Batch-Normalization

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1 Batch Normalization

In this notebook, you will implement the batch normalization layers of a neural network to increase its performance. Please review the details of batch normalization from the lecture notes.

Utils has a solid API for building these modular frameworks and training them, and we will use this very well implemented framework as opposed to "reinventing the wheel." This includes using the Solver, various utility functions, and the layer structure. This also includes nndl.fc_net, nndl.layers, and nndl.layer_utils.

```
[1]: ## Import and setups
     import time
     import numpy as np
     import matplotlib.pyplot as plt
     from nndl.fc_net import *
     from nndl.layers import *
     from utils.data_utils import get_CIFAR10_data
     from utils.gradient_check import eval_numerical_gradient,_
      ⇔eval_numerical_gradient_array
     from utils.solver import Solver
     %matplotlib inline
     plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
     plt.rcParams['image.interpolation'] = 'nearest'
     plt.rcParams['image.cmap'] = 'gray'
     # for auto-reloading external modules
     # see http://stackoverflow.com/questions/1907993/
      \Rightarrow autoreload-of-modules-in-ipython
     %load ext autoreload
     %autoreload 2
     def rel_error(x, y):
         """ returns relative error """
         return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

```
[2]: # Load the (preprocessed) CIFAR10 data.

data = get_CIFAR10_data()
for k in data.keys():
    print('{}: {} '.format(k, data[k].shape))

X_train: (49000, 3, 32, 32)
y_train: (49000,)
X_val: (1000, 3, 32, 32)
y_val: (1000,)
X_test: (1000, 3, 32, 32)
y_test: (1000,)
```

1.1 Batchnorm forward pass

Implement the training time batchnorm forward pass, batchnorm_forward, in nndl/layers.py. After that, test your implementation by running the following cell.

```
[3]: # Check the training-time forward pass by checking means and variances
     # of features both before and after batch normalization
     # Simulate the forward pass for a two-layer network
     N, D1, D2, D3 = 200, 50, 60, 3
     X = np.random.randn(N, D1)
     W1 = np.random.randn(D1, D2)
     W2 = np.random.randn(D2, D3)
     a = np.maximum(0, X.dot(W1)).dot(W2)
     print('Before batch normalization:')
     print(' means: ', a.mean(axis=0))
     print(' stds: ', a.std(axis=0))
     # Means should be close to zero and stds close to one
     print('After batch normalization (gamma=1, beta=0)')
     a norm, = batchnorm forward(a, np.ones(D3), np.zeros(D3), {'mode': 'train'})
     print(' mean: ', a_norm.mean(axis=0))
     print(' std: ', a_norm.std(axis=0))
     # Now means should be close to beta and stds close to gamma
     gamma = np.asarray([1.0, 2.0, 3.0])
     beta = np.asarray([11.0, 12.0, 13.0])
     a_norm, _ = batchnorm_forward(a, gamma, beta, {'mode': 'train'})
     print('After batch normalization (nontrivial gamma, beta)')
     print(' means: ', a_norm.mean(axis=0))
     print(' stds: ', a_norm.std(axis=0))
```

Before batch normalization:

```
means: [-10.00457198 16.04505515 19.23080314] stds: [37.41826382 31.96563484 36.48977956]
```

```
After batch normalization (gamma=1, beta=0)
mean: [-1.60982339e-17 3.61100039e-16 4.03010958e-16]
std: [1. 1. 1.]

After batch normalization (nontrivial gamma, beta)
means: [11. 12. 13.]
stds: [1. 1.99999999 2.99999999]
```

Implement the testing time batchnorm forward pass, batchnorm_forward, in nndl/layers.py. After that, test your implementation by running the following cell.

