

Fair k -Center Clustering for Data Summarization

Matthäus Kleindessner¹ Pranjal Awasthi¹ Jamie Morgenstern²

Abstract

In data summarization we want to choose k prototypes in order to summarize a data set. We study a setting where the data set comprises several demographic groups and we are restricted to choose k_i prototypes belonging to group i . A common approach to the problem without the fairness constraint is to optimize a centroid-based clustering objective such as k -center. A natural extension then is to incorporate the fairness constraint into the clustering problem. Existing algorithms for doing so run in time super-quadratic in the size of the data set, which is in contrast to the standard k -center problem being approximable in linear time. In this paper, we resolve this gap by providing a simple approximation algorithm for the k -center problem under the fairness constraint with running time linear in the size of the data set and k . If the number of demographic groups is small, the approximation guarantee of our algorithm only incurs a constant-factor overhead.

1. Introduction

Machine learning (ML) algorithms have been rapidly adopted in numerous human-centric domains, from personalized advertising to lending to health care. Fast on the heels of this ubiquity have come a whole host of concerning behaviors from these algorithms: facial recognition has higher accuracy on white, male faces (Buolamwini & Gebru, 2017); online advertisements suggesting arrest are shown more frequently to search queries that comprise a name primarily associated with minority groups (Sweeney, 2013); and criminal recidivism tools are likely to mislabel black low-risk defendants as high-risk while mislabeling white high-risk defendants as low-risk (Angwin et al., 2016). There are also several examples of unsavory ML behavior pertaining to unsupervised learning tasks, such as gender stereotypes in

word2vec embeddings (Bolukbasi et al., 2016). Most of the academic work on fairness in ML, however, has investigated how to solve classification tasks subject to various constraints on the behavior of a classifier on different demographic groups (e.g., Hardt et al., 2016; Zafar et al., 2017).

This paper adds to the literature on fair methods for unsupervised learning tasks (see Section 4 for related work). We consider the problem of data summarization (Hesabi et al., 2015) through the lens of algorithmic fairness. The goal of data summarization is to output a small but representative subset of a data set. Think of an image database and a user entering a query that is matched by many images. Rather than presenting the user with all matching images, we only want to show a summary. In such an example, a data summary can be quite unfair on a demographic group. Indeed, Google Images has been found to answer the query “CEO” with a much higher fraction of images of men compared to the real-world fraction of male CEOs (Kay et al., 2015).

One approach to the problem of data summarization is provided by centroid-based clustering, such as k -center (formally defined in Section 2) or k -medoid (Hastie et al., 2009, Section 14.3.10; sometimes referred to as k -median). For a centroid-based clustering objective, an optimal clustering of a data set S can be defined by k points $c_1^*, \dots, c_k^* \in S$, called centroids, such that the clusters are formed by assigning every $s \in S$ to its closest centroid. Since the centroids are good representatives of their clusters, the set of centroids can be used as a summary of S . This approach of data summarization via centroid-based clustering is used in numerous domains, for example in text summarization (Moens et al., 1999) or robotics (Girdhar & Dudek, 2012).

If the data set S comprises several demographic groups S_1, \dots, S_m , we may consider c_1^*, \dots, c_k^* to be a fair summary only if the groups are represented fairly: if in the real world 70% of CEOs are male and we want to output ten images for the query “CEO”, then three of the ten images should show women. Formally, this can be encoded with one parameter k_{S_i} for every group S_i . Our goal is then to minimize the clustering objective under the constraint that k_{S_i} many centroids belong to S_i . A constraint of this form can also enforce balanced summaries: even if in the real world there are more male CEOs than female ones, we might want to output an equal number of male and female images

¹Department of Computer Science, Rutgers University, NJ

²College of Computing, Georgia Tech, GA. Correspondence to: Matthäus Kleindessner <matthaeus.kleindessner@rutgers.edu>, Pranjal Awasthi <pranjal.awasthi@rutgers.edu>, Jamie Morgenstern <jamiemmt@cs.gatech.edu>.

to reflect that gender is not definitional to the role of CEO. Centroid-based clustering under such a constraint has been studied in the theoretical computer science literature (see Sections 2 and 4). However, existing approximation algorithms for this problem run in time $\omega(|S|^2)$, while the unconstrained k -center clustering problem can be approximated in time linear in $|S|$. Since data summarization is particularly useful for massive data sets, such a slowdown may be practically prohibitive. The contribution of this paper is to present a simple approximation algorithm for k -center clustering under our fairness constraint with running time only linear in $|S|$ and k . The improved running time comes at the price of a worse guarantee on the approximation factor if the number of demographic groups is large. However, note that in practical situations concerning fairness, the number of groups is often quite small (e.g., when the groups encode gender or race). Furthermore, in our extensive numerical simulations we *never* observed a large approximation factor, even when the number of groups was large (cf. Section 5), indicating the practical usefulness of our algorithm.

Outline of the paper In Section 2, we formally state the k -center and the fair k -center problem. In Section 3, we present our algorithm and provide a sketch of its analysis. The full proofs can be found in Appendix A. We discuss related work in Section 4 and present a number of experiments in Section 5. Further experiments can be found in Appendix B. We conclude with a discussion in Section 6.

Notation For $l \in \mathbb{N}$, we sometimes use $[l] = \{1, \dots, l\}$.

2. Definition of k -Center and Fair k -Center

Let S be a finite data set and $d : S \times S \rightarrow \mathbb{R}_{\geq 0}$ be a metric on S . In particular, we assume d to satisfy the triangle inequality. The standard k -center clustering problem is the minimization problem

$$\underset{C=\{c_1, \dots, c_k\} \subseteq S}{\text{minimize}} \quad \max_{s \in S} d(s, C), \quad (1)$$

where $k \in \mathbb{N}$ is a given parameter and $d(s, C) = \min_{c \in C} d(s, c)$. Here, c_1, \dots, c_k are called centers. Any set of centers defines a clustering of S by assigning every $s \in S$ to its closest center. The k -center problem is NP-hard and is also NP-hard to approximate to a factor better than 2 (Gonzalez, 1985; Vazirani, 2001, Chapter 5). The famous greedy strategy of Gonzalez (1985) is a 2-approximation algorithm with running time $\mathcal{O}(k|S|)$ if we assume that d can be evaluated in constant time (this is the case, e.g., if a problem instance is given via the distance matrix $(d(s, s'))_{s, s' \in S}$). This greedy strategy chooses an arbitrary element of the data set as first center and then iteratively selects the data point with maximum distance to the current set of centers as the next center to be added.

Algorithm 1 Approximation algorithm for (3)

- 1: **Input:** metric $d : S \times S \rightarrow \mathbb{R}_{\geq 0}$; $k \in \mathbb{N}_0$; $C'_0 \subseteq S$
 - 2: **Output:** $C = \{c_1, \dots, c_k\} \subseteq S$
 - 3: set $C = \emptyset$
 - 4: **for** $i = 1$ **to** $i = k$
 - 5: choose $c_i \in \operatorname{argmax}_{s \in S} d(s, C \cup C'_0)$
 - 6: set $C = C \cup \{c_i\}$
 - 7: **return** C
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We consider a fair variant of the k -center problem as described in Section 1. Our variant also allows for the user to specify a subset $C_0 \subseteq S$ that *has to be included* in the set of centers (think of the example of the image database and the case that we always want to show five prespecified images as part of the summary). Assuming that $S = \dot{\cup}_{i=1}^m S_i$, where S_1, \dots, S_m are the m demographic groups, the fair k -center problem can be stated as the minimization problem

$$\underset{\substack{C=\{c_1, \dots, c_k\} \subseteq S: \\ |C \cap S_i|=k_{S_i}, i=1, \dots, m}}{\text{minimize}} \quad \max_{s \in S} d(s, C \cup C_0), \quad (2)$$

where $k_{S_i} \in \mathbb{N}_0$ with $\sum_{i=1}^m k_{S_i} = k$ and $C_0 \subseteq S$ are given. By means of a partition matroid, the fair k -center problem can be phrased as a matroid center problem, for which Chen et al. (2016) provide a 3-approximation algorithm using matroid intersection (e.g., Cook et al., 1998). Chen et al. (2016) do not discuss the running time of their algorithm, but it requires to sort all distances between elements in S and hence has running time at least $\Omega(|S|^2 \log |S|)$. In our experiments in Section 5 we observe a running time in $\Omega(|S|^{5/2})$.

3. A Linear-time Approximation Algorithm

In this section, we present our approximation algorithm for the minimization problem (2). It is a recursive algorithm with respect to the number of groups m . To increase comprehensibility, we first present the case of two groups and then the general case of an arbitrary number of groups.

At several points, we will consider the standard (unfair) k -center problem (1) generalized to the case of initially given centers $C'_0 \subseteq S$, that is

$$\underset{C=\{c_1, \dots, c_k\} \subseteq S}{\text{minimize}} \quad \max_{s \in S} d(s, C \cup C'_0). \quad (3)$$

We can adapt the greedy strategy of Gonzalez (1985) for (1) to problem (3) while maintaining its 2-approximation guarantee. For the sake of completeness, we provide the algorithm as Algorithm 1 and state the following lemma:

Lemma 1. *Algorithm 1 is a 2-approximation algorithm for the unfair k -center problem (3) with running time $\mathcal{O}((k + |C'_0|)|S|)$, assuming d can be evaluated in constant time.*

Algorithm 2 Approximation algorithm for (2) when $m = 2$

- 1: **Input:** metric $d : S \times S \rightarrow \mathbb{R}_{\geq 0}$; $k_{S_1}, k_{S_2} \in \mathbb{N}_0$ with $k_{S_1} + k_{S_2} = k$; $C_0 \subseteq S$; group-membership vector $\in \{1, 2\}^{|S|}$ encoding membership in S_1 or S_2
- 2: **Output:** $C^A = \{c_1^A, \dots, c_k^A\} \subseteq S$
- 3: run Algorithm 1 on S with $k = k_{S_1} + k_{S_2}$ and $C'_0 = C_0$; let $\tilde{C}^A = \{\tilde{c}_1^A, \dots, \tilde{c}_k^A\}$ denote its output
- 4:
- 5: **if** $|\tilde{C}^A \cap S_1| = k_{S_1}$ # implies $|\tilde{C}^A \cap S_2| = k_{S_2}$
- 6: **return** \tilde{C}^A
- 7: # we assume $|\tilde{C}^A \cap S_1| > k_{S_1}$; otherwise we switch the role of S_1 and S_2
- 8: form clusters $L_1, \dots, L_k, L'_1, \dots, L'_{|C_0|}$ by assigning every $s \in S$ to its closest center in $\tilde{C}^A \cup C_0$
- 9: **while** $|\tilde{C}^A \cap S_1| > k_{S_1}$ **and** there exists L_i with center $\tilde{c}_i^A \in S_1$ and $y \in L_i \cap S_2$
- 10: replace center \tilde{c}_i^A with y by setting $\tilde{c}_i^A = y$
- 11:
- 12: **if** $|\tilde{C}^A \cap S_1| = k_{S_1}$ # implies $|\tilde{C}^A \cap S_2| = k_{S_2}$
- 13: **return** \tilde{C}^A
- 14: let $S' = \cup_{i \in [k]: \tilde{c}_i^A \in S_1} L_i$ # we have $S' \subseteq S_1$
- 15: run Algorithm 1 on $S' \cup C'_0$ with $k = k_{S_1}$ and $C'_0 = C_0 \cup (\tilde{C}^A \cap S_2)$; let \hat{C}^A denote its output
- 16: **return** $\hat{C}^A \cup (\tilde{C}^A \cap S_2)$ as well as $(k_{S_2} - |\tilde{C}^A \cap S_2|)$ many arbitrary elements from S_2

A proof of Lemma 1, similar in structure to a proof in Har-Peled (2011, Section 4.2) for the strategy of Gonzalez (1985) for problem (1), can be found in Appendix A.

