

HW3_neuro

October 14, 2020

1 Homework 3

1.0.1 Yanis Tazi

```
[33]: import numpy as np
import matplotlib.pyplot as plt
import matplotlib.ticker as tck
import math
plt.rcParams["figure.figsize"] = (15,10)
```

1.0.2 To implement this model, the idea is to be in the steady state : $r() = F(I())$.

1.0.3 However, as discussed it is hard to calculate it directly . One reason is that this differential equation is a partial differential equation because it depends on t but also on θ . Therefore , we need to approximate numerically the steady state, the trick is to iterating over a long time period so that it converges to the steady state.

1.0.4 We also need to create different classes to include : connectivity ring with a function that will create the recurrent connectivities J_{ij} and a class dynamics to iterate over time . We also need an initial vector of r taking into consideration the initial. conditions $r(i, t = 0) = a \cos(2(i - 0))$ for all i values, here we will chose 50 ranging from $-\frac{\pi}{2}$ to $\frac{\pi}{2}$. This ring created is considered as the coding space , not the physical space. and the angles ' from the connectivity are considered to be the angle of activity of presynaptic current.

2 Question 1 : Use $J_0 = -0.5$, $J_2 = 1$, $A = 40$ Hz and $\epsilon = 0.1$.

```
[34]: def h(theta,A,c,eps,theta_cue=0):
    return (A*c*(1-eps+eps*math.cos(2*(theta-theta_cue))))
```

```
[35]: def numerical_integrations(N=50,a=2,theta_0=0,A=40,c=0.1,eps=0.1,J_0=-0.
    ↪5,J_2=1,d_t=0.0005,T=100,tau=10,theta_cue=0):

    thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
    r = [a*math.cos(2*(theta-theta_0)) for theta in thetas]
    for t in np.arange(0,T, d_t):
        #print(r)
```

```

        H = [h(theta=theta,A=A,c=c,eps=eps,theta_cue=theta_cue) for theta in
        ↪ thetas]
        sum_I = [(1/(N-1)) * np.sum([(J_0+J_2*math.
        ↪ cos(2*(thetas[i]-thetas[j]))*r[j])
                                for j in range(N)]) for i in range(N)]
        I = [a + b for a, b in zip(H, sum_I)]
        I = [i if i>0 else 0 for i in I]
        r = r + (d_t/tau)*(np.negative(r)+I)
    return (r)

```

3 a) $\theta_{cue} = 0$

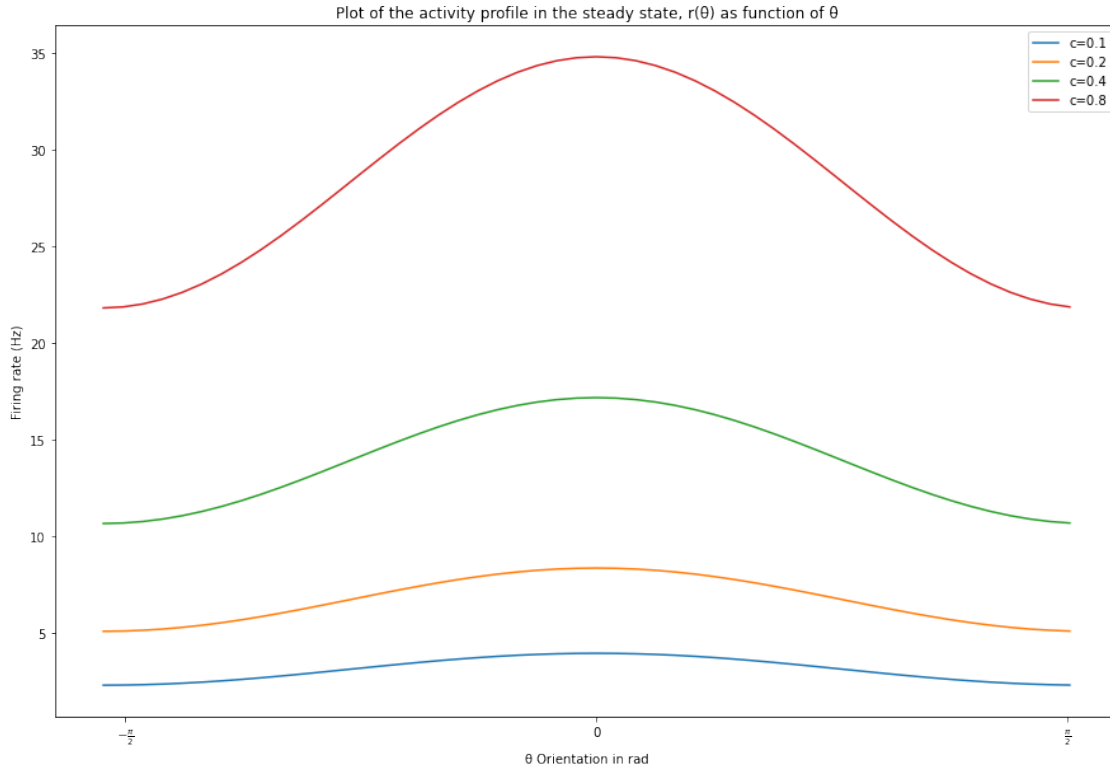
$a=2, \theta_0 = 0$

```

[36]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
        ↪ range(0,N)],numerical_integrations(N=N,a=2,theta_0=0,c=0.1,d_t=0.
        ↪ 05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
        ↪ range(0,N)],numerical_integrations(N=N,a=2,theta_0=0,c=0.2,d_t=0.
        ↪ 05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
        ↪ range(0,N)],numerical_integrations(N=N,a=2,theta_0=0,c=0.4,d_t=0.
        ↪ 05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
        ↪ range(0,N)],numerical_integrations(N=N,a=2,theta_0=0,c=0.8,d_t=0.
        ↪ 05,T=100),label='c=0.8')

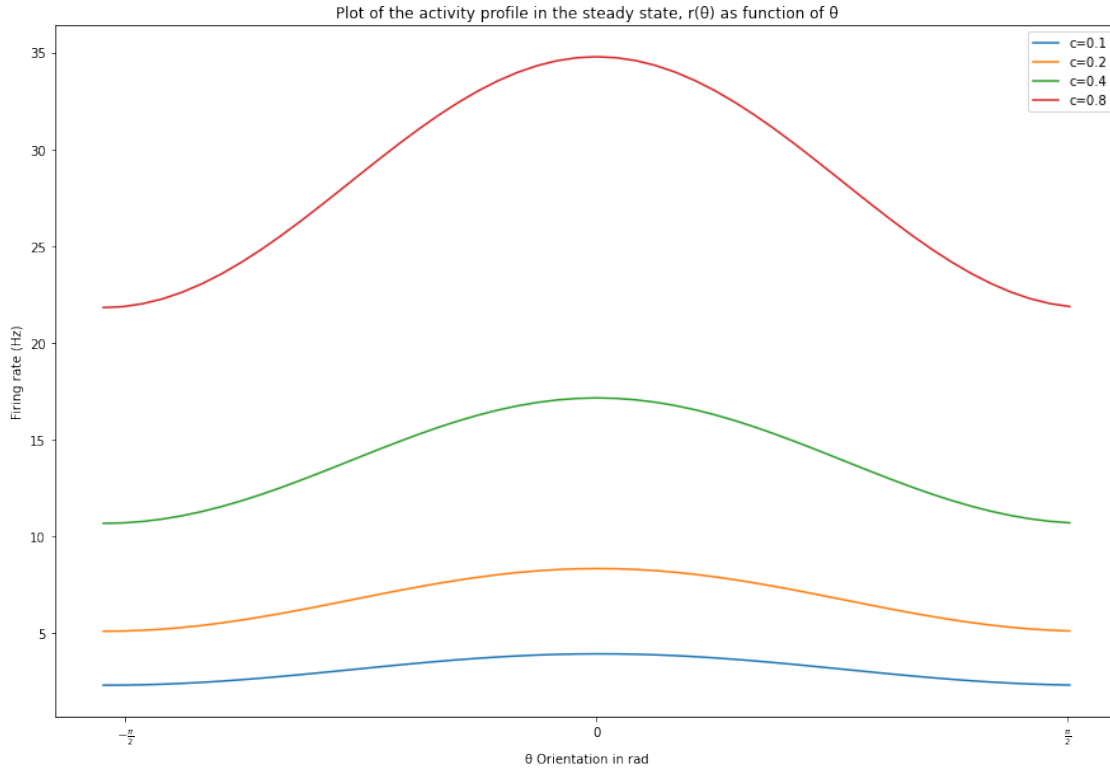
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
        ↪ of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



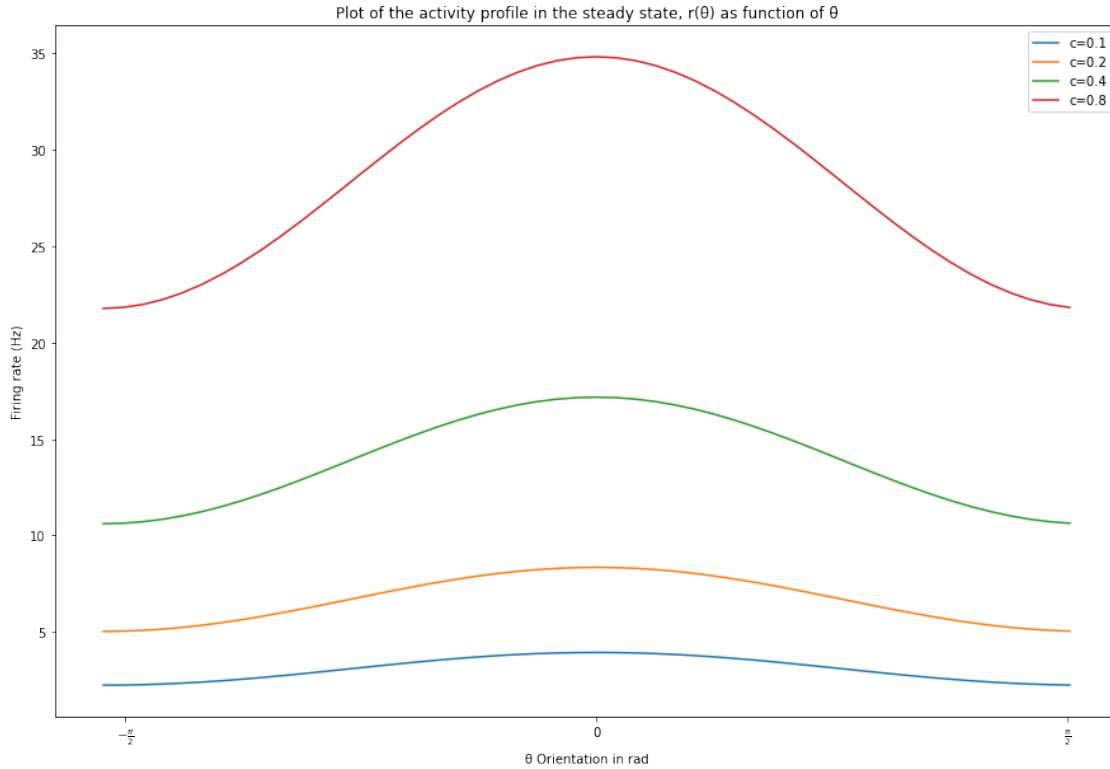
$a=2, \theta_0 = \frac{\pi}{4}$

