

Quantum Phase Estimation Algorithm

- estimate the phase (eigenvalue) of an eigenvector,
- Given unitary operator U and quantum state $|\psi\rangle$,

$$\Rightarrow U|\psi\rangle = e^{2\pi i \theta} |\psi\rangle$$

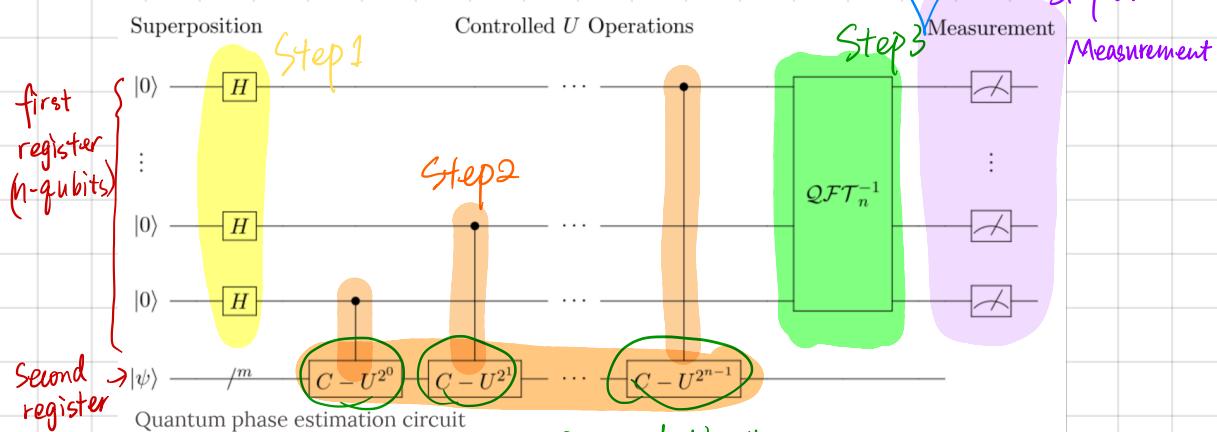
eigen vector eigen value

The algorithm estimates θ with high probability within error ϵ , using $O(1/\epsilon)$ C-U operations.

Step 4. phase approximation representation

Step 5.

Measurement



C-U: Controlled-U gate

the 1st bit serves as a control:

$$|00\rangle \xrightarrow{\text{C-U}} |00\rangle$$

$$|01\rangle \xrightarrow{\text{C-U}} |1\rangle \otimes U|0\rangle = |1\rangle \otimes (U_{00}|0\rangle + U_{01}|1\rangle)$$

$$|10\rangle \xrightarrow{\text{C-U}} |1\rangle \otimes U|1\rangle = |1\rangle \otimes (U_{10}|0\rangle + U_{11}|1\rangle)$$

$$\text{The matrix of C-U is: } C(U) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & U_{00} & U_{01} \\ 0 & 0 & U_{10} & U_{11} \end{bmatrix}$$

- The explanation of whole process:

Step 1
Hadamar
gate
 $|0\rangle^{\otimes n} \mid \psi \rangle$

$$\frac{1}{2^{\frac{n}{2}}} (|0\rangle + |1\rangle)^{\otimes n}$$

Step 2. Apply C-U.

$$\begin{aligned} U|\psi\rangle &= e^{2\pi i \theta} |\psi\rangle \\ U^2|\psi\rangle &= U^{2^{j-1}} \cdot U|\psi\rangle = U^{2^{j-1}} e^{2\pi i \theta} |\psi\rangle = e^{2\pi i \cdot 2^{j-1} \theta} |\psi\rangle \end{aligned}$$

$$\underbrace{\frac{1}{2^{\frac{n}{2}}} (|0\rangle + e^{2\pi i \cdot 2^{j-1} \theta} |1\rangle)}_{\text{1st qubit}} \otimes \dots \otimes \underbrace{(|0\rangle + e^{2\pi i \cdot 2^{j-1} \theta} |1\rangle)}_{(n-1)\text{th qubit}} \otimes \underbrace{(|0\rangle + e^{2\pi i \cdot 2^{j-1} \theta} |1\rangle)}_{n\text{th qubit}}$$

\Rightarrow the implementation method of C-U gate is introduced in Page 3.

