

Artificial Intelligence

V11: Generative Adversarial Learning for Image Synthesis

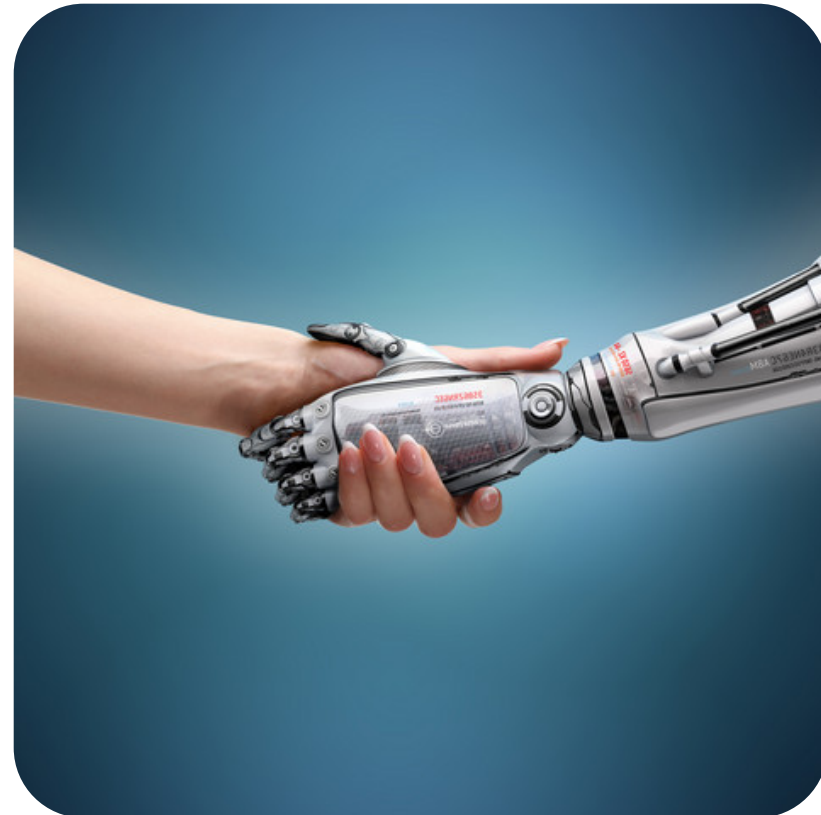
Generative Adversarial Nets
Use case: image inpainting

Mentimeter quizzes: <https://www.menti.com/9kfo33dbw3>



With material from

- Stuart Russell, UC Berkeley
- Arthur Juliani's and Brandon Amos' blog post
- Ian Goodfellow, UC Berkeley COMPSCI 294 guest lecture



Educational objectives

- **Know** the **general idea** behind Generative Adversarial Nets (**GANs**)
- **Understand** the **training** process (and inherent difficulties) **for GANs**
- **Be able** to start **working on open-source GAN** code

➔ Reading: AIMA, ch. 22.1, 22.3, 22.7 (partially)



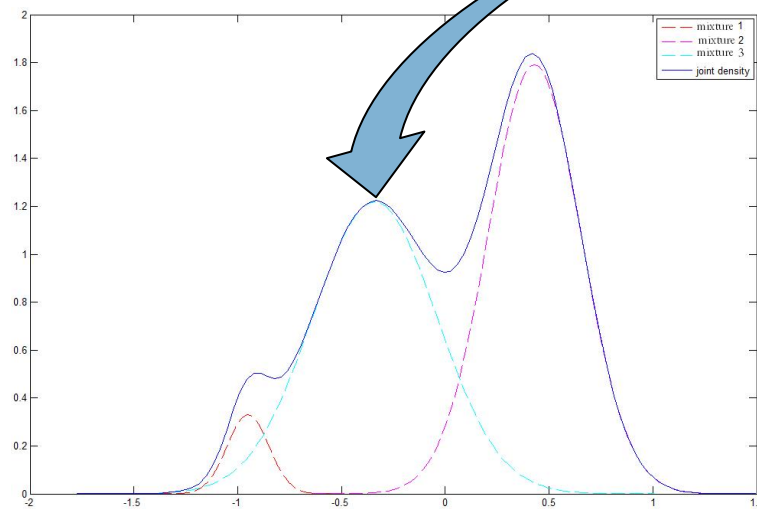
1. GENERATIVE ADVERSARIAL NETS

Probability distributions as generative models

Terminology: its **probability density function (pdf)** is one way to describe a **distribution**.

What does a pdf tell about a set of data?

