Section 1.1: Systems of Linear Equations

A linear equation:

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

EXAMPLE:

$$4x_1 - 5x_2 + 2 = x_1$$
 and $x_2 = 2(\sqrt{6} - x_1) + x_3$
 \downarrow
rearranged
 \downarrow
 $3x_1 - 5x_2 = -2$
 $2x_1 + x_2 - x_3 = 2\sqrt{6}$

Not linear:

$$4x_1 - 6x_2 = x_1x_2$$
 and $x_2 = 2\sqrt{x_1} - 7$

A system of linear equations (or a linear system):

A collection of one or more linear equations involving the same set of variables, say, $x_1, x_2, ..., x_n$.

A **solution** of a linear system:

A list $(s_1, s_2, ..., s_n)$ of numbers that makes each equation in the system true when the values $s_1, s_2, ..., s_n$ are substituted for $x_1, x_2, ..., x_n$, respectively.

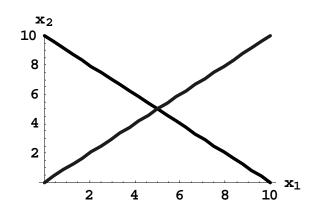
EXAMPLE Two equations in two variables:

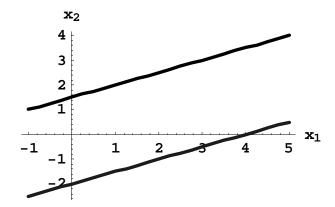
$$x_1 + x_2 = 10$$

$$-x_1 + x_2 = 0$$

$$x_1 - 2x_2 = -3$$

$$2x_1 - 4x_2 = 8$$



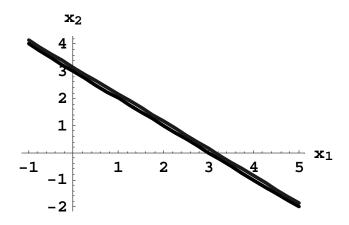


one unique solution

no solution

$$x_1 + x_2 = 3$$

 $-2x_1 - 2x_2 = -6$



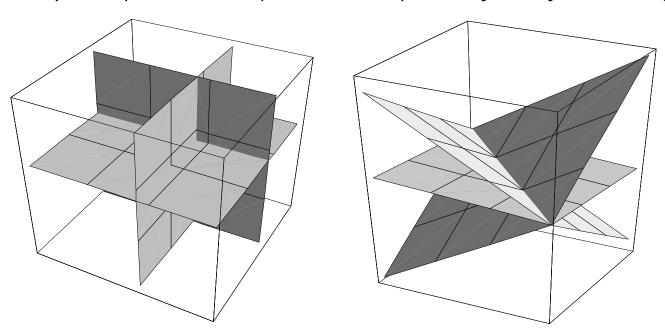
infinitely many solutions

BASIC FACT: A system of linear equations has either

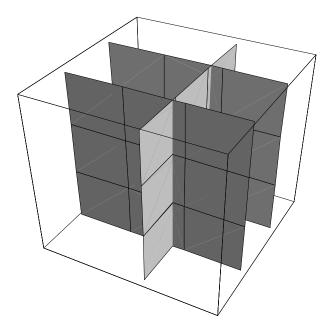
- (i) exactly one solution (consistent) or
- (ii) infinitely many solutions (consistent) or
- (iii) no solution (inconsistent).

EXAMPLE: Three equations in three variables. Each equation determines a plane in 3-space.

- i) The planes intersect in one point. *(one solution)*
- ii) The planes intersect in one line. (infinitely many solutions)



iii) There is not point in common to all three planes. (no solution)



The solution set:

The set of all possible solutions of a linear system.

Equivalent systems:

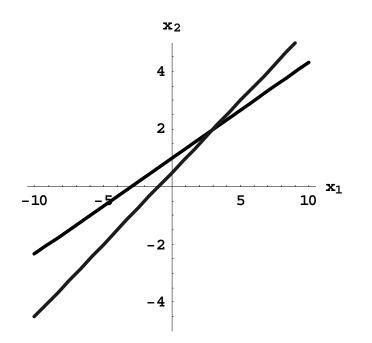
Two linear systems with the same solution set.

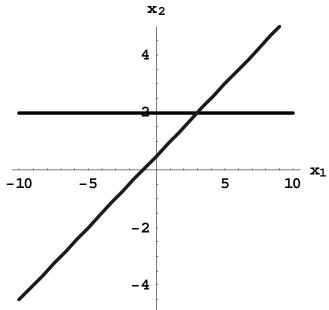
STRATEGY FOR SOLVING A SYSTEM:

 Replace one system with an equivalent system that is easier to solve.