```
[4]: # Check the test-time forward pass by running the training-time
     # forward pass many times to warm up the running averages, and then
     # checking the means and variances of activations after a test-time
     # forward pass.
     N, D1, D2, D3 = 200, 50, 60, 3
     W1 = np.random.randn(D1, D2)
     W2 = np.random.randn(D2, D3)
     bn_param = {'mode': 'train'}
     gamma = np.ones(D3)
     beta = np.zeros(D3)
     for t in np.arange(50):
         X = np.random.randn(N, D1)
         a = np.maximum(0, X.dot(W1)).dot(W2)
         batchnorm_forward(a, gamma, beta, bn_param)
     bn param['mode'] = 'test'
     X = np.random.randn(N, D1)
     a = np.maximum(0, X.dot(W1)).dot(W2)
     a_norm, _ = batchnorm_forward(a, gamma, beta, bn_param)
     # Means should be close to zero and stds close to one, but will be
     # noisier than training-time forward passes.
     print('After batch normalization (test-time):')
     print(' means: ', a_norm.mean(axis=0))
     print(' stds: ', a_norm.std(axis=0))
```

After batch normalization (test-time): means: [-0.07583125 -0.08963107 -0.09446156]

stds: [0.94402115 0.96717243 1.05437211]

1.2 Batchnorm backward pass

Implement the backward pass for the batchnorm layer, batchnorm_backward in nndl/layers.py. Check your implementation by running the following cell.

```
[5]: # Gradient check batchnorm backward pass

N, D = 4, 5
```

```
x = 5 * np.random.randn(N, D) + 12
gamma = np.random.randn(D)
beta = np.random.randn(D)
dout = np.random.randn(N, D)
bn_param = {'mode': 'train'}
fx = lambda x: batchnorm_forward(x, gamma, beta, bn_param)[0]
fg = lambda gamma: batchnorm_forward(x, gamma, beta, bn_param)[0]
fb = lambda beta: batchnorm_forward(x, gamma, beta, bn_param)[0]
dx_num = eval_numerical_gradient_array(fx, x, dout)
da_num = eval_numerical_gradient_array(fg, gamma, dout)
db_num = eval_numerical_gradient_array(fb, beta, dout)
_, cache = batchnorm_forward(x, gamma, beta, bn_param)
dx, dgamma, dbeta = batchnorm_backward(dout, cache)
print('dx error: ', rel_error(dx_num, dx))
print('dgamma error: ', rel_error(da_num, dgamma))
print('dbeta error: ', rel_error(db_num, dbeta))
```

dx error: 1.0286924753847968e-08 dgamma error: 1.051318155351602e-11 dbeta error: 3.282273415383073e-12

1.3 Implement a fully connected neural network with batchnorm layers

Modify the FullyConnectedNet() class in nndl/fc_net.py to incorporate batchnorm layers. You will need to modify the class in the following areas:

- (1) The gammas and betas need to be initialized to 1's and 0's respectively in __init__.
- (2) The batchnorm_forward layer needs to be inserted between each affine and relu layer (except in the output layer) in a forward pass computation in loss. You may find it helpful to write an affine_batchnorm_relu() layer in nndl/layer_utils.py although this is not necessary.
- (3) The batchnorm_backward layer has to be appropriately inserted when calculating gradients.

After you have done the appropriate modifications, check your implementation by running the following cell.

Note, while the relative error for W3 should be small, as we backprop gradients more, you may find the relative error increases. Our relative error for W1 is on the order of 1e-4.

```
[6]: N, D, H1, H2, C = 2, 15, 20, 30, 10
X = np.random.randn(N, D)
y = np.random.randint(C, size=(N,))

for reg in [0, 3.14]:
    print('Running check with reg = ', reg)
    model = FullyConnectedNet([H1, H2], input_dim=D, num_classes=C,
```

```
reg=reg, weight_scale=5e-2, dtype=np.float64,
                               use_batchnorm=True)
    loss, grads = model.loss(X, y)
    print('Initial loss: ', loss)
    for name in sorted(grads):
        f = lambda _: model.loss(X, y)[0]
        grad_num = eval_numerical_gradient(f, model.params[name],_
  overbose=False, h=1e-5)
        print('{} relative error: {}'.format(name, rel_error(grad_num,_
  ⇒grads[name])))
    if reg == 0: print('\n')
Running check with reg = 0
Initial loss: 2.557708804606235
W1 relative error: 2.439478963329463e-05
W2 relative error: 3.36117016126612e-06
W3 relative error: 1.5816378924460456e-08
b1 relative error: 4.440892098500626e-08
b2 relative error: 4.440892098500626e-08
b3 relative error: 1.2203109853432995e-10
beta1 relative error: 5.576873117898441e-08
beta2 relative error: 3.6237143231206144e-09
gamma1 relative error: 5.3111037572313395e-08
gamma2 relative error: 1.0401735996362805e-08
Running check with reg = 3.14
Initial loss: 6.93961610307317
W1 relative error: 5.949456134759869e-06
W2 relative error: 0.00030555164665159657
W3 relative error: 8.816515307898475e-08
b1 relative error: 2.220446049250313e-08
b2 relative error: 2.886579864025407e-07
b3 relative error: 3.3990316943449e-10
beta1 relative error: 6.0586315013477285e-09
beta2 relative error: 5.185544391298469e-09
gamma1 relative error: 6.007944811542892e-09
gamma2 relative error: 7.777982374209474e-09
```

1.4 Training a deep fully connected network with batch normalization.

To see if batchnorm helps, let's train a deep neural network with and without batch normalization.

