# Al Planning for Autonomy 1. Short Introduction to Automated (AI) Planning

Nir Lipovetzky



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## Intro: Nir Lipovetzky

I've completed my PhD on 2012 in Barcelona.

My main research interests are in the area of Automated planning, specifically:

- Planning technology (algorithms LAPKT, and tools planning.domains, planimation, etc.)
- Planning for Autonomy in industry
- Bounded General AI (Atari)  $\neq$  AGI
- Integration of Planning, Learning and Control

I've been at Melbourne Uni since 2012. You can find me at Melbourne Connect building, level 3, office 3328/Zoom/ED/E-mail.

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Love Surfing & Futbol, but not FC. Barcelona;)

## Intro: Joseph West

#### **Education:**

- BSc (Honours) in Electrical Engineering, University of New South Wales;
- PhD in Artifical Intelligence, Queensland University of Technology.

#### Research Interests:

- Machine Learning and Artificial Intelligence with a focus on general decision making and general applications
- deep learning approaches for neurological stimulation therapies covering Deep Brain Stimulation (DBS) and Spinal Cord Stimulation (SCS).

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#### Intro: Sarita Rosentock

#### **Education:**

- BSc Mathematics and Philosophy, Simon's Rock;
- Master in Mathemateical behavior Sciences, University of California Irvine;
- PhD in Logic and Philosophy, University of California Irvine.

#### Research Interests:

- Philosophy and Applied Math;
- Foundations of Physics;
- Quantitative Social Science;
- Game and Decision Theory.

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#### Intro: Tutors

Great Knowledge on COMP90054 topics.

Head Tutors: Guang Hu & Geye Guo

Tutors: Muhammad Bilal, Chenyuan Zhang, Thao Le, Kyle Warwick, Zijie (Jerry)
Xu

All former top-students of COMP90054, most are Phd Students now.

You can find Guang et al. at Melbourne Connect, Level 3/Zoom/ED/E-mail.

Contact: ghu1@student.unimelb.edu.au

Contact: geyeg@student.unimelb.edu.au

## Tell me something about you...

From which country did you watch Messi win his World Cup? ... roughly Mid-December 2022



src: Nov. 1, 2023. (AP Photo/Rodrigo Abd)

Go to pollev.com/nirlipo and enter your answer

## Outline of the Course

- Introduction to AI and (AI) Planning
- Classical Planning as Heuristic Search and Width-Based Search
- Beyond Classical Planning:
  - Factored-Model-Free, Non Determinism, Uncertainty, Soft goals, Plan Recognition, Epistemic (social) Planning, Path-Planning, Control
- 4 Reinforcement Learning: Learning through Experience
- Multi agent Planning
- 6 Hot/Latest exciting discussions on AI Ethics

#### **Acknowledgment:**

→ Slides based on earlier courses by Hector Geffner, Joerg Hoffmann, and Carmel Domshlak

# Things you Should Know to Enjoy the Course

- Algorithms such as Dynamic Programming
- Basic Set Theory and Propositional Logic
- 3 Probabilistic Theory such as Conditional Probabilities
- 4 Python, start this week doing a Tutorial to refresh your knowledge

and importantly, you need to stay up to date reviewing and understanding the content, as most lectures build up on previous knowledge

#### If you don't understand...have a question...

→ use ED: COMP90054 StackOverflow, be active in answering questions!

#### Course Structure

#### Weekly Lectures:

- Short videos covering the equivalent of 1h background knowledge (instead of Thursday's Lecture)
- Live in-person lecture: Q&A, polls, and worked examples
- → In-person Tutorials starting on week 2 watch 10min pre-recorded material
- → Online Review Quiz starting on week 2 ungraded self-assessment

#### Assignments:

- Individual early project: Search,
- Small Individual project: Modeling a planning problem,
- Mid Semester Test: short Quiz
- Final group project in the form of a competition

Rubric: Ungrading

## Competitions and open-ended projects

Pacman code released by Berkeley University, used widely for teaching purposes across best universities around the globe

We are in contact with current competitions run at RMIT, and other universities internationally

#### → The competition will be a turn-based multi-player game

Do not use online solutions, we are going to find out and it's not worth it!

It's an open-ended project, set your own goals

## Artificial + Intelligence?

- Al Concepts: What are we actually talking about?
  - Clarify what the (modern) research field of AI does, and does not, try to do.
- Al History: How did this come about?
  - Just a little background to illustrate how we came from 'classical Al' to 'modern Al'.
- Al Today: What is the landscape of techniques and applications?
  - Rough overview, and some examples.

# What is Intelligence?

#### Question: go to pollev.com/nirlipo

- Breakout room: Introduce yourself, discuss the question, and...
- Type in answers, and vote on other answers too if you agree wit them
- Ability to think . . . ?
- Simulating the brain . . . ?
- Creativity . . . ?
- Ability to learn . . . ?
- Being good at maths . . . ?
- Playing good Chess . . . ?

# What is *Artificial* Intelligence?

#### An engineering standpoint

The science of making machines do things that would require intelligence if done by humans. (M. Minsky)

Is this an operational definition? Hmm...

- How do we know what human activities require intelligence?
- BTW, what is human intelligence?

# Acting Humanly with intelligence: Turing Test



- Not reproducible... only a proof of concept?
- The chinese room experiment Jonh Searle

## What is *Artificial* Intelligence?

#### Another perspective please

The exciting new effort to make computers think. Machines with minds, in the full and literal sense. (J. Haugeland)

Same problems as with Minsky's definition:

- what is thinking?
- what is mind?

## What is *Artificial* Intelligence?

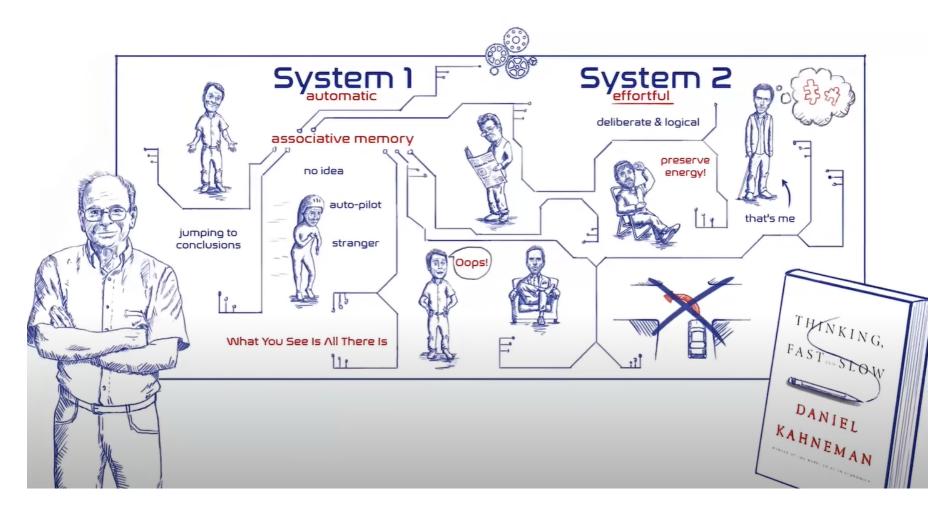
#### A Rational perspective

The branch of computer science that is concerned with the automation of intelligent behavior. (Luger and Stubblefield)

- Intelligent behavior: make 'good' (rational) action choices
- Are humans 'rational' agents? We often make mistakes; we are not all chess grandmasters even though we may know all the rules of chess.

# Rational Agents: System 1 and System 2

More about human systematic errors (*Thinking, fast and slow - Kahneman*)"



src image: https://www.youtube.com/watch?v=uvDtyJ5sg7U

### Rational Agents

#### **Agents:**

- Perceive the environment through sensors (→percepts).
- $\blacksquare$  Act upon the environment through actuators ( $\rightarrow$ actions).
- → Examples? Humans, animals, robots, software agents (softbots), . . .

#### Rational Agents . . . do 'the right thing'!

- → Any idea what that means, 'do the right thing'? Rational agents select their actions so as to maximize a performance measure.
- $\rightarrow$  Q: What's the performance measure of an autonomous vacuum cleaner?  $m^2$  per hour, Level of cleanliness, Energy usage, . . .
- → What if the vacuum cleaner's sensors are not good enough? click: Robot Revolution news "

### Rational Agents

- . . . TRY to do 'the right thing'!
- → The hypothetical best case ('the right thing') is often unattainable.
- → The agent might not be able to perceive all relevant information. (Is there dirt under this bed?)

#### Rationality vs. Omniscience:

- An omniscient agent knows everything about the environment, and knows the actual effects of its actions.
- A rational agent just makes the best of what it has at its disposal, maximizing expected performance given its percepts and knowledge.
- → Example? I check the traffic before crossing the street. As I cross, I am hit by a meteorite. Was I lacking rationality?

Mapping your input to the best possible output:

Performance measure × Percepts × Knowledge → Action

#### What Does Al Do?

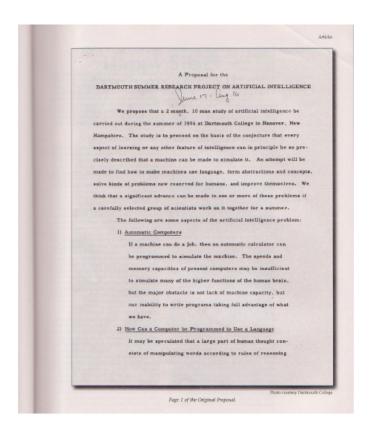
→ Artificial intelligence as an idea can be roughly classified along the dimensions thinking vs. acting and humanly vs. rationally.

	Humanly	Rationally
Thinking	Systems that think like humans	Systems that think rationally
	(Cognitive Science)	(Logics: Knowledge and Deduction)
Acting	Systems that act like humans	Systems that act rationally
	(Turing Test)	(How to make good action choices)

<sup>→</sup> A central aspect of intelligence (and one possible way to define it) is the ability to act successfully in the world

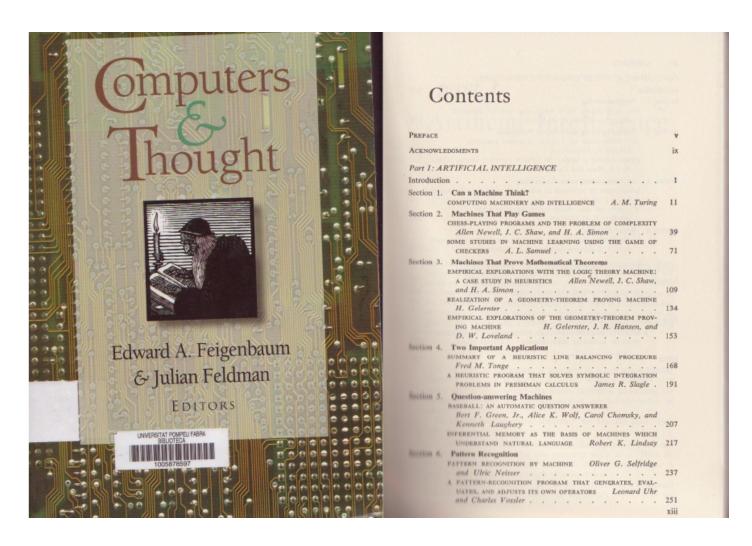
### Origins of AI: Darmouth 1956





The proposal (for the meeting) is to proceed on the basis of the conjecture that every aspect of . . . intelligence can in principle be so precisely described that a machine can be made to simulate it

## Computers and Thought 1963



An early collection of AI papers and programs for playing chess and checkers, proving theorems in logic and geometry, planning, etc.

## Al: 60's, 70's, and 80's

Many of the key AI contributions in 60's, 70's, and early 80's had to to with programming and the representation of knowledge in programs:

- Lisp (Functional Programming)
- Prolog (Logic Programming)
- Rule-based Programming
- 'Expert Systems' Shells and Architectures

## Al Methodology: Theories as Programs

For writing an Al dissertation in the 60's, 70's and 80's, it was common to:

- pick up a task and domain X
- analyze/introspect/find out how task is solved
- capture this reasoning in a program

The dissertation was then

- a theory about X (scientific discovery, circuit analysis, computational humor, story understanding, etc), and
- a program implementing the theory, tested over a few examples.

Many great ideas came out of this work . . . but there was a problem . . .

## Methodology Problem

→ Theories expressed as programs cannot be proved wrong: when a program fails, it can always be blamed on 'missing knowledge'

Three approaches to this problem

- narrow the domain (expert systems)
  - problem: lack of generality
- accept the program is just an illustration, a demo
  - problem: limited scientific value
- fill up the missing knowledge (intuition, commonsense)
  - problem: not successful so far

#### Al Winter: the 80's

- → The knowledge-based approach reached an **impasse** in the 80's, a time also of debates and controversies:
  - Good Old Fashioned AI is 'rule application' but intelligence is not (Haugeland)

Many criticisms of mainstream AI partially valid then; less valid now.

#### Al 90's - 2020

Formalization of AI techniques and increased use of mathematics. Recent issues of AIJ, JAIR, AAAI or IJCAI shows papers on:

- SAT and Constraints
- Search and Planning
- Probabilistic Reasoning
- 4 Probabilistic Planning
- Inference in First-Order Logic
- 6 Machine Learning
- Natural Language
- 8 Vision and Robotics
- 9 Multi-Agent Systems
- → Areas 1 to 4 often deemed about techniques, but more accurate to regard them as models and solvers.

## Solver Example

$$Problem \Longrightarrow \boxed{Solver} \Longrightarrow Solution$$

#### Example:

- **Problem:** The age of John is 3 times the age of Peter. In 10 years, it will be only 2 times. How old are John and Peter?
- **Expressed as:** J = 3P; J + 10 = 2(P + 10)
- **Solver:** Gauss-Jordan (Variable Elimination)
- **Solution:** P = 10 ; J = 30

Solver is **general** as deals with any problem expressed as an instance of **model** Linear Equations Model, however, is **tractable**, Al models are not . . .

#### Al Solver

$$Problem \Longrightarrow \boxed{Solver} \Longrightarrow Solution$$

- The basic models and tasks include
  - Constraint Satisfaction/SAT: find state that satisfies constraints
  - Planning Problems: find action sequence that produces desired state
  - Planning with Feedback: find strategy for producing desired state
- Solvers for these models are **general**; not tailored to specific instances
- All of these models are intractable, and some extremely powerful (POMDPs)
- The challenge is mainly computational: how to scale up
- For this, solvers must **recognize and exploit structure** of the problems
- Methodology is empirical: benchmarks and competitions
- Cignificant program in recent vectors

#### SAT and CSPs

■ SAT: determine if there is a **truth assignment** that satisfies a set of clauses

$$x \vee \neg y \vee z \vee \neg w \vee \dots \tag{1}$$

- Problem is NP-Complete, which in practice means worst-case behavior of SAT algorithms is **exponential** in number of variables ( $2^{100} = 10^{30}$ )
- Yet current SAT solvers manage to solve problems with **thousands of variables** and clauses, and used widely (circuit design, verification, planning, etc)
- Constraint Satisfaction Problems (CSPs) generalize SAT by accommodating non-boolean variables as well, and constraints that are not clauses
- Key is efficient (poly-time) inference in every node of search tree: unit resolution, conflict-based learning, ...
- Many other ideas logically possible, but do not work (don't scale up): pure search, pure inference, etc.

# Classical Planning Model

- Planning is the model-based approach to autonomous behavior,
- A system can be in one of many states
- States assign values to a set of variables
- Actions change the values of certain variables
- Basic task: find action sequence to drive initial state into goal state

$$Model \Longrightarrow \boxed{Planner} \Longrightarrow Action Sequence$$

- Complexity: NP-hard; i.e., exponential in number of vars in worst case
- Planner is generic; it should work on any domain no matter what variables are about

# Why do we need such an AI?

- Cheess: 2 player zero-sum game
- Music/Speech Recognition
- **■** Recommender systems
- Medical Diagnosis: decission support systems
- Self-driven car
- Playing Atari Games Deep Learning
- ...



## Why do we need such Al Planning?

Settings where greater autonomy required:

- Space Exploration: (RAX) first artificial intelligence control system to control a spacecraft without human supervision (1998)
- Business Process Management
- First Person Shooters & Games: classical planners playing Atari Games
- Interactive Storytelling
- Network Security
- Logistics/Transportation/Manufacturing: Multi-model Transportation, forest fire fighting, PARC printer
- Wherehouse Automation: Multi-Agent Path Finding, Post China, Amazon
- Automation of Industrial Operations (Schlumberger)
- Self Driving Cars ...

Find out more at ICAPS in Action (right panel)

## Summary: Al and Automated Problem Solving

- A research agenda that has emerged in last 20 years: solvers for a range of intractable models
- **Solvers** unlike other programs are **general** as they do not target individual problems but families of problems (**models**)
- The challenge is computational: how to scale up
- Sheer size of problem shouldn't be impediment to meaningful solution
- Structure of given problem must recognized and exploited
- Lots of room for ideas but methodology empirical
- Consistent progress
  - effective inference methods (derivation of h, conflict-learning)
  - islands of tractability (treewidth methods and relaxations)
  - transformations (compiling away incomplete info, extended goals, . . . )