## CodeBook

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Collection of the raw data

The data was collected from the Human Activity Recognition Using Smartphones Dataset Version 1.0. This dataset was obtained from the course website, and represent data collected from the accelerometers from the Samsung Galaxy S smartphone. A full description is available at the site where the data was obtained:

http://archive.ics.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones

## Description of the variables in the tidyDataset.txt file

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerkMag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern: '-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

1.tBodyAcc-XYZ 2.tGravityAcc-XYZ 3.tBodyAccJerk-XYZ 4.tBodyGyro-XYZ 5.tBodyGyroJerk-XYZ 6.tBodyAccMag 7.tGravityAccMag 8.tBodyAccJerkMag 9.tBodyGyroMag 10.tBodyGyroJerkMag 11.fBodyAcc-XYZ 12.fBodyAccJerk-XYZ 13.fBodyGyro-XYZ 14.fBodyAccMag 15.fBodyAccJerkMag 16.fBodyGyroMag 17.fBodyGyroJerkMag

The set of variables that were estimated from these signals are:

- mean(): Mean value
   std(): Standard deviation
- For each group of subject-Activy-patternSignal is estimated the average. The dataset contains 180 rows and 81 variables.

The complete list of variables is available next:

 $subjectID : int 1 \dots 30$ 

 $\$  Activity : chr "LAYING" "SITTING" "STANDING" "WALKING" "WALKING\_UPSTAIRS" "WALKING DOWNSTAIRS"

\$fBodyAcc.mean.X : num NaN NaN 0.207 0.2074 0.0456 ...

\$ fBodyAcc.mean.Y : num NaN NaN 0.528 0.234 0.469 . . .

 $\$ fBodyAcc.mean.Z : num NaN NaN 0.524 0.319 0.259 . . .

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\f<br/>Body
Acc.mean
Freq.X : num NaN NaN 0.31 0.316 0.204 . . .
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- $\$ f<br/>Body Acc.mean Freq.Y : num NaN NaN 0.575 0.328 0.276 . . .
- $\$ f<br/>Body Acc.mean Freq.Z : num NaN NaN 0.39 0.349 0.152 . . .
- $\$ f<br/>Body Acc.std.X : num NaN NaN 0.128 0.288 0.276 . . .
- \$ fBodyAcc.std.Y : num NaN NaN 0.191 0.245 0.466 . . .
- $\$ fBodyAcc.std.Z : num NaN NaN 0.294 0.181 0.177 . . .
- $\$  fBodyAccJerk.mean.Y : num NaN 0.5824 0.5257 0.1478 0.0554 . . .
- $\$ f<br/>Body AccJerk.mean.Z : num Na<br/>N0.756 0.367 0.275<br/> 0.214 . . .
- \$fBodyAccJerk.meanFreq.X : num NaN 0.123 0.313 0.113 NaN ...
- $\$ f<br/>Body AccJerk.mean Freq.Y : num Na<br/>N $0.201~0.419~0.239~{\rm NaN}~\dots$
- $\$ f<br/>Body AccJerk.mean Freq.Z : num Na<br/>N $0.0546~0.5338~0.1894~{\rm NaN}$  . . .
- $\$ f<br/>Body AccJerk.std.Y : num NaN -0.2546 0.0179 0.1413 Na<br/>N . . .
- $\$ f<br/>Body AccJerk.std.Z : num Na<br/>N0.1813-0.3468 0.0923 Na<br/>N . . .
- \$ fBodyAccMag.mean(): num NaN 0.2781 NaN 0.0594 NaN ...
- \$ fBodyAccMag.meanFreq(): num NaN 0.216 NaN 0.0933 -0.0615 ...
- \$fBodyAccMag.std(): num NaN 0.29323 NaN 0.06666 0.00207...
- $\$ fBodyBodyAccJerkMag.mean() : num Na<br/>N0.23642NaN0.245397- $0.000929\ldots$
- \$ fBodyBodyAccJerkMag.meanFreq(): num NaN 0.018 NaN 0.152 0.449 ...
- \$fBodyBodyAccJerkMag.std(): num NaN 0.0933 NaN 0.2101 0.2937 ...
- \$ fBodyBodyGyroJerkMag.mean(): num 0.5438 0.5464 NaN 0.0952 0.2799 ...
- \$ fBodyBodyGyroJerkMag.meanFreq(): num 0.408 NaN NaN 0.212 0.422 . . .
- \$ fBodyBodyGyroJerkMag.std(): num 0.2379 NaN NaN 0.2439 0.0623 ...
- \$fBodyBodyGyroMag.mean(): num -0.275 0.218 NaN 0.208 0.158 ...
- \$fBodyBodyGyroMag.meanFreq(): num 0.438 0.148 NaN 0.109 0.169 ...
- fBodyBodyGyroMag.std(): num 0.428473 0.089257 NaN 0.245971 0.000784...
- $\$ f<br/>Body Gyro.mean.X : num NaN 0.0924 0.3979 0.1577 NaN . . .
- $\$ f<br/>Body Gyro.mean. Y : num NaN 0.4537 0.3642 0.0827 NaN . . .
- $\$ f<br/>Body Gyro.mean.Z : num Na<br/>N0.191 0.365 0.176 Na<br/>N  $\dots$
- \$fBodyGyro.meanFreq.X: num NaN 0.459 0.459 0.223 NaN ...
- $\$ fBodyGyro.meanFreq.Y : num Na<br/>N0.350.7370.178 Na<br/>N . . .
- $\$ f<br/>Body Gyro.mean Freq.Z : num Na<br/>N0.165 NaN0.155 NaN . . .
- $\$ f<br/>Body Gyro.std.X : num NaN 0.207 0.752 0.18 NaN . . .
- $\$ f<br/>Body Gyro.std.Y : num NaN 0.107 0.519 0.165 NaN . . .
- $\$ f<br/>Body Gyro.std.Z : num NaN 0.217 0.242 0.218 NaN . . .

- $\$ t<br/>Body Acc.mean.X : num 0.438 NaN NaN 0.236 0.335 . . .
- $\$ t<br/>Body Acc.mean. Y : num 0.4417 Na<br/>N NaN 0.2431 0.0275 . . .
- $\$ t<br/>Body Acc.mean.Z : num 0.58328 NaN NaN NaN 0.00549 . . .
- $\$ tBodyAcc.std.X : num 0.7069 NaN NaN NaN 0.0958 . . .
- $\$ t<br/>Body Acc.std.Y : num 0.552 NaN NaN NaN 0.196 . . .
- $\$ tBodyAcc.std.Z : num 0.498 NaN NaN NaN 0.224 . . .
- $\$ t<br/>Body AccJerk.mean.X : num -0.282 0.231 Na<br/>N NaN 0.342 . . .
- $\$ tBody AccJerk.mean. Y : num -0.525 0.204 Na<br/>N NaN 0.136 . . .
- $\$ tBodyAccJerk.std.X : num -0.27 0.073 NaN NaN NaN . . .
- $\$ tBody AccJerk.std.Y : num 0.293 0.262 Na<br/>N NaN NaN . . .
- $\$ tBodyAccJerk.std.Z : num 0.248 0.459 NaN NaN NaN . . .
- \$ tBodyAccJerkMag.mean(): num NaN NaN 0.69 0.139 NaN . . .
- \$ tBodyAccJerkMag.std() : num NaN NaN 0.74 0.187 NaN . . .
- \$ tBodyAccMag.mean(): num -0.124 NaN 0.314 -0.0873 NaN . . .
- \$ tBodyAccMag.std(): num -0.0787 NaN 0.2674 0.1185 NaN ...
- $\$ tBody Gyro.mean.X : num 0.23 0.508 Na<br/>N NaN NaN . . .
- $\$ t<br/>Body Gyro.mean. Y : num 0.356 0.34 Na<br/>N NaN NaN . . .
- $\$ t<br/>Body Gyro.mean.Z : num 0.425 0.477 NaN NaN NaN . . .
- \$ tBodyGyro.std.X : num NaN -0.478 NaN -0.152 NaN . . .
- $\$ t<br/>Body Gyro.std. Y : num -0.201 NaN NaN 0.174 NaN . . .
- $\$  tBodyGyro.std.Z : num -0.102 NaN 0.158 0.244 NaN . . .
- $\$ t<br/>Body Gyro Jerk.mean.X : num -0.186 Na<br/>N0.4150.263 Na<br/>N $\dots$
- $\$  tBodyGyroJerk.mean.Y : num -0.373 NaN 0.405 0.415 NaN . . .
- $\$ tBody Gyro Jerk.<br/>mean. Z : num -0.3644 Na<br/>N0.08780.3354 Na<br/>N $\dots$
- $\$ tBody Gyro Jerk.std.X : num 0.201 Na<br/>N0.02~0.22 Na<br/>N . . .
- $\$ t<br/>Body Gyro Jerk.std.Y : num 0.133 Na<br/>N 0.146 0.218 Na<br/>N . . .
- $\$ tBody Gyro Jerk.std.Z : num 0.5315 Na<br/>N 0.1364 -0.0209 Na<br/>N  $\dots$
- \$ tBodyGyroJerkMag.mean(): num NaN NaN 0.5607 0.1 0.0824 ...
- tBodyGyroJerkMag.std(): num NaN NaN 0.429 0.173 -0.105 ...
- \$ tBodyGyroMag.mean(): num NaN NaN 0.131 0.194 0.545 ...
- \$ tBodyGyroMag.std(): num NaN NaN 0.662 0.133 0.579 ...
- $\$ tGravityAcc.mean.X : num 0.434 NaN NaN NaN 0.213 . . .
- $\$ t<br/>Gravity Acc.mean.Y : num 0.0664 NaN NaN NaN 0.2377 . . .
- $\$ t<br/>Gravity Acc.mean.Z : num 0.405 NaN NaN NaN 0.183 . . .
- $\$ tGravityAcc.std.X : num -0.1436 NaN NaN NaN 0.0704 . . .

- $\$ t<br/>Gravity Acc.std.Y : num -0.6912 -0.27 Na<br/>N NaN 0.0305 . . .
- $\$ t<br/>Gravity AccMag.mean() : num 0.0991 NaN 0.1205 0.2048 Na<br/>N . . .
- $\$ tGravityAccMag.std() : num NaN NaN 0.351 0.225 NaN ..