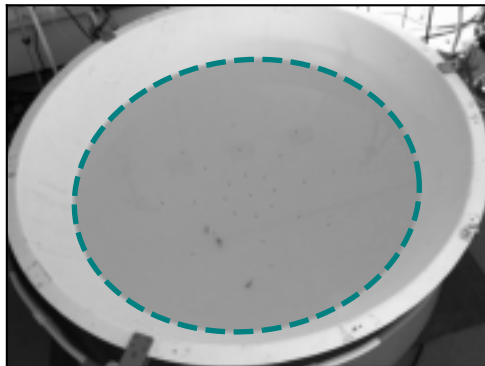


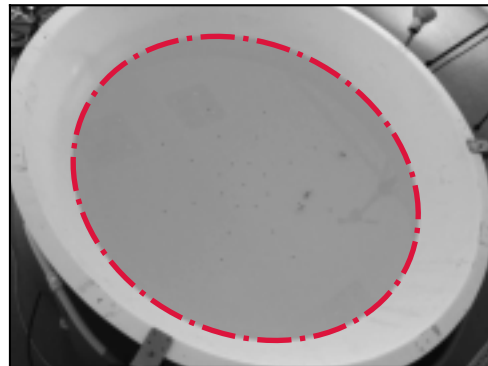
Camera 1



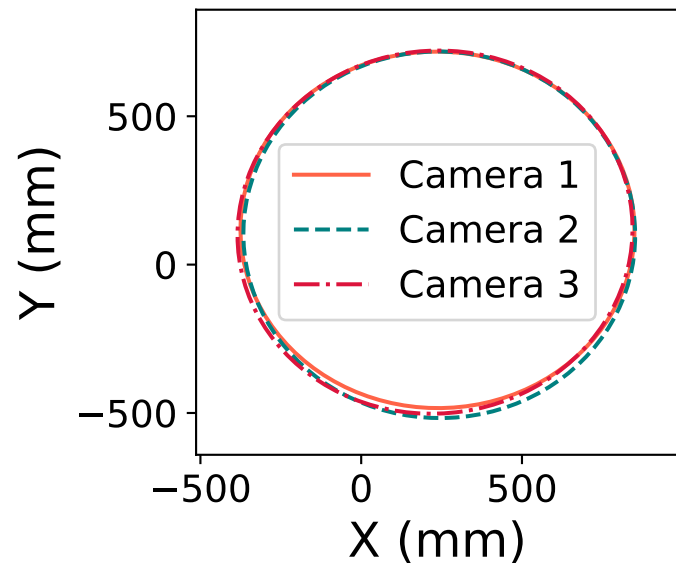
Camera 2



Camera 3



SolvePnP



SolvePnP + Optimise

