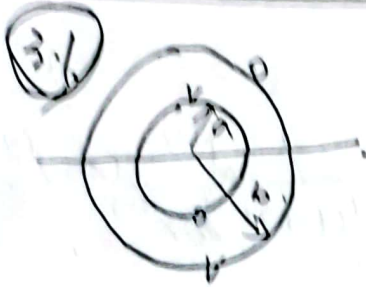




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$$\phi(r, \theta) = \sum_{l=0}^{\infty} (A_l r^l + B_l r^{-l-1}) P_l(\cos \theta)$$

$$\phi(a, \theta) = \begin{cases} V, & 0 \leq \theta \leq \frac{\pi}{2} \\ 0, & \frac{\pi}{2} < \theta < \pi \end{cases}$$

$$\phi(b, \theta) = \begin{cases} 0, & 0 \leq \theta \leq \frac{\pi}{2} \\ V, & \frac{\pi}{2} < \theta < \pi \end{cases}$$

$$\begin{aligned} V \cdot \frac{2l+1}{2} \int_0^{\pi/2} P_l(\cos \theta) d\theta &= A_l a^l + B_l a^{-l-1} \\ V \cdot \frac{2l+1}{2} \int_{\pi/2}^{\pi} P_l(\cos \theta) d\theta &= A_l b^l + B_l b^{-l-1} \end{aligned} \rightarrow \begin{cases} A_l = \frac{2l+1}{2} \frac{V}{a^l b^{-l-1} - b^l a^{-l-1}} \\ B_l = \frac{a^{l+1} (2l+1) V}{2} \int_0^1 dx - A_l a^l \end{cases}$$

$$\int_0^1 P_l(x) dx = \int_0^1 \frac{1}{2^l l!} \frac{d^l (x^2-1)^l}{dx^l} dx = \frac{(-1)^{\frac{l-1}{2}} (l-2)!!}{(l+1)!!} \quad l=2n+1$$

$$\int_{-1}^0 P_l(x) dx = \begin{cases} (-1)^{\frac{l+1}{2}} \frac{(l-2)!!}{(l+1)!!}, & l=2n+1 \\ 0, & l=2n \end{cases}$$

$$\begin{aligned} \therefore \phi(r, \theta) &= \frac{V}{2} + \left[\frac{3V(a^3-b^3)}{4(a^5-b^5)} r + \frac{3Va^2(-b^3-b^2a)}{4(a^3-b^3)} r^{-2} \right] P_1(\cos \theta) \\ &\quad + \left(\frac{7V(a^5+b^5)}{16(a^7-b^7)} r^3 + \frac{7Va^4(-b^7-b^6a)}{16(a^7-b^7)} r^{-4} \right) P_3(\cos \theta) + \dots \end{aligned}$$

 $b \rightarrow \infty, a \rightarrow 0$

$$\phi(r, \theta) = \frac{V}{2} - \frac{3V}{4b} r P_1(\cos \theta) + \frac{7V}{16b^3} r^3 P_3(\cos \theta) - \dots$$



$$1. \frac{dP_{l+1}}{dx} = \frac{d}{dx} \left(\frac{1}{2^{l+1}(l+1)!} \frac{d^{l+1}}{dx^{l+1}} (x^2-1)^{l+1} \right)$$

$$= \frac{1}{2^{l+1}(l+1)!} \frac{d^{l+2}}{dx^{l+2}} (x^2-1)^{l+1} = \frac{1}{2^{l+1}l!} \frac{d^{l+1}}{dx^{l+1}} (x^2-1)^{l+1}$$

$$= \frac{1}{2^{l+1}l!} (2l+1) P_l = (2l+1) \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2-1)^l$$

$$(2l+1)P_l + \frac{dP_{l-1}}{dx} = \frac{1}{2^l l(-1)!} \frac{d^l}{dx^l} (x^2-1)^l + \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2-1)^l + \frac{1}{2^{l+1}(l-1)!} \frac{d^{l+1}}{dx^{l+1}} (x^2-1)^{l+1}$$

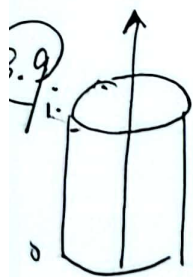
$$\frac{dP_{l+1}}{dx} = \frac{1}{2^l l!} \frac{d^l}{dx^l} \left((x^2-1)^l + 2x^2(x^2-1)^{l-1} \right)$$

$$= \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2-1)^l + \frac{1}{2^{l-1} l(-1)!} \frac{d^l}{dx^l} (x^2 \cdot (x^2-1)^{l-1})$$

$$= P_l + 2l P_{l-1} + \frac{dP_{l-1}}{dx}$$

$$\begin{aligned} & \rightarrow (x^2-1)^{l-1} + (x^2-1)^{l-1} \\ & = (x^2-1)^{l-1} + (x^2-1)^{l-1} \end{aligned}$$

$$= \frac{dP_{l-1}}{dx} + (2l+1) P_l$$



$$\psi(r, \phi, z) = R(r) X(\phi) Y(z)$$

$$\nabla^2 \psi = \frac{1}{r} \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \phi^2} + \frac{\partial^2 \psi}{\partial z^2} = 0$$

$$-\frac{1}{r^3} \frac{\partial R}{\partial r} X Y + \frac{1}{r^2} \frac{\partial^2 R}{\partial r^2} X Y + \frac{1}{r^2} \frac{\partial^2 X}{\partial \phi^2} R Y + \frac{\partial^2 Y}{\partial z^2} R X = 0$$

$$1. \frac{\partial^2 X}{X \partial \phi^2} = -\lambda^2 \rightarrow X = C_1 \sin(\lambda \phi) + C_2 \cos(\lambda \phi)$$

$$2. \frac{\partial^2 Y}{Y \partial z^2} = -\eta^2 \rightarrow Y = C_3 \sin(\eta z) + C_4 \cos(\eta z) \quad Y(0) = 0$$

$$= C_3 \sin(\eta z) = C_3 \sin \frac{n\pi}{L} z \quad Y(L) = 0$$

$$\frac{\partial^2 R}{\partial r^2} - \frac{1}{r} \frac{\partial R}{\partial r} + \lambda^2 R + \eta^2 r^2 R = 0$$

设解为 $C_4(r)$



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$$\phi = \sum_{\lambda=0}^{\infty} C_{\lambda}(r) \sin \frac{n\pi}{L} z \left(C_{\lambda n} \sin \lambda \phi + C_{2\lambda n} \cos \lambda \phi \right)$$

其中 $C_{\lambda n} = \frac{2}{L\pi} \int_0^L \phi \sin \left(\frac{n\pi}{L} z \right) \sin \lambda \phi d\phi.$

$$D_{\lambda n} = \frac{2}{L\pi} \int_0^L \phi \sin \left(\frac{n\pi}{L} z \right) \cos \lambda \phi d\phi.$$

(3.6)

$$\begin{array}{c} +a \\ | \\ 0 \\ | \\ -a \end{array} \begin{array}{c} q \\ \\ \\ -q \end{array}$$

$$\phi(r, \theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l [A_{lm} r^l + B_{lm} r^{-(l+1)}] Y_{lm}(\theta, \phi)$$

$$\phi(r, 0, 0) = \frac{1}{4\pi\epsilon_0} \frac{q}{|r-a|} - \frac{1}{4\pi\epsilon_0} \frac{q}{|r+a|} \quad \underline{\underline{???}}$$

