NLDL

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1) a)

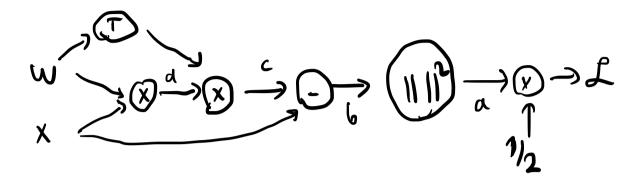
We project vector X using W linear transformation, and in order to reconstruct projected vector, we need to multiply the projected vector WX with WT. Then, reconstructed vector is WTWX=y. Projecting to lower dimension reduces the information of the vector . 50, we try to minimize the information lost by using the loss function. At the end of training, we get w such that it preserves the information and projects data into a lower dimension.

y= w w x -> reconstructed vertor

minimine \frac{1}{2} || y - x ||^2, tries to make y look like x as

Possible as not encoded in the first place

6)
$$J = \frac{1}{2} || w^T w \times - x ||^2$$



$$\omega \rightarrow 0$$

$$\frac{\partial J}{\partial w} = \frac{\partial P_1}{\partial w} \frac{\partial L}{\partial P_1} + \frac{\partial P_2}{\partial w} \frac{\partial L}{\partial P_2}$$

We need to sum derivatives caming from each path to find total derivative.

$$\frac{d}{1} \qquad \mathcal{J} = \frac{\alpha}{2} \implies \frac{\partial \mathcal{J}}{\partial \alpha} = \frac{1}{2}$$

1)
$$a = b^Tb = \frac{\partial a}{\partial b} = 2b = \frac{\partial a}{\partial b} \cdot \frac{\partial b}{\partial a} = \frac{2b}{2} = 6$$

3)
$$b = c - x = \frac{\partial b}{\partial c} = I = \frac{\partial b}{\partial c} \frac{\partial f}{\partial b} = I \cdot b = b$$

4)
$$C = W^{T}d = \frac{\partial C}{\partial d} = W = \frac{\partial C}{\partial d} = \frac{\partial C}{\partial c} = W6$$

5)
$$C = u^T d \Rightarrow \frac{\partial C}{\partial u^T} = d^T = \lambda \frac{\partial C}{\partial u^T} \frac{\partial L}{\partial C} = b d^T$$

6)
$$d = w \times \Rightarrow \frac{\partial d}{\partial w} = x^{T} \Rightarrow \frac{\partial d}{\partial w} \frac{\partial d}{\partial d} = wbx^{T}$$

$$\nabla_{\omega} \mathcal{I} = 5^{T} + b = \left(\frac{\partial \mathcal{L}}{\partial \omega T}\right)^{T} + \frac{\partial \mathcal{Z}}{\partial \omega} = db^{T} + wbn^{T}$$

2)
$$K = \chi \chi \chi^{T} + \beta^{-1} I$$

$$J = -c - \frac{D}{2} |_{og} |_{K1} - \frac{1}{2} |_{Y} CK^{-1} \gamma \gamma^{T})$$
Note, $K^{T} = K$, $K^{-1} = K^{-T}$

$$J_1 = -\frac{0}{7} \log |K|$$

$$I_2 = -\frac{1}{2} \operatorname{tr} \left(K^{-1} 77^{7} \right)$$

$$\frac{\partial \mathcal{L}}{\partial \alpha} = -\frac{D}{2}$$

$$\frac{\partial \alpha}{\partial K} = K^{-T} \Rightarrow \frac{\partial \alpha}{\partial K} \frac{\partial S_1}{\partial \alpha} = -\frac{D}{2} K^{-T}$$

$$K = c + F'I = \frac{\partial K}{\partial k} = I = \frac{\partial K}{\partial c} \frac{\partial d}{\partial K} = \frac{-D}{2} k^{-T}$$

$$c = \alpha d \Rightarrow \frac{\partial c}{\partial d} = \alpha I = s \frac{\partial c}{\partial d} \frac{\partial f_1}{\partial c} = -\alpha \frac{D}{2} K^{-T}$$

$$d = XX^T = Xf$$

$$\frac{\partial \mathcal{I}_{1}}{\partial \mathcal{R}} = \frac{\partial \mathcal{I}_{2}}{\partial \mathcal{I}_{1}} \left(\chi^{T} \right)^{T} = -d \frac{D}{2} k^{-T} \mathcal{R}_{2}$$

$$\frac{1}{3}\frac{1}{3}\frac{1}{3} = x^{T}\frac{1}{3}\frac{1}{3} = x^{T}(-\alpha \frac{1}{2}x^{-T})$$

$$\frac{\partial J_{1}}{\partial X} = -\lambda \frac{D}{2} \mathcal{L}^{-1} X + \left(\frac{\partial \mathcal{L}_{1}}{\partial X^{T}}\right)^{T}$$

$$= -\lambda \frac{D}{2} \left(\mathcal{L}^{-1} X + \mathcal{L}^{-1} X\right)$$

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$$= -\lambda \frac{D}{2} \left(\mathcal{L$$

