

Improved Rendezvous Algorithms and a Semi-Synchronous Model for Heterogeneous Cognitive Radio Networks

Abstract—Cognitive Radio Network (CRN) is a promising technique aiming at solving the wireless spectrum scarcity problem. Rendezvous is the fundamental process of CRN. Heterogeneous CRN allows different users to have different sensing abilities. We are devoted to design faster rendezvous algorithms for heterogeneous CRN. First, we design a non-anonymous rendezvous algorithm which uses users' IDs. This algorithm can guarantee rendezvous for any two users i, j in $(l+1)(|V_i|+2)(|V_j|+2)$ timeslots, where l is the length of ID and $|V_i|, |V_j|$ are the size of the set of available channels for user i and j respectively. Second, we study the two-radio rendezvous problem where every user is equipped with two CRNs and propose a rendezvous algorithm for two-radio problem without using users' IDs. This algorithm can guarantee rendezvous for any two users i and j in $\min\{|V_i||V_j|\} \max\{P_i, P_j\}$ timeslots, where P_i and P_j are the smallest primes which are not less than $|V_i|$ and $|V_j|$ respectively. Third, we propose a semi-synchronous model which suppose there exists a global clock but users don't need to start rendezvous process simultaneously. We also design a rendezvous algorithm for semi-synchronous model which can guarantee rendezvous for any two users in N timeslots, where N is the overall amount of channels in the network. We show that our rendezvous algorithms have full rendezvous degrees. All of our algorithms can be used in multi-user scenario. We conduct plenty of experiments comparing our algorithms with state-of-the-art rendezvous in different scenarios, which corroborate our analysis.

Index Terms—Heterogeneous Cognitive Radio Network, Rendezvous Algorithms, Non-Anonymous, Two-Radio, Semi-Synchronous Model

I. INTRODUCTION

The wireless spectrum is very important for the transmission of wireless signals. However, the wireless spectrum scarcity problem is becoming more and more severe due to the rapid growth of wireless devices. Cognitive Radio Network (CRN) is a solution for this problem. In CRN, the users are divided into primary users (PUs) and secondary users (SUs). A PU owns one or more licensed spectrums while a SU needs to search for "empty" licensed spectrums which are not being occupied by PUs¹.

CRN involves many important problems including broadcasting, routing, data gathering and neighbor discovery. *Rendezvous* is the fundamental task of CRN, which targets finding a common frequency band (channel) for different users to communicate on. Before rendezvous completes, a user may even not aware of the existence of another user, let alone exchange information.

To solve rendezvous problem, many solutions have been proposed. Some works requires a central controller or a common control channel (CCC) to achieve rendezvous. However, when the number of users exceeds the capacity of the central controller or CCC, this method will become invalid. And it is not safe from the perspective of information security, for the probability of adversary attacks. Hence, some researchers proposed some algorithms without central controller or CCC, which are called blind rendezvous algorithms. Blind rendezvous algorithms are more practical than CCC based rendezvous algorithms.

Channel Hopping (CH) technique is widely used in blind rendezvous algorithms. In CH algorithms, users hop to channels according to predefined sequences. Time is divided into timeslots with equal length, which is enough for two users to establish a communication link when they are on a channel at the same time. The length of a timeslot can be set to be 10 ms under IEEE 802.22, which is a recommended standard for CRN.

Rendezvous algorithms can be judged according to some common metrics, such as *Expected Time To Rendezvous (ETTR)*, *Maximum Time To Rendezvous (MTTR)*, *Rendezvous Degree (RD)*. *Time To Rendezvous (TTR)* is the number of timeslots consumed to achieve rendezvous, which begins counting as soon as the latest user begins hopping. ETTR is the average TTR of an algorithm. MTTR is the maximum TTR needed to achieve rendezvous. In other words, MTTR is the TTR in the worst case. It is obvious that two users can have more than one common channel, RD is the ratio of the number of distinct rendezvous channels of an algorithm to the total number of common channels. It is obvious that the larger RD is, the more channels two users can rendezvous on. Because a channel can be occupied by a PU and not useful for rendezvous, the larger RD is, the better.