```
[7]: # Try training a very deep net with batchnorm hidden_dims = [100, 100, 100, 100]
```

```
num_train = 1000
small_data = {
    'X_train': data['X_train'][:num_train],
    'y_train': data['y_train'][:num_train],
    'X_val': data['X_val'],
    'y_val': data['y_val'],
}
weight scale = 2e-2
bn_model = FullyConnectedNet(hidden_dims, weight_scale=weight_scale,_

use batchnorm=True)

model = FullyConnectedNet(hidden_dims, weight_scale=weight_scale,_

use_batchnorm=False)

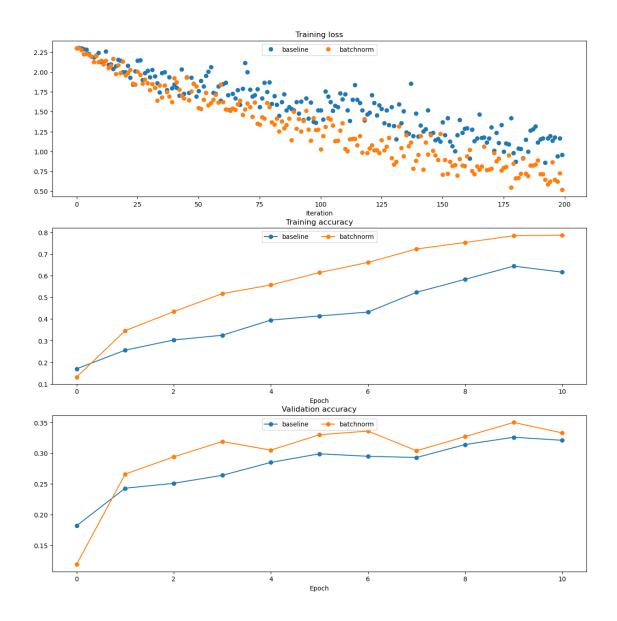
bn_solver = Solver(bn_model, small_data,
                num_epochs=10, batch_size=50,
                update_rule='adam',
                optim_config={
                  'learning_rate': 1e-3,
                },
                verbose=True, print_every=200)
bn_solver.train()
solver = Solver(model, small_data,
                num_epochs=10, batch_size=50,
                update_rule='adam',
                optim config={
                   'learning_rate': 1e-3,
                verbose=True, print_every=200)
solver.train()
(Iteration 1 / 200) loss: 2.300539
(Epoch 0 / 10) train acc: 0.132000; val_acc: 0.119000
(Epoch 1 / 10) train acc: 0.346000; val_acc: 0.266000
(Epoch 2 / 10) train acc: 0.434000; val_acc: 0.294000
(Epoch 3 / 10) train acc: 0.517000; val_acc: 0.319000
(Epoch 4 / 10) train acc: 0.557000; val_acc: 0.305000
(Epoch 5 / 10) train acc: 0.614000; val acc: 0.330000
(Epoch 6 / 10) train acc: 0.661000; val_acc: 0.336000
(Epoch 7 / 10) train acc: 0.723000; val_acc: 0.304000
(Epoch 8 / 10) train acc: 0.753000; val acc: 0.327000
(Epoch 9 / 10) train acc: 0.784000; val_acc: 0.350000
(Epoch 10 / 10) train acc: 0.787000; val acc: 0.333000
```

(Iteration 1 / 200) loss: 2.301798

(Epoch 0 / 10) train acc: 0.170000; val_acc: 0.182000 (Epoch 1 / 10) train acc: 0.256000; val_acc: 0.243000