$$\frac{\partial \mathcal{L}_{2}}{\partial \mathcal{K}} = -\mathcal{K}^{T} \frac{\partial \mathcal{L}_{2}}{\partial \mathcal{K}^{-1}} \mathcal{K}^{-T}$$

$$\frac{\partial \mathcal{L}_{1}}{\partial a} = -\frac{1}{2} \qquad \frac{\partial b}{\partial c} = \gamma \gamma^{T}$$

$$\frac{\partial a}{\partial b} = \mathbf{I}$$

$$\frac{\partial dz}{\partial K''} = \frac{\partial b}{\partial K''} \frac{\partial a}{\partial b} \frac{\partial dz}{\partial a} = -\frac{1}{2} y y^T$$

$$\frac{\partial f_2}{\partial K} = \frac{1}{2} K^{-T} \gamma \gamma^T K^{-T}$$

$$\frac{\partial K}{\partial d} = I = \frac{\partial K}{\partial d} = \frac{1}{2} K^{-T} \gamma \gamma^{T} K^{-T}$$

d- re

$$\frac{\partial f_1}{\partial d} = \frac{1}{2} \chi \chi^{-1} \gamma \gamma^{T} \chi^{-T} = \chi \frac{\partial f_2}{\partial \chi}$$

$$e = XX$$

$$\frac{\partial d_1}{\partial X} = \frac{\partial d_2}{\partial e} X = \frac{\partial d_2}{\partial K} X$$

$$\frac{\partial d_1}{\partial X} = \frac{\partial d_2}{\partial E} X = \frac{\partial d_2}{\partial K} X$$

$$\frac{\partial d_1}{\partial x^T} = \lambda x^T \frac{\partial d_1}{\partial K}$$

$$\frac{\partial J_{L}}{\partial x} = \frac{d}{2} \kappa^{-1} \gamma \gamma^{T} k^{-T} X + \frac{d}{2} \kappa^{-1} \gamma \gamma^{T} k^{-1} X$$

$$= \left(\frac{d}{d} \kappa^{-1} \nabla^{7} \nabla^{T} \kappa^{-1} X \right) \left(\frac{d}{d} \kappa^{-1} \nabla^{7} \kappa^{-1} X \right)$$

$$= \sum_{k=1}^{\infty} \left(\frac{d}{d} \kappa^{-1} \nabla^{7} \nabla^{7} \kappa^{-1} X \right)$$

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Derivative of swish:

$$y = swish(x)$$
 $y = x 6Cx$)

 $y' = 6(x) + 6'(x) x$
 $= 6(x) + 6(x) (1 - 6(x)) x$
 $= 6(x) (1 + x - 6(x) x)$
 $= 6(x) + 6(x) x - 6(x) 6(x) x$
 $= 6(x) + 6(x) x - 6(x) swish$
 $= 6(x) + swish - 6(x) swish$
 $= swish(x) + 6(x) (1 - swish(x))$

$$\frac{\partial \mathcal{L}}{\partial \lambda} = \frac{\partial \mathcal{L}}{\partial z_2} + \sin \alpha$$

$$\frac{\partial \mathcal{L}}{\partial \lambda} = \frac{\partial \mathcal{L}}{\partial z_2}$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \alpha}{\partial w_2} \frac{\partial \mathcal{L}}{\partial \alpha} = \frac{\partial \mathcal{L}}{\partial \alpha} w_1^{\mathsf{T}} = \frac{\partial \mathcal{L}}{\partial z_2} w_1^{\mathsf{T}}$$

$$\frac{\partial \mathcal{L}}{\partial h_1} = \frac{\partial \alpha}{\partial h_1} \frac{\partial \mathcal{L}}{\partial \alpha} = W_2^T \frac{\partial \mathcal{L}}{\partial z_2}$$

$$\frac{\partial \mathcal{L}}{\partial z_1} = \frac{\partial h_1}{\partial z_1} \frac{\partial \mathcal{L}}{\partial h_1}$$

$$\int Swish(z_i) = Sw(z_i)$$

$$\frac{\partial h_i}{\partial z_i} = Sw(z_i) + \delta(z_i) \odot (1-sw(z_i))$$

$$\frac{\partial \mathcal{L}}{\partial z_1} = (SW(z_1) + S(z_1) \odot (1-SW(z_1))) \psi_1^{\dagger} \frac{\partial \mathcal{L}}{\partial z_1}$$

$$\frac{\partial \mathcal{L}}{\partial b_1} = \left(sw(z_1) + 6(z_1)O(1 - sw(z_1))\right) O\left(w_2^{\dagger} \frac{\partial \mathcal{L}}{\partial z_2}\right)$$

$$\frac{3c}{3\zeta} = \frac{361}{361}$$

$$\frac{\partial \mathcal{L}}{\partial w_{1}} = \frac{\partial \mathcal{L}}{\partial b_{1}} x^{T}$$