Homework 8 - Artificial Neural Networks with PyTorch

About

In this homework, you will get your feet wet with deep learning using the PyTorch deep learning platform. This will involve:

- · Preparing data
- · Learning about the components of a deep learning pipeline
- Setting up a model, a loss function, and an optimizer
- Setting up training and testing loops
- · Using a visualizer like tensorboard to monitor logged data

This homework is due **April 15th 2019**. Training neural networks takes some time, particularly on CPUs so start early.

Dev Environment

Working on Google Colab

You may choose to work locally or on Google Colaboratory. You have access to free compute through this service.

- 1. Visit https://colab.research.google.com/drive (https://colab.research.google.com/drive)
- 2. Navigate to the Upload tab, and upload your HW8.ipynb
- 3. Now on the top right corner, under the Comment and Share options, you should see a Connect option. Once you are connected, you will have access to a VM with 12GB RAM, 50 GB disk space and a single GPU. The dropdown menu will allow you to connect to a local runtime as well.

Notes:

- If you do not have a working setup for Python 3, this is your best bet. It will also save you from heavy installations like tensorflow if you don't want to deal with those.
- There is a downside. You can only use this instance for a single 12-hour stretch, after which your data will be deleted, and you would have redownload all your datasets, any libraries not already on the VM, and regenerate your logs.

Installing PyTorch and Dependencies

The instructions for installing and setting up PyTorch can be found at https://pytorch.org/get-started/locally/). Make sure you follow the instructions for your machine. For any of the remaining libraries used in this assignment:

- We have provided a hw8 requirements.txt file on the homework web page.
- Download this file, and in the same directory you can run pip3 install -r hw8_requirements.txt

Check that PyTorch installed correctly by running the following:

The output should look something like

```
tensor([[0.3380, 0.3845, 0.3217], [0.8337, 0.9050, 0.2650], [0.2979, 0.7141, 0.9069], [0.1449, 0.1132, 0.1375], [0.4675, 0.3947, 0.1426]])
```

Let's get started with the assignment.

Instructions

Part 1 - Datasets and Dataloaders (10 points)

In this section we will download the MNIST dataset using PyTorch's own API.

Helpful Resources:

- https://pytorch.org/docs/stable/torchvision/datasets.html#mnist (https://pytorch.org/docs/stable/torchvision/datasets.html#mnist)
- https://pytorch.org/docs/stable/torchvision/transforms.html (https://pytorch.org/docs/stable/torchvision/transforms.html)
- https://pytorch.org/tutorials/beginner/data_loading_tutorial.html (https://pytorch.org/tutorials/beginner/data_loading_tutorial.html)

The torchvision package consists of popular datasets, model architectures, and common image transformations for computer vision. We are particularly concerned with torchvision.datasets and torchvision.transforms. Check out the API for these modules in the links provided above.

Create a directory named hw8_data with the following command.

```
In [92]: !mkdir hw8_data
```

A subdirectory or file hw8_data already exists.

Now use torch.datasets.MNIST to load the Train and Test data into hw8 data.

- Use the directory you created above as the root directory for your datasets
- Populate the transformations variable with any transformations you would like to perform on your data. (Hint: You will need to do at least one)
- Pass your transformations variable to torch.datasets.MNIST. This allows you to perform arbitrary transformations to your data at loading time.

```
In [93]: from torchvision import datasets, transforms

## YOUR CODE HERE ##

#we tested the below flip and it works. commented to avoid impact on accuracy
    for Later part of the HW.

#transformations = transforms.Compose([transforms.RandomHorizontalFlip(), tran
    sforms.ToTensor()])

transformations = transforms.Compose([transforms.ToTensor()])

mnist_train = datasets.MNIST('./hw8_data', train=True, transform=transformatio
    ns, download=True)

mnist_test = datasets.MNIST('./hw8_data', train=False, transform=transformatio
    ns, download=True)
```

Check that your torch datasets have been successfully downloaded into your data directory by running the next two cells.

- · Each will output some metadata about your dataset.
- Check that the training set has 60000 datapoints and a Root Location: hw8_data
- Check that the testing (also validation in our case) set has 10000 datapoints and Root Location: hw8_data

Notice that these datasets implement the python __len__ and __getitem__ functions. Each element in the dataset should be a 2-tuple. What does yours look like?

