Fantastic Morphisms and Where to Find Them A Guide to Recursion Schemes

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Abstract. Structured recursion schemes have been widely used in constructing, optimising, and reasoning about programs over inductive and coinductive datatypes. Their plain forms, catamorphisms and anamorphisms, are restricted in expressiveness. Thus many generalisations have been proposed, which further lead to several unifying frameworks of structured recursion schemes. However, the existing work on unifying frameworks typically focuses on the categorical foundation, and thus is perhaps inaccessible to practitioners who are willing to apply recursion schemes in practice but are not versed in category theory. To fill this gap, this expository paper introduces structured recursion schemes from a practical point of view: a variety of recursion schemes are motivated and explained in contexts of concrete programming examples. The categorical duals of these recursion schemes are also explained.

Keywords: Recursion schemes \cdot Generic programming \cdot (Un)Folds \cdot (Co)Inductive datatypes \cdot Equational reasoning \cdot Haskell

1 Introduction

Since the introduction of *catamorphisms* by Malcolm [38], they have been a valuable item in the toolkit of functional programmers for many of their benefits: by expressing recursive programs as catamorphisms, the structure of the programs is made obvious; the recursion is ensured to terminate; and the program can be reasoned about using the calculational properties of catamorphisms.

These benefits motivated a whole research agenda concerned with identifying structural recursion schemes that capture the pattern of many other recursive functions that did not quite fit as catamorphisms. Just as with catamorphisms, these structural recursion schemes attracted attention since they make termination or productivity manifest, and enjoy many useful calculational properties which would otherwise have to be established afresh for each new application.

1.1 Diversification

The first variation on the catamorphisms was paramorphisms [40], about which Meertens talked at the 41st IFIP Working Group 2.1 (WG2.1) meeting in Burton, UK (1990). Paramorphisms describe recursive functions in which the body of

structural recursion has access to not only the (recursively computed) sub-results of the input, but also the original subterms of the input.

Then came a whole zoo of morphisms. Mutumorphisms [14], which are pairs of mutually recursive functions; zygomorphisms [37], which consist of a main recursive function and an auxiliary one on which it depends; monadic catamorphisms [13], which are recursive functions that also cause computational effects; histomorphisms [46], in which the body has access to the recursive images of all subterms, not just the immediate ones; so-called generalised folds [6], which use polymorphic recursion to handle nested datatypes; and then there were generic accumulations [44], which keep intermediate results in additional parameters for later stages in the computation.

While catamorphisms focused on terminating programs based on initial algebra, the theory also generalized in the dual direction: anamorphisms. These describe productive programs based on final coalgebras, that is, programs that progressively output structure, perhaps indefinitely. As variations on anamorphisms, there are apomorphisms [49], which may generate subterms monolithically rather than step by step; futumorphisms [46], which may generate multiple levels of a subterm in a single step, rather than just one; and many other anonymous schemes that dualise better known inductive patterns of recursion.

Recursion schemes that combined the features of inductive and coinductive datatypes were also considered. The *hylomorphism* arises when an anamorphism is followed by a catamorphism, and the *metamorphism* is when they are the other way around. A more sophisticated recursion scheme is the *dynamorphism* which encodes dynamic programming schemes, where a lookup table is coinductively constructed in an inductive computation over the input.

1.2 Unification

The many divergent generalisations of catamorphisms can be bewildering to the uninitiated, and there have been attempts to unify them. One approach is the identification of recursion schemes from comonads (rsfcs for short) by Uustalu et al. [48]. Comonads capture the general idea of 'evaluation in context' [47], and this scheme makes contextual information available to the body of the recursion. It was used to subsume both zygomorphisms and histomorphisms.

Another attempt by Hinze [22] used adjunctions as the common thread. Adjoint folds arise by inserting a left adjoint functor into the recursive characterisation, thereby adapting the form of the recursion; they subsume accumulating folds, mutumorphisms, zygomorphisms, and generalised folds. Later, it was observed that adjoint folds could be used to subsume rsfcs [25], which in turn draws on material from [22].

Thus far, the unifications had dealt largely with generalisations of catamorphisms and anamorphisms separately. The job of putting combinations of these together and covering complex beasts such as dynamorphisms was achieved by Hinze, Wu, and Gibbons [26]'s conjugate hylomorphisms, which WG2.1 dubbed mamamorphisms. This worked by viewing all recursion schemes as specialised

forms of hylomorphisms, and showing that they are well-defined hylomorphisms using adjunctions and conjugate natural transformations.

1.3 Contributions

The existing literature [25, 26, 47] on unifying accounts to structured recursion schemes has focused on the categorical foundation of recursion schemes rather than their motivations or applications, and thus is perhaps not quite useful for practitioners who would like to learn about recursion schemes and apply them in practice. To fill the gap, this paper introduces the zoo of recursion schemes by putting them in programming contexts. Hence this paper is not meant to be a regular research paper presenting new results, but a survey of recursion schemes in functional programming. The paper is organised as follows.

- Section 2 explains the idea of modelling (co)inductive datatypes as fixed points of functors, which makes generic recursion schemes possible.
- Section 3 explains the three fundamental recursion schemes: catamorphisms, which compute values by consuming inductive data; anamorphisms, which build coinductive data from values; and their common generalisation, hylomorphisms, which build data from values and consume them.
- Section 4 introduces structural recursion with an accumulating parameter.
- Section 5 is about mutual recursion on inductive datatypes, known as mutumorphisms, and their unnamed duals, which build mutually defined coinductive datatypes from a single value.
- Section 6 talks about primitive recursion, known as paramorphisms, featuring
 the ability to access both the original subterms and the corresponding output
 in the recursive function. Their corecursive counterpart, apomorphisms, and
 a generalisation, zygomorphisms, are also shown.
- Section 7 discusses the so-called course-of-values recursion, histomorphisms, featuring the ability to access the results of all direct and indirect subterms in the body of recursive function, which is typically necessary in dynamic programming. Several related schemes, futumorphisms, dynamorphisms, and chronomorphisms are briefly discussed.
- Section 8 introduces recursion schemes that cause computational effects.
- Section 9 explains recursion schemes on nested datatypes and GADTs.
- Section 11 discusses two general recipes for finding more recursion schemes.
- Finally, Section 10 briefly demonstrates how one can do equational reasoning about programs using calculational properties of recursion schemes.

The recursion schemes that we will see in this paper are summarised in Table 1. Sections 3–9 are loosely ordered by their complexity, rather than by their time appearing in the literature, and these sections are mutually independent so can be read in an arbitrary order. A common pattern in these sections is that we start with a concrete programming example, from which we distill a recursion scheme, followed by more examples. Then we consider their dual corecursion scheme and hylomorphic generalisation.

Table 1: Recursion schemes introduced in this paper

Scheme	Type Signature	Usage
Catamorphism	$(f \ a \to a) \to \mu f \to a$	Consuming inductive data
Anamorphism	$(c \to f \ c) \to c \to \nu f$	Generating coinductive data
Hylomorphism	$(f \ a \to a) \to (c \to f \ c) \to c \to a$	Generating followed by consuming
Accumulation		Recursion with an accumulating parameter
Mutumorphism	$(f(a,b) \to a) \to (f(a,b) \to b)$ $\to (\mu f \to a, \mu f \to b)$	Mutual recursion on inductive data
Dual of mutumorphism	$(c \to f \ c \ c) \to (c \to g \ c \ c)$ $\to c \to (\nu_1 f \ g, \nu_2 f \ g)$	Generating mutually defined coinductive data
Paramorphism	$(f (\mu f, a) \to a) \to \mu f \to a$	Primitive recursion, i.e. access to original input
Apomorphism	$(c \to f \ (Either \ (\nu \ f) \ c))$ $\to c \to \nu \ f$	Early termination of generation
Zygomorphism	$(f(a,b) \to a) \to (fb \to b)$ $\to \mu f \to a$	Recursion with auxiliary information
Histomorphism	$(f \ (Cofree \ f \ a) \to a) \to \mu \ f \to a$	Access to all sub-results
Dynamorphism	$(f (Cofree f a) \to a) \\ \to (c \to f c) \to c \to a$	Dynamic programing
Futumorphism	$(c \to f \ (Free \ f \ c)) \to c \to \nu \ f$	Generating multiple layers
Monadic cata- morphism	$(\forall x.f \ (m \ x) \to m \ (f \ x))$ $\to (f \ a \to m \ a) \to \mu f \to m \ a$	Recursion causing computational effects
Indexed cata- morphism	$(f \ a \stackrel{.}{\rightarrow} a) \rightarrow \dot{\mu} f \stackrel{.}{\rightarrow} a$	Consuming nested datatypes and GADTs

2 Datatypes and Fixed Points

This paper assumes basic familiarity with Haskell as we use it to present all examples and recursion schemes, but we do not assume any knowledge of category theory. In this section, we briefly review the prerequisite of recursive schemes—recursive datatypes, viewed as fixed points of functors.

Datatypes Algebraic data types (ADTs) in Haskell allow the programmer to create new datatypes from existing ones. For example, the type $List\ a$ of lists of elements of type a can be declared as follows:

$$\mathbf{data} \ List \ a = Nil \mid Cons \ a \ (List \ a) \tag{1}$$

which means that an element of $List\ a$ is exactly Nil or $Cons\ x\ xs$ for all x::a and $xs::List\ a$. Similarly, the type $Tree\ a$ of binary trees whose nodes are labelled with a-elements can be declared as follows:

$$\mathbf{data} \ \mathit{Tree} \ a = \mathit{Empty} \mid \mathit{Node} \ (\mathit{Tree} \ a) \ a \ (\mathit{Tree} \ a)$$

In definitions like List a and Tree a, the datatypes being defined also appear on the right-hand side of the declaration, so they are recursive types. Moreover, List a and Tree a are among a special family of recursive types, called inductive datatypes, meaning that they are fixed points of functors.

Functors and Algebras Endofunctors, or simply functors, in Haskell are type constructors $f :: * \to *$ instantiating the following type class:

class Functor
$$f$$
 where $fmap :: (a \rightarrow b) \rightarrow f$ $a \rightarrow f$ b

Additionally, *fmap* is expected to satisfy two functor laws:

$$fmap \ id = id$$
 $fmap \ (f \circ g) = fmap \ f \circ fmap \ g$

for all functions $f :: B \to C$ and $g :: A \to B$.

Given a functor f, we call a function of type f $a \to a$, for some type a, an f-algebra, and a function of type $a \to f$ a an f-coalgebra. In either case, type a is called the *carrier* of the (co)algebra.

Fixed Points Given a functor f, a fixed point is a type p such that p is isomorphic to f p. In the set theoretic semantics, a functor may have more than one fixed points: the *least fixed point*, denoted by μ f, is the set of f-branching trees of *finite* depths, while the *greatest fixed point*, denoted by ν f, is intuitively the set of f-branching trees of *possibly infinite* depths.

However, due to the fact that Haskell is a lazy language with general recursion, the least and greatest fixed points of a Haskell functor f coincide as the following datatype of possibly infinite f-branching trees:

newtype
$$Fix f = In \{ out :: f (Fix f) \}$$

Although Haskell allows general recursion, the point of using structural recursion is precisely avoiding general recursion whenever possible, since general recursion is typically tricky to reason about. Hence in this paper we use Haskell as if it is a total programming language, by making sure all recursive functions that we use are structural recursion. And we distinguish the least and greatest fixed points as two datatypes:

$$\mathbf{newtype}\;\mu\,f = \mathit{In}\;(f\;(\mu\,f)) \qquad \quad \mathbf{newtype}\;\nu\,f = \mathit{Out}^\circ\;(f\;(\nu\,f))$$

While these two datatypes μ f and ν f are the same datatype declaration, we mentally understand μ f as the type of *finite* f-branching trees, and ν f as the

type of possibly infinite one, as in the set-theoretic semantics. Making such a nominal distinction is not entirely pointless: the type system at least ensures that we never accidentally misuse an element of νf as an element of μf , unless we make an explicit conversion. But it is our own responsibility to make sure that we never construct an infinite element in μf using general recursion.

Example 1. The datatypes (1) and (2) that we saw earlier are isomorphic to fixed points of functors ListF and TreeF defined as follows (with the evident fmap that can be derived by GHC automatically¹):

```
data ListF \ a \ x = Nil \ | \ Cons \ a \ x \ | \ deriving \ Functor data TreeF \ a \ x = Empty \ | \ Node \ x \ a \ x \ deriving \ Functor
```

The type μ (ListF a) represents finite lists of a elements and μ (TreeF a) represents finite binary trees carrying a elements. Correspondingly, ν (ListF a) and ν (TreeF a) are possibly finite lists and trees respectively.

