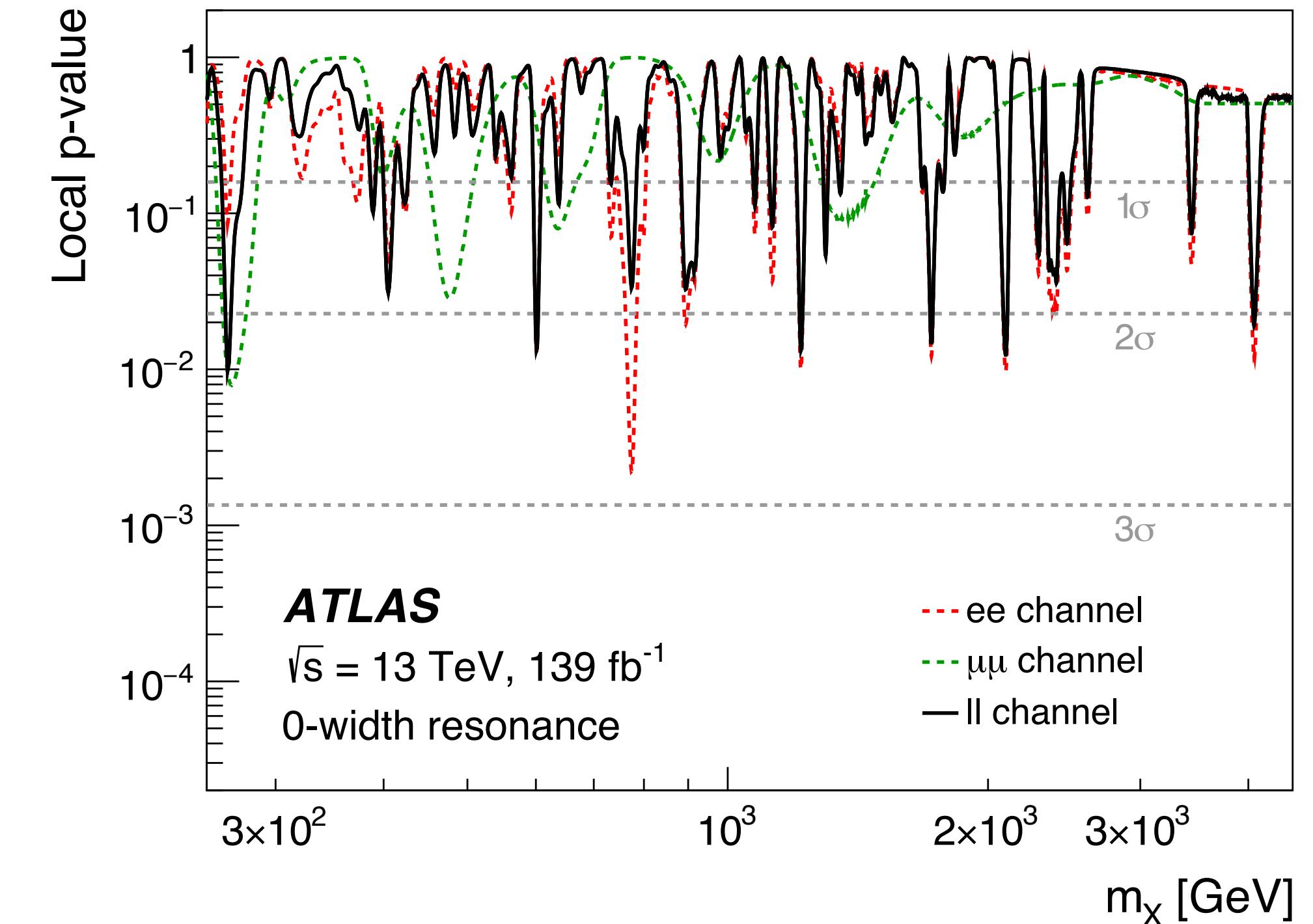
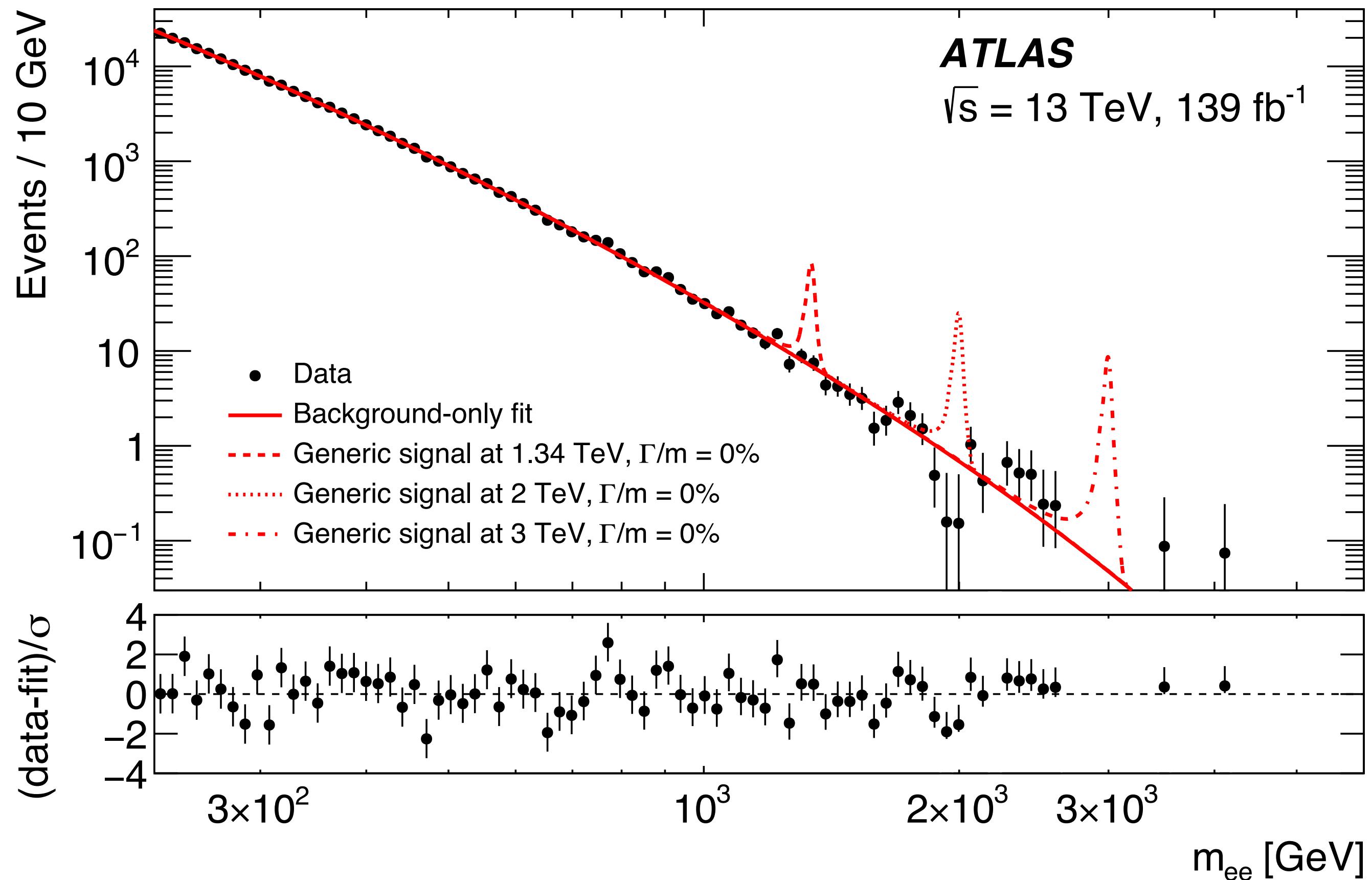
$$\mathcal{L} \times \Pi = Z \times P$$

Likelihood x Prior = Evidence x Posterior

*“Think of “Bayesian Inference” as generation of the Evidence, with the Posterior following if needed.*

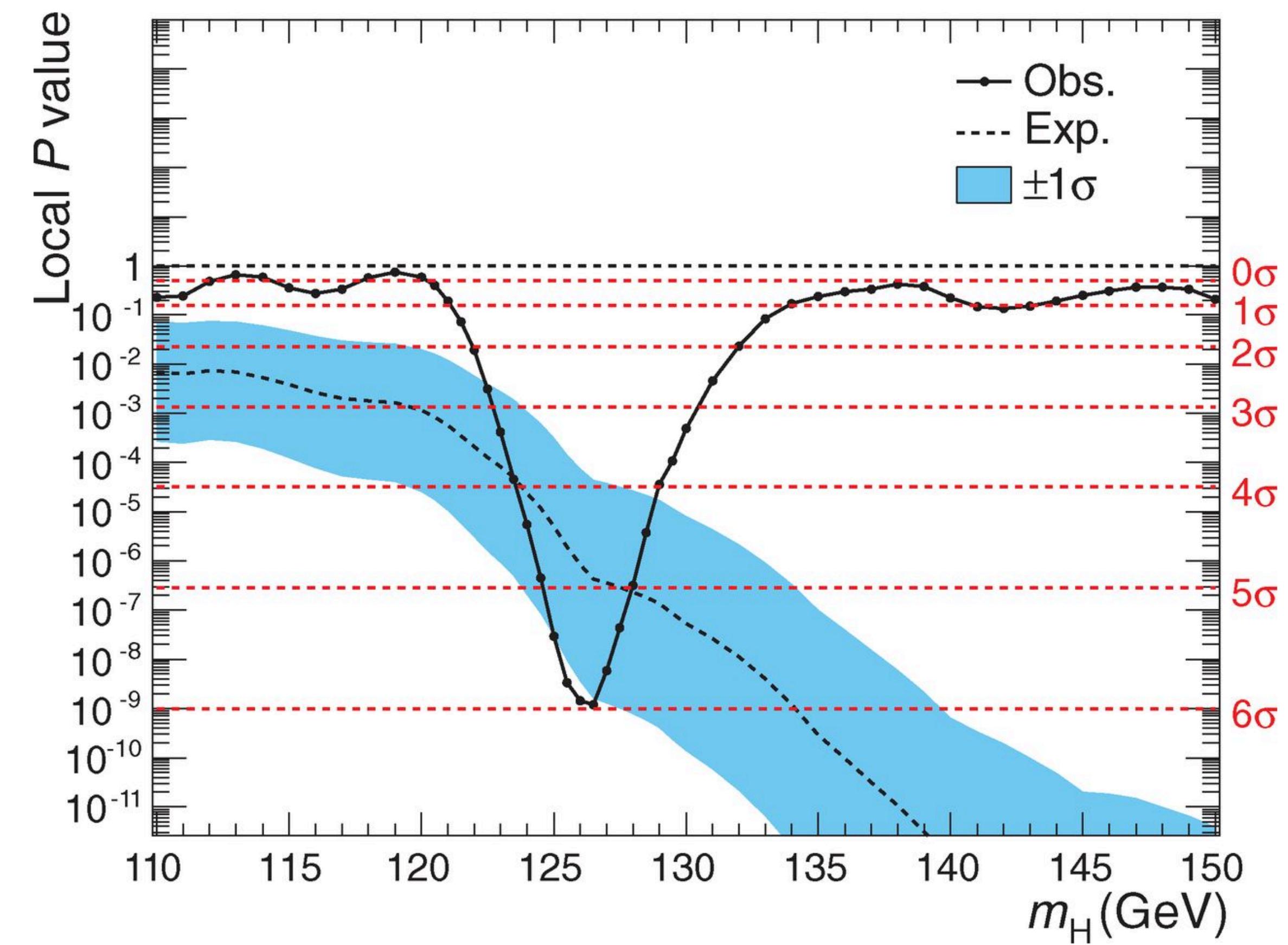
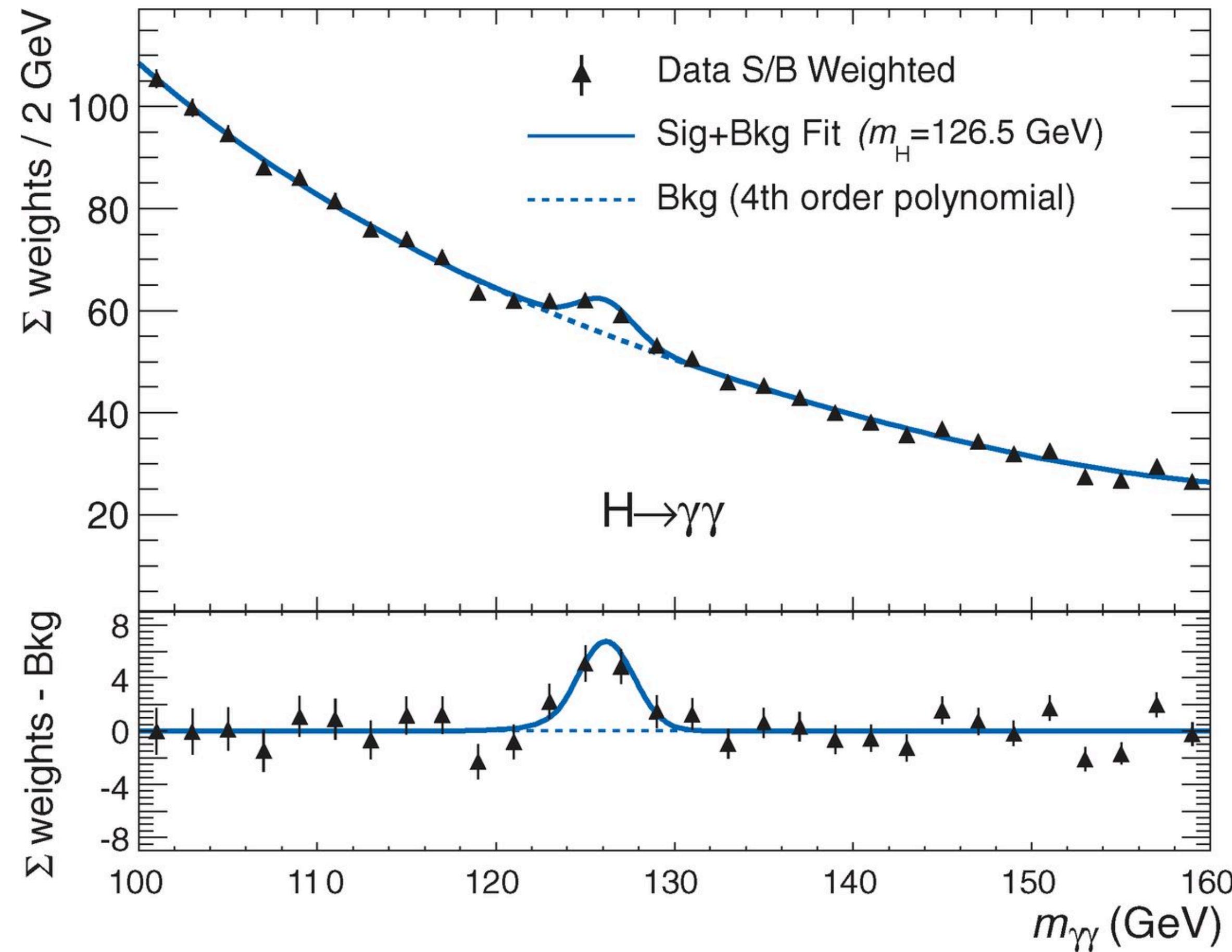
***Evidence is primary.”***