In this paper, we introduce some simple but efficient rendezvous algorithms under different scenarios. The following are the main contributions of our paper:

- 1) We propose a non-anonymous heterogeneous rendezvous algorithm which outperforms state-of-the-art non-anonymous heterogeneous rendezvous algorithms.
- 2) We propose a two-radio heterogeneous rendezvous algorithm which outperforms the state-of-the-art two-radio heterogeneous rendezvous algorithm.
- 3) We formulate the concept of semi-synchronous model and propose a semi-synchronous rendezvous algorithm

¹Unless specifically pointed out, "users" in the rest of this paper refer to SUs.

TABLE I
Comparisons between rendezvous algorithms

Algorithm	MTTR	RD	Synchronous	Non-Anonymous	Non-Oblivious	Two-Radio
JS	$3NP(P-G) + 3P$	100%	×	×	✓	×
DRDS	$3P^2 + 2P$	100%	×	×	✓	×
CBH	$2l_p P^2$	100%	×	✓	×	×
HH	$3 C_a C_b $	$< 100\%$	×	×	✓	×
advanced HCH	$(\log M + \log \log M)P_i P_j$	100%	×	✓	×	×
MTP	$O((\max\{ V_i , V_j \})^2 \log \log N)$	100%	×	×	×	×
NAH(this paper)	$\log M(P_i + 2)(P_j + 2)$	100%	×	✓	×	×
TRAH(this paper)	$\min\{ V_i V_j \} \max\{P_i, P_j\}$	100%	×	×	×	✓
SSH(this paper)	N	100%	semi-synchronous	×	×	×

which is a feasible and has a MTTR of N , which is least in all the existing rendezvous algorithms.

- 4) We conduct lots of experiments to compare our algorithms with state-of-the-art algorithms.

The rest of this paper is organized as follows. Section II introduces the background and some related works. Section III introduces different categories of models for rendezvous problem and problem formulation. Section IV presents a non-anonymous heterogeneous rendezvous algorithm and analyzes its performance. Section V presents a two-radio heterogeneous rendezvous algorithm and analyzes its performance. Section VI presents a semi-synchronous heterogeneous rendezvous algorithm and analyzes its performance. Simulation results are displayed in Section VII. And we conclude this paper in Section VIII.

II. BACKGROUND AND RELATED WORKS

A. Prime number and Co-prime Numbers

Prime number is a very important concept in number theory. We first introduce the definition of prime number:

Definition 2.1: A prime number is a natural number which is larger than 1 and can be divided with no remainder only by 1 and itself.

The smallest prime number is 2. There is an important theory about prime number:

Theorem 1: If n is a positive integer and $n \geq 2$, there must exist at least one prime number between n and $2n$.

Then we introduce the definition of composite number:

Definition 2.2: A composite number is a natural number which is larger than 1 and has factors besides 1 and itself.

The smallest composite number is 4. There is a property about prime and composite numbers:

Lemma 2.1: Any positive integer larger than 1 is either a prime number or a composite number.

Then we introduce the definition of co-prime numbers:

Definition 2.3: Two nonzero natural integers a and b are said to be co-prime if the only common factor which could divide them with no remainder is 1.

Co-prime numbers have many important properties:

Lemma 2.2: If a and b are co-prime, the least common multiple of them is their product: $a \times b$.

Number	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
mod 4	1	2	3	0	1	2	3	0	1	2	3	0	1	2	3	0	1	2	3	0
mod 5	1	2	3	4	0	1	2	3	4	0	1	2	3	4	0	1	2	3	4	0

Fig. 1. An example of Theorem 2.

Lemma 2.3: If a and b are two consecutive positive integers, a and b are co-prime.

Lemma 2.4: If a and b are two consecutive positive odd numbers, a and b are co-prime.

Lemma 2.5: Suppose a is a prime number and b is a composite number. If a is larger than b , they are co-prime. If b is larger than a , but b is not a multiple of a , they are co-prime.