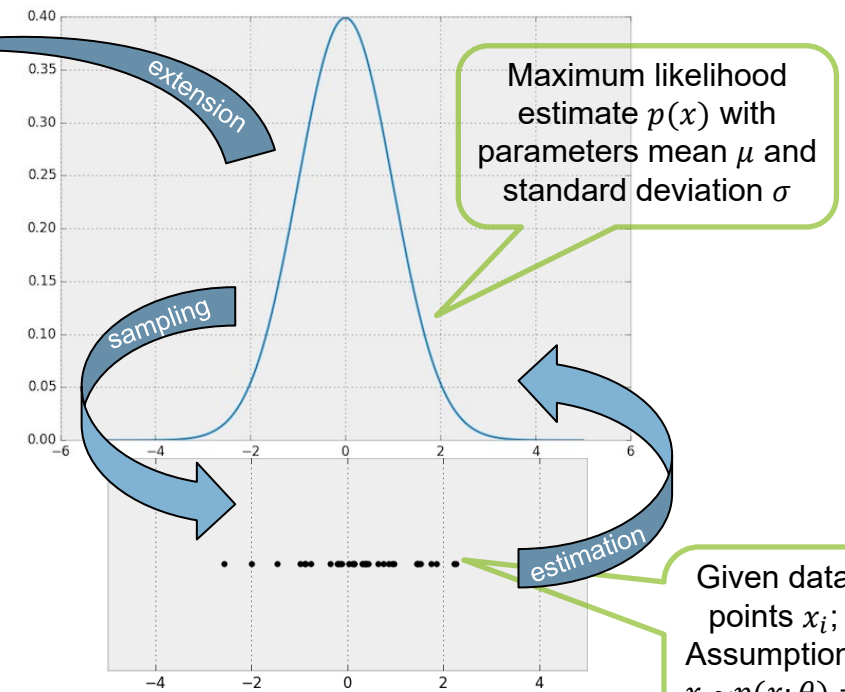
- For data coming from some stochastic processes, the pdf tells **everything there is to know** about the data *without seeing it*
- **Allows for sampling** data from the underlying distribution



Example of a multimodal (but univariate) distribution, approximated by a Gaussian Mixture Model (GMM) with 3 mixtures.

A Gaussian as base generative model

- Recovering a known, parametric pdf:
The univariate Gaussian



Given data points x_i ;
Assumption:
 $x_i \sim p(x; \theta) = N(x; \mu, \sigma)$

Source: Brandon Amos, «Image Completion with Deep Learning in TensorFlow», 2016,
<https://bamos.github.io/2016/08/09/deep-completion/>

Pros and cons of generative models

Flavors of generative models

- **Statistical** models that directly model the pdf (e.g., GMM, hidden Markov model HMM)
- **Graphical** (i.e., graph-based) models with latent variables (e.g., Boltzmann machines RBM/DBM, deep belief networks DBN)
- **Autoencoders** (e.g., Kingma & Welling, “*Autoencoding Variational Bayes*”, 2013)

Promises

- Help **learning about** high-dimensional, complicated probability **distributions** (*even if pdf is not represented explicitly*)
- **Simulate** possible futures for planning or simulated reinforcement learning
- Handle **missing data** (in particular, semi-supervised learning)
- Some applications actually require **generation** (e.g., sound synthesis, identikit pictures, content reconstruction)

Common drawbacks

- Statistical models suffer severely from the **curse of dimensionality**
- Approximations needed for **intractable probabilistic computations** during ML estimation
- **Unbacked assumptions** (e.g., Gaussianity) and averaging e.g., in VAEs