Any file in our dataset will now be read at runtime, and the specified transformations we need on it will be applied when we need it..

We could iterate through these directly using a loop, but this is not idiomatic. PyTorch provides us with this abstraction in the form of DataLoaders. The module of interest is torch.utils.data.DataLoader.

DataLoader allows us to do lots of useful things

- · Group our data into batches
- Shuffle our data
- Load the data in parallel using multiprocessing workers

Use DataLoader to create a loader for the training set and one for the testing set

- Use a batch_size of 32 to start, you may change it if you wish.
- Set the shuffle parameter to True.

```
In [96]: from torch.utils.data import DataLoader

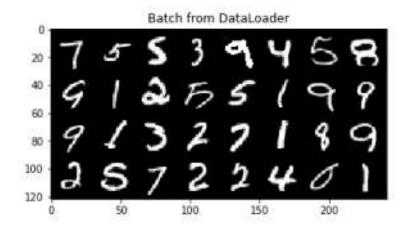
## YOUR CODE HERE ##
train_loader = DataLoader(mnist_train, batch_size=32, shuffle=True)

# Set batch size to full & no shuffle for validation set, for better performan
ce.
test_loader = DataLoader(mnist_test, batch_size=len(mnist_test), shuffle=False
)
```

The following function is adapted from show_landmarks_batch at https://pytorch.org/tutorials/beginner/data_loading_tutorial.html#iterating-through-the-dataset).

Run the following cell to see that your loader provides a random batch_size number of data points.

```
In [97]:
         import matplotlib.pyplot as plt
         from torchvision import utils
         %matplotlib inline
         def show_mnist_batch(sample_batched):
              """Show images for a batch of samples."""
             images_batch = sample_batched[0]
             batch_size = len(images_batch)
             im_size = images_batch.size(2)
             grid = utils.make_grid(images_batch)
             plt.imshow(grid.numpy().transpose((1, 2, 0)))
             plt.title('Batch from DataLoader')
         # Displays the first batch of images
         for i, batch in enumerate(train_loader):
             if i==1:
                 break
             show_mnist_batch(batch)
```



Part 2 - Models, Loss Functions and Optimizers (10 points)

In this section, we will do the following:

- Learn about how to build your deep learning model and define its parameters
- Choose a loss function to optimize
- Choose an optimization method to maximize/minimize the loss

We'll first start with a single layer neural network to do handwritten digit classification. The math may ring some bells from homework 7.

torch.nn is the module we will be using here. You can find the API at https://pytorch.org/docs/stable/nn.html). There is also a quick summary at https://pytorch.org/tutorials/beginner/nn_tutorial.html#closing_thoughts).

Models

We will use the following python modules in building our one layer model.

- torch.nn.Module: Your model will be abstracted as a python class. Your python class must subclass torch.nn.Module. It is the base class for all neural network modules in PyTorch (Do not confuse python modules with PyTorch Modules). These implement the forward() function which defines how your model handles input and produces an output. Your model class can also have torch.nn.Module s as members, allowing nested tree like structures, and it is leveraging this that you are able to build neural networks in PyTorch.
- torch.nn.Linear: A unit of computation in neural networks are *Layers* and PyTorch provides abstractions for layers as nn.Modules. These come in many forms including *Convolutional*, *Recurrent*, and *Linear*. You can find the API for linear layers here https://pytorch.org/docs/stable/nn.html#linear-layers).

Now use the information provided to define the <code>OneLayerModel</code> class below. The superclass constructor has been called for you, and this allows your subclass to access superclass methods and members.

- Finish the __init__() function.
- Finish the forward() function. (Hint: Use that fact that layer modules implement their own forward() function)

```
In [98]: from torch import nn
    class OneLayerModel(nn.Module):
    def __init__(self, input_dim, output_dim):
        super(OneLayerModel, self).__init__()
        ## YOUR CODE HERE ##
        self.lin = nn.Linear(input_dim,output_dim)

def forward(self, x):
    ## YOUR CODE HERE ##
    return self.lin(x)
```

Loss Functions and Optimizers

You've defined your model but now what? It's just a black box that takes an input and spits out some numbers. You haven't yet defined what it means to be a good or bad model.