# Evidence is all you need

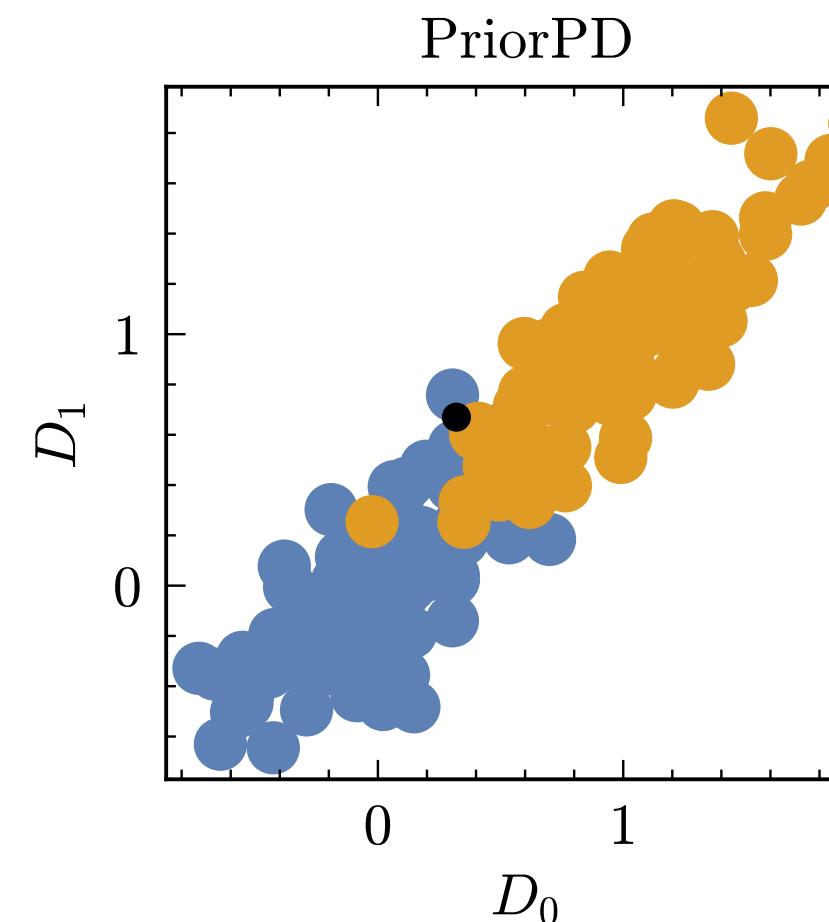
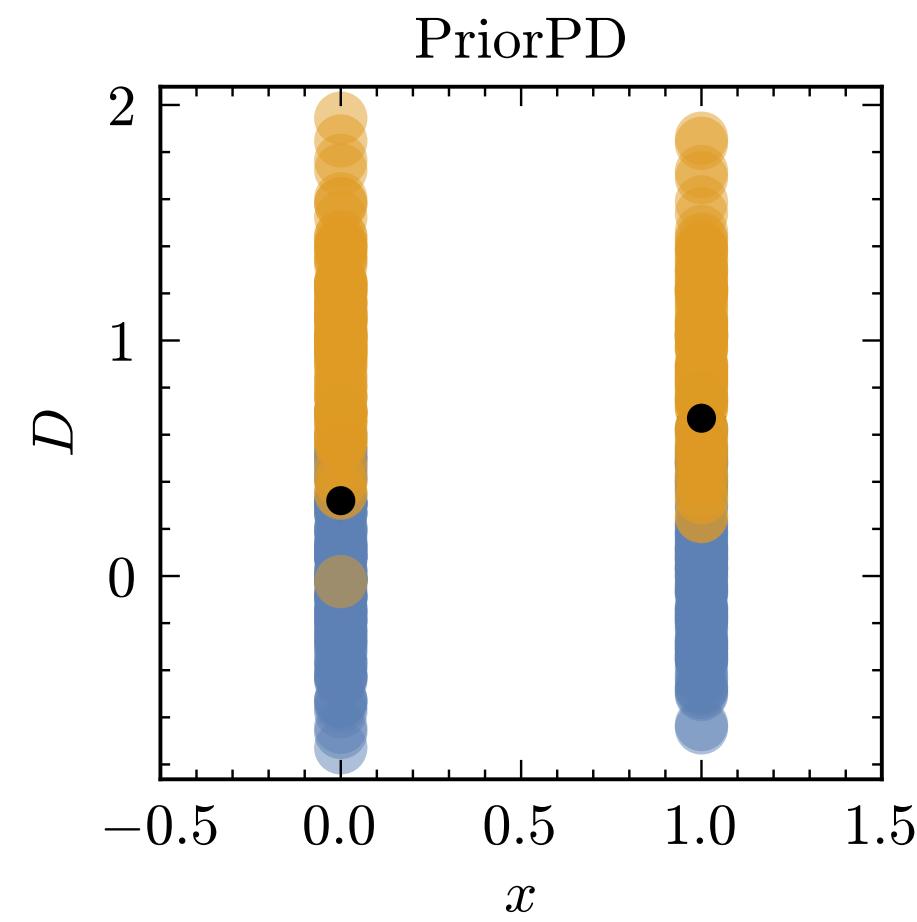
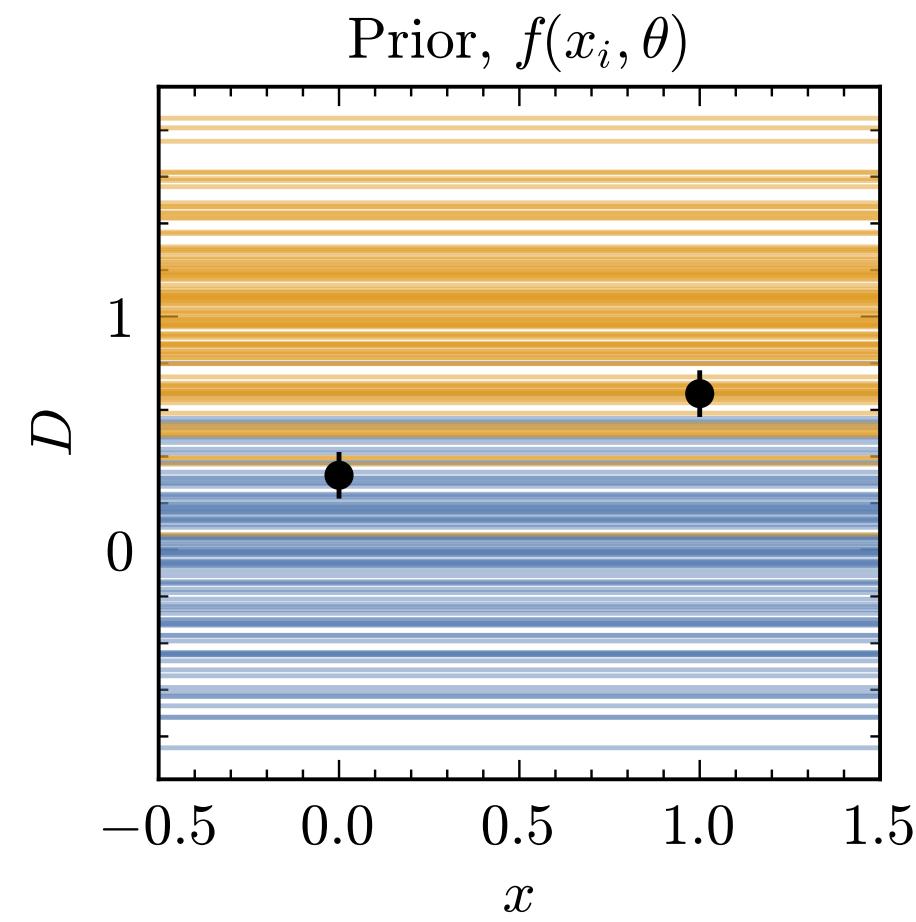


No significant excess is observed. The largest deviations from the background-only hypothesis in the dielectron, dimuon and combined dilepton channels are observed at masses of 774 GeV, 267 GeV and 264 GeV for zero-width signals with a local  $p_0$  of  $2.9\sigma$ ,  $2.4\sigma$  and  $2.3\sigma$  and a **global significance of  $0.1\sigma$ ,  $0.3\sigma$ , and zero**, respectively