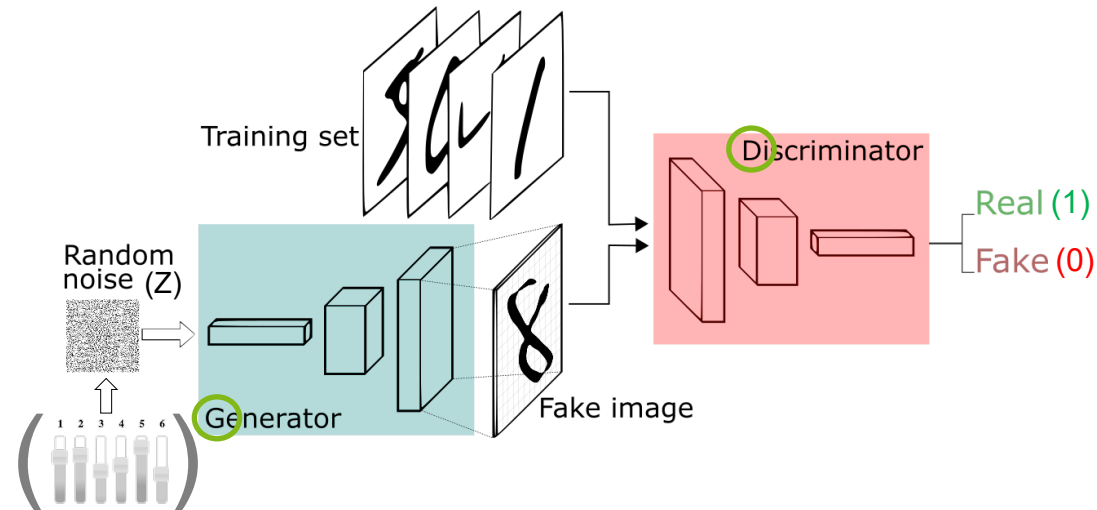
Maximum Likelihood

Adversarial nets

Bootstrapping implicit generative representations

Train 2 models simultaneously [1]

- G: Generator
→ learns to generate data points x
- D: Discriminator
→ learns $p(x \text{ not being generated})$



Sources: <https://deeplearning4j.org/generative-adversarial-network>;
http://www.dpkimgma.com/sgvb_mnist_demo/demo.html

- Both differentiable functions D&G learn while competing
- The **latent space** Z serves as a source of variation to generate different data points
- Only D has access to real data

[1] Schmidhuber, «Learning Factorial Codes by Predictability Minimization», 1992

No weenies allowed! How SpongeBob helps.. ...to understand bootstrapping untrained (G)enerator & (D)iscriminator



Bouncer newbie (D) decides on entry: for tough guys only



SpongeBob (G) wants to appear tough to be admitted (i.e., synthesizes behavior)



In the beginning, D focuses on obvious things to discriminate: e.g., physical strength



So G tries to imitate that, but fails



By observation, G discovers more detailed features of tough guys: e.g., fighting



So G learns to imitate that as well

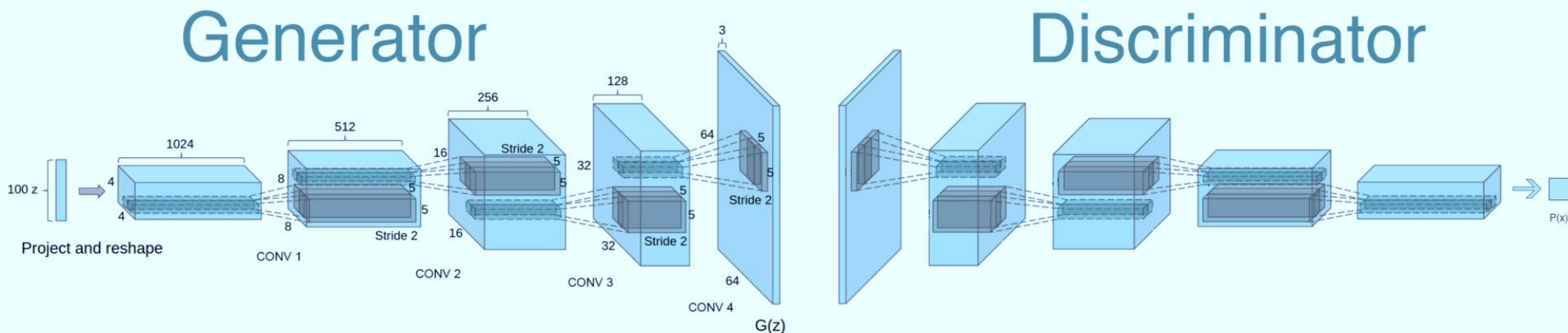


...and eventually tricks D.

Source: Arthur Juliani, «*Generative Adversarial Networks Explained with a Classic Spongebob Squarepants Episode*», 2016, <https://medium.com/@awjuliani/generative-adversarial-networks-explained-with-a-classic-spongebob-squarepants-episode-54deab2fce39#gcoxuaruk>

GAN model formulation (improved)

Deep convolutional generative adversarial nets [2]



Implement both G and D as deep convnets (DCGAN)

- **No pooling**, only fractionally-strided convolutions (G) and strided convolutions (D)
- **No fully connected** hidden layers for deeper architectures
- Apply **batchnorm** in both
- **ReLU** activation in **G** (output layer: tanh)
- **LeakyReLU** activation in **D** (all layers)

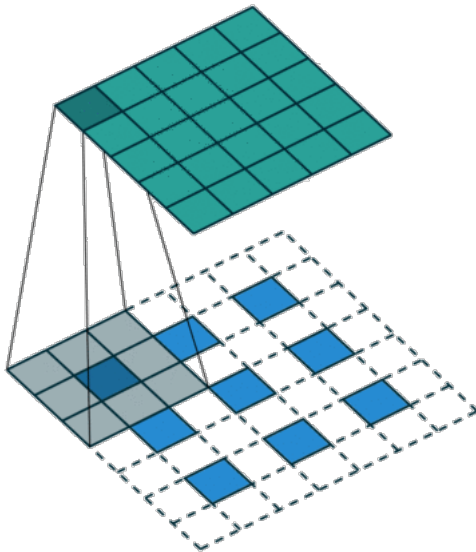
[2] Radford, Metz, Chintala, «Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks», 2016

