FC nets

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# 1 Fully connected networks

In the previous notebook, you implemented a simple two-layer neural network class. However, this class is not modular. If you wanted to change the number of layers, you would need to write a new loss and gradient function. If you wanted to optimize the network with different optimizers, you'd need to write new training functions. If you wanted to incorporate regularizations, you'd have to modify the loss and gradient function.

Instead of having to modify functions each time, for the rest of the class, we'll work in a more modular framework where we define forward and backward layers that calculate losses and gradients respectively. Since the forward and backward layers share intermediate values that are useful for calculating both the loss and the gradient, we'll also have these function return "caches" which store useful intermediate values.

The goal is that through this modular design, we can build different sized neural networks for various applications.

In this HW #3, we'll define the basic architecture, and in HW #4, we'll build on this framework to implement different optimizers and regularizations (like BatchNorm and Dropout).

# 1.1 Modular layers

This notebook will build modular layers in the following manner. First, there will be a forward pass for a given layer with inputs (x) and return the output of that layer (out) as well as cached variables (cache) that will be used to calculate the gradient in the backward pass.

#### def layer forward(x, w):

```
""" Receive inputs x and weights w """
# Do some computations ...
z = # ... some intermediate value
# Do some more computations ...
out = # the output

cache = (x, w, z, out) # Values we need to compute gradients
return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
      Receive derivative of loss with respect to outputs and cache,
      and compute derivative with respect to inputs.
      11 11 11
      # Unpack cache values
      x, w, z, out = cache
      # Use values in cache to compute derivatives
      dx = # Derivative of loss with respect to x
      dw = # Derivative of loss with respect to w
      return dx, dw
[1]: ## Import and setups
     import time
     import numpy as np
     import matplotlib.pyplot as plt
     from nndl.fc_net import *
     from utils.data_utils import get_CIFAR10_data
     from utils.gradient_check import eval_numerical_gradient, u
      →eval_numerical_gradient_array
     from utils.solver import Solver
     %matplotlib inline
     plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
     plt.rcParams['image.interpolation'] = 'nearest'
     plt.rcParams['image.cmap'] = 'gray'
     # for auto-reloading external modules
     # see http://stackoverflow.com/questions/1907993/
      \rightarrow autoreload-of-modules-in-ipython
     %load ext autoreload
     %autoreload 2
     def rel_error(x, y):
       """ returns relative error """
       return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
[2]: # Load the (preprocessed) CIFAR10 data.
     data = get_CIFAR10_data()
     for k in data.keys():
       print('{}: {} '.format(k, data[k].shape))
    X_train: (49000, 3, 32, 32)
    y_train: (49000,)
    X_val: (1000, 3, 32, 32)
```

```
y_val: (1000,)
X_test: (1000, 3, 32, 32)
y_test: (1000,)
```

### 1.2 Linear layers

In this section, we'll implement the forward and backward pass for the linear layers.

The linear layer forward pass is the function affine\_forward in nndl/layers.py and the backward pass is affine\_backward.

After you have implemented these, test your implementation by running the cell below.

### 1.2.1 Affine layer forward pass

Implement affine forward and then test your code by running the following cell.

```
[3]: # Test the affine forward function
     num_inputs = 2
     input\_shape = (4, 5, 6)
     output_dim = 3
     input_size = num_inputs * np.prod(input_shape)
     weight_size = output_dim * np.prod(input_shape)
     x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape)
     w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape),_
      →output_dim)
     b = np.linspace(-0.3, 0.1, num=output_dim)
     out, _ = affine_forward(x, w, b)
     correct_out = np.array([[ 1.49834967, 1.70660132, 1.91485297],
                             [ 3.25553199, 3.5141327, 3.77273342]])
     # Compare your output with ours. The error should be around 1e-9.
     print('Testing affine forward function:')
     print('difference: {}'.format(rel_error(out, correct_out)))
```

Testing affine\_forward function: difference: 9.76984888397517e-10

### 1.2.2 Affine layer backward pass

Implement affine\_backward and then test your code by running the following cell.

```
[4]: # Test the affine_backward function

x = np.random.randn(10, 2, 3)
w = np.random.randn(6, 5)
```

Testing affine\_backward function:

dx error: 5.188780577152063e-10 dw error: 5.302565153628167e-10 db error: 5.914019455721815e-11

# 1.3 Activation layers

In this section you'll implement the ReLU activation.