We then introduce an important theorem for rendezvous:

Theorem 2: If m and n are co-prime numbers, then for any integer a , the integers $a, a + n, a + 2n, \dots, a + (m - 1)n$ are m distinct numbers under modulo- p arithmetic.

Proof: Choose any two integers from $a, a + n, a + 2n, \dots, a + (m - 1)n$, the absolute value of their difference is kn , where $0 < k < m$. If $kn \bmod m$ equal 0, then $kn = lm$, where l is a positive integer. Then kn or lm is a common multiple of m and n . From Lemma 2.2 we know mn is the least common multiple of m and n , and because $0 < k < m$, kn is a common multiple of m and n that is less than mn , which is a contradiction. Hence, Theorem 2 holds. ■

Fig. 1 illustrates an example of Theorem 2. In Fig. 1, the first row is a string of numbers starting from 1. The second row is the results of these numbers under modulo 4 arithmetic. The third row is the results of these numbers under modulo 5 arithmetic. We can clearly see that 1, 5, 9, 13, 17 all correspond to 1 under modulo 4 arithmetic, but correspond to 1, 0, 4, 3, 2 respectively under modulo 5 arithmetic, which are all the possible results under modulo 5 arithmetic. Theorem 2 plays an important role in rendezvous algorithms and is the main tool we use to design the following algorithms.

B. Related Works

III. MODELS AND PROBLEM FORMULATIONS

In this section, we will introduce the foundation model and some other models which are based on the foundation model.

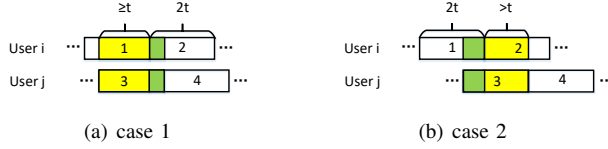


Fig. 2. An example of different cases of timeslot overlapping.

Models are of great importance in the design of rendezvous algorithms, because models constrain the resources that we can use. Hence, we need to design different algorithms under different models to achieve high performance for rendezvous process. We will also give the formulation for rendezvous problem in this section.

A. Foundation Model

Suppose there are M users in the network. Suppose the licensed spectrum is divided into n channels which are non-overlapping. Denote the set of channels as $U = \{1, 2, \dots, n\}$, where n is the total number of channels in U . We assume that every user in the network is equipped with a CRN. User i can sense a set of channels as $C_i = \{c_{i1}, c_{i2}, \dots, c_{in_i}\}$, where n_i is the number of channels in set C_i . A channel is available to user i when it is not occupied by a PU and it is in C_i . User i has a set of available channels as $V_i = \{v_{i1}, v_{i2}, \dots, v_{im_i}\}$, where m_i is the number of channels in set V_i . For simplicity, we suppose that V_i doesn't change during the rendezvous process. Let the length of every timeslot be $2t$, where $t = 10ms$ according to IEEE 802.22.

Because the lengths of all users' timeslots are equal, user j 's one timeslot can overlap with at most two consecutive timeslots of user i . Fig. 2 illustrates this problem in two cases. Suppose timeslot 3 is one timeslot of user j . And the left timeslot of user i which overlaps with timeslot 3 is timeslot 1. The right timeslot of user i which overlaps with timeslot 3 is timeslot 4. The yellow part stands for the overlapping part of timeslot 1 and 3, while the green part stands for the overlapping part of timeslot 2 and 3. In Fig. 2(a), the length of the yellow part is greater than or equal to t . In Fig. 2(b), the length of the green part is greater than t . There is a special case that the length of the yellow part or the green part is zero, which means that the timeslots of user i and user j are aligned. Hence, no matter when the users start their rendezvous process, the maximum overlap of their timeslots is at least t , which is enough for two users to find each other and exchange information. Foundation model is the basis of other models we will introduce in the following subsections.