```
[37]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=2,theta_0=math.pi/4,c=0.1,d_t=0.
    05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=2,theta_0=math.pi/4,c=0.2,d_t=0.
    05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=2,theta_0=math.pi/4,c=0.4,d_t=0.
    05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=2,theta_0=math.pi/4,c=0.8,d_t=0.
    05,T=100),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



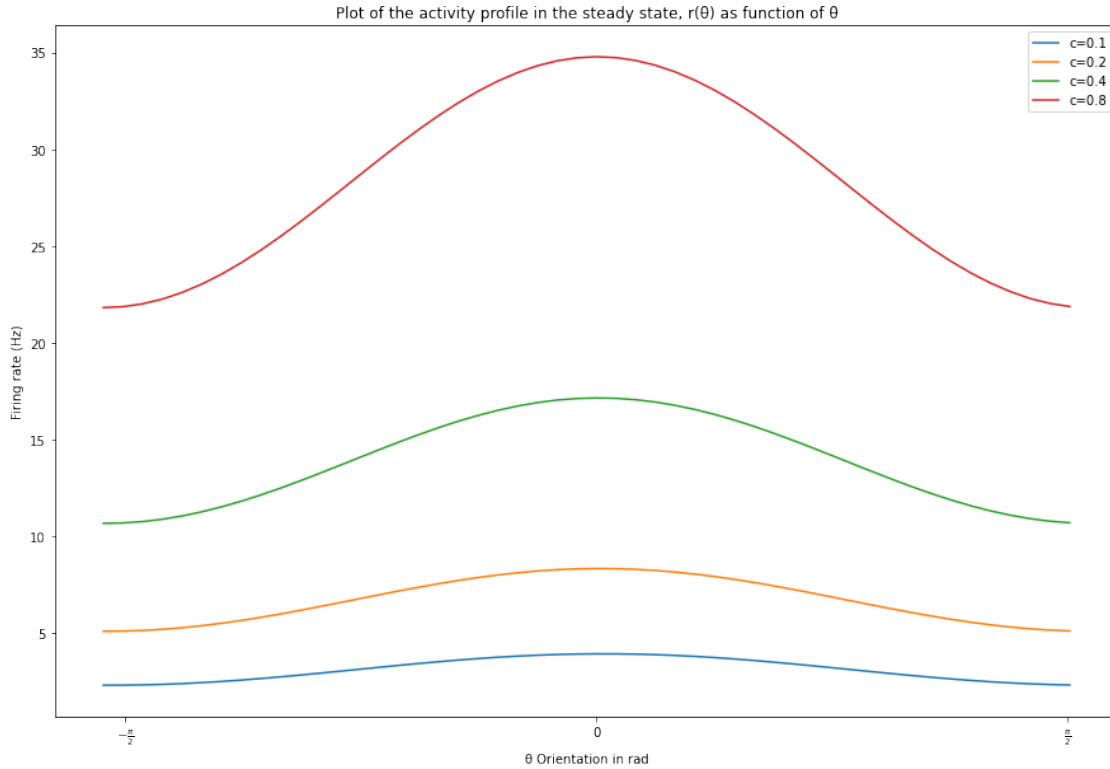
$a=5, \theta_0 = 0$

```
[38]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=0,c=0.1,d_t=0.
    05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=0,c=0.2,d_t=0.
    05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=0,c=0.4,d_t=0.
    05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=0,c=0.8,d_t=0.
    05,T=100),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



$a=5, \theta_0 = \frac{\pi}{4}$

```
[39]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=math.pi/4,c=0.1,d_t=0.
    05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=math.pi/4,c=0.2,d_t=0.
    05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=math.pi/4,c=0.4,d_t=0.
    05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations(N=N,a=5,theta_0=math.pi/4,c=0.8,d_t=0.
    05,T=100),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



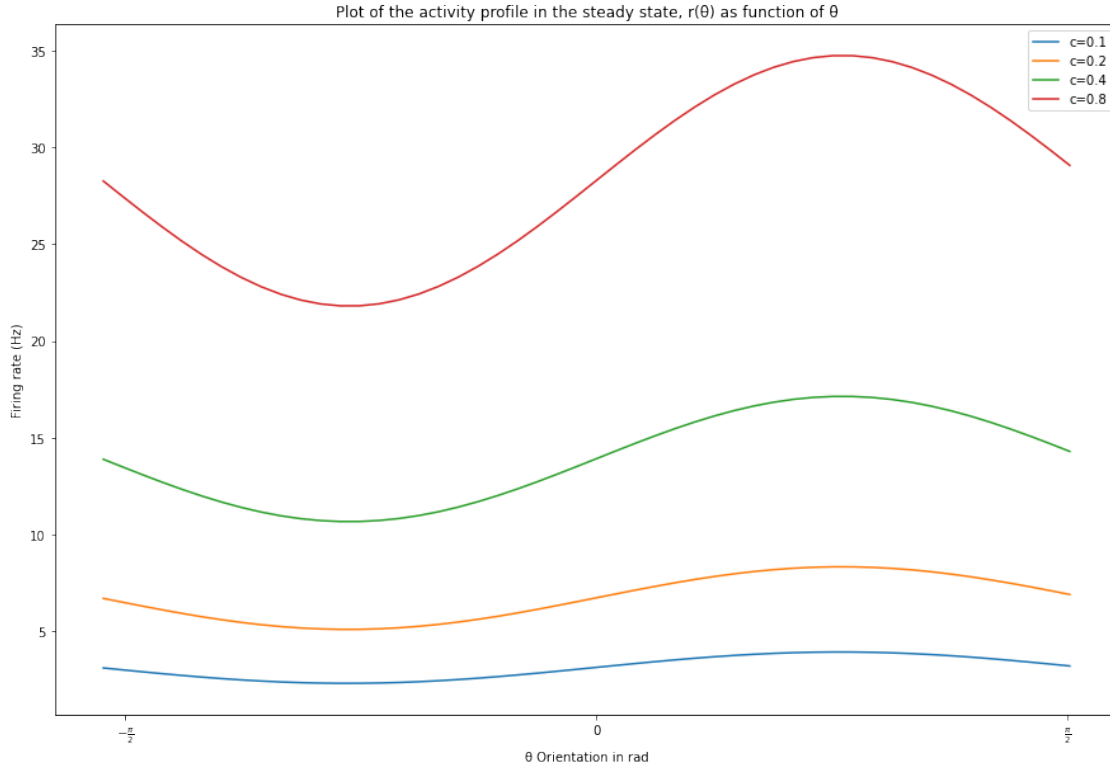
4 b) $\theta_{cue} = \frac{\pi}{4}$

$a=2, \theta_0 = 0$

```
[40]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=0,c=0.
→1,d_t=0.05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=0,c=0.
→2,d_t=0.05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=0,c=0.
→4,d_t=0.05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=0,c=0.
→8,d_t=0.05,T=100),label='c=0.8')

plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
```

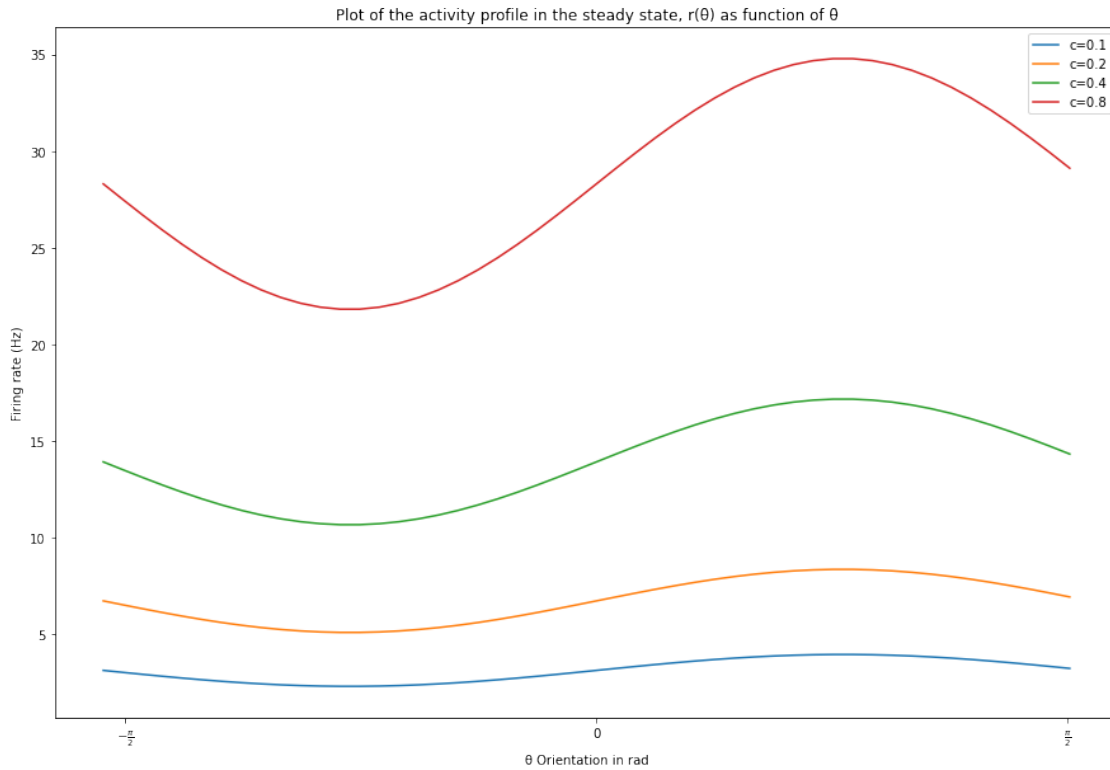
```
plt.title("Plot of the activity profile in the steady state,  $r(\theta)$  as function of  $\theta$ ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



$a=2, \theta_0 = \frac{\pi}{4}$

```
[41]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=math.
pi/4,c=0.1,d_t=0.05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=math.
pi/4,c=0.2,d_t=0.05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=math.
pi/4,c=0.4,d_t=0.05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=2,theta_0=math.
pi/4,c=0.8,d_t=0.05,T=100),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
```

```
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of  $\theta$ ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