#### 1.3.1 ReLU forward pass

Implement the relu\_forward function in nndl/layers.py and then test your code by running the following cell.

```
[5]: # Test the relu_forward function
    x = np.linspace(-0.5, 0.5, num=12).reshape(3, 4)
    out, _ = relu_forward(x)
    correct_out = np.array([[ 0.,
                                           0.,
                                                                    0.,
                                                        0.,
                                                                                ],
                             [ 0.,
                                                        0.04545455, 0.13636364,],
                                           0.,
                             [ 0.22727273, 0.31818182, 0.40909091, 0.5,
                                                                                ]])
    # Compare your output with ours. The error should be around 1e-8
    print('Testing relu_forward function:')
    print('difference: {}'.format(rel_error(out, correct_out)))
```

Testing relu\_forward function: difference: 4.999999798022158e-08

### 1.3.2 ReLU backward pass

Implement the relu\_backward function in nndl/layers.py and then test your code by running the following cell.

```
[6]: x = np.random.randn(10, 10)
dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

_, cache = relu_forward(x)
dx = relu_backward(dout, cache)

# The error should be around 1e-12
print('Testing relu_backward function:')
print('dx error: {}'.format(rel_error(dx_num, dx)))
```

Testing relu\_backward function: dx error: 3.2756308201641777e-12

### 1.4 Combining the affine and ReLU layers

Often times, an affine layer will be followed by a ReLU layer. So let's make one that puts them together. Layers that are combined are stored in nndl/layer\_utils.py.

### 1.4.1 Affine-ReLU layers

We've implemented affine\_relu\_forward() and affine\_relu\_backward in nndl/layer\_utils.py. Take a look at them to make sure you understand what's going on. Then run the following cell to ensure its implemented correctly.

```
[7]: from nndl.layer_utils import affine_relu_forward, affine_relu_backward

x = np.random.randn(2, 3, 4)
w = np.random.randn(12, 10)
b = np.random.randn(10)
dout = np.random.randn(2, 10)

out, cache = affine_relu_forward(x, w, b)
dx, dw, db = affine_relu_backward(dout, cache)

dx_num = eval_numerical_gradient_array(lambda x: affine_relu_forward(x, w,u,b)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: affine_relu_forward(x, w,u,b)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w,u,b)[0], b, dout)

print('Testing affine_relu_forward and affine_relu_backward:')
```

```
print('dx error: {}'.format(rel_error(dx_num, dx)))
print('dw error: {}'.format(rel_error(dw_num, dw)))
print('db error: {}'.format(rel_error(db_num, db)))
```

Testing affine\_relu\_forward and affine\_relu\_backward:

dx error: 3.5380055980550577e-10
dw error: 1.7032374818634383e-09
db error: 2.6316567501740803e-11

#### 1.5 Softmax loss

You've already implemented it, so we have written it in layers.py. The following code will ensure they are working correctly.

Testing softmax\_loss: loss: 2.3023774616675117 dx error: 8.176700987976612e-09

### 1.6 Implementation of a two-layer NN

In nndl/fc\_net.py, implement the class TwoLayerNet which uses the layers you made here. When you have finished, the following cell will test your implementation.

```
[9]: N, D, H, C = 3, 5, 50, 7
X = np.random.randn(N, D)
y = np.random.randint(C, size=N)

std = 1e-2
model = TwoLayerNet(input_dim=D, hidden_dims=H, num_classes=C, weight_scale=std)

print('Testing initialization ... ')
W1_std = abs(model.params['W1'].std() - std)
b1 = model.params['b1']
```

```
W2_std = abs(model.params['W2'].std() - std)
b2 = model.params['b2']
assert W1_std < std / 10, 'First layer weights do not seem right'
assert np.all(b1 == 0), 'First layer biases do not seem right'
assert W2_std < std / 10, 'Second layer weights do not seem right'
assert np.all(b2 == 0), 'Second layer biases do not seem right'
print('Testing test-time forward pass ... ')
model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct_scores = np.asarray(
  [[11.53165108, 12.2917344, 13.05181771, 13.81190102, 14.57198434, 15.
 →33206765, 16.09215096],
   [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128, 15.
 →49994135, 16.18839143],
   [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822, 15.
 →66781506, 16.2846319 ]])
scores_diff = np.abs(scores - correct_scores).sum()
assert scores_diff < 1e-6, 'Problem with test-time forward pass'</pre>
print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct_loss = 3.4702243556
assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time loss'
model.reg = 1.0
loss, grads = model.loss(X, y)
correct_loss = 26.5948426952
assert abs(loss - correct_loss) < 1e-10, 'Problem with regularization loss'
for reg in [0.0, 0.7]:
 print('Running numeric gradient check with reg = {}'.format(reg))
 model.reg = reg
 loss, grads = model.loss(X, y)
 for name in sorted(grads):
   f = lambda _: model.loss(X, y)[0]
   grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)
   print('{} relative error: {}'.format(name, rel_error(grad_num,__
 ⇒grads[name])))
```

```
Testing initialization ...
Testing test-time forward pass ...
Testing training loss (no regularization)
Running numeric gradient check with reg = 0.0
W1 relative error: 1.833656129733658e-08
W2 relative error: 3.3727467137085415e-10
b1 relative error: 8.008665519199494e-09
b2 relative error: 2.5307826250578787e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.527915286171985e-07
W2 relative error: 2.8508510893102143e-08
b1 relative error: 1.3467618820476118e-08
b2 relative error: 1.968057921260679e-09
```