3.1. Fair k -Center with Two Groups

Assume that $S = S_1 \dot{\cup} S_2$. Our algorithm first runs Algorithm 1 for the unfair problem (3) with $k = k_{S_1} + k_{S_2}$ and $C'_0 = C_0$. If we are lucky and Algorithm 1 picks k_{S_1} many centers from S_1 and k_{S_2} many centers from S_2 , our algorithm terminates. Otherwise, Algorithm 1 picks too many centers from one group, say S_1 , and too few from S_2 . We try to decrease the number of centers in S_1 by replacing any such a center with an element in its cluster belonging to S_2 . Once we have made all such available swaps, the remaining clusters with centers in S_1 are entirely contained within S_1 . We then run Algorithm 1 on these clusters with $k = k_{S_1}$ and the centers from S_2 as well as C_0 as initially given centers, and return both the centers from the recursive call (all in S_1) and those from the initial call and the swapping in S_2 .

This algorithm is formally stated as Algorithm 2. The following theorem states that it is a 5-approximation algorithm and that our analysis is tight—in general, Algorithm 2 does not achieve a better approximation factor.

Theorem 1. *Algorithm 2 is a 5-approximation algorithm for the fair k -center problem (2) with $m = 2$, but not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$. It can be implemented in time $\mathcal{O}((k + |C_0|)|S|)$, assuming d can be evaluated in constant time.*

Proof. Here we only present a sketch of the proof. The full proof can be found in Appendix A. For showing that Algorithm 2 is a 5-approximation algorithm, let r_{fair}^* be the optimal value of (2) and r^* be the optimal value of (3) (for $C'_0 = C_0$). Clearly, $r^* \leq r_{\text{fair}}^*$. Let C^A be the set of centers returned by Algorithm 2. It is clear that C^A comprises k_{S_1} many elements from S_1 and k_{S_2} many elements from S_2 . We need to show that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$ for every $s \in S$. Let \tilde{C}^A be the output of Algorithm 1 when called in Line 3 of Algorithm 2. Since Algorithm 1 is a 2-approximation algorithm for (3) according to Lemma 1, we have $\min_{c \in \tilde{C}^A \cup C_0} d(s, c) \leq 2r^* \leq 2r_{\text{fair}}^*$, $s \in S$. Assume that $|\tilde{C}^A \cap S_1| > k_{S_1}$. It follows from the triangle inequality that after exchanging centers in the while-loop in Line 9 of Algorithm 2 we have $\min_{c \in \tilde{C}^A \cup C_0} d(s, c) \leq 4r_{\text{fair}}^*$, $s \in S$. Assume that still $|\tilde{C}^A \cap S_1| > k_{S_1}$. We only need to show that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$ for $s \in S'$. Let C_{fair}^* be an optimal solution to (2). We split S' into two subsets $S' = S'_a \dot{\cup} S'_b$, where S'_a comprises all $s \in S'$ for which the closest center in $C_{\text{fair}}^* \cup C_0$ is in $S_2 \cup C_0$. Using the triangle inequality we can show that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$, $s \in S'_a$. We partition S'_b into at most k_{S_1} many clusters corresponding to the closest center in C_{fair}^* . Each of these clusters has diameter not greater than $2r_{\text{fair}}^*$. If Algorithm 1 in Line 15 of Algorithm 2 chooses one element from each of these clusters, we immediately have $\min_{c \in C^A \cup C_0} d(s, c) \leq 2r_{\text{fair}}^*$, $s \in S'_b$. Otherwise, Algorithm 1 chooses an element from S'_a or two elements from the same cluster of S'_b . In both cases, it follows from the greedy choice property of Algorithm 1 that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$, $s \in S'_b$.

A family of examples shows that Algorithm 2 is not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$. \square

3.2. Fair k -Center with Arbitrary Number of Groups

The main idea to handle an arbitrary number of groups m is the same as for the case $m = 2$: we first run Algorithm 1. We then exchange centers for elements in their clusters in such a way that the number of centers from a group S_i comes closer to k_{S_i} , which is the requested number of centers from S_i . If via exchanging centers we can actually hit k_{S_i} for every group S_i , we are done. Otherwise, we wish that, when no more exchanging is possible, we are left with a subset $S' \subseteq S$ that only comprises elements from $m - 1$ or fewer groups. Denote the set of these groups by \mathcal{G} . We also wish that for those groups not in \mathcal{G} we have picked only the requested number of centers or fewer and we can consider the groups not in \mathcal{G} to have been “resolved”. If both are true,

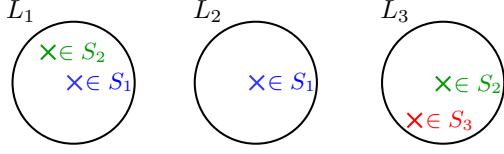


Figure 1. An example illustrating the need for a more sophisticated procedure for exchanging centers in the case of three or more groups compared to the case of only two groups: we would like to exchange a center from S_1 for an element from S_3 , but cannot do that directly. Rather, we have to make a series of exchanges.

we can recursively apply our algorithm to S' and a smaller number of groups. We might recurse down to the case of only one group, which we can solve with Algorithm 1.

The difficulty with this idea comes from the exchanging process. Formally, we are given k centers $\tilde{c}_1^A, \dots, \tilde{c}_k^A$ and the corresponding clustering $S \setminus S_{C_0} = \bigcup_{i=1}^k L_i$, where $S_{C_0} = \bigcup_{i=1}^{|C_0|} L'_i$ is the union of clusters with a center in C_0 , and we want to exchange some centers \tilde{c}_i^A for an element in their cluster L_i such that there exists a strict subset of groups $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$ with the following properties:

$$\bigcup_{i \in [k]: \tilde{c}_i^A \text{ is from a group in } \mathcal{G}} L_i \subseteq \bigcup_{S_i \in \mathcal{G}} S_i, \quad (4)$$

$$\forall S_j \in \{S_1, \dots, S_m\} \setminus \mathcal{G}: \sum_{i=1}^k \mathbb{1}\{\tilde{c}_i^A \in S_j\} \leq k_{S_j}. \quad (5)$$

While in the case of only two groups this can easily be achieved by exchanging centers from the group that has more than the requested number of centers for elements from the other group, as we do in Algorithm 2, it is not immediately clear how to deal with a situation as shown in Figure 1. There are three groups S_1, S_2, S_3 (elements of these groups are shown in blue, green, and red, respectively), and we have $k_{S_1} = k_{S_2} = k_{S_3} = 1$. For the current set of centers (elements at the centers of the circles) there does not exist $\mathcal{G} \subsetneq \{S_1, S_2, S_3\}$ satisfying (4) and (5). We would like to decrease the number of centers in S_1 and increase the number of centers in S_3 , but the clusters with a center in S_1 do not comprise an element from S_3 . Hence, we cannot directly exchange a center from S_1 for an element in S_3 . Rather, we first have to exchange a center from S_1 for an element in S_2 (although this increases the number of centers from S_2 over k_{S_2}) and then a center from S_2 for an element in S_3 . An algorithm that can deal with such a situation is Algorithm 3. It exchanges some centers for an element in their cluster L_i and yields $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$ that provably satisfies (4) and (5), as stated by the following lemma. Its proof can be found in Appendix A.

Lemma 2. *Algorithm 3 is well-defined, it terminates, and exchanges centers in such a way that the set \mathcal{G} that it returns satisfies $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$ and properties (4) and (5).*

Algorithm 3 Algorithm for exchanging centers & finding \mathcal{G}

- 1: **Input:** centers $\tilde{c}_1^A, \dots, \tilde{c}_k^A$ and the corresponding clustering $S \setminus S_{C_0} = \bigcup_{i=1}^k L_i$; $k_{S_1}, \dots, k_{S_m} \in \mathbb{N}_0$ with $\sum_{i=1}^m k_{S_i} = k$; group-membership vector $\in \{1, \dots, m\}^{|S \setminus S_{C_0}|}$
- 2: **Output:** $\tilde{c}_1^A, \dots, \tilde{c}_k^A$, where some centers \tilde{c}_i^A have been replaced with an element in L_i , and $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$ satisfying (4) and (5)
- 3: set $\tilde{k}_{S_j} = \sum_{i=1}^k \mathbb{1}\{\tilde{c}_i^A \in S_j\}$ for $S_j \in \{S_1, \dots, S_m\}$
- 4: construct a directed unweighted graph G on $V = \{S_1, \dots, S_m\}$ as follows: we have $S_i \rightarrow S_j$, that is there is a directed edge from S_i to S_j , if and only if there exists L_t with center $\tilde{c}_t^A \in S_i$ and $y \in L_t \cap S_j$
- 5: compute all shortest paths on G
- 6:
- 7: **while** $\tilde{k}_{S_j} \neq k_{S_j}$ for some S_j and there exist S_r, S_s such that $\tilde{k}_{S_r} > k_{S_r}$ and $\tilde{k}_{S_s} < k_{S_s}$ and there exists a shortest path $P = S_{v_0} S_{v_1} \dots S_{v_w}$ with $S_{v_0} = S_r$, $S_{v_w} = S_s$ that connects S_r to S_s in G
- 8: **for** $l = 0, \dots, w - 1$
- 9: find L_t with center $\tilde{c}_t^A \in S_{v_l}$ and $y \in L_t \cap S_{v_{l+1}}$; replace \tilde{c}_t^A with y by setting $\tilde{c}_t^A = y$
- 10: update $\tilde{k}_{S_r} = \tilde{k}_{S_r} - 1$ and $\tilde{k}_{S_s} = \tilde{k}_{S_s} + 1$
- 11: recompute G and all shortest paths on G
- 12:
- 13: **if** $\tilde{k}_{S_j} = k_{S_j}$ for all $S_j \in \{S_1, \dots, S_m\}$
- 14: **return** $\tilde{c}_1^A, \dots, \tilde{c}_k^A$ and $\mathcal{G} = \emptyset$
- 15: **else**
- 16: set $\mathcal{G}' = \{S_j \in \{S_1, \dots, S_m\} : \tilde{k}_{S_j} > k_{S_j}\}$ and $\mathcal{G} = \mathcal{G}' \cup \{S_j \in \{S_1, \dots, S_m\} \setminus \mathcal{G}' : \text{there exists } S_i \in \mathcal{G}' \text{ and a path from } S_i \text{ to } S_j \text{ in } G\}$
- 17: **return** $\tilde{c}_1^A, \dots, \tilde{c}_k^A$ and \mathcal{G}

Observing that the number of iterations of the while-loop in Line 7 is upper-bounded by k as the proof of Lemma 2 shows, that the number of iterations of the for-loop in Line 8 is upper-bounded by m , and that all shortest paths on G can be computed in running time $\mathcal{O}(m^3)$ (Cormen et al., 2009, Chapter 25), it is not hard to see that Algorithm 3 can be implemented with running time $\mathcal{O}(km|S| + km^3)$.

