Recorded at time: 1752134893.734 base link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1752134893.734 sec old) Most recent transform: 0.000 (1752134893.734 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link_inertia base Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec shoulder link Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec upper_arm_link Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec forearm link Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec wrist_1_link Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec $wrist_2_{link}$ Broadcaster: /robot state publisher Average rate: 10.286 Hz Most recent transform: 1752134892.250 (1.484 sec old) Buffer length: 3.500 sec $wrist_3_{link}$ Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1752134893.734 sec old) Buffer length: 0.000 sec flange Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1752134893.734 sec old) Buffer length: 0.000 sec tool0

view frames Result