### 1.7 Solver

We will now use the utils Solver class to train these networks. Familiarize yourself with the API in utils/solver.py. After you have done so, declare an instance of a TwoLayerNet with 200 units and then train it with the Solver. Choose parameters so that your validation accuracy is at least 50%.

```
[10]: model = TwoLayerNet()
    solver = None
    # YOUR CODE HERE:
       Declare an instance of a TwoLayerNet and then train
      it with the Solver. Choose hyperparameters so that your validation
      accuracy is at least 50%. We won't have you optimize this further
       since you did it in the previous notebook.
    # ------ #
    model = TwoLayerNet(hidden_dims = 200, reg = 0.25)
    solver = Solver(model, data,
                print_every=1000, num_epochs=10, batch_size=100,
                update rule='sgd',
                lr_decay = 0.9,
                 optim_config={
                  'learning_rate': 1e-3,
                 })
    solver.train()
    # ----- #
    # END YOUR CODE HERE
    # ----- #
```

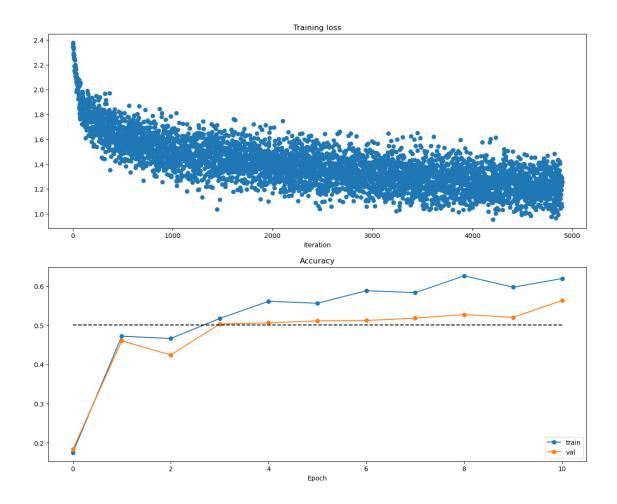
(Iteration 1 / 4900) loss: 2.377735 (Epoch 0 / 10) train acc: 0.175000; val\_acc: 0.183000

```
(Epoch 1 / 10) train acc: 0.472000; val_acc: 0.460000
(Epoch 2 / 10) train acc: 0.466000; val_acc: 0.424000
(Iteration 1001 / 4900) loss: 1.565635
(Epoch 3 / 10) train acc: 0.517000; val_acc: 0.503000
(Epoch 4 / 10) train acc: 0.561000; val_acc: 0.506000
(Iteration 2001 / 4900) loss: 1.418426
(Epoch 5 / 10) train acc: 0.556000; val_acc: 0.511000
(Epoch 6 / 10) train acc: 0.588000; val_acc: 0.512000
(Iteration 3001 / 4900) loss: 1.126180
(Epoch 7 / 10) train acc: 0.583000; val_acc: 0.518000
(Epoch 8 / 10) train acc: 0.626000; val_acc: 0.527000
(Iteration 4001 / 4900) loss: 1.310355
(Epoch 9 / 10) train acc: 0.597000; val_acc: 0.520000
(Epoch 10 / 10) train acc: 0.619000; val_acc: 0.563000
```

```
[11]: # Run this cell to visualize training loss and train / val accuracy

plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss_history, 'o')
plt.xlabel('Iteration')

plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train_acc_history, '-o', label='train')
plt.plot(solver.val_acc_history, '-o', label='val')
plt.plot([0.5] * len(solver.val_acc_history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set_size_inches(15, 12)
plt.show()
```



## 1.8 Multilayer Neural Network

Now, we implement a multi-layer neural network.

Read through the FullyConnectedNet class in the file nndl/fc\_net.py.

Implement the initialization, the forward pass, and the backward pass. There will be lines for batchnorm and dropout layers and caches; ignore these all for now. That'll be in HW #4.

