



Micro 2 Lab Assignments

Rules and Helpful tips

TA: Ioannis Smanis

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TA Info

TA:	Ioannis Smanis
TA Office hours :	(posted on Piazza thread “TA Office Hours”)
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Deliverables (ONLY) e-mail:	<u>micro2tamailbox@gmail.com</u>

- Please do not hesitate to discuss with me any difficulty that you cope with
- See me at my office during my office hours or e-mail me for anything related with your Lab assignments and I will find a solution for you as fast as I can !
- Please, expect quick e-mail responses **ONLY** during my office hours.
- Please , **ALWAYS** refer your Group # in the subject of your e-mail (i.e.: subject: “**Group #05 clarification on lab X**”)
- Please do not hesitate to bother me out of my office hours **ONLY WHEN** you have an **urgent issue** with your lab assignment (defective parts, need more components, fried parts, etc.). In this case, e-mail me with subject: “**URGENT - Group #xx**” or visit me at my office space
- Please, **NO QUESTIONS** about mid-term exam and final exam are allowed.

Lab Assignments General Info

- Any announcement, update or Lab assignment adjustment is going to be posted on “**Piazza**” (<https://piazza.com/class/j5fnal0lsvb5af>) *Make sure you get Piazza notification e-mails*
- **You are responsible to follow Piazza** discussion threads or announcement threads
- Lab assignments materials will be uploaded on **GitHub** repository: <http://github.com/yanluo-uml/micro2.git>
- Lab assignments are described in the **pdf documents**
- **New lab assignment** will usually be released few days before your prior lab demo time
- **It is your responsibility** to review all given materials from GitHub repo
- **It is your responsibility** to choose the right partners for your team

Lab Reports Rules

- **Lab Report Materials:**

1. Hard-copy: a **printed copy of the PDF document** named “**LabX_name_lastname.pdf**” (*Lab Report document format will be posted on GitHub as sample Lab_Report_Template*)
2. Soft-copy: a **ZIP file** with name “**LabX_GroupXX.zip**” should include the following materials:
 1. All group-members' PDF documents
 2. Shared design files exported in *a common readable/acceptable file format* (jpg,png, pdf) which you utilized to complete your lab project: *circuit design CAD files (Fritzing, Eagle CAD, etc), schematics, project/ circuit images*
 3. Shared Source code files should be in *.c/.h file format or the entire project file structure as it was originally created by MPLABX.*

Deliverables: both Hard-copies and Soft-copies are required to be delivered on time!!!

- **Hard-copies :** All group members should deliver their own Hard-copies in TA's physical mailbox **on time** according to the **specified project deadline**.
- **Soft-copies :** Only one group member should sent **One ZIP file** for his/her group via e-mail to **micro2tamailbox@gmail.com** **on time** according to the **specified project deadline**.

e-mail format:

Subject: *Lab X Group XX*

e-mail content: *LabX_GroupXX.zip (just the zip file)*

Lab Reports Rules

1. **Lab Report Materials:** Non-complete Lab report soft-copies will be rejected automatically.
2. **Lab Report Deadlines:**

Soft-copies and Hard-copies should be delivered by each **Monday 10am**, 4 days after the last demo day. For important dates review Micro 2 course syllabus on Piazza. Please, follow Piazza announcements for any deadline change.
3. **Delayed Lab Report Materials** will be **penalized individually** with 10% of the total earned points for each additional delayed day. There is no group penalties.
4. Group members who have not delivered their lab report PDF documents to the responsible (for submission) group member on time (before the group's soft-copies submission time), they will be **penalized individually** as it is described at #4.

