

## 第 2 次作业题解答

1. 求证: 函数  $f(x, y) = \begin{cases} \frac{x^3}{y}, & y \neq 0 \\ 0, & y = 0 \end{cases}$  在原点处不连续, 但沿任何方向的方向导数均存在.

证明: 因  $\lim_{x \rightarrow 0} f(x, x^3) = 1 \neq f(0, 0)$ , 由复合函数极限法则知  $f$  在原点间断.

设  $\vec{\ell}^0 = (a, b)^T$  为任意单位向量. 若  $b \neq 0$ , 则我们有

$$\frac{\partial f}{\partial \vec{\ell}^0}(0, 0) = \lim_{h \rightarrow 0^+} \frac{f(ah, bh) - f(0, 0)}{h} = \lim_{h \rightarrow 0^+} \frac{(ah)^3}{bh^2} = 0.$$

若  $b = 0$ , 则  $\forall h > 0$ , 均有  $f(ah, bh) = f(ah, 0) = 0$ , 从而  $\frac{\partial f}{\partial \vec{\ell}^0}(0, 0) = 0$ .

综上所述可知  $f$  在原点处沿任何方向的方向导数均存在.

2. 求  $z = \sum_{i=1}^n \sum_{j=1}^n x_i x_j$  在  $P_0 = (1, 1, \dots, 1)$  处沿方向  $\vec{\ell} = (-1, -1, \dots, -1)^T$  的方向导数.

解: 由题设可知  $z = (\sum_{j=1}^n x_j)^2$ , 则对任意整数  $1 \leq i \leq n$ , 我们有

$$\frac{\partial z}{\partial x_i}(P_0) = 2 \sum_{j=1}^n x_j|_{P_0} = 2n.$$

于是所求方向导数为

$$\frac{\partial z}{\partial \vec{\ell}}(P_0) = \text{grad } z(P_0) \cdot \frac{\vec{\ell}}{\|\vec{\ell}\|} = -\frac{2n^2}{\sqrt{n}} = -2n\sqrt{n}.$$

3. 设  $u(x, y, z) = x^2 + y^2 + z^2 - xy - xz + yz$ ,  $P = (1, 1, 1)$ , 求  $u$  在点  $P$  的方向导数  $\frac{\partial u}{\partial \vec{\ell}}(P)$  的最值, 并指出取得最值时的方向, 再指出沿哪一个方向的方向导数为零.

解: 由于  $u$  为初等函数, 故可微, 于是我们有

$$\text{grad } u(P) = \begin{pmatrix} 2x - y - z \\ 2y - x + z \\ 2z - x + y \end{pmatrix} \Big|_P = \begin{pmatrix} 0 \\ 2 \\ 2 \end{pmatrix}, \quad \|\text{grad } u(P)\| = 2\sqrt{2},$$

从而  $u$  在点  $P$  的方向导数的最大值为  $2\sqrt{2}$ , 最小值为  $-2\sqrt{2}$ , 相应方向为

$$\begin{pmatrix} 0 \\ \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{pmatrix}, \quad \begin{pmatrix} 0 \\ -\frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} \end{pmatrix}.$$

而方向导数为零的方向  $\vec{\ell}^0 = (a, b, c)^T$  满足  $0 = \text{grad } u(P) \cdot \vec{\ell}^0 = 2b + 2c$ , 由此可得  $c = -b$ , 从而所求方向为  $\vec{\ell}^0 = (a, b, -b)^T$ , 其中  $a^2 + 2b^2 = 1$ .

4. 证明下列函数所满足的相应等式:

- (1)  $u = 2 \cos^2(x - \frac{y}{2})$  满足  $2 \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial x \partial y} = 0$ ,  
 (2)  $n > 0$ ,  $u = (\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^{2-n}$  满足  $\frac{\partial^2 u}{\partial x_1^2} + \frac{\partial^2 u}{\partial x_2^2} + \cdots + \frac{\partial^2 u}{\partial x_n^2} = 0$ .

证明: (1) 由题设可得

$$\begin{aligned}\frac{\partial u}{\partial y} &= 4 \cos(x - \frac{y}{2}) \cdot (-\sin(x - \frac{y}{2})) \cdot (-\frac{1}{2}) = \sin(2x - y), \\ \frac{\partial^2 u}{\partial x \partial y} &= 2 \cos(2x - y), \\ \frac{\partial^2 u}{\partial y^2} &= -\cos(2x - y),\end{aligned}$$

于是我们有  $2 \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial x \partial y} = 2 \times (-\cos(2x - y)) + 2 \cos(2x - y) = 0$ .

(2) 对任意整数  $1 \leq i \leq n$ , 我们有

$$\begin{aligned}\frac{\partial u}{\partial x_i} &= \frac{(2-n)x_i}{(\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^n}, \\ \frac{\partial^2 u}{\partial x_i^2} &= \frac{(2-n)}{(\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^n} - \frac{(2-n)nx_i^2}{(\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^{n+2}},\end{aligned}$$

由此可得  $\sum_{i=1}^n \frac{\partial^2 u}{\partial x_i^2} = \frac{(2-n)n}{(\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^n} - \sum_{i=1}^n \frac{(2-n)nx_i^2}{(\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2})^{n+2}} = 0$ .

5. 求由变换  $\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \cos \theta \cos \varphi \\ z = r \sin \varphi \end{cases} \quad (r > 0, 0 \leq \theta \leq 2\pi, 0 \leq \varphi \leq \pi)$  所确定的  
 向量值函数  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} f_1(r, \theta, \varphi) \\ f_2(r, \theta, \varphi) \\ f_3(r, \theta, \varphi) \end{pmatrix}$  的 Jacobi 矩阵和微分.

解: 由题设可知所求 Jacobi 矩阵为

$$\frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} = \begin{pmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \cos \theta \cos \varphi & -r \sin \theta \cos \varphi & -r \cos \theta \sin \varphi \\ \sin \varphi & 0 & r \cos \varphi \end{pmatrix},$$

由此可得所求微分为

$$\begin{aligned}d \begin{pmatrix} x \\ y \\ z \end{pmatrix} &= \frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} \begin{pmatrix} dr \\ d\theta \\ d\varphi \end{pmatrix} \\ &= \begin{pmatrix} \sin \theta \cos \varphi dr + r \cos \theta \cos \varphi d\theta - r \sin \theta \sin \varphi d\varphi \\ \cos \theta \cos \varphi dr - r \sin \theta \cos \varphi d\theta - r \cos \theta \sin \varphi d\varphi \\ \sin \varphi dr + r \cos \varphi d\varphi \end{pmatrix}.\end{aligned}$$

6. 设  $z = \arctan \frac{u}{v}$ ,  $u = x^2 + y^2$ ,  $v = xy$ . 求  $\frac{\partial z}{\partial x}$ ,  $\frac{\partial z}{\partial y}$ ,  $\frac{\partial^2 z}{\partial x^2}$ ,  $\frac{\partial^2 z}{\partial y^2}$ ,  $\frac{\partial^2 z}{\partial x \partial y}$ .

解: 由题设可知

$$\begin{aligned}
 \frac{\partial z}{\partial x} &= \frac{\frac{1}{v}}{1 + (\frac{u}{v})^2} \cdot (2x) + \frac{-\frac{u}{v^2}}{1 + (\frac{u}{v})^2} \cdot y = \frac{2xv - uy}{u^2 + v^2} = \frac{x^2y - y^3}{x^2y^2 + (x^2 + y^2)^2}, \\
 \frac{\partial z}{\partial y} &= \frac{\frac{1}{v}}{1 + (\frac{u}{v})^2} \cdot (2y) + \frac{-\frac{u}{v^2}}{1 + (\frac{u}{v})^2} \cdot x = \frac{2vy - ux}{u^2 + v^2} = \frac{xy^2 - x^3}{x^2y^2 + (x^2 + y^2)^2}, \\
 \frac{\partial^2 z}{\partial x^2} &= \frac{(2v + 2xy - 2xy)(u^2 + v^2) - (2xv - uy)(4ux + 2vy)}{(u^2 + v^2)^2} \\
 &= \frac{2xy(x^4 + 3x^2y^2 + y^4) - (x^2y - y^3)(6xy^2 + 4x^3)}{(x^2y^2 + (x^2 + y^2)^2)^2} \\
 &= \frac{-2x^5y + 4x^3y^3 + 8xy^5}{(x^2y^2 + (x^2 + y^2)^2)^2}, \\
 \frac{\partial^2 z}{\partial y \partial x} &= \frac{(2x^2 - 2y^2 - u)(u^2 + v^2) - (2xv - uy)(4uy + 2vx)}{(u^2 + v^2)^2} \\
 &= \frac{(x^2 - 3y^2)(x^4 + 3x^2y^2 + y^4) - (x^2y - y^3)(6x^2y + 4y^3)}{(x^2y^2 + (x^2 + y^2)^2)^2} \\
 &= \frac{x^6 - 6x^4y^2 - 6x^2y^4 + y^6}{(x^2y^2 + (x^2 + y^2)^2)^2}, \\
 \frac{\partial^2 z}{\partial y^2} &= \frac{(2xy + 2v - 2yx)(u^2 + v^2) - (2vy - ux)(4uy + 2vx)}{(u^2 + v^2)^2} \\
 &= \frac{2xy(x^4 + 3x^2y^2 + y^4) - (xy^2 - x^3)(6x^2y + 4y^3)}{(x^2y^2 + (x^2 + y^2)^2)^2} \\
 &= \frac{8x^5y + 4x^3y^3 - 2xy^5}{(x^2y^2 + (x^2 + y^2)^2)^2}.
 \end{aligned}$$

7. 已知  $u = f(x, y)$ , 其中  $x = r \cos \theta$ ,  $y = r \sin \theta$ ,  $f$  可微, 证明:

$$\left(\frac{\partial u}{\partial r}(r, \theta)\right)^2 + \left(\frac{1}{r} \frac{\partial u}{\partial \theta}(r, \theta)\right)^2 = \left(\frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta)\right)^2 + \left(\frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta)\right)^2.$$

证明: 由题设可知

$$\begin{aligned}
 &\left(\frac{\partial u}{\partial r}(r, \theta)\right)^2 + \left(\frac{1}{r} \frac{\partial u}{\partial \theta}(r, \theta)\right)^2 \\
 &= \left(\frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta) \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta) \frac{\partial y}{\partial r}\right)^2 \\
 &\quad + \left(\frac{1}{r} \frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta) \frac{\partial x}{\partial \theta} + \frac{1}{r} \frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta) \frac{\partial y}{\partial \theta}\right)^2 \\
 &= \left(\frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta) \cos \theta + \frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta) \sin \theta\right)^2 \\
 &\quad + \left(\frac{1}{r} \frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta)(-r \sin \theta) + \frac{1}{r} \frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta)(r \cos \theta)\right)^2 \\
 &= \left(\frac{\partial f}{\partial x}(r \cos \theta, r \sin \theta)\right)^2 + \left(\frac{\partial f}{\partial y}(r \cos \theta, r \sin \theta)\right)^2,
 \end{aligned}$$

因此所证结论成立.

8. 设  $f$  满足 Laplace 方程  $\partial_{11}f + \partial_{22}f = 0$ , 证明:  $u(x, y) = f(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2})$  也满足 Laplace 方程.

证明: 令  $g(x, y) = \frac{x}{x^2+y^2}$ ,  $h(x, y) = \frac{y}{x^2+y^2}$ . 则  $u = f(g, h)$ , 从而由题设可知

$$\begin{aligned} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} &= \frac{\partial}{\partial x}(\partial_1 f(g, h) \frac{\partial g}{\partial x} + \partial_2 f(g, h) \frac{\partial h}{\partial x}) + \frac{\partial}{\partial y}(\partial_1 f(g, h) \frac{\partial g}{\partial y} + \partial_2 f(g, h) \frac{\partial h}{\partial y}) \\ &= (\partial_{11}f(g, h) \frac{\partial g}{\partial x} + \partial_{21}f(g, h) \frac{\partial h}{\partial x}) \frac{\partial g}{\partial x} + \partial_1 f(g, h) \frac{\partial^2 g}{\partial x^2} \\ &\quad + (\partial_{12}f(g, h) \frac{\partial g}{\partial x} + \partial_{22}f(g, h) \frac{\partial h}{\partial x}) \frac{\partial h}{\partial x} + \partial_2 f(g, h) \frac{\partial^2 h}{\partial x^2} \\ &\quad + (\partial_{11}f(g, h) \frac{\partial g}{\partial y} + \partial_{21}f(g, h) \frac{\partial h}{\partial y}) \frac{\partial g}{\partial y} + \partial_1 f(g, h) \frac{\partial^2 g}{\partial y^2} \\ &\quad + (\partial_{12}f(g, h) \frac{\partial g}{\partial y} + \partial_{22}f(g, h) \frac{\partial h}{\partial y}) \frac{\partial h}{\partial y} + \partial_2 f(g, h) \frac{\partial^2 h}{\partial y^2} \\ &= \partial_{11}f(g, h) \left( \left( \frac{\partial g}{\partial x} \right)^2 + \left( \frac{\partial g}{\partial y} \right)^2 \right) + \partial_{22}f(g, h) \left( \left( \frac{\partial h}{\partial x} \right)^2 + \left( \frac{\partial h}{\partial y} \right)^2 \right) \\ &\quad + 2\partial_{12}f(g, h) \left( \frac{\partial g}{\partial x} \frac{\partial h}{\partial x} + \frac{\partial g}{\partial y} \frac{\partial h}{\partial y} \right) + \partial_1 f(g, h) \left( \frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} \right) \\ &\quad + \partial_2 f(g, h) \left( \frac{\partial^2 h}{\partial x^2} + \frac{\partial^2 h}{\partial y^2} \right). \end{aligned}$$

注意到  $\frac{\partial g}{\partial x} = \frac{y^2-x^2}{(x^2+y^2)^2}$ ,  $\frac{\partial g}{\partial y} = -\frac{2xy}{(x^2+y^2)^2}$ ,  $\frac{\partial h}{\partial x} = -\frac{2xy}{(x^2+y^2)^2}$ ,  $\frac{\partial h}{\partial y} = \frac{x^2-y^2}{(x^2+y^2)^2}$ , 于是  $\frac{\partial g}{\partial x} = -\frac{\partial h}{\partial y}$ ,  $\frac{\partial g}{\partial y} = \frac{\partial h}{\partial x}$ , 则  $\left( \frac{\partial g}{\partial x} \right)^2 + \left( \frac{\partial g}{\partial y} \right)^2 = \left( \frac{\partial h}{\partial x} \right)^2 + \left( \frac{\partial h}{\partial y} \right)^2$ ,  $\frac{\partial g}{\partial x} \frac{\partial h}{\partial x} + \frac{\partial g}{\partial y} \frac{\partial h}{\partial y} = 0$ , 故

$$\begin{aligned} \frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} &= \frac{\partial}{\partial x} \left( -\frac{\partial h}{\partial y} \right) + \frac{\partial}{\partial y} \left( \frac{\partial h}{\partial x} \right) = -\frac{\partial^2 h}{\partial x \partial y} + \frac{\partial^2 h}{\partial y \partial x} = 0, \\ \frac{\partial^2 h}{\partial x^2} + \frac{\partial^2 h}{\partial y^2} &= \frac{\partial}{\partial x} \left( \frac{\partial g}{\partial y} \right) + \frac{\partial}{\partial y} \left( -\frac{\partial g}{\partial x} \right) = \frac{\partial^2 g}{\partial x \partial y} - \frac{\partial^2 g}{\partial y \partial x} = 0, \end{aligned}$$

由此以及题设可得  $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = (\partial_{11}f(g, h) + \partial_{22}f(g, h)) \left( \left( \frac{\partial g}{\partial x} \right)^2 + \left( \frac{\partial g}{\partial y} \right)^2 \right) = 0$ .

9. 设向量值函数  $\mathbf{Y} = \mathbf{f}(\mathbf{U})$ ,  $\mathbf{U} = \mathbf{g}(\mathbf{X})$  可微, 求复合函数  $\mathbf{Y} = \mathbf{f} \circ \mathbf{g}(\mathbf{X})$  的 Jacobi 矩阵和全微分, 其中

$$\begin{cases} y_1 = u_1 + u_2 \\ y_2 = u_1 u_2 \\ y_3 = \frac{u_2}{u_1} \end{cases}, \quad \begin{cases} u_1 = \frac{x}{x^2+y^2} \\ u_2 = \frac{y}{x^2+y^2} \end{cases}.$$

解: 由复合函数求微分法则可知所求 Jacobi 矩阵为

$$\begin{aligned} J_{\mathbf{Y}}(\mathbf{X}) &= \begin{pmatrix} 1 & 1 \\ u_2 & u_1 \\ -\frac{u_2}{u_1^2} & \frac{1}{u_1} \end{pmatrix} \Big|_{\mathbf{U}=\mathbf{g}(\mathbf{X})} \begin{pmatrix} \frac{y^2-x^2}{(x^2+y^2)^2} & -\frac{2xy}{(x^2+y^2)^2} \\ -\frac{2xy}{(x^2+y^2)^2} & \frac{x^2-y^2}{(x^2+y^2)^2} \end{pmatrix} \\ &= \begin{pmatrix} 1 & 1 \\ \frac{y}{x^2+y^2} & \frac{x}{x^2+y^2} \\ -\frac{y(x^2+y^2)}{x^2} & \frac{x^2+y^2}{x} \end{pmatrix} \begin{pmatrix} \frac{y^2-x^2}{(x^2+y^2)^2} & -\frac{2xy}{(x^2+y^2)^2} \\ -\frac{2xy}{(x^2+y^2)^2} & \frac{x^2-y^2}{(x^2+y^2)^2} \end{pmatrix} \\ &= \begin{pmatrix} \frac{y^2-2xy-x^2}{(x^2+y^2)^2} & \frac{x^2-2xy-y^2}{(x^2+y^2)^2} \\ \frac{y^3-3xy^2}{(x^2+y^2)^3} & \frac{x^3-3xy^2}{(x^2+y^2)^3} \\ -\frac{y}{x^2} & \frac{1}{x} \end{pmatrix}, \end{aligned}$$

进而可知所求微分为

$$dY = J_Y(\mathbf{X})d\mathbf{X} = \begin{pmatrix} \frac{(y^2-2xy-x^2)dx+(x^2-2xy-y^2)dy}{(x^2+y^2)^2} \\ \frac{(y^3-3x^2y)dx+(x^3-3xy^2)dy}{(x^2+y^2)^3} \\ \frac{-ydx+xdy}{x^2} \end{pmatrix}.$$

10. 问方程  $e^{-(x+y+z)} = x+y+z$  在哪些点附近可确定一个隐函数  $z = z(x, y)$ , 并求相应的  $\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}$ .

解: 方法 1.  $\forall (x, y, z) \in \mathbb{R}^3$ , 定义  $F(x, y, z) = e^{-(x+y+z)} - (x+y+z)$ , 从而  $F$  为初等函数, 因此连续可导, 并且我们还有

$$\begin{aligned} \frac{\partial F}{\partial x}(x, y, z) &= -e^{-(x+y+z)} - 1, \\ \frac{\partial F}{\partial y}(x, y, z) &= -e^{-(x+y+z)} - 1, \\ \frac{\partial F}{\partial z}(x, y, z) &= -e^{-(x+y+z)} - 1 \neq 0. \end{aligned}$$

由隐函数定理知,  $\forall (x_0, y_0, z_0) \in \mathbb{R}^3$ , 若  $F(x_0, y_0, z_0) = 0$ , 则方程  $F(x, y, z) = 0$  在点  $(x_0, y_0, z_0)$  附近可确定一个隐函数  $z = z(x, y)$ , 并且

$$\frac{\partial z}{\partial x} = -\frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial z}} = -1, \quad \frac{\partial z}{\partial y} = -\frac{\frac{\partial F}{\partial y}}{\frac{\partial F}{\partial z}} = -1.$$

方法 2.  $\forall t \in \mathbb{R}$ , 定义  $f(t) = xe^x - 1$ . 则当  $x \leq 0$  时, 我们有  $f(x) \leq -1$ , 而当  $x > -1$  时, 则  $f'(x) = (1+x)e^x > 0$ , 因此  $f$  在  $(-1, +\infty)$  上严格递增. 又  $f(1) > 0$ , 于是由连续函数介值定理可知  $f$  在  $\mathbb{R}$  有唯一的零点, 记作  $a$ . 于是  $F(x, y, z) = 0$  当且仅当  $x+y+z = a$ , 也即  $z = a - x - y$ . 由此可得

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial y} = -1.$$

附注: 方法 2 太特殊, 缺乏普适性, 不是好的解题方法.

11. 问方程组  $\begin{cases} x+y+z+z^2=0 \\ x+y^2+z+z^3=0 \end{cases}$  在点  $P(-1, 1, 0)$  的附近能否确定一个向量值函数  $\begin{pmatrix} y \\ z \end{pmatrix} = \mathbf{f}(x)$ ? 如果能, 求  $y'(-1), z'(-1)$ .

解:  $\forall (x, y, z) \in \mathbb{R}^3$ , 定义  $F_1(x, y, z) = x+y+z+z^2$ ,  $F_2(x, y, z) = x+y^2+z+z^3$ , 则  $F_1, F_2$  均为初等函数, 因此连续可导, 并且

$$\frac{\partial(F_1, F_2)}{\partial(y, z)}(-1, 1, 0) = \begin{pmatrix} 1 & 1+2z \\ 2y & 1+3z^2 \end{pmatrix} \Big|_{(-1, 1, 0)} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix},$$

故  $\frac{D(F_1, F_2)}{D(y, z)}(-1, 1, 0) = -1 \neq 0$ , 从而由隐函数定理知, 题设方程组在点  $P$  的附近可确定一个向量值函数  $\begin{pmatrix} y \\ z \end{pmatrix} = \mathbf{f}(x)$ . 将上述方程组在点  $P$  处关于  $x$  求导可得  $1 + y'(-1) + z'(-1) = 0$ ,  $1 + 2y'(-1) + z'(-1) = 0$ , 于是我们有

$$y'(-1) = 0, \quad z'(-1) = -1.$$