Week 18: Trends of deep learning

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2 Lifelong learning

Limitation of deep learning

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when large training dataset is available!

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Impossible?!

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$$\hat{y} = \sum_{i=1}^{k} a(\hat{x}, x_i) y_i$$

where $\{(x_i, y_i)\}$ are small dataset as input to meta-classifier, and $a(\cdot)$ could be considered as an attention model

$$a(\hat{x}, x_i) = e^{c(f(\hat{x}), g(x_i))} / \sum_{j=1}^k e^{c(f(\hat{x}), g(x_j))}$$

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• Meta-classifier training: using many sets of small datasets to learn to find the optimal $f(\cdot)$ and $g(\cdot)$.

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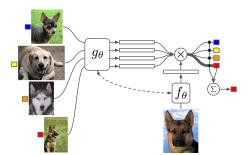
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- So in each training iteration, training set consists of two small subsets $\{(x_i, y_i)\}$ and $\{(\tilde{x}_j, \tilde{y}_j)\}$.
- Over iterations: training sets may be from different classes.

• So meta-classifier training is to find the optimal $f(\cdot)$ and $g(\cdot)$ by minimizing the prediction error of the classifier

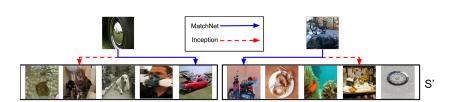
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on training set $\{\{(x_i,y_i)\},\{(\hat{x}_j,\hat{y}_j)\}\}$ over iterations.



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- The method learned better feature extractor $f(\cdot)$ and $g(\cdot)$ compared to using pretrained CNN as feature extractor:



Matching network: result

 The proposed method outperforms all others on Omniglot (below) and mini-ImageNet (not shown)!

| Model | Matching Fn | Fine Tune | 5-way Acc 1-shot 5-shot | 20-way Acc 1-shot 5-shot |
|--------------------------------|-------------|-----------|----------------------------|-----------------------------|
| PIXELS | Cosine | N | 41.7% 63.2% | 26.7% 42.6% |
| BASELINE CLASSIFIER | Cosine | N | 80.0% 95.0% | 69.5% 89.1% |
| BASELINE CLASSIFIER | Cosine | Y | 82.3% 98.4% | 70.6% 92.0% |
| BASELINE CLASSIFIER | Softmax | Y | 86.0% 97.6% | 72.9% 92.3% |
| MANN (No Conv) [21] | Cosine | N | 82.8% 94.9% | |
| CONVOLUTIONAL SIAMESE NET [11] | Cosine | N | 96.7% 98.4% | 88.0% 96.5% |
| CONVOLUTIONAL SIAMESE NET [11] | Cosine | Y | 97.3% 98.4% | 88.1% 97.0% |
| MATCHING NETS (OURS) | Cosine | N | 98.1% 98.9% | 93.8 % 98.5% |
| MATCHING NETS (OURS) | Cosine | Y | 97.9% 98.7% | 93.5% 98.7 % |

Note: 'Baseline classifier': trained on all training data, then extract feature from last conv layer for attention module.

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• Better model f_{θ} means less loss $\mathcal{L}_{\mathcal{T}_i}(f_{\theta_i'})$ on new tasks after one/few (so 'quick adapt') update of model parameter to θ_i' .

$$\min_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta_i'}) = \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta - \alpha \nabla_{\theta} \mathcal{L}_{\mathcal{T}_i}(f_{\theta})})$$

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• Note: meta-optimization is performed over model parameters θ , but loss is computed using updated parameters θ'_i .

MAML (cont')

 \bullet Meta-optimization over tasks ('training data') to update model param θ

$$\theta \leftarrow \theta - \beta \nabla_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta_i'})$$

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Meta-gradient update involves a gradient through gradient

Algorithm 1 Model-Agnostic Meta-Learning

Require: $p(\mathcal{T})$: distribution over tasks

Require: α , β : step size hyperparameters

- 1: randomly initialize θ
- 2: while not done do
- 3: Sample batch of tasks $\mathcal{T}_i \sim p(\mathcal{T})$
- 4: for all \mathcal{T}_i do
- 5: Evaluate $\nabla_{\theta} \mathcal{L}_{\mathcal{T}_{\delta}}(f_{\theta})$ with respect to K examples
 - Compute adapted parameters with gradient descent: $\theta'_i = \theta \alpha \nabla_{\theta} \mathcal{L}_{T_i}(f_{\theta})$
- 7: end for

6:

- 8: Update $\theta \leftarrow \theta \beta \nabla_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta_i'})$
- 9: end while

MAML: result

- MAML works for any differentiable objective, including those of regression and reinforcement learning!
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- MAML works for any differentiable objective, including those of regression and reinforcement learning!
- Matching network learns feature embedding, while MAML learns good model initialization for multiple tasks.
- Classification: MAML outperforms matching networks.

