

## CS398 HW3: Convolution Network

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In this assignment, I used stochastic gradient descent to train a convolution network model with multiple channels and reached 94.35% accuracy. Firstly, I generated  $K$ ,  $b$ ,  $W$  using `randn()` function. Then I set dimension of  $K$  to be 6, number of channels to be 8. I chose ReLU for  $\sigma$ , and constructed distribution function with the formula for derivatives from lecture, and upgrade new parameters each time I iterate. I used a learning rate of 0.005 because it has been good for stochastic gradient decent in previous homework. After 50000 iterations, I finally got 94.35% accuracy for test data.

(Code next page)

In [42]:

```

import numpy as np

import h5py
import time
import copy
import random
from random import randint

#load MNIST data
MNIST_data = h5py.File('MNISTdata.hdf5', 'r')
x_train = np.float32(MNIST_data['x_train'][:])
y_train = np.int32(np.array(MNIST_data['y_train'][:,0]))
x_test = np.float32( MNIST_data['x_test'][:])
y_test = np.int32( np.array( MNIST_data['y_test'][:,0] ) )
MNIST_data.close()

#####
###
#Implementation of stochastic gradient descent algorithm
def softmax(x):
    return np.exp(x) / np.sum(np.exp(x), axis=0)
def relu(x):
    return x * (x > 0)
def reluDerivative(x):
    x_new = np.copy(x)
    x_new[x_new <= 0] = 0
    x_new[x_new > 0] = 1
    return x_new

#number of inputs
num_inputs = 28*28
#number of outputs
num_outputs = 10
model = {}
model['W1'] = np.random.randn(num_outputs,num_inputs) / np.sqrt(num_inputs)
model_grads = copy.deepcopy(model)

#####
d = 28
ky = 6
C = 8
dy = num_outputs
dim = d-ky+1
K = np.random.randn(ky, ky, C)
b = np.random.randn(dy)
W = np.random.randn(dy, dim, dim, C)

l_rate = 0.005
iteration_num = 50000

# def con_mult(x,k):
#     result = np.zeros(dim*dim).reshape(dim,dim)
#     for i in range(dim):
#         for j in range(dim):
#             for m in range(ky):
#                 for n in range(ky):
#                     result[i][j] = k[m][n]*x[i+m][j+n]

```

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deriv = np.zeros(10)
U = np.zeros(dy)
Z = np.zeros(dim*dim*C).reshape(dim,dim,C)
H = np.zeros(dim*dim*C).reshape(dim,dim,C)
sigma = np.zeros(dim*dim*C).reshape(dim,dim,C)
de_W = np.zeros(dy*dim*dim*C).reshape(dy,dim,dim,C)
de_K = np.zeros(ky*ky*C).reshape(ky,ky,C)
i = 0
while (i < iteration_num):
    if (i%1000 == 0):
        print(i)
    idx = random.randint(0, len(x_train)-1)
    x_t = x_train[idx].reshape(28, 28)
    y_t = y_train[idx]
    for idx_z in range(C):
        for idx_x in range(dim):
            for idx_y in range(dim):
                Z[idx_x][idx_y][idx_z] = np.sum(x_t[idx_x:idx_x+ky,idx_y:idx_y+ky]
y]*K[:, :, idx_z])
#         H[:, :, idx_z] = relu(Z[:, :, idx_z])
    H = relu(Z)
    for idx in range(dy):
        U[idx] = np.sum(W[idx, :, :, :] * H) + b[idx]
    fun_x = softmax(U)

    for k in range(10):
        if k == y_t:
            deriv[k] = -(1-fun_x[k])
        else:
            deriv[k] = fun_x[k]
    for idx_z in range(C):
        for idx_x in range(dim):
            for idx_y in range(dim):
                sigma[idx_x][idx_y][idx_z] = deriv@W[:, idx_x, idx_y, idx_z]
    for idx in range(dy):
        de_W[idx, :, :, :] = deriv[idx]*H
    W = W - l_rate*de_W
    b = b - l_rate*deriv
    der_Z = 1*(Z>1)
    temp = der_Z*sigma
    for idx_z in range(C):
        for idx_x in range(ky):
            for idx_y in range(ky):
                de_K[idx_x, idx_y, idx_z] = np.sum(x_t[idx_x:idx_x+ky, idx_y:idx_y+ky]
y]*temp[idx_x, idx_y, idx_z])
    K = K - l_rate*de_K

    i += 1

model['W'] = W
model['b'] = b
model['K'] = K

def forward(x, y, model):
    for idx_z in range(C):
        for idx_x in range(dim):
            for idx_y in range(dim):
                Z[idx_x][idx_y][idx_z] = np.sum(x[idx_x:idx_x+ky, idx_y:idx_y+ky]

```

```
*model['K'][:, :, idx_z])
#      H[:, :, idx_z] = relu(Z[:, :, idx_z])
    H = relu(Z)
    for idx in range(dy):
        U[idx] = np.sum(model['W'][:, :, :, idx]*H) + model['b'][idx]
    return softmax(U)

# #test data

total_correct = 0

for n in range( len(x_test)):
    if (n%1000 == 0):
        print(n)
    y = y_test[n]
    x = x_test[n][:].reshape(28,28)
    p = forward(x, y, model)
    prediction = np.argmax(p)
    if (prediction == y):
        total_correct += 1

print(total_correct/np.float(len(x_test)) )
```

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