$\leq |S|$ for every $S \subseteq V(G)$. corollary 1 (Peterson 1891) Every 3-regular graph with no cut-edge has a 1-factor. **definition 1** $defect_G = \max_{S \subset V(G)} o(G - S) - |S|$ theorem 1.2 (Berge-Tutte Formula, Berge 1958). The maximum number of vertices saturated by a matching in G is n(G) -defect G = n(G) $min \ S \subseteq V(G) \ (n(G) - (o(G-S)-|S|))$ 2 Connectivity **definition 2** A separating set or vertex cut of a graph G is a set S V(G) s.t. G-S has more than one component. **definition 3** The connectivity of G, written $\kappa(G)$, is the minimum size of a vertex set S s.t. G-S is disconnected or has only one vertex. A graph G is k-connected if $\kappa(G) \geq k$, i.e., G-S is connected with at

theorem 1.1 (Tutte 1947). A graph G has a 1-factor \iff o(G-S)

1 matching

s.t. G is k-edge-connected

disjoint u,v-paths in G.

G' is k-connected.

fact 1 Every edge cut is a disconnecting set.

least two vertices for every k-1-vertex set S. **lemma 1** $\kappa(G) = n(G)-1 \iff G \text{ contains } Kn(G), \text{ i.e., every vertex}$ is adjacent to every other vertex. **definition 4** A disconnecting set of edges is a set $F \subseteq E(G)$ s.t. G-Fhas more than one component. **definition 5** A graph is k-edge-connected if every disconnecting set has at least k edges. The edge-connectivity of G, written $\kappa'(G)$, is the

minimum size of a disconnecting set or equivalently, the maximum k

fact 2 Every minimal disconnecting set of edges is an edge cut. **definition 6** $\delta(G) = minimum \ vertex \ degree \ of \ G$ **theorem 2.1** (Whitney 1932). $\kappa(G) \leq \kappa'(G) \leq \delta(G)$ for every graph **theorem 2.2** If G is a 3-regular graph of order more than 2, then $kappa(G) = \kappa'(G).$ definition 7 Two paths are internally disjoint if they do not have common internal vertices. Two x,y-paths are edge-disjoint if they do not share any edges theorem 2.3 (Whitney) A graph G having at least 3 vertices is 2-

connected \iff for every distinct $u,v \in V(G)$ there exist internally

lemma 2 (Expansion Lemma) If G is k-connected, and G' is obtained

from G by adding a new vertex y with at least k neighbors in G, then

theorem 2.4 For a graph G of order at least 3, the following condi-

tions are equivalent and characterize 2-connected graphs.

every edge appears in exactly one subgraph in the list.

• G is connected and has no cut-vertex. • For all $x,y \in V(G)$ there are internally disjoint x,y-paths. • For all $x,y \in V(G)$ there is a cycle through x and y. • $\delta(G) \geq 1$ and every pair of edges in G lies on a common cycle.

definition 8 A subdivision of an edge e = xy is a replacement of ewith path x, z, y where z is a new vertex. **corollary 2** If G is 2-connected, then the graph G' obtained by sub-

division of an edge e = xy of G is 2-connected. **definition 9** An ear of a graph G is a nontrivial path in G whose endpoints have degree at least 3 and all its internal vertices have degree 2. **definition 10** A decomposition of a graph is a list of subgraphs s.t.

P0,...,Pk s.t. P0 is a cycle of length at least 3 and Pi for $i \in [k]$ is an ear of $P0 \cup \cdots \cup Pi$ **theorem 2.5** (Whitney) A graph G is 2-connected \iff it has a near decomposition. Furthermore, every cycle of length at least 3 in a 2-connected graph G is the initial cycle in some ear decomposition. **definition 12** Given $x,y \in V(G)$, a set $S \subseteq V(G) - \{x,y\}$ is an x,yseparator or x,y-cut if G-S has no x,y-path. **definition 13** $\kappa(x,y)$: the minimum size of an x,y-cut. $\lambda(x,y)$:

definition 11 An ear decomposition of G is a decomposition

 $\kappa(x,y) = \lambda(x,y).$ **theorem 2.6** (Menger's Theorem for vertex) If x,y are nonadjacent vertices of a graph G, then $\kappa(x,y) = \lambda(x,y)$. **lemma 3** x,y are nonadjacent vertices. There are some k internally disjoint x,y-paths, and removing some k vertices disconnects x from

y. Then $\kappa(x,y) = \lambda(x,y) = k$.

the maximum size of a set of pairwise internally disjoint x,y-paths.

augmenting path is a s,t-path P in the underlying graph G s.t. for each $e \in E(P)$ 1. if P follows e in the forward direction, then f(e)< c(e) 2. if P follows e in the backward direction, then 0 < f(e) Let $\epsilon(e) = c(e)$ -f(e) when e is forward on P, and let $\epsilon(e) = f(e)$ when e is backward on P. The tolerance of P is $min_{e \in E(P)} \epsilon(e)$.

