

ZHAOJING YANG

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EDUCATION

University of Southern California
M.S in Computer Science

Aug 2022 - May 2024

Shanghai Jiao Tong University
B.Eng in Computer Science

Sep 2018 - June 2022

RESEARCH INTERESTS

My research interests lie in **Robot Learning**, especially in developing generalizable policies for real-world tasks. I am interested in applying learning methods to obtain optimal robot policies that can be deployed in the real world. My vision is to enable robots to perform complex tasks in the real world and interpret human instructions for better human-robot collaboration.

RESEARCH EXPERIENCES

Legged Robot Locomotion with Reinforcement Learning

Visiting Researcher, UCSD

Jun 2024 - Now

Advisor: Xiaolong Wang

- Trained locomotion policy with obstacle avoidance capability using RL in IsaacLab. Our policy takes LiDAR as exteroception input and is trained in a one-stage manner.
- Deployed the trained policy on the Unitree Go2 robot and integrated with a navigation VLM.

Preference-based Learning with Human Language Feedback

Research Assistant, USC

Aug 2023 - Jun 2024

Advisor: Erdem Bıyık

- Proposed a learning-based framework to learn a latent space that aligns human preferences through comparative language feedback with robot trajectories, which can then be used to learn human reward functions or improve robot trajectories.
- Conducted user studies on real robot, which demonstrate that our approach achieves a 23.9% higher subjective score on average and is 11.3% more time-efficient compared to the baseline

Multi-drones Collision Avoidance with Reinforcement Learning

Research Assistant, USC

Nov 2022 - Jun 2023

Advisor: Gaurav Sukhatme

- Proposed an end-to-end model that outputs direct thrusts to control quadrotors and achieved 97% agent success rate in obstacle and neighbor avoidance in simulation.
- Applied attention module in the model and deployed the model on micro quadrotors (Crazyflies) in the real world.

PUBLICATIONS

- [1] **NaVILA: Legged Robot Vision-Language-Action Model for Navigation**
An-Chieh Cheng*, Yandong Ji*, **Zhaojing Yang***, Xueyan Zou, Jan Kautz, Erdem Bıyık, Hongxu Yin[†], Sifei Liu[†], Xiaolong Wang[†]
In Submission to ICLR 2025 [[paper](#)]
- [2] **Trajectory Improvement and Reward Learning from Comparative Language Feedback**
Zhaojing Yang, Miru Jun, Jeremy Tien, Stuart J. Russell, Anca Dragan, Erdem Bıyık
CoRL 2024 [[website](#), [paper](#), [code](#)]
HRI 2024 Human-Interactive Robot Learning Workshop
- [3] **Collision Avoidance and Navigation for a Quadrotor Swarm Using End-to-end Deep Reinforcement Learning**
Zehui Huang*, **Zhaojing Yang***, Rahul Krupani, Baskın Şenbaşlar, Sumeet Batra, Gaurav S. Sukhatme
ICRA 2024 [[website](#), [paper](#), [code](#)]
- [4] **QuadSwarm: A Modular Multi-Quadrotor Simulator for Deep Reinforcement Learning with Direct Thrust Control**
Zehui Huang, Sumeet Batra, Tao Chen, Rahul Krupani, Tushar Kumar, Artem Molchanov, Aleksei Petrenko, James Alan Preiss, **Zhaojing Yang**, Gaurav S. Sukhatme
ICRA 2023 The Role of Robotics Simulators for Unmanned Aerial Vehicles Workshop [[paper](#), [code](#)]

AWARDS

Zhiyuan Honor Scholarship (Top 5%)	SJTU, 2021
Undergraduate Academic Excellence Scholarship (Top 10%)	SJTU, 2019

SKILLS

- Programming Language:** Python, C++, Shell
- Robotics:** ROS, IsaacLab, IsaacGym