B. Oblivious and Non-Oblivious Models

The difference between oblivious and non-oblivious models is whether there exists a global label for every channel in U and users label channels as same as their global labels. In oblivious model, there doesn't exist any global label and every user labels channels in its own way. For example, for the same channel, denote it as c , user i can label it as 1 while user j can label it as 2. In non-oblivious model, there exist global

labels for channels such as $U = \{1, 2, \dots, n\}$ where we label the i -th channel in U as i . And the label of every channel for every user is as same as its global label. It is obvious that designing rendezvous algorithms for oblivious model is at least not easier than non-oblivious model, since in non-oblivious model, we could use the labels of channels as an extra resource for designing rendezvous algorithms.

C. Anonymous and Non-Anonymous Models

The difference between an is whether each user in the network has a unique ID. In anonymous model, there doesn't exist a unique ID for each user. Hence, a user can't be distinguished from the other users. In non-anonymous model, there exists a unique ID for each user. Hence, a user is easily distinguishable from the other users. Designing rendezvous algorithms for non-anonymous model is easier than anonymous model, because we can use IDs, which will be shown very powerful for rendezvous process.

D. Synchronous, Asynchronous and Semi-Synchronous Models

In the previous works, there exist synchronous and asynchronous rendezvous algorithms. In synchronous model, there exists a global clock, and time is divided into equal timeslots. And every user start their rendezvous process from the same timeslot. In asynchronous model, there doesn't exist any global clock, time is divided into equal timeslots according to their local clock. And every user can start its own rendezvous process at any time.

In this paper, we introduce a new model about timing, which is semi-synchronous model. In semi-synchronous model, there exists a global clock, and time is divided into equal timeslots. However, every user can start its own rendezvous process at any timeslot. Though synchronous model is difficult to implement, semi-synchronous model is practical. There exist many techniques to achieve time giving, such as GPS timing, Beidou satellite time giving, CSAO time giving and so on. These time services have high precision. For example, GPS timing can achieve 10 nanosecond level precision. Because our timeslot is 20 ms long, this level of precision is enough for our use.

We need to point out that different models in different subsections can be combined to generate a new model. We will propose some algorithms for three combined models.

E. Problem Formulations

In this paper, we focus on designing rendezvous algorithms for two-user scenario, because it is the fundamental process for multiple-user rendezvous. Two-user rendezvous algorithms can be expanded into multiple-user rendezvous algorithms. Then we give the formulations of the three problems we will solve:

Problem 1: Design a rendezvous algorithm which has low MTTR and highest RD for heterogeneous non-anonymous model.

Problem 2: Design a two-radio rendezvous algorithm which has low MTTR and highest RD for heterogeneous anonymous model.

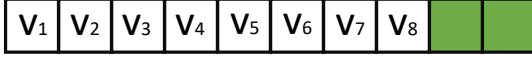


Fig. 3. An example of Alg. 1.

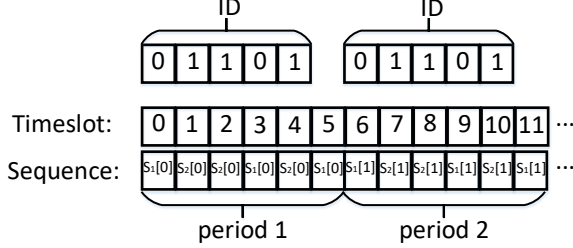


Fig. 4. An example of Alg. 2.

Problem 3: Design a rendezvous algorithm which has low MTTR and highest RD for semi-heterogeneous model.

IV. NON-ANONYMOUS HETEROGENEOUS RENDEZVOUS ALGORITHM

In this section, we will propose a heterogeneous non-anonymous rendezvous algorithm. The main idea of this algorithm is to create a channel hopping sequence composed of $\lceil \log_2 M \rceil + 1$ subsequences. We first propose an algorithm to generate the subsequences to be used.

Algorithm 1 Subsequence Generating Algorithm

- 1: Input: the set of available channels $V = \{v_1, v_2, \dots, v_m\}$, and length L ;
- 2: Initialize $i := 0$;
- 3: **while** $i < L$ **do**
- 4: **if** $i \leq m$ **then**
- 5: $S[i] := v_i$;
- 6: **else**
- 7: Randomly choose a channel from V , denote it as c ;
- 8: $S[i] := c$;
- 9: **end if**
- 10: $i := i + 1$;
- 11: **end while**
- 12: Output: Sequence S .