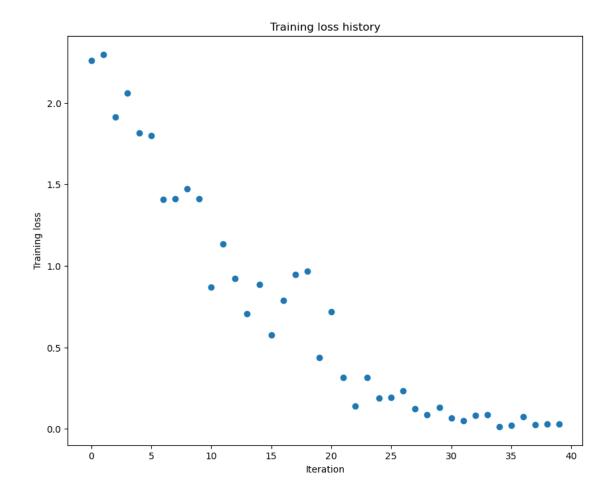
```
for name in sorted(grads):
              f = lambda _: model.loss(X, y)[0]
              grad_num = eval_numerical_gradient(f, model.params[name],__
       →verbose=False, h=1e-5)
              print('{} relative error: {}'.format(name, rel error(grad num, | ))
       ⇒grads[name])))
     Running check with reg = 0
     Initial loss: 2.3108671690350207
     W1 relative error: 2.8315456899923375e-07
     W2 relative error: 0.001684289359416663
     W3 relative error: 2.716426959871108e-08
     b1 relative error: 3.19010957223319e-06
     b2 relative error: 5.640601172063617e-07
     b3 relative error: 7.534315355290147e-11
     Running check with reg = 3.14
     Initial loss: 6.846772499866336
     W1 relative error: 3.684629955124396e-08
     W2 relative error: 2.139127401336952e-08
     W3 relative error: 3.4031092093698525e-08
     b1 relative error: 1.541039165717124e-08
     b2 relative error: 1.0872372718805577e-08
     b3 relative error: 1.793099179966473e-10
[14]: # Use the three layer neural network to overfit a small dataset.
      num_train = 50
      small data = {
        'X_train': data['X_train'][:num_train],
        'y_train': data['y_train'][:num_train],
        'X val': data['X val'],
        'y_val': data['y_val'],
      #### !!!!!!
      # Play around with the weight scale and learning rate so that you can overfit and
       \hookrightarrowsmall dataset.
      # Your training accuracy should be 1.0 to receive full credit on this part.
      weight_scale = 1e-2
      learning_rate = 1e-2 #Changed this to overfit
      model = FullyConnectedNet([100, 100],
                    weight_scale=weight_scale, dtype=np.float64)
      solver = Solver(model, small_data,
```

```
print_every=10, num_epochs=20, batch_size=25,
                update_rule='sgd',
                optim_config={
                   'learning_rate': learning_rate,
solver.train()
plt.plot(solver.loss history, 'o')
plt.title('Training loss history')
plt.xlabel('Iteration')
plt.ylabel('Training loss')
plt.show()
(Iteration 1 / 40) loss: 2.260469
(Epoch 0 / 20) train acc: 0.120000; val_acc: 0.106000
(Epoch 1 / 20) train acc: 0.180000; val acc: 0.129000
(Epoch 2 / 20) train acc: 0.460000; val_acc: 0.141000
(Epoch 3 / 20) train acc: 0.520000; val acc: 0.171000
(Epoch 4 / 20) train acc: 0.560000; val_acc: 0.160000
(Epoch 5 / 20) train acc: 0.620000; val_acc: 0.177000
(Iteration 11 / 40) loss: 0.869075
(Epoch 6 / 20) train acc: 0.720000; val acc: 0.172000
(Epoch 7 / 20) train acc: 0.760000; val_acc: 0.165000
(Epoch 8 / 20) train acc: 0.820000; val acc: 0.218000
(Epoch 9 / 20) train acc: 0.660000; val_acc: 0.146000
(Epoch 10 / 20) train acc: 0.760000; val acc: 0.205000
(Iteration 21 / 40) loss: 0.719245
(Epoch 11 / 20) train acc: 0.960000; val_acc: 0.196000
(Epoch 12 / 20) train acc: 0.960000; val_acc: 0.206000
(Epoch 13 / 20) train acc: 0.960000; val_acc: 0.184000
```

(Epoch 14 / 20) train acc: 0.980000; val\_acc: 0.182000 (Epoch 15 / 20) train acc: 1.000000; val\_acc: 0.177000

(Epoch 16 / 20) train acc: 1.000000; val\_acc: 0.185000 (Epoch 17 / 20) train acc: 1.000000; val\_acc: 0.187000 (Epoch 18 / 20) train acc: 1.000000; val\_acc: 0.187000 (Epoch 19 / 20) train acc: 1.000000; val\_acc: 0.201000 (Epoch 20 / 20) train acc: 1.000000; val\_acc: 0.198000

(Iteration 31 / 40) loss: 0.066636



[]: