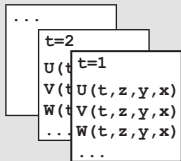
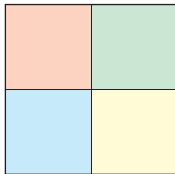


流场数据
(定常/非定常)
Flow Data
(Steady/Unsteady)

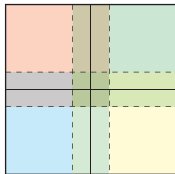


初始化 Initialization

初始数据划分
Initial Data Domain
Partitioning

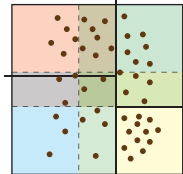


允许数据重叠下的
块扩展
Block Expansion with
Data Overlapping



负载均衡的计算 Load-Balanced Computation

集合性粒子重分配
Collective Particle
Redistribution



自主性粒子追踪
Independent
Particle Tracing