The main idea of Alg.1 is to generate a subsequence S with length T according to V . The process is rather simple. We fill the first m elements in S with the channels in V . For the last $(T - m)$ elements, we randomly pick channels from V to fill them. Fig.3 shows an example of Alg.1, in which $V = \{v_1, v_2, \dots, v_8\}$ and $T = 10$. We can clearly see that the first 8 elements are set to be v_1, v_2, \dots, v_8 respectively. The last $10 - 8 = 2$ elements are colored in green, which means that they are randomly picked from V .

In Alg.2, we create a channel hopping sequence consisting of $(\lceil \log_2 M \rceil + 1)$ subsequences. The $(\lceil \log_2 M \rceil + 1)$ sub-

Algorithm 2 Non-Anonymous Heterogeneous Rendezvous Algorithm

- 1: Input: the set of available channels $V = \{v_1, v_2, \dots, v_m\}$, and its ID whose length is $\lceil \log_2 M \rceil$ bits;
- 2: Find the smallest prime P that ensure $P \geq m$;
- 3: **if** $P=3$ **then**
- 4: $P := 5$;
- 5: **end if**
- 6: Initialize $t := 0$;
- 7: Invoke Alg.1 to generate three sequences S_1, S_2, S_3 with channel set V and length $P, P+1, P+2$ respectively;
- 8: **while** Not rendezvous **do**
- 9: **if** $t \% (\lceil \log_2 M \rceil + 1) \neq 0$ **then**
- 10: **if** $ID[t \% (\lceil \log_2 M \rceil + 1)] == 0$ **then**
- 11: Access channel $S_2[(t / (\lceil \log_2 M \rceil + 1)) \bmod (P + 1)]$;
- 12: **else**
- 13: Access channel $S_3[(t / (\lceil \log_2 M \rceil + 1)) \bmod (P + 2)]$;
- 14: **end if**
- 15: **else**
- 16: Access channel $S_1[(t / (\lceil \log_2 M \rceil + 1)) \bmod P]$;
- 17: **end if**
- 18: $t := t + 1$;
- 19: **end while**

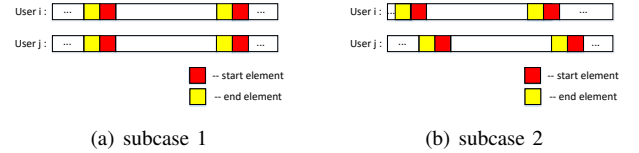


Fig. 5. Two subcases of case 1 and case 2.

sequences are generated by Alg.1. There are three kinds of subsequences, which are S_1, S_2 and S_3 . The lengths of S_1, S_2 and S_3 are $P, P+1, P+2$ respectively.

Fig.4 illustrates an example of Alg.2. In this example, the length of ID is 5 and user i's ID is 01101. In round 1, the first $\lceil \log_2 M \rceil$ elements of round 1 are either $S_2[0]$ or $S_3[0]$. If the corresponding digit of the i -th element in ID is 0, then the i -th element will be $S_2[0]$. If the corresponding digit of the i -th element in ID is 1, then the i -th element will be $S_3[1]$. The last element of round 1 is $S_1[0]$.

Theorem 3: Alg.2 can guarantee rendezvous for two asynchronous users in $(\lceil \log_2 M \rceil + 1)(P_i + 2)(P_j + 2)$ timeslots if $V_i \cap V_j \neq \emptyset$.

Proof: We discuss in two cases:

Case 1 :

Suppose $P_i = P_j$. Let $P = P_i = P_j$. We divide this case into two subcases:

Subcase 1.1 : Suppose user i and j's periods are aligned, as illustrated in Fig.5(a). Because user i and user j are two different users, their ID must be different in at least one digit.

Without lose of generality, suppose the k -th digit in ID_i is 0 while the k -th digit in ID_j is 1. Then the k -th element in user i 's period corresponds to subsequence S_{2i} , whose length is $P + 1$. The k -th element in user j 's period corresponds to subsequence S_{3j} , whose length is $P + 2$. Then in every period, one element of S_{2i} will meet one element of S_{2j} . According to Lemma 2.3, $P+1$ and $P+2$ are co-prime. Then rendezvous can be achieved in $(\lceil \log_2 M \rceil + 1)(P + 1)(P + 2)$ timeslots according to Theorem 2, as long as user i and j have at least one common channel.

Subcase 1.2 : Suppose user i and j 's periods are not aligned, as illustrated in Fig.5(b). In this case, the last element in user i 's period will meet one of the first $(\lceil \log_2 M \rceil + 1)$ elements of user j 's period. The last element in user i 's period corresponds to subsequence S_{1i} . The corresponding element of user j corresponds to subsequence S_{2j} or S_{3j} . From Lemma 2.3 and 2.4, we know that P and $P+1$ are co-prime, P and $P+2$ are also co-prime. Hence, according to Theorem 2, rendezvous can be achieved in $(\lceil \log_2 M \rceil + 1)P(P+1)$ or $(\lceil \log_2 M \rceil + 1)P(P+2)$ timeslots respectively.

Case 2 : Suppose $P_i \neq P_j$. We divide this case into two subcases:

Subcase 2.1 : Suppose user i and j 's periods are aligned, as illustrated in Fig.5(a). In this case, the last element in user i 's period will meet the last element in user j 's period. The last element in user i 's period corresponds to subsequence S_{i1} . The last element in user j 's period corresponds to subsequence S_{j1} . Because $P_i \neq P_j$, rendezvous can be achieved in $(\lceil \log_2 M \rceil + 1)P_i P_j$ timeslots according to Theorem 2, as long as user i and j have at least one common channel.

Subcase 2.2 : Suppose user i and j 's periods are not aligned, as illustrated in Fig.5(b). Without lose of generality, suppose $P_i > P_j$. In this case, the last element in user i 's period will meet one of the first $(\lceil \log_2 M \rceil + 1)$ elements of user j 's period. The last element in user j 's period will meet one of the first $(\lceil \log_2 M \rceil + 1)$ elements of user i 's period. The last element in user j 's period corresponds to subsequence S_{1j} , whose length is P_j . The corresponding element of user i corresponds to subsequence S_{2i} or S_{3i} , whose lengths are $P_i + 1$ and $P_i + 2$ respectively. Because P_i and P_j are two different primes, $P_i > P_j + 2$ or $P_i = P_j + 2$. If $P_i > P_j + 2$, from Lemma 2.5, we know P_i and $P_j + 1$ are co-prime, P_i and $P_j + 2$ are co-prime. According to Theorem 2, rendezvous can be achieved in $(\lceil \log_2 M \rceil + 1)P_i(P_j + 1)$ or $(\lceil \log_2 M \rceil + 1)P_i(P_j + 2)$ timeslots respectively. If $P_i = P_j + 2$, then $P_i + 1 = P_j + 3$, $P_i + 2 = P_j + 4$. If $P_j = 2$, $P_i = 2 + 2 = 4$ is not a prime. In Alg.2, we set P to be 5 if $P = 3$. Because $P_2 \neq 2$ and $P_2 \neq 3$, $P_2 + 3$ and $P_2 + 4$ can not be divided by P_2 without remainder. From Lemma 2.5, we know that both $P_i + 1$ and $P_i + 2$ are co-prime with P_j . According to Theorem 2, rendezvous can be achieved in $(\lceil \log_2 M \rceil + 1)(P_i + 1)P_j$ or $(\lceil \log_2 M \rceil + 1)(P_i + 2)P_j$ timeslots respectively.

Combine the above together, Theorem 3 holds. ■

Theorem 4: The RD of Alg.2 is 100%.

