

4.5 The Dimension of a Vector Space

THEOREM 9

If a vector space V has a basis $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$, then any set in V containing more than n vectors must be linearly dependent.

Proof: Suppose $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is a set of vectors in V where $p > n$. Then the coordinate vectors $\{[\mathbf{u}_1]_\beta, \dots, [\mathbf{u}_p]_\beta\}$ are in \mathbf{R}^n . Since $p > n$, $\{[\mathbf{u}_1]_\beta, \dots, [\mathbf{u}_p]_\beta\}$ are linearly dependent and therefore $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ are linearly dependent. ■

THEOREM 10

If a vector space V has a basis of n vectors, then every basis of V must consist of n vectors.

Proof: Suppose β_1 is a basis for V consisting of exactly n vectors. Now suppose β_2 is any other basis for V . By the definition of a basis, we know that β_1 and β_2 are both linearly independent sets.

By Theorem 9, if β_1 has more vectors than β_2 , then _____ is a linearly dependent set (which cannot be the case).

Again by Theorem 9, if β_2 has more vectors than β_1 , then _____ is a linearly dependent set (which cannot be the case).

Therefore β_2 has exactly n vectors also. ■

DEFINITION

If V is spanned by a finite set, then V is said to be **finite-dimensional**, and the **dimension** of V , written as $\dim V$, is the number of vectors in a basis for V . The dimension of the zero vector space $\{\mathbf{0}\}$ is defined to be 0. If V is not spanned by a finite set, then V is said to be **infinite-dimensional**.

EXAMPLE: The standard basis for \mathbf{P}_3 is $\{ \quad \quad \quad \}$. So $\dim \mathbf{P}_3 = \underline{\hspace{2cm}}$.

In general, $\dim \mathbf{P}_n = n + 1$.

EXAMPLE: The standard basis for \mathbf{R}^n is $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ where $\mathbf{e}_1, \dots, \mathbf{e}_n$ are the columns of I_n . So, for example, $\dim \mathbf{R}^3 = 3$.

EXAMPLE: Find a basis and the dimension of the subspace

$$W = \left\{ \begin{bmatrix} a + b + 2c \\ 2a + 2b + 4c + d \\ b + c + d \\ 3a + 3c + d \end{bmatrix} : a, b, c, d \text{ are real} \right\}.$$

Solution: Since

$$\begin{bmatrix} a + b + 2c \\ 2a + 2b + 4c + d \\ b + c + d \\ 3a + 3c + d \end{bmatrix} = a \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix} + b \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 2 \\ 4 \\ 1 \\ 3 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix},$$

$$W = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$$

where $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} 2 \\ 4 \\ 1 \\ 3 \end{bmatrix}$, $\mathbf{v}_4 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$.

- Note that \mathbf{v}_3 is a linear combination of \mathbf{v}_1 and \mathbf{v}_2 , so by the Spanning Set Theorem, we may discard \mathbf{v}_3 .
- \mathbf{v}_4 is not a linear combination of \mathbf{v}_1 and \mathbf{v}_2 . So $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_4\}$ is a basis for W . Also, $\dim W = \underline{\hspace{1cm}}$.

EXAMPLE: *Dimensions of subspaces of \mathbf{R}^3*

0-dimensional subspace contains only the zero vector

$$\left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}.$$

1-dimensional subspaces. $\text{Span}\{\mathbf{v}\}$ where $\mathbf{v} \neq \mathbf{0}$ is in \mathbf{R}^3 .

These subspaces are _____ through the origin.

2-dimensional subspaces. $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ where \mathbf{u} and \mathbf{v} are in \mathbf{R}^3 and are not multiples of each other.

These subspaces are _____ through the origin.

3-dimensional subspaces. $\text{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ where $\mathbf{u}, \mathbf{v}, \mathbf{w}$ are linearly independent vectors in \mathbf{R}^3 . This subspace is \mathbf{R}^3 itself because the columns of $A = [\mathbf{u} \ \mathbf{v} \ \mathbf{w}]$ span \mathbf{R}^3 according to the IMT.

THEOREM 11

Let H be a subspace of a finite-dimensional vector space V . Any linearly independent set in H can be expanded, if necessary, to a basis for H . Also, H is finite-dimensional and

$$\dim H \leq \dim V.$$

EXAMPLE: Let $H = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$. Then H is a

subspace of \mathbf{R}^3 and $\dim H < \dim \mathbf{R}^3$.

We could expand the spanning set $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$ to

$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ to form a basis for \mathbf{R}^3 .

THEOREM 12 THE BASIS THEOREM

Let V be a p – dimensional vector space, $p \geq 1$. Any linearly independent set of exactly p vectors in V is automatically a basis for V . Any set of exactly p vectors that spans V is automatically a basis for V .

EXAMPLE: Show that $\{t, 1 - t, 1 + t - t^2\}$ is a basis for \mathbf{P}_2 .

Solution: Let $\mathbf{v}_1 = t, \mathbf{v}_2 = 1 - t, \mathbf{v}_3 = 1 + t - t^2$ and $\beta = \{1, t, t^2\}$.

Corresponding coordinate vectors

$$[\mathbf{v}_1]_{\beta} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, [\mathbf{v}_2]_{\beta} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, [\mathbf{v}_3]_{\beta} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

$[\mathbf{v}_2]_{\beta}$ is not a multiple of $[\mathbf{v}_1]_{\beta}$

$[\mathbf{v}_3]_{\beta}$ is not a linear combination of $[\mathbf{v}_1]_{\beta}$ and $[\mathbf{v}_2]_{\beta}$

$\Rightarrow \{[\mathbf{v}_1]_{\beta}, [\mathbf{v}_2]_{\beta}, [\mathbf{v}_3]_{\beta}\}$ is linearly independent and therefore $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is also linearly independent.

Since $\dim \mathbf{P}_2 = 3$, $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a basis for \mathbf{P}_2 according to The Basis Theorem.

Dimensions of Col A and Nul A

Recall our techniques to find basis sets for column spaces and null spaces.

EXAMPLE: Suppose $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8 \end{bmatrix}$. Find $\dim \text{Col } A$ and $\dim \text{Nul } A$.

Solution

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

So $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \end{bmatrix} \right\}$ is a basis for Col A and
 $\dim \text{Col } A = 2$.

Now solve $A\mathbf{x} = \mathbf{0}$ by row-reducing the corresponding augmented matrix. Then we arrive at

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 2 & 4 & 7 & 8 & 0 \end{bmatrix} \sim \dots \sim \begin{bmatrix} 1 & 2 & 0 & 4 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

$$x_1 = -2x_2 - 4x_4$$

$$x_3 = 0$$

and

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -4 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

So $\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a basis for $\text{Nul } A$ and

$$\dim \text{Nul } A = 2.$$

Note

$\dim \text{Col } A = \text{number of pivot columns of } A$

$\dim \text{Nul } A = \text{number of free variables of } A$.