lemma 9 If P is an f-augmenting path with tolerance z, then chang-

ing flow by +z on edges followed forward by P and by -z on edges fol-

lowed backward on P produces a feasible flow f' with val(f')=val(f)+z.

definition 17 In a network, a s/t cut [S, T] consists of the edges from

a source set S to a sink set T, where S,T partition the set of vertices

with $s \in S, t \in T$. The capacity of the cut [S,T], written cap(S,T), is

the total of the capacities on the edges with tail in S and head in T.

definition 18 • net flow out of $U:=sum\ of\ net\ flow\ from\ vertices$

definition 14 Given $x,y \in V(G)$ $\kappa'(x,y)$: the minimum number of

edges whose deletion makes y unreachable from $x \lambda'(x,y)$: the maxi-

mum size of a set of pairwise edge-disjoint x,y-paths Clearly $\kappa'(x,y)$

lemma 4 x,y are distinct vertices. There are some k pairwise edgedisjoint x,y-paths, and removing some k edges disconnects x from y.

lemma 5 $\kappa'(G) = minx, y \lambda'(x,y)$. Equivalently, for every $k \in [n(G)]$

- 1/, G is k-edge-connected $\iff \lambda'(x,y) \geq k$ for every distinct $x,y \in$

theorem 2.7 (Menger's Theorem for edge) If x,y are distinct vertices

lemma 6 Deletion of an edge reduces connectivity $\kappa(G)$ by at most

lemma 7 $\kappa(G) = \min\{n(G)-1, \min x, y \mid \lambda(x,y)\}$. Equivalently, for ev-

ery $k \in [n(G) - 1]$, G is k-connected $\iff \lambda(x,y) \geq k$ for every

definition 15 Given a set U of vertices and a vertex $x \notin U$, an x, U-

fan is a set of paths from x to U s.t. any two of them share only the

lemma 8 (Fan Lemma, Dirac 1960) A graph G is k-connected \iff

it has at least k+1 vertices and, for every choice of x, U with $|U| \ge$

definition 16 When f is a feasible flow in a network N, an f-

• $U:=sum\ of\ net\ flow\ from\ vertices\ not\ in\ U\ to\ vertices\ in\ U.$ **lemma 10** If f is a feasible flow and [S,T] is an s/t cut, then the net flow out of S and net flow into T equal val(f). corollary 3 (Weak duality, Max-Flow Min-Cut inequality) If f is a feasible flow and [S,T] is an s/t cut, then $val(f) \leq cap(S,T)$. Thus $max_f val(f) \le min_{[S,T]} cap(S,T).$

corollary 4 If there is a flow f and an s/t cut [S,T] s.t.

cap(S,T)=val(f), then f is a maximum flow and [S,T] is a minimum

1956) In every network N, the maximum value of a feasible flow

theorem 2.9 (IntegrityTheorem) If all capacities in a network are

integers, then there is a maximum flow f assigning integral flow to

every edge. Furthermore, f can be partitioned into flows of unit value a

in U to vertices not in U. net flow into

equals the minimum value of a s/tcut.

If there is a flow f and an s/t cut [S,T] s.t. cap(S,T) = val(f), then f is a maximum flow and [S,T] is a minimum s/t cut. theorem 2.8 (Max-FlowMin-Cut Theorem, Ford and Fulkerson

lemma 11 The maximum flow in N found by Ford-Fulkerson or Edmonds-Karp algorithm corresponds to a maximum matching in G. **theorem 2.10** (Menger's Theorem for edge in digraphs). If s,t are

 $\geq \lambda'(x,y)$

In fact, $\kappa'(x,y) = \lambda'(x,y)$

Then $\kappa'(x,y) = \lambda'(x,y) = k$.

 $distinct \ x,y \in V(G).$

k, it has an x, U-fan of size k.

of a graph G, then $\kappa'(x,y) = \lambda'(x,y)$.

vertices of a digraph D, then $\kappa'(s,t) = \lambda'(s,t)$. **theorem 2.11** (Menger's Theorem for vertex in digraphs). If s,t are

nonadjacent vertices of a digraph D, then $\kappa(s,t) = \lambda(s,t)$. 3 Planar graph

long paths from s to t.

common endpoint is a crossing.

definition 19 A curve is the image of a continuous map from [0,1] to R^2 . A polygonal curve is a curve composed of finitely many line