Strided what? Convolutional arithmetic [3]

NN wiring to save weights while exploiting local structure

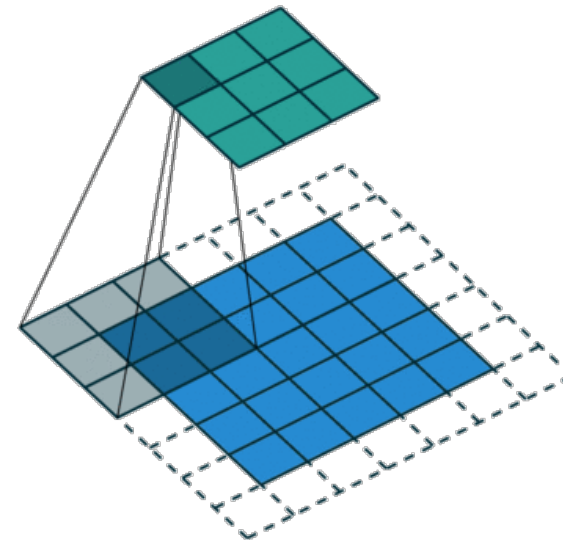
Fractionally-strided conv. in G

- Performing transposed convolution
- Used to «**up-sample**» from input (blue) to output (green)



Strided convolutions in D

- Stride (stepsize) = 2
- Used instead of (max) **pooling** [4]



[3] Dumoulin, Visin, «A guide to convolution arithmetic for deep learning », 2016

[4] Springenberg, Dosovitsiy, Brox, Riedmiller, «Striving for simplicity: The all convolutional net», 2014

Model training [5]

for number of training iterations do

for k steps do

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Sample minibatch of m examples $\{x^{(1)}, \dots, x^{(m)}\}$ from data generating distribution $p_{\text{data}}(x)$.
- Update the discriminator by ascending its stochastic gradient:

change θ_D to maximize $\left\{ \nabla_{\theta_D} \frac{1}{m} \sum_{i=1}^m \left[\underbrace{\log D(x^{(i)})}_{\substack{\text{log likelihood of } x \\ \text{being real} \rightarrow 0}} + \log \left(1 - D(G(z^{(i)})) \right) \right] \right\}$.

log likelihood $G(z)$
not being real $\rightarrow 0$

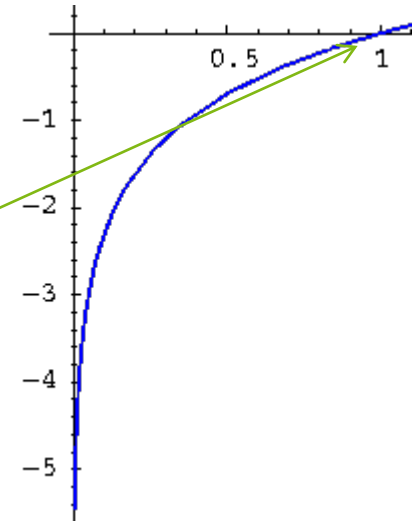
end for

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Update the generator by descending its stochastic gradient:

change θ_G to minimize $\left\{ \nabla_{\theta_G} \frac{1}{m} \sum_{i=1}^m \log \left(1 - D(G(z^{(i)})) \right) \right\}$.

end for

G just get's gradients on how well
it can fool D (no direct training
labels)

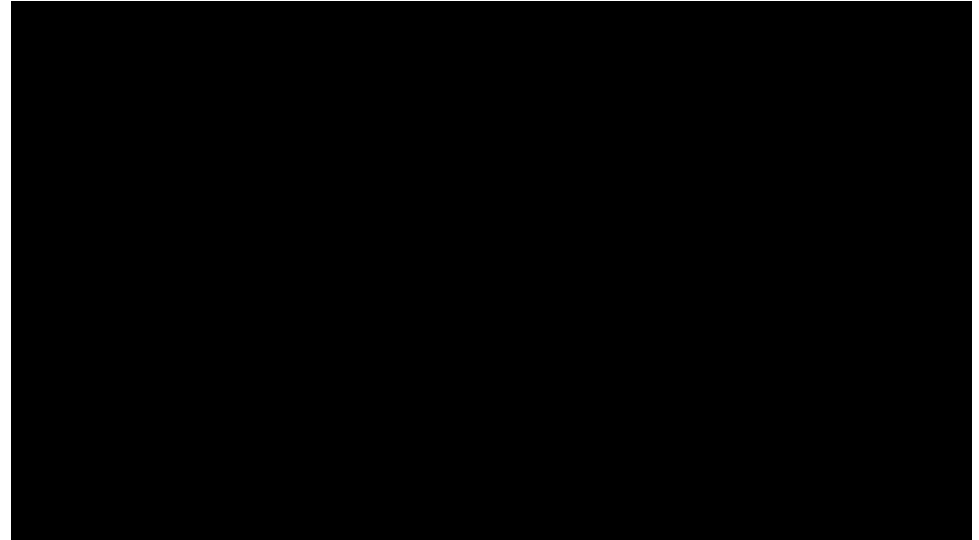


[5] Goodfellow, Pouget-Abadie, Mirza, Xu, Warde-Farley, Ozair, Courville, Bengio, «[Generative Adversarial Nets](#)», 2014

Visualizing the training process

Observations

- G starts with producing **random noise**
- Quickly arrives at what seems to be **pencil strokes**
- It takes a while for the network to produce **different images** for different z
- It takes nearly to the end before the synthesized **images per z stabilize** at certain digits



6x6 samples $G(z)$ from fixed z 's every 2 mini batches (for 50k iterations). See <https://stdm.github.io/Experimenting-with-generative-adversarial-nets/>.

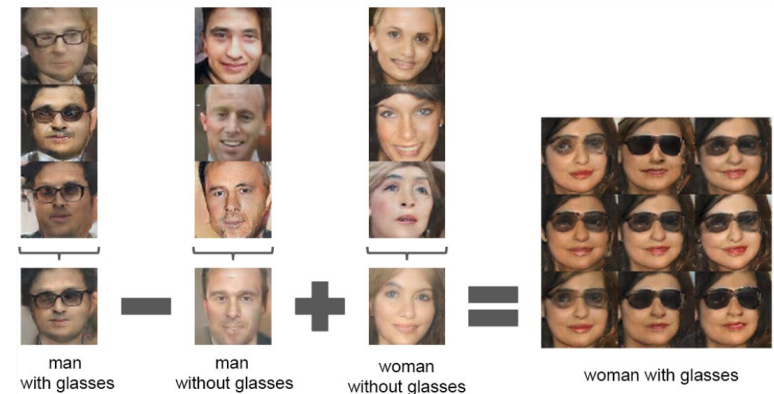
Features of (DC)GANs

Learn semantically meaningful latent space

- Examples of **z-space vector arithmetic** from DCGAN paper [2]:

Training is not guaranteed to converge

- D and G play a **game-theoretic game** against each other (in terms of slide 10: minimax)
- **Gradient descent isn't meant to find the corresponding Nash Equilibria** (saddle point of joint loss function, corresponding to minima of both player's costs) [6]
- How to **sync D's and G's training** is experimental (if G is trained too much, it may collapse all of z 's variety to a single convincing output)
- The improvements of [2] and [7] make them **stable enough for first practical applications**
- **Research** on adversarial training of neural networks is still **ongoing** (as of 2021)



The z vectors in the left 3 columns have been averaged, then arithmetic has been performed. The middle image on the right is the output of G (resulting z vector). The other 8 pictures are the result of adding noise to the resulting z vector (showing that smooth transitions in input space result in smooth transitions in output space).

[6] Goodfellow, Courville, Bengio, «Deep Learning», ch. 20.10.4, 2016

[7] Salimans, Goodfellow, Zaremba, Cheung, «Improved Techniques for Training GANs», 2016

2. USE CASE: IMAGE INPAINTING

Based on material from Brandon Amos,
«Image Completion with Deep Learning in TensorFlow», 2016

<https://bamos.github.io/2016/08/09/deep-completion/>

GAN use cases

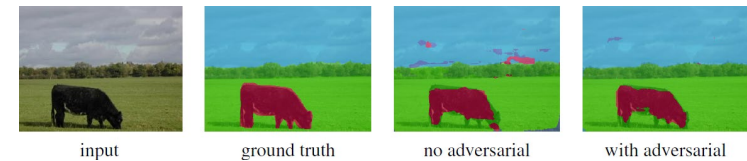
Research has **gained** a lot of **momentum very quickly**; see appendix for more!

- Generate images from text
Reed et al., «*Generative Adversarial Text to Image Synthesis*», 2016

a man in a wet
suit riding a
surfboard on a
wave.



- Segment images into semantically meaningful parts
Luc et al., «*Semantic Segmentation using Adversarial Networks*», 2016



- Complete missing parts in images
Yeh et al., «*Semantic Image Inpainting with Perceptual and Contextual Losses*», 2016
→ see next slides

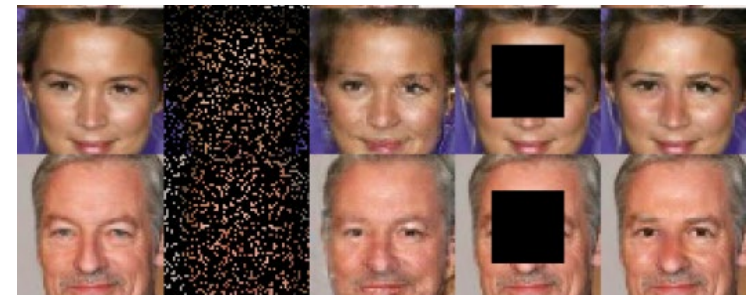
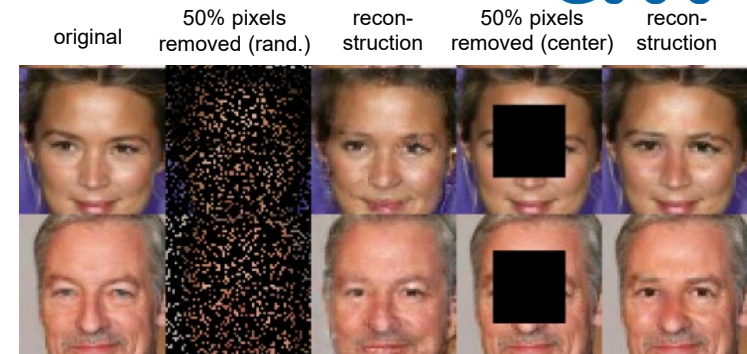


Image inpainting as a sampling problem

...approached by machine learning

Yeh et al., «*Semantic Image Inpainting with Perceptual and Contextual Losses*», 2016



Training: Regard **images as samples** of some underlying probability distribution p_G

1. Learn to represent this distribution using a GAN setup (G and D)

--

Testing/Application: Draw a *suitable* sample from p_G by...

1. Fixing parameters θ_G and θ_D of G and D, respectively
2. **Finding input \hat{z} to G such that $G(\hat{z})$ fits two constraints:**
 - a) **Contextual:** Output must **match** the **known parts** of the **image** that needs inpainting
 - b) **Perceptual:** Output must **look generally «real»** according to D's judgment
3. ...by using gradient-based **optimization on \hat{z}**

Powerful idea: application of trained ML model may again involve optimization!

Reconstruction formulation

Given

- Uncomplete/corrupted image $x_{corrrputed}$
- Binary mask M (same size as $x_{corrrputed}$, 1 for given pixels, 0 for missing/corrupted pixels)
- Trained generator network $G()$, discriminator network $D()$

Problem

- Find \hat{z} such that $x_{reconstructed} = M \odot x_{corrrputed} + (1 - M) \odot G(\hat{z})$
(\odot here is the element-wise product of two matrices)

Input			Binary Mask			Output	
1	2	\odot	1	0	=	1	0
3	4		0	1		0	4

Solution

- Define contextual and perceptual loss as follows:

$$L_{contextual}(z) = \|M \odot G(z) - M \odot x_{corrrputed}\|_1 \quad (\text{distance between known parts of image and reconstruction})$$

$$L_{perceptual}(z) = \log(1 - D(G(z))) \quad (\text{as before: log-likelihood of } G(z) \text{ **not** being real according to } D)$$

$$L(z) = L_{contextual}(z) + \lambda \cdot L_{perceptual}(z) \quad (\text{combined loss})$$

→ Optimize $\hat{z} = \arg \min_z L(z)$

Results



See it move: <https://github.com/bamos/dcgan-completion.tensorflow>

Where's the intelligence?

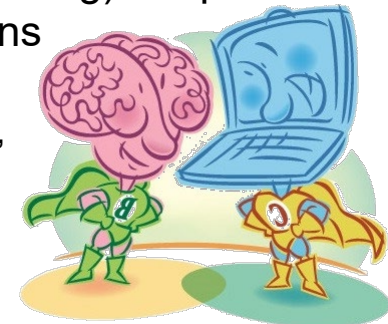
Man vs. machine

- **Learning** smooth approximations of complex probability **density** functions (PDF) enables us to **sample previously unseen examples**
 - That is, we can **create** new images, new music, ...



Source: <https://nerdist.com/nvidia-ai-headshots-fake-celebrities/>.

- But isn't **creativity** more **the power to surprise**, i.e., (technically speaking) the power to **come up with new yet reasonable PDFs** instead of new instantiations from a given PDF?
 - That would mean that to create does not mean to know the PDF of «*things*», but the PDF of the «*reasonableness of things*». As this is unknown for novel things, it needs to be **continually explored**.



Review

- **Neural networks** with at least one hidden layer **are general function approximators**, trained by gradient descent
- **GANs** have been shown to **produce realistic output** on a wide range of (still smallish) image, audio and text generation tasks
- **Finding Nash equilibria** in high-dimensional, continuous, non-convex games **is an important open research problem**
- **Image inpainting works by optimizing the output** of a fully trained generator to fit the given context & realism criteria, **using again gradient descent**
 - ➔ Applying machine learned models might involve optimization (~training) steps again
 - ➔ **This is in line with human learning:** Once trained to draw, hand-copying a painting involves “optimization” on the part of the painter

Further reading: Goodfellow, «*NIPS 2016 Tutorial: Generative Adversarial Networks*», 2016





APPENDIX

Recap: Basic idea of deep learning

Add depth (layers → capability) to learn features automatically

Classic computer vision

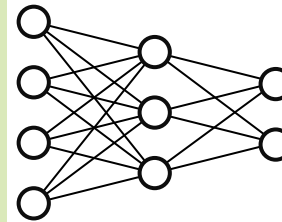


Feature extraction
(SIFT, SURF, LBP, HOG, etc.)

(0.2, 0.4, ...)

(0.4, 0.3, ...)

Classification
(SVM, neuronal net, etc.)



container ship

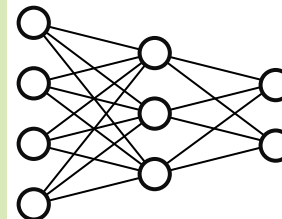
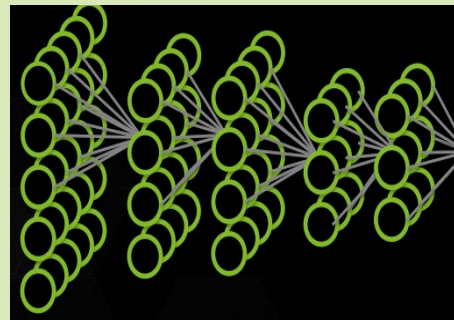
tiger

...

Convolutional
neural networks
(CNNs)



Takes raw pixels as input, learns
good features automatically!



container ship

tiger

...

The GAN zoo

Avinash Hindupur's list at <https://github.com/hindupuravinash>
(as of Apr 2017; last update Sep 2018: #502 GANs)

GAN - Generative Adversarial Networks
 3D-GAN - Learning a Probabilistic Latent Space of Object Shapes via 3D Generative-Adversarial Modeling
 AC-GAN - Conditional Image Synthesis With Auxiliary Classifier GANs
 AdaGAN - AdaGAN: Boosting Generative Models
 AffGAN - Amortised MAP Inference for Image Super-resolution
 AL-CGAN - Learning to Generate Images of Outdoor Scenes from Attributes and Semantic Layouts
 ALI - Adversarially Learned Inference
 AMGAN - Generative Adversarial Nets with Labeled Data by Activation Maximization
 AnoGAN - Unsupervised Anomaly Detection with Generative Adversarial Networks to Guide Marker Discovery
 ArtGAN - ArtGAN: Artwork Synthesis with Conditional Categorical GANs
 b-GAN - b-GAN: Unified Framework of Generative Adversarial Networks
 Bayesian GAN - Deep and Hierarchical Implicit Models
 BEGAN - BEGAN: Boundary Equilibrium Generative Adversarial Networks
 BiGAN - Adversarial Feature Learning
 BS-GAN - Boundary-Seeking Generative Adversarial Networks
 CGAN - Conditional Generative Adversarial Nets
 CCGAN - Semi-Supervised Learning with Context-Conditional Generative Adversarial Networks
 CatGAN - Unsupervised and Semi-supervised Learning with Categorical Generative Adversarial Networks
 CoGAN - Coupled Generative Adversarial Networks
 Context-RNN-GAN - Contextual RNN-GANs for Abstract Reasoning Diagram Generation
 C-RNN-GAN - C-RNN-GAN: Continuous recurrent neural networks with adversarial training
 CVAE-GAN - CVAE-GAN: Fine-Grained Image Generation through Asymmetric Training
 CycleGAN - Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks
 DTN - Unsupervised Cross-Domain Image Generation
 DCGAN - Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks
 DiscoGAN - Learning to Discover Cross-Domain Relations with Generative Adversarial Networks
 DR-GAN - Disentangled Representation Learning GAN for Pose-Invariant Face Recognition
 DualGAN - DualGAN: Unsupervised Dual Learning for Image-to-Image Translation
 EBGAN - Energy-based Generative Adversarial Network
 f-GAN - f-GAN: Training Generative Neural Samplers using Variational Divergence Minimization
 FF-GAN - Towards Large-Pose Face Frontalization in the Wild
 GAWWN - Learning What and Where to Draw
 GoGAN - Gang of GANs: Generative Adversarial Networks with Maximum Margin Ranking
 GP-GAN - GP-GAN: Towards Realistic High-Resolution Image Blending
 IAN - Neural Photo Editing with Introspective Adversarial Networks
 iGAN - Generative Visual Manipulation on the Natural Image Manifold
 IcGAN - Invertible Conditional GANs for image editing
 ID-CGAN - Image De-raining Using a Conditional Generative Adversarial Network
 Improved GAN - Improved Techniques for Training GANs
 InfoGAN - InfoGAN: Interpretable Representation Learning by Information Maximizing Generative Adversarial Nets
 LAPGAN - Deep Generative Image Models using a Laplacian Pyramid of Adversarial Networks
 LR-GAN - LR-GAN: Layered Recursive Generative Adversarial Networks for Image Generation

LSGAN - Least Squares Generative Adversarial Networks
 LS-GAN - Loss-Sensitive Generative Adversarial Networks on Lipschitz Densities
 MGAN - Precomputed Real-Time Texture Synthesis with Markovian Generative Adversarial Networks
 MAGAN - MAGAN: Margin Adaptation for Generative Adversarial Networks
 MAD-GAN - Multi-Agent Diverse Generative Adversarial Networks
 MalGAN - Generating Adversarial Malware Examples for Black-Box Attacks Based on GAN
 MARTA-GAN - Deep Unsupervised Representation Learning for Remote Sensing Images
 McGAN - McGAN: Mean and Covariance Feature Matching GAN
 MedGAN - Generating Multi-label Discrete Electronic Health Records using Generative Adversarial Networks
 MIX+GAN - Generalization and Equilibrium in Generative Adversarial Nets (GANs)
 MPM-GAN - Message Passing Multi-Agent GANs
 MV-BiGAN - Multi-view Generative Adversarial Networks
 pix2pix - Image-to-Image Translation with Conditional Adversarial Networks
 PPGN - Plug & Play Generative Networks: Conditional Iterative Generation of Images in Latent Space
 PrGAN - 3D Shape Induction from 2D Views of Multiple Objects
 RenderGAN - RenderGAN: Generating Realistic Labeled Data
 RTT-GAN - Recurrent Topic-Transition GAN for Visual Paragraph Generation
 SGAN - Stacked Generative Adversarial Networks
 SGAN - Texture Synthesis with Spatial Generative Adversarial Networks
 SAD-GAN - SAD-GAN: Synthetic Autonomous Driving using Generative Adversarial Networks
 SalGAN - SalGAN: Visual Saliency Prediction with Generative Adversarial Networks
 SEGAN - SEGAN: Speech Enhancement Generative Adversarial Network
 SeGAN - SeGAN: Segmenting and Generating the Invisible
 SeqGAN - SeqGAN: Sequence Generative Adversarial Nets with Policy Gradient
 SketchGAN - Adversarial Training For Sketch Retrieval
 SL-GAN - Semi-Latent GAN: Learning to generate and modify facial images from attributes
 Softmax-GAN - Softmax GAN
 SRGAN - Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network
 S*2GAN - Generative Image Modeling using Style and Structure Adversarial Networks
 SSL-GAN - Semi-Supervised Learning with Context-Conditional Generative Adversarial Networks
 StackGAN - StackGAN: Text to Photo-realistic Image Synthesis with Stacked Generative Adversarial Networks
 TGAN - Temporal Generative Adversarial Nets
 TAC-GAN - TAC-GAN - Text Conditioned Auxiliary Classifier Generative Adversarial Network
 TP-GAN - Beyond Face Rotation: Global and Local Perception GAN for Photorealistic and Identity Preserving Frontal View Synthesis
 Triple-GAN - Triple Generative Adversarial Nets
 Unrolled GAN - Unrolled Generative Adversarial Networks
 VGAN - Generating Videos with Scene Dynamics
 VGAN - Generative Adversarial Networks as Variational Training of Energy Based Models
 VAE-GAN - Autoencoding beyond pixels using a learned similarity metric
 VariGAN - Multi-View Image Generation from a Single-View
 ViGAN - Image Generation and Editing with Variational Info Generative Adversarial Networks
 WGAN - Wasserstein GAN
 WGAN-GP - Improved Training of Wasserstein GANs
 WaterGAN - WaterGAN: Unsupervised Generative Network to Enable Real-time Color Correction of Monocular Underwater Images