1st register

$$= \frac{1}{2^{\frac{n}{2}}} \sum_{k=0}^{2^{n-1}} e^{2\pi i \cdot k \theta} |k\rangle$$

inverse quantum Fourier transform

Step 3. inverse QFT

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$$\frac{1}{2^n} \sum_{k=0}^{2^n-1} e^{2\pi i k \theta} |k\rangle$$

Step 4. iQFT

inverse QFT

$$\frac{1}{2^n} \sum_{x=0}^{2^n-1} \sum_{k=0}^{2^n-1} e^{2\pi i k \theta} e^{-\frac{2\pi i k x}{2^n}} |x\rangle = \frac{1}{2^n} \sum_{x=0}^{2^n-1} \sum_{k=0}^{2^n-1} e^{-\frac{2\pi i k}{2^n} (x - 2^n \theta)} |x\rangle$$

1st register

Thus the 2 registers are now:

$$\frac{1}{2^n} \sum_{x=0}^{2^n-1} \sum_{k=0}^{2^n-1} e^{-\frac{2\pi i k}{2^n} (x - 2^n \theta)} |x\rangle \otimes |\psi\rangle$$

Step 4. phase approximation

Approximate θ by rounding $2^n \theta$ to the nearest integer:

$$2^n \theta = a + 2^n \delta, \quad 0 \leq |2^n \delta| \leq \frac{1}{2}$$

nearest integer

$$\frac{1}{2^n} \sum_{x=0}^{2^n-1} \sum_{k=0}^{2^n-1} e^{-\frac{2\pi i k}{2^n} (x - a)} \cdot e^{2\pi i \delta k} |x\rangle \otimes |\psi\rangle$$

measurement: probability that $|\psi\rangle$ collapse to $|a\rangle$ after measurement = $|\langle a | \psi \rangle|^2$

Step 5.

measurement

$$\Pr(a) = \left| \left\langle a \left| \frac{1}{2^n} \sum_{x=0}^{2^n-1} \sum_{k=0}^{2^n-1} e^{-\frac{2\pi i k}{2^n} (x-a)} e^{2\pi i \delta k} \right| x \right\rangle \right|^2 = \frac{1}{2^{2n}} \left| \sum_{k=0}^{2^n-1} e^{2\pi i \delta k} \right|^2 = \begin{cases} 1 & \delta = 0 \\ \frac{1}{2^{2n}} \left| \frac{1-e^{2\pi i 2^n \delta}}{1-e^{2\pi i \delta}} \right|^2 & \delta \neq 0 \end{cases}$$

geometric progression

$$|2^n \theta\rangle \otimes |\psi\rangle$$

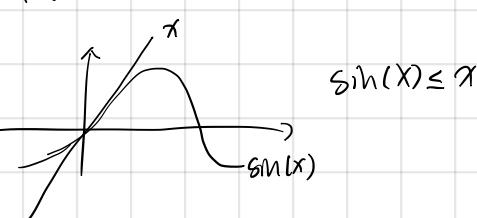
for $\delta \neq 0$, since $0 \leq |2^n \delta| \leq \frac{1}{2} \Leftrightarrow |\delta| \leq \frac{1}{2^{n+1}}$,

If θ is an exact binary fraction, we can measure its phase with probability 1. O.W., we can measure it with

$$\Pr(a) = \frac{1}{2^{2n}} \left| \frac{1 - e^{2\pi i 2^n \delta}}{1 - e^{2\pi i \delta}} \right|^2 \quad \text{for } \delta \neq 0 \quad \text{probability close to 1.}$$

$$= \frac{1}{2^{2n}} \left| \frac{\sin(\pi \cdot 2^n \delta)}{\sin(\pi \delta)} \right|^2 \Leftrightarrow \left| 1 - e^{2\pi i \delta} \right|^2 = 4 \left| \sin(\delta) \right|^2$$

$$> \frac{1}{2^{2n}} \left| \frac{\sin(\pi \cdot 2^n \delta)}{\pi \delta} \right|^2 \Leftrightarrow$$