Proof: For any user, the corresponding subsequence

S_1, S_2, S_3 all contains all the channels in its available channel set. From the proof of Theorem 3, we know that one subsequence of user i will meet one subsequence of user j and the lengths of the subsequences are co-prime. Denote the two subsequences as S_i and S_j . From Theorem 2, we know that every element in S_i will meet all of the elements in S_j and vice versa. Hence, the RD of Alg.2 is 100%. ■

This algorithm can also be used when the setting is oblivious. Our algorithm is more simple than the state-of-the-art algorithm and has a less MTTR than it, which is $(\log_2 M + \log_2 \log_2 M)|P_i||P_j|$.

V. TWO-RADIO ANONYMOUS HETEROGENEOUS RENDEZVOUS ALGORITHM

Although Theorem 2 is a very powerful tool to design rendezvous algorithms, it is hard to design heterogeneous rendezvous algorithms by leveraging it under anonymous model. The reason is that if the primes which is not less than the size of available channels for two users are equal, and they happen to start rendezvous process simultaneously, Theorem 2 will lose use. In this scenario, an element in user i 's period will meet an element at the same position of user j 's period in all periods. In non-anonymous model, we can leverage each user's ID to solve this problem as Alg.2. However, in non-anonymous model, there doesn't exist any distinct ID for each user.

In this section, we propose a rendezvous algorithm for a CRN network where each user is equipped with two CRNs. Because each user has two CRNs, it can hop to two different channels simultaneously.

Algorithm 3 Two-radio Heterogeneous Rendezvous Algorithm

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1: Input: the set of available channels  $V = \{v_1, v_2, \dots, v_m\}$ ;
2: Find the smallest prime  $P$  which is not less than  $m$ ;
3: if  $P == m$  then
4:    $P = m + 1$ ;
5: end if
6: Initialize  $t := 0, i := 0, j := 0$ .
7: while Not rendezvous do
8:   Let  $i = t \bmod m + 1, j = P - t \bmod P$ ;
9:   Radio 1 access Channel ( $v_i$ );
10:  if  $1 \leq j \leq m$  and  $j \neq i$  then
11:    Radio 2 access Channel ( $v_j$ );
12:  else
13:    Randomly picks a channel from  $V - \{v_i\}$  and let
      Radio 2 access it;
14:  end if
15:   $t := t + 1$ 
16: end while

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In Alg.3 every user has two CRNs. Hence, we need to design hopping sequences for the two radios. Fig.6 shows an example of Alg.3. In this example, user i 's available channel set $V_i = \{v_{i1}, v_{i2}, v_{i3}\}$ and user j 's available channel set is $V_j = \{v_{j1}, v_{j2}, v_{j3}, v_{j4}\}$. Because $m_i = 3$ is a prime, P_i is

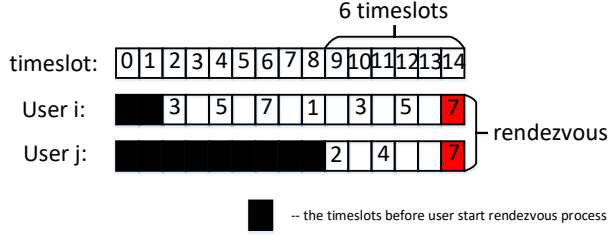


Fig. 7. An example of Alg. 4.

Fig.7 illustrates an example of Alg.4. In this example, N is set to be 8. User i starts at the third timeslot and user j starts at tenth timeslot. $V_i = \{1, 3, 5, 7\}$ and $V_j = \{2, 4, 7\}$. We can clearly see that TTR is $6 < 8$.

We need to point out that the timeslots don't need to be exactly aligned under the fundamental model. Because in fundamental model, the length of a timeslot is set to be 20 ms, from Fig.2(a) we know that as long as the accuracy of time is less than 10 ms. This is already achievable by using GPS or Beidou timing service. Hence, semi-synchronous model is practical. And Alg.4 has the least MTTR compared with the existing rendezvous algorithms.

Theorem 8: The RD of Alg.4 is 100%.

Proof: In Alg.4, users will hop to all of their common channels in same timeslots. Hence, they will rendezvous at all of their common channels. Hence, the RD of Alg.4 is 100%. ■

VII. SIMULATION

VIII. CONCLUSION

IX. ACKNOWLEDGEMENTS