# Evidence is all you need (sort of)



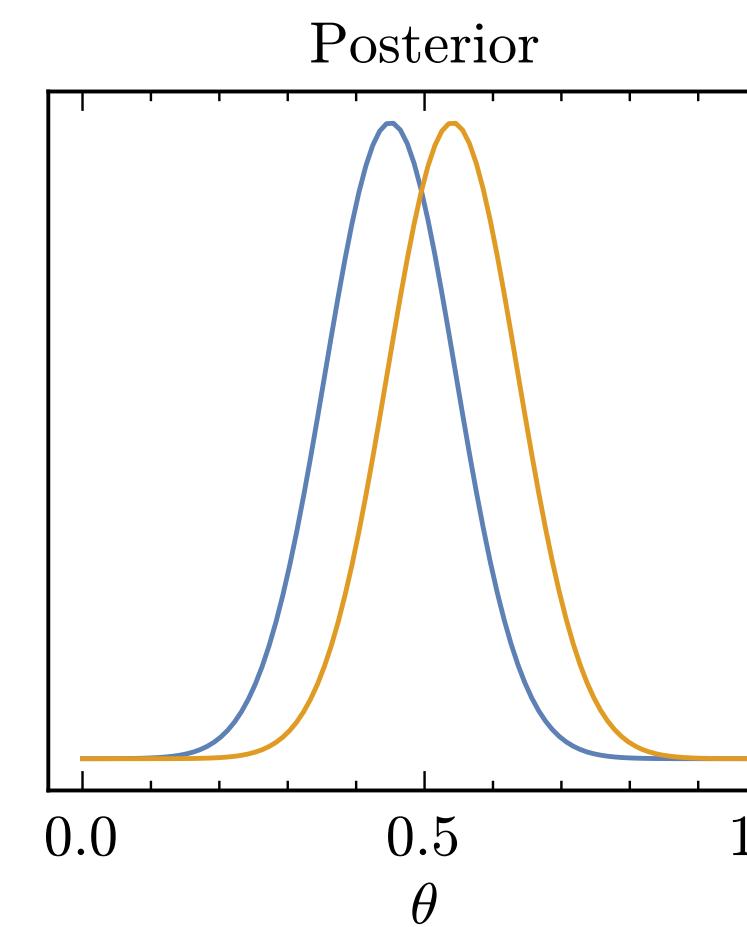
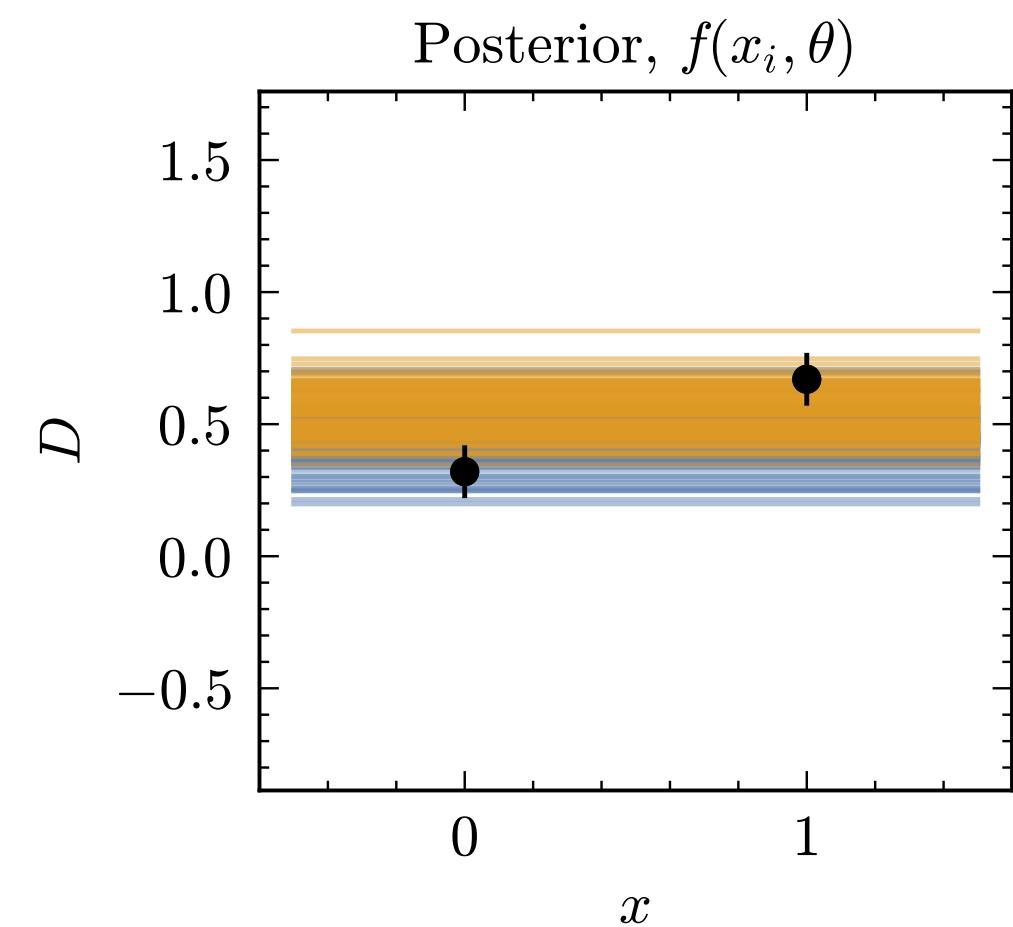
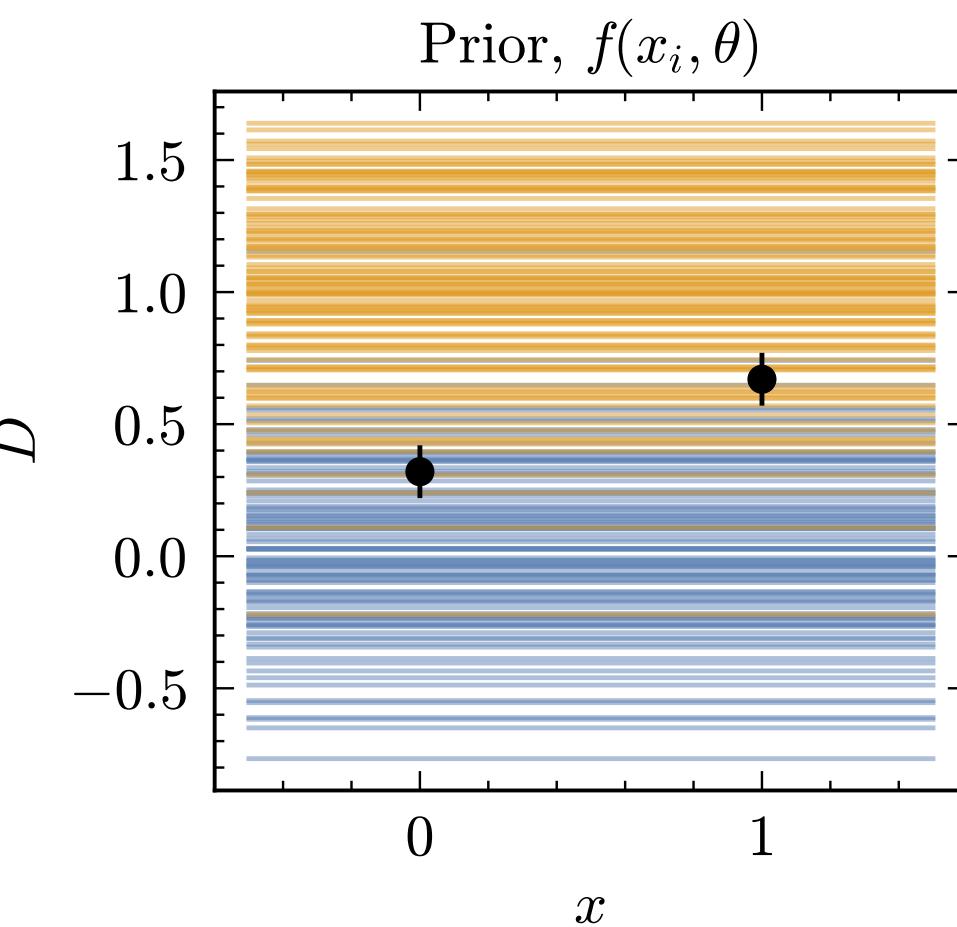
Refine simulations??



Ingredients:  
Model for your data:  $f(x_i, \theta)$   
Noise model for your data e.g.:  $n_i \leftarrow \mathcal{N}(0, \sigma)$

