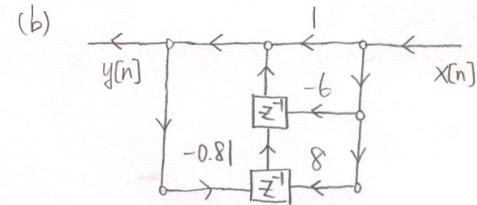
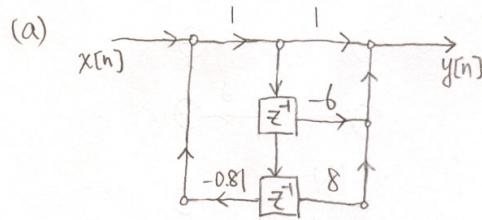


- 1.
- (a) (IV-39) (X)
(課本 204~205) use a 1 less bit \rightarrow use a $\frac{1}{2}$ less bit
 - (b) (IV-42) (X)
(課本 206~209) input signal unchanged
 - (c) (V-25) (X)
allpass system can't be a minimum-phase system
 - (d) (VI-19) (O)
 - (e) (VI-19) (X)
parallel: $FIR + FIR \neq FIR$
 - (f) (VI-31) (O)
 - (g) (VI-42 ~ VI-44) (O)
 - (h) (課本 518) (X)
only the bilinear transform will result in an allpass filter
 - (i) (課本 518) (O)
 - (j) (O)

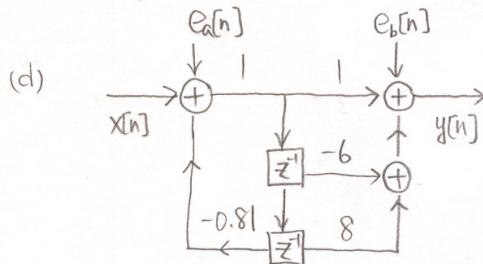
$$2. \quad H(z) = \frac{(1-2z^{-1})(1-4z^{-1})}{1+0.81z^{-2}} = \frac{1-6z^{-1}+8z^{-2}}{1+0.81z^{-2}} = \frac{(1-2z^{-1})(1-4z^{-1})}{(1-0.9iz^{-1})(1+0.9iz^{-1})}$$



(c) $b = [1 \ -6 \ 8];$

$\alpha = [1 \ 0 \ 0.81];$

`freqz(b, a);`



where $e_a[n], e_b[n]$ are round-off noise sources.

(e) power of $e_a[n] = \sigma_B^2$

power of $e_b[n] = 2\sigma_B^2$

Output noise power $\sigma_{eo}^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \sigma_B^2 |H(e^{j\omega})|^2 d\omega + 2\sigma_B^2.$

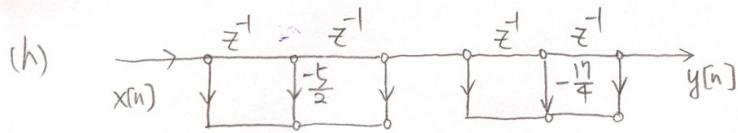
(f) $H(z) = \frac{(1-2z^{-1})(1-4z^{-1})}{(1-0.9iz^{-1})(1+0.9iz^{-1})} = \underbrace{\frac{8(1-\frac{1}{2}z^{-1})(1-\frac{1}{4}z^{-1})}{(1-0.9iz^{-1})(1+0.9iz^{-1})}}_{H_L(z)} \cdot \underbrace{\frac{(z^{-1}-\frac{1}{2})(z^{-1}-\frac{1}{4})}{(1-\frac{1}{2}z^{-1})(1-\frac{1}{4}z^{-1})}}_{H_{ap}(z)}$

$$= H_L(z) \cdot H_{ap}(z).$$

$$(g) \quad H(z) = \frac{(1-2z^{-1})(1-4z^{-1})}{(1-0.9iz^{-1})(1+0.9iz^{-1})}$$

$$= \underbrace{\frac{1}{(1-0.9iz^{-1})(1+0.9iz^{-1})} \cdot \frac{1}{(1-\frac{1}{2}z^{-1})(1-\frac{1}{4}z^{-1})}}_{H_2(z)} \cdot \underbrace{(1-\frac{1}{2}z^{-1})(1-\frac{1}{4}z^{-1})(1-z^{-1})(1-4z^{-1})}_{H_{lin}(z)}$$

$$= H_2(z) \cdot H_{lin}(z)$$



Because the linearity of $H(z) = 1 + az^{-1} + z^{-2}$ only depends on the value of a , even the quantizer is coarse, we can still have linear-phase subsystems as well as $H_{lin}(z)$.

$$(i) \quad H_3(z) = \frac{(1-2z^{-1})(1-4z^{-1})}{(z^{-2}+0.81)}, \quad R.O.C.: |z| < \frac{1}{0.9}.$$

$$\frac{(1-2z^{-1})(1-4z^{-1})}{(z^{-1}-0.9i)(z^{-1}+0.9i)} \cdot \frac{(z^{-1}-0.9i)(z^{-1}+0.9i)}{(1-0.9iz^{-1})(1+0.9iz^{-1})} \cdot \frac{z^{-2}+0.81}{z^{-2}+0.81}$$

3. (a)

consider a 1-st order analog filter $H_c(s) = \frac{b}{s-a}$,

the differential equation is $y'(t) = ay(t) + bx(t)$

suppose now two sampled data $y(nT)$ and $y(nT-T)$ are given.

$y(t)$

Consider the halfway time instant
 $t = nT - \frac{T}{2}$, we have

$$\left. \begin{aligned} y'(t) &\approx \frac{y(nT) - y(nT-T)}{T} \\ y(t) &\approx \frac{y(nT) + y(nT-T)}{2} \\ x(t) &\approx \frac{x(nT) + x(nT-T)}{2} \end{aligned} \right\} (*)$$

In discrete time, $y'(t) = a \cdot y(t) + b \cdot x(t)$ with (*) becomes:

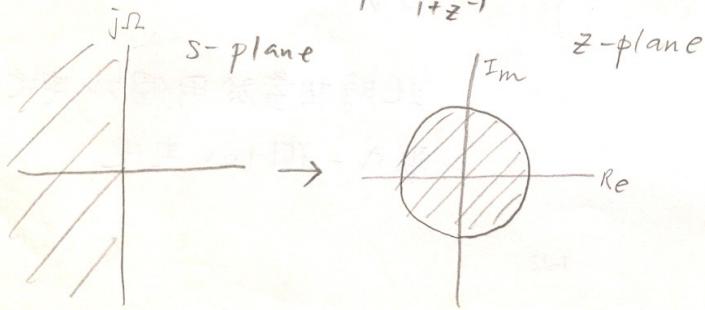
$$\frac{y[n] - y[n-1]}{T} = a \cdot \frac{y[n] + y[n-1]}{2} + b \cdot \frac{x[n] + x[n-1]}{2}$$

Transform to Z -domain:

$$H(z) = \frac{Y}{X} = \frac{\frac{b(1+z^{-1})}{z}}{\frac{1-z^{-1}}{T} - \frac{a(1+z^{-1})}{2}} = \frac{b}{\frac{2}{T} \cdot \frac{1-z^{-1}}{1+z^{-1}} - a}$$

$$\text{comparing with } H_c(s) = \frac{b}{s-a}$$

$$\therefore H(z) = H_c(s) \Big|_{s=\frac{2}{T} \cdot \frac{1-z^{-1}}{1+z^{-1}}}$$



(b) Given the digital filter spec's

Digital filter $H(z)$

↓
spec's

Prewarping

$$\omega_p = \frac{\pi}{T} \tan \frac{w_p}{2}$$

$$\omega_s = \frac{\pi}{T} \tan \frac{w_s}{2}$$

analog spec's



Analog filter
design

find N, Ω_c



$H_c(s)$



Bilinear
Transformation

$$s = \frac{2}{T} \cdot \frac{1-z^{-1}}{1+z^{-1}}$$



$H(z)$

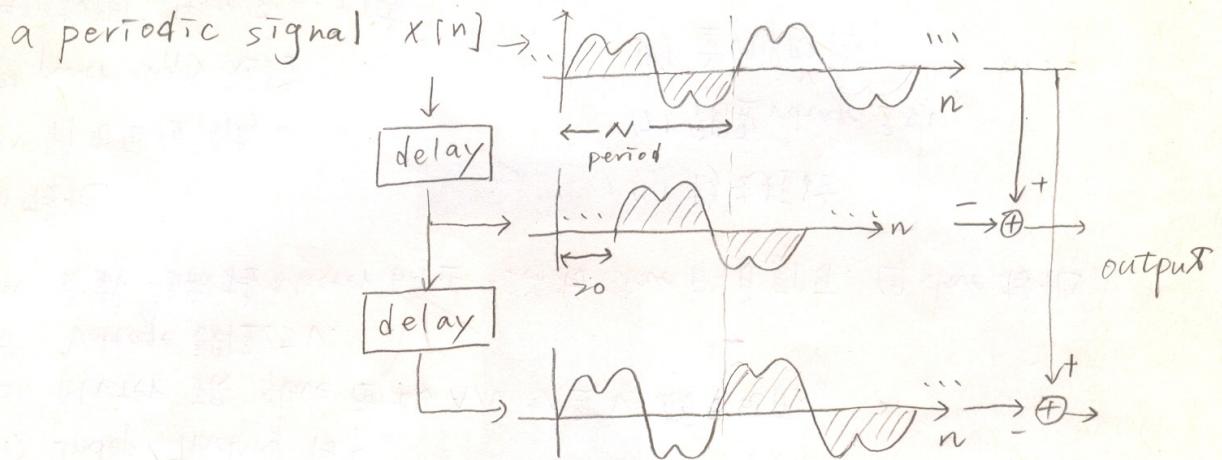
done!

(c)

Bilinear transformation is 1-to-1 mapping from s-plane to z-plane, where impulse invariance isn't. Digital IIR filter design using impulse invariance needs to recheck because aliasing is possible.

4.

(a) from time domain perspectives,

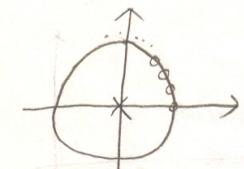


我們 shift 原訊號，再和原訊號相減，當 shift 到正確 period 時，得到的相減 output 就會很小，即可 detect 原訊號的週期。

(b) from frequency domain perspectives.

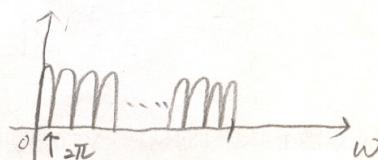
$$\text{ex: } X(z) \xrightarrow{z^{-20}} Y(z) = (1 - z^{-20}) X(z)$$

pole-zero plot :



unit circle 上
均分 20 個點

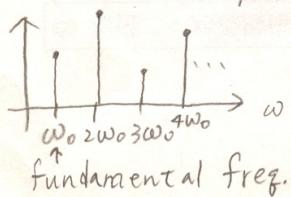
frequency response :



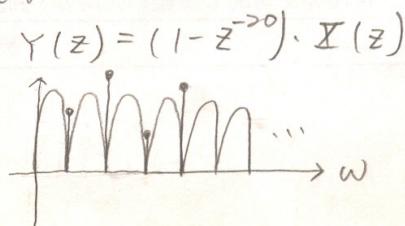
$0 \sim 2\pi$ 上有 20 個
掉到 zero 的突

i. if 原訊號 $X(w)$ 是週期訊號，

frequency response can be:



\Rightarrow

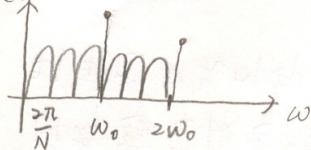


所以，我們調整 filter 為均分 $0 \sim 2\pi$ 201個 zero, 21個 zero...
 當 zero 沒剛好都把原訊號週期濾掉時，output 就會
 很小，即可 detect 原訊號週期。

$$\frac{2\pi}{N} = w_0, N \text{ is the Number of delay.}$$

* 有一處需要注意，如果 w_0 是 $\frac{2\pi}{N}$ 的整數倍，output 也會
 都會很小。所以要取 N 最小且那一個為週期。

i.e.



(c) sample at 10 kHz.

$$\frac{10k}{N} = 50, \Rightarrow N = 200$$

$$\frac{10k}{N} = 500, \Rightarrow N = 20$$

(or one 20-time delay plus
180 unit-time delays.)

So, in the possible range, we need 200 unit-time delays.

Because N is integer, the fundamental frequency can only
 be: $\frac{10k}{20}, \frac{10k}{21}, \frac{10k}{22}, \dots, \frac{10k}{200}$

So, it is not uniformly distributed in 50~500 Hz.