```
(Epoch 2 / 10) train acc: 0.303000; val_acc: 0.251000 (Epoch 3 / 10) train acc: 0.325000; val_acc: 0.264000 (Epoch 4 / 10) train acc: 0.395000; val_acc: 0.285000 (Epoch 5 / 10) train acc: 0.414000; val_acc: 0.299000 (Epoch 6 / 10) train acc: 0.432000; val_acc: 0.295000 (Epoch 7 / 10) train acc: 0.523000; val_acc: 0.293000 (Epoch 8 / 10) train acc: 0.583000; val_acc: 0.314000 (Epoch 9 / 10) train acc: 0.644000; val_acc: 0.326000 (Epoch 10 / 10) train acc: 0.616000; val_acc: 0.321000
```

```
[8]: fig, axes = plt.subplots(3, 1)
     ax = axes[0]
     ax.set_title('Training loss')
     ax.set_xlabel('Iteration')
     ax = axes[1]
     ax.set_title('Training accuracy')
     ax.set_xlabel('Epoch')
     ax = axes[2]
     ax.set_title('Validation accuracy')
     ax.set_xlabel('Epoch')
     ax = axes[0]
     ax.plot(solver.loss history, 'o', label='baseline')
     ax.plot(bn_solver.loss_history, 'o', label='batchnorm')
     ax = axes[1]
     ax.plot(solver.train_acc_history, '-o', label='baseline')
     ax.plot(bn_solver.train_acc_history, '-o', label='batchnorm')
     ax = axes[2]
     ax.plot(solver.val_acc_history, '-o', label='baseline')
     ax.plot(bn_solver.val_acc_history, '-o', label='batchnorm')
     for i in [1, 2, 3]:
         ax = axes[i - 1]
         ax.legend(loc='upper center', ncol=4)
     plt.gcf().set_size_inches(15, 15)
     plt.show()
```



1.5 Batchnorm and initialization

The following cells run an experiment where for a deep network, the initialization is varied. We do training for when batchnorm layers are and are not included.

```
[9]: # Try training a very deep net with batchnorm
hidden_dims = [50, 50, 50, 50, 50, 50]

num_train = 1000
small_data = {
    'X_train': data['X_train'][:num_train],
    'y_train': data['y_train'][:num_train],
    'X_val': data['X_val'],
```

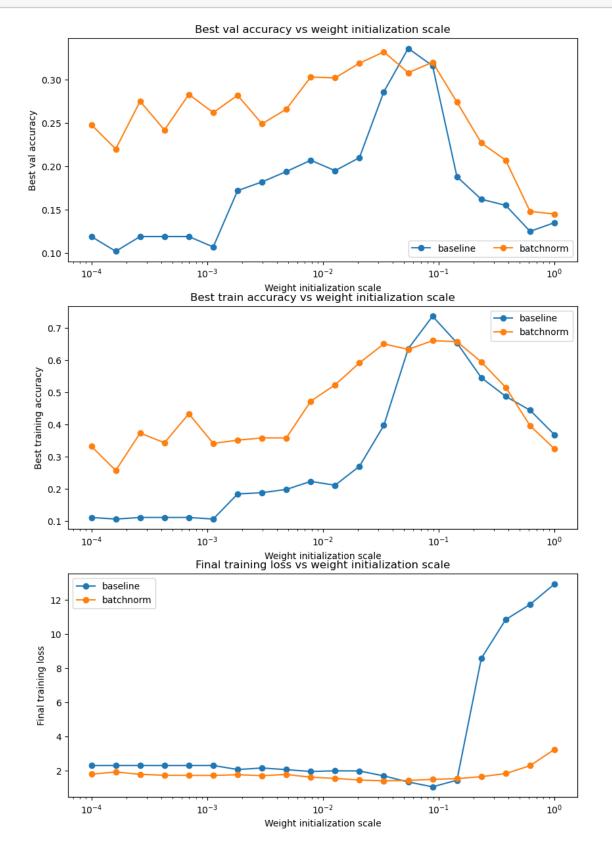
```
'y_val': data['y_val'],
}
bn_solvers = {}
solvers = {}
weight_scales = np.logspace(-4, 0, num=20)
for i, weight_scale in enumerate(weight_scales):
    print('Running weight scale {} / {}'.format(i + 1, len(weight_scales)))
    bn_model = FullyConnectedNet(hidden_dims, weight_scale=weight_scale,__

