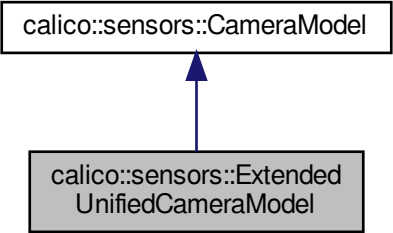


calico::sensors::CameraModel



```
graph BT; A[calico::sensors::Unified CameraModel] --> B[calico::sensors::CameraModel]
```

calico::sensors::Unified
CameraModel