For nonadjacent vertices x,y, clearly $\kappa(x,y) \geq \lambda(x,y)$ In fact, segments. It is a polygonal u,v-curve when it starts at u and ends at **definition 20** A drawing of a graph G is a function f defined on $V(G)\cup E(G)$ that assigns each vertex v a point f(v) in the plane and assigns each edge with endpoints u,v a polygonal f(u),f(v)-curve. The

images of vertices are distinct. A point in $f(e) \cap f(e')$ that is not a

definition 21 A graph is planar if it has a drawing without crossings. Such a drawing is a planar embedding of G. A plane graph is a particular planar embedding of a planar graph. A curve is closed if its first and last points are the same. It is simple if it has no repeated points except possibly first=last. An open set in the plane is a set $U \subseteq R2$ s.t. for every $p \in U$, all points within some small distance from p belong to U. A region is an open set U that contains a polygonal u,v-curve for every pair of $u,v \in U$. The faces of a plane graph are the maximal regions of the plane that contain no point used in the embedding. The length l(F) of a face F in a plane graph G is the total length of the closed walk(s) in G bounding the face F. theorem 3.1 (RestrictedJordanCurveTheorem) A simple closed polygonal curve C consisting of finitely many segments partitions the plane into exactly two faces, each having C as boundary.

proposition 1 If l(Fi) denotes the length of face Fi in a plane graph G, then $\sum_{i} l(F_i) = 2e(G)$ theorem 3.2 (Euler1758) If a connected plane graph G has exactly $n \ vertices, e \ edges, and f faces, then n-e+f=2.$ **corollary 5** All planar embeddings of a connected planar graph G have the same number of faces. **theorem 3.3** If G is a simple planar graph with at least 3 vertices, then $e(G) \le 3n(G)$ -6. Also if G is triangle-free, then $e(G) \le 2n(G)$ -4. **corollary 6** Every simple planar graph G has $\delta(G) \leq 5$ **lemma 12** A graph embeds in the plane \iff it embeds on a sphere. definition 22 Informally, a regular polyhedron is a solid whose boundary consists of regular polygons of the same length k, with the same number of faces d meeting at each vertex. A Platonic solid is a convex regular polyhedron. corollary 7 There are at most 5 platonic solids. **definition 23** A maximal planar graph G is a simple planar graph s.t. adding any non-loop edge not parallel to any edge of G results in a nonplanar graph. A triangulation is a simple plane graph where every face boundary is a 3-cycle. **proposition 2** Let $n \ge 3$. For a simple n-vertex plane graph G, the following are equivalent. (A)G has 3n-6 edges. (B)G is a triangulation. (C)G is a maximal plane graph.

proposition 3 If a graph G has a subgraph that is a subdivision of K5 or K3,3, then G is not planar. corollary 8 Petersen graph is not planar. theorem 3.4 (Kuratowski 1930) A graph is planar ⇐⇒ it does not contain a subdivision of K5 nor K3,3 **definition 25** A graph H is a minor of a graph G if H can be obtained from G by a sequence of these operations in any order: 1. deleting an edge 2. contracting an edge

theorem 3.5 (Wagner's Theorem) A graph G is planar \iff it does

definition 26 A graph is outerplanar if it has an embedding with

every vertex on the boundary of the unbounded face. An outerplane

definition 24 A subdivision of an edge e = xy is a replacement of e

A graph H is a subdivision of a graph G if H can be obtained from

with path x,z,y where z is a new vertex.

G by a sequence of subdivisions of edges.

not contain K5 nor K3.3 as minors.

proposition 5 $\chi(G) \leq \Delta(G) + 1$

chromatic triangle-free graph G.

fact 3 Subdividing edges does not affect planarity.

graph is such an embedding of an outerplanar graph. **theorem 3.6** A graph G is outerplanar \iff G does not contain subdivisions of K4 nor K2,3. 4 Coloring

definition 27 $\alpha(G)$: maximum size of independent set $\alpha'(G)$: maximum size of matching $\beta(G)$: minimum size of vertex cover $\beta'(G)$: minimum size of edge cover **proposition 4** $\chi(G) \ge \max\{\omega(G), \frac{n(G)}{\alpha(G)}\}\$

 $G, \delta(H) \leq k, i.e., every subgraph of G has a vertex with degree at$ **proposition 6** A graph G is k-degenerate $\iff V(G)$ can be ordered v1, v2, ..., vn s.t. for every $i \in \{2, 3, ..., n\}$ vertex vi has at most kneighbors in $\{v1, v2, ..., vi-1\}$. **proposition 7** Every k-degenerate graph G is k+1-colorable. **corollary 9** Every planar graph G is 6-colorable.