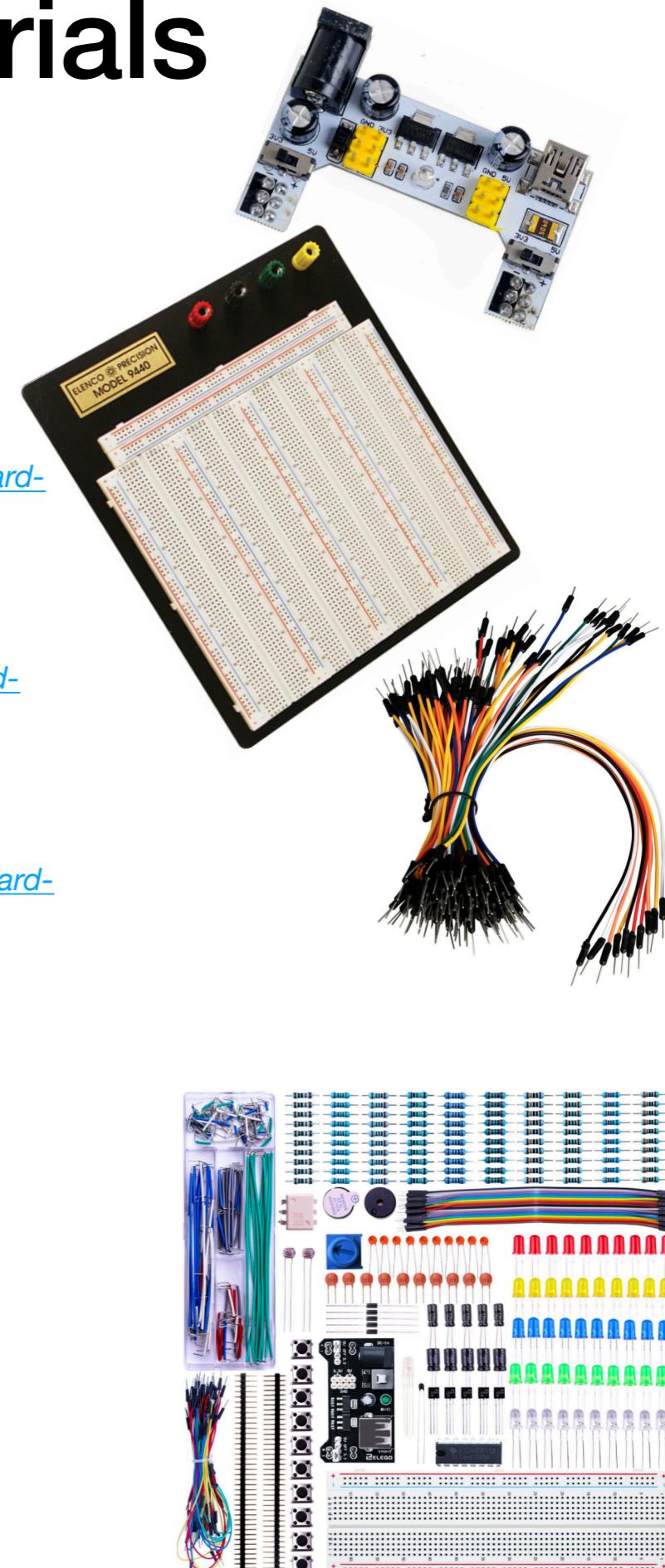


Lab Rules & Warnings !!

- Students are **responsible** for any damage to the given Lab Hardware kit
- Students **should return** the Lab Hardware Kit with fully functional components
- If you by mistake **fry or brick** any component, you should order replacement parts before you return your Lab Hardware Kit back
- A Lab Report is **an individual job** - each student should write his/her own lab report document
- **Shared Files between group-members** are **ONLY:** CAD file, schematics, pictures, voltage/signal readings measurement tables, source code
- **Copied-Pasted** content in the lab reports will be **penalized** from **other students** or from **provided documents**