$a=5$, $\theta_0 = 0$

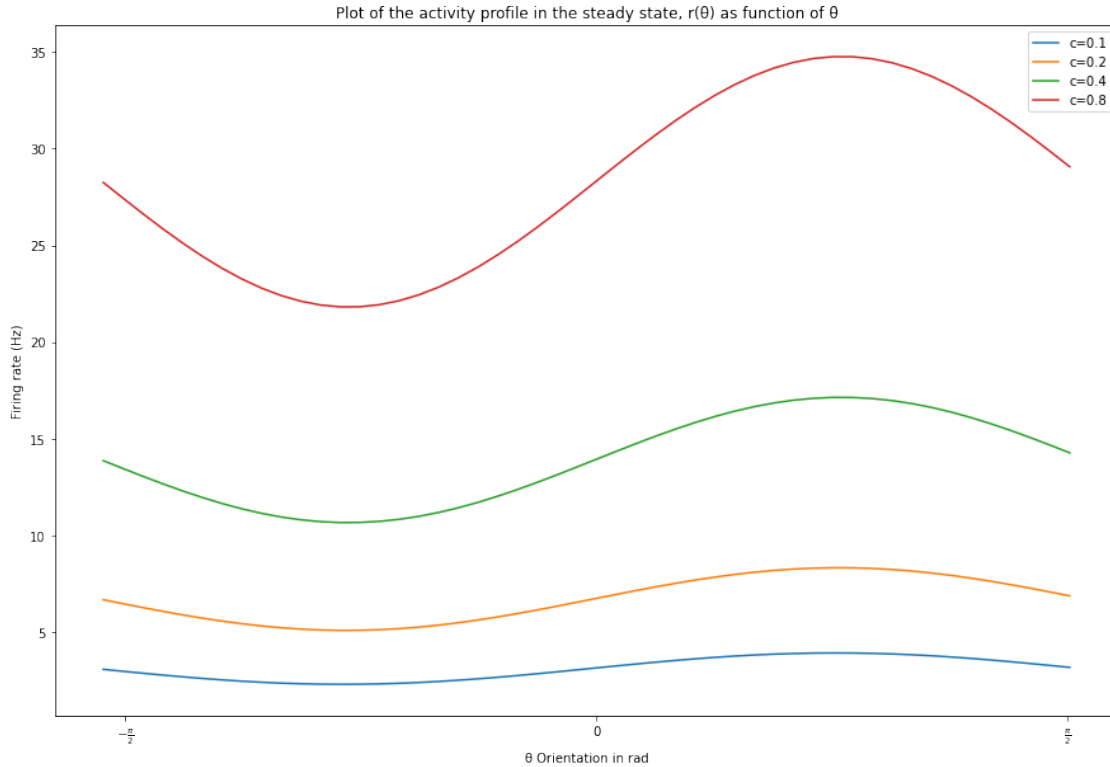
```
[42]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=0,c=0.1,d_t=0.05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=0,c=0.2,d_t=0.05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=0,c=0.4,d_t=0.05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=0,c=0.8,d_t=0.05,T=100),label='c=0.8')
plt.xlabel(' Orientation in rad')
```



```

plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of  $\theta$ ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



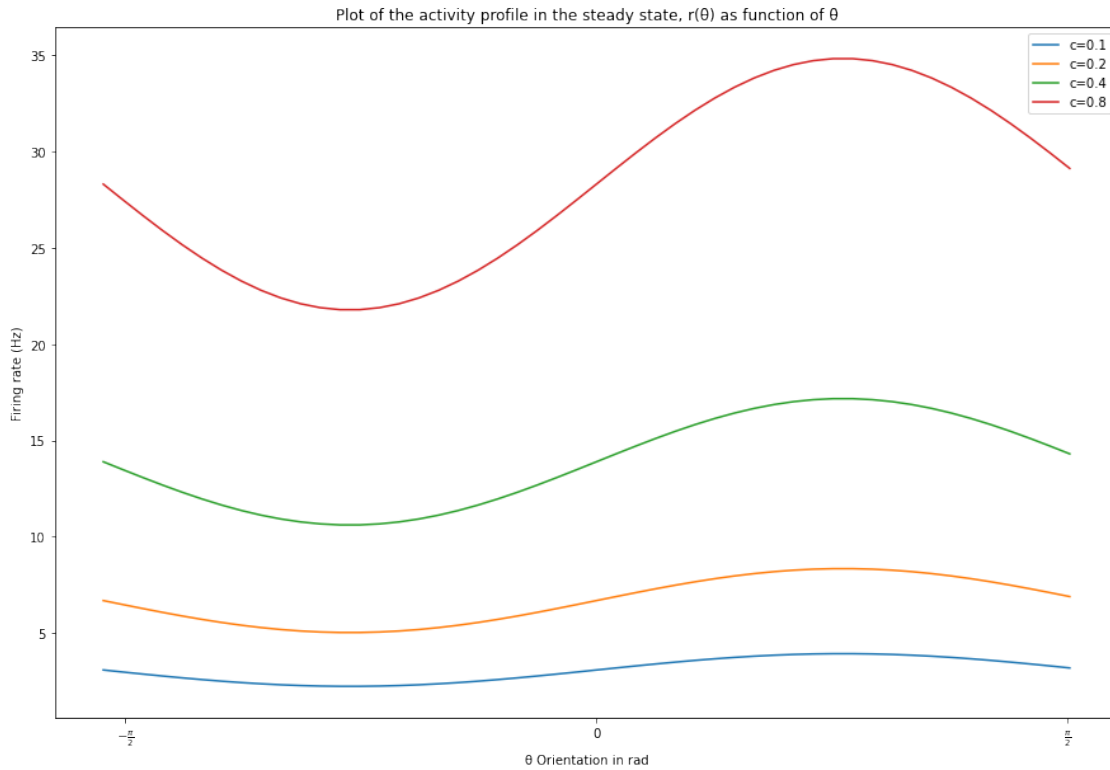
$a=5$, $\theta_0 = \frac{\pi}{4}$

```

[43]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=math.
→pi/4,c=0.1,d_t=0.05,T=100),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=math.
→pi/4,c=0.2,d_t=0.05,T=100),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=math.
→pi/4,c=0.4,d_t=0.05,T=100),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
→range(0,N)],numerical_integrations(theta_cue=math.pi/4,N=N,a=5,theta_0=math.
→pi/4,c=0.8,d_t=0.05,T=100),label='c=0.8')

```

```
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



4.0.1 The parameter c also plays an important role here as it expresses the contrast and increasing c will increase linearly the thalamic input ,highlights the relative luminescence and increase the firing rate .

5 Single neuron : $-\frac{\pi}{2}$

```
[45]: selected_neuron = 0
r_cues = []
r_cues1 = []
r_cues2 = []
r_cues3 = []
N=50
for cue in [(math.pi/N)*i - math.pi/2 for i in range(0,N)]:
```

```

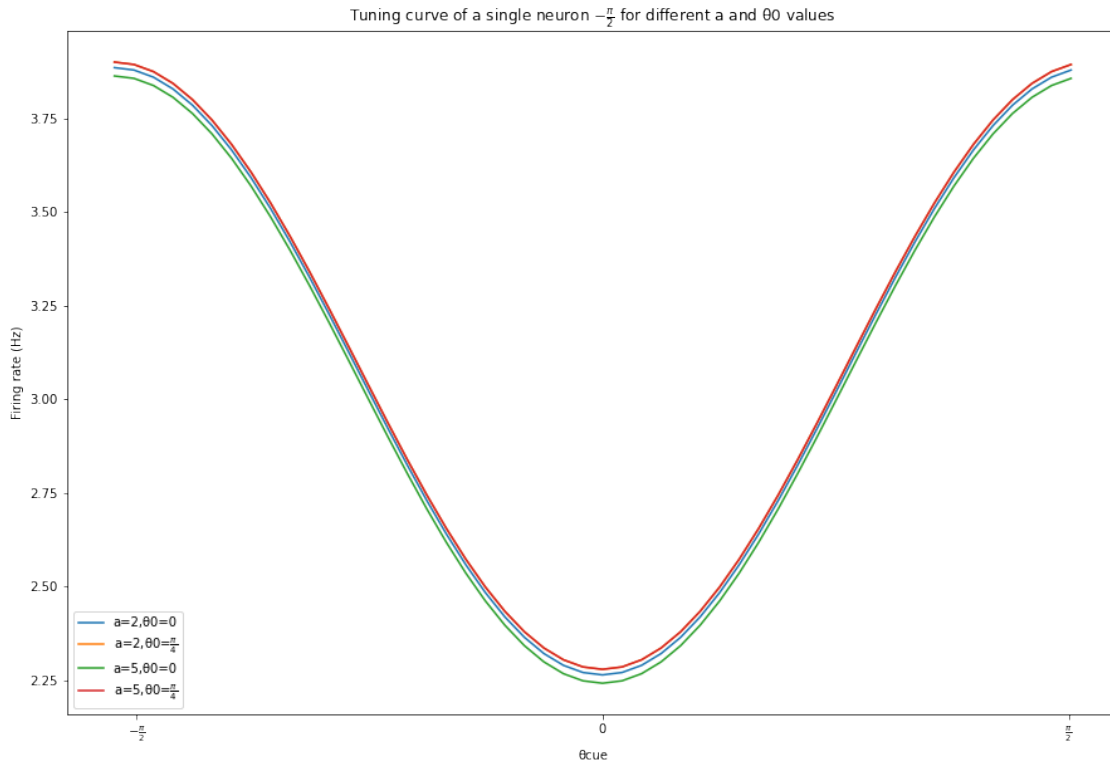
    r_cues.append(numerical_integrations(N=N,a=2,theta_0=0,c=0.1,d_t=0.
↪05,T=100,theta_cue=cue))
    r_cues1.append(numerical_integrations(N=N,a=2,theta_0=math.pi/4,c=0.1,d_t=0.
↪05,T=100,theta_cue=cue))
    r_cues2.append(numerical_integrations(N=N,a=5,theta_0=0,c=0.1,d_t=0.
↪05,T=100,theta_cue=cue))
    r_cues3.append(numerical_integrations(N=N,a=5,theta_0=math.pi/4,c=0.1,d_t=0.
↪05,T=100,theta_cue=cue))

```

```

[46]: plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)], [r_cues[i][0] for i_
↪in range(50)], label='a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)], [r_cues1[i][0] for i_
↪in range(50)],
        label='a=2, 0='+r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)], [r_cues2[i][0] for i_
↪in range(50)], label='a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)], [r_cues3[i][0] for i_
↪in range(50)],
        label='a=5, 0='+r'$\frac{\pi}{4}$')
plt.legend()
plt.title("Tuning curve of a single neuron " + r'$-\frac{\pi}{2}$' + " for_
↪different a and 0 values ")
plt.xlabel(" cue")
plt.ylabel("Firing rate (Hz)")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



5.0.1 No differences for the tuning curves of a single neuron for different a and θ_0 values.

6 Question 2 : Use $J_0 = -7.3$, $J_2 = 11$, $A = 40$ Hz and $\epsilon = 0.1$.

$a=2$, $\theta_0 = 0$

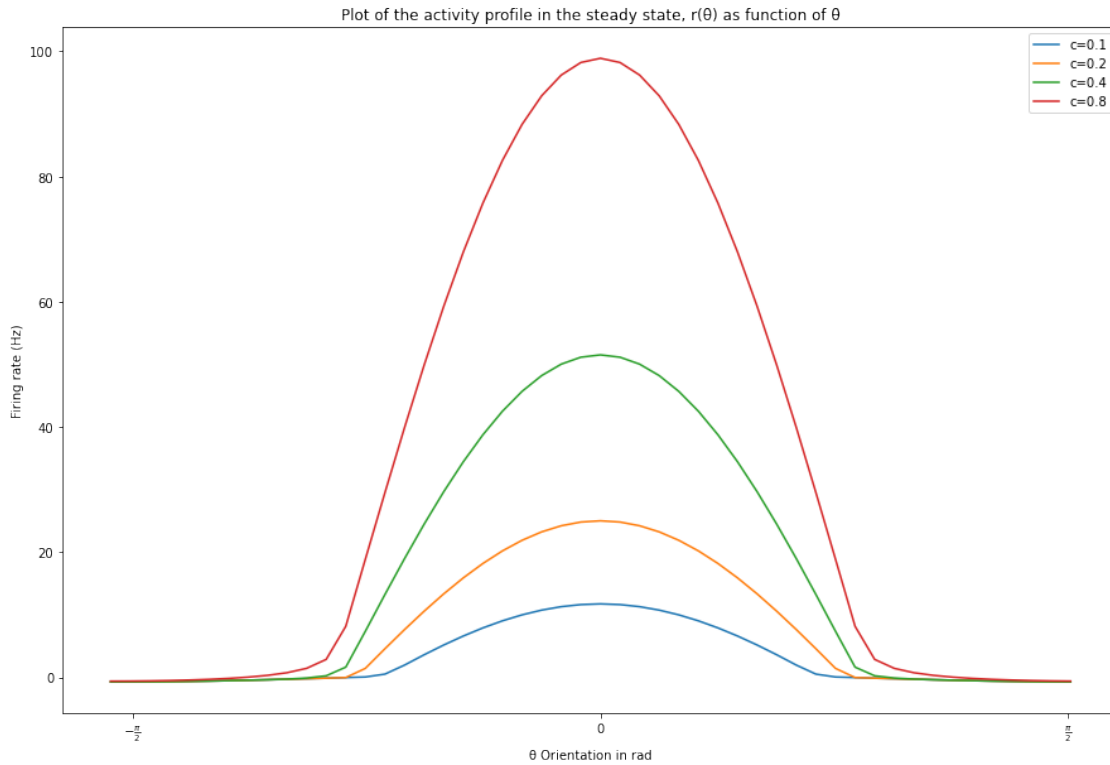
```
[47]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.1,d_t=0.
         ↪005,T=10),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.2,d_t=0.
         ↪005,T=10),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.4,d_t=0.
         ↪005,T=10),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.8,d_t=0.
         ↪005,T=10),label='c=0.8')

plt.xlabel(' Orientation in rad')
```

```

plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of  $\theta$ ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