definition 28 A graph G is k-degenerate if for every subgraph H of

clique or an odd cycle, then $\chi(G) \leq \Delta(G)$ theorem 4.3 (Appel-Haken-Koch 1977) Every planar graph is 4colorable.**definition 29** A k-edge-coloring of G is a labeling $f: E(G) \to [k]$. The labels are colors. The edges of one color form a color class. A k-edge-coloring is proper if incident edges have different labels; that is, if each color class is a matching. A graph is k-edge-colorable if it

has a proper k-edge-coloring. The edge-chromatic number $\chi'(G)$ of a

loopless graph G is the least k such that G is k-edge-colorable. G is

theorem 4.2 (Brooks 1941) If G is a connected graph other than a

k-edge-chromatic $\iff \chi'(G) = k$. Loops are excluded because they are incident to themselves. However, we allow multiple edges and they affect edge-coloring. proposition 8 $\chi'(G) \geq \Delta(G)$ $\chi'(G) \leq 2\Delta(G) - 1$ **theorem 4.4** The Petersen graph is not 3-edge-colorable. Thus, it

is 4-edge-chromatic. **theorem 4.5** (Konig 1916) If G is bipartite, then $\chi'(G) = \Delta(G)$ Hamiltonian cycle **definition 30** c(G) = number of components of G.**proposition 9** If G is Hamiltonian, then $c(G - S) \leq |S|$ for all $\emptyset \neq$ $S \subseteq V(G)$. **corollary 10** Every Hamiltonian graph is 2-connected.

 $3,\delta(G) \geq n/2$, then G is Hamiltonian. **lemma 13** (Ore 1960) Let G be a simple graph. If x, y are distinct nonadjacent vertices of G with $deg(x) + deg(y) \ge n(G)$, then G is $Hamiltonian \iff G + xy \text{ is } Hamiltonian.$ **corollary 11** Let G be a simple graph. If deg(u)+deg(v) > n(G) for

every nonadjacent vertices u,v, then G is Hamiltonian.

theorem 5.1 (Dirac 1952) If G is a simple n-vertex graph with $n \ge$

is at least n(G), until no such pair remains. theorem 5.2 (Bondy-Chvatal 1976) A simple n-vertex graph is $Hamiltonian \iff its \ closure \ is \ Hamiltonian.$ lemma 14 The closure of G is well-defined, i.e., the order in which to add edges does not affect the resulting graph. theorem 5.3 Petersen's graph is not Hamiltonian. **6 HW hw 1** *problem* 1:

Prove that graph G shown below is not Hamiltonian by finding a

definition 31 The Hamiltonian closure of a graph G, denoted C(G),

is the graph with vertex set V(G) obtained from G by iteratively

adding edges joining pairs of nonadjacent vertices whose degree sum

nonempty $S \in V(G)$ such that c(G - S) > |S|.



induct on n(G). sol:Prove by induction on n(G). For n(G) = 1, the statement holds because $\chi(G) = \chi(G) = 1$.

Suppose that n(G) = k > 1. Consider an arbitrary vertex $v \in$

V(G). We have $|N_G(v)| + |N_{\overline{G}}(v)| = k - 1$. By inductive hypothesis,

 $\chi(G-v) \leq |N_G(v)|$ and $\chi(G-v) \leq |N_{\overline{G}}(v)|$, implying $\chi(G-v) +$ $\chi(\overline{G-v}) \leq |N_G(v)| + |N_{\overline{G}}(v)| = k-1$, a contradiction. Without loss of generality assume that $\chi(G-v) > |N_G(v)|$. We can then extend an

Case 2: If $\chi(G-v) + \chi(\overline{G-v}) < k$, then we extend an optimal

theorem 4.1 (Mycielski's construction) From a k-chromatic

when any k - 2 edges are deleted. Prove that G has a 1-factor.

hw 2 Let G be a k-regular graph of even order that remains connected

triangle-free graph G, Mycielski's construction produces a k+1-

coloring of G - v to a coloring of G by coloring v with a new color, and extend an optimal coloring of $\overline{G-v}$ to a coloring of G by coloring v with a new color. Thus $\chi(G) + \chi(\overline{G}) \leq 1 + 1 + k - 1 = k + 1$.

We find that for $S = \{1, 3, 5\}, c(G-S) = 5 > |S| = 3$. Thus G is not Hamiltonian.

problem 2:

Graph G is simple. Prove that $\chi(G) + \chi(G) \leq n(G) + 1$. Hint:

 $\chi(G-v) + \chi(\overline{G-v}) \le k.$ Case 1: If $\chi(G-v) + \chi(\overline{G-v}) = k > k-1$, then either $\chi(G-v) > k$

 $|N_G(v)|$ or $\chi(\overline{G-v}) > |N_{\overline{G}}(v)|$. This is because otherwise we have

optimal coloring f' of G-v to an optimal coloring f of G by coloring v with some color in $[\chi(G-v)]$ not used by any neighbor of v in G, which exists because $\chi(G-v) > |N_G(v)|$. Thus $\chi(G) = \chi(G-v)$, and $\chi(G) + \chi(\overline{G}) \le \chi(G - v) + \chi(\overline{G - v}) + 1 \le k + 1$.