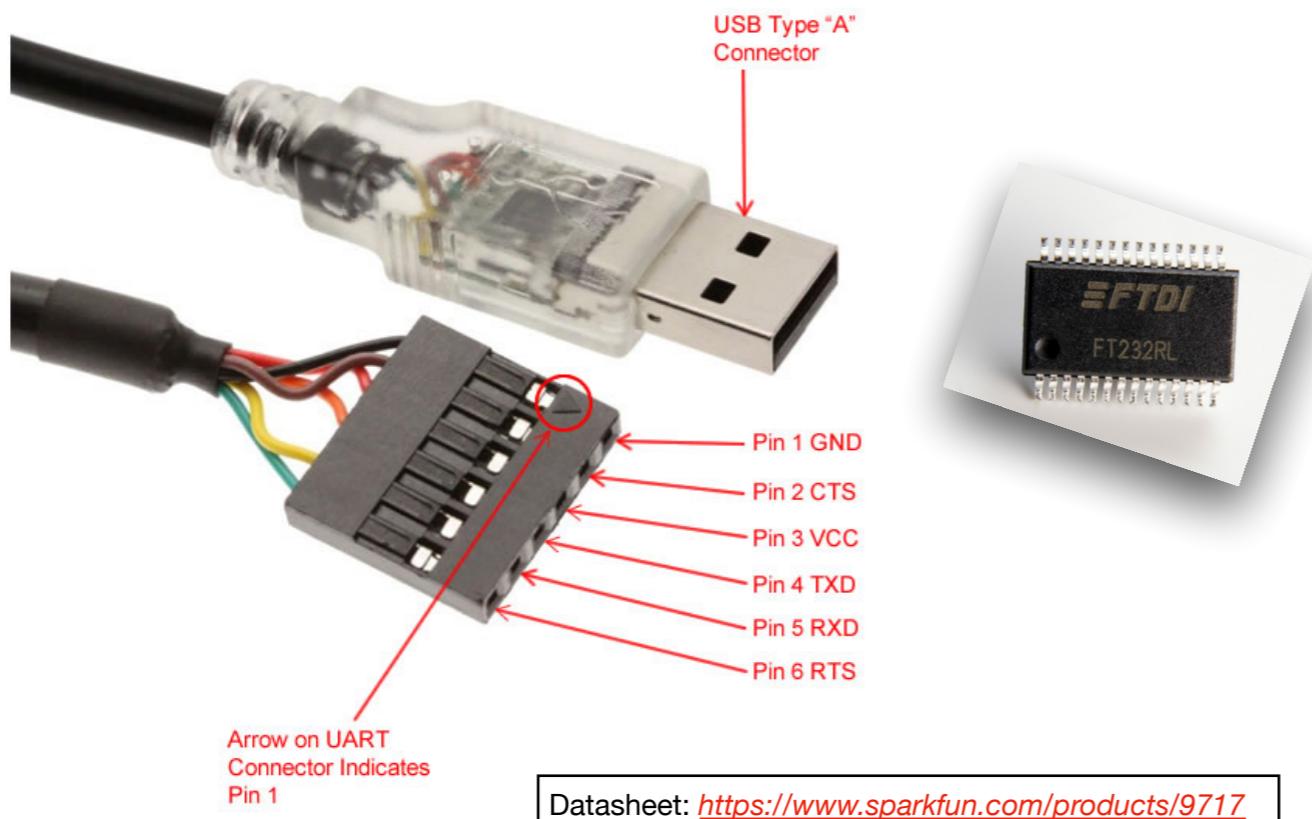
Recommended Materials

- **Breadboard** source: https://www.amazon.com/Wangdd22-Solderless-Breadboard-Protoboard-Tie-point/dp/B01N41WW61/ref=sr_1_3?ie=UTF8&qid=1505235805&sr=1-3&keywords=solderless+Breadboard+Protoboard
- **Solid Core wires** source: https://www.amazon.com/Makerfocus-140pcs-Breadboard-Board-Jumper/dp/B01M36HQWN/ref=sr_1_16?ie=UTF8&qid=1505235298&sr=1-16&keywords=breadboard+wires
- **Jumper cables** source: https://www.amazon.com/Haitronic-Multicolored-Breadboard-Arduino-raspberry/dp/B01LZF1ZSZ/ref=sr_1_3?ie=UTF8&qid=1505235183&sr=1-3&keywords=jumper+cables
- **3.3V Power Supply** source: https://www.amazon.com/WINGONEER-Breadboard-Supply-Arduino-Solderless/dp/B06XXXGFJ1/ref=sr_1_22?ie=UTF8&qid=1505235992&sr=1-22&keywords=breadboard+3.3v+supply
- **Recommended Starter Kits:**
[\(Recommended\) https://www.amazon.com/16Hertz-Electronics-Breadboard-Resistors-Raspberry/dp/B00J4RN61A/ref=sr_1_7?ie=UTF8&qid=1505234890&sr=8-7&keywords=electronics+starter+kit](https://www.amazon.com/16Hertz-Electronics-Breadboard-Resistors-Raspberry/dp/B00J4RN61A/ref=sr_1_7?ie=UTF8&qid=1505234890&sr=8-7&keywords=electronics+starter+kit)
