## Algorithm 2 求解地理位置

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▷ 输入通过附件数据所求得的方位角,影长和时间
Input: G: Fs', Ls', Time
                                                                                 ▷影长,纬度,经度
Output: P: [l w j]
 1: function ROUGHTRAVERSAL
       L = [0, 10]
 2:
       W = [-90, 90]
 3:
       J = [-180, 180]
 4:
       for each l in L step = 1 do
 5:
          for each w in W step = 10 do
 6:
              for each j in J step = 10 do
 7:
                 for each t in Time do
 8:
 9:
                     Ls(i) = 1/tan(\theta_H)
                     Fs(i) = arccos((sin(C) - sin(\theta_H) * sin(w)) / (cos(\theta_H) * cos(w)))
10:
                 end for
11:
                 FsError = \frac{1}{20} * \sum_{i=1}^{20} (Fs(i) - Fs'(i))^2
12:
                 LsError = \frac{1}{21} * \sum_{j=1}^{21} (Ls(j) - Ls'(j))^2
13:
                 Error = 0.6*FsError + 0.4*LsError
                                                                                              ▷ 误差
14:
                 if Error < \delta then
15:
                                                                 ▷ 误差最小的杆长, 纬度和经度数组
                     P = [l w j]
16:
                 end if
17:
              end for
18:
          end for
19:
20:
       end for
       return P
21:
22: end function
```