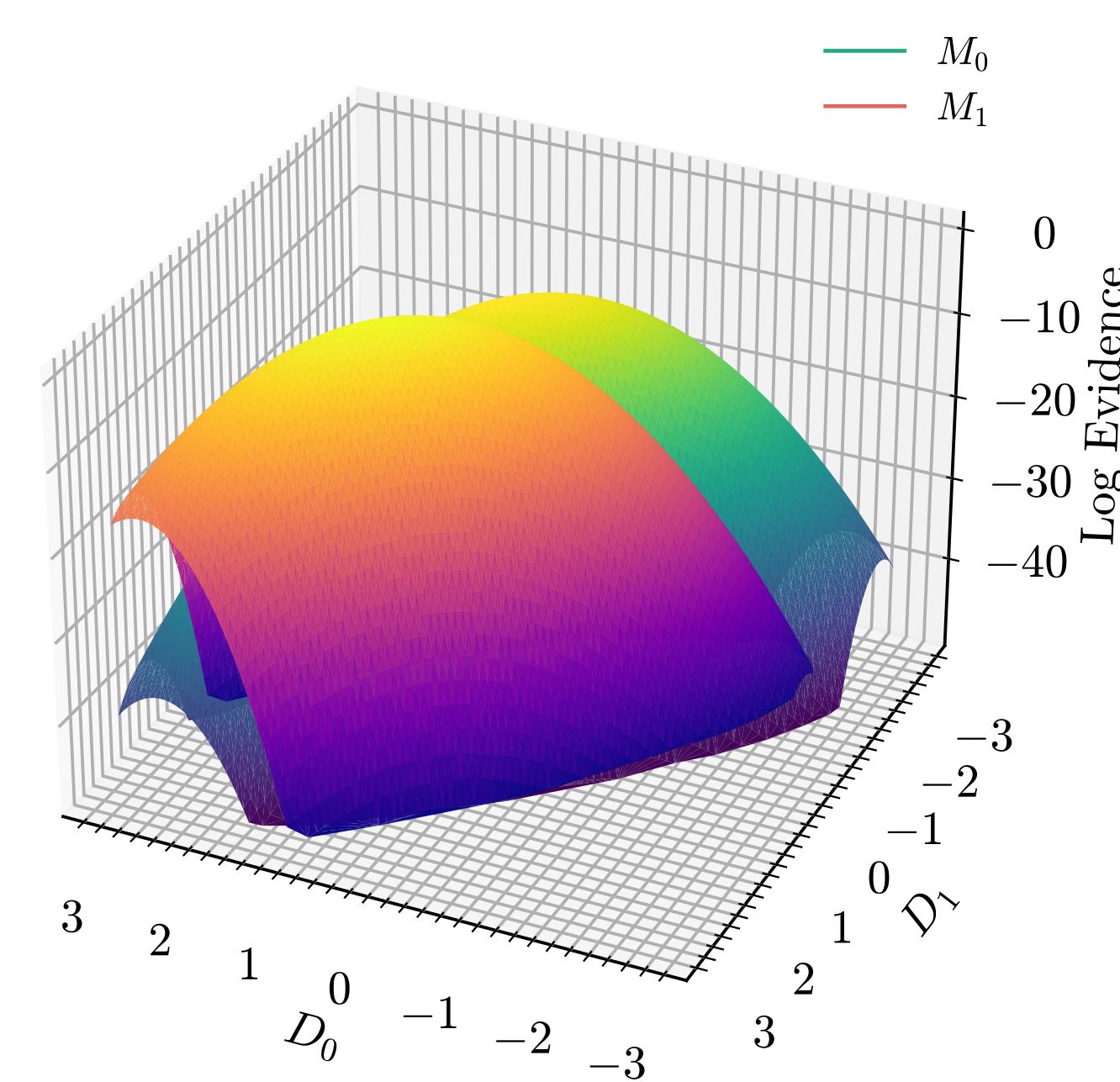
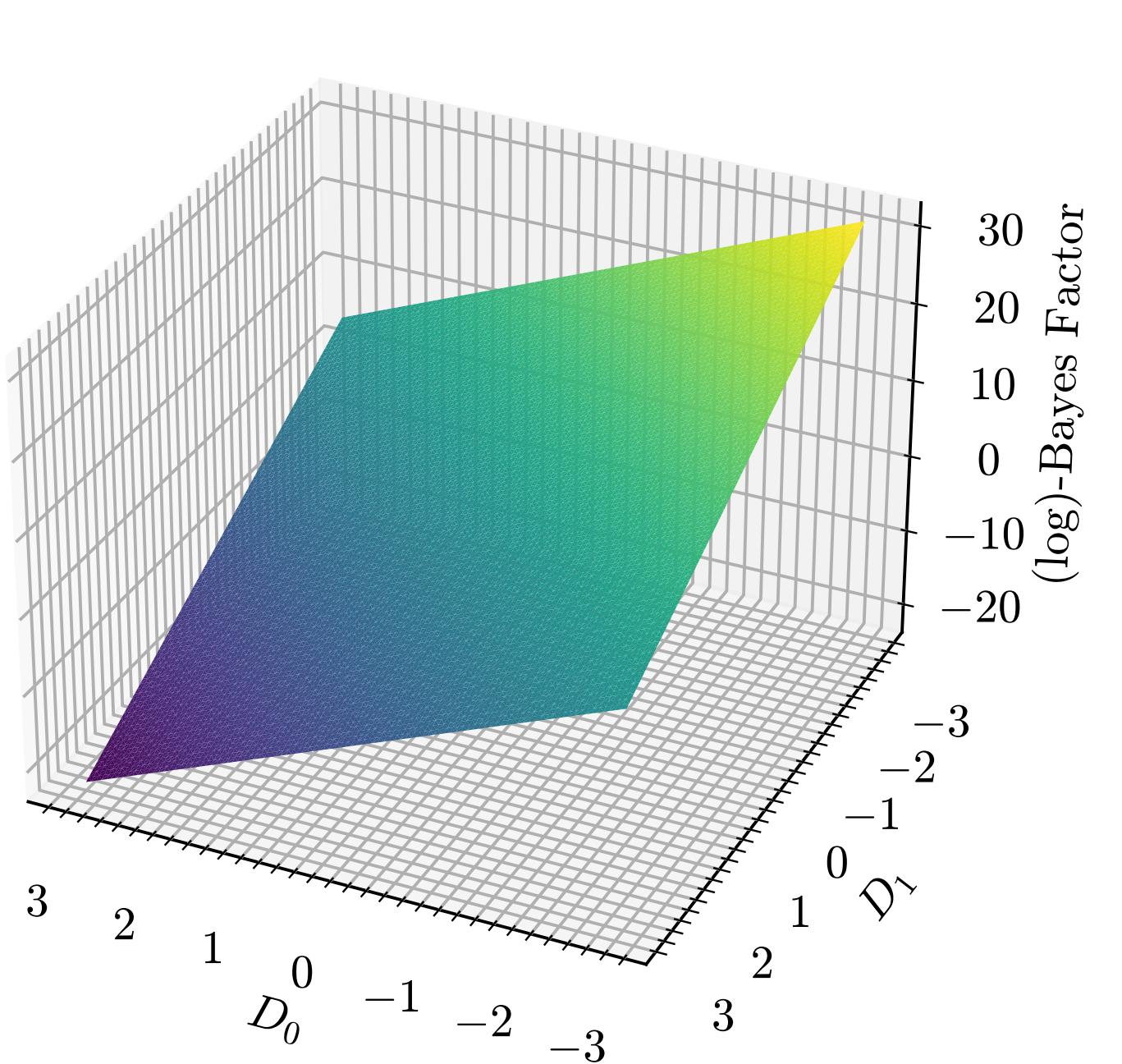
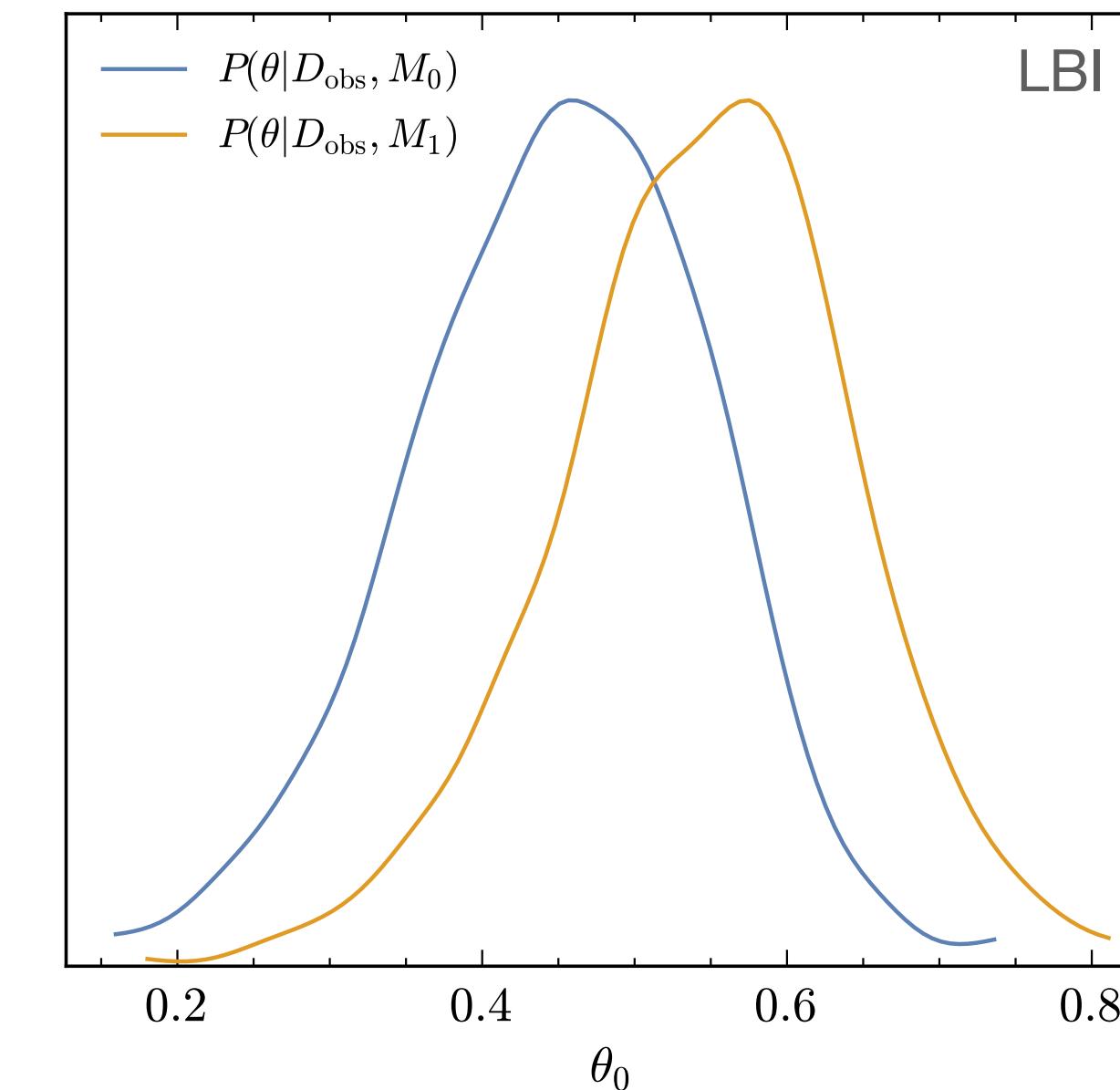
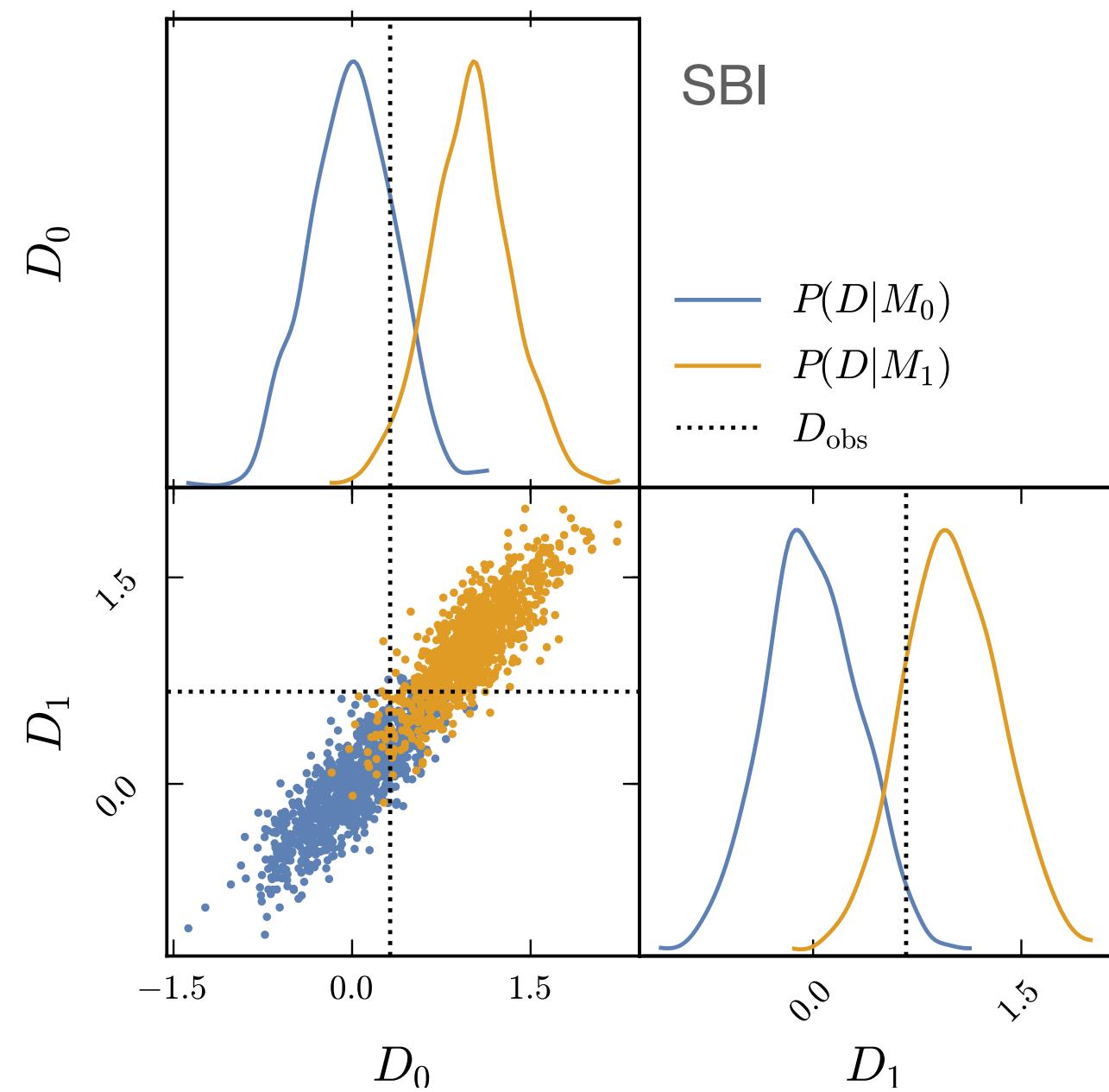
$$D_i = f(x_i, \theta) + n_i$$

SBI



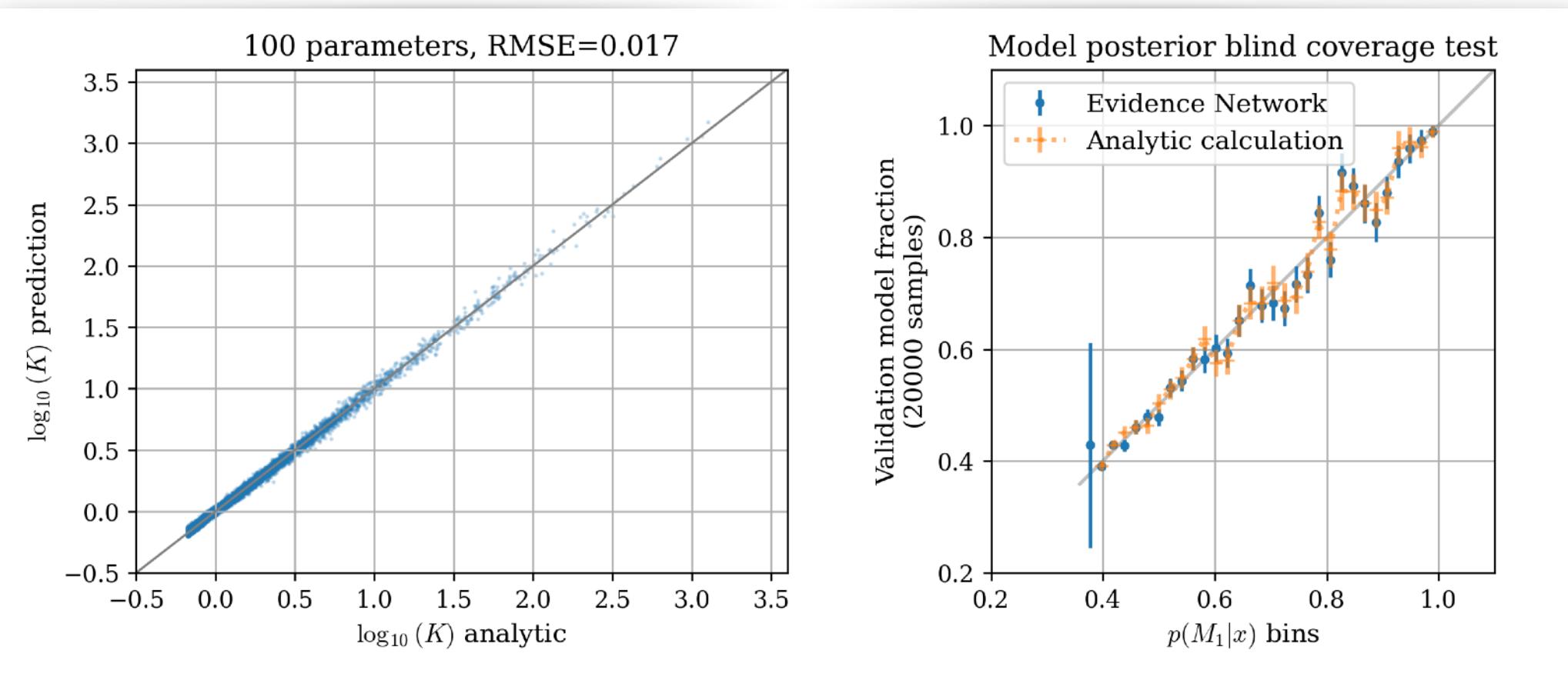
$$L(D | \theta, M) = \prod_i \frac{1}{\sqrt{2\pi}\sigma} e^{\frac{-(f(x_i, \theta) - D_i^{obs})^2}{2\sigma^2}}$$

LBI



The likelihood ratio trick appears to imply model comparison is “easier” than parameter estimation in SBI.

This is what I find most interesting about SBI!