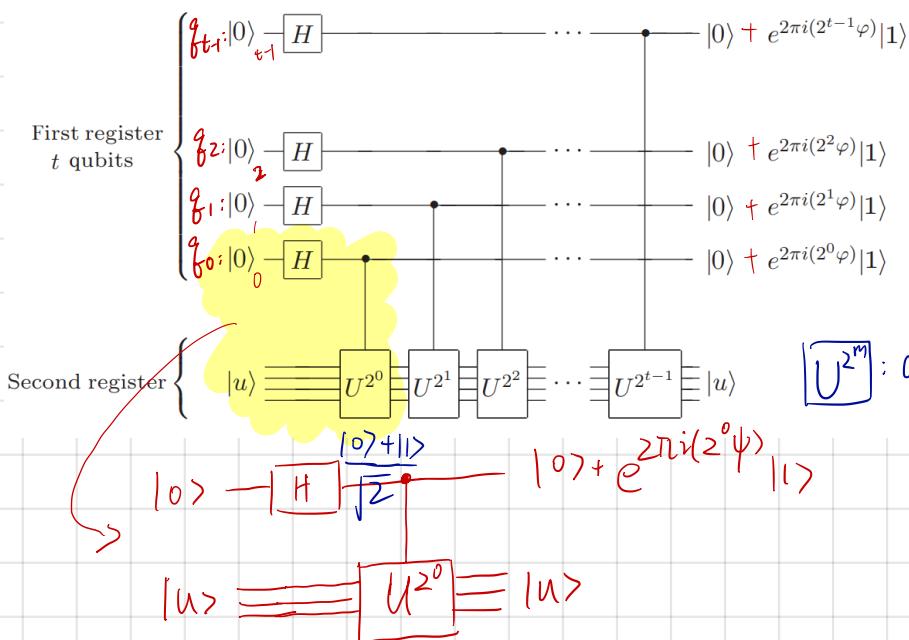
$$\sin(x) \leq x$$

$$> \frac{1}{2^{2n}} \left| \frac{2 \cdot 2^n \delta}{\pi \delta} \right|^2 \Leftrightarrow |2 \cdot 2^n \delta| \leq \sin(\pi 2^n \delta) \quad \text{for } |\delta| \leq \frac{1}{2^{n+1}}$$

$$= \frac{4}{\pi^2}$$

∴ The probability for getting correct result if $\delta \neq 0$ is:

$\Pr(a) > \frac{4}{\pi^2} \approx 0.405$. \Rightarrow Can be increased to 1- ϵ when increasing the amount of qubits by $O(\log(\frac{1}{\epsilon}))$



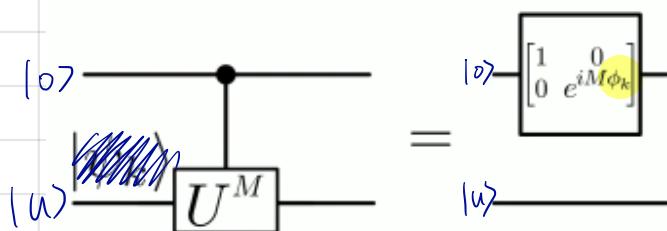
How to understand the Controlled-U gate?

$|0\rangle + \frac{|1\rangle + |1\rangle}{\sqrt{2}}$ is the control qubit of gate U^{2^0} , and $|u\rangle$ is the target qubits.

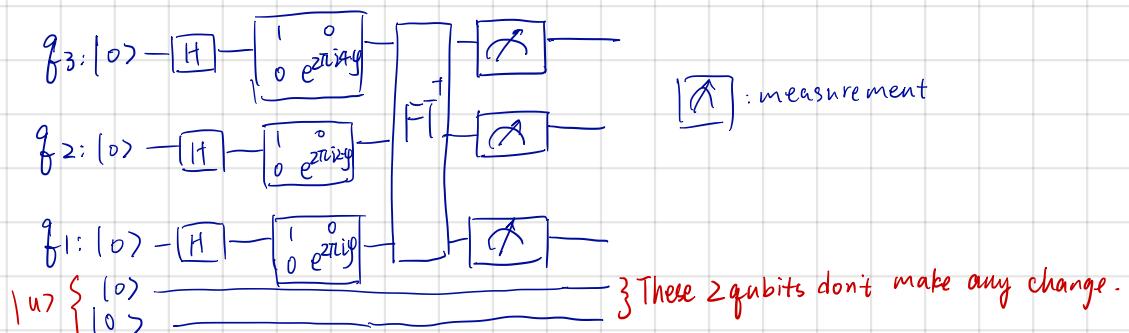
However, $|u\rangle$ doesn't make any change after the gate, instead,

$\frac{|0\rangle + |1\rangle}{\sqrt{2}}$ becomes $\frac{1}{\sqrt{2}}[|0\rangle + e^{2\pi i (2^0\psi)}|1\rangle]$ after the controlled-U gate.

Thus the controlled-U gate can be replaced by a controlled phase gate:



Because the above two circuits are the same, when implementing the controlled phase gate, an example circuit is (1st register has 3qubits, 2nd register has 2qubits):



During my implementation, I use $\varphi = \frac{\pi}{8}$ as an example.

Then after the measurement, I get 001, then divided by 2^t ($t=3$), I get 0.001, which is $\frac{1}{8}$. Same with the φ in the controlled phase gates.