Using Algorithm 3, it is straightforward to design a recursive approximation algorithm for the fair k -center problem (2) as outlined at the beginning of Section 3.2. We state the algorithm as Algorithm 4. Applying, by means of induction, a similar technique as in the proof of Theorem 1 to every (recursive) call of Algorithm 4, we can prove the following:

Theorem 2. *Algorithm 4 is a $(3 \cdot 2^{m-1} - 1)$ -approximation algorithm for the fair k -center problem (2) with m groups. It can be implemented in time $\mathcal{O}((|C_0|m + km^2)|S| + km^4)$, assuming d can be evaluated in constant time.*

Algorithm 4 Approximation alg. for (2) for arbitrary m

- 1: **Input:** metric $d : S \times S \rightarrow \mathbb{R}_{\geq 0}$; $k_{S_1}, \dots, k_{S_m} \in \mathbb{N}_0$ with $\sum_{i=1}^m k_{S_i} = k$; $C_0 \subseteq S$; group-membership vector $\in \{1, \dots, m\}^{|S|}$
- 2: **Output:** $C^A = \{c_1^A, \dots, c_k^A\} \subseteq S$
- 3: run Algorithm 1 on S with $k = \sum_{i=1}^m k_{S_i}$ and $C'_0 = C_0$; let $\tilde{C}^A = \{\tilde{c}_1^A, \dots, \tilde{c}_k^A\}$ denote its output
- 4: **if** $m = 1$
- 5: **return** \tilde{C}^A
- 6:
- 7: form clusters $L_1, \dots, L_k, L'_1, \dots, L'_{|C_0|}$ by assigning every $s \in S$ to its closest center in $\tilde{C}^A \cup C_0$
- 8: apply Algorithm 3 to $\tilde{c}_1^A, \dots, \tilde{c}_k^A$ and $\dot{\cup}_{i=1}^k L_i$ in order to exchange some centers \tilde{c}_i^A and obtain $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$
- 9: **if** $\mathcal{G} = \emptyset$
- 10: **return** \tilde{C}^A
- 11:
- 12: let $S' = \cup_{i \in [k]}: \tilde{c}_i^A$ is from a group in \mathcal{G} L_i and $C' = \{\tilde{c}_i^A \in \tilde{C}^A : \tilde{c}_i^A$ is from a group not in $\mathcal{G}\}$; recursively call Algorithm 4, where:
 - $S' \cup C' \cup C_0$ plays the role of S
 - we assign elements in $C' \cup C_0$ to an arbitrary group in \mathcal{G} and hence there are $|\mathcal{G}| < m$ many groups $S_{j_1}, \dots, S_{j_{|\mathcal{G}|}}$
 - the requested numbers of centers are $k_{S_{j_1}}, \dots, k_{S_{j_{|\mathcal{G}|}}}$
 - $C' \cup C_0$ plays the role of initially given centers C_0
 let \hat{C}^R denote its output
- 13: **return** $\hat{C}^R \cup C'$ as well as $(k_{S_j} - |C' \cap S_j|)$ many arbitrary elements from S_j for every group S_j not in \mathcal{G}

It is not clear to us whether our analysis of Algorithm 4 is tight and the approximation factor achieved by Algorithm 4 can indeed be as large as $(3 \cdot 2^{m-1} - 1)$ or whether the dependence on m is actually less severe (compare with Section 5 and Section 6). Although trying hard to find instances for which the approximation factor of Algorithm 4 is large, we never observed a factor greater than 8.

Lemma 3. *Algorithm 4 is not a $(8 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$ for (2) with $m \geq 3$ groups.*

The proofs of Theorem 2 and Lemma 3 are in Appendix A.

4. Related Work

Fairness By now, there is a huge body of work on fairness in machine learning. For a recent paper providing an overview of the literature on fair classification see Donini et al. (2018). Our paper adds to the literature on fair methods

for unsupervised learning tasks (Chierichetti et al., 2017; Celis et al., 2018a;b;c; Samadi et al., 2018; Schmidt et al., 2018). Note that all these papers assume to know which demographic group a data point belongs to just as we do. We discuss the two works most closely related to our paper.

First, Celis et al. (2018b) also deal with the problem of fair data summarization. They study the same fairness constraint as we do, that is the summary must contain k_{S_i} many elements from group S_i . However, while we aim for a *representative* summary, where every data point should be close to at least one center in the summary, Celis et al. aim for a *diverse* summary. Their approach requires the data set S to consist of points in \mathbb{R}^n , and then the diversity of a subset of S is measured by the volume of the parallelepiped that it spans (Kulesza & Taskar, 2012). This summarization objective is different from ours, and in different applications one or the other may be more appropriate. An advantage of our approach is that it only requires access to a metric on the data set rather than feature representations of data points.

The second line of work we discuss centers around the paper of Chierichetti et al. (2017). Their paper proposes a notion of fairness for clustering different from ours. Based on the fairness notion of disparate impact (Feldman et al., 2015) / the $p\%$ -rule (Zafar et al., 2017) for classification, the paper by Chierichetti et al. asks that every group be approximately equally represented in each cluster. In their paper, Chierichetti et al. focus on k -medoid and k -center clustering and the case of two groups. Subsequently, Rösner & Schmidt (2018) study such a fair k -center problem for multiple groups, and Schmidt et al. (2018) build upon the work of Chierichetti et al. to devise algorithms for such a fair k -means problem. Kleindessner et al. (2019) incorporate the fairness notion of Chierichetti et al. into the spectral clustering framework. While we certainly consider the fairness notion of Chierichetti et al. (2017), which can be applied to any kind of clustering, to be meaningful in some scenarios, we believe that in certain applications of centroid-based clustering (such as data summarization) our proposed fairness notion provides a more sensible alternative.

Centroid-based clustering There are many papers proposing heuristics and approximation algorithms for both k -center (e.g., Hochbaum & Shmoys, 1986; Mladenović et al., 2003; Ferone et al., 2017) and k -medoid (e.g., Charikar et al., 2002; Arya et al., 2004; Li & Svensson, 2013) under various assumptions on S and the distance function d . There are also numerous papers on versions with constraints, such as lower or upper bounds on the size of the clusters (Aggarwal et al., 2010; Cygan et al., 2012; Rösner & Schmidt, 2018).

Most important to mention are the works by Hajiaghayi et al. (2010), Krishnaswamy et al. (2011) and Chen et al. (2016). Hajiaghayi et al. are the first that consider our fairness constraint (for two groups) for k -medoid. They present

a local search algorithm and prove it to be a constant-factor approximation algorithm. Their work has been generalized by Krishnaswamy et al., who consider k -medoid under the constraint that the centers have to form an independent set in a given matroid. This kind of constraint contains our fairness constraint as a special case (for an arbitrary number of groups). Krishnaswamy et al. obtain a 16-approximation algorithm for this so-called matroid median problem based on rounding the solution of a linear programming relaxation. Subsequently, Chen et al. study the matroid center problem. Using matroid intersection as black box, they obtain a 3-approximation algorithm. Note that none of Hajiaghayi et al., Krishnaswamy et al. or Chen et al. discuss the running time of their algorithm, except for arguing it to be polynomial (see Section 2). We also mention the works by Chakrabarty & Negahbani (2018), who provide a generalization of the matroid center problem and in doing so recover the result of Chen et al. (2016), and by Kale (2018), who studies the matroid center problem in a streaming setting.

5. Experiments

In this section, we present a number of experiments¹. We begin with a motivating example on a small image data set illustrating that a summary produced by Algorithm 1 (i.e., the standard greedy strategy for the unfair k -center problem) can be quite unfair. We also compare summaries produced by our algorithm to summaries produced by the method of Celis et al. (2018b). We then investigate the approximation factor of our algorithm on several artificial instances with known or computable optimal value of the fair k -center problem (2) and compare our algorithm to the one for the matroid center problem by Chen et al. (2016), both in terms of approximation factor / cost of output and running time. Next, on both synthetic and real data, we compare our algorithm in terms of the cost of its output to two baseline heuristics (with running time linear in $|S|$ and k just as for our algorithm). Finally, we compare our algorithm to Algorithm 1 more systematically. We study the difference in the costs of the outputs of our algorithm and Algorithm 1, a quantity one may refer to as *price of fairness*, and measure how unfair the output of Algorithm 1 can be. In the following, all boxplots show results of 200 runs of an experiment.

5.1. Motivating Example and Comparison with Celis et al. (2018b)

Consider the 14 images² of medical doctors shown in the first row of Figure 2. Assume we want to generate a sum-

¹Python code is available on https://github.com/matthklein/fair_k_center_clustering.

²All images were found on <https://pexels.com>, <https://pixnio.com> or <https://commons.wikimedia.org> and are in the public domain.

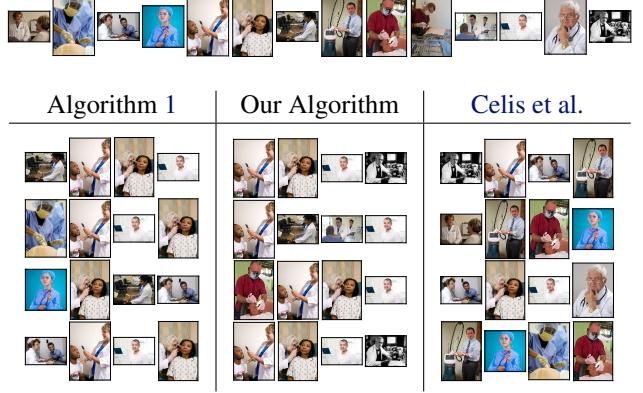


Figure 2. A data set consisting of 14 images of medical doctors (7 female, 7 male) and four summaries computed by the unfair Algorithm 1, our algorithm and the algorithm proposed by Celis et al. (2018b) (all three algorithms are randomized algorithms).

mary of size four of these images. One way to do so is to run Algorithm 1. The first column of the table in Figure 2 shows in each row the summary produced in one run of Algorithm 1 (recall that all algorithms considered here are randomized algorithms). These summaries are quite unfair: although there is an equal number of images of female doctors and images of male doctors, all these summaries show three or even four females. To overcome this bias we can apply our algorithm or the method of Celis et al. (2018b), which both allow us to explicitly state the numbers of females and males that we want in the summary. The second and the third column of the table show summaries produced by these algorithms. It is hard to say which of them produces more useful summaries and the results ultimately depend on the feature representations of the images (see the next paragraph). To provide further illustration, we present a similar experiment in Figure 11 in Appendix B.

For computing feature representations of the images and running the algorithm of Celis et al. we used the code provided by them. The feature vector of an image is a histogram based on the image's SIFT descriptors; see Celis et al. for details. We used the Euclidean metric between these feature vectors as metric d for Algorithm 1 and our algorithm.

5.2. Approximation Factor and Comparison with Chen et al. (2016)

We implemented the algorithm by Chen et al. (2016) using the generic algorithm for matroid intersection provided in SageMath³. To speed up computation, rather than testing all distance values as threshold as suggested by Chen et al., we implemented binary search to look for the optimal value.

In the experiment shown in the left part of Figure 3, we study

³<http://sagemath.org/>

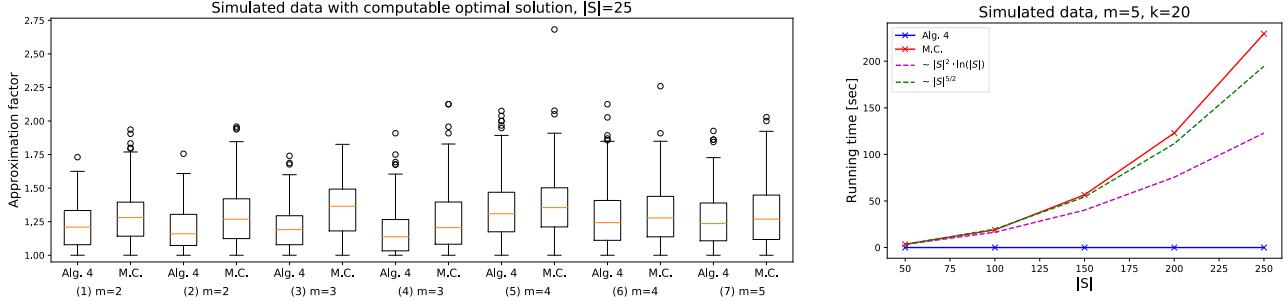


Figure 3. Left: Approx. factor of Alg. 4 and the algorithm by Chen et al. (M.C.) on simulated data with computable optimal solution. $|S| = 25$; various settings with $m \in \{2, 3, 4, 5\}$. (1) $|C_0| = 2, (k_{S_1}, k_{S_2}) = (2, 2)$ (2) $|C_0| = 2, (k_{S_1}, k_{S_2}) = (4, 2)$ (3) $|C_0| = 2, (k_{S_1}, k_{S_2}, k_{S_3}) = (2, 2, 2)$ (4) $|C_0| = 1, (k_{S_1}, k_{S_2}, k_{S_3}) = (5, 1, 1)$ (5) $C_0 = \emptyset, (k_{S_1}, k_{S_2}, k_{S_3}, k_{S_4}) = (2, 2, 2, 2)$ (6) $C_0 = \emptyset, (k_{S_1}, k_{S_2}, k_{S_3}, k_{S_4}) = (3, 3, 1, 1)$ (7) $C_0 = \emptyset, (k_{S_1}, k_{S_2}, k_{S_3}, k_{S_4}, k_{S_5}) = (2, 2, 2, 1, 1)$. **Right:** Running time as a function of $|S|$.