| | 5-way Accuracy | | |
|---|--------------------------|--------------------------|--|
| MiniImagenet (Ravi & Larochelle, 2017) | 1-shot | 5-shot | |
| fine-tuning baseline | $28.86 \pm 0.54\%$ | $49.79 \pm 0.79\%$ | |
| nearest neighbor baseline | $41.08 \pm 0.70\%$ | $51.04 \pm 0.65\%$ | |
| matching nets (Vinyals et al., 2016) | $43.56 \pm 0.84\%$ | $55.31 \pm 0.73\%$ | |
| meta-learner LSTM (Ravi & Larochelle, 2017) | $43.44 \pm 0.77\%$ | $60.60 \pm 0.71\%$ | |
| MAML, first order approx. (ours) | ${\bf 48.07 \pm 1.75\%}$ | ${\bf 63.15 \pm 0.91\%}$ | |
| MAML (ours) | ${\bf 48.70 \pm 1.84\%}$ | ${\bf 63.11 \pm 0.92\%}$ | |

Lifelong learning: another limitation

We learn new knowledge without forgetting old!

But Al catastrophically forgets old!

Lifelong learning: elastic weight consolidation (EWC)

• EWC idea: when learning a new task, do not change weights too much which are important to previous tasks.

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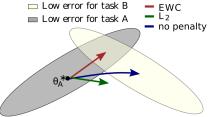
- EWC idea: when learning a new task, do not change weights too much which are important to previous tasks.
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- EWC idea: when learning a new task, do not change weights too much which are important to previous tasks.
- ullet Fisher information matrix ${f F}$: importance of model params.
- Can overcome catastrophic forgetting by minimizing loss

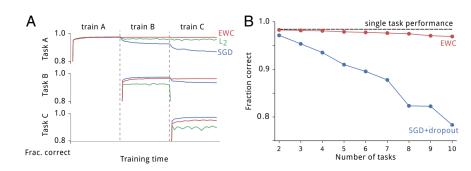
$$\mathcal{L}(\theta) = \mathcal{L}_B(\theta) + \sum_i \frac{\lambda}{2} F_i (\theta_i - \theta_{A,i}^*)^2$$

• Fisher-weighted regularization helps update model parameters (red arrow) good for both previous task A and new task B.



EWC: result

- On MNIST, with EWC: classifier does not degrade on current and previous tasks
- Blue curve: updating model by just focuing on current task



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$$F(x_1; \theta + \delta) - F(x_1; \theta) \approx \sum_{i,j} g_{ij}(x_1)\delta_{ij}$$

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where g_{ij} is the partial derivative of network output F w.r.t. parameter $\theta_{i,j}$ at data point x_1

• Importance of parameter $\theta_{i,j}$ can be estimated by accumulating g_{ij} over all available data points

$$\Omega_{ij} = \frac{1}{N} \sum_{k=1}^{N} || g_{ij}(x_k) ||$$

Loss is similar to EWC, except the importance parameter

$$L(\theta) = L_{new}(\theta) + \frac{\lambda}{2} \sum_{i,j} \Omega_{ij} (\theta_{ij} - \theta_{ij}^*)^2$$

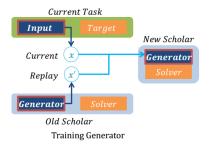
- Data label is not necessary when computing Ω_{ij} , so Ω_{ij} can be updated on any available data (without corresponding labels).
- Both this method and EWC focus on model parameters.
- Another idea: somehow get 'data' of previous tasks!

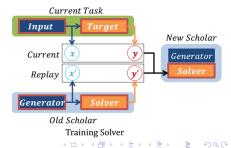
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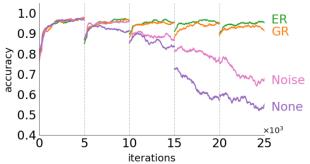
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- Dual model 'scholar': (GAN, Solver); Solver, e.g., classifier
- Train GAN: with GAN-generated data and new task's data
- Train Solver: with new task's (data, labels) and old scholar's (generated data, predicted labels)





- On MNIST, 5 tasks, continuously learning to recognize new classes of digits; test on all tasks' (test) data
- Similar performance between ER and GR



- ER: using exact past real data with predicted labels for replay
- GR (proposed): using realistic synthetic data for replay
- 'Noise': using un-realistic synthetic data for replay



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- Learn from partially labelled data: semi-supervised
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- Current deep learning depends on gradient descent.
- But human brains probably does not use gradient descent.
- Learning and inference by reasoning!
 e.g., deep learning + graphical model

Project reports

Course project report:

- Title; Team members
- Abstract: problem, difficulty, method idea, key result.
- Introduction: application background, research problem, related existing methods, implemented methods, main results including team ranking (e.g., ranked 5th over 120 teams).
- Problem formulation: formally describe the research problem, better with math representation.
- Method: the basic ideas, model structures, etc.
- Experiments: all experiments, including worse and better results, better explaining why.
- Conclusion: very short summary, conclusion from experimental evaluation, future work.
- Source code!

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No plagiarism!!