[2305.11241]

Evidence Networks:

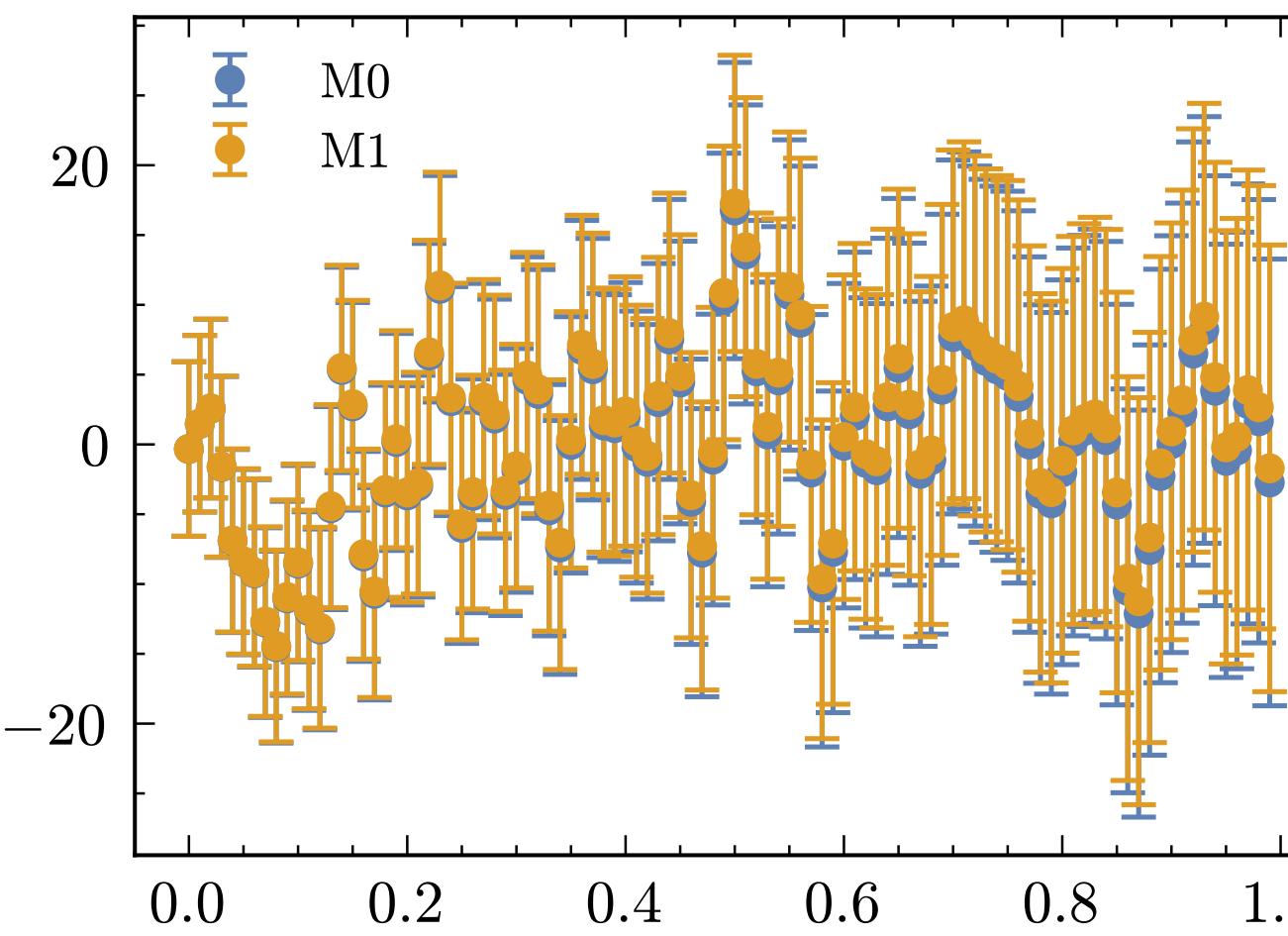
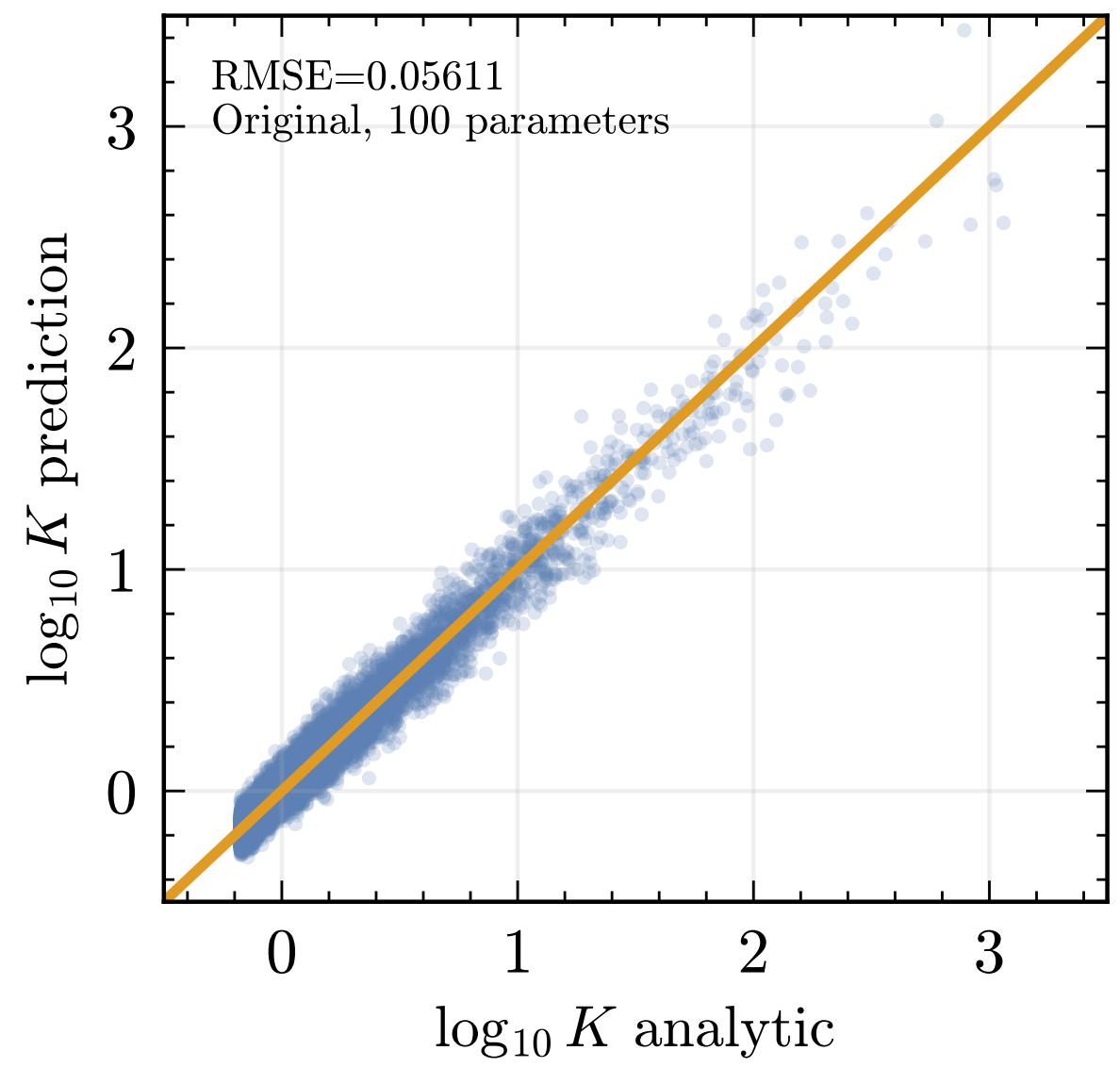
Take the “Likelihood ratio trick” seriously with generation of data from a prior distribution.

[1805.12244]

**The likelihood ratio trick (LRT).** A surrogate model for the likelihood ratio  $\hat{r}(x|\theta_0, \theta_1)$  can be defined by training a probabilistic classifier to discriminate between two equal-sized samples  $\{x_i\} \sim p(x|\theta_0)$  and  $\{x_i\} \sim p(x|\theta_1)$ . The binary cross-entropy loss

$$L_{XE} = -\mathbb{E}[\mathbf{1}(\theta = \theta_1) \log \hat{s}(x|\theta_0, \theta_1) + \mathbf{1}(\theta = \theta_0) \log(1 - \hat{s}(x|\theta_0, \theta_1))] \quad (1)$$

is minimized by the optimal decision function  $s(x|\theta_0, \theta_1) = p(x|\theta_1)/(p(x|\theta_0) + p(x|\theta_1))$ . Inverting this relation, the likelihood ratio can be estimated from the classifier decision function  $\hat{s}(x)$  as  $\hat{r}(x|\theta_0, \theta_1) = (1 - \hat{s}(x|\theta_0, \theta_1))/\hat{s}(x|\theta_0, \theta_1)$ . This “likelihood ratio trick” is widely appreciated [5–



$$A_{i0} = 2x_i,$$

$$A_{ij} = \cos(j - 1/2)x_i,$$

$$n_i \leftarrow \mathcal{N}(0, \{2, \dots, 4.5\}),$$

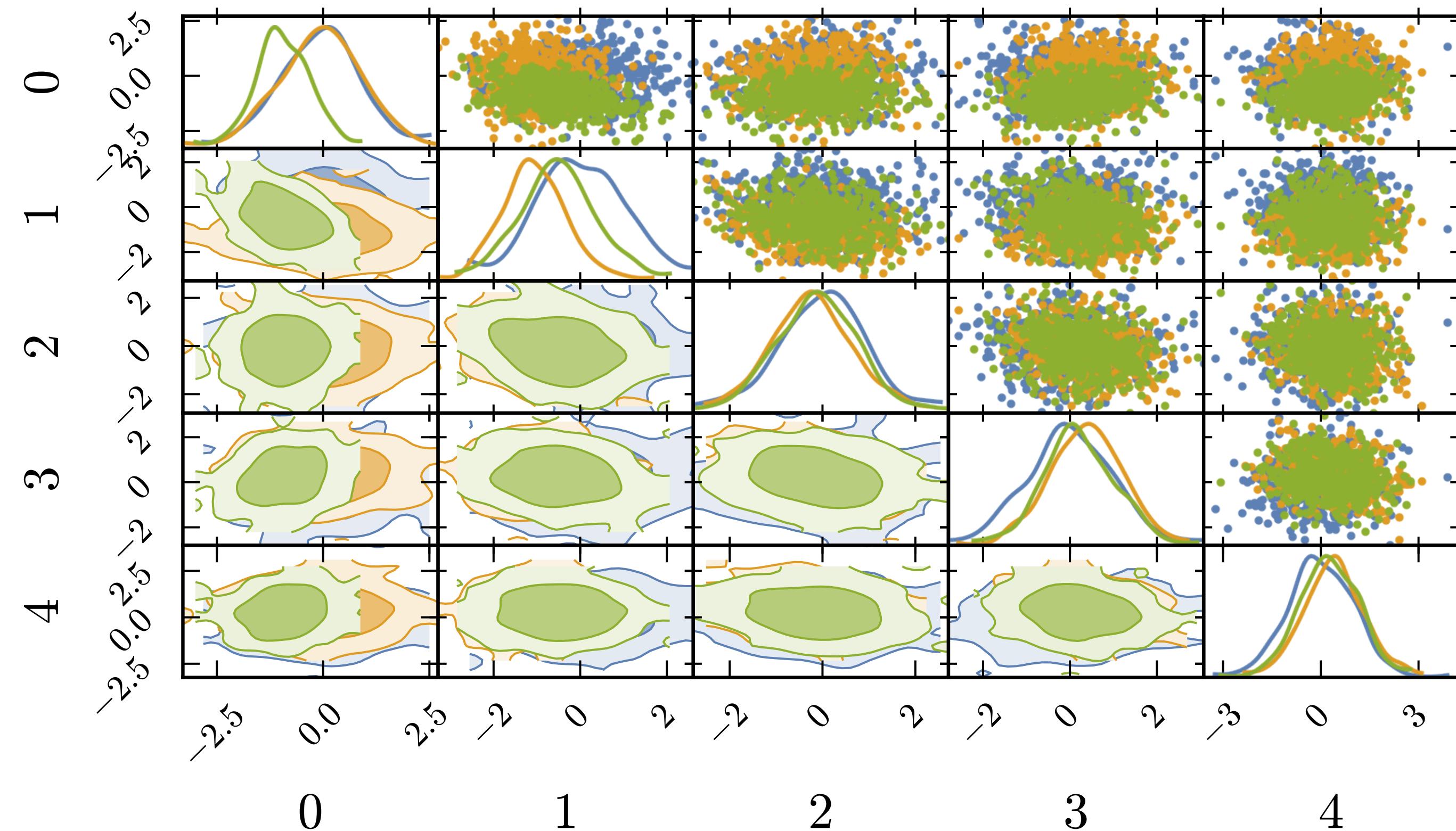
$$\theta_i \leftarrow \mathcal{N}(0, 1).$$