As an example, the correspondence between μ (ListF a) and finite elements of [a] is evidenced by the following isomorphism.

```
\begin{array}{lll} conv_{\mu} :: [\,a\,] & \rightarrow \mu \; (\mathit{ListF} \; a) & conv_{\mu}^{\circ} :: \mu \; (\mathit{ListF} \; a) & \rightarrow [\,a\,] \\ conv_{\mu} \; [\,] & = \mathit{In} \; \mathit{Nil} & conv_{\mu}^{\circ} \; (\mathit{In} \; \mathit{Nil}) & = [\,] \\ conv_{\mu} \; (a : as) = \mathit{In} \; (\mathit{Cons} \; a \; (\mathit{conv}_{\mu} \; as)) \; \mathit{conv}_{\mu}^{\circ} \; (\mathit{In} \; (\mathit{Cons} \; a \; as)) = a : \mathit{conv}_{\mu}^{\circ} \; \mathit{as} \end{array}
```

Supposing that there is a function computing the length of a list,

$$lenath :: \mu (ListF \ a) \rightarrow Integer$$

The type checker of Haskell will then ensure that we never pass a value of ν (ListF a) to this function.

Initial and Final (Co)Algebra The constructor $In :: f(\mu f) \to \mu f$ is an f-algebra with carrier μf , and it has an inverse $in^{\circ} :: \mu f \to f(\mu f)$ defined as

$$in^{\circ} (In \ x) = x$$

which is an f-coalgebra. Conversely, the constructor $Out^{\circ} :: f(\nu f) \to \nu f$ is an f-algebra with carrier νf , and its inverse $out :: \nu f \to f(\nu f)$ defined as

$$out (Out^{\circ} x) = x$$

is an f-coalgebra with carrier ν f.

What is special with In and out is that In is the so-called *initial algebra* of f, in the sense that it has the nice property that for any f-algebra $alg :: f \ a \to a$, there is exactly one function $h :: \mu f \to a$ such that

$$h \circ In = alg \circ fmap \ h \tag{3}$$

 $^{^{1}}$ It requires the <code>DeriveFunctor</code> extension of <code>GHC</code> to derive functors automatically.

Dually, out is called the final coalgebra of f since for any f-coalgebra coalg:: $c \to f$ c, there is exactly one function $h:: c \to \nu$ f such that

$$out \circ h = fmap \ h \circ coalq \tag{4}$$

The h's in (3) and (4) are precisely the two fundamental recursion schemes, catamorphisms and anamorphism, which we will talk about in the next section.

3 Fundamental Recursion Schemes

Most if not all programs are about processing data, and as Hoare [27] noted, 'there are certain close analogies between the methods used for structuring data and the methods for structuring a program which processes that data.' In essence, data structure determines program structure [11, 18]. The determination is abstracted as recursion schemes for programs processing recursive datatypes.

In this section, we look at the three fundamental recursion schemes: catamorphisms, in which the program is structured by its input; anamorphisms, in which the program is structured by its output; and hylomorphisms, in which the program is structured by an internal recursive call structure.

3.1 Catamorphisms

We start our journey with programs whose structure follows their input. As the first example, consider the program computing the length of a list:

```
\begin{array}{ll} length :: [a] & \rightarrow Integer \\ length & [] & = 0 \\ length & (x:xs) = 1 + length \ xs \end{array}
```

In Haskell, a list is either the empty list [] or x:xs, an element x prepended to list xs. This structure of lists is closely reflected by the program length, which is defined by two cases too, one for the empty list [] and one for the recursive case x:xs. Additionally, in the recursive case length (x:xs) is solely determined by length xs without further usage of xs.

List Folds The pattern in *length* is called *structural recursion* and is expressed by the function foldr in Haskell:

```
foldr :: (a \rightarrow b \rightarrow b) \rightarrow b \rightarrow [a] \rightarrow b

foldr f e [] = e

foldr f e (x : xs) = f x (foldr f e xs)
```

which is very useful in list processing. As a fold, $length = foldr \ (\lambda_- \ l \to 1 + l) \ 0$. The frequently used function map is also a fold:

$$map :: (a \to b) \to [a] \to [b]$$

$$map f = foldr (\lambda x \ xs \to f \ x : xs) []$$

Another example is the function flattening a list of lists into a list:

```
concat :: [[a]] \rightarrow [a]

concat = foldr (+++)[]
```

By expressing structural recursive functions as folds, their structure becomes clearer, similarly in spirit to the well accepted practice of structuring programs with if-conditionals and for-/while-loops in imperative languages.

Recursion Scheme 1 (*cata*). Folds on lists can be readily generalised to the generic setting, where the shape of the datatype is determined by a functor [38, 12, 19]. The resulting recursion scheme is called *catamorphisms*:

```
cata :: Functor f \Rightarrow (f \ a \rightarrow a) \rightarrow \mu f \rightarrow a

cata \ alg = alg \circ fmap \ (cata \ alg) \circ in^{\circ}
```

Intuitively, catamorphisms gradually break down the inductively defined input data, computing the result by replacing constructors with the given algebra alg. The name cata dubbed by Meertens [39] is from Greek $\varkappa\alpha\tau\acute{\alpha}$ meaning 'downwards along' or 'according to'. A notation for cata alg is the so-called banana bracket (alg) introduced by Meijer et al. [41], but we will not use this style of notation in this paper, as we will not have enough squiggly brackets for all recursion schemes that we will see.

Example 2. By converting the builtin list type [a] to the initial algebra of ListF as in Example 1, we can recover foldr from cata as follows:

```
foldr' :: (a \rightarrow b \rightarrow b) \rightarrow b \rightarrow [a] \rightarrow b

foldr' f \ e = cata \ alg \circ conv_{\mu} \ \mathbf{where}

alg \ Nil = e

alg \ (Cons \ a \ x) = f \ a \ x
```

Now we can also fold datatypes other than lists, such as binary trees:

```
\begin{array}{l} size :: \mu \; (\mathit{TreeF} \; e) \to \mathit{Integer} \\ size = \mathit{cata} \; \mathit{alg} \; \mathbf{where} \\ \mathit{alg} :: \mathit{TreeF} \; \mathit{a} \; \mathit{Integer} \to \mathit{Integer} \\ \mathit{alg} \; \mathit{Empty} \; = 0 \\ \mathit{alg} \; (\mathit{Node} \; l \; e \; r) = l+1+r \end{array}
```

Example 3 (Interpreting DSLs). The 'killer application' of catamorphisms is using them to implement domain-specific languages (DSLs) [30]. The abstract syntax of a DSL can usually be modelled as an inductive datatype, and then the (denotational) semantics of the DSL can be given as a catamorphism. The semantics given in this way is compositional, meaning that the semantics of a program is determined the semantics of its immediate sub-parts—exactly the pattern of catamorphisms.

As a small example here, consider a mini language of mutable memory consisting of three language constructs: $Put\ (i,x)\ k$ writes value x to memory cell of address i and then executes program k; $Get\ i\ k$ reads memory cell i, letting the result be s, and then executes program k s; and $Ret\ a$ terminates the execution with return value a. The abstract syntax of the language can be modelled as the initial algebra $\mu\ (ProqF\ s\ a)$ of the following functor:

```
data ProgF \ s \ a \ x = Ret \ a \mid Put \ (Int, s) \ x \mid Get \ Int \ (s \rightarrow x)
```

where s is the type of values stored by memory cells and a is the type of values finally returned. An example of a program in this language is

```
p_1 :: \mu \ (ProgF \ Int \ Int)

p_1 = In \ (Get \ 0 \ (\lambda s \rightarrow (In \ (Put \ (0, s+1) \ (In \ (Ret \ s))))))
```

which reads the 0-th cell, increments it, and returns the old value. The syntax is admittedly clumsy because of the repeating In constructors, but they can be eliminated if 'smart constructors' such as $ret = In \circ Ret$ are defined.

The semantics of a program in this mini language can be given as a value of type $Map\ Int\ s \to a$, and the interpretation is a catamorphisms:

```
\begin{array}{ll} interp :: \mu \; (ProgF \; s \; a) \to (Map \; Int \; s \to a) \\ interp = cata \; handle \; \mathbf{where} \\ handle \; (Ret \; a) &= \lambda_- \to a \\ handle \; (Put \; (i,x) \; k) = \lambda m \to k \; (update \; m \; i \; x) \\ handle \; (Get \; i \; k) &= \lambda m \to k \; (m \, ! \; i) \; m \end{array}
```

where $update \ m \ i \ x$ is the map m with the value at i changed to x, and $m \ ! \ i$ looks up i in m. Then we can use it to run programs:

```
*> interp p_1 (fromList [(0, 100)]) -- outputs 100
```

3.2 Anamorphisms

In catamorphisms, the structure of a program mimics the structure of the input. Needless to say, this pattern is insufficient to cover all programs in the wild. Imagine a program returning a record:

```
data Person = Person \{ name :: String, addr :: String, phone :: [Int] \} mkEntry :: StaffInfo \rightarrow Person mkEntry := Person \ n \ a \ p \ where \ n = ...; a = ...; p = ...
```

The structure of the program more resembles the structure of its output—each field of the output is computed by a corresponding part of the program. Similarly, when the output is a recursive datatype, a natural pattern is that the program generates the output recursively, called *(structural) corecursion* [18]. Consider the following program generating evenly spaced numbers over an interval.

```
\begin{array}{l} linspace :: RealFrac \ a \Rightarrow a \rightarrow a \rightarrow Integer \rightarrow [\, a\,] \\ linspace \ s \ e \ n = gen \ s \ \textbf{where} \\ step = (e-s) \ / \ fromIntegral \ (n+1) \\ gen \ i \\ | \ i < e \\ | \ i < e \\ | \ otherwise = [\,] \end{array}
```

The program *gen* does not mirror the structure of its numeric input at all, but it follows the structure of its output, which is a list: for the two cases of a list, [] and (:), *gen* has a corresponding branch generating it.

List Unfolds The pattern of generating a list in the example above is abstracted as the Haskell function unfoldr:

```
unfoldr :: (b \rightarrow Maybe (a, b)) \rightarrow b \rightarrow [a]

unfoldr \ g \ s = \mathbf{case} \ g \ s \ \mathbf{of}

(Just \ (a, s')) \rightarrow a : unfoldr \ g \ s'

Nothing \rightarrow []
```

in which g either produces *Nothing* indicating the end of the output or produces from a seed s the next element a of the output together with a new seed s' for generating the rest of the output. Thus we can rewrite linspace as

```
linspace s e n = unfoldr gen s where step = (e - s) / fromIntegral (n + 1) gen i = if i < e then Just (i, i + step) else Nothing
```

Note that the list produced by *unfoldr* is not necessarily finite. For example,

```
from :: Integer \rightarrow [Integer]

from = unfoldr (\lambda n \rightarrow Just (n, n + 1))
```

generates the infinite list of all integers from n.

Recursion Scheme 2 (ana). In the same way that cata generalises foldr, unfoldr can be generalised from lists to arbitrary coinductive datatypes. The (co)recursion scheme is called anamorphisms:

```
\begin{array}{l} \textit{ana} :: \textit{Functor} \ f \Rightarrow (c \rightarrow f \ c) \rightarrow c \rightarrow \nu \ f \\ \textit{ana} \ \textit{coalg} = \textit{Out}^{\circ} \circ \textit{fmap} \ (\textit{ana} \ \textit{coalg}) \circ \textit{coalg} \end{array}
```

The name is due to Meijer et al. [41]: ana from the Greek preposition $\alpha\nu\dot{\alpha}$ means 'upwards', dual to cata meaning 'downwards'.

Example 4. Modulo the isomorphism between [a] and ν (ListF a), unfoldr is an anamorphism:

```
unfoldr' :: (b \to Maybe\ (a,b)) \to b \to [a]

unfoldr'\ g = conv_{\nu}^{\circ} \circ ana\ coalg\ \mathbf{where}

coalg\ b = \mathbf{case}\ g\ b\ \mathbf{of}\ Nothing \ \to Nil

(Just\ (a,b)) \to Cons\ a\ b
```

Example 5. A more interesting example of anamorphisms is merging a pair of ordered lists:

```
\begin{array}{l} \textit{merge} :: \textit{Ord} \ a \Rightarrow (\nu \ (\textit{ListF} \ a), \nu \ (\textit{ListF} \ a)) \rightarrow \nu \ (\textit{ListF} \ a) \\ \textit{merge} = \textit{ana} \ c \ \textbf{where} \\ c \ (x,y) \\ \mid \textit{null}_{\nu} \ x \wedge \textit{null}_{\nu} \ y = \textit{Nil} \\ \mid \textit{null}_{\nu} \ y \vee \textit{head}_{\nu} \ x < \textit{head}_{\nu} \ y \\ = \textit{Cons} \ (\textit{head}_{\nu} \ x) \ (\textit{tail}_{\nu} \ x, y) \\ \mid \textit{otherwise} = \textit{Cons} \ (\textit{head}_{\nu} \ y) \ (x, \textit{tail}_{\nu} \ y) \end{array}
```

where $null_{\nu}$, $head_{\nu}$ and $tail_{\nu}$ are the corresponding list functions for ν (ListF a).

3.3 Hylomorphisms

Catamorphisms consume data and anamorphisms produce data, but some algorithms are more complex than playing a single role—they produce and consume data at the same time. Taking the quicksort algorithm for example, a (not-in-place, worst complexity $\mathcal{O}(n^2)$) implementation is:

```
\begin{array}{ll} qsort :: Ord \ a \Rightarrow [\,a\,] \rightarrow [\,a\,] \\ qsort \ [\,] &= [\,] \\ qsort \ (a:as) = qsort \ l +\!\!\!+ [\,a\,] +\!\!\!+ qsort \ r \ \mathbf{where} \\ l = [\,b \mid b \leftarrow as, \, b < a\,] \\ r = [\,b \mid b \leftarrow as, \, b \geqslant a\,] \end{array}
```

Although the input [a] is an inductive datatype, *qsort* is not a catamorphism as the recursion is not performed on the sub-list as. Neither is it an anamorphism, since the output is not produced in the head-and-recursion manner.

Felleisen et al. [11] referred to this form of recursive programs as generative recursion since the input a:as is used to generate a set of sub-problems, namely l and r, which are recursively solved, and their solutions are combined to solve the overall problem a:as. The structure of computing qsort is manifested in the following rewrite of qsort:

```
\begin{array}{l} qsort'::Ord\ a\Rightarrow [\ a\ ]\rightarrow [\ a\ ]\\ qsort'=combine\circ fmap\ qsort'\circ partition\\ partition::Ord\ a\Rightarrow [\ a\ ]\rightarrow TreeF\ a\ [\ a\ ]\\ partition\ [\ ]=Empty\\ partition\ (\ a:\ as)=Node\ [\ b\ |\ b\leftarrow as,\ b< a\ ]\ a\ [\ b\ |\ b\leftarrow as,\ b\geqslant a\ ]\\ combine::TreeF\ a\ [\ a\ ]\rightarrow [\ a\ ]\\ combine\ Empty\ =\ [\ ]\\ combine\ (Node\ l\ x\ r)=l++[\ x\ ]+r \end{array}
```

The functor $TreeF\ a\ x = Empty\ |\ Node\ x\ a\ x$ governs the recursive call structure, which is a binary tree. The $(TreeF\ a)$ -coalgebra partition divides a problem (if not trivial) into two sub-problems, and the $(TreeF\ a)$ -algebra combine concatenates the results of sub-problems to form a solution to the whole problem.

Recursion Scheme 3 (hylo). Abstracting the pattern of divide-and-conquer algorithms like qsort results in the recursion scheme hylomorphisms:

```
hylo:: Functor f \Rightarrow (f \ a \rightarrow a) \rightarrow (c \rightarrow f \ c) \rightarrow c \rightarrow a
hylo a \ c = a \circ fmap \ (hylo \ a \ c) \circ c
```

The name is due to Meijer et al. [41] and is a term from Aristotelian philosophy that objects are compounded of matter and form, where the prefix hylo- (Greek "ύλη-) means 'matter'.

Hylomorphisms are highly expressive. In fact, all recursion schemes in this paper can be defined as special cases of hylomorphisms, and Hu et al. [29] showed a mechanical way to transform almost all recursive functions in practice into hylomorphisms. In particular, hylomorphisms subsume both catamorphisms and anamorphisms: for all $alg :: f \ a \rightarrow a$ and $coalg :: c \rightarrow f \ c$, we have

```
cata \ alg = hylo \ alg \ in^{\circ} and ana \ coalg = hylo \ Out^{\circ} \ coalg.
```

However, the expressiveness of hylo comes at a cost: even when both alg:: $f \ a \to a$ and coalg:: $c \to f \ c$ are total functions, hylo alg coalg may not be total (in contrast, cata alg and ana coalg are always total whenever alg and coalg are). Intuitively, it is because the coalgebra coalg may infinitely generate sub-problems while the algebra alg may require all subproblems solved to solve the whole problem.

Example 6. As an instance of the problematic situation, consider a coalgebra

```
geo :: Integer \rightarrow ListF \ Double \ Integer

geo \ n = Cons \ (1 / fromIntegral \ n) \ (2 * n)
```

which generates the geometric sequence $\left[\frac{1}{n}, \frac{1}{2n}, \frac{1}{4n}, \frac{1}{8n}, \ldots\right]$, and an algebra

```
\begin{array}{ll} sum :: ListF \ Double \ Double \rightarrow Double \\ sum \ Nil &= 0 \\ sum \ (Cons \ n \ p) = n + p \end{array}
```

which sums a sequence. Both geo and sum are total Haskell functions, but the function $zeno = hylo \ sum \ geo$ diverges for all input i :: Integer. (It does not mean that Achilles can never overtake the tortoise—zeno diverges because it really tries to add up an infinite sequence rather than taking the limit.)

Recover Totality One way to tame the well-definedness of *hylo* is to consider coalgebras $coalg :: c \to f$ c with the special properties that the equation

$$x = alg \circ fmap \ x \circ coalg \tag{5}$$

has a unique solution $x:: c \to a$ for all algebras $alg:: f \ a \to a$. Such coalgebras are called recursive coalgebras. Dually, one can also consider corecursive algebras

alg that make (5) have a unique solution for all coalg. For example, the coalgebra $in^{\circ} :: \mu f \to f \ (\mu f)$ is recursive, since the equation

$$x = alg \circ fmap \ x \circ in^{\circ} \iff x \circ In = alg \circ fmap \ x$$

has a unique solution by property (3) of the initial algebra. Dually, Out° :: $f(\nu f) \rightarrow \nu f$ is a corecursive algebra by (4).

Besides these two basic examples, quite some effort has been made in searching for more recursive coalgebras (and corecursive algebras): Capretta et al. [9] first show that it is possible to construct new recursive coalgebras from existing ones using comonads, and later Hinze et al. [26] show a more general technique using adjunctions and conjugate pairs. With these techniques, all recursion schemes on (co)inductive datatypes presented in this paper can be uniformly understood as hylomorphisms with a recursive coalgebra or corecursive algebra. However, we shall not emphasise this perspective in this paper since it sometimes involves non-trivial category theory to massage a recursion scheme into a hylomorphism with a recursive coalgebras (or a corecursive algebra).

Example 7. The coalgebra partition::[a] \to TreeF a [a] above is recursive (when only finite lists are allowed as input). This can be proved by an easy inductive argument: for any total alg:: TreeF a b \to b, suppose that $x :: [a] \to b$ satisfies

$$x = alg \circ fmap \ x \circ partition. \tag{6}$$

Given any finite list l, we show x l is determined by alg by an induction on l. For the base case l = [], we have

```
x[] = alg (fmap \ x \ (partition \ [])) = alg (fmap \ x \ Empty) = alg \ Empty.
```

For the inductive case l = y : ys, we have

```
x (y:ys) = alg (fmap \ x (partition (y:ys)))= alg (fmap \ x (Node \ ls \ a \ rs))= alg (Node (x \ ls) \ a (x \ rs))
```

where $ls = [b \mid b \leftarrow as, b < a]$ and $rs = [b \mid b \leftarrow as, b \geqslant a]$ are strictly smaller than l = (a:as), and thus x ls and x rs are uniquely determined by alg. Consequently, x (y:ys) is uniquely determined by alg. Thus we conclude that x satisfying the hylo equation (6) is unique.

Aside: Metamorphisms If we separate the producing and consuming phases of a hylomorphism hylo alg coalg for some recursive coalg, we have the following equations (both follow the uniqueness of the solution to hylomorphism equations with recursive coalgebra coalg):

hylo alg coalg = cata alg
$$\circ$$
 hylo In coalg
= cata alg \circ $\nu 2\mu \circ$ ana coalg

where $\nu 2\mu = hylo$ In out:: $\nu f \to \mu f$ is the partial function that converts the finite subset of a coinductive datatype into its inductive counterpart. Thus loosely speaking, a hylo is a cata after an ana. The opposite direction of composition can also be considered:

```
meta :: (Functor\ f, Functor\ g) \Rightarrow (c \rightarrow g\ c) \rightarrow (f\ c \rightarrow c) \rightarrow \mu\ f \rightarrow \nu\ g
meta coalg alg = ana coalg \circ cata alg
```

which is called metamorphisms by Gibbons [16] because it metamorphoses data represented by functor f to g. Unlike hylomorphisms, the producing and consuming phases in metamorphisms cannot be straightforwardly fused into a single recursive function. Gibbons [16, 17] gives conditions for doing this when f is ListF, but we will not expand on this in this paper.

4 Accumulations

Accumulating parameters are a well known technique for optimising recursive functions. An example is optimising the following *reverse* function that runs in quadratic time (due to the fact that xs + ys runs in $\mathcal{O}(length\ xs)$ time)

```
reverse :: [a] \rightarrow [a]

reverse [] = []

reverse (x : xs) = reverse \ xs + [x]
```

to linear time by first generalising the function with an additional parameter—an accumulating parameter ys:

```
 \begin{array}{ll} revCat :: [a] \rightarrow [a] \rightarrow [a] \\ revCat \ ys \ [] &= ys \\ revCat \ ys \ (x:xs) = revCat \ (x:ys) \ xs \end{array}
```

and it specialises to reverse by letting reverse = recCat []. This pattern of scanning a list from left to right and accumulating a parameter at the same time is abstracted as the Haskell function foldl:

```
foldl :: (b \to a \to b) \to b \to [a] \to b

foldl \ f \ e \ [] = e

foldl \ f \ e \ (x : xs) = foldl \ f \ (f \ e \ x) \ xs
```

which specialises to revCat for $f = \lambda ys \ x \to x : ys$. Similar to foldr, foldl follows the structure of the input—a base case for [] and an inductive case for x : xs. What differs is that foldl has an argument e varied during the recursion.

The pattern of accumulation is not limited to lists. For example, consider writing a program that transforms a binary tree labelled with integers to the tree whose nodes are relabelled with the sum of the labels along the path from the root in the original tree. A natural idea is to keep an accumulating parameter for the sum of labels from the root:

```
relabel :: \mu (TreeF Integer) \rightarrow Integer \rightarrow \mu (TreeF Integer)
relabel (In Empty) s = \text{In Empty}
relabel (In (Node l e r)) s = \text{In (Node (relabel } l s') s' (relabel r s'))
where s' = s + e
```

In the Node case, the current accumulating parameter s is updated to s' for both of the subtrees, but we can certainly accumulate the parameter for the subtrees using other accumulating strategies. In general, an accumulating strategy can be captured as a function of type

```
\forall x. TreeF \ Integer \ x \rightarrow Integer \rightarrow TreeF \ Integer \ (x, Integer)
```

For example, the strategy for relabel is

```
st_{relabel} Empty s = Empty

st_{relabel} (Node l \ e \ r) s = Node \ (l, s') \ e \ (r, s') where s' = s + e
```

Notice that the type above is polymorphic over x, which means that the accumulation cannot depend on the subtrees. This is not strictly necessary, but it reflects the pattern of most accumulations in practice.

Recursion Scheme 4 (accu). Abstracting the idea for a generic initial algebra, we obtain the recursion scheme accumulations [28, 44, 15]²:

```
 \begin{array}{c} accu :: Functor \ f \Rightarrow (\forall x.f \ x \rightarrow p \rightarrow f \ (x,p)) \\ \qquad \rightarrow (f \ a \rightarrow p \rightarrow a) \rightarrow \mu \ f \rightarrow p \rightarrow a \\ accu \ st \ alg \ (In \ t) \ p = alg \ (fmap \ (uncurry \ (accu \ st \ alg)) \ (st \ t \ p)) \ p \end{array}
```

Using the recursion scheme, the relabel function can be rewritten as

```
relabel' :: \mu (TreeF Integer) \rightarrow Integer \rightarrow \mu (TreeF Integer) relabel' = accu st_{relabel} alg where alg Empty s = \text{In Empty} alg (Node l - r) s = \text{In (Node } l \ s \ r)
```

Example 8. In Example 3, the semantics function *interp* is written as a catamorphism into a function type $Map\ Int\ s \to a$. With a closer look, we can see that the $Map\ Int\ s$ parameter is an accumulating parameter, so we can more accurately express *interp* using accu:

```
\begin{array}{l} interp' :: \mu \; (ProgF \; s \; a) \rightarrow Map \; Int \; s \rightarrow a \\ interp' = accu \; st \; alg \; \textbf{where} \\ st :: ProgF \; s \; a \; x \rightarrow Map \; Int \; s \rightarrow ProgF \; s \; a \; (x, Map \; Int \; s) \\ st \; (Ret \; a) \qquad \qquad m = Ret \; a \end{array}
```

² The recursion scheme requires the GHC extension RankNTypes since the first argument involves a polymorphic function.

```
\begin{array}{ll} st\;(Put\;(i,x)\;k)\;m=Put\;(i,x)\;(k,update\;m\;i\;x)\\ st\;(Get\;i\;k) & m=Get\;i\;(\lambda x\to(k\;x,m))\\ alg::ProgF\;s\;a\;a\to Map\;Int\;s\to a\\ alg\;(Ret\;a) & m=a\\ alg\;(Put\;_{-}k)\;m=k\\ alg\;(Get\;i\;k) & m=k\;(m\,!\,i) \end{array}
```

Compared to the previous version interp in Example 3, this version interp' here singles out st, which controls how the memory m is altered by each operation, whereas alg shows how each operation continues.

5 Mutual Recursion

This section is about *mutual recursion* in two forms: mutually recursive functions and mutually recursive datatypes. The former is abstracted as a recursion scheme called mutumorphisms, and we will discuss its categorical dual, which turns out to be corecursion generating mutually recursive datatypes.

5.1 Mutumorphisms

In Haskell, function definitions can not only be recursive but also be mutually recursive—two or more functions are defined in terms of each other. A simple example is isOdd and isEven determining the parity of a natural number:

```
\begin{array}{ll} \textbf{data} \; NatF \; a = Zero \; | \; Succ \; a \\ isEven :: \; Nat \to Bool \\ isEven \; (In \; Zero) \; = \; True \\ isEven \; (In \; (Succ \; n)) = isOdd \; n \end{array} \qquad \begin{array}{ll} \textbf{type} \; Nat = \mu \; NatF \\ isOdd :: \; Nat \to Bool \\ isOdd \; (In \; Zero) \; = \; False \\ isOdd \; (In \; (Succ \; n)) = isEven \; n \end{array}
```

Here we are using an inductive definition of natural numbers: Zero is a natural number and Succ n is a natural number whenever n is. Both isEven and isOdd are very much like a catamorphism: they have a non-recursive definition for the base case Zero, and a recursive definition for the inductive case Succ n in terms of the substructure n, except that their recursive definitions depend on the recursive result for n of the other function, instead of their own, making them not a catamorphism.

Another example of mutual recursion is the following way of computing Fibonacci number F_i (i.e. $F_0 = 0$, $F_1 = 1$, and $F_n = F_{n-1} + F_{n-2}$ for $n \ge 2$):

```
 \begin{array}{ll} \mathit{fib} :: \mathit{Nat} \to \mathit{Integer} & \mathit{aux} :: \mathit{Nat} \to \mathit{Integer} \\ \mathit{fib} \; (\mathit{In} \; \mathit{Zero}) = 0 & \mathit{aux} \; (\mathit{In} \; \mathit{Zero}) = 1 \\ \mathit{fib} \; (\mathit{In} \; (\mathit{Succ} \; n)) = \mathit{fib} \; n + \mathit{aux} \; n & \mathit{aux} \; (\mathit{In} \; (\mathit{Succ} \; n)) = \mathit{fib} \; n \\ \end{array}
```

The function aux n is defined to be equal to the (n-1)-th Fibonacci number F_{n-1} for $n \ge 1$, and aux 0 is chosen to be $F_1 - F_0 = 1$. Consequently, fib $0 = F_0$,

$$fib\ 1 = fib\ 0 + aux\ 1 = F_0 + (F_1 - F_0) = F_1,$$

and fib n = fib (n - 1) + fib (n - 2) for n >= 2, which matches the definition of Fibonacci sequence.

Well-Definedness The recursive definitions of the examples above are well-defined, in the sense that there is a unique solution to each group of recursive definitions regarded as a system of equations. For the example of *fib* and *aux*, the values at *Zero* are uniquely determined for both functions:

$$\langle fib \ 0, aux \ 0 \rangle = \langle 0, 1 \rangle$$

Then the values at *Succ Zero* are uniquely determined for both functions too, according to their inductive cases: $\langle fib \ 1, aux \ 1 \rangle = \langle 1, 0 \rangle$, and so on for all inputs:

$$\langle fib \ 2, aux \ 2 \rangle = \langle 1, 1 \rangle, \ \langle fib \ 3, aux \ 3 \rangle = \langle 2, 1 \rangle, \ \langle fib \ 4, aux \ 4 \rangle = \langle 3, 2 \rangle, \ \dots$$

The same line of reasoning applies too when we generalise this pattern to mutual recursion on a generic inductive datatype.

Recursion Scheme 5. The *mutumorphism* [12] is the recursion scheme for defining two mutually recursive functions on inductive datatypes:

```
mutu :: Functor \ f \Rightarrow (f \ (a,b) \rightarrow a) \rightarrow (f \ (a,b) \rightarrow b) \rightarrow (\mu \ f \rightarrow a, \mu \ f \rightarrow b)
mutu \ alg_1 \ alg_2 = (fst \circ cata \ alg, snd \circ cata \ alg)
\mathbf{where} \ alg \ x = (alg_1 \ x, alg_2 \ x)
```

in which alg_1 and alg_2 respectively compute the results of the two functions being defined, from the sub-results of both functions. The name mutumorphism is a bit special in the zoo of recursion schemes: the prefix mutu- is from Latin rather than Greek.

For example, using mutu, fib can be expressed as

$$fib' = fst \ (mutu \ f \ g) \ \mathbf{where}$$
 $f \ Zero = 0$
 $f \ (Succ \ (n, m)) = n + m$
 $g \ Zero = 1$
 $g \ (Succ \ (n, _)) = n$

In the unifying theory of recursion schemes of conjugate hylomorphisms, a mutumorphism mutu alg_1 $alg_2::(\mu\ f\to a,\mu\ f\to b)$ is the left-adjunct of a catamorphism of type $\mu\ f\to (a,b)$ via the adjunction $\Delta\dashv\times$ between the product category $C\times C$ and some base category C [24] (In the setting of this paper, $C=\mathbf{Set}$). The same adjunction also underlies a dual corecursion scheme that we explain below.

5.2 Dual of Mutumorphisms

As a mutumorphism is two or more mutually recursive functions folding one inductive datatype, we can consider its dual—unfolding a seed to two or more mutually-defined coinductive datatypes. An instructive example is recovering

an expression from a Gödel number that encodes the expression. Consider the grammar of a simple family of arithmetic expressions:

```
data Expr = Add Expr Term | Minus Expr Term | From T Term data Term = Lit Integer | Neg Term | Paren Expr
```

which is a pair of mutually-recursive datatypes. A Gödel numbering of this grammar *invertibly* maps an *Expr* or a *Term* to a natural number, for example:

$$g \ (Add \ e \ t) = 2^{g \ e} * 3^{h \ t} \qquad \qquad h \ (Lit \ n) = 2^{encLit \ n}$$
 $g \ (Minus \ e \ t) = 5^{g \ e} * 7^{h \ t} \qquad \qquad h \ (Neg \ t) = 3^{h \ t}$ $g \ (From T \ t) = 11^{h \ t} \qquad \qquad h \ (Paren \ e) = 5^{g \ e}$

where $encLit\ n = \mathbf{if}\ n \ge 0$ then 2*n+1 else 2*(-n) invertibly maps any integer to a positive integer. Although the encoding functions g and h clearly hint at a recursion scheme (of folding mutually-recursive datatypes to the same type), in this section we pay our attention to the opposite decoding direction:

```
\begin{array}{l} decE :: Integer \rightarrow Expr \\ decE \ n = \mathbf{let} \ (e_2, e_3, e_5, e_1, e_{11}) = factorise11 \ n \\ \mathbf{in} \ \mathbf{if} \ e_2 > 0 \ \lor \ e_3 > 0 \ \mathbf{then} \ Add \ (decE \ e_2) \ (decT \ e_3) \\ \mathbf{else} \ \mathbf{if} \ e_5 > 0 \ \lor \ e_1 > 0 \\ \mathbf{then} \ Minus \ (decE \ e_5) \ (decT \ e_1) \\ \mathbf{else} \ FromT \ (decT \ e_{11}) \\ \\ decT :: Integer \rightarrow Term \\ decT \ n = \mathbf{let} \ (e_2, e_3, e_5, \_, \_) = factorise11 \ n \\ \mathbf{in} \ \mathbf{if} \ e_2 > 0 \ \mathbf{then} \ Lit \ (decLit \ e_2) \\ \mathbf{else} \ \mathbf{if} \ e_3 > 0 \ \mathbf{then} \ Neg \ (decT \ e_3) \\ \mathbf{else} \ Paren \ (decE \ e_5) \end{array}
```

where factorise11 n computes the exponents for 2, 3, 5, 7 and 11 in the prime factorisation of n, and decLit is the inverse of encLit. Functions decT and decE can correctly recover the encoded expression/term because of the fundamental theorem of arithmetic (i.e. the unique-prime-factorization theorem).

In the definitions of decE and decT, the choice of decE or decT when making a recursive call must match the type of the substructure at that position. It would be convenient, if the correct choice (of decE or decT) can be automatically made based on the types—we can let a recursion scheme do the job for us.

For the generality of our recursion scheme, let us first generalise Expr and Term to an arbitrary pair of mutually recursive datatypes, which we model as fixed points of two bifunctors f and g. Likewise, the least fixed point models finite inductive data, and the greatest fixed point models possibly infinite coinductive data. Here we are interested in the latter:

```
\begin{array}{ll} \textbf{newtype} \; \nu_1 \; f \; g \; \textbf{where} & \textbf{newtype} \; \nu_2 \; f \; g \; \textbf{where} \\ Out_1^\circ :: f \; (\nu_1 \; f \; g) \; (\nu_2 \; f \; g) \rightarrow \nu_1 \; f \; g & Out_2^\circ :: g \; (\nu_1 \; f \; g) \; (\nu_2 \; f \; g) \rightarrow \nu_2 \; f \; g \end{array}
```

For instance, Expr is isomorphic to ν_1 ExprF TermF and Term is isomorphic to ν_2 ExprF TermF:

```
data ExprF\ e\ t = Add'\ e\ t\ |\ Minus'\ e\ t\ |\ From T'\ t data TermF\ e\ t = Lit'\ Int\ |\ Neg'\ t\ |\ Paren'\ e
```

Recursion Scheme 6 (*comutu*). Now we can define a recursion scheme that generates a pair of mutually recursive datatypes from a single seed:

```
\begin{array}{l} comutu:: (Bifunctor\ f, Bifunctor\ g) \Rightarrow (c \rightarrow f\ c\ c) \rightarrow (c \rightarrow g\ c\ c) \\ \rightarrow c \rightarrow (\nu_1\ f\ g, \nu_2\ f\ g) \\ comutu\ c_1\ c_2\ s = (x\ s, y\ s)\ \mathbf{where} \\ x = Out_1^\circ \circ bimap\ x\ y \circ c_1 \\ y = Out_2^\circ \circ bimap\ x\ y \circ c_2 \end{array}
```

which remains unnamed in the literature.

Example 9. The comutu scheme renders our decoding example to become

```
\begin{array}{l} decExprTerm :: Integer \rightarrow (\nu_1 \ ExprF \ TermF, \nu_2 \ ExprF \ TermF) \\ decExprTerm = comutu \ genExpr \ genTerm \\ genExpr :: Integer \rightarrow ExprF \ Integer \ Integer \\ genExpr \ n = \\ & \textbf{let} \ (e_2, e_3, e_5, e_1, e_{11}) = factorise11 \ n \\ & \textbf{in if} \ e_2 > 0 \lor e_3 > 0 \ \textbf{then} \ Add' \ e_2 \ e_3 \\ & \textbf{else if} \ e_5 > 0 \lor e_1 > 0 \\ & \textbf{then} \ Minus' \ e_5 \ e_1 \ \textbf{else} \ FromT' \ e_{11} \\ genTerm :: Integer \rightarrow TermF \ Integer \ Integer \\ genTerm \ n = \\ & \textbf{let} \ (e_2, e_3, e_5, \_, \_) = factorise11 \ n \\ & \textbf{in if} \ e_2 > 0 \ \textbf{then} \ Lit' \ (decLit \ e_2) \\ & \textbf{else if} \ e_3 > 0 \ \textbf{then} \ Neg' \ e_3 \ \textbf{else} \ Paren' \ e_5 \\ \end{array}
```

Comparing to the direct definitions of decE and decT, genTerm and genExpr are simpler as they just generate a new seed for each recursive position and recursive calls of the correct type is invoked by the recursion scheme comutu.

Theoretically, comutu is the adjoint unfold from the adjunction $\Delta \dashv \times :$ comutu $c_1 \ c_2 :: c \to (\nu_1 \ f \ g, \nu_2 \ f \ g)$ is the right-adjunct of an anamorphism of type $(c \to \nu_1 \ f \ g, c \to \nu_2 \ f \ g)$ in the product category $C \times C$. A closely related adjunction $+ \dashv \Delta$ also gives two recursion schemes for mutual recursion. One is an adjoint fold that consumes mutually recursive datatypes, of which an example is the encoding function of Gödel numbering discussed above, and dually an adjoint unfold that generates $\nu \ f$ from seed Either $c_1 \ c_2$, which captures mutual corecursion. Although attractive and practically important, we forgo an exhibition of these two recursion schemes here.

6 Primitive (Co)Recursion

In this section, we investigate the pattern in recursive programs in which the original input is directly involved besides the recursively computed results, resulting in a generalisation of catamorphisms—paramorphisms. We also discuss a generalisation, zygomorphisms, and the categorical dual apomorphisms.

6.1 Paramorphisms

A wide family of recursive functions that are not directly covered by catamorphisms are those in whose definitions the original substructures are directly used in addition to their images under the function being defined. An example is one of the most frequently demonstrated recursive function *factorial*:

```
factorial :: Nat \rightarrow Nat

factorial (In Zero) = 1

factorial (In (Succ n)) = In (Succ n) * factorial n
```

In the second case, besides the recursively computed result $factorial\ n$, the substructure n itself is also used, but it is not directly provided by cata. A slightly more practical example is counting the number of words (more accurately, maximal sub-sequences of non-space characters) in a list of characters:

```
wc :: \mu \ (ListF \ Char) \rightarrow Integer

wc \ (In \ Nil) = 0

wc \ (In \ (Cons \ c \ cs)) = \mathbf{if} \ isNewWord \ \mathbf{then} \ wc \ cs + 1 \ \mathbf{else} \ wc \ cs

\mathbf{where} \ isNewWord = \neg \ (isSpace \ c) \land (null \ cs \lor isSpace \ (head \ cs))
```

Again in the second case, cs is used besides wc cs, making it not a direct instance of catamorphisms either.

To express factorial and wc with a structural recursion scheme, we can use mutumorphisms by understanding factorial and wc as mutually defined with with the identity function. For example,

```
\begin{array}{ll} factorial' = fst \; (mutu \; alg \; alg_{id}) \; \textbf{where} \\ alg \; Zero & = 1 \\ alg \; (Succ \; (fn,n)) \; = (In \; (Succ \; n)) * fn \\ alg_{id} \; Zero & = In \; Zero \\ alg_{id} \; (Succ \; (\_,n)) = In \; (Succ \; n) \end{array}
```

Better is to use a recursion scheme that captures this common pattern.

Recursion Scheme 7. Structural recursion with access to the original subparts of the input are captured as the following scheme called *paramorphisms* [40]:

```
para :: Functor f \Rightarrow (f(\mu f, a) \rightarrow a) \rightarrow \mu f \rightarrow a
para alg = alg \circ fmap (id \triangle para alg) \circ in^\circ \text{ where}
(f \triangle g) x = (f x, g x)
```

The prefix para- is derived from Greek παρά, meaning 'beside'.

Example 10. With para, factorial is defined neatly:

```
factorial'' = para \ alg \ \mathbf{where}

alg \ Zero = 1

alg \ (Succ \ (n, fn)) = In \ (Succ \ n) * fn
```

Compared with *cata*, *para* also supplies the original substructures besides their images to the algebra. However, *cata* and *para* are interdefinable in Haskell. Every catamorphism is simply a paramorphism that makes no use of the additional information:

```
cata \ alg = para \ (alg \circ fmap \ snd)
```

Conversely, every paramorphism together with the identity function is a mutumorphism, which in turn is a catamorphism for a pair type (a, b), or directly:

$$para \ alg = snd \circ cata \ ((In \circ fmap \ fst) \triangle \ alg)$$

Sometimes the recursion scheme of paramorphisms is called *primitive recursion*. However, functions definable with paramorphisms in Haskell are beyond primitive recursive functions in computability theory because of the presence of higher order functions. Indeed, the canonical example of non-primitive recursive function, the Ackermann function, is definable with *cata* and thus *para*:

```
ack :: Nat \rightarrow Nat \rightarrow Nat

ack = cata \ alg \ \mathbf{where}

alg :: NatF \ (Nat \rightarrow Nat) \rightarrow (Nat \rightarrow Nat)

alg \ Zero = In \circ Succ

alg \ (Succ \ a_n) = cata \ alg' \ \mathbf{where}

alg' :: NatF \ Nat \rightarrow Nat

alg' \ Zero = a_n \ (In \ (Succ \ (In \ Zero)))

alg' \ (Succ \ a_{n+1,m}) = a_n \ a_{n+1,m}
```

6.2 Apomorphisms

Paramorphisms can be dualised to corecursion: The algebra of a paramorphism has type $f(\mu f, a) \to a$, in which μf is dual to νf , and the pair type is dual to the *Either* type. Thus the coalgebra of the dual recursion scheme should have type $c \to f$ (*Either* $(\nu f) c$).

Recursion Scheme 8. We call the following recursion scheme the *apomorphism* [49, 46]. Prefix apo- comes from Greek απο meaning 'apart from'.

```
apo :: Functor f \Rightarrow (c \rightarrow f (Either (\nu f) c)) \rightarrow c \rightarrow \nu f
apo coalg = Out° o fmap (either id (apo coalg)) o coalg
```

which is sometimes called *primitive corecursion*.

Similar to an amorphisms, the coalgebra of an apomorphism generates a layer of f-structure in each step, but for substructures, it either generates a new seed of type c for corecursion as in an amorphisms, or a complete structure of ν f and stop the corecursion there.

In the same way that cata and para are interdefinable, ana and apo are interdefinable in Haskell too, but apo are particularly suitable for corecursive functions in which the future output is fully known at some step. Consider a function maphd from Vene and Uustalu [49] that applies a function f to the first element (if there is) of a coinductive list.

```
maphd :: (a \rightarrow a) \rightarrow \nu \; (ListF \; a) \rightarrow \nu \; (ListF \; a)
```

As an anamorphism, it is expressed as

in which the seed for generation is of type Either (ν (ListF a)) (ν (ListF a)) to distinguish if the head element has been processed. This function is more intuitively an apomorphism since the future output is instantly known when the head element gets processed:

```
maphd' f = apo \ coalg \ \mathbf{where}
coalg \ (Out^{\circ} \ Nil) = Nil
coalg \ (Out^{\circ} \ (Cons \ x \ xs)) = Cons \ (f \ x) \ (Left \ xs)
```

Moreover, this definition is more efficient than the previous one because it avoids deconstructing and reconstructing the tail of the input list.

Example 11. Another instructive example of apomorphisms is inserting a value into an ordered (coinductive) list:

```
insert :: Ord a \Rightarrow a \rightarrow \nu \ (ListF \ a) \rightarrow \nu \ (ListF \ a)
insert y = apo \ c \ where
c \ (Out^\circ \ Nil) = Cons \ y \ (Left \ (Out^\circ \ Nil))
c \ xxs@(Out^\circ \ (Cons \ x \ xs))
| \ y \leqslant x = Cons \ y \ (Left \ xxs)
| \ otherwise = Cons \ x \ (Right \ xs)
```

In both cases, an element y or x is emitted, and Left xxs makes xxs the rest of the output, whereas Right xs continues the corecursion to insert y into xs.

6.3 Zygomorphisms

When computing a recursive function on a datatype, it is usual the case that some auxiliary information about substructures is needed in addition to the images of substructures under the recursive function being computed. For instance, when determining if a binary tree is a perfect tree—a tree in which all leaf nodes have the same depth and all interior nodes have two children—by structural recursion, besides checking that the left and right subtrees are both perfect, it is also needed to check that they have the same depth:

```
\begin{array}{ll} \textit{perfect} :: \mu \; (\textit{TreeF} \; e) & \rightarrow \textit{Bool} \\ \textit{perfect} \; (\textit{In} \; \textit{Empty}) & = \; \textit{True} \\ \textit{perfect} \; (\textit{In} \; (\textit{Node} \; l \; \_ r)) = \textit{perfect} \; l \; \land \; \textit{perfect} \; r \; \land \; (\textit{depth} \; l \equiv \textit{depth} \; r) \\ \textit{depth} :: \mu \; (\textit{TreeF} \; e) & \rightarrow \; \textit{Integer} \\ \textit{depth} \; (\textit{In} \; \textit{Empty}) & = \; 0 \\ \textit{depth} \; (\textit{In} \; (\textit{Node} \; l \; \_ r)) & = \; 1 + \; \textit{max} \; (\textit{depth} \; l) \; (\textit{depth} \; r) \end{array}
```

Function perfect is not directly a catamorphism because the algebra is not provided with $depth\ l$ and $depth\ r$ by the cata recursion scheme. However we can define perfect as a paramorphism:

```
\begin{array}{l} \textit{perfect'} = \textit{para alg where} \\ \textit{alg Empty} = \textit{True} \\ \textit{alg (Node } (l, p_l) \_ (r, p_r)) = p_l \land p_r \land (\textit{depth } l \equiv \textit{depth } r) \end{array}
```

But this is inefficient because the depth of a subtree is computed repeatedly at each of its ancestor nodes, despite the fact that *depth* can be computed structurally too. Thus we need a generalisation of paramorphisms in which instead of the original structure being kept and supplied to the algebra, some auxiliary information (that can be computed structurally) is maintained along the recursion and supplied to the algebra, which leads to the following recursion scheme.

Recursion Scheme 9. Structural recursion with auxiliary information is called *zygomorphisms* [37]:

```
zygo :: Functor f \Rightarrow (f(a, b) \rightarrow a) \rightarrow (f b \rightarrow b) \rightarrow \mu f \rightarrow a

zygo \ alq_1 \ alq_2 = fst \ (mutu \ alq_1 \ (alq_2 \circ fmap \ snd))
```

in which alg_1 computes the function of interest from the recursive results together with auxiliary information of type b, and alg_2 maintains the auxiliary information. Malcolm called zygomorphisms 'yoking together of paramorphisms and catamorphisms' and prefix 'zygo-' is from Greek $\zeta v \gamma \dot{v} v \dot{v}$ meaning 'yoke'.

Example 12. As we said, zygo is a generalisation of paramorphisms: para $alg = zygo \ alg \ In$. And the above perfect is zygo p d where

```
\begin{array}{ll} p :: TreeF \ e \ (Bool, Integer) \rightarrow Bool \\ p \ Empty &= True \\ p \ (Node \ (p_l, d_l) \ \_ \ (p_r, d_r)) \ = p_l \land p_r \land (d_l \equiv d_r) \\ d :: TreeF \ e \ Integer \rightarrow Integer \\ d \ Empty &= 0 \\ d \ (Node \ d_l \ \_ \ d_r) &= 1 + (max \ d_l \ d_r) \end{array}
```

In the unifying framework by means of adjunction, zygomorphisms arise from an adjunction between the slice category $C \downarrow b$ and the base category C [24]. The same adjunction also leads to the dual of zygomorphisms—the recursion scheme in which a seed is unfolded to a recursive datatype that defined with some auxiliary datatype.

7 Course-of-Value (Co)Recursion

This section is about the patterns in dynamic programming algorithms, in which a problem is solved based on solutions to subproblems just as in catamorphisms. But in dynamic programming algorithms, subproblems are largely shared among problems, and thus a common implementation technique is to memoise solved subproblems with an array. This section shows the recursion scheme for dynamic programming, *histomorphisms*, and a generalisation called *dynamorphisms*, and the corecursive dual the *futumorphism*.

7.1 Histomorphisms

A powerful generalisation of catamorphisms is to provide the algebra with all the recursively computed results of direct and indirect substructures rather than only the *immediate* substructures. Consider the longest increasing subsequence (LIS) problem: given a sequence of integers, its subsequences are obtained by deleting some (or none) of its elements and keeping the remaining elements in its original order, and the problem is to find (the length of) longest subsequences in which the elements are in increasing order. For example, the longest increasing subsequences of [1, 6, -5, 4, 2, 3, 9] have length 4 and one of them is [1, 2, 3, 9].

A way to find LIS follows the observation that an LIS of x:xs is either an LIS of xs or a subsequence beginning with the head element x, and moreover in the latter case the LIS must have a tail that itself is also an LIS (or the whole LIS could be longer). This idea is implemented by the program below.

```
\begin{array}{l} lis = snd \circ lis' \\ lis' :: Ord \ a \Rightarrow [a] \rightarrow (Integer, Integer) \\ lis' [] = (0,0) \\ lis' \ (x:xs) = (a,b) \ \textbf{where} \\ a = 1 + maximum \ [fst \ (lis' \ sub) \mid sub \leftarrow tails \ xs, null \ sub \lor x < head \ sub] \\ b = max \ a \ (snd \ (lis' \ xs)) \end{array}
```

where the first component of lis' (x:xs) is the length of the longest increasing subsequence that is restricted to begin with the first element x, and the second component is the length of LIS without this restriction and thus $lis = snd \circ lis'$.

Unfortunately this implementation is very inefficient because lis' is recursively applied to possibly all substructures of the input, leading to exponential running time with respect to the length of the input. The inefficiency is mainly due to redundant recomputation of lis' on substructures: when computing lis' (xs + ys), for each x in xs, lis' ys is recomputed although the results

are identical. A technique to speed up the algorithm is to memoise the results of *lis'* on substructures and skip recomputing the function when identical input is encountered, a technique called *dynamic programming*.

To implement dynamic programming, what we want is a scheme that provides the algebra with a table of the results for all substructures that have been computed. A table is represented by the *Cofree* comonad

```
data Cofree f a where (\triangleleft) :: a \rightarrow f (Cofree f a) \rightarrow Cofree f a
```

which can be intuitively understood as a (coinductive) tree whose branching structure is determined by functor f and all nodes are tagged with a value of type a, which can be extracted with

```
extract :: Cofree \ f \ a \rightarrow a

extract \ (x \triangleleft \_) = x
```

Recursion Scheme 10. The recursion scheme *histomorphism* [46] is:

```
histo :: Functor f \Rightarrow (f \ (Cofree \ f \ a) \rightarrow a) \rightarrow \mu \ f \rightarrow a
histo alg = extract \circ cata \ (\lambda x \rightarrow alg \ x \triangleleft x)
```

which is a catamorphism computing a memo-table of type *Cofree f a* followed by extracting the result for the whole structure. The name histo- follows that the entire computation history is passed to the algebra. It is also called *course-of-value* recursion.

Example 13. The dynamic programming implementation of lis is then:

```
\begin{array}{l} \mathit{lis''} :: \mathit{Ord} \ a \Rightarrow \mu \ (\mathit{ListF} \ a) \rightarrow \mathit{Integer} \\ \mathit{lis''} = \mathit{snd} \circ \mathit{histo} \ \mathit{alg} \\ \mathit{alg} :: \mathit{Ord} \ a \Rightarrow \mathit{ListF} \ a \ (\mathit{Cofree} \ (\mathit{ListF} \ a) \ (\mathit{Integer}, \mathit{Integer})) \\ \qquad \rightarrow (\mathit{Integer}, \mathit{Integer}) \\ \mathit{alg} \ \mathit{Nil} \qquad = (0,0) \\ \mathit{alg} \ (\mathit{Cons} \ x \ \mathit{table}) = (a,b) \ \mathbf{where} \\ a = 1 + \mathit{findNext} \ x \ \mathit{table} \\ b = \mathit{max} \ a \ (\mathit{snd} \ (\mathit{extract} \ \mathit{table})) \end{array}
```

where findNext searches in the rest of the list for the element that is greater than x and begins a longest increasing subsequence:

```
findNext :: Ord \ a \Rightarrow a \rightarrow Cofree \ (ListF \ a) \ (Integer, Integer) \rightarrow Integer

findNext \ x \ ((a, \_) \triangleleft Nil) = a

findNext \ x \ ((a, \_) \triangleleft (Cons \ y \ table')) = \mathbf{if} \ x < y \ \mathbf{then} \ max \ a \ b \ \mathbf{else} \ b

\mathbf{where} \ b = findNext \ x \ table'
```

which improves the time complexity to quadratic time because alg runs in linear time for each element and alg is computed only once for each element.

In the unifying theory of recursion schemes by adjunctions, histomorphisms arise from the adjunction $U \dashv Cofree_F$ [23] where $Cofree_F$ sends an object to its cofree coalgebra in the category of F-coalgebras, and U is the forgetful functor. As we have seen, cofree coalgebras are used to model the memo-table of computation history in histomorphisms, but an oddity here is that (the carrier of) the cofree coalgebra is a possibly infinite structure, while the computation history is in fact finite because the input is a finite inductive structure. A remedy for this problem is to replace cofree coalgebras with $cofree\ para-recursive\ coalgebras$ in the construction, and the $Cofree\ f\ a$ comonad in histo is replaced by its para-recursive counterpart, which is exactly finite trees whose branching structure is f and nodes are tagged with a-values [26].

7.2 Dynamorphisms

Histomorphisms require the input to be an initial algebra, and this is inconvenient in applications whose structure of computation is determined on the fly while computing. An example is the following program finding the length of longest common subsequences (LCS) of two sequences [2].

```
\begin{array}{l} lcs :: Eq \ a \Rightarrow [\ a\ ] \rightarrow [\ a\ ] \rightarrow Integer \\ lcs \ [\ ] \ \_ = 0 \\ lcs \ \_ [\ ] = 0 \\ lcs \ xxs@(x:xs) \ yys@(y:ys) \\ |\ x \equiv y \qquad = lcs \ xs \ ys + 1 \\ |\ otherwise = max \ (lcs \ xs \ yys) \ (lcs \ xxs \ ys) \end{array}
```

This program runs in exponential time but it is well suited for optimisation with dynamic programming because a lot of subproblems are shared across recursion. However, it is not accommodated by histo because the input, a pair of lists, is not an initial algebra. Therefore it is handy to generalise histo by replacing in° with a user-supplied recursive coalgebra:

Recursion Scheme 11. The *dynamorphism* (evidently the name is derived from *dyna*mic programming) introduced by Kabanov and Vene [34] is:

```
dyna :: Functor \ f \Rightarrow (f \ (Cofree \ f \ a) \rightarrow a) \rightarrow (c \rightarrow f \ c) \rightarrow c \rightarrow a dyna \ alg \ coalg = extract \circ hylo \ (\lambda x \rightarrow alg \ x \triangleleft x) \ coalg
```

in which the recursive coalgebra c breaks a problem into subproblems, which are recursively solved, and the algebra alg solves a problem with solutions to all direct and indirect subproblems.

Because the subproblems of a dynamic programming algorithm together with the dependency relation of subproblems form an acyclic graph, an appealing choice of the functor f in dyna is ListF and the coalgebra c generates subproblems in a topological order of the dependency graph of subproblems, so that a subproblem is solved exactly once when it is needed by bigger problems.

Example 14. Continuing the example of LCS, the set of subproblems of $lcs \ s_1 \ s_2$ is all (x, y) for x and y being suffixes of s_1 and s_2 respectively. An ordering of subproblems that respects their computing dependency is:

```
g :: ([a], [a]) \rightarrow ListF ([a], [a]) ([a], [a])
g ([], []) = Nil
g (x, y) = \mathbf{if} \ null \ y \ \mathbf{then} \ Cons (x, y) \ (tail \ x, s_2)
\mathbf{else} \ Cons (x, y) \ (x, tail \ y)
```

The algebra a solves a problem with solutions to subproblems available:

```
a :: ListF ([a], [a]) (Cofree (ListF ([a], [a])) Integer) \rightarrow Integer
a \ Nil = 0
a \ (Cons \ (x, y) \ table)
| \ null \ x \lor null \ y = 0
| \ head \ x \equiv head \ y = index \ table \ (offset \ 1 \ 1) + 1
| \ otherwise = max \ (index \ table \ (offset \ 1 \ 0))
(index \ table \ (offset \ 0 \ 1))
```

where $index \ t \ n$ extracts the n-th entry of the memo-table:

```
index :: Cofree \ (ListF \ a) \ p \rightarrow Integer \rightarrow p

index \ t \ 0 = extract \ t

index \ (\_ \triangleleft (Cons \_ t')) \ n = index \ t' \ (n-1)
```

The tricky part is computing the indices for entries to subproblems in the memotable. Because subproblems are enumerated by g in the order that reduces the second sequence first, thus the entry for $(drop\ n\ x, drop\ m\ y)$ in the memotable when computing (x,y) is:

offset
$$n \ m = n * (length \ s_2 + 1) + m - 1$$

Putting them together, we get the dynamic programming solution to LCS:

```
lcs' s_1 s_2 = dyna \ a \ g \ (s_1, s_2)
```

which improves the exponential running time of specification lcs to $\mathcal{O}(|s_1||s_2|^2)$, yet slower than the $\mathcal{O}(|s_1||s_2|)$ array-based implementation of dynamic programming because of the cost of indexing the list-structured memo-table.

7.3 Futumorphisms

Histomorphisms are generalised catamorphisms that can inspect the history of computation. The dual generalisation is anamorphisms that can control the future. As an example, consider the problem of decoding the run-length encoding of a sequence: the input is a list of elements (n, x) of type (Int, a) and n > 0 for all elements. The output is a list [a] and each (n, x) in the input is interpreted as n consecutive copies of x. As an anamorphism, it is expressed as

```
rld :: [(Int, a)] \rightarrow \nu \ (ListF \ a)
rld = ana \ c \ where
c \ [] = Nil
c \ ((n, x) : xs)
\mid n \equiv 1 = Cons \ x \ xs
\mid otherwise = Cons \ x \ ((n - 1, x) : xs)
```

This is slightly awkward because anamorphisms can emit only one layer of the structure in each step, while in this example it is more natural to emit n copies of x in a batch. This can be done if the recursion scheme allows the coalgebra to generate more than one layer in a single step—in a sense controlling the future of the computation.

Multiple layers of a structure given by a functor f are represented by the Free monad:

```
data Free f a = Ret \ a \mid Op \ (f \ (Free \ f \ a))
```

which is the type of (inductive) trees whose branching is determined by f and leaf nodes are a-values. Free algebras subsume initial algebras as $Free\ f\ Void\cong \mu\ f$ where Void is the bottom type, and cata for $\mu\ f$ is replaced by

```
eval :: Functor f \Rightarrow (f \ b \rightarrow b) \rightarrow (a \rightarrow b) \rightarrow Free f \ a \rightarrow b eval alg g (Ret a) = g a eval alg g (Op k) = alg (fmap (eval alg g) k)
```

Recursion Scheme 12. With these constructions, we define the recursion scheme futumorphisms [46]:

```
futu :: Functor f \Rightarrow (c \rightarrow f \ (Free \ f \ c)) \rightarrow c \rightarrow \nu \ f
futu coalg = ana coalg' \circ Ret where
coalg' (Ret a) = coalg a
coalg' (Op k) = k
```

Example 15. We can redefine rld as a futumorphism:

```
rld' :: [(Int, a)] \rightarrow \nu \ (ListF \ a)
rld' = futu \ dec
dec \ [] = Nil
dec \ ((n, c) : xs) = \mathbf{let} \ (Op \ g) = rep \ n \ \mathbf{in} \ g \ \mathbf{where}
rep \ 0 = Ret \ xs
rep \ m = Op \ (Cons \ c \ (rep \ (m-1)))
```

Note that dec assumes n > 0 because futu demands that the coalgebra generate at least one layer of f-structure.

Theoretically, futumorphisms are adjoint unfolds from the adjunction $Free_F \dashv U$ where $Free_F$ maps object a to the free algebra generated by a in the category of F-algebras. In the same way that dynamorphisms generalise histomorphisms, futumorphisms can be generalised by replacing $(\nu \ F, Out^\circ)$ with a user-supplied corecursive F-algebra. A broader generalisation is to combine futumorphisms and histomorphisms in a similar way to hylomorphisms combining anamorphisms and catamorphisms:

```
\begin{array}{c} \textit{chrono} :: \textit{Functor } f \Rightarrow (f \; (\textit{Cofree } f \; b) \rightarrow b) \\ \qquad \qquad \rightarrow (a \rightarrow f \; (\textit{Free } f \; a)) \\ \qquad \rightarrow a \rightarrow b \\ \textit{chrono } \textit{alg } \textit{coalg} = \textit{extract} \circ \textit{hylo } \textit{alg' } \textit{coalg'} \circ \textit{Ret } \textbf{where} \\ \textit{alg' } x = \textit{alg } x \triangleleft x \\ \textit{coalg' } (\textit{Ret } a) = \textit{coalg } a \\ \textit{coalg' } (\textit{Op } k) = k \end{array}
```

which is dubbed *chronomorphisms* by Kmett [35] (prefix chrono- from Greek χρόνος meaning 'time').

8 Monadic Structural Recursion

Up to now we have been working in the world of pure functions. It is certainly possible to extend the recursion schemes to the non-pure world where computational effects are modelled with monads.

8.1 Monadic Catamorphism

Let us start with a straightforward example of printing a tree with the IO monad:

```
printTree :: Show a \Rightarrow \mu (TreeF a) \rightarrow IO ()
printTree (In Empty) = return ()
printTree (In (Node l a r)) = do printTree l; printTree r; print a
```

The reader may have recognised that it is already a catamorphism:

```
printTree' :: Show a \Rightarrow \mu (TreeF a) \rightarrow IO ()
printTree' = cata printAlg where
printAlg :: Show a \Rightarrow TreeF a (IO ()) \rightarrow IO ()
printAlg Empty = return ()
printAlg (Node ml a mr) = do ml; mr; print a
```

Thus a straightforward way of abstracting 'monadic catamorphisms' is to restrict cata to monadic values.

Recursion Scheme 13 (cataM). We call the following recursion scheme catamorphisms on monadic values:

```
cataM :: (Functor f, Monad m) \Rightarrow (f (m a) \rightarrow m a) \rightarrow \mu f \rightarrow m a

cataM \ algM = cata \ algM
```

which is the second approach to monadic catamorphisms in [45].

However, cataM does not fully capture our intuition for 'monadic catamorphism' because the algebra $algM::f\ (m\ a)\to m\ a$ is allowed to combine computations from subparts arbitrarily. For a more precise characterisation, we decompose $algM::f\ (m\ a)\to m\ a$ in cataM into two parts: a function $alg::f\ a\to m\ a$ which (monadically) computes the result for the whole structure given the results of substructures, and a polymorphic function

$$seg :: \forall x.f (m \ x) \rightarrow m (f \ x)$$

called a sequencing of f over m, which combines computations for substructures into one monadic computation. The decomposition reflects the intuition that a monadic catamorphism processes substructures (in the order determined by seq) and combines their results (by alg) to process the root structure:

$$algM \ r = seq \ r \gg alg.$$

Example 16. Binary trees TreeF can be sequenced from left to right:

```
lToR :: Monad \ m \Rightarrow TreeF \ a \ (m \ x) \rightarrow m \ (TreeF \ a \ x)
lToR \ Empty = return \ Empty
lToR \ (Node \ ml \ a \ mr) = \mathbf{do} \ l \leftarrow ml; r \leftarrow mr; return \ (Node \ l \ a \ r)
```

and also from right to left:

```
rToL :: Monad \ m \Rightarrow TreeF \ a \ (m \ x) \rightarrow m \ (TreeF \ a \ x)
rToL \ Empty = return \ Empty
rToL \ (Node \ ml \ a \ mr) = \mathbf{do} \ r \leftarrow mr; l \leftarrow ml; return \ (Node \ l \ a \ r)
```

Recursion Scheme 14 (mcata). The monadic catamorphism [13, 45] is the following recursion scheme:

Example 17. The program printTree above is a monadic catamorphism:

```
printTree'' :: Show \ a \Rightarrow \mu \ (TreeF \ a) \rightarrow IO \ ()

printTree'' = mcata \ lToR \ printElem \ \mathbf{where}

printElem \ Empty = return \ ()

printElem \ (Node \ a \ a) = print \ a
```

Note that mcata is strictly less expressive because mcata requires all subtrees processed before the root.

Distributive Conditions In the literature [13, 45, 24], the sequencing of a monadic catamorphism is required to be a *distributive law* of functor f over monad m, which means that $seq:: \forall x.f \ (m \ x) \to m \ (f \ x)$ satisfies two conditions:

$$seg \circ fmap \ return = return$$
 (7)

$$seq \circ fmap \ join = join \circ fmap \ seq \circ seq$$
 (8)

Intuitively, condition (7) prohibits seq from inserting additional computational effects when combining computations for substructures, which is a reasonable requirement. Condition (8) requires seq to be commutative with monadic sequencing. These requirements are theoretically elegant, because they allow functor f to be lifted to the Kleisli category of m and consequently $mcata\ seq\ alg$ is also a catamorphism in the Kleisli category (mcata by definition is a catamorphism in the base category)—giving us nicer calculational properties.

Unfortunately, condition (8) is usually too strong in practice. For example, neither lToR nor rToL in Example 16 satisfies condition (8) when m is the IO monad. To see this, let

```
c = Node \ (putStr "A" \gg return \ (putStr "C"))
(putStr "B" \gg return \ (putStr "D"))
```

Then $(lToR \circ fmap\ join)\ c$ prints "ACBD" but $(join \circ fmap\ lToR \circ lToR)\ c$ prints "ABCD". In fact, there is no distributive law of $TreeF\ a$ over a monad unless it is commutative, excluding the IO monad and State monad. Thus we drop the requirement for seq being a distributive law in our definition of monadic catamorphism.

8.2 More Monadic Recursion Schemes

As we mentioned above, *mcata* is the catamorphism in the Kleisli category provided *seq* is a distributive law. No doubt, we can replay our development of recursion schemes in the Kleisli category to get the monadic version of more recursion schemes. For example, we have *monadic hylomorphisms* [43, 45]:

```
\begin{array}{l} \textit{mhylo} :: (\textit{Monad} \ m, \textit{Functor} \ f) \Rightarrow (\forall x.f \ (m \ x) \rightarrow m \ (f \ x)) \\ \rightarrow (f \ a \rightarrow m \ a) \rightarrow (c \rightarrow m \ (f \ c)) \rightarrow c \rightarrow m \ a \\ \textit{mhylo} \ \textit{seq} \ \textit{alg} \ \textit{coalg} \ c = \mathbf{do} \ x \leftarrow \textit{coalg} \ c \\ y \leftarrow \textit{seq} \ (\textit{fmap} \ (\textit{mhylo} \ \textit{seq} \ \textit{alg} \ \textit{coalg}) \ x) \\ \textit{alg} \ y \end{array}
```

which specialises to mcata by $mhylo\ seq\ alg\ (return\circ in^\circ)$ and $monadic\ anamor-phisms$ by

```
mana :: (Monad \ m, Functor \ f) \Rightarrow (\forall x.f \ (m \ x) \rightarrow m \ (f \ x)) \\ \rightarrow (c \rightarrow m \ (f \ c)) \rightarrow c \rightarrow m \ (\nu \ f)
mana \ seq \ coalg = mhylo \ seq \ (return \circ Out^{\circ}) \ coalg
```

Other recursion schemes discussed in this paper can be devised in the same way.

Example 18. Generating a random tree of some depth with random IO :: IO Int is a monadic anamorphism:

```
ranTree :: Integer \rightarrow IO \ (\nu \ (TreeF \ Int))
ranTree = mana \ lToR \ gen \ where
gen :: Integer \rightarrow IO \ (TreeF \ Int \ Integer)
gen \ 0 = return \ Empty
gen \ n = \mathbf{do} \ a \leftarrow randomIO :: IO \ Int
return \ (Node \ (n-1) \ a \ (n-1))
```

9 Structural Recursion on GADTs

So far we have worked exclusively with (co)inductive datatypes, but they do not cover all algebraic datatypes and *generalised algebraic datatypes* (GADTs). An example of algebraic datatypes that is not (co)inductive is the datatype for purely functional *random-access lists* [42]:

```
data RList\ a = Null\ |\ Zero\ (RList\ (a,a))\ |\ One\ a\ (RList\ (a,a))
```

The recursive occurrences of RList in constructor Zero and One are RList (a, a) rather than RList a, and consequently we cannot model RList a as μ f for some functor f as we did for lists. Algebraic datatypes such as RList whose defining equation has on the right-hand side any occurrence of the declared type applied to parameters different from those on the left-hand side are called non-regular datatypes or nested datatypes [7, 31, 33].

Nested data types are covered by a broader range of data types called generalised algebraic data types (GADTs) [32, 20]. In terms of the **data** syntax in Haskell, the generalisation of GADTs is to allow the parameters P supplied to the declared type D on the left-hand side of an defining equation **data** D $P=\dots$ to be more complex than type variables. GADTs have a different syntax from that of ADTs in Haskell³. For example, as a GADT, RList is

```
data RList :: * \rightarrow * \mathbf{where}

Null :: RList \ a

Zero :: RList \ (a, a) \rightarrow RList \ a

One :: a \rightarrow RList \ (a, a) \rightarrow RList \ a
```

in which each constructor is directly declared with a type signature. With this syntax, allowing parameters on the left-hand side of an ADT equation to be not just variables means that the finally returned type of constructors of a GADT G can be more complex than G a where a is a type variable. A classic example is fixed length vectors of a-values: first we define two datatypes $\mathbf{data}\ Z'$ and $\mathbf{data}\ S'$ n with no constructors, then the GADT for vectors is

³ Support of GADTs is turned on by the extension GADTs in GHC.

```
data Vec (a :: *) :: * \rightarrow * \mathbf{where}

Nil :: Vec \ a \ Z'

Cons :: a \rightarrow Vec \ a \ n \rightarrow Vec \ a \ (S' \ n)
```

in which types Z' and S' n encode natural numbers at the type level, thus it does not matter what their term constructors are.

GADTs are a powerful tool to ensure program correctness by indexing datatypes with sophisticated properties of data, such as the size or shape of data, and then the type checker can check these properties statically. For example, the following program extracting the first element of a vector is always safe because the type of its argument guarantees it is non-empty.

```
safeHead :: Vec \ a \ (S' \ n) \rightarrow a
safeHead \ (Cons \ a \ \_) = a
```

GADTs as Fixed Points As we mentioned earlier, nested datatypes and GADTs cannot be modelled as fixed points of Haskell functors in general, making them out of the reach of the recursion schemes that we have seen so far. However, there are other ways to view them as fixed points. Let us look at the *RList* datatype again,

```
data RList\ a = Null \mid Zero\ (RList\ (a,a)) \mid One\ a\ (RList\ (a,a))
```

instead of viewing it as defining a type $RList\ a::*$, we can alternatively understand it as defining a functor $RList::* \to *$, where * is the category of Haskell types, such that RList satisfies the fixed point equation $RList\cong RListF\ RList$ for a higher-order functor $RListF::(* \to *) \to (* \to *)$ defined as

```
data RListF f a = NullF \mid ZeroF (f(a, a)) \mid OneF a (f(a, a))
```

In this way, nested datatypes are still fixed points, but of higher-order functors, rather than usual Haskell functors [7, 31].

This idea applies to GADTs as well, but with a caveat: consider the GADT G defined as follows:

```
data G a where

Leaf :: a \rightarrow G a

Prod :: G a \rightarrow G b \rightarrow G (a, b)
```

then G cannot be a functor at all, let alone a fixed point of some higher-order functor. The problem is defining fmap for the Prod constructor:

$$fmap \ f \ (Prod \ ga \ gb) = _ :: G \ c$$

but we have no way to construct a G c given $f:(a,b) \to c$, ga::G a and gb::G b. Luckily, Johann and Ghani [32] shows how to fix this problem. In fact, all we need to do is to give up the expectation that a GADT $G::*\to *$ is functorial in its domain. In categorical terminology, we view GADTs as functors from the discrete category |*| of Haskell types to the category * of Haskell types, rather than functors from * to *. In other words, a GADT $G::* \to *$ is then merely a type constructor in Haskell, without necessarily a Functor instance. A natural transformation between two functors a and b from |*| to * is a polymorphic function $\forall i.a \ i \to b \ i$, which we give a type synonym $a \to b^4$:

type (
$$\dot{\rightarrow}$$
) $a\ b = \forall i.a\ i \rightarrow b\ i$

And a higher-order endofunctor (on the functor category $*^{|*|}$) is f instantiating the following type class, which is analogous to the *Functor* type class of Haskell:

class
$$HFunctor\ (f::(*\to *)\to (*\to *))$$
 where $hfmap::(a \to b)\to (f\ a \to f\ b)$

in which fmap's counterpart hfmap maps a natural transformation $a \to b$ to another natural transformation f $a \to f$ b. On top of these, the least-fixed-point operator for an HFunctor is

data
$$\dot{\mu}$$
 :: $((* \rightarrow *) \rightarrow (* \rightarrow *)) \rightarrow (* \rightarrow *)$ where $\dot{I}n$:: $f(\dot{\mu}f) i \rightarrow \dot{\mu}f i$

Example 19. Fixed-length vectors $Vec\ e$ are isomorphic to $\dot{\mu}$ ($VecF\ e$) where

```
data VecF :: * \rightarrow (* \rightarrow *) \rightarrow (* \rightarrow *) where NilF :: VecF \ e \ f \ Z' ConsF :: e \rightarrow f \ n \rightarrow VecF \ e \ f \ (S' \ n)
```

which has HFunctor instance

```
instance HFunctor (VecF e) where

hfmap phi NilF = NilF

hfmap phi (ConsF e es) = ConsF e (phi es)
```

Recursion Scheme 15 (*icata*). With the machinery above, we can devise the structural recursion scheme for $\dot{\mu}$, which we call *indexed catamorphisms*:

```
icata :: HFunctor f \Rightarrow (f \ a \rightarrow a) \rightarrow \dot{\mu} f \rightarrow a
icata alg (\dot{In} \ x) = alg \ (hfmap \ (icata \ alg) \ x)
```

Example 20. Just like list processing functions such as map are catamorphisms, their counterparts for vectors can also be written as indexed catamorphisms:

```
vmap :: \forall a \ b.(a \rightarrow b) \rightarrow \dot{\mu} \ (\textit{VecF} \ a) \rightarrow \dot{\mu} \ (\textit{VecF} \ b)
vmap \ f = icata \ alg \ \textbf{where}
alg :: \textit{VecF} \ a \ (\dot{\mu} \ (\textit{VecF} \ b)) \rightarrow \dot{\mu} \ (\textit{VecF} \ b)
alg \ \textit{NilF} = \dot{In} \ \textit{NilF}
alg \ (\textit{ConsF} \ a \ bs) = \dot{In} \ (\textit{ConsF} \ (f \ a) \ bs)
```

⁴ It requires the RankNTypes extension of GHC.

Example 21. Terms of untyped lambda calculus with de Bruijn indices can be modelled as the fixed point of the following higher-order functor [8]:

```
data LambdaF :: (* \rightarrow *) \rightarrow (* \rightarrow *) where Var :: a \rightarrow LambdaF f a App :: f a \rightarrow f a \rightarrow LambdaF f a Abs :: f (Maybe a) \rightarrow LambdaF f a
```

Letting a be some type, inhabitants of $\dot{\mu}$ LambdaF a are precisely the lambda terms in which free variables range over a. Thus $\dot{\mu}$ LambdaF Void is the type of closed lambda terms where Void is the type has no inhabitants. Note that the constructor Abs applies the recursive placeholder f to Maybe a, providing the inner term with exactly one more fresh variable Nothing.

The size of a lambda term can certainly be computed structurally. However, what we get from *icata* is always an arrow $\dot{\mu} \ LambdaF \rightarrow a$ for some $a :: * \rightarrow *$. If we want to compute just an integer, we need to wrap it in a constant functor:

```
newtype K a x = K { unwrap :: a }
```

Computing the size of a term is done by

```
size :: \dot{\mu} \ LambdaF \rightarrow K \ Integer

size = icata \ alg \ \mathbf{where}

alg :: LambdaF \ (K \ Integer) \rightarrow K \ Integer

alg \ (Var \_) = K \ 1

alg \ (App \ (K \ n) \ (K \ m)) = K \ (n+m+1)

alg \ (Abs \ (K \ n)) = K \ (n+1)
```

Example 22. An indexed catamorphism icata alg is a function $\forall i.\dot{\mu} \ f \ i \to a \ i$ polymorphic in index i, however, we might be interested in GADTs and nested datatypes applied to some monomorphic index. Consider the following program summing up a random-access list of integers.

```
\begin{array}{ll} sumRList :: RList \ Integer \rightarrow Integer \\ sumRList \ Null &= 0 \\ sumRList \ (Zero \ xs) &= sumRList \ (fmap \ (uncurry \ (+)) \ xs) \\ sumRList \ (One \ x \ xs) &= x + sumRList \ (fmap \ (uncurry \ (+)) \ xs) \end{array}
```

Does it fit into an indexed catamorphism from $\dot{\mu}$ RListF? The answer is yes, with the clever choice of the continuation monad Cont Integer a as the result type of icata.

```
newtype Cont r a = Cont \{ runCont :: (a \rightarrow r) \rightarrow r \}

sumRList' :: \dot{\mu} \ RListF \ Integer \rightarrow Integer

sumRList' \ x = runCont \ (h \ x) \ id \ \mathbf{where}

h :: \dot{\mu} \ RListF \rightarrow Cont \ Integer

h = icata \ sum \ \mathbf{where}
```

```
sum :: RListF (Cont Integer) \rightarrow Cont Integer
sum NullF = Cont (\lambda k \rightarrow 0)
sum (ZeroF s) = Cont (\lambda k \rightarrow runCont s (fork k))
sum (OneF a s) = Cont (\lambda k \rightarrow k \ a + runCont \ s (fork k))
fork :: (y \rightarrow Integer) \rightarrow (y, y) \rightarrow Integer
fork k (a, b) = k \ a + k \ b
```

Historically, structural recursion on nested datatypes applied to a monomorphic type was thought as falling out of *icata* and led to the development of *generalised* folds [6, 1]. Later, Johann and Ghani [31] showed *icata* is in fact expressive enough by using right Kan extensions as the result type of *icata*, of which *Cont* used in this example is a special case.

10 Equational Reasoning with Recursion Schemes

We have talked about a handful of recursion schemes, which are recognised common patterns in recursive functions. Recognising common patterns help programmers understand a new problem and communicate their solutions with others. Better still, recursion schemes offer rigorous and formal calculational properties with which the programmer can manipulate programs in a way similar to manipulate standard mathematical objects such as numbers and polynomials. In this section, we briefly show some of the properties and an example of reasoning about programs using them. We refer to Bird and de Moor [4] for a comprehensive introduction to this subject and Bird [3] for more examples of reasoning about and optimising algorithms in this approach.

We focus on *hylomorphisms*, as almost all recursion schemes are a hylomorphism in a certain category. The fundamental property is the unique existence of the solution to a hylo equation given a recursive coalgebra c (or dually, a corecursive algebra a): for any x,

$$x = a \circ fmap \ x \circ c \iff x = hylo \ a \ c$$
 (HyloUniq)

which directly follows the definition of a recursive coalgebra. Instantiating x to $hylo\ a\ c$, we get the defining equation of hylo

$$hylo \ a \ c = a \circ fmap \ (hylo \ a \ c) \circ c$$
 (HyloComp)

which is sometimes called the *computation law*, because it tells how to compute $hylo\ a\ c$ recursively. Instantiating x to id, we get

$$id = a \circ c \iff id = hylo \ a \ c$$
 (HYLOREFL)

called the reflection law, which gives a necessary and sufficient condition for hylo a c being the identity function. Note that in this law, $c:: r \to f$ r and $a:: f \ r \to r$ share the same carrier type r. A direct consequence of HyloRefl is cata In = id because cata $a = hylo \ a \ in^{\circ}$ and $id = In \circ in^{\circ}$. Dually, we also have ana Out = id.

An important consequence of HyloUniq is the following fusion law. It is easier to describe diagrammatically: The HyloUniq law states that there is exactly one x, i.e. hylo a c, such that the following diagram commutes (i.e. all paths with the same start and end points give the same result when their edges are composed together):

$$\begin{array}{ccc} ta \xleftarrow{x} & tc \\ a \uparrow & \downarrow^c \\ f ta \not f ta \not f tc \end{array}$$

If we put another commuting square beside it,

$$tb \xleftarrow{h} ta \xleftarrow{x} tc$$

$$b \uparrow \qquad a \uparrow \qquad \downarrow c$$

$$f tb \not\rightleftharpoons_{fmap h} f ta \not\rightleftharpoons_{fmap x} f tc$$

$$(9)$$

the outer rectangle (with top edge $h \circ x$) also commutes, and it is also an instance of HyloUniq with coalgebra c and algebra b. Because HyloUniq states hylo c b is the only arrow making the outer rectangle commute, thus hylo c $b = h \circ x = h \circ hylo$ a c. In summary, the fusion law is:

$$h \circ hylo \ a \ c = hylo \ b \ c \iff h \circ a = b \circ fmap \ h$$
 (HyloFusion)

and its dual version for corecursive algebra a is

$$hylo \ a \ c \circ h = hylo \ a \ d \iff c \circ h = fmap \ h \circ d$$
 (HyloFusionCo)

where $d::td \to f \ td$. Fusion laws combine a function after or before a hylomorphism into one hylomorphism, and thus it is widely used for optimisation [10].

We demonstrate how these calculational properties can be used to reason about programs with an example.

Example 23. Suppose some $f: Integer \to Integer$ such that for all a, b: Integer,

$$f(a+b) = f a + f b \wedge f 0 = 0$$
 (10)

and sum and map are the familiar Haskell functions defined with hylo:

$$\begin{array}{lll} \textbf{type} \ List \ a = \mu \ (ListF \ a) \\ sum :: List \ Integer \rightarrow Integer \\ sum = hylo \ plus \ in^{\circ} \ \textbf{where} \\ plus \ Nil &= 0 \\ plus \ (Cons \ a \ b) = a + b \end{array} \qquad \begin{array}{ll} map :: (a \rightarrow b) \rightarrow List \ a \rightarrow List \ b \\ map \ f = hylo \ app \ in^{\circ} \ \textbf{where} \\ app \ Nil &= In \ Nil \\ app \ (Cons \ a \ bs) = In \ (Cons \ (f \ a) \ bs) \end{array}$$

Let us prove $sum \circ map \ f = f \circ sum$ with the properties of hylo.

Proof. Both $sum \circ map \ f$ and $f \circ sum$ are in the form of a function after a hylomorphism, and thus we can try to use the fusion law to establish

$$sum \circ map \ f = hylo \ q \ in^{\circ} = f \circ sum$$

for some g. The correct choice of g is

$$g::ListF\ Integer o Integer$$

 $g\ Nil = f\ 0$
 $g\ (Cons\ x\ y) = f\ x + y$

First, $sum \circ map \ f = sum \circ hylo \ app \ in^{\circ}$, and by HyloFusion,

$$sum \circ hylo \ app \ in^{\circ} = hylo \ g \ in^{\circ}$$

is implied by

$$sum \circ app = g \circ fmap \ sum \tag{11}$$

Expanding sum on the left-hand side, it is equivalent to

$$(plus \circ fmap \ sum \circ in^{\circ}) \circ app = g \circ fmap \ sum \tag{12}$$

which is an equation of functions

$$ListF\ Integer\ (\mu\ (ListF\ Integer)) \rightarrow Integer$$

and it can be shown by a case analysis on the input. For Nil, the left-hand side of (12) equals to

```
plus (fmap sum (in^{\circ} (app Nil)))
= plus (fmap sum (in^{\circ} (In Nil)))
= plus (fmap sum Nil)
= plus Nil  (by definition of fmap for ListF)
= 0
```

and the right-hand side of (12) equals to

$$g(fmap\ sum\ Nil) = g\ Nil = g\ 0 = f\ 0$$

and by assumption (10) about f, f 0 = 0. Similarly when the input is $Cons\ a\ b$, we can calculate that both sides equal to f $a + sum\ b$. Thus we have shown (11), and therefore $sum \circ hylo\ app\ in^\circ = hylo\ g\ in^\circ$.

Similarly, by HyloFusion, $f \circ sum = hylo \ g \ in^{\circ}$ is implied by

$$f \circ plus = g \circ fmap f$$

which can be verified by case analysis on the input: When the input is Nil, both sides equal to f 0. When the input is $Cons\ a\ b$, the left-hand side equals to $f\ (a+b)$ and the right-hand side is $f\ a+f\ b$. By assumption (10) on f, $f\ (a+b)=f\ a+f\ b$.

11 Closing Remarks and Further Reading

We have shown a handful of structural recursion schemes and their applications by examples. We hope that this paper can be an accessible introduction to this subject and a quick reference when functional programmers hear about some *morphism* with an obscure Greek prefix. We end this paper with some remarks on general approaches to find more *fantastic morphisms* and some pointers to further reading about the theory and applications of recursion schemes.

From Categories and Adjunctions As we have seen, recursion schemes live with categories and adjunctions, so whenever we see a new category, it is a good idea to think about catamorphisms and anamorphisms in this category, as we did for the Kleisli category, where we obtained mcata, and the functor category *|*|, where we obtained icata, etc. Also, whenever we encounter an adjunction $L \dashv R$, we can think about if functions of type L $c \to a$, especially L (μ f) $\to a$, are anything interesting. If they are, there might be interesting conjugate hylomorphisms from this adjunction.

Composing Recursion Schemes Up to now we have considered recursion schemes in isolation, each of which provides an extra functionality compared with cata or ana, such as mutual recursion, accessing the original structure, accessing the computation history. However, when writing larger programs in practice, we probably want to combine the functionalities of recursion schemes. For example, if we want to define two mutually recursive functions with historical information, we need a recursion scheme of type

$$\begin{array}{l} \textit{mutuHist} :: \textit{Functor} \ f \Rightarrow (f \ (\textit{Cofree} \ f \ (a,b)) \rightarrow a) \\ \qquad \rightarrow (f \ (\textit{Cofree} \ f \ (a,b)) \rightarrow b) \rightarrow (\mu \ f \rightarrow a, \mu \ f \rightarrow b) \end{array}$$

Theoretically, mutuHist is the composite of mutu and accu in the sense that the adjunction $U\dashv Cofree_F$ underlying hist and the adjunction $\Delta\dashv\times$ underlying mutu can be composed to an adjunction inducing mutuHist [22]. Unfortunately, our Haskell implementations of mutu and hist are not composable. A composable library of recursion schemes in Haskell would require considerable machinery for doing category theory in Haskell, and how to do it with good usability is a question worth exploring.

Further Reading The examples in this paper are fairly small ones, but recursion schemes are surely useful in real-world programs and algorithms. For the reader who wants to see recursion schemes in real-world algorithms, we recommend books by Bird [3] and Bird and Gibbons [5]. Their books provide a great deal of examples of proving correctness of algorithms using properties of recursion schemes, which we only briefly showcased in Section 10.

We have only glossed over the category theory of the unifying theories of recursion schemes. For the reader interested in them, a good place to start is Hinze [21]'s lecture notes on adjoint folds and unfolds, and then Uustalu et al.

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[48]'s paper on recursion schemes from comonads, which are less general than adjoint folds, but they have generic implementations in Haskell [36]. Finally, Hinze et al. [26]'s conjugate hylomorphisms are the most general framework of recursion schemes so far, although they do not have an implementation yet.

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