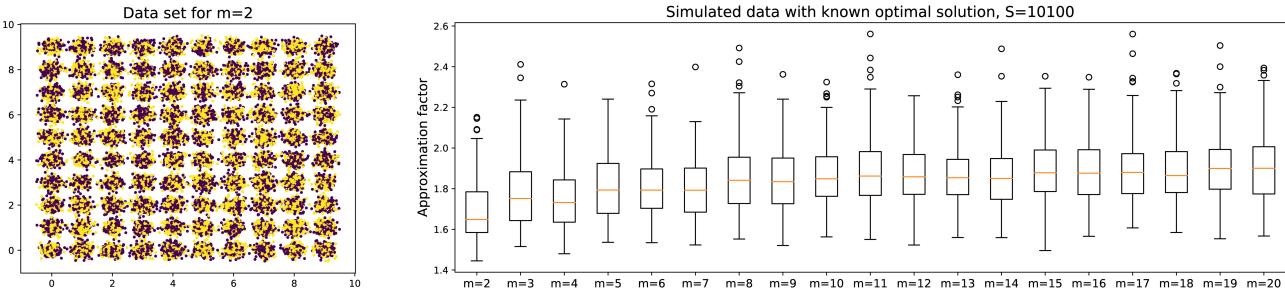


Figure 4. Approximation factor of our algorithm on simulated data with known optimal solution. $|S| = 10100$, $C_0 = \emptyset$, $\sum_{i=1}^m k_{S_i} = 100$. **Left:** Example of the data set when $m = 2$. The optimal solution consists of 100 points located at the centers of the visible clusters and has cost 0.5. **Right:** Approximation factor for $m \in \{2, \dots, 20\}$.

the approximation factor achieved by our algorithm (Alg. 4) and the algorithm by Chen et al. (M.C.) in various settings of values of m , $|C_0|$ and k_{S_i} , $i \in [m]$. The data set S always consists of 25 vertices of a random graph and is small enough to explicitly compute an optimal solution to the fair k -center problem (2). The random graph is constructed according to an Erdős-Rényi model, where any possible edge between two vertices is contained in the graph with probability $2 \log(|S|)/|S|$. With high probability such a graph is connected (if not, we discard it). We put random weights on the edges, drawn from the uniform distribution on $[100]$, and let the metric d be the shortest-path distance on the graph. We assign every vertex to one of m groups uniformly at random and randomly choose a subset $C_0 \subseteq S$ of initially given centers. As we can see from the boxplots, the approximation factor achieved by our algorithm is *never* larger than 2.2. We also see that in each of the seven settings that we consider the median of the achieved approximation factors (indicated by the red lines in the boxes) is smaller for our algorithm than for the algorithm by Chen et al..

In the experiment shown in the right part of Figure 3, we study the running time of the two algorithms as a function of the size of the data set, which is created analogously to the experiment in the left part. We set $m = 5$, $C_0 = \emptyset$

and $k_{S_i} = 4$, $i \in [5]$. The shown curves are obtained from averaging the running times of 200 runs of the experiment (performed on an iMac with 3.4 GHz i5 / 8 GB DDR4). While our algorithm never runs for more than 0.01 seconds, the algorithm by Chen et al., on average, runs for 230 seconds when $|S| = 250$. Its run time grows at least as $|S|^{5/2}$, which proves it to be inappropriate for massive data sets. Boxplots of the costs of the outputs obtained in this experiment are provided in Figure 9 in Appendix B. We can see there that the costs are very similar for the two algorithms.

In the experiment of Figure 4, we once more study the approximation factor achieved by our algorithm. We place 100 optimal centers at $(i, j) \in \mathbb{R}^2$, $i, j \in \{0, \dots, 9\}$, and sample 10000 points around them such that for every center the farthest point in its cluster is at distance 0.5 from the center (Euclidean distance). One such a point set can be seen in the left plot of Figure 4. We randomly assign every point and center to one of m groups and set k_{S_i} to the number of centers that have been assigned to group S_i . We let $C_0 = \emptyset$. For $m \in \{2, \dots, 20\}$, the right part of Figure 4 shows boxplots of the approximation factors for our algorithm. Similarly as before, the approximation factor achieved by our algorithm is *never* larger than 2.6. Most interestingly, the approximation factor increases very moderately with m .

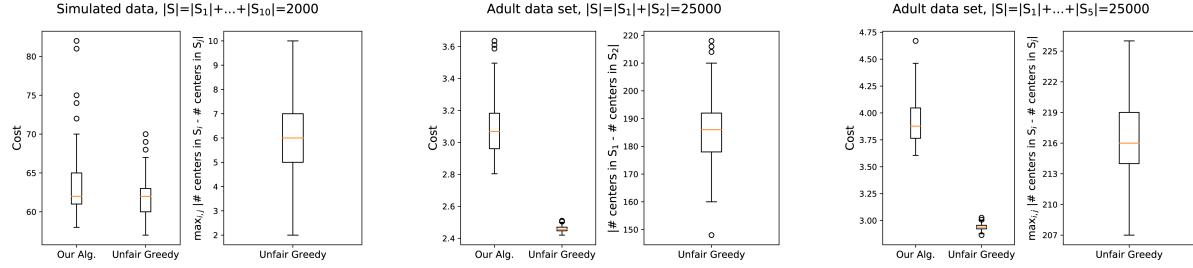


Figure 5. Cost of the output of our algorithm in comparison to the unfair Algorithm 1 and maximum deviation of the numbers of centers in S_i and S_j , $i, j \in [m]$, in the output of Algorithm 1 (it is $k_{S_i} = k_{S_j}$, $i, j \in [m]$). **Left:** $m = 10$. **Middle:** $m = 2$. **Right:** $m = 5$.

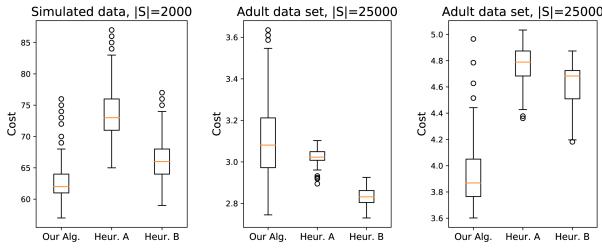


Figure 6. Cost of the output of our algorithm in comparison to two heuristics. **Left:** $m = 10$. **Middle:** $m = 2$. **Right:** $m = 5$.

5.3. Comparison with Baseline Approaches

We compare our algorithm in terms of the cost of an approximate solution to two linear-time baseline heuristics for the fair k -center problem (2). The first one, referred to as Heuristic A, runs Algorithm 1 on each group separately (with $k = k_{S_i}$ and $C'_0 = S_i \cap C_0$ for group S_i) and outputs the union of the centers obtained for the groups. The second one, Heuristic B, greedily chooses centers similarly to Algorithm 1, but only from those groups for which we have not reached the requested number of centers yet. It is easy to see that the approximation factor achieved by these heuristics can be arbitrarily large on some worst-case instances.

Figure 6 shows boxplots of the costs of the approximate solutions returned by our algorithm and the two heuristics for three data sets: the data set in the left plot consists of 2000 vertices of a random graph constructed similarly as in the experiments of Figure 3. We set $m = 10$, $k_{S_i} = 4$, $i \in [10]$, and $|C_0| = 10$. The data set in the middle and in the right plot consists of the first 25000 records of the Adult data set (Dua & Graff, 2019). We only use its six numerical features (e.g., age, hours worked per week), normalized to zero mean and unit variance, for representing records and use the l_1 -distance as metric d . For the experiment shown in the middle plot, we split the data set into two groups according to the sensitive feature gender (#Female=8291, #Male=16709) and set $k_{S_1} = k_{S_2} = 200$. For the experiment shown in the right plot, we split the data set into five groups according to the feature race (#White=21391, #Asian-Pac-Islander=775,

#Amer-Indian-Eskimo=241, #Other=214, #Black=2379) and set $k_{S_i} = 50$, $i \in [5]$. In Figure 10 in Appendix B we present results for other choices of k_{S_i} . We always let C_0 be a randomly chosen subset of size $|C_0| = 100$. The two heuristics perform surprisingly well. Although coming without any worst-case guarantees, the cost of their solutions is comparable to the cost of the output of our algorithm.

5.4. Comparison with Unfair Algorithm 1

We compare the cost of the solution produced by our algorithm to the cost of the (potentially) unfair solution provided by Algorithm 1. Of course, we expect the latter to be lower. We consider the case $k_{S_i} = k_{S_j}$, $i, j \in [m]$, and also examine how balanced the numbers of centers from a group S_i in the output of Algorithm 1 are. Figure 5 shows the results, where the data sets and settings equal the ones in the experiments of Figure 6. Similar experiments with different settings are provided in Figure 12 in Appendix B. Remarkably, the costs of the solutions produced by our algorithm and Algorithm 1 have the same order of magnitude in all experiments, showing that the price of fairness is small. On the other hand, the output of Algorithm 1 can be highly unfair.

6. Discussion

In this work, we considered k -center clustering under a fairness constraint that is motivated by the application of centroid-based clustering for data summarization. We presented a simple approximation algorithm with running time only linear in the size of the data set S and the number of centers k and proved our algorithm to be a 5-approximation algorithm when S consists of two groups. For more than two groups, we proved an upper bound on the approximation factor that increases exponentially with the number of groups. We do not know whether this exponential dependence is necessary or whether our analysis is loose—in our extensive numerical simulations we *never* observed a large approximation factor. Besides answering this question, in future work it would be interesting to extend our results to k -medoid clustering or to characterize properties of data sets that guarantee that fast algorithms find an optimal fair clustering.

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Appendix

A. Proofs

Proof of Lemma 1:

It is straightforward to see that Algorithm 1 can be implemented in time $\mathcal{O}((k + |C'_0|)|S|)$. We only need to show that it is a 2-approximation algorithm for (3).

If $k = 0$, there is nothing to show, so assume that $k \geq 1$. Let $C = \{c_1, \dots, c_k\}$ be the output of Algorithm 1 and $C^* = \{c_1^*, \dots, c_k^*\}$ be an optimal solution to (3) with objective value r^* . Let $s \in S$ be arbitrary. We need to show that $d(s, \hat{c}) \leq 2r^*$ for some $\hat{c} \in C \cup C'_0$. If $s \in C \cup C'_0$, there is nothing to show. So assume $s \notin C \cup C'_0$. If

$$C'_0 \cap \operatorname{argmin}_{c \in C^* \cup C'_0} d(s, c) \neq \emptyset,$$

there exists $\hat{c} \in C'_0$ with $d(s, \hat{c}) \leq r^*$ and we are done. Otherwise, let $c_i^* \in \operatorname{argmin}_{c \in C^* \cup C'_0} d(s, c)$ and hence $d(s, c_i^*) \leq r^*$. We distinguish two cases:

- $\exists c_j \in C$ with $c_i^* \in \operatorname{argmin}_{c \in C^* \cup C'_0} d(c_j, c)$:

We have $d(c_j, c_i^*) \leq r^*$ and hence $d(s, c_j) \leq d(s, c_i^*) + d(c_i^*, c_j) \leq 2r^*$.

- $\nexists c_j \in C$ with $c_i^* \in \operatorname{argmin}_{c \in C^* \cup C'_0} d(c_j, c)$:

There must be $c' \neq c'' \in C \cup C'_0$, where not both c' and c'' can be in C'_0 , and $\hat{c} \in C^* \cup C'_0$ such that

$$\hat{c} \in \operatorname{argmin}_{c \in C^* \cup C'_0} d(c', c) \cap \operatorname{argmin}_{c \in C^* \cup C'_0} d(c'', c).$$

Since $d(c', \hat{c}) \leq r^*$ and $(c'', c^*) \leq r^*$, it follows that $d(c', c'') \leq d(c', \hat{c}) + d(\hat{c}, c'') \leq 2r^*$.

Without loss of generality, assume that in the execution of Algorithm 1, c'' has been added to the set of centers after c' has been added. In particular, we have $c'' \in C$ and $c'' = c_l$ for some $l \in \{1, \dots, k\}$. Due to the greedy choice in Line 5 of the algorithm and since s has not been chosen by the algorithm, we have

$$2r^* \geq d(c', c'') \geq \min_{c \in \{c_1, \dots, c_{l-1}\} \cup C'_0} d(c'', c) \geq \min_{c \in \{c_1, \dots, c_{l-1}\} \cup C'_0} d(s, c).$$

□

Proof of Theorem 1:

Again it is easy to see that Algorithm 2 can be implemented in time $\mathcal{O}((k + |C_0|)|S|)$. We need to prove that it is a 5-approximation algorithm, but not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$:

1. Algorithm 2 is a 5-approximation algorithm:

Let r_{fair}^* be the optimal value of the fair problem (2) and r^* be the optimal value of the unfair problem (3). Clearly, $r^* \leq r_{\text{fair}}^*$. Let $C_{\text{fair}}^* = \{c_1^{(1)*}, \dots, c_{k_{S_1}}^{(1)*}, c_1^{(2)*}, \dots, c_{k_{S_2}}^{(2)*}\}$ with $c_1^{(1)*}, \dots, c_{k_{S_1}}^{(1)*} \in S_1$ and $c_1^{(2)*}, \dots, c_{k_{S_2}}^{(2)*} \in S_2$ be an optimal solution to the fair problem (2) with cost r_{fair}^* and $C^A = \{c_1^A, \dots, c_k^A\}$ be the centers returned by Algorithm 2. It is clear that Algorithm 2 returns k_{S_1} many elements from S_1 and k_{S_2} many elements from S_2 and hence $C^A = \{c_1^{(1)A}, \dots, c_{k_{S_1}}^{(1)A}, c_1^{(2)A}, \dots, c_{k_{S_2}}^{(2)A}\}$ with $c_1^{(1)A}, \dots, c_{k_{S_1}}^{(1)A} \in S_1$ and $c_1^{(2)A}, \dots, c_{k_{S_2}}^{(2)A} \in S_2$. We need to show that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*, \quad s \in S.$$

Let $\tilde{C}^A = \{\tilde{c}_1^A, \dots, \tilde{c}_k^A\}$ be the output of Algorithm 1 when called in Line 3 of Algorithm 2. Since Algorithm 1 is a 2-approximation algorithm for the unfair problem (3) according to Lemma 1, we have

$$\min_{c \in \tilde{C}^A \cup C_0} d(s, c) \leq 2r^* \leq 2r_{\text{fair}}^*, \quad s \in S. \quad (6)$$

If Algorithm 2 returns \tilde{C}^A in Line 6, that is $C^A = \tilde{C}^A$, we are done. Otherwise assume, as in the algorithm, that $|\tilde{C}^A \cap S_1| > k_{S_1}$. Let $\tilde{c}_i^A \in S_1$ be a center of cluster L_i that we replace with $y \in L_i \cap S_2$ and let \hat{y} be an arbitrary element in L_i . Because of (6), we have $d(\tilde{c}_i^A, y) \leq 2r_{\text{fair}}^*$ and $d(\tilde{c}_i^A, \hat{y}) \leq 2r_{\text{fair}}^*$, and hence $d(y, \hat{y}) \leq d(y, \tilde{c}_i^A) + d(\tilde{c}_i^A, \hat{y}) \leq 4r_{\text{fair}}^*$ due to the triangle inequality. Consequently, after the while-loop in Line 9, every $s \in S$ is in distance of $4r_{\text{fair}}^*$ or smaller to the center of its cluster. In particular, we have

$$\min_{c \in \tilde{C}^A \cup C_0} d(s, c) \leq 4r_{\text{fair}}^*, \quad s \in S,$$

and if Algorithm 2 returns \tilde{C}^A in Line 13, we are done. Otherwise, we still have $|\tilde{C}^A \cap S_1| > k_{S_1}$ after exchanging centers in the while-loop in Line 9. Let $S' = \bigcup_{i \in [k]: \tilde{c}_i^A \in S_1} L_i$, that is the union of clusters with a center $\tilde{c}_i^A \in S_1$. Since there is no more center in S_1 that we can exchange for an element in S_2 , we have $S' \subseteq S_1$. Let $S'' = \bigcup_{i \in [k]: \tilde{c}_i^A \in S_2} L_i$ be the union of clusters with a center $\tilde{c}_i^A \in S_2$ and $S_{C_0} = L'_1 \cup \dots \cup L'_{|C_0|}$ be the union of clusters with a center in C_0 . Then we have $S = S' \dot{\cup} S'' \dot{\cup} S_{C_0}$. We have $\tilde{C}^A \cap S_2 \subseteq C^A$ and

$$\min_{c \in C^A \cup C_0} d(s, c) \leq \min_{c \in (\tilde{C}^A \cap S_2) \cup C_0} d(s, c) \leq 4r_{\text{fair}}^*, \quad s \in S'' \cup S_{C_0}. \quad (7)$$

Hence we only need to show that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$ for every $s \in S'$. We split S' into two subsets $S'_a = S'_a \dot{\cup} S'_b$, where

$$S'_a = \left\{ s \in S' : \underset{c \in C_{\text{fair}}^* \cup C_0}{\operatorname{argmin}} d(s, c) \cap (C_0 \cup S_2) \neq \emptyset \right\}$$

and $S'_b = S' \setminus S'_a$. For every $s \in S'_a$ there is $c \in (C_0 \cup S_2) \subseteq (S'' \cup S_{C_0})$ with $d(s, c) \leq r_{\text{fair}}^*$ and it follows from (7) and the triangle inequality that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq \min_{c \in (\tilde{C}^A \cap S_2) \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*, \quad s \in S'_a. \quad (8)$$

It remains to show that $\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*$ for every $s \in S'_b$. For every $s \in S'_b$ there exists $c \in \{c_1^{(1)*}, \dots, c_{k_{S_1}}^{(1)*}\}$ with $d(s, c) \leq r_{\text{fair}}^*$. We can write $S'_b = \bigcup_{j=1}^{k_{S_1}} \{s \in S'_b : d(s, c_j^{(1)*}) \leq r_{\text{fair}}^*\}$ (some of the sets in this union might be empty, but that does not matter). Note that for every $j \in \{1, \dots, k_{S_1}\}$ we have

$$d(s, s') \leq 2r_{\text{fair}}^*, \quad s, s' \in \left\{ s \in S'_b : d(s, c_j^{(1)*}) \leq r_{\text{fair}}^* \right\}, \quad (9)$$

due to the triangle inequality. It is

$$S' = S'_a \cup S'_b = S'_a \cup \bigcup_{j=1}^{k_{S_1}} \left\{ s \in S'_b : d(s, c_j^{(1)*}) \leq r_{\text{fair}}^* \right\}$$

and when, in Line 15 of Algorithm 2, we run Algorithm 1 on $S' \cup C'_0$ with $k = k_{S_1}$ and initial centers $C'_0 = C_0 \cup (\tilde{C}^A \cap S_2)$, one of the following three cases has to happen (we denote the centers returned by Algorithm 1 by $\hat{C}^A = \{c_1^{(1)A}, \dots, c_{k_{S_1}}^{(1)A}\}$):

- For every $j \in \{1, \dots, k_{S_1}\}$ there exists $j' \in \{1, \dots, k_{S_1}\}$ such that $c_{j'}^{(1)A} \in \{s \in S'_b : d(s, c_j^{(1)*}) \leq r_{\text{fair}}^*\}$. In this case it immediately follows from (9) that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq \min_{c \in \hat{C}^A} d(s, c) \leq 2r_{\text{fair}}^*, \quad s \in S'_b.$$

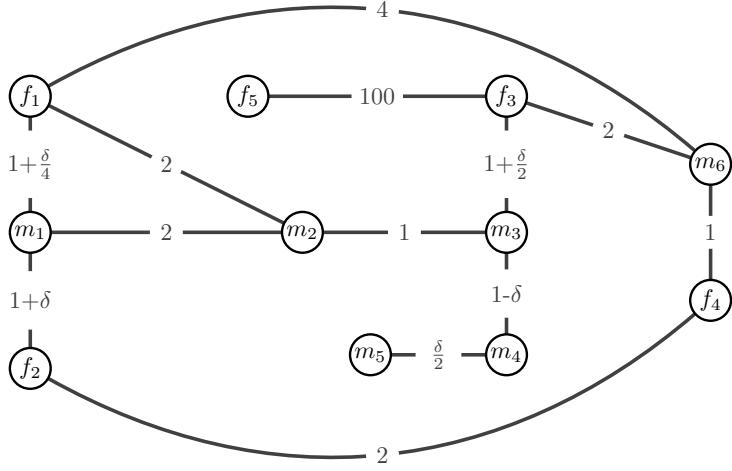


Figure 7. An example showing that Algorithm 2 is not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$.

- There exists $j' \in \{1, \dots, k_{S_1}\}$ such that $c_{j'}^{(1)A} \in S'_a$. When Algorithm 1 picks $c_{j'}^{(1)A}$, any other element in S' cannot be at a larger minimum distance from a center in $(\tilde{C}^A \cap S_2) \cup C_0$ or a previously chosen center in \hat{C}^A than $c_{j'}^{(1)A}$. It follows from (8) that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*, \quad s \in S'.$$

- There exist $j \in \{1, \dots, k_{S_1}\}$ and $j' \neq j'' \in \{1, \dots, k_{S_1}\}$ such that $c_j^{(1)A}, c_{j''}^{(1)A} \in \{s \in S'_b : d(s, c_j^{(1)*}) \leq r_{\text{fair}}^*\}$. Assume that Algorithm 1 picks $c_{j'}^{(1)A}$ before $c_{j''}^{(1)A}$. When Algorithm 1 picks $c_{j''}^{(1)A}$, any other element in S' cannot be at a larger minimum distance from a center in $(\tilde{C}^A \cap S_2) \cup C_0$ or a previously chosen center in \hat{C}^A than $c_{j''}^{(1)A}$. Because of $d(c_{j'}^{(1)A}, c_{j''}^{(1)A}) \leq 2r_{\text{fair}}^*$ according to (9), it follows that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq 2r_{\text{fair}}^*, \quad s \in S'.$$

In all cases we have

$$\min_{c \in C^A \cup C_0} d(s, c) \leq 5r_{\text{fair}}^*, \quad s \in S'_b,$$

which completes the proof of the claim that Algorithm 2 is a 5-approximation algorithm.

2. Algorithm 2 is not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$:

Consider the example given by the weighted graph shown in Figure 7, where $0 < \delta < \frac{1}{10}$. We have $S = S_1 \dot{\cup} S_2$ with $S_1 = \{f_1, f_2, f_3, f_4, f_5\}$ and $S_2 = \{m_1, m_2, m_3, m_4, m_5, m_6\}$. All distances are shortest-path-distances. Let $k_{S_1} = 1$, $k_{S_2} = 3$, and $C_0 = \emptyset$. We assume that Algorithm 1 in Line 3 of Algorithm 2 picks f_5 as first center. It then chooses f_2 as second center, f_3 as third center and f_1 as fourth center. Hence, $\tilde{C}^A = \{f_5, f_2, f_3, f_1\}$ and $|\tilde{C}^A \cap S_1| > k_{S_1}$. The clusters corresponding to \tilde{C}^A are $\{f_5\}$, $\{f_2, f_4\}$, $\{f_3, m_3, m_4, m_5, m_6\}$ and $\{f_1, m_1, m_2\}$. Assume we replace f_3 with m_4 and f_1 with m_2 in Line 10 of Algorithm 2. Then it is still $|\tilde{C}^A \cap S_1| > k_{S_1}$, and in Line 15 of Algorithm 2 we run Algorithm 1 on $\{f_2, f_4, f_5\} \cup \{m_2, m_4\}$ with $k = 1$ and initially given centers $C'_0 = \{m_2, m_4\}$. Algorithm 1 returns $\hat{C}^A = \{f_5\}$. Finally, assume that m_5 is chosen as arbitrary third center from S_2 in Line 16 of Algorithm 2. So the centers returned by Algorithm 2 are $C^A = \{f_5, m_2, m_4, m_5\}$ with a cost of $5 - \frac{\delta}{2}$ (incurred for f_4). However, the optimal solution $C_{\text{fair}}^* = \{f_5, m_1, m_3, m_6\}$ has cost only $1 + \delta$. Choosing δ sufficiently small shows that Algorithm 2 is not a $(5 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$.

□

Proof of Lemma 2:

We want to show three things:

1. Algorithm 3 is well-defined:

If the condition of the while-loop in Line 7 is true, there exists a shortest path $P = S_{v_0} S_{v_1} \cdots S_{v_w}$ with $S_{v_0} = S_r$, $S_{v_w} = S_s$ that connects S_r to S_s in G . Since P is a shortest path, all S_{v_i} are distinct. By the definition of G , for every $l = 0, \dots, w-1$ there exists L_t with center $\tilde{c}_t^A \in S_{v_l}$ and $y \in L_t \cap S_{v_{l+1}}$. Hence, the for-loop in Line 8 is well defined.

2. Algorithm 3 terminates:

Let, at the beginning of the execution of Algorithm 3 in Line 3, $H_1 = \{S_j \in \{S_1, \dots, S_m\} : \tilde{k}_{S_j} = k_{S_j}\}$, $H_2 = \{S_j \in \{S_1, \dots, S_m\} : \tilde{k}_{S_j} > k_{S_j}\}$ and $H_3 = \{S_j \in \{S_1, \dots, S_m\} : \tilde{k}_{S_j} < k_{S_j}\}$. For $S_j \in H_1$, \tilde{k}_{S_j} never changes during the execution of the algorithm. For $S_j \in H_2$, \tilde{k}_{S_j} never increases during the execution of the algorithm and decreases at most until it equals k_{S_j} . For $S_j \in H_3$, \tilde{k}_{S_j} never decreases during the execution of the algorithm and increases at most until it equals k_{S_j} . In every iteration of the while-loop, there is $S_j \in H_3$ for which \tilde{k}_{S_j} increases by one. It follows that the number of iterations of the while-loop is upper-bounded by k .

3. Algorithm 3 exchanges centers in such a way that the set \mathcal{G} that it returns satisfies $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$ and properties (4) and (5):

Note that throughout the execution of Algorithm 3 we have $\tilde{k}_{S_j} = \sum_{i=1}^k \mathbb{1}\{\tilde{c}_i^A \in S_j\}$ for the current centers $\tilde{c}_1^A, \dots, \tilde{c}_k^A$. If the condition of the if-statement in Line 13 is true, then $\mathcal{G} = \emptyset$ and (4) and (5) are satisfied.

Assume that the condition of the if-statement in Line 13 is not true. Clearly, the set \mathcal{G} returned by Algorithm 3 satisfies (5). Since the condition of the if-statement in Line 13 is not true, there exist S_j with $\tilde{k}_{S_j} > k_{S_j}$ and S_i with $\tilde{k}_{S_i} < k_{S_i}$. We have $S_j \in \mathcal{G}$, but since the condition of the while-loop in Line 7 is not true, we cannot have $S_i \in \mathcal{G}$. This shows that $\mathcal{G} \subsetneq \{S_1, \dots, S_m\}$. We need to show that (4) holds. Let L_h be a cluster with center $\tilde{c}_h^A \in S_f$ for some $S_f \in \mathcal{G}$ and assume it contained an element $o \in S_{f'}$ with $S_{f'} \notin \mathcal{G}$. But then we had a path from S_f to $S_{f'}$ in G . If $S_{f'} \in \mathcal{G}'$, this is an immediate contradiction to $S_{f'} \notin \mathcal{G}$. If $S_{f'} \notin \mathcal{G}'$, since $S_f \in \mathcal{G}$, there exists $S_g \in \mathcal{G}'$ such that there is a path from S_g to $S_{f'}$. But then there is also a path from S_g to S_f , which is a contradiction to $S_{f'} \notin \mathcal{G}$.

□

Proof of Theorem 2:

For showing that Algorithm 4 is a $(3 \cdot 2^{m-1} - 1)$ -approximation algorithm let r_{fair}^* be the optimal value of problem (2) and C_{fair}^* be an optimal solution with cost r_{fair}^* . Let C^A be the centers returned by Algorithm 4. A simple proof by induction over m shows that C^A actually comprises k_{S_i} many elements from every group S_i . We need to show that

$$\min_{c \in C^A \cup C_0} d(s, c) \leq (3 \cdot 2^{m-1} - 1)r_{\text{fair}}^*, \quad s \in S. \quad (10)$$

Let T be the total number of calls of Algorithm 4, that is we have one initial call and $T - 1$ recursive calls. Since with each recursive call the number of groups is decreased by at least one, we have $T \leq m$. For $1 \leq j \leq T$, let $S^{(j)}$ be the data set in the j -th call of Algorithm 4. We additionally set $S^{(T+1)} = \emptyset$. We have $S^{(1)} = S$ and $S^{(j)} \supseteq S^{(j+1)}$, $1 \leq j \leq T$. For $1 \leq j < T$, let $\mathcal{G}^{(j)}$ be the set of groups in \mathcal{G} returned by Algorithm 3 in Line 8 in the j -th call of Algorithm 4. If in the T -th call of Algorithm 4 the algorithm terminates from Line 10 (note that in this case we must have $T < m$), we also let $\mathcal{G}^{(T)} = \emptyset$ be the set of groups in \mathcal{G} returned by Algorithm 3 in the T -th call. Otherwise we leave $\mathcal{G}^{(T)}$ undefined. Setting $\mathcal{G}^{(0)} = \{S_1, \dots, S_m\}$, we have $\mathcal{G}^{(j)} \supseteq \mathcal{G}^{(j+1)}$ for all j such that $\mathcal{G}^{(j+1)}$ is defined. For $1 \leq j < T$, let C_j be the set of centers returned by Algorithm 3 in Line 8 in the j -th call of Algorithm 4 that belong to a group not in $\mathcal{G}^{(j)}$ (in Algorithm 4, the set of these centers is denoted by C'). We analogously define C_T if in the T -th call of Algorithm 4 the algorithm terminates from Line 10. Note that the centers in C_j are comprised in the final output C^A of Algorithm 4, that is

$C_j \subseteq C^A$ for $1 \leq j < T$ or $1 \leq j \leq T$. As always, C_0 denotes the set of centers that are given initially (for the initial call of Algorithm 4). Note that in the j -th call of Algorithm 4 the set of initially given centers is $C_0 \cup \bigcup_{l=1}^{j-1} C_l$.

We first prove by induction that for all $j \geq 1$ such that $\mathcal{G}^{(j)}$ is defined, that is $1 \leq j < T$ or $1 \leq j \leq T$, we have

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l} d(s, c) \leq (2^{j+1} + 2^j - 2)r_{\text{fair}}^*, \quad s \in (S^{(j)} \setminus S^{(j+1)}) \cup \left(C_0 \cup \bigcup_{l=1}^j C_l \right). \quad (11)$$

Base case $j = 1$: In the first call of Algorithm 4, Algorithm 1, when called in Line 3 of Algorithm 4, returns an approximate solution to the unfair problem (3). Let $r^* \leq r_{\text{fair}}^*$ be the optimal cost of (3). Since Algorithm 1 is a 2-approximation algorithm for (3) according to Lemma 1, after Line 3 of Algorithm 4 we have

$$\min_{c \in \tilde{C}^A \cup C_0} d(s, c) \leq 2r^* \leq 2r_{\text{fair}}^*, \quad s \in S.$$

Let $\tilde{c}_i^A \in \tilde{C}^A$ be a center and $s_1, s_2 \in L_i$ be two points in its cluster. It follows from the triangle inequality that $d(s_1, s_2) \leq d(s_1, \tilde{c}_i^A) + d(\tilde{c}_i^A, s_2) \leq 4r_{\text{fair}}^*$. Hence, after running Algorithm 3 in Line 8 of Algorithm 4 and exchanging some of the centers in \tilde{C}^A , we have $d(s, c(s)) \leq 4r_{\text{fair}}^*$ for every $s \in S$, where $c(s)$ denotes the center of its cluster. In particular,

$$\min_{c \in C_0 \cup C_1} d(s, c) \leq (2^{1+1} + 2^1 - 2)r_{\text{fair}}^* = 4r_{\text{fair}}^*$$

for all $s \in S$ for which its center $c(s)$ is in C_0 or in a group not in $\mathcal{G}^{(1)}$, that is for $s \in (S^{(1)} \setminus S^{(2)}) \cup (C_0 \cup C_1)$.

Inductive step $j \mapsto j + 1$: Recall property (4) of a set \mathcal{G} returned by Algorithm 3. Consequently, $S^{(j+1)}$ only comprises items in a group in $\mathcal{G}^{(j)}$ and, additionally, the given centers $C_0 \cup \bigcup_{l=1}^j C_l$.

