# Yancong Lin

Postdoc on Inductive Knowledge Priors for Visual Perception, TUDelft

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# Summary

My research focuses on creating scalable perception models for automated vehicles by pre-wiring deep learning with generic innate priors. This eliminates the need for large annotation to learn inductive knowledge. My research enhances the data efficiency of end-to-end learning with built-in differentiable priors, particularly on scene understanding and 3D reconstruction.

EXPERIENCE	
04/2022 - Now	Postdoc, Intelligent Vehicles Group, TUDelft.
	Working with Dr. Holger Caesar on scalable perception models.
01/2022 - Now	Collaborator, AIIR Innovation (industrial partner).
	3D modeling of engine blades (textureless and repetitive) from a video
EDUCATION	
09/2017 - 04/2022	PhD, Computer Vision Lab, TUDelft, The Netherlands.
PhD Thesis:	Data-efficient learning of geometric structures from single-view images
09/2014 - 06/2017	MEng in Computer Science, Tianjin University, China.
09/2010 - 06/2014	<b>BSc</b> in Physics, Southwest Jiaotong University, China.
Awards	
Grant	
2023	NGF AiNed XS Europa (80K EUR).
	In collaboration with Prof. Konrad Schindler, ETH Zurich.
Challenge	
2024	Argoverse2 Scene Flow challenge.
	1st place on the leaderboard (unsupervised).
Conference	
10/2022	Outstanding reviewer, ECCV.
06/2022	Outstanding reviewer, CVPR.
07/2021	Best student paper, ICCV workshop on
	Deep Learning for Geometric Computing.
SERVICE	
Reviewing	
2020 - Now	CVPR/ICCV/ECCV/BMVC.
Conference	
2023	Local chair, Netherlands Conference on Computer Vision.
Workshop	•
2020 - 2022	Visual Inductive Priors for Data-Efficient Deep Learning.
TEACHING	

Msc  $\times$  4 theses (×1 Cum Laude).

Courses 2019 - 2022

PhD

Supervision

Seminar Computer Vision by Deep Learning (CS4245).

Ted de Vries Lentsch and Shiming Wang (ongoing).

## REFERENCES

Dr. Holger Caesar TUDelft, h.caesar@tudelft.nl@tudelft.nl.

Dr. Jan van Gemert TUDelft, j.c.vangemert@tudelft.nl.

Dr. Silvia-Laura Pintea Leiden University Medical Center, s.l.pintea@lumc.nl.

#### Interests

Power lifting, Auto and Autobahn enthusiast.

### **PUBLICATIONS**

1. ICP Flow: Scene Flow Estimation with Iterative Closest Point.

Y. Lin, and H. Caesar.

Conference on Computer Vision and Pattern Recognition (CVPR), 2024.

2. BaSAL: Size Balanced Warm Start Active Learning for LiDAR Semantic Segmentation.

J. Wei, Y. Lin\* and H. Caesar. (\* Daily supervisor)

International Conference on Robotics and Automation (ICRA), 2024.

3. A Step Towards Understanding Why Classification Helps Regression.

S. Pintea,  $\mathbf{Y.}$  Lin, J. Dijkstra, and J. van Gemert.

International Conference on Computer Vision (ICCV), 2023.

4. NeRD++: Improved 3D-mirror symmetry learning from a single image.

Y. Lin, S. Pintea, and J. C. van Gemert.

British Machine Vision Conference (BMVC), 2022.

5. Deep vanishing point detection: Geometric priors make dataset variations vanish.

Y. Lin, R. Wiersma, S. Pintea, K. Hildebrandt, E. Eisemann and J. C. van Gemert. Conference on Computer Vision and Pattern Recognition (CVPR), 2022.

6. Investigating transformers in the decomposition of polygonal shapes as point collections.

A. Alfieri, Y. Lin\*, and J. C. van Gemert. (\* Daily supervisor)

International Conference on Computer Vision Workshop (ICCVW), 2021.

Best student paper.

7. Semi-supervised lane detection with deep Hough Transform.

Y. Lin, S. Pintea, and J. C. van Gemert.

International Conference on Image Processing (ICIP), 2021.

8. Deep Hough-Transform line priors.

Y. Lin, S. Pintea, and J. C. van Gemert.

European Conference on Computer Vision (ECCV), 2020.

June 13, 2024