1新建工作空间

```
mkdir -p ~/catkin_ws/src
cd ~/catkin_ws/
catkin make
```

2新建功能包

```
cd ~/catkin_ws/src
# catkin_create_pkg 功能包名 [依赖功能包1] [依赖功能包2]...
catkin_create_pkg msgtest std_msgs roscpp
```

3新建msg文件

```
cd ~/catkin_ws/src/msgtest/
mkdir msg
cd msg/
vim msgl.msg

在msgl.msg中写入以下内容:
int32 num
string str
```

4 新建发布文件pub.cpp

```
cd ~/catkin ws/src/msgtest/src
vim pub.cpp
写入以下内容:
#include "ros/ros.h"
// msgtest是功能包名, msg1是msg文件名,编译成功后会在devel/include自动生成一个头文件
#include "msgtest/msg1.h"
int main(int argc, char **argv)
ros::init(argc, argv, "msgpub"); // msgpub为节点的名字
// 创建一个句柄
  ros::NodeHandle n;
 // 新建一个pub对象,<>中是自定义的msg文件,pub_msg为topic的名字
  ros::Publisher msg pub = n.advertise<msgtest::msg1>("mymsg", 1000);
// 发送频率
  ros::Rate loop_rate(10);
  while (ros::ok())
 // 自定义的msg类的一个新变量,并赋值
    msgtest::msg1 msg;
    msg.num = 1024;
 msq.str = "hello slam";
 // 发送msg
    msg pub.publish(msg);
 //ROS的printf
    ROS INFO("Publish : number = %d string = %s", msg.num, msg.str.c_str());
 //循环刷新
    ros::spinOnce();
    loop rate.sleep();
 }
 return 0;
```

5 新建订阅文件sub.cpp

```
cd ~/catkin_ws/src/msgtest/src
vim sub.cpp
```

```
写入以下内容:
```

```
#include "ros/ros.h"
#include "msgtest/msg1.h"
// 回调函数
void chatterCallback(const msgtest::msg1::ConstPtr& msg)
 ROS INFO("I heard: [num = %d, string = %s]", msg->num, msg->str.c str());
int main(int argc, char **argv)
 ros::init(argc, argv, "msgsub");
 ros::NodeHandle n;
 //新建一个sub, chatterCallback是回调函数名
 ros::Subscriber sub = n.subscribe("mymsg", 1000, chatterCallback);
 ros::spin();
 return 0;
6修改配置文件
CMakelists.txt
cd ~/catkin_ws/src/msgtest/
vim CMakeLists.txt
在文件中第13行处添加上message_generation:
find_package(catkin REQUIRED COMPONENTS
 std msgs
roscpp
 message generation
将50行处注释取消掉, 并且按照下面代码修改:
add message files (
  FILES
  msg1.msg
将70行处注释取消掉,如下:
generate messages (
  DEPENDENCIES
  std_msgs
在文件最后添加如下代码:
# msgpub是自定义节点名, pub.cpp是文件名
add executable (msgpub src/pub.cpp)
# msqpub是节点名
target link libraries(msgpub ${catkin LIBRARIES})
# msgsub是自定义节点名, sub.cpp是文件名
add_executable(msgsub src/sub.cpp)
# msgsub是节点名
target_link_libraries(msgsub ${catkin_LIBRARIES})
package.xml
cd ~/catkin ws/src/msgtest/
vim package.xml
```

<build_depend>message_generation</build_depend>
<exec_depend>message_runtime</exec_depend>

7编译并运行

在58行之后加入:

cd ~/catkin_ws/
catkin_make
roscore

新建一个终端:

source ~/catkin_ws/devel/setup.bash
rosrun msgtest msgpub

再新建一个终端:

source ~/catkin_ws/devel/setup.bash
rosrun msgtest msgsub

大功告成:

```
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
 INFO] [1606984971.146787793]: Publish : number = 1024 string = hello slam
        [1606984971.246788215]: Publish : number = 1024 string = hello slam
        [1606984971.346782853]: Publish : number = 1024 string = hello slam
        [1606984971.446792779]: Publish:
                                             number = 1024 string = hello slam
                                            number = 1024 string = hello slam
        [1606984971.546784079]: Publish
                                           : number = 1024 string = hello slam
        [1606984971.646887889]: Publish
                                           : number = 1024 string = hello slam
        [1606984971.746790472]: Publish
  INFO] [1606984971.846786301]: Publish : number = 1024 string = hello slam
  INFO] [1606984971.946786187]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.046781696]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.146758533]: Publish : number = 1024 string = hello slam INFO] [1606984972.246793186]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.346784337]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.446791885]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.546783268]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.646785583]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.746780428]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.846780763]: Publish : number = 1024 string = hello slam
 INFO] [1606984972.946781186]: Publish : number = 1024 string = hello slam
 INFO] [1606984973.046864102]: Publish : number = 1024 string = hello slam
 INFO] [1606984973.146863752]: Publish : number = 1024 string = hello slam
 INFO] [1606984973.246688077]: Publish : number = 1024 string = hello slam
  INFO] [1606984973.346734653]: Publish : number = 1024 string = hello slam
                                                                                 wade@wade-Ubuntu: ~
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[ INFO] [1606984971.147162979]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.247153446]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.347154801]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.447163682]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.547157353]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.647256255]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.747163412]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.847130059]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984971.947164551]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984972.047176974]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984972.147003648]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.247125228]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.347155818]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.447159108]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.547155731]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.647142171]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.747125302]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.847148404]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984972.947133118]: I heard: [num = 1024, string = hello slam]
  INFO] [1606984973.047214303]: I heard: [num = 1024, string = hello slam]
 INFO] [1606984973.147249298]: I heard: [num = 1024, string = hello slam] INFO] [1606984973.246890657]: I heard: [num = 1024, string = hello slam] INFO] [1606984973.346954078]: I heard: [num = 1024, string = hello slam]
                                                              https://blog.csdn.net/whatiscode
```