We split $S^{(j+1)}$ into two subsets $S^{(j+1)} = S_a^{(j+1)} \dot{\cup} S_b^{(j+1)}$, where

$$S_a^{(j+1)} = \left\{ s \in S^{(j+1)} : \underset{c \in C_{\text{fair}}^* \cup C_0}{\operatorname{argmin}} d(s, c) \cap \left(C_0 \cup \bigcup_{W \in \{S_1, \dots, S_m\} \setminus \mathcal{G}^{(j)}} W \right) \neq \emptyset \right\}$$

and $S_b^{(j+1)} = S^{(j+1)} \setminus S_a^{(j+1)}$. For every $s \in S_a^{(j+1)}$ there exists

$$c \in C_0 \cup \bigcup_{W \in \{S_1, \dots, S_m\} \setminus \mathcal{G}^{(j)}} W \subseteq (S \setminus S^{(j+1)}) \cup \left(C_0 \cup \bigcup_{l=1}^j C_l \right)$$

with $d(s, c) \leq r_{\text{fair}}^*$. It follows from the inductive hypothesis that there exists $c' \in C_0 \cup \bigcup_{l=1}^j C_l$ with $d(c, c') \leq (2^{j+1} + 2^j - 2)r_{\text{fair}}^*$ and consequently

$$d(s, c') \leq d(s, c) + d(c, c') \leq r_{\text{fair}}^* + (2^{j+1} + 2^j - 2)r_{\text{fair}}^* = (2^{j+1} + 2^j - 1)r_{\text{fair}}^*.$$

Hence,

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l} d(s, c) \leq (2^{j+1} + 2^j - 1)r_{\text{fair}}^*, \quad s \in S_a^{(j+1)}. \quad (12)$$

For every $s \in S_b^{(j+1)}$ there exists $c \in C_{\text{fair}}^* \cap \bigcup_{W \in \mathcal{G}^{(j)}} W$ with $d(s, c) \leq r_{\text{fair}}^*$. Let $C_{\text{fair}}^* \cap \bigcup_{W \in \mathcal{G}^{(j)}} W = \{\tilde{c}_1^*, \dots, \tilde{c}_{\tilde{k}}^*\}$ with $\tilde{k} = \sum_{W \in \mathcal{G}^{(j)}} k_W$, where k_W is the number of requested centers from group W . We can write

$$S_b^{(j+1)} = \bigcup_{l=1}^{\tilde{k}} \left\{ s \in S_b^{(j+1)} : d(s, \tilde{c}_l^*) \leq r_{\text{fair}}^* \right\},$$

where some of the sets in this union might be empty, but that does not matter. Note that for every $l = 1, \dots, \tilde{k}$ we have

$$d(s, s') \leq 2r_{\text{fair}}^*, \quad s, s' \in \left\{ s \in S_b^{(j+1)} : d(s, \tilde{c}_l^*) \leq r_{\text{fair}}^* \right\} \quad (13)$$

due to the triangle inequality. It is

$$S^{(j+1)} = S_a^{(j+1)} \cup S_b^{(j+1)} = S_a^{(j+1)} \cup \bigcup_{l=1}^{\tilde{k}} \left\{ s \in S_b^{(j+1)} : d(s, \tilde{c}_l^*) \leq r_{\text{fair}}^* \right\}$$

and when, in Line 3 of Algorithm 4, we run Algorithm 1 on $S^{(j+1)}$ with $k = \tilde{k}$ and initial centers $C_0 \cup \bigcup_{l=1}^j C_l$, one of the following three cases has to happen (we denote the centers returned by Algorithm 1 in this $(j+1)$ -th call of Algorithm 4 by $\tilde{F}^A = \{\tilde{f}_1^A, \dots, \tilde{f}_{\tilde{k}}^A\}$ and assume that for $1 \leq l < l' \leq \tilde{k}$ Algorithm 1 has chosen \tilde{f}_l^A before $\tilde{f}_{l'}^A$):

- For every $l \in \{1, \dots, \tilde{k}\}$ there exists $l' \in \{1, \dots, \tilde{k}\}$ such that $\tilde{f}_{l'}^A \in \{s \in S_b^{(j+1)} : d(s, \tilde{c}_l^*) \leq r_{\text{fair}}^*\}$. In this case it immediately follows that

$$\min_{c \in \tilde{F}^A} d(s, c) \leq 2r_{\text{fair}}^*, \quad s \in S_b^{(j+1)},$$

and using (12) we obtain

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l \cup \tilde{F}^A} d(s, c) \leq (2^{j+1} + 2^j - 1)r_{\text{fair}}^*, \quad s \in S^{(j+1)}.$$

- There exists $l' \in \{1, \dots, \tilde{k}\}$ such that $\tilde{f}_{l'}^A \in S_a^{(j+1)}$. When Algorithm 1 picks $\tilde{f}_{l'}^A$, any other element in $S^{(j+1)}$ cannot be at a larger minimum distance from a center in $C_0 \cup \bigcup_{l=1}^j C_l$ or an already chosen center in $\{\tilde{f}_{l'}^A, \dots, \tilde{f}_{l'-1}^A\}$ than $\tilde{f}_{l'}^A$. It follows from (12) that

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l \cup \tilde{F}^A} d(s, c) \leq (2^{j+1} + 2^j - 1)r_{\text{fair}}^*, \quad s \in S^{(j+1)}.$$

- There exist $l \in \{1, \dots, \tilde{k}\}$ and $l', l'' \in \{1, \dots, \tilde{k}\}$ with $l' < l''$ such that $\tilde{f}_{l'}^A, \tilde{f}_{l''}^A \in \{s \in S_b^{(j+1)} : d(s, \tilde{c}_l^*) \leq r_{\text{fair}}^*\}$. When Algorithm 1 picks $\tilde{f}_{l''}^A$, any other element in $S^{(j+1)}$ cannot be at a larger minimum distance from a center in $C_0 \cup \bigcup_{l=1}^j C_l$ or an already chosen center in $\{\tilde{f}_{l'}^A, \dots, \tilde{f}_{l''-1}^A\}$ than $\tilde{f}_{l''}^A$. Because of $d(\tilde{f}_{l'}^A, \tilde{f}_{l''}^A) \leq 2r_{\text{fair}}^*$ according to (13), it follows that

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l \cup \tilde{F}^A} d(s, c) \leq 2r_{\text{fair}}^* \leq (2^{j+1} + 2^j - 1)r_{\text{fair}}^*, \quad s \in S^{(j+1)}.$$

In any case, we have

$$\min_{c \in C_0 \cup \bigcup_{l=1}^j C_l \cup \tilde{F}^A} d(s, c) \leq (2^{j+1} + 2^j - 1)r_{\text{fair}}^*, \quad s \in S^{(j+1)}. \quad (14)$$

Similarly to the base case, it follows from the triangle inequality that after running Algorithm 3 in Line 8 of Algorithm 4 and exchanging some of the centers in \tilde{F}^A , we have

$$d(s, c(s)) \leq 2(2^{j+1} + 2^j - 1)r_{\text{fair}}^* = (2^{j+2} + 2^{j+1} - 2)r_{\text{fair}}^*$$

for every $s \in S^{(j+1)}$, where $c(s)$ denotes the center of its cluster. In particular, we have

$$\min_{c \in C_0 \cup \bigcup_{l=1}^{j+1} C_l} d(s, c) \leq (2^{j+2} + 2^{j+1} - 2)r_{\text{fair}}^*, \quad s \in \left(S^{(j+1)} \setminus S^{(j+2)} \right) \cup \left(C_0 \cup \bigcup_{l=1}^{j+1} C_l \right),$$

and this completes the proof of (11).

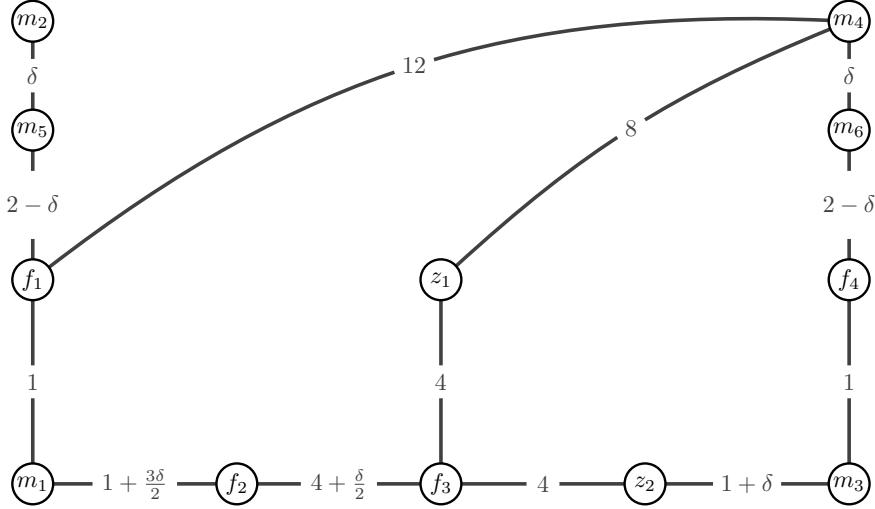


Figure 8. An example showing that Algorithm 4 is not a $(8 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$.

If in the T -th call of Algorithm 4 the algorithm terminates from Line 10, it follows from (11) that

$$\min_{c \in C_0 \cup \bigcup_{l=1}^T C_l} d(s, c) \leq (2^{T+1} + 2^T - 2)r_{\text{fair}}^*, \quad s \in S. \quad (15)$$

In this case, since $T < m$, we have

$$2^{T+1} + 2^T - 2 \leq 2^m + 2^{m-1} - 2 < 2^m + 2^{m-1} - 1,$$

and (15) implies (10). If in the T -th call of Algorithm 4 the algorithm does not terminate from Line 10, it must terminate from Line 5. It follows from (11) that

$$\min_{c \in C_0 \cup \bigcup_{l=1}^{T-1} C_l} d(s, c) \leq (2^T + 2^{T-1} - 2)r_{\text{fair}}^*, \quad s \in \left(S \setminus S^{(T)} \right) \cup \left(C_0 \cup \bigcup_{l=1}^{T-1} C_l \right). \quad (16)$$

In the same way as we have shown (14) in the inductive step in the proof of (11), we can show that

$$\min_{c \in C_0 \cup \bigcup_{l=1}^{T-1} C_l \cup \tilde{H}^A} d(s, c) \leq (2^T + 2^{T-1} - 1)r_{\text{fair}}^* \leq (2^m + 2^{m-1} - 1)r_{\text{fair}}^*, \quad s \in S^{(T)}, \quad (17)$$

where \tilde{H}^A is the set of centers returned by Algorithm 1 in the T -th call of Algorithm 4. Since $\bigcup_{l=1}^{T-1} C_l \cup \tilde{H}^A$ is contained in the output C^A of Algorithm 4, (17) together with (16) implies (10).

Since running Algorithm 4 involves at most m (recursive) calls of the algorithm and the running time of each of these calls is dominated by the running times of Algorithm 1 and Algorithm 3, it follows that the running time of Algorithm 4 is $\mathcal{O}(|C_0|m + km^2)|S| + km^4)$. \square

Proof of Lemma 3:

Consider the example given by the weighted graph shown in Figure 8, where $0 < \delta < \frac{1}{10}$. We have $S = S_1 \dot{\cup} S_2 \dot{\cup} S_3$ with $S_1 = \{m_1, m_2, m_3, m_4, m_5, m_6\}$, $S_2 = \{f_1, f_2, f_3, f_4\}$ and $S_3 = \{z_1, z_2\}$. All distances are shortest-path-distances. Let $k_{S_1} = 4$, $k_{S_2} = 1$, $k_{S_3} = 1$ and $C_0 = \emptyset$. We assume that Algorithm 1 in Line 3 of Algorithm 4 picks f_1 as first center. It then chooses f_4 as second center, z_1 as third center, f_3 as fourth center, f_2 as fifth center and z_2 as sixth center. Hence, $\tilde{C}^A = \{f_1, f_4, z_1, f_3, f_2, z_2\}$ and the corresponding clusters are $\{f_1, m_1, m_2, m_5\}$, $\{f_4, m_3, m_4, m_6\}$, $\{z_1\}$, $\{f_3\}$, $\{f_2\}$ and $\{z_2\}$. When running Algorithm 3 in Line 8 of Algorithm 4, it replaces f_1 with one of m_1, m_2 or m_5 and it replaces f_4

with one of m_3 , m_4 or m_6 . Assume that it replaces f_1 with m_2 and f_4 with m_4 . Algorithm 3 then returns $\mathcal{G} = \{S_2, S_3\}$ and when recursively calling Algorithm 4 in Line 12, we have $S' = \{f_2, f_3, z_1, z_2\}$ and $C' = \{m_2, m_4\}$. In the recursive call, the given centers are C' and Algorithm 1 chooses f_3 and f_2 . The corresponding clusters are $\{f_3, z_1, z_2\}$, $\{f_2\}$, $\{m_2\}$ and $\{m_4\}$. When running Algorithm 3 with clusters $\{f_3, z_1, z_2\}$ and $\{f_2\}$, it replaces f_3 with either z_1 or z_2 and returns $\mathcal{G} = \emptyset$, that is afterwards we are done. Assume Algorithm 3 replaces f_3 with z_2 . Then the centers returned by Algorithm 4 are z_2, f_2, m_2, m_4 and two arbitrary elements from S_1 , which we assume to be m_5 and m_6 . These centers have a cost of 8 (incurred for z_1). However, an optimal solution such as $C_{\text{fair}}^* = \{m_1, m_2, m_3, m_4, f_3, z_1\}$ has cost only $1 + \frac{3\delta}{2}$. Choosing δ sufficiently small shows that Algorithm 4 is not a $(8 - \varepsilon)$ -approximation algorithm for any $\varepsilon > 0$. \square

B. Further Experiments

In Figure 9 we show the costs of the approximate solutions produced by our algorithm (Alg. 4) and the algorithm by Chen et al. (2016) (M.C.) in the run-time experiment shown in the right part of Figure 3. In Figure 10, Figure 11 and Figure 12 we provide similar experiments as shown in Figure 6, Figure 2 and Figure 5, respectively.