$a=2$, $\theta_0 = \frac{\pi}{4}$

```

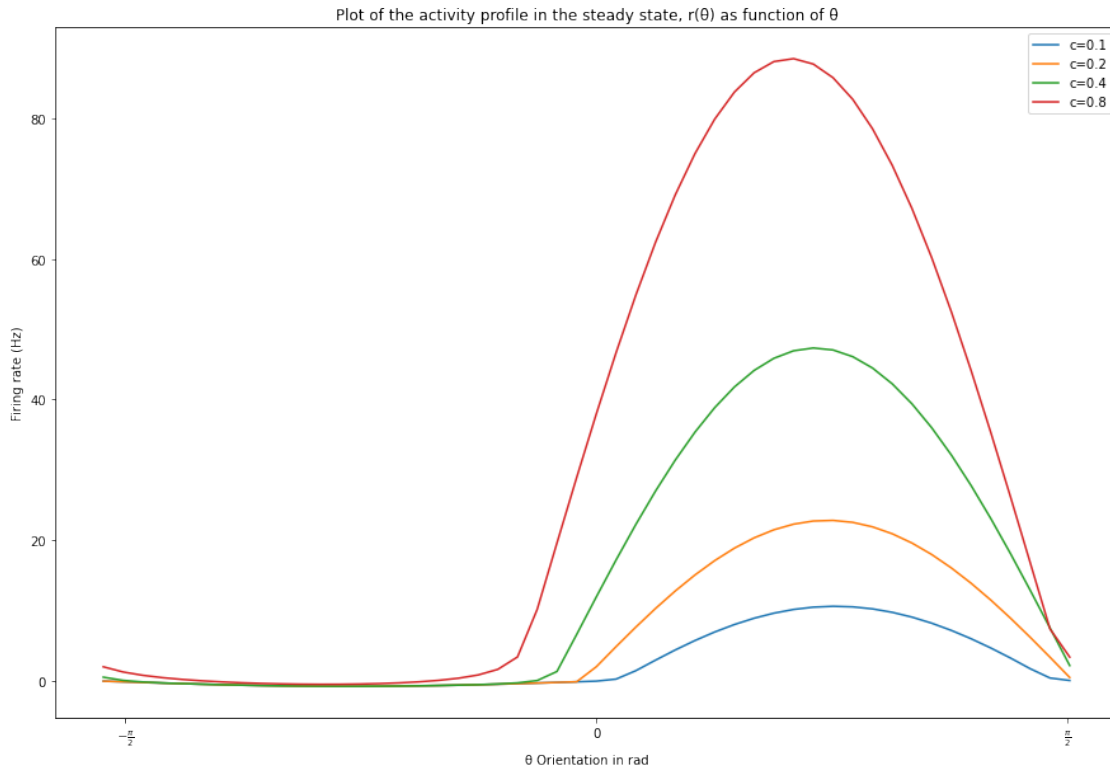
[48]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/4,c=0.
         ↪1,d_t=0.005,T=10),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/4,c=0.
         ↪2,d_t=0.005,T=10),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/4,c=0.
         ↪4,d_t=0.005,T=10),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/4,c=0.
         ↪8,d_t=0.005,T=10),label='c=0.8')

```

```

plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r(\theta)$  as function of  $\theta$ ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



$a=5$, $\theta_0 = 0$

```

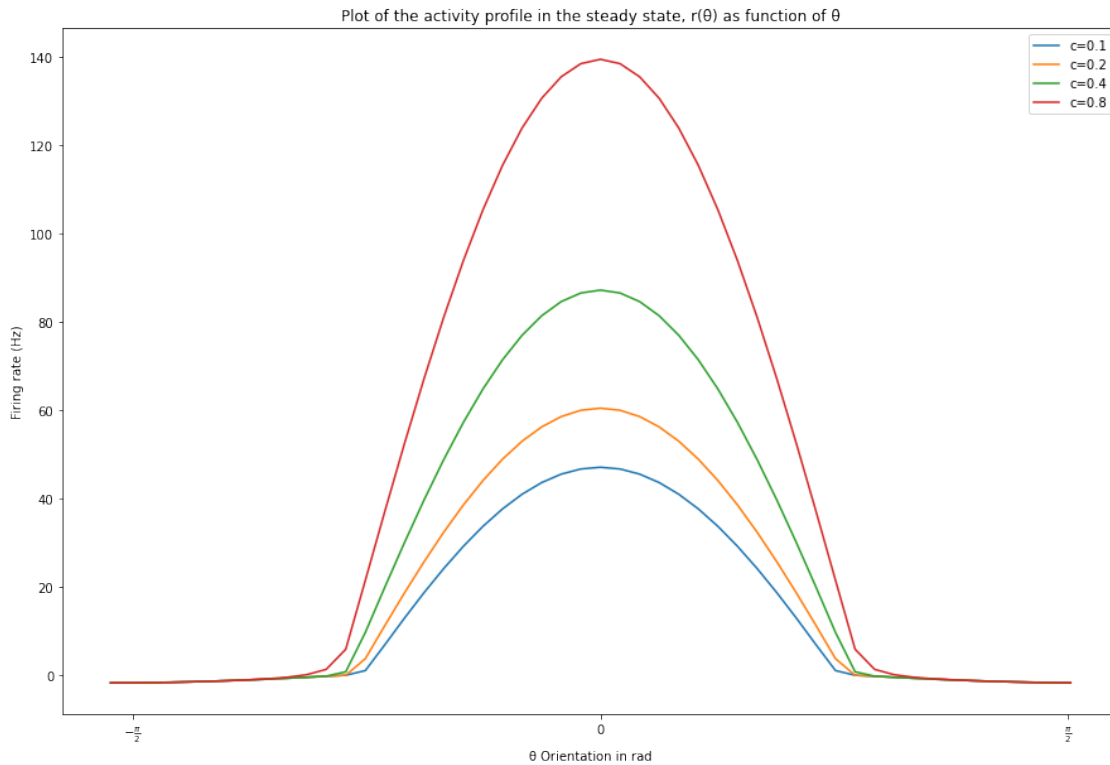
[49]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.1,d_t=0.
         ↳005,T=10),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.2,d_t=0.
         ↳005,T=10),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.4,d_t=0.
         ↳005,T=10),label='c=0.4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],

```

```

        numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.8,d_t=0.
↪005,T=10),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function_
↪of ")
plt.xticks([-1.5,0,1.5], [r'\frac{\pi}{2}', '0', r'\frac{\pi}{2}'])
plt.show()

```



$a=5$, $\theta_0 = \frac{\pi}{4}$

```

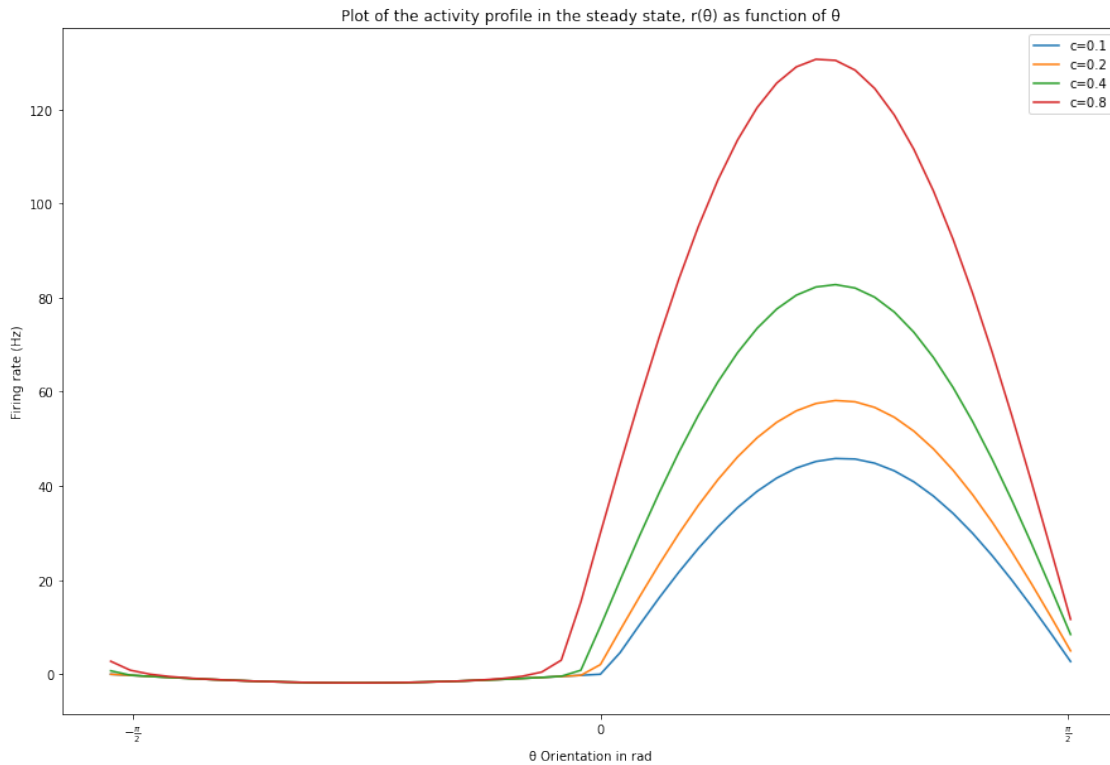
[50]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
        numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/4,c=0.
↪1,d_t=0.005,T=10),label='c=0.1')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
        numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/4,c=0.
↪2,d_t=0.005,T=10),label='c=0.2')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
        numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/4,c=0.
↪4,d_t=0.005,T=10),label='c=0.4')

```

```

plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/4,c=0.
         ↪8,d_t=0.005,T=10),label='c=0.8')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function_
         ↪of ")
plt.xticks([-1.5,0,1.5], [r'${-\frac{\pi}{2}}$', '0', r'${\frac{\pi}{2}}$'])
plt.show()

```



6.0.1 J_2 controls the strength of excitation while J_0 accounts for the recurrent inhibition.

6.0.2 We see that width of the model remains pretty much the same while c agains control the firing rate amplitude. Those amplitudes are much stronger than earlier because the parameter space has changed and therefore the current phase too.

7 Question 3 : Use $J_0 = -7.3$, $J_2 = 11$, $A = 40$ Hz and $\epsilon = 0.1$.

8 $\theta_{cue} = 0$

```
[51]: def h_noise(theta,A,c,eps,sigma=3,theta_cue=0):
        np.random.seed(17)
        return (A*c*(1-eps+eps*math.cos(2*(theta-theta_cue)))+sigma*np.random.
        ↪normal(0,1))

[52]: def numerical_integrations_noise(N=50,a=2,theta_0=0,A=40,c=0.1,eps=0.1,J_0=-0.
        ↪5,J_2=1,d_t=0.01,T=300,tau=10,sigma=3,theta_cue=0):

        thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
        r = [a*math.cos(2*(theta-theta_0)) for theta in thetas]
        for t in np.arange(0,T, d_t):
            #print(r)
            H = [h_noise(theta=theta,A=A,c=c,eps=eps,theta_cue=theta_cue) for theta_
            ↪in thetas]
            sum_I = [(1/(N-1)) * np.sum([(J_0+J_2*math.
            ↪cos(2*(thetas[i]-thetas[j]))*r[j])
                                for j in range(N)]) for i in range(N)]
            I = [a + b for a, b in zip(H, sum_I)]
            I = [i if i>0 else 0 for i in I]
            r = r + (d_t/tau)*(np.negative(r)+I)
        return (r)
```

9 Like question 1 : Use $J_0 = -0.5$, $J_2 = 1$, $A = 40$ Hz and $\epsilon = 0.1$.

10 $r()$ as function of

```
[53]: N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in_
        ↪range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=0,c=0.1,d_t=0.
        ↪05,T=100),label='c=0.1,a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in_
        ↪range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=0,c=0.2,d_t=0.
        ↪05,T=100),label='c=0.2,a=2, 0=0')
```

```

plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=0,c=0.4,d_t=0.
    05,T=100),label='c=0.4,a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=0,c=0.8,d_t=0.
    05,T=100),label='c=0.8,a=2, 0=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=math.pi/4,c=0.
    1,d_t=0.05,T=100),label='c=0.1,a=2, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=math.pi/4,c=0.
    2,d_t=0.05,T=100),label='c=0.2,a=2, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=math.pi/4,c=0.
    4,d_t=0.05,T=100),label='c=0.4,a=2, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=2,theta_0=math.pi/4,c=0.
    8,d_t=0.05,T=100),label='c=0.8,a=2, 0=pi/4')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=0,c=0.1,d_t=0.
    05,T=100),label='c=0.1,a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=0,c=0.2,d_t=0.
    05,T=100),label='c=0.2,a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=0,c=0.4,d_t=0.
    05,T=100),label='c=0.4,a=5, 0=0')

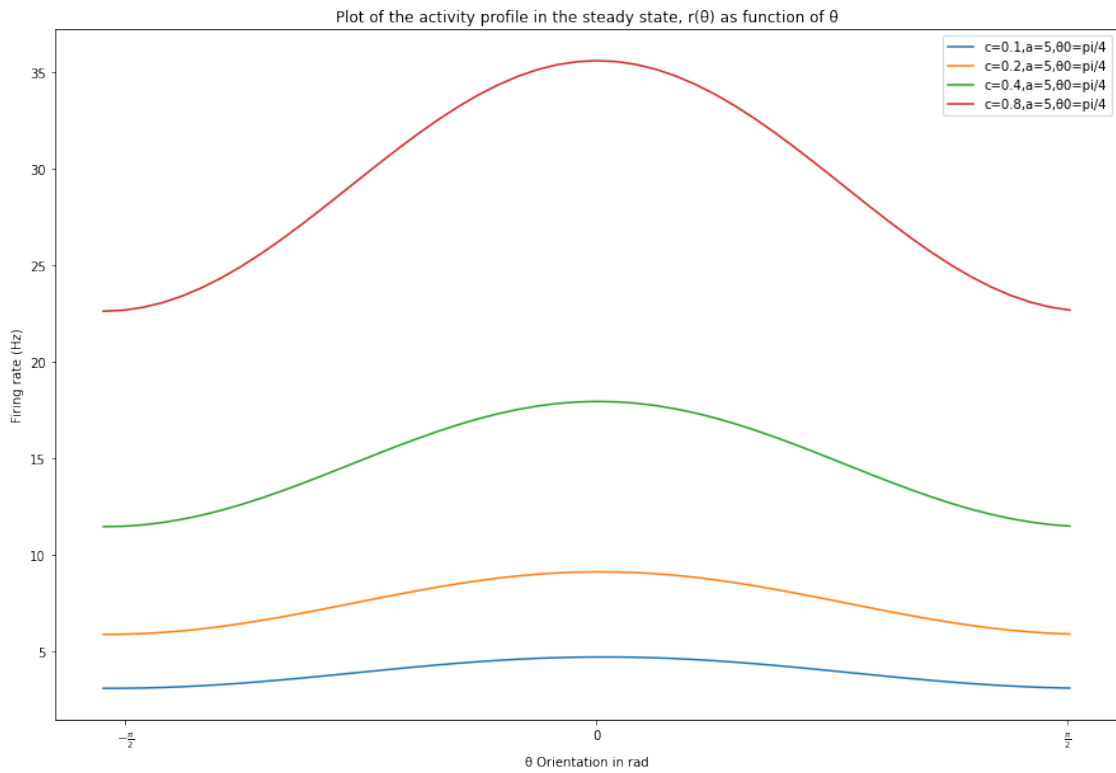
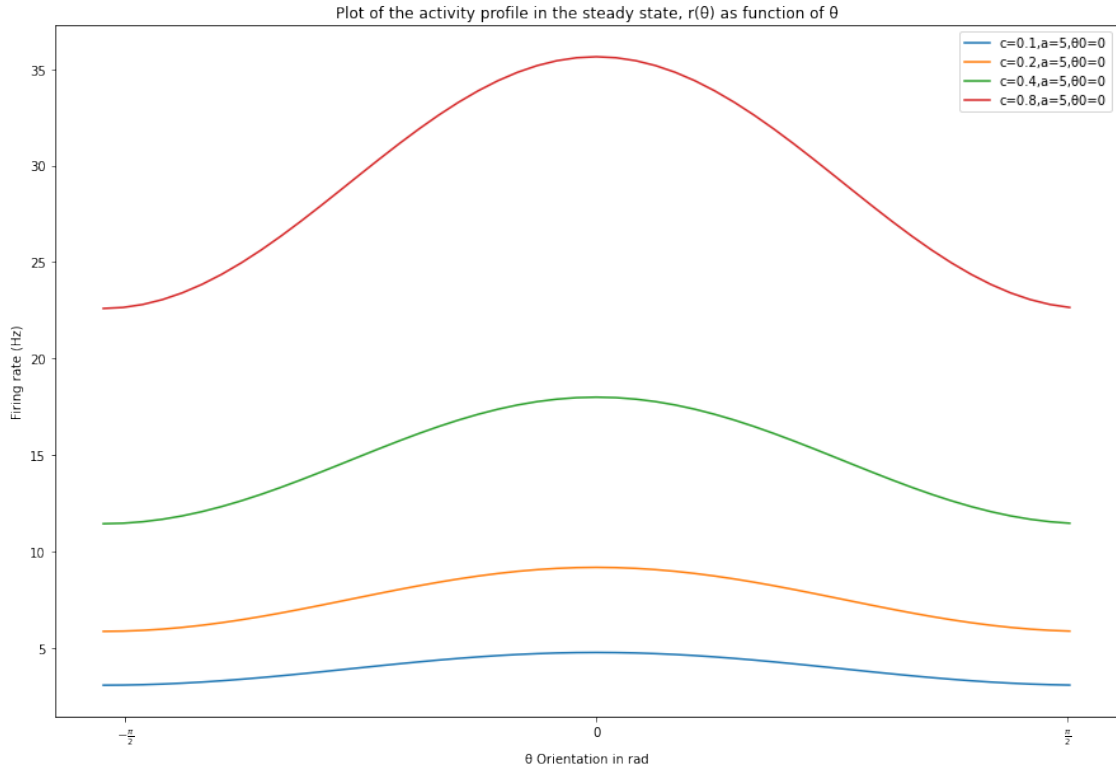
```

```

plt.plot([(math.pi/N)*i - math.pi/2 for i in
    ↪range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=0,c=0.8,d_t=0.
    ↪05,T=100),label='c=0.8,a=5, 0=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    ↪of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

N=50
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    ↪range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=math.pi/4,c=0.
    ↪1,d_t=0.05,T=100),label='c=0.1,a=5, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    ↪range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=math.pi/4,c=0.
    ↪2,d_t=0.05,T=100),label='c=0.2,a=5, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    ↪range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=math.pi/4,c=0.
    ↪4,d_t=0.05,T=100),label='c=0.4,a=5, 0=pi/4')
plt.plot([(math.pi/N)*i - math.pi/2 for i in
    ↪range(0,N)],numerical_integrations_noise(N=N,a=5,theta_0=math.pi/4,c=0.
    ↪8,d_t=0.05,T=100),label='c=0.8,a=5, 0=pi/4')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function
    ↪of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