A **Loss Function** takes what your model outputs and compares it to what it *should* have put out. It returns some meaningful value used to update your model parameters, and so train your model. Check out Section 21.2.1 of the textbook for more details about types of loss functions. The Loss function represents the overall goal of building this model, and the choice of loss function is very important.

We must examine our model parameters and our problem instance to see about how to choose a loss function.

- We take in a 784-dimensional vector and output 10 real values, giving our model 784 x 10 parameters.
- It is natural given that our problem is an instance of *multi-class classification* that we would want each of our output values to model P(y==i|x).
- If we go this route, we get an added constraint that the sum of all 10 of our output values should be 1 (forming a probability mass distribution).

Turns out there is a very convenient loss function for just our use case known as *cross-entropy loss*. Check out this reference https://ml-cheatsheet.readthedocs.io/en/latest/loss_functions.html#cross-entropy) for a little more intuition on this.

Once again, PyTorch has abstractions built in for us in the torch.nn module, namely torch.nn.CrossEntropyLoss . The API can be found at https://pytorch.org/docs/stable/nn.html#crossentropyloss (https://pytorch.org/docs/stable/nn.html#crossentropyloss).

We're still not ready to train our model because while we have some parameters, and we have some measure of how good or bad our predictions are, we have no notion of how to go about updating our parameters in order to improve our loss.

This is where *Optimizers* come in. In general, we have one main way of minimizing loss functions (training our models), and that is through *Stochastic Gradient Descent*https://en.wikipedia.org/wiki/Stochastic_gradient_descent
(https://en.wikipedia.org/wiki/Stochastic_gradient_descent). There are many variants and optimizations of this method, however, and the torch.optim package gives us abstractions for these. The API can be found at https://pytorch.org/docs/stable/optim.html# (https://pytorch.org/docs/stable/optim.html# (https://pytorch.org/docs/stable/optim.html#).

In [99]: from torch import optim

Part 3 - Training and Validation (45 points)

In this section we will learn how to use the concepts we've learned about so far to train the model we built, and validate how well it does. We also want to monitor how well our training is going while it is happening.

For this we can use a package called tensorboardX . You will need to install this package using pip or Anaconda , based on your dev environment. Additionally, we'll want to use a logging module called tensorboardX.SummaryWriter . You can consult the API here

https://tensorboardx.readthedocs.io/en/latest/tutorial.html

(https://tensorboardx.readthedocs.io/en/latest/tutorial.html). Run the next cell to ensure that all is working well.

The tensorboard.notebook extension is already loaded. To reload it, use: %reload ext tensorboard.notebook

We have provided the code to use tensorboard just before calling your train function. You don't have to change the top-level log directory, but you can create multiple runs (different parameters or versions of your code) just by creating subdirectories for these within your top-level directory.

Now use the information provided above to do the following:

- Instantiate a OneLayerModel with the appropriate input/output parameters.
- Define a cross-entropy loss function.
- Define a stochastic gradient descent optimizer based for you model's parameters. Start with a
 learning rate of 0.001, and adjust as necessary. You can start with the vanilla optim.SGD optimizer,
 and change it if you wish.
- Create a SummaryWriter object that will be responsible for logging our training progress into a directory called logs/expt1 (Or whatever you wish your top-level directory to be called).

```
In [101]: ## YOUR CODE HERE ##
model = OneLayerModel(784,10)
loss = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), lr=0.01)
writer = SummaryWriter(log_dir="./logs/expt1")
```

We've finally come to the point where we need to write our training set up. We're going to use both our training and testing (validation) sets for this. Note that traditionally, you would separate part of your training data into validation data in order to get an unbiased estimate of how your model performs, but here we'll just pretend that our testing data is our validation data.

Training a model with batches of data broadly involves the following steps:

- 1. One epoch is defined as a full pass of your dataset through your model. We choose the number of epochs we wish to train our model for.
- 2. In each epoch, set your model to train mode.
- 3. you feed your model batch_size examples at a time, and receive batch_size number of outputs until you've gotten through your entire dataset.
- 4. Calculate the loss function for those outputs given the labels for that batch.
- Now calculate the gradients for each model parameter. (Hint: Your loss function object can do this for you)
- 6. **Update your model parameters** (Hint: The optimizer comes in here)
- 7. Set the gradients in your model to zero for the next batch.
- 8. After each epoch, set your model to evaluation mode.
- 9. Now evaluate your model on the validation data. Log the total loss and accuracy over the validation data. (Note: PyTorch does automatic gradient calculations in the background through its Autograd mechanism https://pytorch.org/docs/stable/notes/autograd.html). Make sure to do evaluation in a context where this is turned off!)