use_batchnorm=True)

    model = FullyConnectedNet(hidden_dims, weight_scale=weight_scale,_
  ⇔use_batchnorm=False)
    bn_solver = Solver(bn_model, small_data,
                     num_epochs=10, batch_size=50,
                     update_rule='adam',
                     optim_config={
                       'learning_rate': 1e-3,
                     },
                     verbose=False, print_every=200)
    bn solver.train()
    bn_solvers[weight_scale] = bn_solver
    solver = Solver(model, small_data,
                     num_epochs=10, batch_size=50,
                     update_rule='adam',
                     optim config={
                       'learning_rate': 1e-3,
                     verbose=False, print_every=200)
    solver.train()
    solvers[weight_scale] = solver
Running weight scale 1 / 20
```

```
Running weight scale 2 / 20
Running weight scale 3 / 20
Running weight scale 4 / 20
Running weight scale 5 / 20
Running weight scale 5 / 20
Running weight scale 6 / 20
Running weight scale 7 / 20
Running weight scale 8 / 20
Running weight scale 9 / 20
Running weight scale 10 / 20
Running weight scale 11 / 20
Running weight scale 12 / 20
Running weight scale 12 / 20
Running weight scale 13 / 20
Running weight scale 14 / 20
```

```
Running weight scale 15 / 20
     Running weight scale 16 / 20
     Running weight scale 17 / 20
     Running weight scale 18 / 20
     Running weight scale 19 / 20
     Running weight scale 20 / 20
[10]: # Plot results of weight scale experiment
      best_train_accs, bn_best_train_accs = [], []
      best_val_accs, bn_best_val_accs = [], []
      final train loss, bn final train loss = [], []
      for ws in weight scales:
          best_train_accs.append(max(solvers[ws].train_acc_history))
          bn_best_train_accs.append(max(bn_solvers[ws].train_acc_history))
          best_val_accs.append(max(solvers[ws].val_acc_history))
          bn_best_val_accs.append(max(bn_solvers[ws].val_acc_history))
          final_train_loss.append(np.mean(solvers[ws].loss_history[-100:]))
          bn final_train_loss.append(np.mean(bn_solvers[ws].loss_history[-100:]))
      plt.subplot(3, 1, 1)
      plt.title('Best val accuracy vs weight initialization scale')
      plt.xlabel('Weight initialization scale')
      plt.ylabel('Best val accuracy')
      plt.semilogx(weight scales, best val accs, '-o', label='baseline')
      plt.semilogx(weight_scales, bn_best_val_accs, '-o', label='batchnorm')
      plt.legend(ncol=2, loc='lower right')
      plt.subplot(3, 1, 2)
      plt.title('Best train accuracy vs weight initialization scale')
      plt.xlabel('Weight initialization scale')
      plt.ylabel('Best training accuracy')
      plt.semilogx(weight_scales, best_train_accs, '-o', label='baseline')
      plt.semilogx(weight_scales, bn_best_train_accs, '-o', label='batchnorm')
      plt.legend()
      plt.subplot(3, 1, 3)
      plt.title('Final training loss vs weight initialization scale')
      plt.xlabel('Weight initialization scale')
      plt.ylabel('Final training loss')
      plt.semilogx(weight_scales, final_train_loss, '-o', label='baseline')
      plt.semilogx(weight_scales, bn_final_train_loss, '-o', label='batchnorm')
      plt.legend()
      plt.gcf().set_size_inches(10, 15)
```



1.6 Question:

In the cell below, summarize the findings of this experiment, and WHY these results make sense.

1.7 Answer:

Using a batchnorm in a neural network makes our network more robust to changes in weight initialization. If we do not use batchnorm, layer's activation output can become zero as we proceed to deeper layers (last layer is the deepest layer) depending on the initialization. Therefore, when we do not use batchnorm, neural networks are sensitive to weight initialization.

[]: