## CodeBook

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##Collection of the raw data The data was collected from the Human Activity Recognition Using Smartphones Dataset Version 1.0. This dataset was obtained from the course website, and represent data collected from the accelerometers from the Samsung Galaxy S smartphone. A full description is available at the site where the data was obtained:

http://archive.ics.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones

##Creating the tidy datafile

The script run\_analysis.R is to performing the analysis of the dataset.

###Guide to create the tidy data file

to create the tidy data file

- 1. Merges the training and the test sets to create one data set.
- 2. Extracts only the measurements on the mean and standard deviation for each measurement.
- 3. Uses descriptive activity names to name the activities in the data set
- 4. Appropriately labels the data set with descriptive variable names.
- 5. From the data set in step 4, creates a second, independent tidy data set with the average of each variable for each activity and each subject.

##Description of the variables in the tidyDataset.txt file

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerkMag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern: '-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

1.tBodyAcc-XYZ 2.tGravityAcc-XYZ 3.tBodyAccJerk-XYZ 4.tBodyGyro-XYZ 5.tBodyGyroJerk-XYZ 6.tBodyAccMag 7.tGravityAccMag 8.tBodyAccJerkMag 9.tBodyGyroMag 10.tBodyGyroJerkMag 11.fBodyAcc-XYZ 12.fBodyAccJerk-XYZ 13.fBodyGyro-XYZ 14.fBodyAccMag 15.fBodyAccJerkMag 16.fBodyGyroMag 17.fBodyGyroJerkMag

The set of variables that were estimated from these signals are:

mean(): Mean value
std(): Standard deviation

And for each group of subject-Activy-patternSignal is estimated the average.

The complete list of variables of each feature vector is available next:

- $subjectID : int 1 \dots 30$
- \$ Activity : chr "LAYING" "SITTING" "STANDING" "WALKING" "WALKING\_UPSTAIRS" "WALKING DOWNSTAIRS"
- $\$ f<br/>Body Acc.mean.X : num NaN NaN 0.207 0.2074 0.0456 . . .
- $\$ f<br/>Body Acc.mean.Y : num NaN NaN 0.528 0.234 0.469 . . .
- $\$ f<br/>Body Acc.mean.Z : num NaN NaN 0.524 0.319 0.259 . . .
- \$fBodyAcc.meanFreq.X : num NaN NaN 0.31 0.316 0.204 ...
- $\$ f<br/>Body Acc.mean Freq.Y : num NaN NaN 0.575 0.328 0.276 . . .
- $\$ f<br/>Body Acc.mean Freq.Z : num NaN NaN 0.39 0.349 0.152 . . .
- $\$ f<br/>Body Acc.std.X : num NaN NaN 0.128 0.288 0.276 . . .
- $\$ f<br/>Body Acc.std.Y : num NaN NaN 0.191 0.245 0.466 . . .
- $\$ f<br/>Body Acc.std.Z : num NaN NaN 0.294 0.181 0.177 . . .
- $\$  fBodyAccJerk.mean.X : num NaN -0.2576 0.1265 0.2637 0.0538 . . .
- $\$  fBodyAccJerk.mean.Y : num NaN 0.5824 0.5257 0.1478 0.0554 . . .
- $\$ fBodyAccJerk.mean.Z : num Na<br/>N0.756 0.367 0.275 0.214 . . .
- fBodyAccJerk.meanFreq.X : num NaN 0.123 0.313 0.113 NaN ...
- $\$ f<br/>Body AccJerk.mean Freq.Y : num Na<br/>N $0.201~0.419~0.239~{\rm NaN}~\dots$
- $\$ f<br/>Body AccJerk.mean Freq.Z : num Na<br/>N0.05460.53380.1894 Na<br/>N . . .
- \$fBodyAccJerk.std.X : num NaN -0.4635 0.0834 0.2393 0.2171 ...
- $\$ fBodyAccJerk.std.Y : num NaN -0.2546 0.0179 0.1413 NaN . . .
- $\$ f<br/>Body AccJerk.std.Z : num Na<br/>N0.1813-0.3468 0.0923 Na<br/>N . . .
- \$ fBodyAccMag.mean(): num NaN 0.2781 NaN 0.0594 NaN ...
- \$ fBodyAccMag.meanFreq(): num NaN 0.216 NaN 0.0933 -0.0615 ...
- \$ fBodyAccMag.std(): num NaN 0.29323 NaN 0.06666 0.00207 ...
- \$ fBodyBodyAccJerkMag.mean(): num NaN 0.23642 NaN 0.245397 -0.000929 ...
- \$ fBodyBodyAccJerkMag.meanFreq(): num NaN 0.018 NaN 0.152 0.449 . . .
- $\$ fBodyBodyAccJerkMag.std() : num NaN 0.0933 NaN 0.2101 0.2937 ...
- \$ fBodyBodyGyroJerkMag.mean(): num 0.5438 0.5464 NaN 0.0952 0.2799 ...
- \$ fBodyBodyGyroJerkMag.meanFreq(): num 0.408 NaN NaN 0.212 0.422 ...
- \$ fBodyBodyGyroJerkMag.std(): num 0.2379 NaN NaN 0.2439 0.0623 ...
- \$ fBodyBodyGyroMag.mean(): num -0.275 0.218 NaN 0.208 0.158 ...
- \$ fBodyBodyGyroMag.meanFreq(): num 0.438 0.148 NaN 0.109 0.169 ...
- $\$  fBodyBodyGyroMag.std(): num 0.428473 0.089257 NaN 0.245971 0.000784 ...
- $\$ f<br/>Body Gyro.mean.X : num NaN 0.0924 0.3979 0.1577 NaN . . .
- $\$  fBodyGyro.mean.Y : num NaN 0.4537 0.3642 0.0827 NaN . . .

- $\$ f<br/>Body Gyro.mean.Z : num NaN 0.191 0.365 0.176 NaN . . .
- $\$ f<br/>Body Gyro.mean Freq.X : num Na<br/>N $0.459~0.459~0.223~{\rm NaN}~\dots$
- $\$ f<br/>Body Gyro.mean Freq.Y : num Na<br/>N0.35~0.737~0.178 Na<br/>N . . .
- $\$ f<br/>Body Gyro.mean Freq.Z : num Na<br/>N0.165 NaN0.155 NaN . . .
- \$fBodyGyro.std.X : num NaN 0.207 0.752 0.18 NaN ...
- $\$ f<br/>Body Gyro.std.Y : num NaN 0.107 0.519 0.165 NaN . . .
- $\$ f<br/>Body Gyro.std.Z : num NaN 0.217 0.242 0.218 NaN . . .
- $\$ tBody Acc.mean.X : num 0.438 Na<br/>N NaN 0.236 0.335 . . .
- $\$ tBody Acc.<br/>mean. Y : num 0.4417 NaN NaN 0.2431 0.0275 . . .
- $\$ tBodyAcc.mean.Z : num 0.58328 NaN NaN NaN 0.00549 . . .
- $\$ tBodyAcc.std.X : num 0.7069 NaN NaN NaN 0.0958 . . .
- $\$ t<br/>Body Acc.std.Y : num 0.552 NaN NaN NaN 0.196 . . .
- $\$ t<br/>Body Acc.std.Z : num 0.498 NaN NaN NaN 0.224 . . .
- $\$  tBodyAccJerk.mean.X : num -0.282 0.231 NaN NaN 0.342 . . .
- $\$  tBodyAccJerk.mean.Y : num -0.525 0.204 NaN NaN 0.136 . . .
- $\$ tBodyAccJerk.std.X : num -0.27 0.073 NaN NaN NaN . . .
- $\$ t<br/>Body AccJerk.std.Y : num 0.293 0.262 NaN NaN NaN . . .
- $\$ t<br/>Body AccJerk.std.Z : num 0.248 0.459 Na<br/>N NaN NaN . . .
- \$ tBodyAccJerkMag.mean(): num NaN NaN 0.69 0.139 NaN ...
- \$ tBodyAccJerkMag.std(): num NaN NaN 0.74 0.187 NaN . . .
- \$ tBodyAccMag.mean(): num -0.124 NaN 0.314 -0.0873 NaN ...
- \$ tBodyAccMag.std(): num -0.0787 NaN 0.2674 0.1185 NaN ...
- $\$ t<br/>Body Gyro.mean.X : num 0.23 0.508 NaN NaN NaN . . .
- $\$ t<br/>Body Gyro.mean. Y : num 0.356 0.34 Na<br/>N NaN NaN . . .
- $\$ t<br/>Body Gyro.mean.Z : num 0.425 0.477 Na<br/>N NaN NaN . . .
- $\$ tBody Gyro.std.X : num NaN -0.478 NaN -0.152 Na<br/>N  $\dots$
- \$ tBodyGyro.std.Y : num -0.201 NaN NaN 0.174 NaN . . .
- $\$  tBodyGyro.std.Z : num -0.102 NaN 0.158 0.244 NaN . . .
- $\$ tBody Gyro Jerk.<br/>mean. X : num -0.186 NaN 0.415 0.263 NaN . . .
- $\$  tBody GyroJerk.mean.Y : num -0.373 NaN 0.405 0.415 NaN . . .
- $\$  tBody GyroJerk.mean.Z : num -0.3644 NaN 0.0878 0.3354 NaN . . .
- $\$ t<br/>Body Gyro Jerk.std.X : num 0.201 Na<br/>N 0.02 0.22 Na<br/>N  $\dots$
- $\$ tBody Gyro Jerk.std.Y : num 0.133 Na<br/>N0.1460.218 Na N $\dots$
- $\$ tBody Gyro Jerk.std.Z : num 0.5315 Na<br/>N0.1364-0.0209 Na<br/>N $\dots$
- \$ tBodyGyroJerkMag.mean(): num NaN NaN 0.5607 0.1 0.0824 ...

- $\$ tBody Gyro Jerk Mag.std<br/>() : num NaN NaN 0.429 0.173 -0.105 . . .
- tBodyGyroMag.mean(): num NaN NaN 0.131 0.194 0.545 ...
- tBodyGyroMag.std(): num NaN NaN 0.662 0.133 0.579 ...
- $\$ t<br/>Gravity Acc.mean.X : num 0.434 NaN NaN NaN 0.213 . . .
- $\$ t<br/>Gravity Acc.mean.Y : num 0.0664 NaN NaN NaN 0.2377 . . .
- $\$ t<br/>Gravity Acc.mean.Z : num 0.405 NaN NaN NaN 0.183 . . .
- $\$ t<br/>Gravity Acc.std.X : num -0.1436 NaN NaN NaN 0.0704 . . .
- $\$ t<br/>Gravity Acc.std.Y : num -0.6912 -0.27 Na<br/>N NaN 0.0305 . . .
- tGravityAccMag.mean() : num 0.0991 NaN 0.1205 0.2048 NaN ...
- \$ tGravityAccMag.std(): num NaN NaN 0.351 0.225 NaN ..