Complete the train() function below. Try to make it as general as possible, so that it can be used for improved versions of you model. Feel free to define as many helper functions as needed. Make sure that you do the following:

- Log the training loss and training accuracy on each batch for every epoch, such that it will show up on tensorboard.
- · Log the loss on the validation set and the accuracy on the validation set every epoch

You will need to produce the plots for these.

You may also want to add some print statements in your training function to report progress in this notebook.

```
In [102]: def accuracy(predict, target):
              pred = torch.argmax(predict, dim=1)
              return (pred == target).float().mean()
          def train(model, train_loader, val_loader, loss_func, opt,num_epochs=10, write
          r=None):
              batch id = 0
              for epoch in range(num epochs):
                  model.train()
                  for x,y in train_loader:
                       x=x.reshape(len(x),-1)
                       loss = loss_func(model(x), y)
                       loss.backward()
                       opt.step()
                       opt.zero grad()
                       with torch.no_grad():
                           train accuracy = accuracy(model(x),y)
                           writer.add_scalars('Train set', {'loss':loss.item(),
                                                        'accuracy': train_accuracy.item
           ()}, batch id)
                       batch id=batch id+1
                  model.eval()
                  with torch.no_grad():
                       # Actually val loader has only one batch (of all data), but we sti
          ll keep below for mutiple batches just in case.
                       outputs = [[model(x val.reshape(len(x val),-1)),y val] for x val,
          y_val in val_loader]
                       val loss = sum(loss func(output[0],output[1]) for output in output
          s)
                       epoch_accuracy = sum(accuracy(output[0],output[1]) for output in o
          utputs)
                      writer.add scalars('validation set', {'loss':val loss.item()/len(v
          al_loader),
                                                        'accuracy': epoch_accuracy.item()/
          len(val loader)}, epoch)
                       print('training accuracy for epoch:',epoch," is: ",train accuracy.
          item())
                       print('Validation loss for epoch:',epoch," is: ", val loss.item()/
          len(val loader))
                       print('Validation accuracy for epoch:',epoch," is: ", epoch_accura
          cy.item())
```

Finally call train with the relevant parameters. Run the tensorboard command on your top-level logs directory to monitor training. If there is logging data from a previous run, just delete the directory for the run, and reinstantiate the SummaryWriter for that run. (You may want to reinstantiate the model itself if you want to clear the model parameters too).

Note: This function may take a while to complete if you're training for many epochs on a cpu. This is where it comes in handy to be running on Google Colab, or just have a GPU on hand.

In [103]: #%tensorboard --logdir=logs
train(model, train_loader, test_loader, loss, optimizer, 15, writer)

training accuracy for epoch: 0 is: 0.84375 Validation loss for epoch: 0 is: 0.4769645631313324 Validation accuracy for epoch: 0 is: 0.881600022315979 training accuracy for epoch: 1 is: 0.90625 Validation loss for epoch: 1 is: 0.39942118525505066 Validation accuracy for epoch: 1 is: 0.8953999876976013 training accuracy for epoch: 2 is: 0.875 Validation loss for epoch: 2 is: 0.3664940297603607 Validation accuracy for epoch: 2 is: 0.9027000069618225 training accuracy for epoch: 3 is: 0.9375 Validation loss for epoch: 3 is: 0.3480450212955475 Validation accuracy for epoch: 3 is: 0.9067000150680542 training accuracy for epoch: 4 is: 0.90625 Validation loss for epoch: 4 is: 0.3349950909614563 Validation accuracy for epoch: 4 is: 0.9097999930381775 training accuracy for epoch: 5 is: 0.9375 Validation loss for epoch: 5 is: 0.3263709545135498 Validation accuracy for epoch: 5 is: 0.9108999967575073 training accuracy for epoch: 6 is: 0.90625 Validation loss for epoch: 6 is: 0.3195890486240387 Validation accuracy for epoch: 6 is: 0.9122999906539917 training accuracy for epoch: 7 is: 0.9375 Validation loss for epoch: 7 is: 0.31426218152046204 Validation accuracy for epoch: 7 is: 0.9140999913215637 training accuracy for epoch: 8 is: 0.875 Validation loss for epoch: 8 is: 0.31001031398773193 Validation accuracy for epoch: 8 is: 0.9150000214576721 training accuracy for epoch: 9 is: 0.9375 Validation loss for epoch: 9 is: 0.30654090642929077 Validation accuracy for epoch: 9 is: 0.9162999987602234 training accuracy for epoch: 10 is: 0.875 Validation loss for epoch: 10 is: 0.3023914098739624 Validation accuracy for epoch: 10 is: 0.9162999987602234 training accuracy for epoch: 11 is: 0.96875 Validation loss for epoch: 11 is: 0.29961732029914856 Validation accuracy for epoch: 11 is: 0.9169999957084656 training accuracy for epoch: 12 is: 0.90625 Validation loss for epoch: 12 is: 0.2984837293624878 Validation accuracy for epoch: 12 is: 0.9161999821662903 training accuracy for epoch: 13 is: 0.84375 Validation loss for epoch: 13 is: 0.29688239097595215 Validation accuracy for epoch: 13 is: 0.9169999957084656 training accuracy for epoch: 14 is: 0.9375 Validation loss for epoch: 14 is: 0.29364025592803955 Validation accuracy for epoch: 14 is: 0.917900025844574

Final Validation Loss: 0.29364025592803955

Final Validation Accuracy: 91.7900025844574%

What is familiar about a 1-layer neural network with cross-entopy loss? Have you seen this before?

Answer: It is like a SVM which was trained by SGD with similar regularization term and hinge loss. It also reminds me about logistic regression: an linear calculation followed by a link function which is similar to softmax output.

Part 4 - Two Layer Neural Net (20 points)

The thing that makes neural networks really powerful is that they are able to do complex function approximation. As we saw earlier, we can organize the computation done in neural networks into units called *layers*. In a general neural network, there is an *input layer*, and an *output layer*. These may be the same layer as they were in our previous example. When they are not the same, there are intermediate layers known as *hidden layers*. These layers receive input from other layers and send their output to other layers.

We have been dealing with a certain type of neural network known as a **fully connected** network. For our purposes, this just means that the output of the layer is just the dot product of its input x, its weights w plus a bias term b, all wrapped in a non-linear activation function F.

$$y = F(w^T x + b).$$

These non-linear activation functions are very important but where in our last neural network did we apply such a function? Implicitly we applied what's known as a **softmax activation** in order to compute cross-entropy loss https://en.wikipedia.org/wiki/Softmax_function (https://en.wikipedia.org/wiki/Softmax_function).

We'll now try to create a neural network with one hidden layer. This means that we have to come up with an activation function for the output of that hidden layer. A famous, simple but powerful activation function is the **Rectified Linear Unit (ReLU)** function defined nas ReLU(x) = max(x,0). We will use this on the output of the hidden layer.

torch.nn has a module known as nn.Sequential that allows us to chain together other modules. This module implements a forward() function that automatically handles input-output connections etc. Check out the API at https://pytorch.org/docs/stable/nn.html#sequential (https://pytorch.org/docs/stable/nn.html#sequential).

Just like you did with the single layer model, define a class TwoLayerModel, a neural network with ReLU activation for the hidden layer. nn.Sequential may come in handy.

Once again use the information provided above to do the following:

- Instantiate a TwoLayerModel with the appropriate input/output/hidden layer parameters.
- Define a cross-entropy loss function again.
- Define a stochastic gradient descent optimizer based for you model's parameters. Start with a learning rate of 0.001, and adjust as necessary. You can start with the vanilla optim.SGD optimizer, and change it if you wish.
- Create a SummaryWriter object that will be responsible for logging our training progress into a directory called logs/expt2 (Or whatever you wish your top-level directory to be called, just make sure the subdirectory is different from your previous SummaryWriter).

```
In [105]: ## YOUR CODE HERE ##
model2 = TwoLayerModel(784,256,10)
loss2 = nn.CrossEntropyLoss()
optimizer2 = optim.SGD(model2.parameters(), lr=0.01)
writer2 = SummaryWriter(log_dir="./logs/expt2")
```

Call train on your two layer neural network.

In [106]: #%tensorboard --logdir=logs
 train(model2, train_loader, test_loader, loss2, optimizer2, 15, writer2)

training accuracy for epoch: 0 is: 0.90625 Validation loss for epoch: 0 is: 0.4015713036060333 Validation accuracy for epoch: 0 is: 0.8944000005722046 training accuracy for epoch: 1 is: 0.875 Validation loss for epoch: 1 is: 0.32098308205604553 Validation accuracy for epoch: 1 is: 0.9104999899864197 training accuracy for epoch: 2 is: 0.96875 Validation loss for epoch: 2 is: 0.29066798090934753 Validation accuracy for epoch: 2 is: 0.91839998960495 training accuracy for epoch: 3 is: 0.9375 Validation loss for epoch: 3 is: 0.26399171352386475 Validation accuracy for epoch: 3 is: 0.9258999824523926 training accuracy for epoch: 4 is: 0.9375 Validation loss for epoch: 4 is: 0.24683232605457306 Validation accuracy for epoch: 4 is: 0.9302999973297119 training accuracy for epoch: 5 is: 0.96875 Validation loss for epoch: 5 is: 0.23134367167949677 Validation accuracy for epoch: 5 is: 0.9352999925613403 training accuracy for epoch: 6 is: 1.0 Validation loss for epoch: 6 is: 0.21605442464351654 Validation accuracy for epoch: 6 is: 0.9381999969482422 training accuracy for epoch: 7 is: 0.875 Validation loss for epoch: 7 is: 0.2041420191526413 Validation accuracy for epoch: 7 is: 0.9416999816894531 training accuracy for epoch: 8 is: 1.0 Validation loss for epoch: 8 is: 0.1927328109741211 Validation accuracy for epoch: 8 is: 0.9448000192642212 training accuracy for epoch: 9 is: 0.96875 Validation loss for epoch: 9 is: 0.1832217425107956 Validation accuracy for epoch: 9 is: 0.9473000168800354 training accuracy for epoch: 10 is: 1.0 Validation loss for epoch: 10 is: 0.17185720801353455 Validation accuracy for epoch: 10 is: 0.9506999850273132 training accuracy for epoch: 11 is: 0.90625 Validation loss for epoch: 11 is: 0.16462653875350952 Validation accuracy for epoch: 11 is: 0.95169997215271 training accuracy for epoch: 12 is: 0.96875 Validation loss for epoch: 12 is: 0.1568337231874466 Validation accuracy for epoch: 12 is: 0.9550999999046326 training accuracy for epoch: 13 is: 0.9375 Validation loss for epoch: 13 is: 0.1501466929912567 Validation accuracy for epoch: 13 is: 0.9556999802589417 training accuracy for epoch: 14 is: 0.96875 Validation loss for epoch: 14 is: 0.1445414125919342 Validation accuracy for epoch: 14 is: 0.9573000073432922

Final Validation Loss: 0.1445414125919342

Final Validation Accuracy: 95.73000073432922%

Did your accuracy on the validation set improve with multiple layers? Why do you think this is?

Answer: Yes, it improves with multiple layers. Comparing to single layer, with hidden layers it has more neurons which provide capability to construct more 'complex features'. Also it have more parameters provides better freedom and a more complex non linear function for the model.

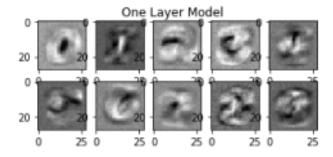
Part 5 - What is being learned at each layer? (10 points)

So what exactly are these weights that our network is learning at each layer? By conveniently picking our layer dimensions as perfect square numbers, we can try to visualize the weights learned at each layer as square images. Use the following function to do so for *all interesting layers* across your models. Feel free to modify the function as you wish.

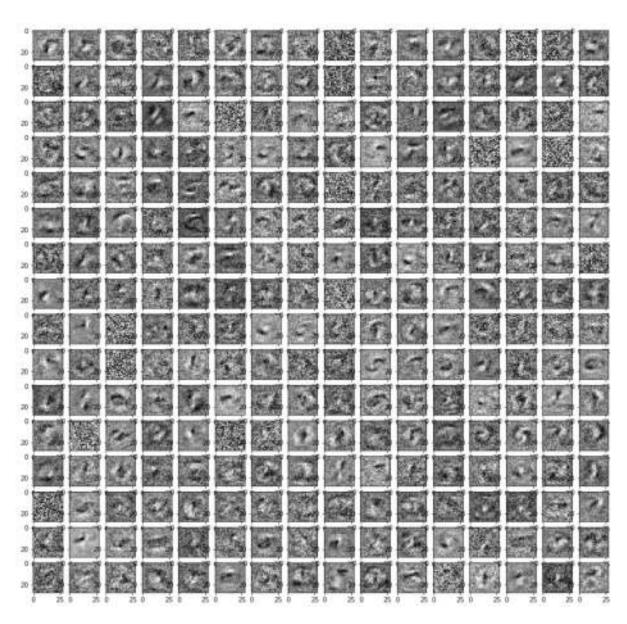
At the very least, you must generate:

- 1. The ten 28x28 weight images learned by your one layer model.
- 2. The 256 28x28 weight images learned by the hidden layer in your two-layer model.

In [83]: def visualize_layer_weights(model, layer_idx, num_images, image_dim, title): # Find number of rows and columns based on number of images for d in range(1, num images): f = num images/d if int(f)==f: dim1 = int(min(f,d))dim2 = int(max(f,d))**if** d > f: break # Plot weights as square images fig, ax = plt.subplots(dim1, dim2) # At least 1 inch by 1 inch images fig.set_size_inches(dim2, dim1) weights = (list(model.parameters())[layer_idx]) fig.suptitle(title) for i in range(dim1): for j in range(dim2): ax[i][j].imshow(weights[dim2*i+j].reshape(image_dim,image_dim).det ach().numpy(), cmap='gray') visualize_layer_weights(model, 0, 10, 28, "One Layer Model") visualize_layer_weights(model2, 0, 256, 28, "Two Layers Model")

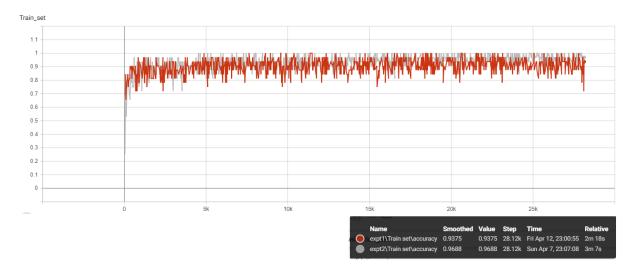


Two Layers Model

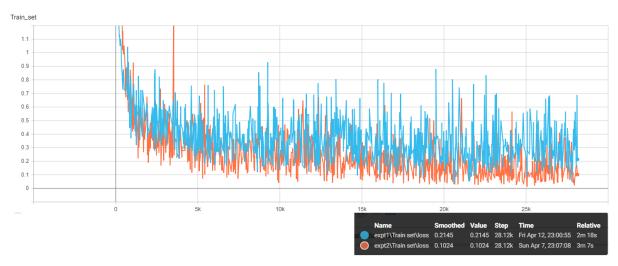


In []:

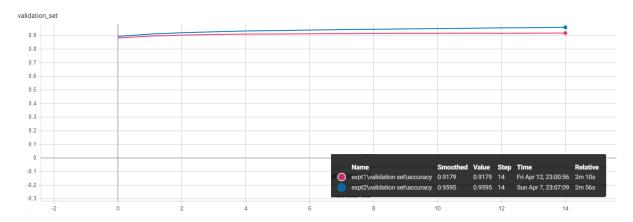
Plot #1 - Train set accuracy (per batch). expt1 – 1 layer mode. expt2 – 2 layers mode.



Plot #2 - Train set loss (per batch). expt1 – 1 layer mode. expt2 – 2 layers mode.



Plot #3 - Validation set accuracy (per epoch). expt1 – 1 layer mode. expt2 – 2 layers mode.



Plot #4 - Validation set loss (per epoch). expt1 – 1 layer mode. expt2 – 2 layers mode.

