

$$1. (1) I = \frac{mL^2}{3} + \frac{MR^2}{2} + mL^2.$$

$$(2) l_c = \frac{m \cdot \frac{L}{2} + ML}{m+M}$$

$$I_c = I - (m+M)l_c^2 = \frac{mL^2}{3} + \frac{MR^2}{2} + mL^2 - \frac{(m \cdot \frac{L}{2} + ML)^2}{m+M}$$

$$(3) E_p = (m+M)g l_c (1 - \cos \theta) \approx \frac{L}{2} (m+M) g \theta^2$$

刚性连接

$$E_k = \frac{1}{2} I \dot{\theta}^2$$

$$= \frac{1}{2} \left(\frac{mL^2}{3} + \frac{MR^2}{2} + mL^2 \right) \dot{\theta}^2$$

$$k_{\theta} = (m+M)gL \quad m_{\theta} = \left(\frac{mL^2}{3} + \frac{MR^2}{2} + mL^2 \right)$$

$$\therefore T = 2\pi \sqrt{\frac{m_{\theta}}{k_{\theta}}} = 2\pi \sqrt{\frac{\frac{mL^2}{3} + \frac{MR^2}{2} + mL^2}{(m+M)gL}}$$

自由转动:

$$E_k = \frac{1}{2} \left(\frac{mL^2}{3} + mL^2 \right) \dot{\theta}^2$$

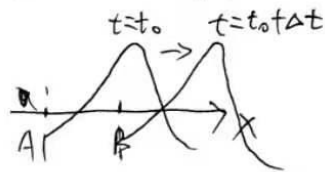
$$\therefore m'_{\theta} = \left(\frac{mL^2}{3} + mL^2 \right)$$

$$T' = 2\pi \sqrt{\frac{m'_{\theta}}{k_{\theta}}} = 2\pi \sqrt{\frac{\frac{mL^2}{3} + mL^2}{(m+M)gL}}$$

$$T > T'$$

\therefore 周期变短

2. 波向右传播时.



A在 t_0 时的相位经 Δt 后传播给B.

即B在 $t_0+\Delta t$ 时的相位与A在 t_0 时相同

\therefore 此时A相位超前于B.

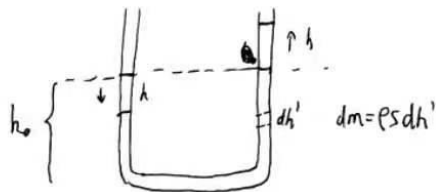
\therefore A超前 向右传播
B超前 向左传播

3. 重力势能:

$$dh \therefore dm = \rho S dh$$

$$E_p = \int gh' dm = \int_0^{h_0+h} \rho S g h' dh'$$

$$+ \int_0^{h_0-h} \rho S g h' dh' = \frac{\rho S g}{2} [(h_0-h)^2 + (h_0+h)^2] = \rho S g (h^2 + h_0^2)$$



动能:

$$E_k = \frac{M}{2} \dot{h}^2 = \frac{\rho S L}{2} \dot{h}^2 \quad (M \text{ 为液柱总质量, } L \text{ 为总长度})$$

$$\therefore \omega = \sqrt{\frac{2\rho S g}{\rho S L}} = \sqrt{\frac{2g}{L}} \quad T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{2g}}$$

4. (1) 设 x_0 时重力与弹力平衡了.

$$\therefore mg = kx_0.$$

\therefore 最低位置在 $x' = 10 \text{ cm}$ 处.

$$\therefore mgx' = \frac{1}{2}kx'^2 \Rightarrow x_0 = \frac{mg}{k} = \frac{x'}{2} = 5 \text{ cm}$$

$$m\ddot{x}' = mg - kx = k(x_0 - x)$$

$$\text{设 } y = x - x_0 \quad \therefore m\ddot{y} + ky = 0$$

$$\therefore \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{g}{5 \text{ cm}}} \approx 14 \text{ rad/s}$$



$$(2) \quad y = x - x_0 = A \cos(\omega t + \phi) \quad | \quad x = 8 \text{ cm 时.}$$

$$\text{当 } t=0 \text{ 时, } x=0 \quad v=0$$

$$\therefore \begin{cases} -x_0 = A \cos \phi \\ 0 = -A \omega \sin \phi \end{cases}$$

$$\therefore \begin{cases} \phi = 0 \\ A = -x_0 \end{cases}$$

$$x = x_0 - x_0 \cos \omega t$$

$$8 = 5(1 - \cos \omega t)$$

$$\cos \omega t = -\frac{3}{5}$$

$$\therefore \sin \omega t = \frac{4}{5}$$

$$v = x_0 \omega \sin \omega t$$

$$= 5 \times 14 \times \frac{4}{5} = 56 \text{ cm/s}$$

$$(3) \quad \omega = \sqrt{\frac{k}{m+300g}} = \frac{\omega}{2} = \frac{1}{2} \sqrt{\frac{k}{m}}$$

$$\therefore m = 100 \text{ g}$$

$$(4) \quad x_0' = \frac{(m+300g)g}{k} = \frac{4mg}{k} = 20 \text{ cm.}$$

5. 圆柱与地面间、平板与圆柱间均有 $v = \omega r$ 的相对速度，设 x 为 m 偏离平衡位置的距离

$$\therefore v_m = \omega r \quad v_M = 2\omega r = \dot{x}$$

$$\therefore v_m = \frac{\dot{x}}{2} \quad \omega = \frac{\dot{x}}{2r}$$

$$\begin{aligned} \text{动能 } E_k &= \frac{1}{2} \dot{x}^2 + 2 \left(\frac{1}{2} v_m^2 + \frac{1}{2} I \omega^2 \right) \\ &= \frac{1}{2} \dot{x}^2 + m \left(\frac{\dot{x}^2}{4} + \frac{r^2 \dot{x}^2}{2 \cdot 4r^2} \right) \\ &= \frac{1}{2} \left(m + \frac{3}{4}m \right) \dot{x}^2 \end{aligned}$$


$$\text{势能 } E_p = 2 \cdot \frac{1}{2} k x^2 = k x^2$$

\therefore 简谐运动

$$\omega = \sqrt{\frac{2k}{m + \frac{3}{4}m}} = \sqrt{\frac{2k}{m + \frac{3}{4}m}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{4m + 3m}{8k}}$$

1. 先求弹簧在自身重量下伸长的长度 (l_0 为原长):



 取一段 dy , 质量为 $dm = \rho dy = \frac{m}{l_0 + x_0} dy$
 重力势能 $dE = -dm \cdot g \cdot y = -\frac{mg}{l_0 + x_0} y dy$

总势能 $E_p = \frac{1}{2} k x_0^2 + \int dE = \frac{1}{2} k x_0^2 - \frac{mg}{l_0 + x_0} \int_0^{l_0 + x_0} y dy$
 $= \frac{1}{2} k x_0^2 - \frac{mg}{2} (l_0 + x_0)$

平衡时势能取极小值

$\frac{dE_p}{dx_0} = 0 \Rightarrow k x_0 = \frac{mg}{2} \quad x_0 = \frac{mg}{2k}$


所以弹簧在自身重量下的伸长等于无质量的弹簧挂 $\frac{m}{2}$ 的物体。


 此时 ~~重力~~ 势能为:
 $E_p = \frac{1}{2} k (x_0 + x)^2 - (\frac{m}{2} + m) g x$

x_0 为平衡时伸长长度, 有 $k x_0 = (\frac{m}{2} + m) g$

$\therefore E_p = \frac{1}{2} k x^2 + k x_0 x - (\frac{m}{2} + m) g x$
 $= \frac{1}{2} k x^2$

动能: $E_{km} = \frac{1}{2} \dot{x}^2$


 考虑 dx' 段, $dm = \frac{m}{L} dx'$ $v = \frac{x'}{L} \dot{x}$

$\therefore dE_{km} = \frac{1}{2} dm v^2 = \frac{1}{2} (\frac{m}{L} dx') (\frac{x'}{L} \dot{x})^2$

$E_{km} = \int dE_{km} = \frac{m \dot{x}^2}{2L^3} \int_0^L x'^2 dx' = \frac{m}{6} \dot{x}^2$

$E_k = E_{km} + E_{km} = \frac{1}{2} (M + \frac{m}{3}) \dot{x}^2$

$T = 2\pi \sqrt{\frac{M + \frac{m}{3}}{k}}$

$$7. \quad A = 0.001 \text{ m} \quad \lambda = 2 \times 0.1 \text{ m} = 0.2 \text{ m} \quad v = 330 \text{ m/s}$$

$$k = \frac{2\pi}{\lambda} = 10\pi \text{ rad/m}$$

$$\omega = kv = 3300\pi \text{ rad/s}$$

$$u = A \cos(kx + \omega t + \phi)$$

$$\because t=0 \quad x=0 \text{ 时 } u=0 \quad \therefore \phi = \frac{\pi}{2} \quad \therefore u = 0.001 \cos\left(10\pi x + 3300\pi t + \frac{\pi}{2}\right)$$