

## 第 11 次作业题

1. 验证  $\frac{1}{x^2}(yz dx - zx dy - xy dz)$  为某个三元函数  $u$  的全微分并求该函数.

解: 方法 1. 由题设立刻可得

$$\begin{aligned}\frac{\partial}{\partial y}\left(-\frac{y}{x}\right) - \frac{\partial}{\partial z}\left(-\frac{z}{x}\right) &= \left(-\frac{1}{x}\right) - \left(-\frac{1}{x}\right) = 0, \\ \frac{\partial}{\partial z}\left(\frac{yz}{x^2}\right) - \frac{\partial}{\partial x}\left(-\frac{y}{x}\right) &= \left(\frac{y}{x^2}\right) - \left(\frac{y}{x^2}\right) = 0, \\ \frac{\partial}{\partial x}\left(-\frac{z}{x}\right) - \frac{\partial}{\partial y}\left(\frac{yz}{x^2}\right) &= \left(\frac{z}{x^2}\right) - \left(\frac{z}{x^2}\right) = 0,\end{aligned}$$

因此  $\frac{1}{x^2}(yz dx - zx dy - xy dz)$  为某个三元函数  $u$  的全微分. 另外我们有

$$\begin{aligned}du &= \frac{1}{x^2}(yz dx - zx dy - xy dz) = -yz d\left(\frac{1}{x}\right) - \frac{z}{x} dy - \frac{y}{x} dz \\ &= -\left(yz d\left(\frac{1}{x}\right) + \frac{1}{x} d(yz)\right) + \frac{1}{x} d(yz) - \frac{z}{x} dy - \frac{y}{x} dz \\ &= -d\left(\frac{yz}{x}\right),\end{aligned}$$

于是所求原函数为  $u(x, y, z) = -\frac{yz}{x} + C$ , 其中  $C$  为任意常数.

方法 2. 由题设可知

$$\begin{aligned}\frac{1}{x^2}(yz dx - zx dy - xy dz) &= -yz d\left(\frac{1}{x}\right) - \frac{z}{x} dy - \frac{y}{x} dz \\ &= -\left(yz d\left(\frac{1}{x}\right) + \frac{1}{x} d(yz)\right) + \frac{1}{x} d(yz) - \frac{z}{x} dy - \frac{y}{x} dz \\ &= -d\left(\frac{yz}{x}\right),\end{aligned}$$

故题设微分形式为  $u$  的全微分, 其中  $u(x, y, z) = -\frac{yz}{x} + C$ , 而  $C$  为任意常数.

2. 证明曲线积分  $\int_{(0,0,0)}^{(1,2,1)} (y+z) dx + (z+x) dy + (x+y) dz$  与路径无关, 并求积分值.

解: 由于  $(y+z) dx + (z+x) dy + (x+y) dz = d(xy + yz + zx)$ , 故题设积分与路径无关, 且其积分值为  $(xy + yz + zx)\Big|_{(0,0,0)}^{(1,2,1)} = 5$ .

3. 已知标量函数  $u$ , 向量值函数  $\vec{V}, \vec{A}, \vec{B}$  为  $\mathbb{R}^3$  中的光滑函数, 证明:

- (1)  $\operatorname{div}(u\vec{V}) = u \operatorname{div}\vec{V} + \operatorname{grad}u \cdot \vec{V}$ ;
- (2)  $\operatorname{rot}(u\vec{A}) = u \operatorname{rot}\vec{A} + \operatorname{grad}u \times \vec{A}$ ;
- (3)  $\operatorname{div}(\vec{A} \times \vec{B}) = \vec{B} \cdot \operatorname{rot}\vec{A} - \vec{A} \cdot \operatorname{rot}\vec{B}$ ;
- (4)  $\operatorname{rot}(\operatorname{grad}u) = \vec{0}$ ;
- (5)  $\operatorname{div}(\operatorname{rot}\vec{A}) = 0$ .

证明: (1) 设  $\vec{V} = (V_1, V_2, V_3)^T$ , 则我们有

$$\begin{aligned}\operatorname{div}(u\vec{V}) &= \frac{\partial(uV_1)}{\partial x} + \frac{\partial(uV_2)}{\partial y} + \frac{\partial(uV_3)}{\partial z} \\ &= u\frac{\partial V_1}{\partial x} + \frac{\partial u}{\partial x}V_1 + u\frac{\partial V_2}{\partial y} + \frac{\partial u}{\partial y}V_2 + u\frac{\partial V_3}{\partial z} + \frac{\partial u}{\partial z}V_3 \\ &= u\left(\frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z}\right) + \left(\frac{\partial u}{\partial x}V_1 + \frac{\partial u}{\partial y}V_2 + \frac{\partial u}{\partial z}V_3\right) = u\operatorname{div}\vec{V} + \operatorname{gradu} \cdot \vec{V}.\end{aligned}$$

(2) 设  $\vec{A} = (A_1, A_2, A_3)^T$ , 而  $\vec{i}, \vec{j}, \vec{k}$  为  $\mathbb{R}^3$  的标准基底, 则我们有

$$\begin{aligned}\operatorname{rot}(u\vec{A}) &= \left(\frac{\partial(uA_3)}{\partial y} - \frac{\partial(uA_2)}{\partial z}\right)\vec{i} + \left(\frac{\partial(uA_1)}{\partial z} - \frac{\partial(uA_3)}{\partial x}\right)\vec{j} + \left(\frac{\partial(uA_2)}{\partial x} - \frac{\partial(uA_1)}{\partial y}\right)\vec{k} \\ &= \left(u\frac{\partial A_3}{\partial y} + \frac{\partial u}{\partial y}A_3 - u\frac{\partial A_2}{\partial z} - \frac{\partial u}{\partial z}A_2\right)\vec{i} + \left(u\frac{\partial A_1}{\partial z} + \frac{\partial u}{\partial z}A_1 - u\frac{\partial A_3}{\partial x} - \frac{\partial u}{\partial x}A_3\right)\vec{j} \\ &\quad + \left(u\frac{\partial A_2}{\partial x} + \frac{\partial u}{\partial x}A_2 - u\frac{\partial A_1}{\partial y} - \frac{\partial u}{\partial y}A_1\right)\vec{k} \\ &= u\left(\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z}\right)\vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x}\right)\vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y}\right)\vec{k}\right) \\ &\quad + \left(\left(\frac{\partial u}{\partial y}A_3 - \frac{\partial u}{\partial z}A_2\right)\vec{i} + \left(\frac{\partial u}{\partial z}A_1 - \frac{\partial u}{\partial x}A_3\right)\vec{j} + \left(\frac{\partial u}{\partial x}A_2 - \frac{\partial u}{\partial y}A_1\right)\vec{k}\right) \\ &= u\operatorname{rot}\vec{A} + \operatorname{gradu} \times \vec{A}.\end{aligned}$$

(3) 设  $\vec{B} = (B_1, B_2, B_3)^T$ , 则我们有

$$\begin{aligned}\operatorname{div}(\vec{A} \times \vec{B}) &= \operatorname{div}\left((A_2B_3 - A_3B_2)\vec{i} + (A_3B_1 - A_1B_3)\vec{j} + (A_1B_2 - A_2B_1)\vec{k}\right) \\ &= \frac{\partial(A_2B_3 - A_3B_2)}{\partial x} + \frac{\partial(A_3B_1 - A_1B_3)}{\partial y} + \frac{\partial(A_1B_2 - A_2B_1)}{\partial z} \\ &= \left(B_3\frac{\partial A_2}{\partial x} + A_2\frac{\partial B_3}{\partial x}\right) - \left(B_2\frac{\partial A_3}{\partial x} + A_3\frac{\partial B_2}{\partial x}\right) + \left(B_1\frac{\partial A_3}{\partial y} + A_3\frac{\partial B_1}{\partial y}\right) \\ &\quad - \left(B_3\frac{\partial A_1}{\partial y} + A_1\frac{\partial B_3}{\partial y}\right) + \left(B_2\frac{\partial A_1}{\partial z} + A_1\frac{\partial B_2}{\partial z}\right) - \left(B_1\frac{\partial A_2}{\partial z} + A_2\frac{\partial B_1}{\partial z}\right) \\ &= \left(B_1\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z}\right) + B_2\left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x}\right) + B_3\left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y}\right)\right) \\ &\quad - \left(A_1\left(\frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z}\right) + A_2\left(\frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x}\right) + A_3\left(\frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y}\right)\right) \\ &= \vec{B} \cdot \operatorname{rot}\vec{A} - \vec{A} \cdot \operatorname{rot}\vec{B}.\end{aligned}$$

(4) 因为  $\operatorname{gradu} = \frac{\partial u}{\partial x}\vec{i} + \frac{\partial u}{\partial y}\vec{j} + \frac{\partial u}{\partial z}\vec{k}$ , 从而由光滑性可知

$$\operatorname{rot}(\operatorname{gradu}) = \left(\frac{\partial^2 u}{\partial y \partial z} - \frac{\partial^2 u}{\partial z \partial y}\right)\vec{i} + \left(\frac{\partial^2 u}{\partial z \partial x} - \frac{\partial^2 u}{\partial x \partial z}\right)\vec{j} + \left(\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 u}{\partial y \partial x}\right)\vec{k} = \vec{0}.$$

(5) 由定义可知

$$\operatorname{rot}\vec{A} = \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z}\right)\vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x}\right)\vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y}\right)\vec{k},$$

进而由光滑性可知

$$\begin{aligned}\operatorname{div}(\operatorname{rot}\vec{A}) &= \frac{\partial}{\partial x}\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z}\right) + \frac{\partial}{\partial y}\left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x}\right) + \frac{\partial}{\partial z}\left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y}\right) \\ &= \left(\frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial^2 A_2}{\partial x \partial z}\right) + \left(\frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial y \partial x}\right) + \left(\frac{\partial^2 A_2}{\partial z \partial x} - \frac{\partial^2 A_1}{\partial z \partial y}\right) = 0.\end{aligned}$$