

THE UNIVERSITY OF TEXAS AT ARLINGTON, TEXAS DEPARTMENT OF ELECTRICAL ENGINEERING

EE 5327 - 001 SYSTEM IDENTIFICATION & ESTIMATION

HW # 6 ASSIGNMENT

by

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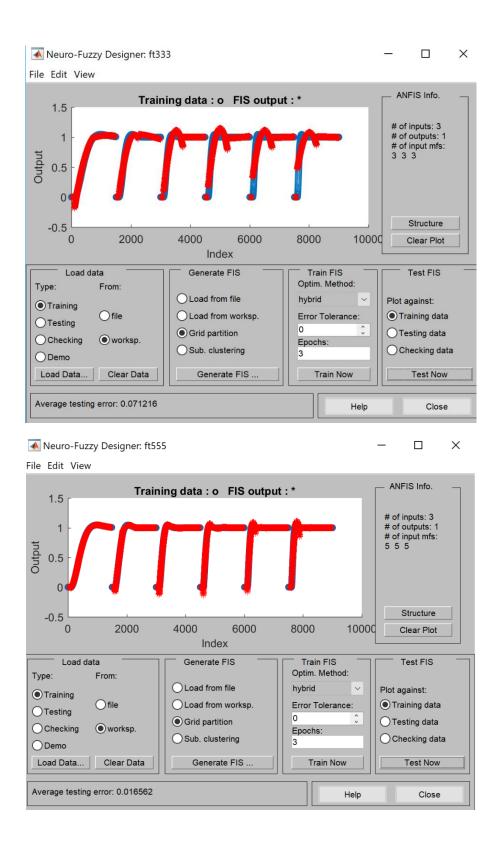
Presented to
Prof. Michael Niestroy

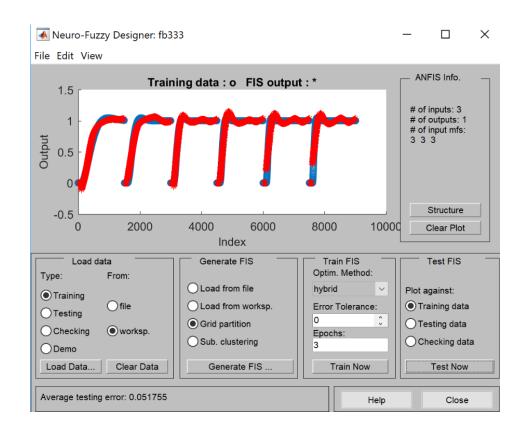
Nov 30, 2017

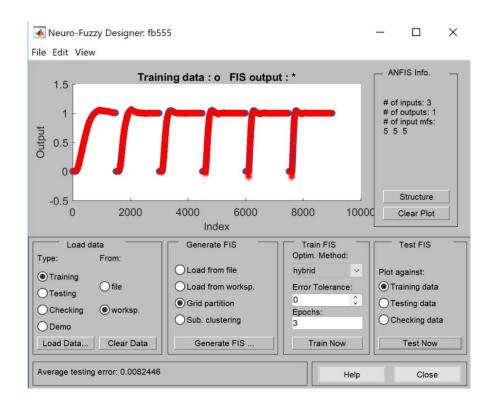
Problem 1:

MATLAB code for generating the training set for Fuzzy controller

```
clc
close all
w=0;
wk=[0.5 1.0 1.5 2.0 2.5 3.0];
t=0;
i=0;
nnin=zeros(1001,4);
for i=1:6
    w=wk(i);
    [t,y]=sim('Hw6P1a',[0 15]);
    if i==1
        nnin=NN TrainData;
    else
       nnin=[nnin;NN_TrainData];
    end
   end
  Step
                             Transfer Fcn
                                         Clock
                                                                           ►NN_TrainData
                                                                           To Workspace1
                                          Constant
```







1. 3-3-3 with triangular membership functions and linear output

Final Error = 0.071216

2. 5-5-5 with triangular membership functions and linear output

Final Error = 0.016562

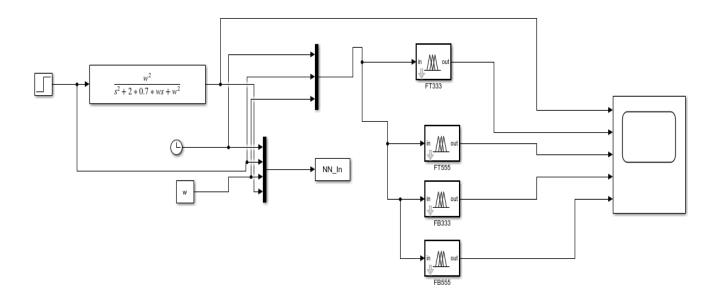
3. 3-3-3 with generalized bell membership functions and linear output

Final Error = 0.051755

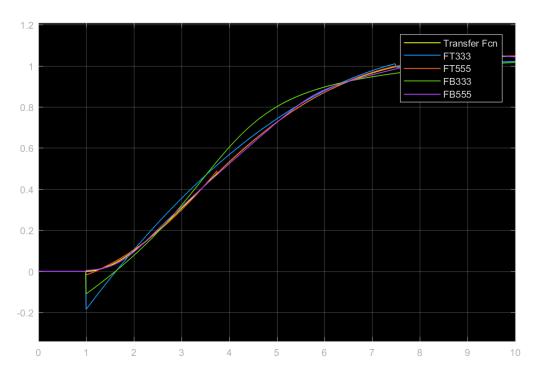
4. 5-5-5 with generalized bell membership functions and linear output

Final Error = 0.008245

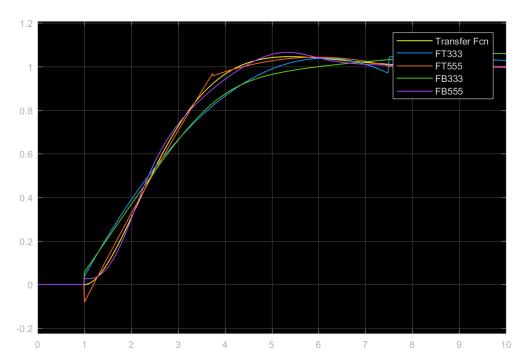
b) Comparison of training data & FIS output (zeta=0.7)