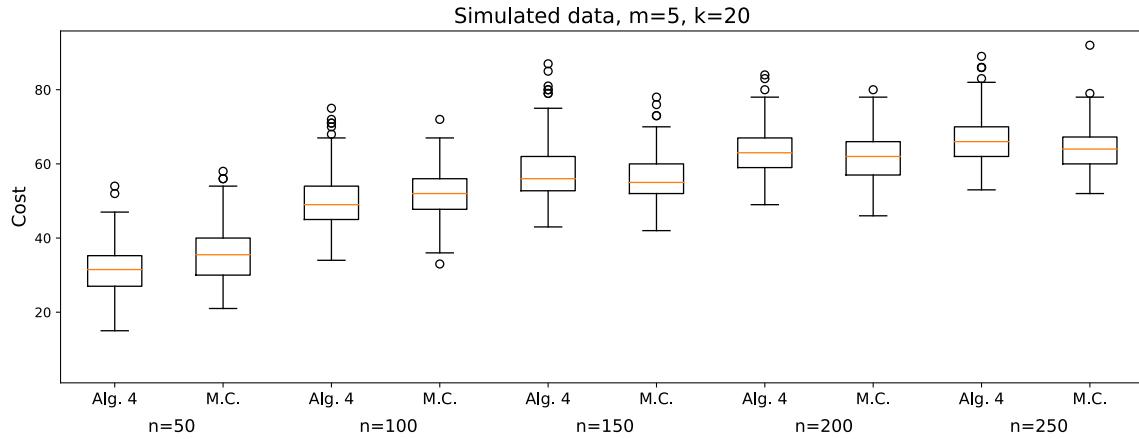


Figure 9. Cost of the output of our algorithm (Alg. 4) in comparison to the algorithm by Chen et al. (M.C.) in the run-time experiment shown in the right part of Figure 3.

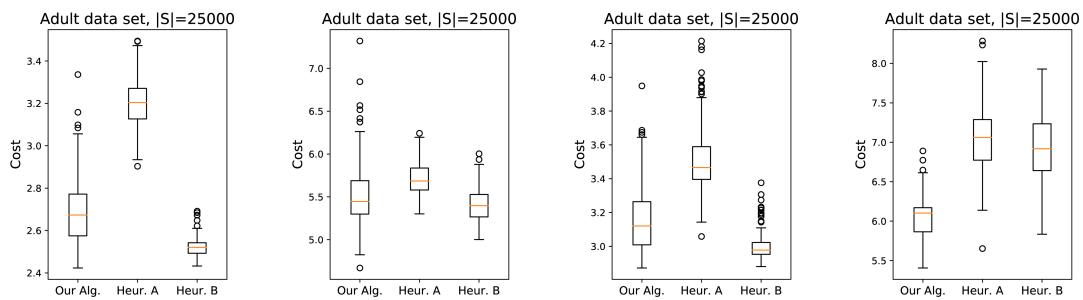


Figure 10. Similar experiments on the Adult data set as shown in Figure 6, but with different values of k_{S_i} . **1st plot:** $m = 2, k_{S_1} = 300, k_{S_2} = 100$ (S_1 corresponds to male and S_2 to female). **2nd plot:** $m = 2, k_{S_1} = k_{S_2} = 25$. **3rd plot:** $m = 5, k_{S_1} = 214, k_{S_2} = 8, k_{S_3} = 2, k_{S_4} = 2, k_{S_5} = 24$ ($S_1 \sim$ White, $S_2 \sim$ Asian-Pac-Islander, $S_3 \sim$ Amer-Indian-Eskimo, $S_4 \sim$ Other, $S_5 \sim$ Black). **4th plot:** $m = 5, k_{S_1} = k_{S_2} = k_{S_3} = k_{S_4} = k_{S_5} = 10$.

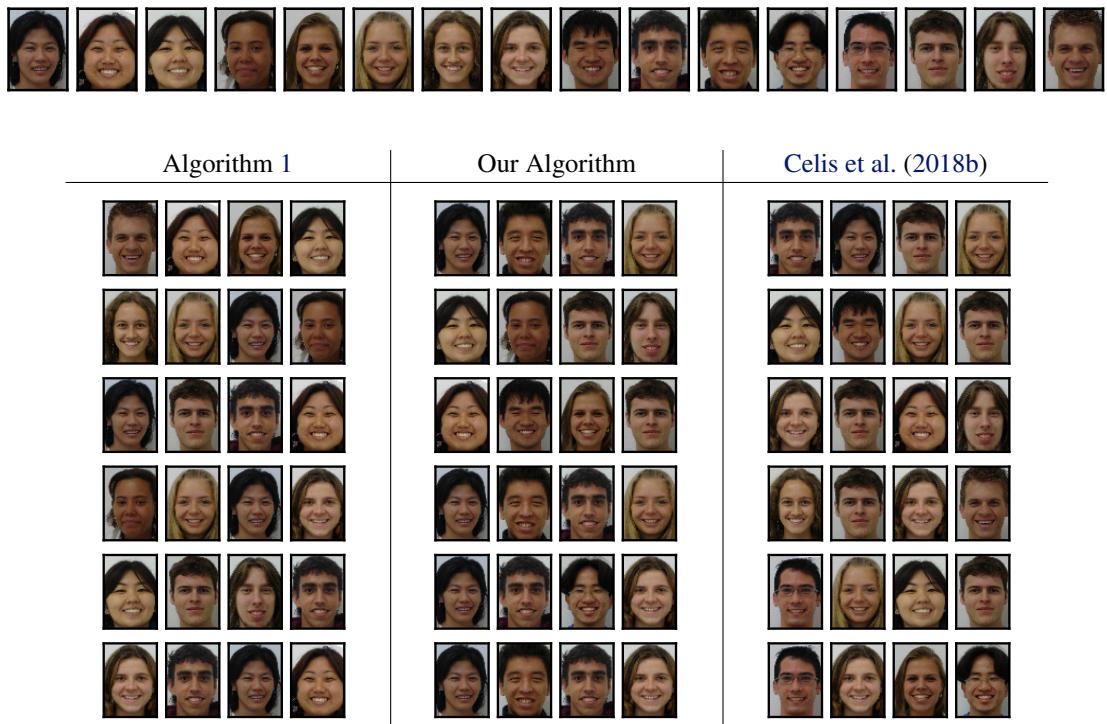


Figure 11. Similar experiment as shown in Figure 2. A data set consisting of 16 images of faces (8 female, 8 male) and six summaries computed by the unfair Algorithm 1, our algorithm and the algorithm of Celis et al. (2018b). The images are taken from the FEI face database available on <https://fei.edu.br/~cet/facedatabase.html>. Note that in this experiment (and the one shown in Figure 2) we are dealing with a very small number of images solely for the purpose of easy visual digestion.

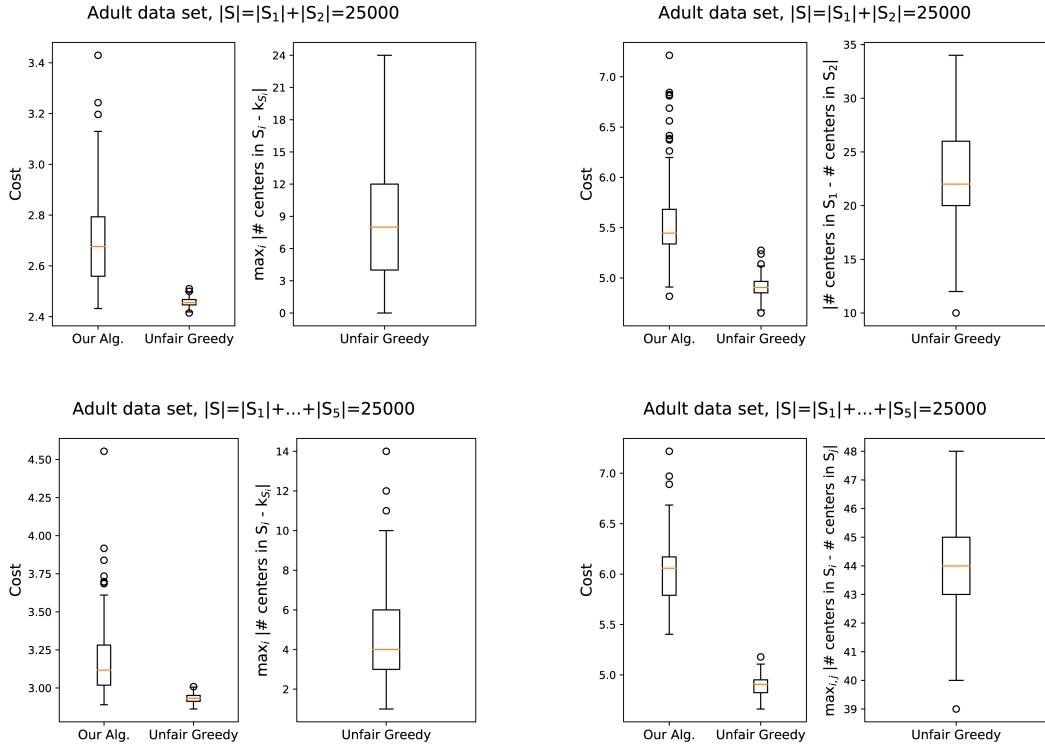


Figure 12. Similar experiments on the Adult data set as shown in Figure 5, but with different values of k_{S_i} . **Top left:** $m = 2, k_{S_1} = 300, k_{S_2} = 100$ (S_1 corresponds to male and S_2 to female). **Top right:** $m = 2, k_{S_1} = k_{S_2} = 25$. **Bottom left:** $m = 5, k_{S_1} = 214, k_{S_2} = 8, k_{S_3} = 2, k_{S_4} = 2, k_{S_5} = 24$ ($S_1 \sim$ White, $S_2 \sim$ Asian-Pac-Islander, $S_3 \sim$ Amer-Indian-Eskimo, $S_4 \sim$ Other, $S_5 \sim$ Black). **Bottom right:** $m = 5, k_{S_1} = k_{S_2} = k_{S_3} = k_{S_4} = k_{S_5} = 10$.