11 Like question 2 : Use $J_0 = -7.3$, $J_2 = 11$, $A = 40$ Hz and $\epsilon = 0.1$.

12 $r()$ as function of

```
[54]: N=50

plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.
         ↪1,d_t=0.005,T=10),label='c=0.1,a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.
         ↪2,d_t=0.005,T=10),label='c=0.2,a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.
         ↪4,d_t=0.005,T=10),label='c=0.4,a=2, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=0,c=0.
         ↪8,d_t=0.005,T=10),label='c=0.8,a=2, 0=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function_
         ↪of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/
         ↪4,c=0.1,d_t=0.005,T=10),
         label='c=0.1,a=2, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/
         ↪4,c=0.2,d_t=0.005,T=10),
         label='c=0.2,a=2, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/
         ↪4,c=0.4,d_t=0.005,T=10),
         label='c=0.4,a=2, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=2,theta_0=math.pi/
         ↪4,c=0.8,d_t=0.005,T=10),
         label='c=0.8,a=2, 0=' + r'$\frac{\pi}{4}$')
```

```

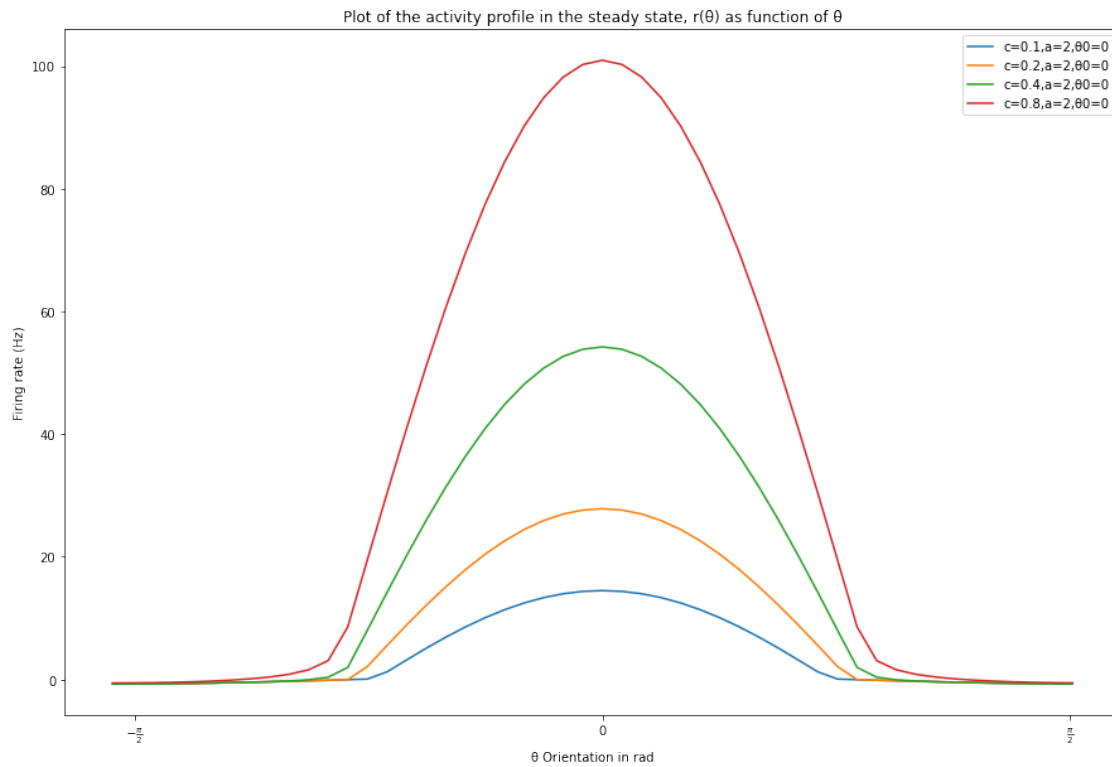
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

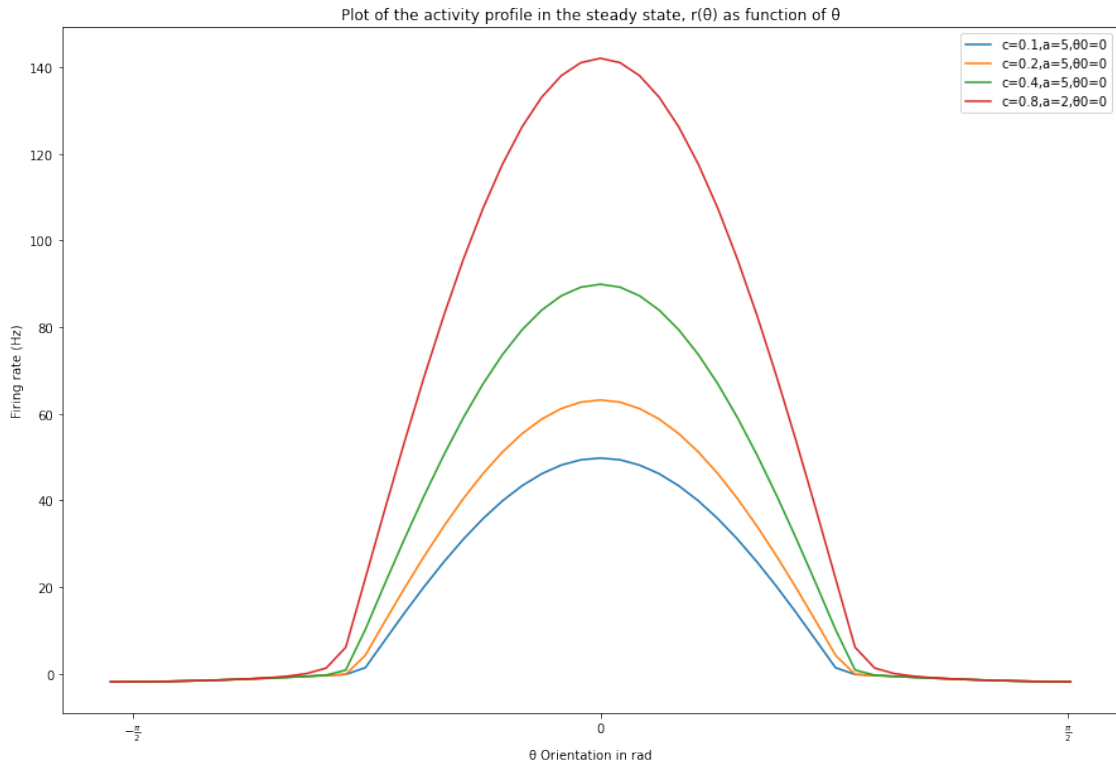
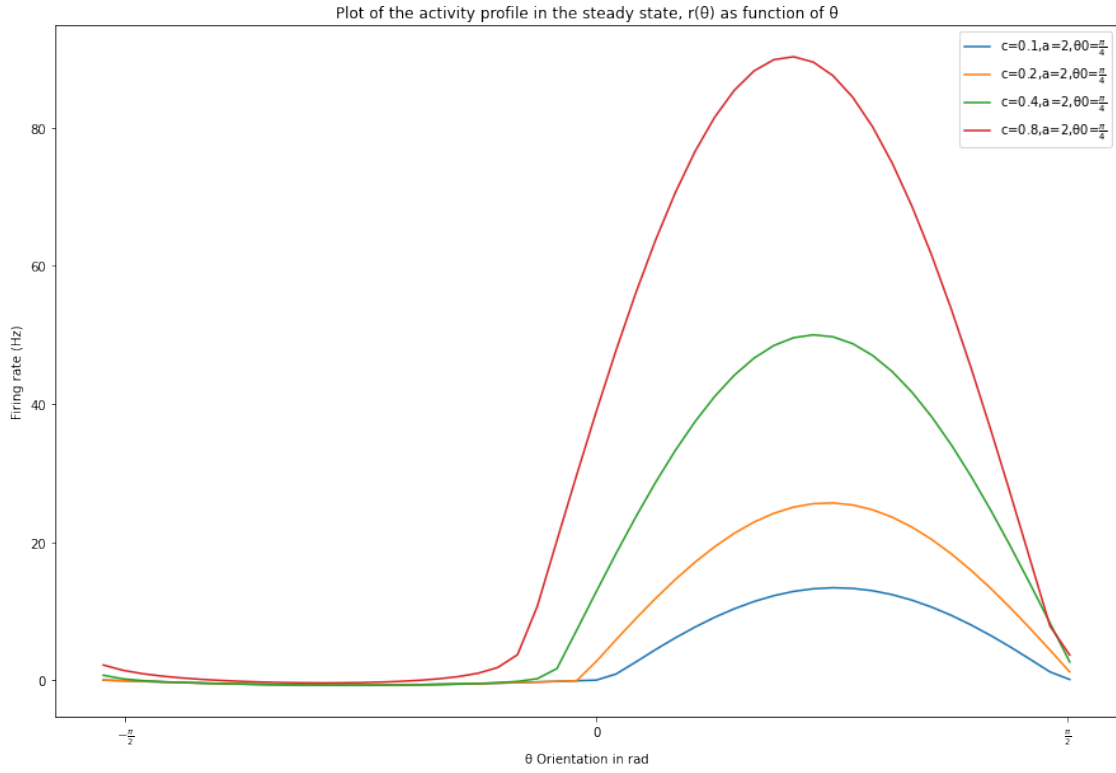
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.
         ↪1,d_t=0.005,T=10),label='c=0.1,a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.
         ↪2,d_t=0.005,T=10),label='c=0.2,a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.
         ↪4,d_t=0.005,T=10),label='c=0.4,a=5, 0=0')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=0,c=0.
         ↪8,d_t=0.005,T=10),label='c=0.8,a=2, 0=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r()$  as function of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

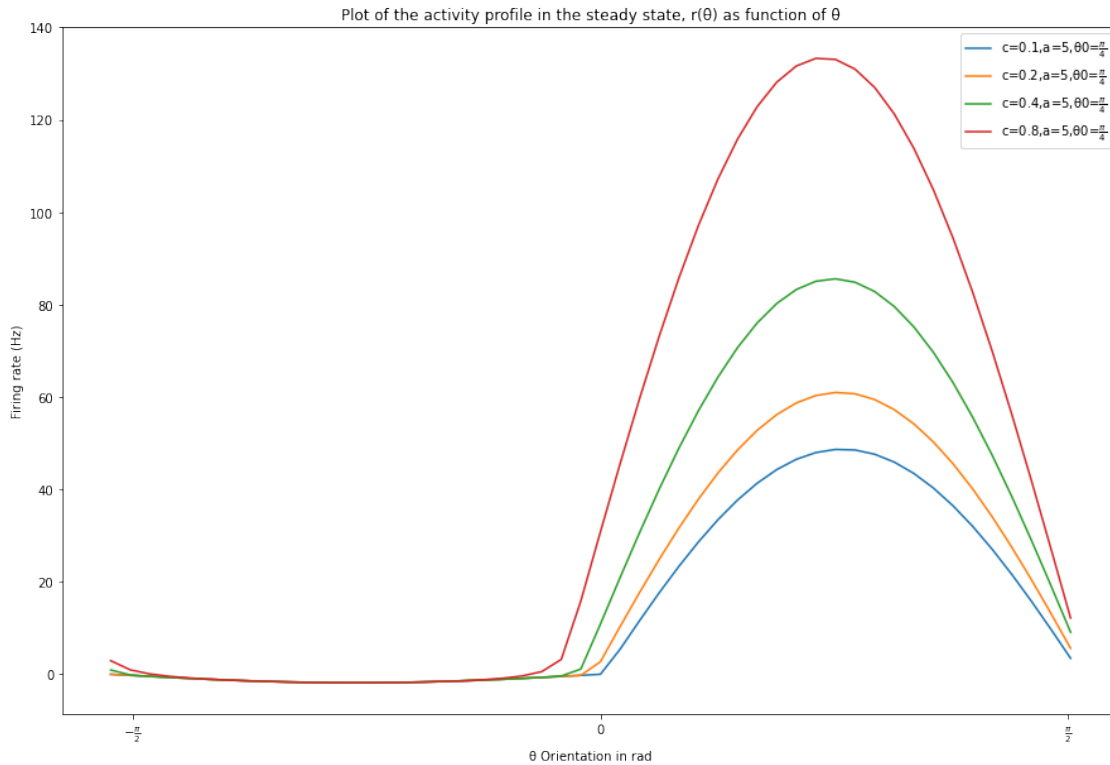
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/
         ↪4,c=0.1,d_t=0.005,T=10),
         label='c=0.1,a=5, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/
         ↪4,c=0.2,d_t=0.005,T=10)
         ,label='c=0.2,a=5, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/
         ↪4,c=0.4,d_t=0.005,T=10),
         label='c=0.4,a=5, 0=' + r'$\frac{\pi}{4}$')
plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
         numerical_integrations_noise(N=N,J_0=-7.3,J_2=11,a=5,theta_0=math.pi/
         ↪4,c=0.8,d_t=0.005,T=10),
         label='c=0.8,a=5, 0=' + r'$\frac{\pi}{4}$')
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')