$$D_i = A_{ij}\theta_j + n_i$$

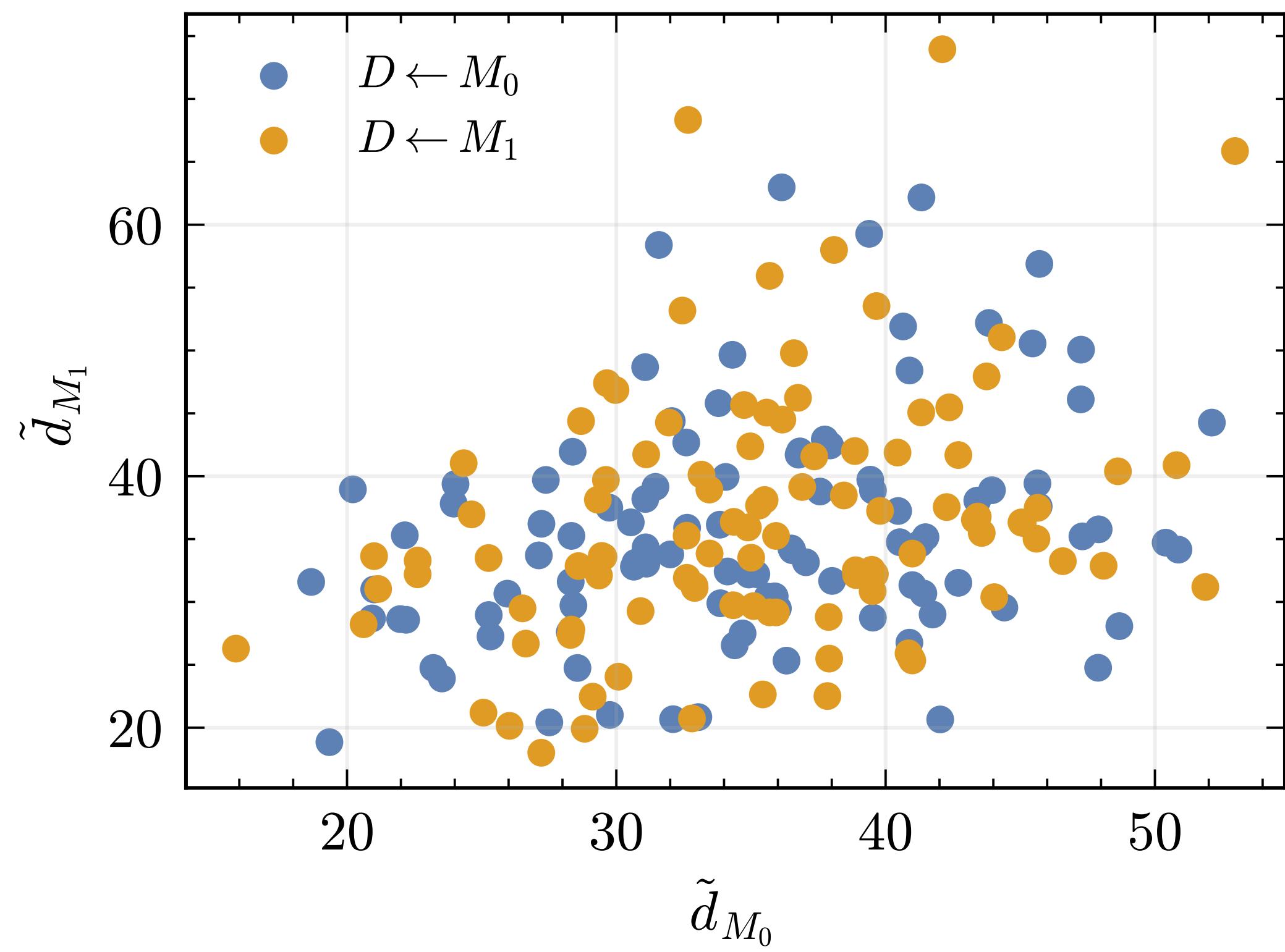
[1903.06682]

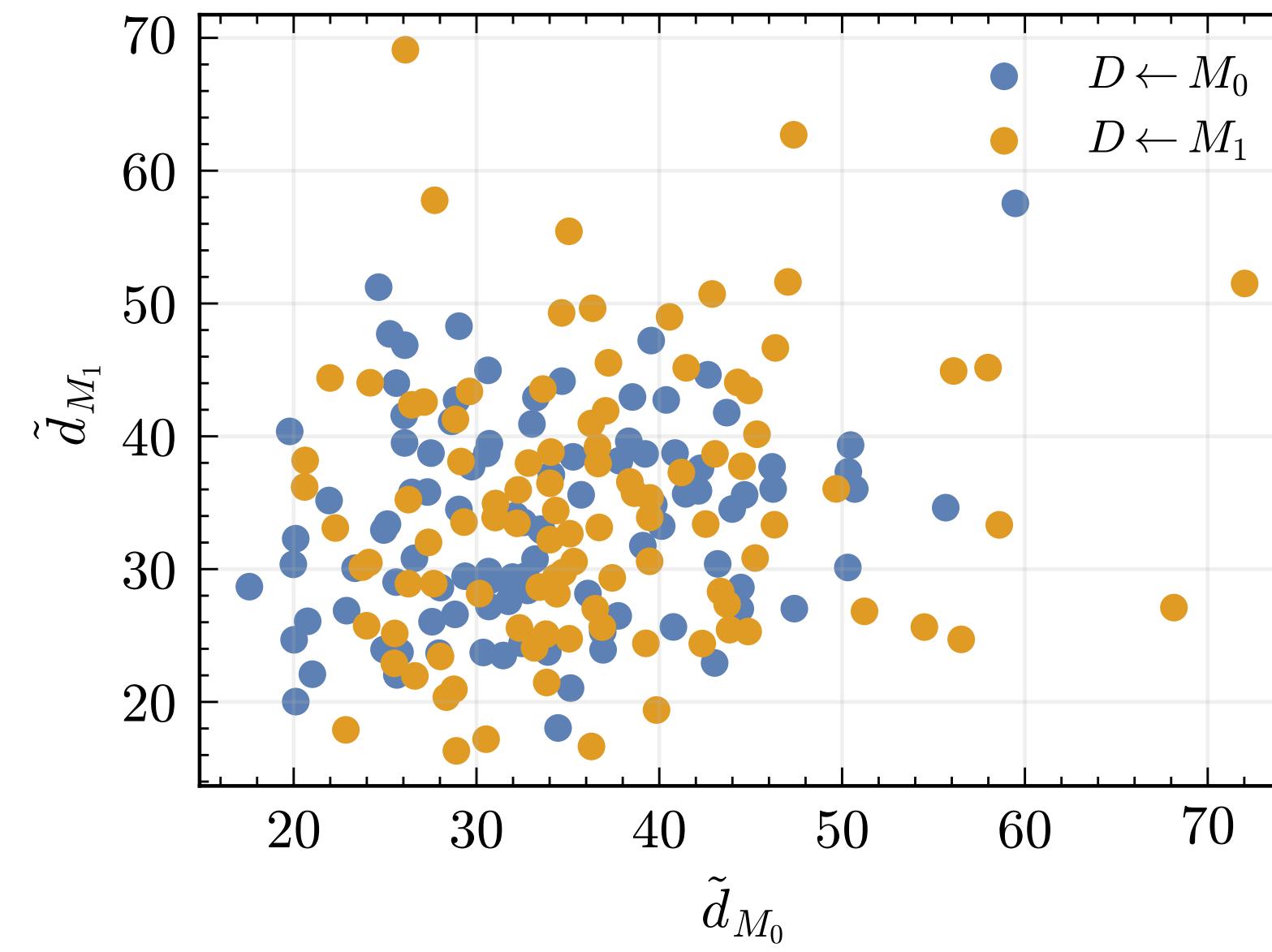
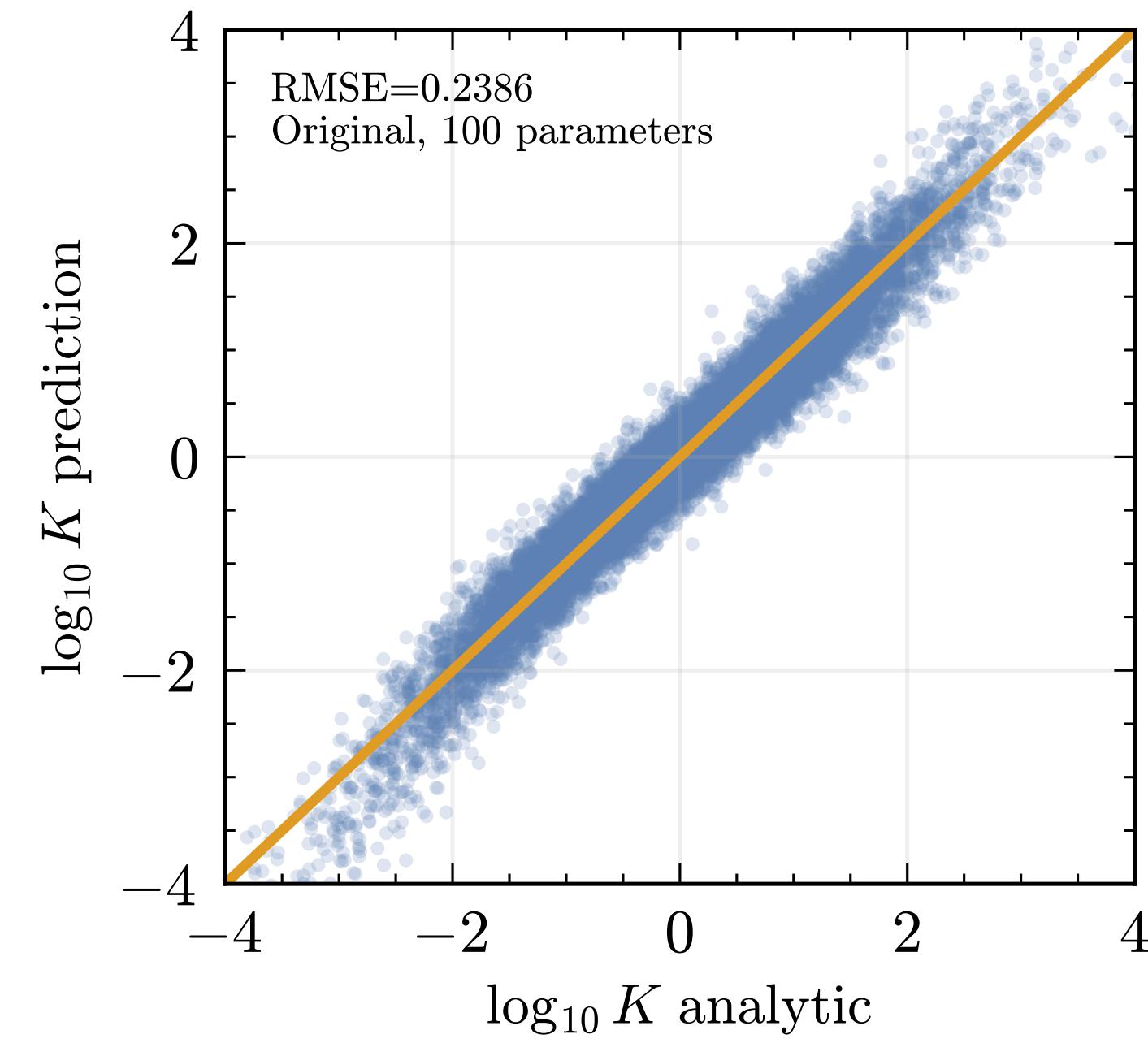
$$\frac{\tilde{d}}{2} = \langle (\ln \mathcal{L})^2 \rangle_P - \langle \ln \mathcal{L} \rangle_P^2$$