EXAMPLE:

$$x_1 - 2x_2 = -1$$
 $-x_1 + 3x_2 = 3$
 $x_1 - 2x_2 = -1$
 $x_2 = 2$
 $x_1 = 3$
 $x_2 = 2$

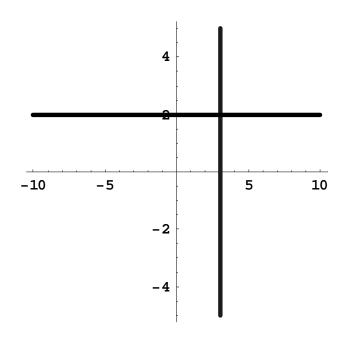




$$x_1 - 2x_2 = -1$$

 $-x_1 + 3x_2 = 3$

$$x_1 - 2x_2 = -1$$
$$x_2 = 2$$



$$x_1 = 3$$

$$x_2 = 2$$

Matrix Notation

$$x_1 - 2x_2 = -1$$
 $-x_1 + 3x_2 = 3$

$$\begin{bmatrix} 1 & -2 \\ -1 & 3 \end{bmatrix}$$
(coefficient matrix)

$$x_1 - 2x_2 = -1$$
 $-x_1 + 3x_2 = 3$

$$\begin{bmatrix} 1 & -2 & -1 \\ -1 & 3 & 3 \end{bmatrix}$$
(augmented matrix)

$$x_1 = 3 \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \end{bmatrix}$$

Elementary Row Operations:

- 1. (Replacement) Add one row to a multiple of another row.
- 2. (Interchange) Interchange two rows.
- 3. (Scaling) Multiply all entries in a row by a nonzero constant.

Row equivalent matrices: Two matrices where one matrix can be transformed into the other matrix by a sequence of elementary row operations.

Fact about Row Equivalence: If the augmented matrices of two linear systems are row equivalent, then the two systems have the same solution set.

EXAMPLE:

$$x_1 - 2x_2 + x_3 = 0$$

$$2x_2 - 8x_3 = 8$$

$$-4x_1 + 5x_2 + 9x_3 = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix}$$

$$x_1 - 2x_2 + x_3 = 0 - 2x_2 - 8x_3 = 8 - 3x_2 + 13x_3 = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$

$$x_1 - 2x_2 + x_3 = 0$$

$$x_2 - 4x_3 = 4$$

$$- 3x_2 + 13x_3 = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$

$$x_1 - 2x_2 + x_3 = 0$$

$$x_2 - 4x_3 = 4$$

$$x_3 = 3$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

Solution: (29, 16, 3)

Check: Is (29, 16, 3) a solution of the *original* system?

$$x_1 - 2x_2 + x_3 = 0$$

$$2x_2 - 8x_3 = 8$$

$$-4x_1 + 5x_2 + 9x_3 = -9$$

$$(29) - 2(16) + 3 = 29 - 32 + 3 = 0$$

 $2(16) - 8(3) = 32 - 24 = 8$
 $-4(29) + 5(16) + 9(3) = -116 + 80 + 27 = -9$

Two Fundamental Questions (Existence and Uniqueness)

- 1) Is the system consistent; (i.e. does a solution **exist**?)
- 2) If a solution exists, is it **unique**? (i.e. is there one & only one solution?)

EXAMPLE: Is this system consistent?

$$x_1 - 2x_2 + x_3 = 0$$

$$2x_2 - 8x_3 = 8$$

$$-4x_1 + 5x_2 + 9x_3 = -9$$

In the last example, this system was reduced to the triangular form:

$$x_1 - 2x_2 + x_3 = 0 x_2 - 4x_3 = 4 x_3 = 3$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

This is sufficient to see that the system is consistent and unique. Why?

EXAMPLE: Is this system consistent?

$$3x_{2} - 6x_{3} = 8$$

$$x_{1} - 2x_{2} + 3x_{3} = -1$$

$$5x_{1} - 7x_{2} + 9x_{3} = 0$$

$$\begin{bmatrix}
0 & 3 & -6 & 8 \\
1 & -2 & 3 & -1 \\
5 & -7 & 9 & 0
\end{bmatrix}$$

Solution: Row operations produce:

$$\begin{bmatrix} 0 & 3 & -6 & 8 \\ 1 & -2 & 3 & -1 \\ 5 & -7 & 9 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 3 & -1 \\ 0 & 3 & -6 & 8 \\ 0 & 3 & -6 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 3 & -1 \\ 0 & 3 & -6 & 8 \\ 0 & 0 & 0 & -3 \end{bmatrix}$$

Equation notation of triangular form:

$$x_1 - 2x_2 + 3x_3 = -1$$

 $3x_2 - 6x_3 = 8$
 $0x_3 = -3 \leftarrow Never true$

The original system is inconsistent!

EXAMPLE: For what values of h will the following system be consistent?

$$3x_1 - 9x_2 = 4$$
$$-2x_1 + 6x_2 = h$$

Solution: Reduce to triangular form.

$$\begin{bmatrix} 3 & -9 & 4 \\ -2 & 6 & h \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & \frac{4}{3} \\ -2 & 6 & h \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & \frac{4}{3} \\ 0 & 0 & h + \frac{8}{3} \end{bmatrix}$$

The second equation is $0x_1 + 0x_2 = h + \frac{8}{3}$. System is consistent only if $h + \frac{8}{3} = 0$ or $h = \frac{-8}{3}$.