```

```
plt.legend()
plt.title("Plot of the activity profile in the steady state,  $r(\theta)$  as function of  $\theta$ ")
plt.xticks([-1.5, 0, 1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```







13 $h(\)$ as function of

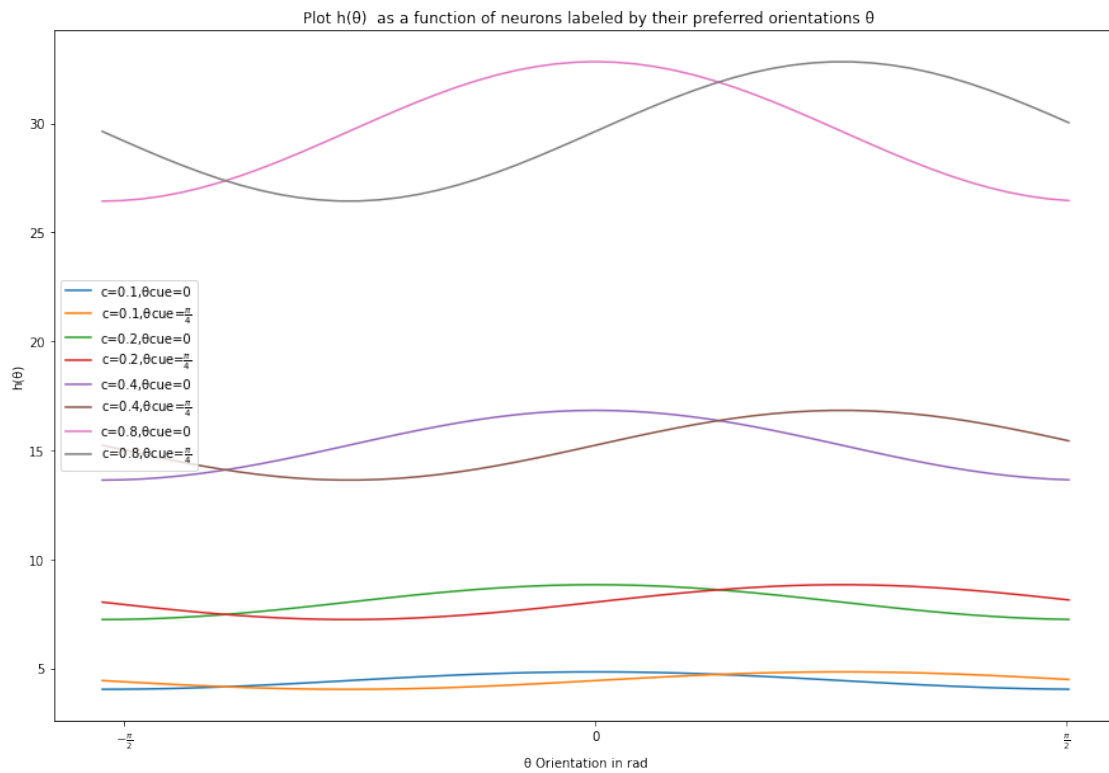
14 a) h with noise

```
[55]: thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
plt.plot(thetas, [h_noise(theta=theta, c=0.1, A=40, eps=0.1, theta_cue=0) for theta
    ↪ in thetas], label='c=0.1, cue=0')
plt.plot(thetas, [h_noise(theta=theta, c=0.1, A=40, eps=0.1, theta_cue=math.pi/4)
    ↪ for theta in thetas],
    label='c=0.1, cue=' + r'\frac{\pi}{4}')
plt.plot(thetas, [h_noise(theta=theta, c=0.2, A=40, eps=0.1, theta_cue=0) for theta
    ↪ in thetas], label='c=0.2, cue=0')
plt.plot(thetas, [h_noise(theta=theta, c=0.2, A=40, eps=0.1, theta_cue=math.pi/4)
    ↪ for theta in thetas],
    label='c=0.2, cue=' + r'\frac{\pi}{4}')
plt.plot(thetas, [h_noise(theta=theta, c=0.4, A=40, eps=0.1, theta_cue=0) for theta
    ↪ in thetas], label='c=0.4, cue=0')
plt.plot(thetas, [h_noise(theta=theta, c=0.4, A=40, eps=0.1, theta_cue=math.pi/4)
    ↪ for theta in thetas],
    label='c=0.4, cue=' + r'\frac{\pi}{4}')
```

```

plt.plot(thetas, [h_noise(theta=theta, c=0.8, A=40, eps=0.1, theta_cue=0) for theta in thetas], label='c=0.8, cue=0')
plt.plot(thetas, [h_noise(theta=theta, c=0.8, A=40, eps=0.1, theta_cue=math.pi/4) for theta in thetas],
        label='c=0.8, cue=' + r'\frac{\pi}{4}')
plt.legend()
plt.xlabel(' Orientation in rad')
plt.ylabel('h()')
plt.title(" Plot h() as a function of neurons labeled by their preferred orientations ")
plt.xticks([-1.5, 0, 1.5], [r'\frac{\pi}{2}', '0', r'\frac{\pi}{2}'])
plt.show()

```



15 b) h without noise

```

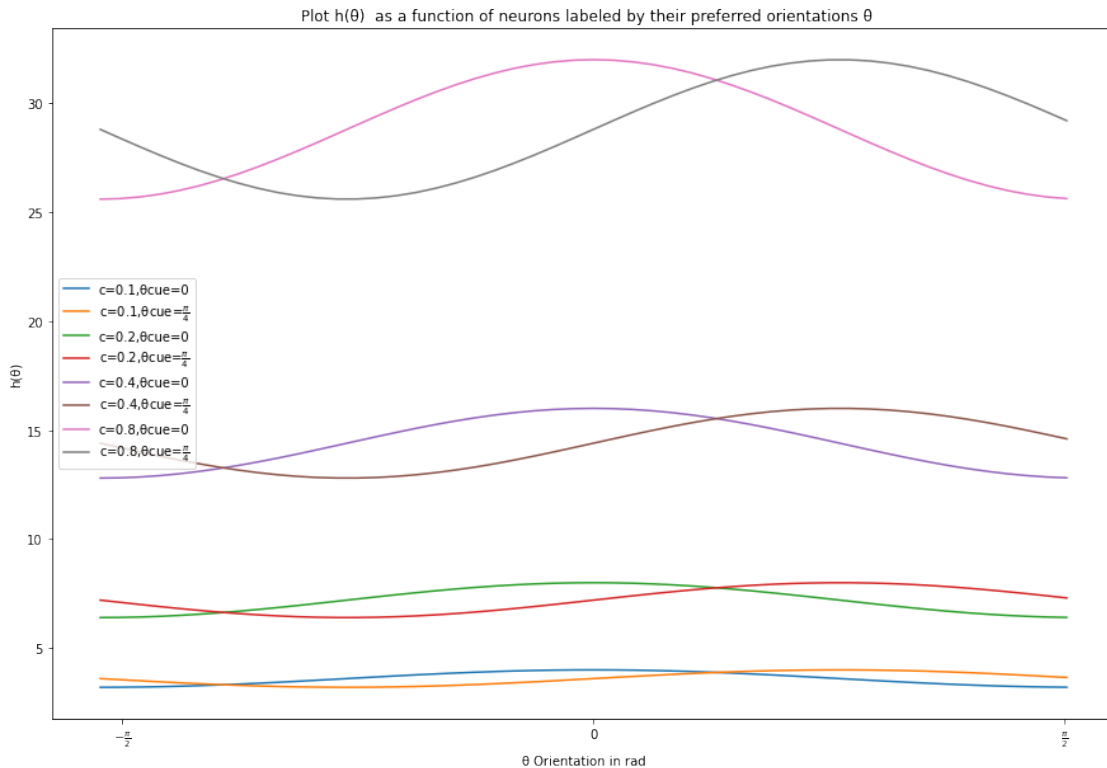
[60]: thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
plt.plot(thetas, [h(theta=theta, c=0.1, A=40, eps=0.1, theta_cue=0) for theta in thetas], label='c=0.1, cue=0')
plt.plot(thetas, [h(theta=theta, c=0.1, A=40, eps=0.1, theta_cue=math.pi/4) for theta in thetas],
        label='c=0.1, cue=' + r'\frac{\pi}{4}')

```

```

plt.plot(thetas, [h(theta=theta, c=0.2, A=40, eps=0.1, theta_cue=0) for theta in
↳ thetas], label='c=0.2, cue=0')
plt.plot(thetas, [h(theta=theta, c=0.2, A=40, eps=0.1, theta_cue=math.pi/4) for
↳ theta in thetas],
        label='c=0.2, cue=' + r'$\frac{\pi}{4}$')
plt.plot(thetas, [h(theta=theta, c=0.4, A=40, eps=0.1, theta_cue=0) for theta in
↳ thetas], label='c=0.4, cue=0')
plt.plot(thetas, [h(theta=theta, c=0.4, A=40, eps=0.1, theta_cue=math.pi/4) for
↳ theta in thetas],
        label='c=0.4, cue=' + r'$\frac{\pi}{4}$')
plt.plot(thetas, [h(theta=theta, c=0.8, A=40, eps=0.1, theta_cue=0) for theta in
↳ thetas], label='c=0.8, cue=0')
plt.plot(thetas, [h(theta=theta, c=0.8, A=40, eps=0.1, theta_cue=math.pi/4) for
↳ theta in thetas],
        label='c=0.8, cue=' + r'$\frac{\pi}{4}$')
plt.legend()
plt.xlabel(' Orientation in rad')
plt.ylabel('h()')
plt.title(" Plot h() as a function of neurons labeled by their preferred
↳ orientations ")
plt.xticks([-1.5, 0, 1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()

```



16 Question 4 : Use $\epsilon = 0$, $J_0 = -1$ and $J_2 = 1, 1.5, 2.5, 4.5$

16.0.1 This parameter ϵ explains how well h is tuned . The greater ϵ the better the thalamic input is tuned (feedforward model).

16.0.2 Indeed for $\epsilon = 0$, the input is flat and tuning is non existant.

16.0.3 When $\epsilon = 0$, there is no stimulus orientation since we have a constant input h .

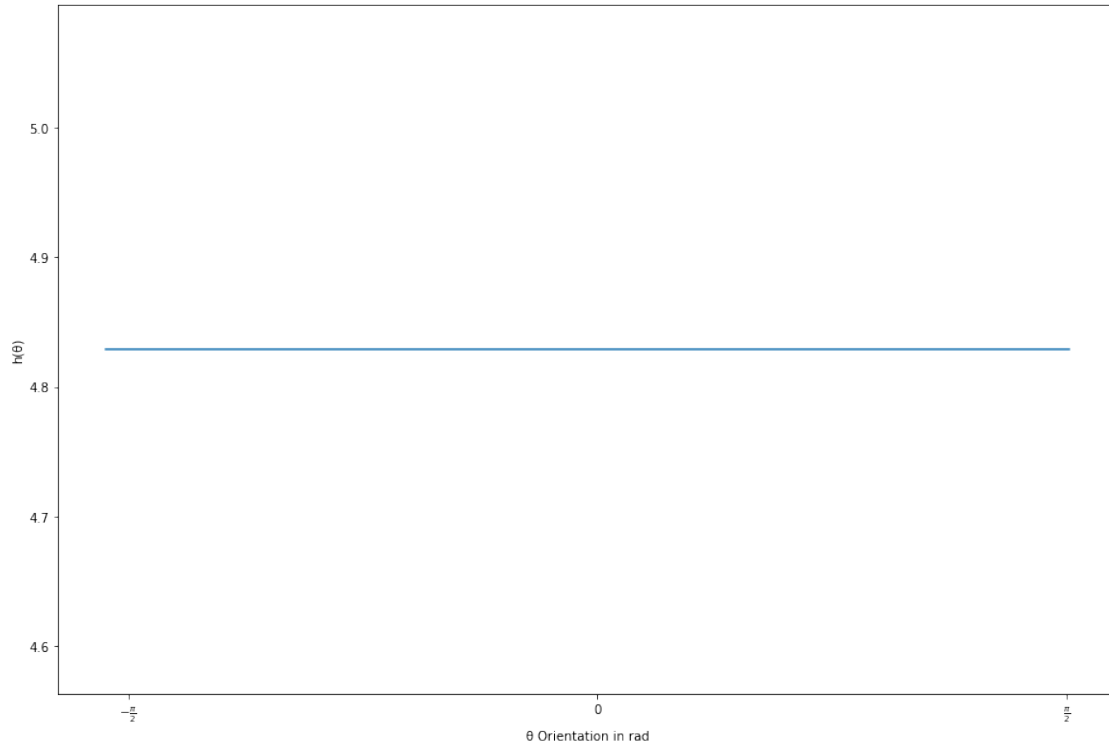
16.0.4 The parameter space is divided into three domains.

16.0.5 When $\epsilon = 0$, for fixed $J_0 = -1$ and $J_2 \leq 2$, we have lots of inhibition and a little bit of excitation and therefore the firing rate will be almost constant across the network model : homogeneous state. However, when we change ϵ , this does not hold anymore because the input is tuned.

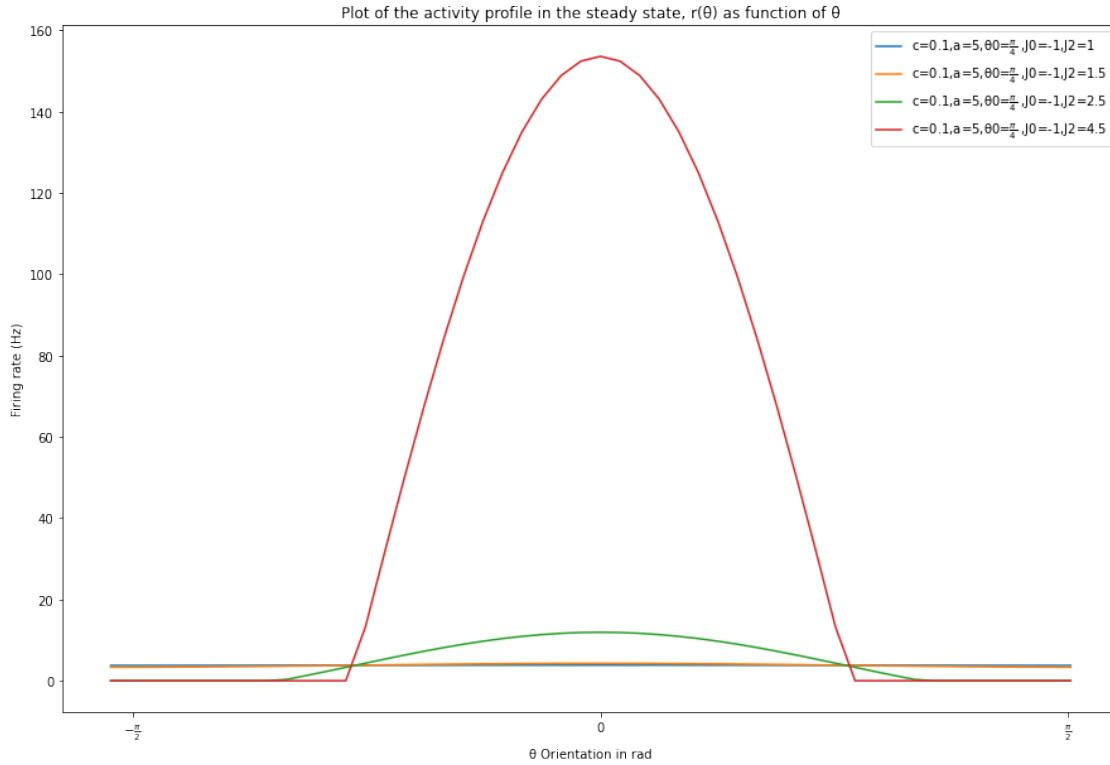
16.0.6 When $\epsilon = 0$, for fixed $J_0 = -1$ and $J_2 > 1$, we have a more balanced regime where we have strong recurrent inhibition as well as strong recurrent excitation : marginal .

16.0.7 First let's show that h is fixed when $\epsilon = 0$