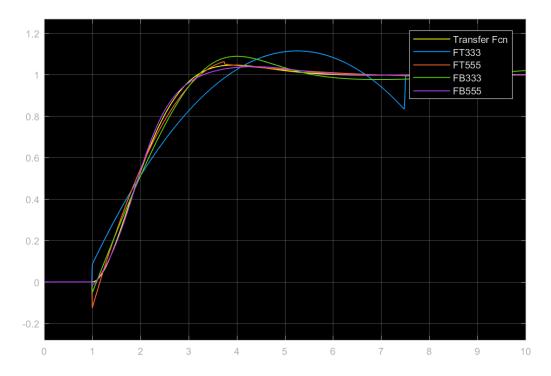
Comparison when w=0.5



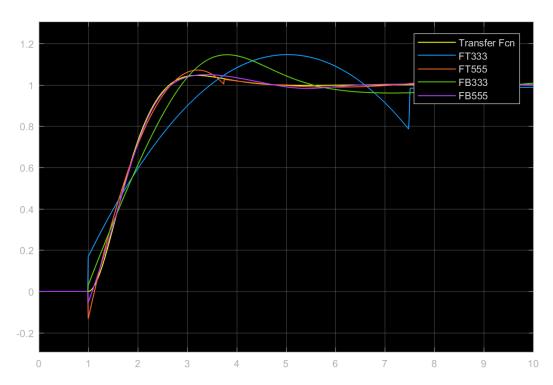
Comparison when w=1



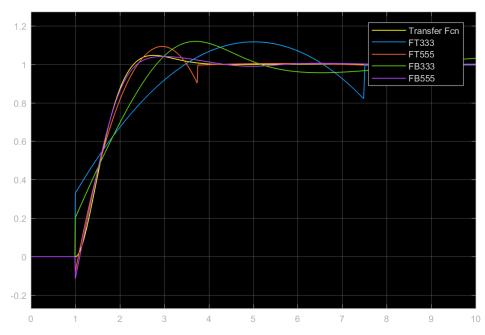
Comparison when w=1.5



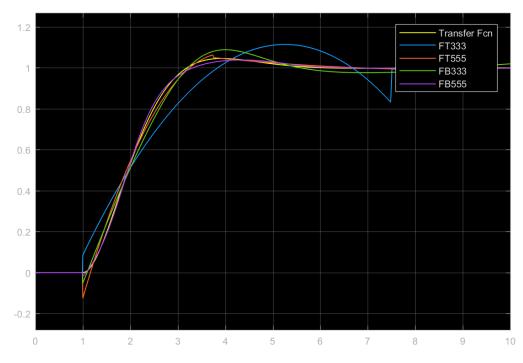
Comparison when w=2



Comparison when w=2.5

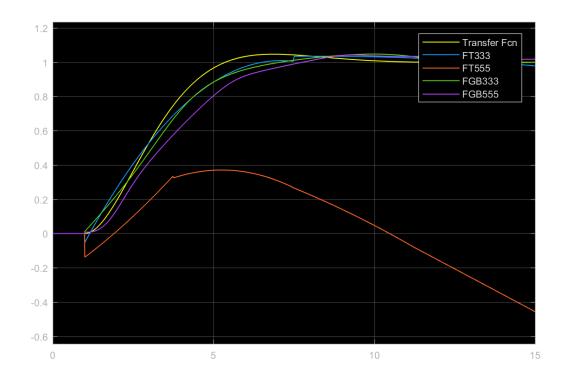


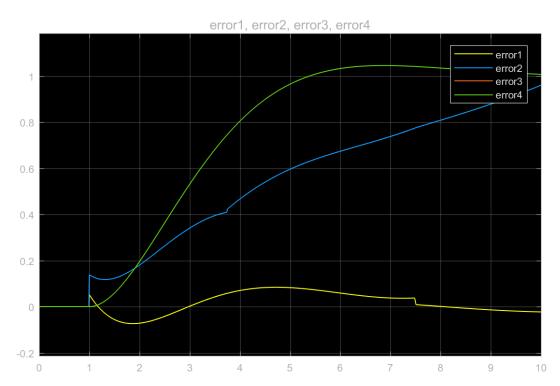
Comparison when w=3



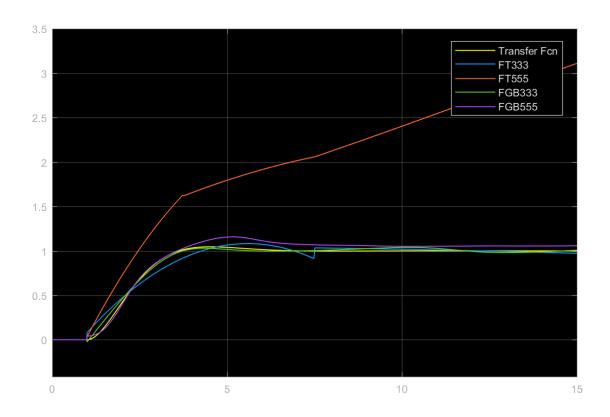
As per the comparison, the FIS with 5-5-5 generalized bell membership function is the closest to the training data at various values of w. Now, if we observe the error between the training data at 'w' value & the FIS output, we can see a clear difference in the accuracy of various types of FIS.

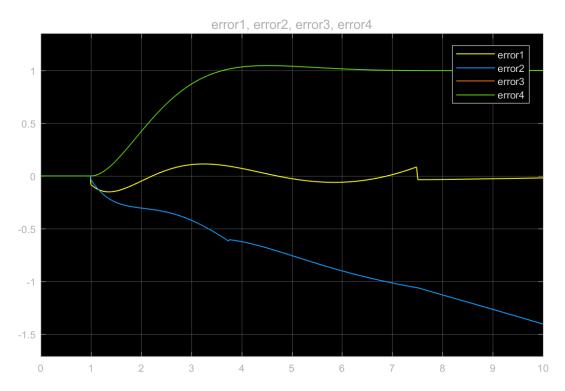
When w=0.75, the comparison and the error plots are as follows:



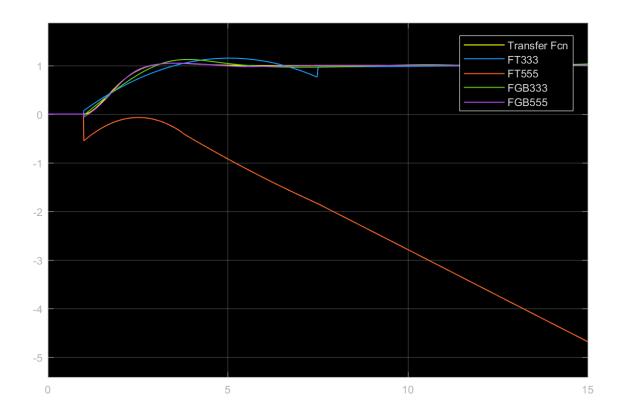


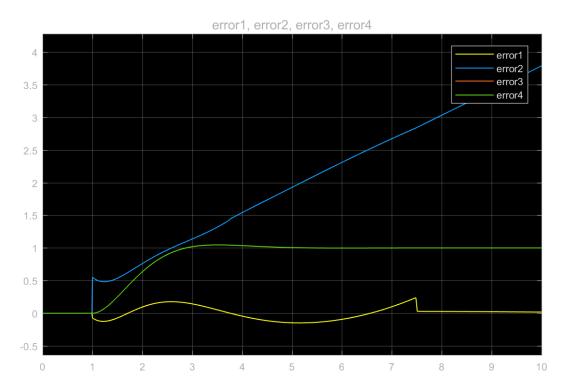
When w=1.25, the comparison and the error plots are as follows:



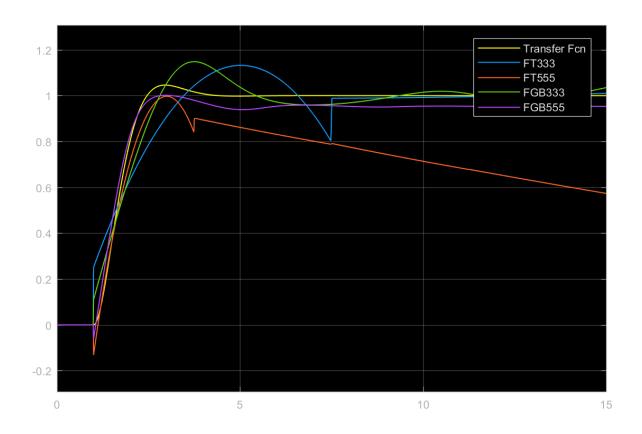


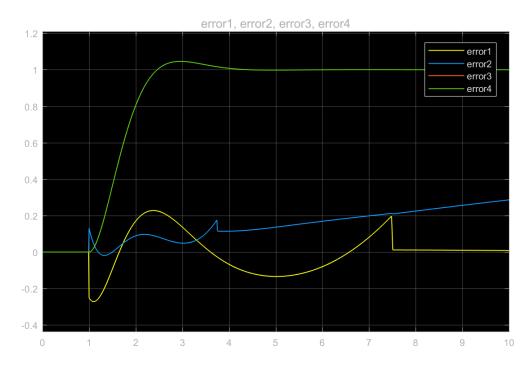
When w=1.75, the comparison and the error plots are as follows:



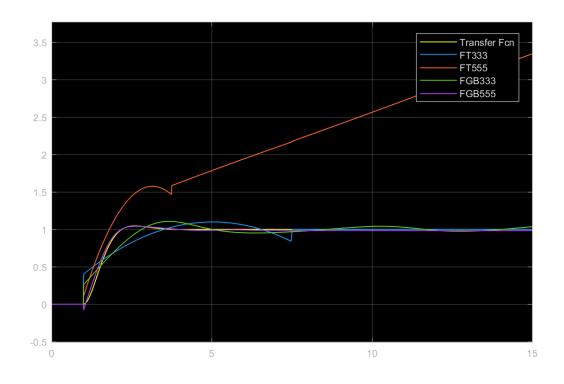


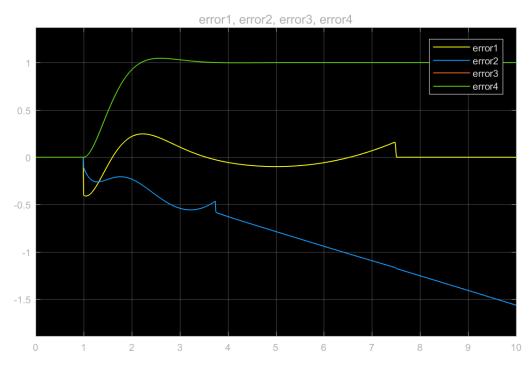
When w=2.25, the comparison and the error plots are as follows:





When w=2.75, the comparison and the error plots are as follows:





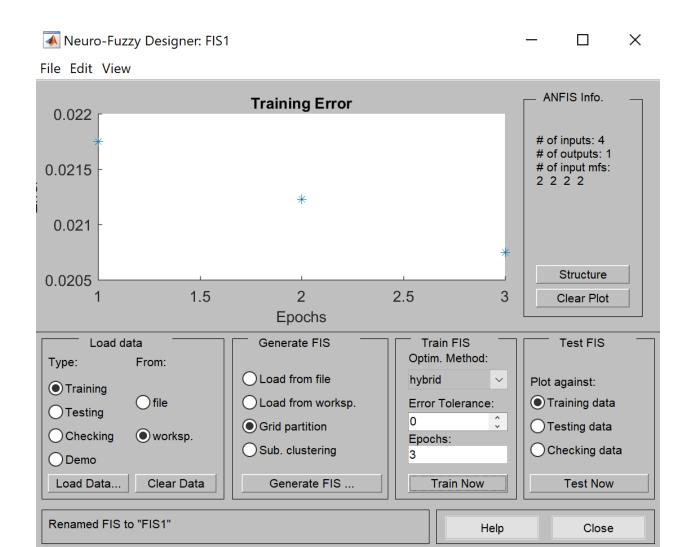
Generalized bell membership function (5-5-5) produces a pretty accurate estimate of the training data in all the different values of 'w'.

d) For the application using a FIS to fit the training data works when using a Generalized bell membership function with linear output, the generalized bell membership function with 5-5-5 configuration is accurate with 0.008245 overall error.

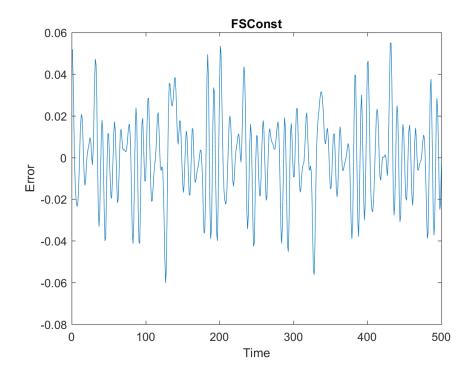
Problem 2

MATLAB Code for Generating the data for the Fuzzy Controller

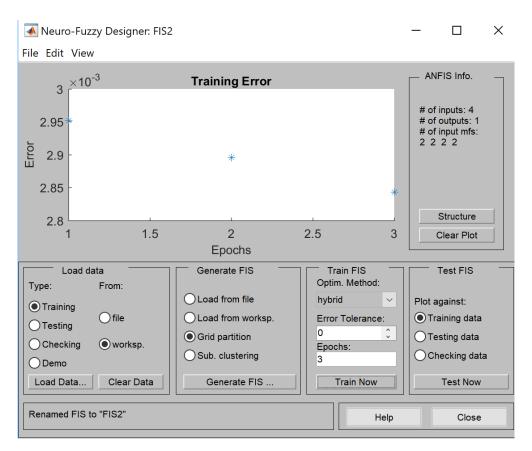
```
load mgdata.dat
a = mgdata;
time = a(:, 1);
x_t = a(:, 2);
trn data = zeros(500, 5);
chk data = zeros(500, 5);
% prepare training data
trn data(:, 1) = x t(101:600);
trn data(:, 2) = x t(107:606);
trn_{data(:, 3)} = x_t(113:612);
trn data(:, 4) = x t(119:618);
trn data(:, 5) = x t(125:624);
% prepare checking data
chk data(:, 1) = x t(601:1100);
chk data(:, 2) = x t(607:1106);
chk_{data}(:, 3) = x_t(613:1112);
chk data(:, 4) = x t(619:1118);
chk data(:, 5) = x t(625:1124);
```



For sum squared error calculation:



b) For Linear output membership function



For sum squared error calculation:

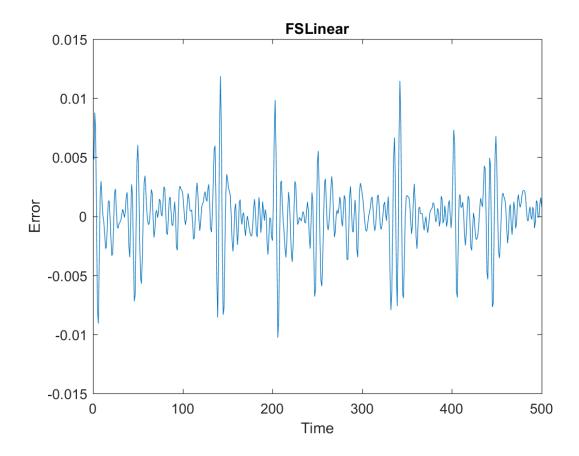
```
%For sum squared error calculation
fis_data=evalfis(chk_data(:,1:4),FIS2);
error= chk_data(:,5)-fis_data;

plot(error);
xlabel('Time');
ylabel('Error');
title('FSLinear');

%For sum squared error
Sserror2=sum(error.^2)
```

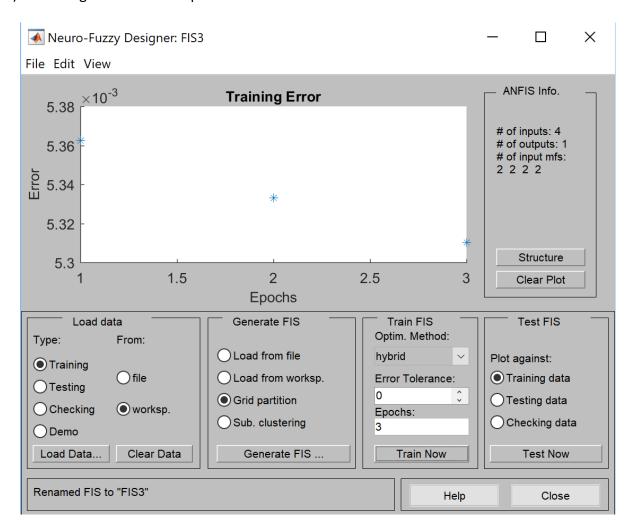
Result:

```
sserror2 = 0.0038
```



From the sum squared error value we observe that the FIS with linear output membership function has lower error as compared to the constant case. Hence, FIS with 2-2-2-2 Generalized bell membership function with linear membership function is better.

c) For Triangular Membership Function

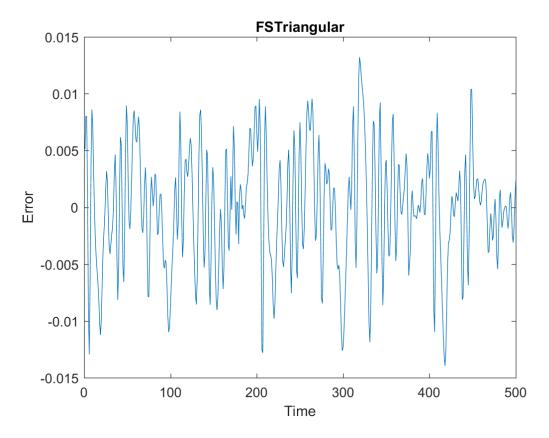


For Sum Squared Error calculation:

```
%For sum squared error calculation
fis_data=evalfis(chk_data(:,1:4),FIS3);
error= chk_data(:,5)-fis_data;
plot(error);
xlabel('Time');
ylabel('Error');
title('FSTrianguka');
%For sum squared error
sserror3=sum(error.^2)
```

Result:

sserror3 = 0.0132



Thus, we can observe that the FIS with 2-2-2-2 Generalized bell membership function & linear output membership function has much lower error than the other two cases (sse = 0.0038) & is better as compared to the other two FIS.