Blue (Prior), Yellow/Green (Posterior) first  
5 params



Bayesian Model Dimensionality - on a Gaussian gives the effective DoF

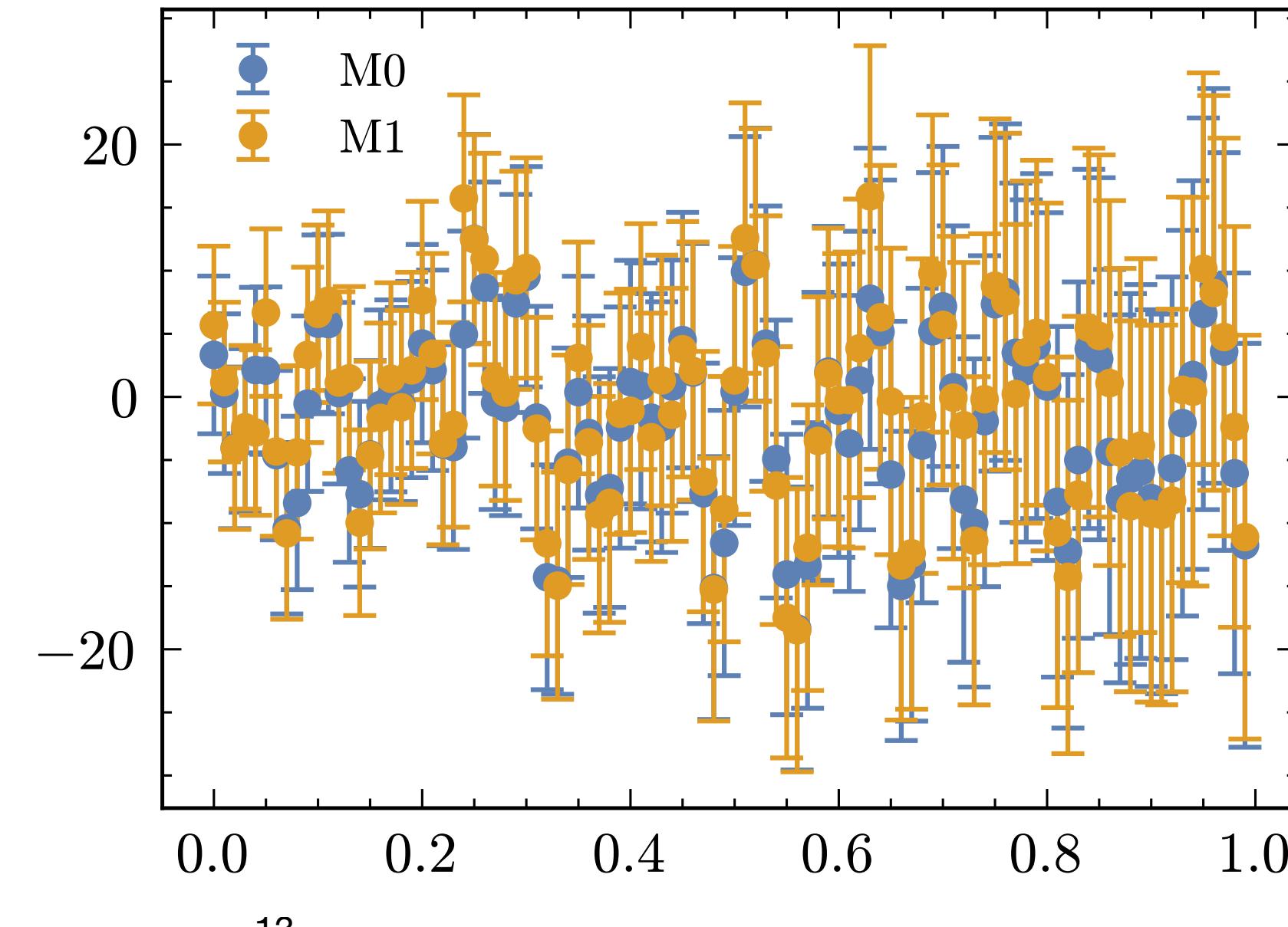
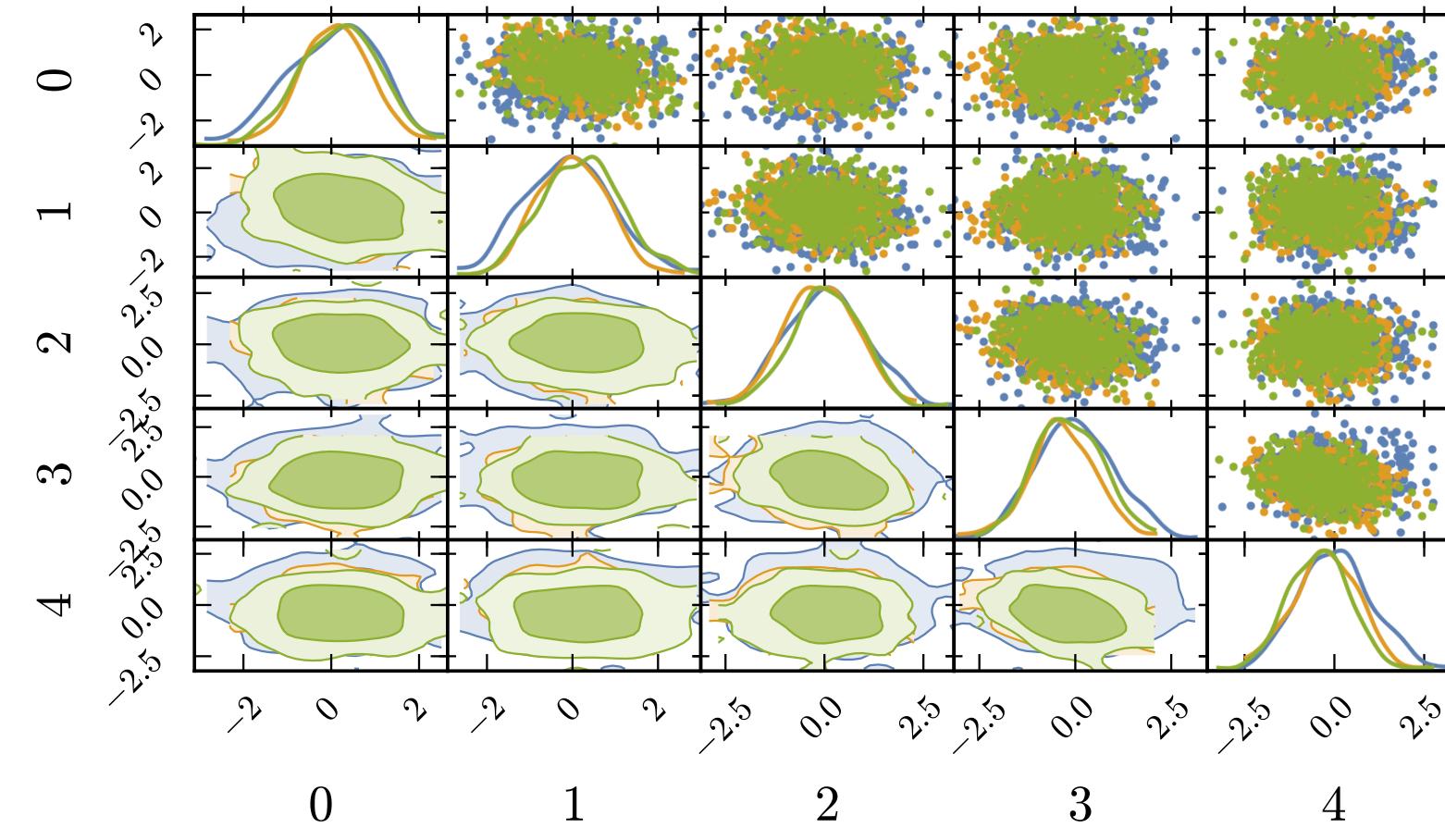


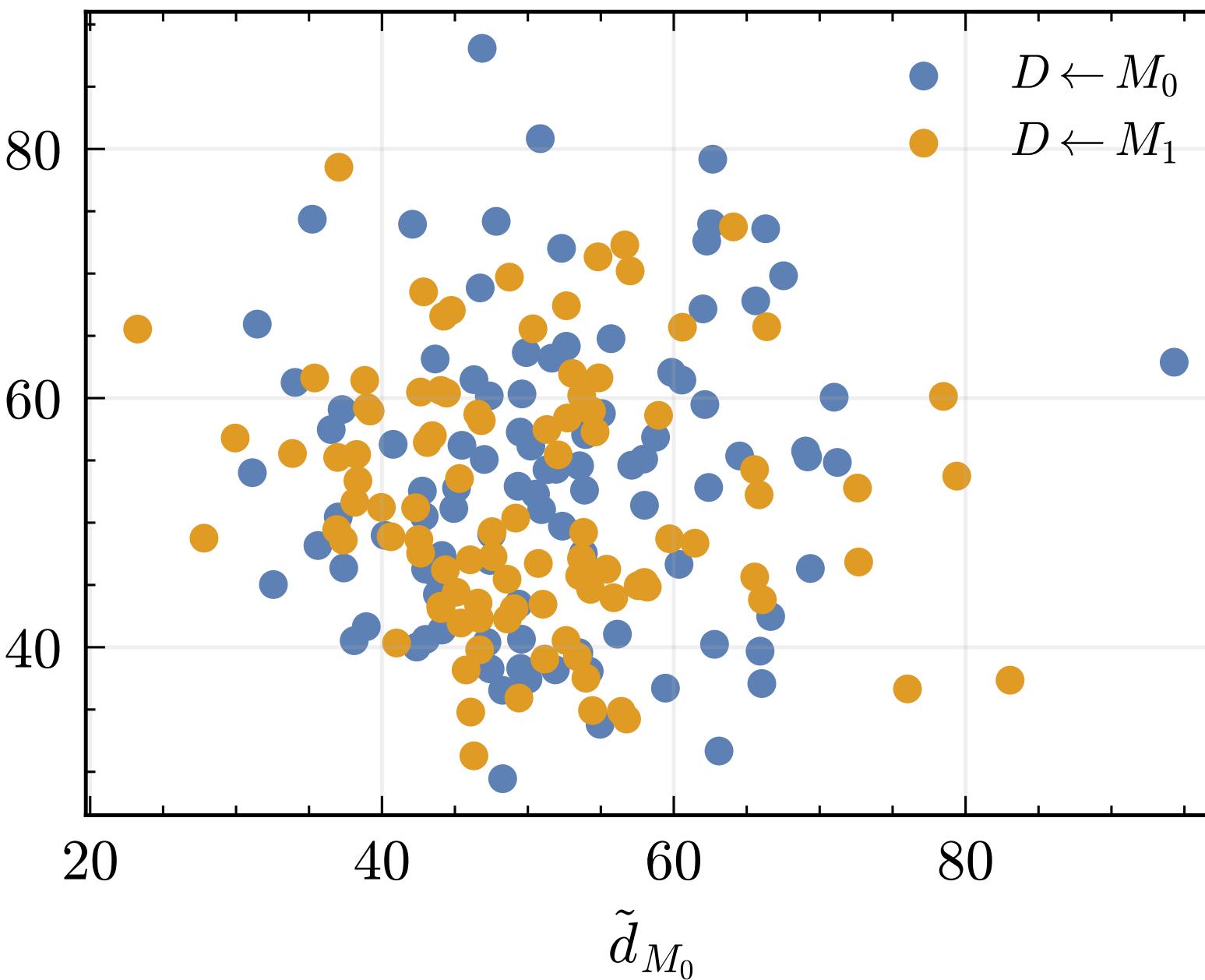
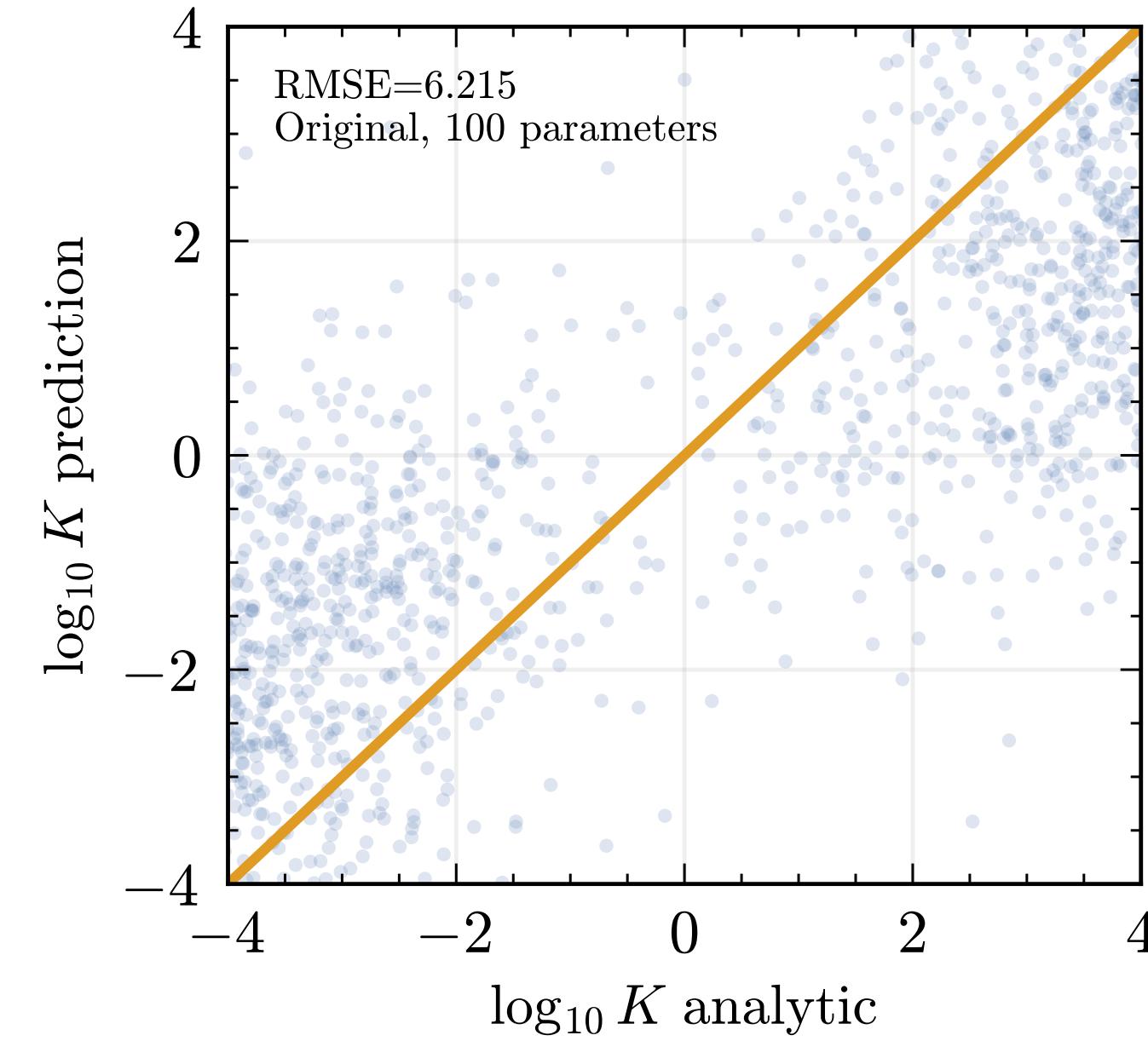