```
[56]: N=50
thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
plt.plot(thetas, [h_noise(theta=theta, c=0.1, A=40, eps=0, theta_cue=0) for theta in
    ↪ thetas], label='c=0.1, cue=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('h()')
plt.xticks([-1.5, 0, 1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



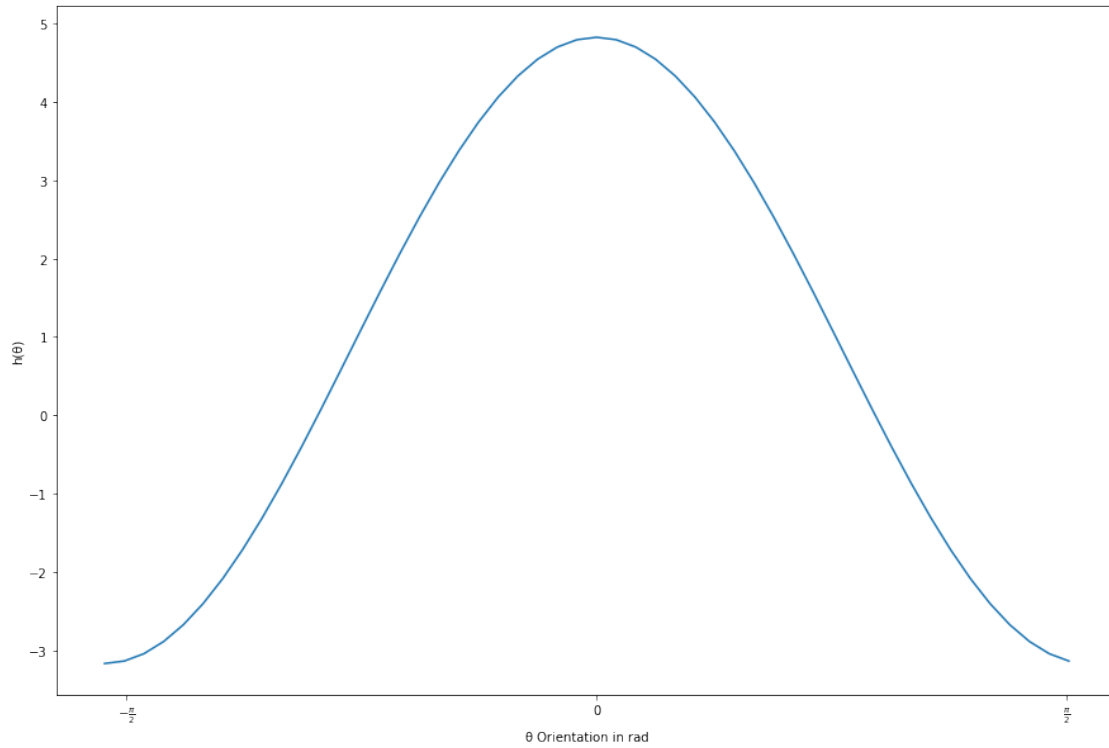
```
[57]: for j2 in [1,1.5,2.5,4.5]:
    plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
             numerical_integrations_noise(N=N,J_0=-1,J_2=j2,a=5,theta_0=0,c=0.
             ↪1,d_t=0.05,T=100,eps=0),
             label='c=0.1,a=5, 0='+ r'\frac{\pi}{4}$'+ ' ,J0=-1,J2='+str(j2))
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function_
↪of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



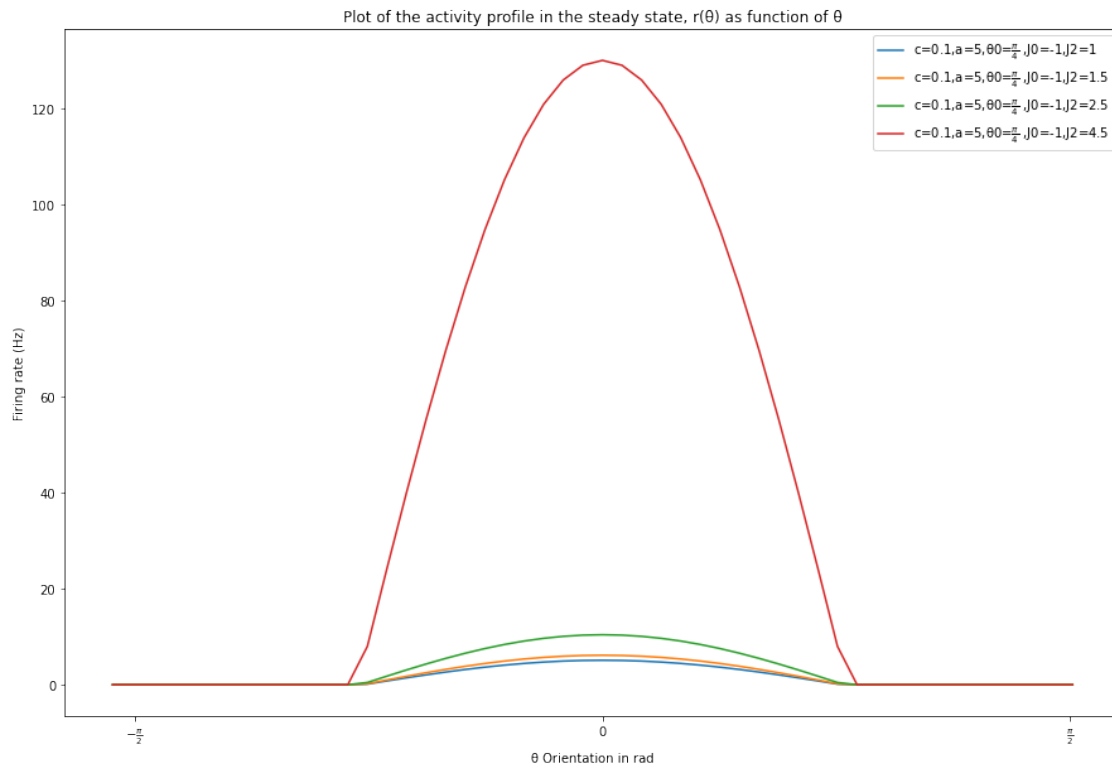
16.0.8 Flat firing for $J_2 < 2$ as expected.

16.0.9 Let's try for $\epsilon = 1$ when the thalamic input is tuned.

```
[58]: N=50
thetas = [(math.pi/N)*i - math.pi/2 for i in range(0,N)]
plt.plot(thetas, [h_noise(theta=theta, c=0.1, A=40, eps=1, theta_cue=0) for theta in
    ↳ thetas], label='c=0.1, cue=0')
plt.xlabel(' Orientation in rad')
plt.ylabel('h()')
plt.xticks([-1.5, 0, 1.5], [r'$-\frac{\pi}{2}$', '0', r'$\frac{\pi}{2}$'])
plt.show()
```



```
[59]: for j2 in [1,1.5,2.5,4.5]:
    plt.plot([(math.pi/N)*i - math.pi/2 for i in range(0,N)],
              numerical_integrations_noise(N=N,J_0=-1,J_2=j2,a=5,theta_0=0,c=0.
    ↪1,d_t=0.05,T=100,eps=1),
              label='c=0.1,a=5, 0='+ r'\frac{\pi}{4}$'+ ' ,J0=-1,J2='+str(j2))
plt.xlabel(' Orientation in rad')
plt.ylabel('Firing rate (Hz)')
plt.legend()
plt.title("Plot of the activity profile in the steady state, r() as function_
    ↪of ")
plt.xticks([-1.5,0,1.5], [r'$-\frac{\pi}{2}$', '0', r'\frac{\pi}{2}$'])
plt.show()
```



16.0.10 We can see that the regime have changed when the input is tuned with $\epsilon = 1$.
Now, we do not have this flat firing for $J_2 < 2$

[]: