'ARM mbed' Example Codes

You can find the list of APIs of mebd OS5

https://os.mbed.com/docs/mbed-os/v5.13/apis/index.html

Also, there are many more examples found in

- https://os.mbed.com/code/
- https://os.mbed.com/teams/ST/code/

```
GPIO LED control
Blinking
                                                       LED control with a button
 #include "mbed.h"
                                                         DigitalIn button (USER BUTTON);
 DigitalOut led(LED1);
                                                        DigitalOut led(LED1);
pint main() {
      while(1) {
                                                            while(1) {
         led = !led;
                                                                if(!button) led = 1;
          wait(0.5); // 0.5[sec]
                                                                else led = 0;
1
                                                        L
UART (polling)
Writing to PC
                                                       Receiving from PC
 #include "mbed.h"
                                                         #include "mbed.h"
 Serial pc(USBTX, USBRX, 9600);
                                                         Serial pc(USBTX, USBRX, 9600);
 int main()
                                                        int main()
₽{
                                                       □ {
      while (1)
                                                             char RXD:
                                                             while(1)
          pc.printf("Hello!\r\n");
          wait(1);
                                                                 if(uart.readable()){
                                                                    RXD = pc.getc();
L,
                                                                     pc.printf("%c", RXD);
Analog Measurement
Measuring Analog Voltage
#include "mbed.h"
 Serial
             pc (USBTX, USBRX, 9600);
 AnalogIn
             sensor(A0);
pint main() {
     float measure;
     while(1) {
                                                 // 0 ~ 3.3V -> 0.0 ~ 1.0
        measure = sensor.read();
        measure = measure * 3.3;
pc.printf("measure = %f [V]\n\r", measure);
                                                  // 0.0 ~ 1.0 -> 0 ~ 3.3V
         wait(0.2);
```

Interrupt(external)

Edge trigger Handler

```
#include "mbed.h"

InterruptIn button(USER_BUTTON);
DigitalOut led(LED1);

void pressed()

{
    led = 1;
}

void released() {
    led = 0;
}

int main()

{
    button.fall(&pressed);
    button.rise(&released);
    while (1);
}
```

Timer

```
Measuring Time

#include "mbed.h"

#include "mbed.h"
```

```
DigitalOut led(LED1);
Timer timer;
Serial pc(USBTX, USBRX, 9600);
int begin, end;
int cnt = 0;

Bint main(void) {
   timer.start();
   begin = timer.read_us();
   led = 1;
   led = 0;
   end = timer.read_us();
   pc.printf("Blinking LED takes %d [us]", end-begin);
}
Ticker tic DigitalOut led
Note:
DigitalOut led
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Note:
DigitalOut led
Di
```

```
#include "mbed.h"

Ticker tick;
DigitalOut led(LED1);

void INT() {
 led = !led;
}

int main(void) {
 tick.attach(&INT, 1); // 1[sec] 마다 INT 함수 실행
 while(1);
}
```