$$A_{ij}^0 = \cos(j - 1/2)x_i,$$

$$A_{ij}^1 = A_{ij}^0 \cdot R$$

$$R \leftarrow O(N, \epsilon)$$



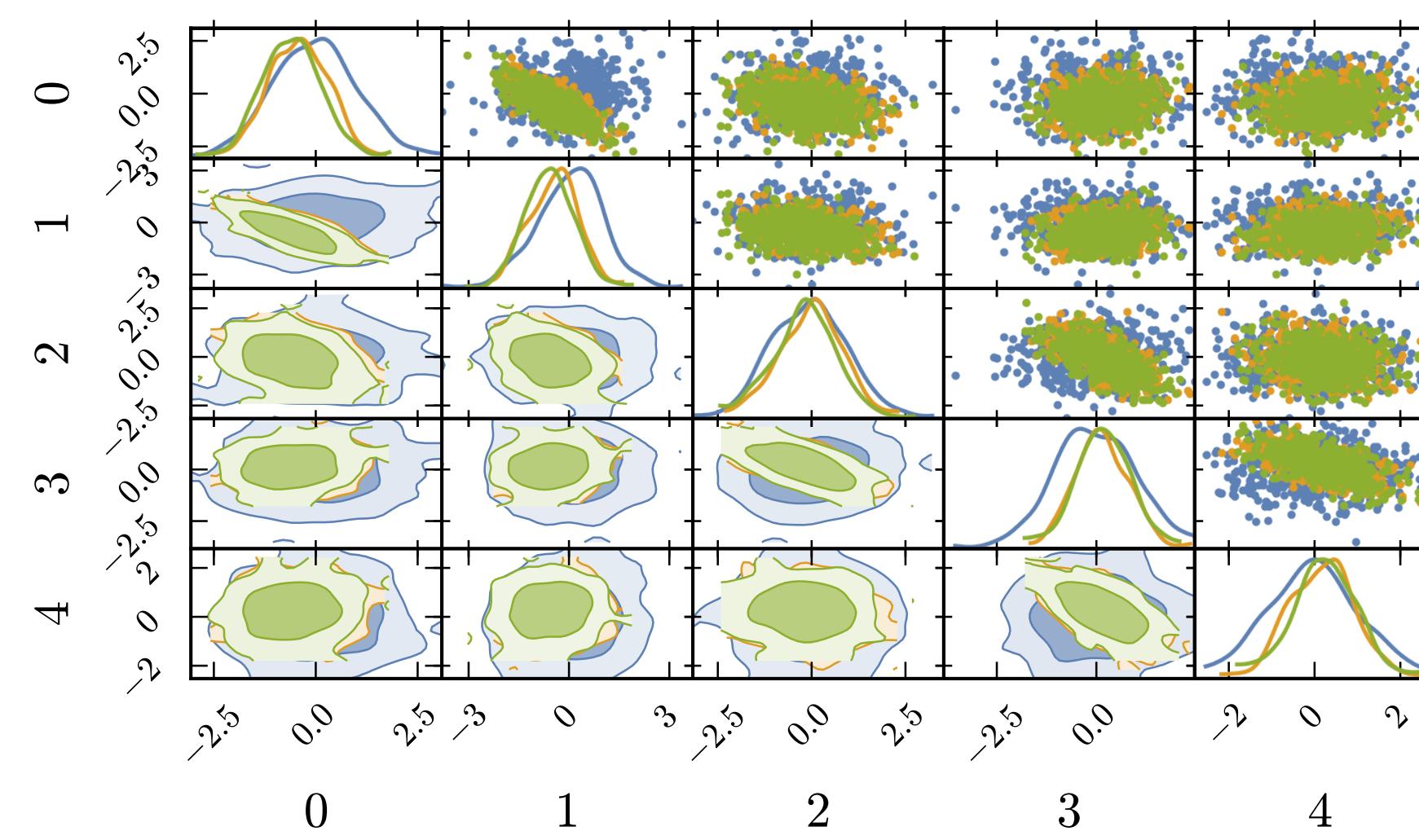
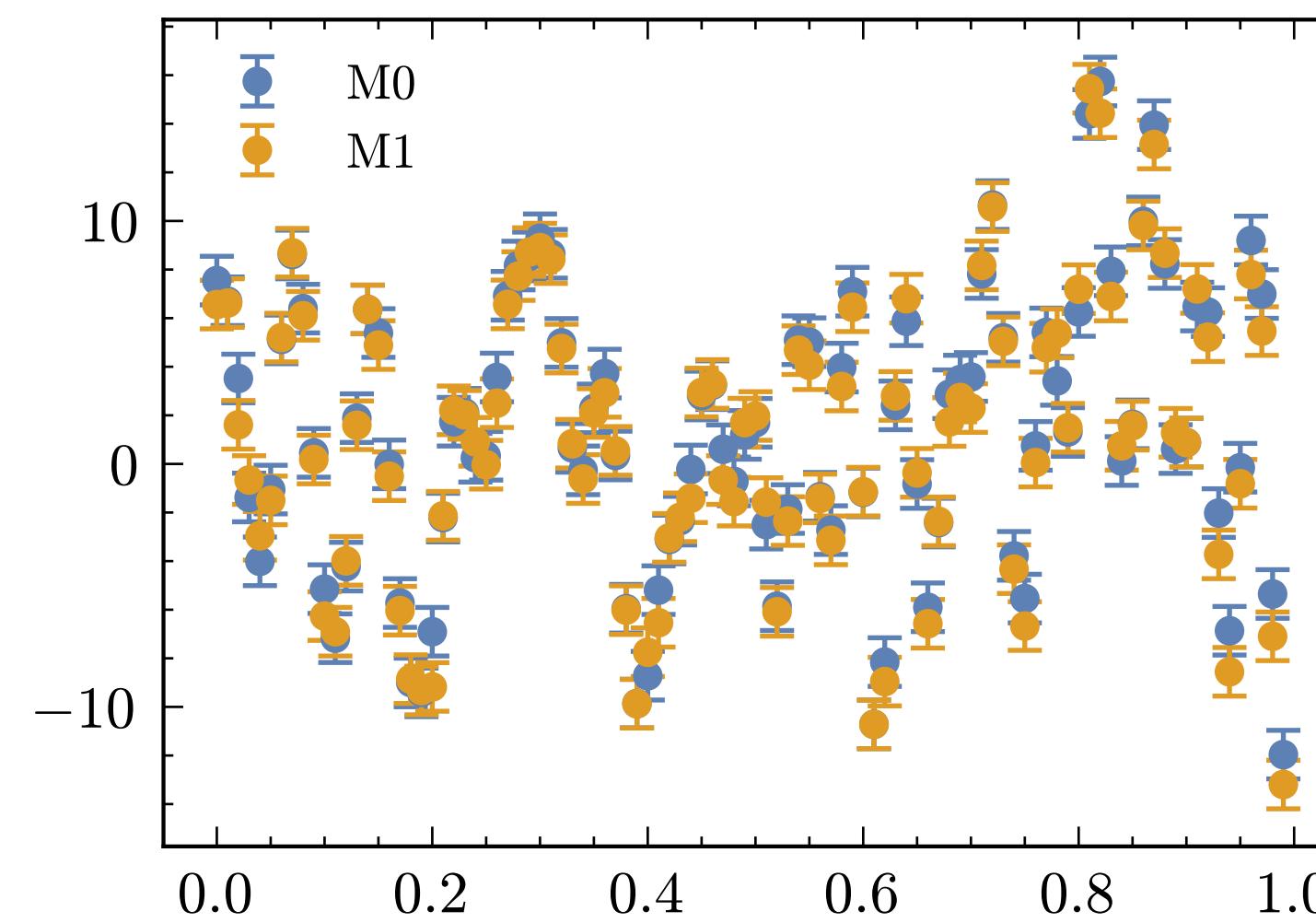


$$A_{ij}^0 = \cos(j - 1/2)x_i,$$

$$A_{ij}^1 = A_{ij}^0 \cdot R$$

$$R \leftarrow O(N, \epsilon)$$

$$n_i \leftarrow \mathcal{N}(0, 1)$$



# How good do your simulations have to be?

- Model misspecification – “*All models are wrong some are useful*”, expect data we analyse will *never* be drawn from the model we are proposing
  - How well can neural techniques extrapolate
- Relevance of simulation data to observed data
  - A lot of the really juicy parts of SBI are gaining from being apparently vastly more economical here, amortization over all data?
  - **How good do your {simulations} have to be?**

# Assorted thoughts

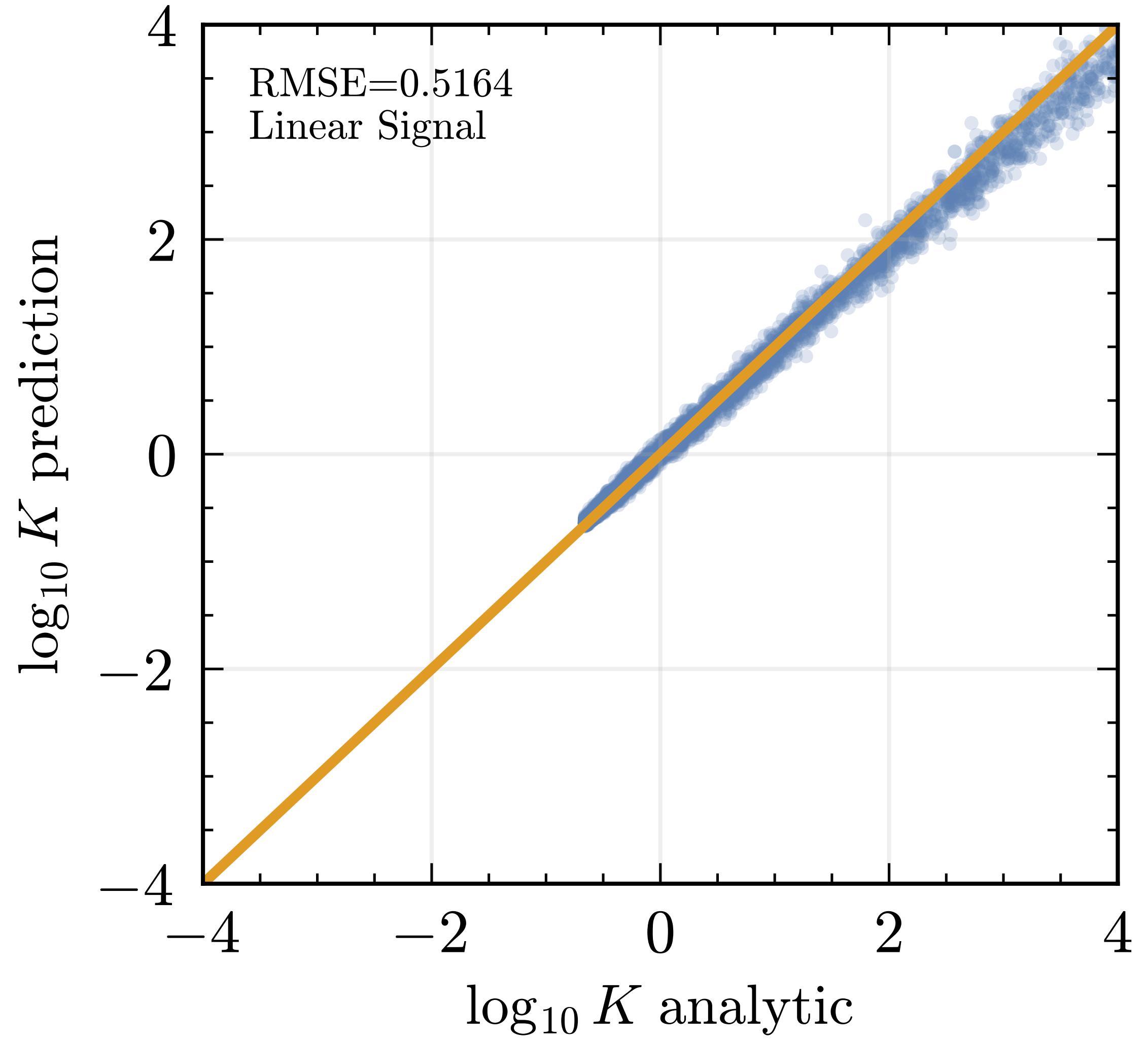
- How different is using a GP acquisition to get a new set of sims for my amortized SBI pipeline from using a GP surrogate in parameter space?  
 $\mathcal{O}(D) \ll \mathcal{O}(\theta),$
- What regime are we in:  $\mathcal{O}(D) = \mathcal{O}(\theta),$   
 $\mathcal{O}(D) \gg \mathcal{O}(\theta)$
- It's very hard to think of something analytic, non-linear, representative of real problems! Writing good test problems is a lot harder than it seems

# Conclusions

- Ratios are interesting, potential cancellation that simplifies problems
- How we [sequential] or [amortize] + [active learning??] is for my money the open problem
- The above can be mapped onto traditional methods?
- SBI is here to stay

*If your experiment needs statistics, you ought to have done a better experiment.*

**Ernest Rutherford**



$$\begin{aligned}
 A_{i0} &= 2x_i, \\
 A_{ij} &= \sin \frac{\pi}{10} (j + 1/2)x_i, \\
 n_i &\leftarrow \mathcal{N}(0, 1), \\
 \theta_i &\leftarrow \mathcal{N}(0, 1). \\
 D_i &= A_{ij}\theta_j + n_i
 \end{aligned}$$