HW6

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Algorithm 1: Construct Graph

input : Image I
output: Graph G(V,E)

```
grad ← calculate gradient of I;
foreach pixel i ∈ I do
    add i to V;
    foreach neighbor j of i do
        add edge ij to E;
        assign edge capacity c_ij according to image gradient;
    end
end
```

Algorithm 2: GCBAC

input : initial contour c_0, image I, graph G, step_size

```
C ← ∅ ;
i ← 0;
while true do
    IC_i ← shrink c_i by step_size;
    OC_i ← dilate c_i by step_size;
    CN_{c_i} ← IC_i ∪ OC_i ;
    V_s ← pixels corresponding to IC_i;
    G_i, s_i ← node_identification(G, V_s);
    V_s ← pixels corresponding to OC_i;
    G_i, t_i ← node_identification(G_i, V_s);
    cut_value, cut_sets ← minimum_cut(G_i, s_i, t_i);
    c_{i+1} ← argmin_{c∈CN_{C_I}} E(c) where E(c) = capacity of cut_set that c
      belongs to ;
    if c_{i+1} ∈ C then
        break;
    else
        add c_{i+1} to C;
        i ← i + 1;;
    end
end
```

Algorithm 3: node_identification

input : $G(V, E), V_s$
output: $G(V', E'), v$

$v \leftarrow$ merge V_s to a new node ;
$E(V_S) \leftarrow \{(u_1, u_2)\}$ where $u_1 \in V_s$ or $u_2 \in V_s$;
$E(V) \leftarrow \{(u, v), (v, u)\}$ where $u \in V - V_s$;
$c^{'}(v, u) \leftarrow \sum_i c(v_i, u)$;
$c^{'}(u, v) \leftarrow \sum_i c(u, v_i)$;
$V^{'} \leftarrow V - V_s + v$;
$E^{'} \leftarrow E - E(V_S) + E(V)$;

Algorithm 1 is used to construct the required graph for algorithm2. In algorithm 2, we can use morphological operations from the opencv library to dilate or shrink the contour [1], and we can use the minimum cut function implemented from the networkx library in python[2]. Algorithm 3 is used to merge all the verticals corresponding to a contour to a single source or sink vertical and construct the new graph that will be used for graph cut algorithm.

[1] https://opencv-python-tutroals.readthedocs.io/en/latest/py_tutorials/py_imgproc/py_morphological_ops/py_morphological_ops.html

[2] https://networkx.org/documentation/stable//reference/algorithms/generated/networkx.algorithms.flow.minimum_cut.html