[\(Recommended\) https://www.amazon.com/Solderless-Breadboard-jumper-supply-connector/dp/B01M11AVG8/ref=sr_1_21?ie=UTF8&qid=1505235045&sr=8-21&keywords=breadboard](https://www.amazon.com/Solderless-Breadboard-jumper-supply-connector/dp/B01M11AVG8/ref=sr_1_21?ie=UTF8&qid=1505235045&sr=8-21&keywords=breadboard)



Tools & Tips: USB-to-UART cable

- What is this ?



What software you will need ?

MacOSX/Windows/Linux systems:
FTDI drivers

&

Putty.exe for Windows
Terminal app for Mac OSX/Linux

- An a USB RS-323 Serial port adapter at 3.3V



A screenshot of a terminal window titled "ch208a.cae.tntech.edu - PuTTY". The window displays a Linux login session. The user "mwr" logs in using keyboard-interaction authentication. The terminal shows the following text:

```
login as: mwr
Using keyboard-interactive authentication.
Password:
Linux ch208a 2.6.8-2-686-smp #1 SMP Tue Aug 16 12:08:30 UTC 2005 i686 GNU/Linux

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/*copyright.

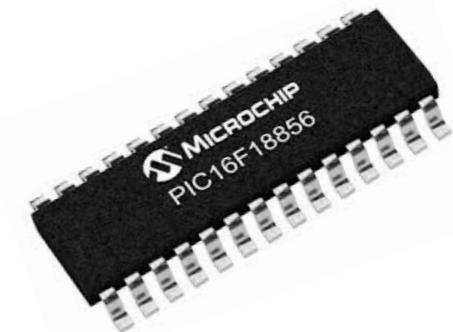
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
No mail.

Last login: Mon May  1 13:49:31 2006 from ch314c.cae.tntech.edu
mwr@ch208a:~$
```

PIC Project requirements

Project (LAB 1): LDR sensor + Servo Motor + LED + PIC micro-controller

Easy Project Debugging: use *UART to Serial cable (Console output)*



Working with a PIC micro-controller:

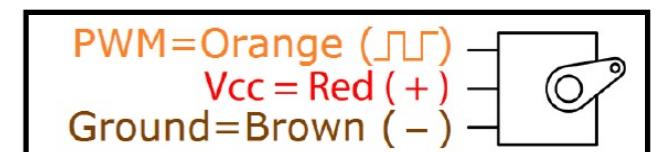
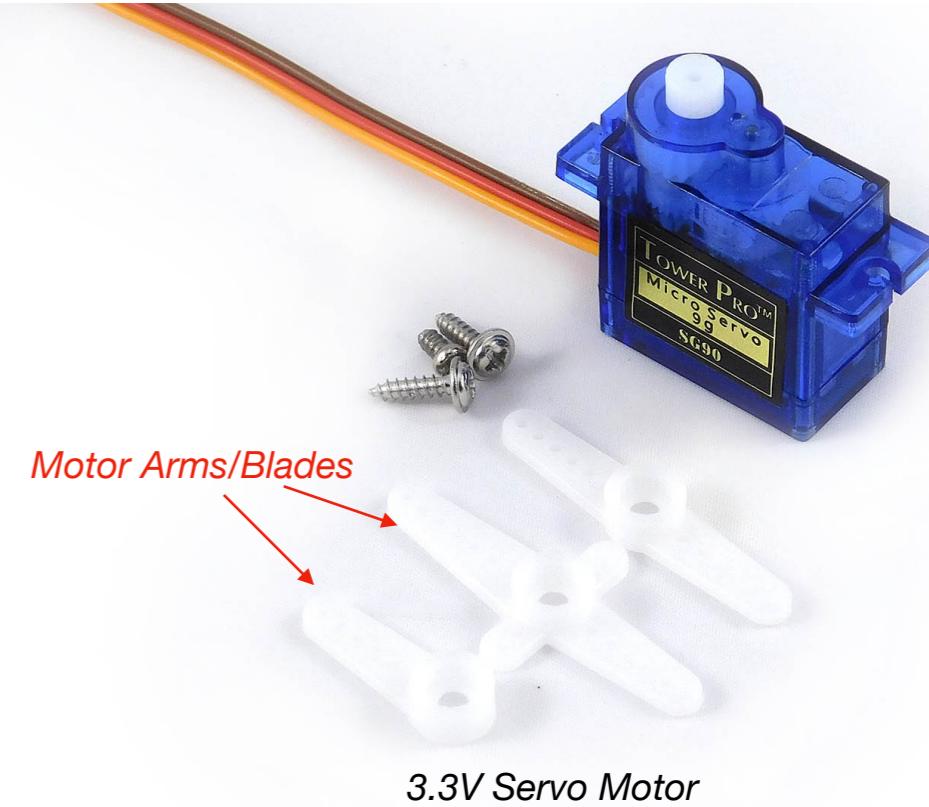
- You need a **PIC Kit 3** Debugger/Programmer (*PICKit3 wiring is provided via specified document*), an 8bit **PIC** micro-controller and MPLAB X development environment



Programming a PIC microcontroller

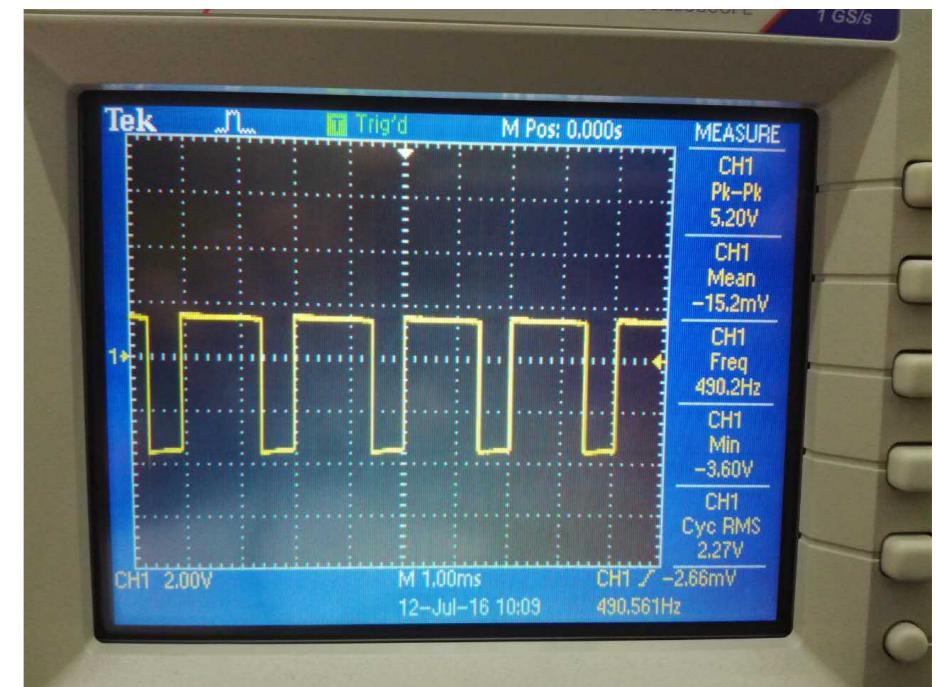
PIC Project requirements

- Servo Motor: **PWM** Signal Input
- Keep **PWM** output **frequency** low (*close to 50Hz*) using wait/delay functions
- Change the **Duty Cycle** to set the motor arm to a specific position
- Servo motors **does not** spin around. Rotation range is up to 180 degrees (90 degrees for each direction +/-)
- Refer to its datasheet on git repository



PIC Project - Tips

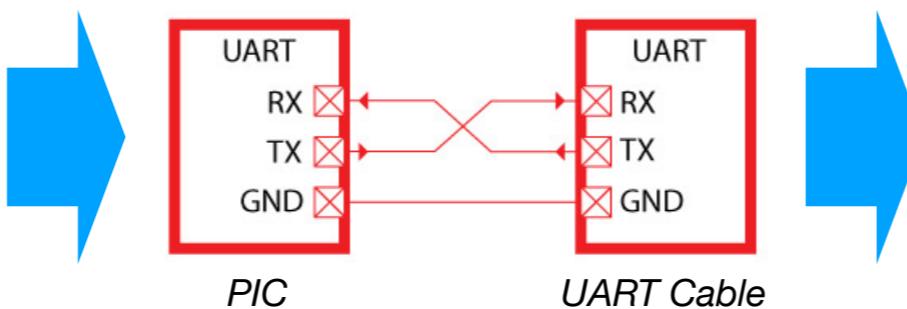
- How to test your PWM output signal from PIC?
- Increase/Decrease Duty Cycle and see if the square wave pulse changes



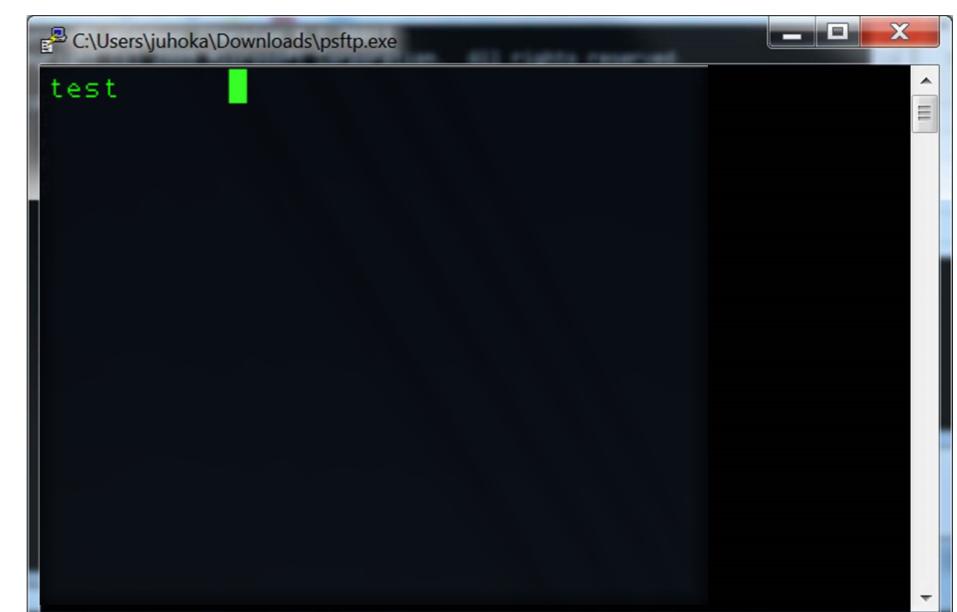
check your PWM signal on the Oscilloscope

- Debugging a PIC application via Serial Cable:

```
void main(void) {  
    SYSTEM_Initialize();  
    printf("Test \n\r");  
}
```



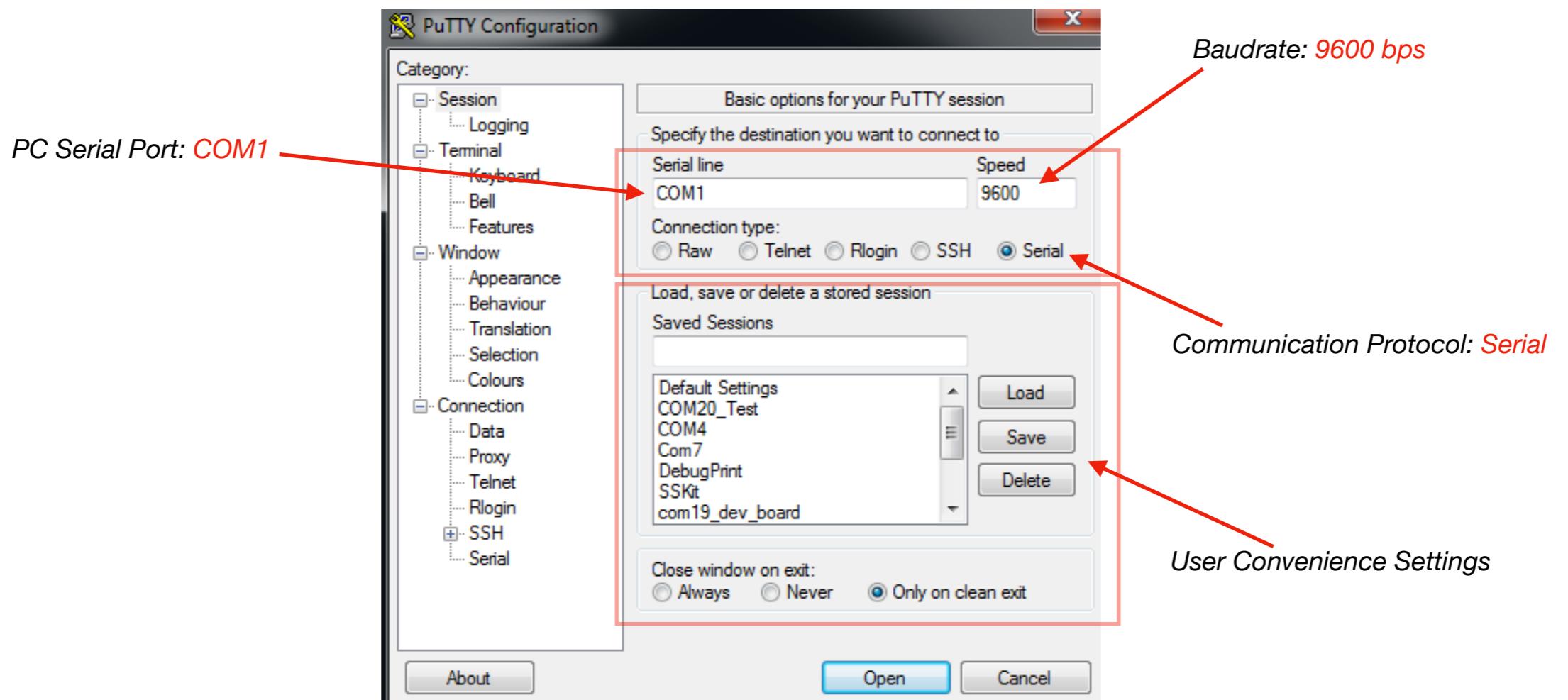
main.c code in MPLAB X IDE:
debugging statement



Putty Client: printed output context

PIC Project - Tips

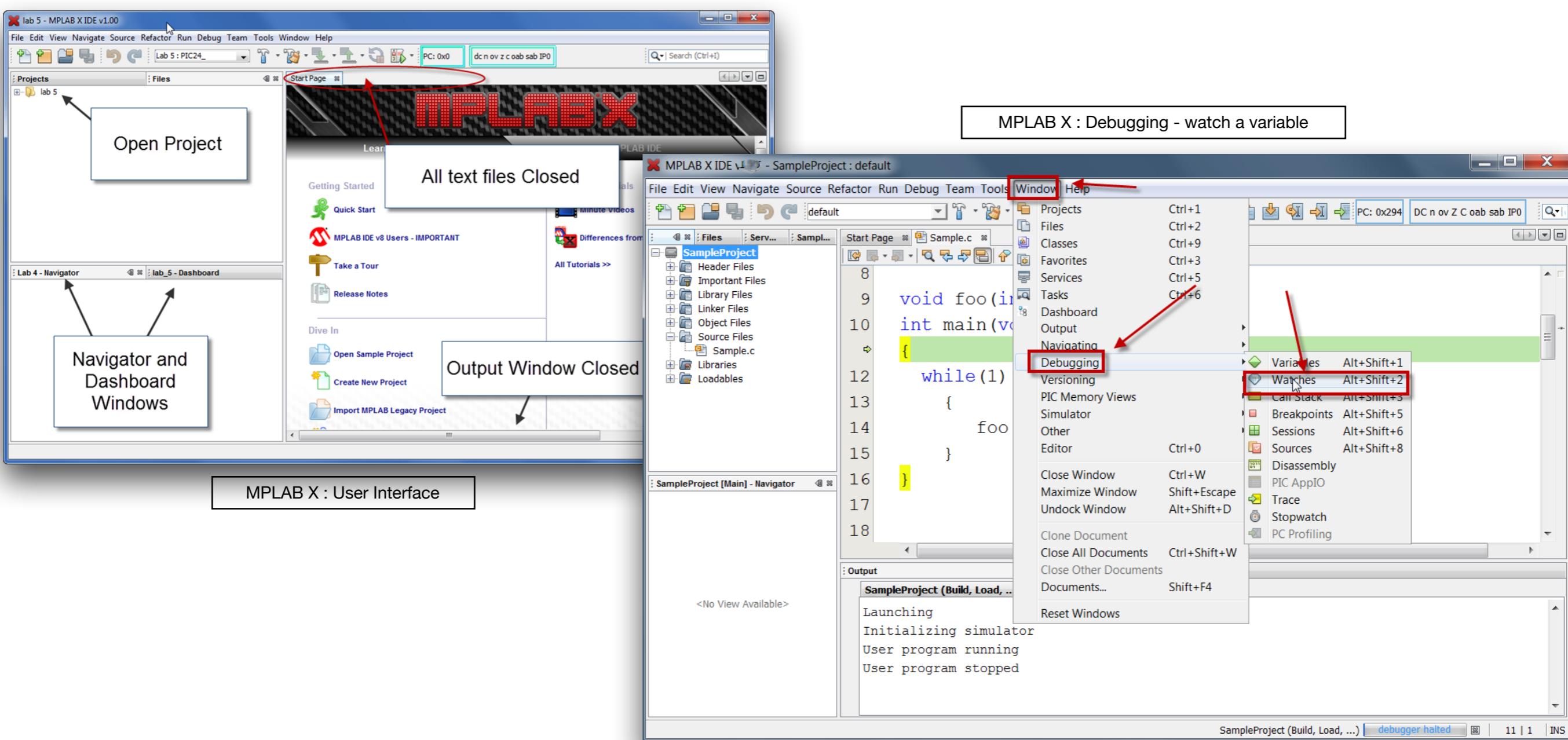
- Setting up a Putty console PC application for Serial port Mode:



Working with a PIC

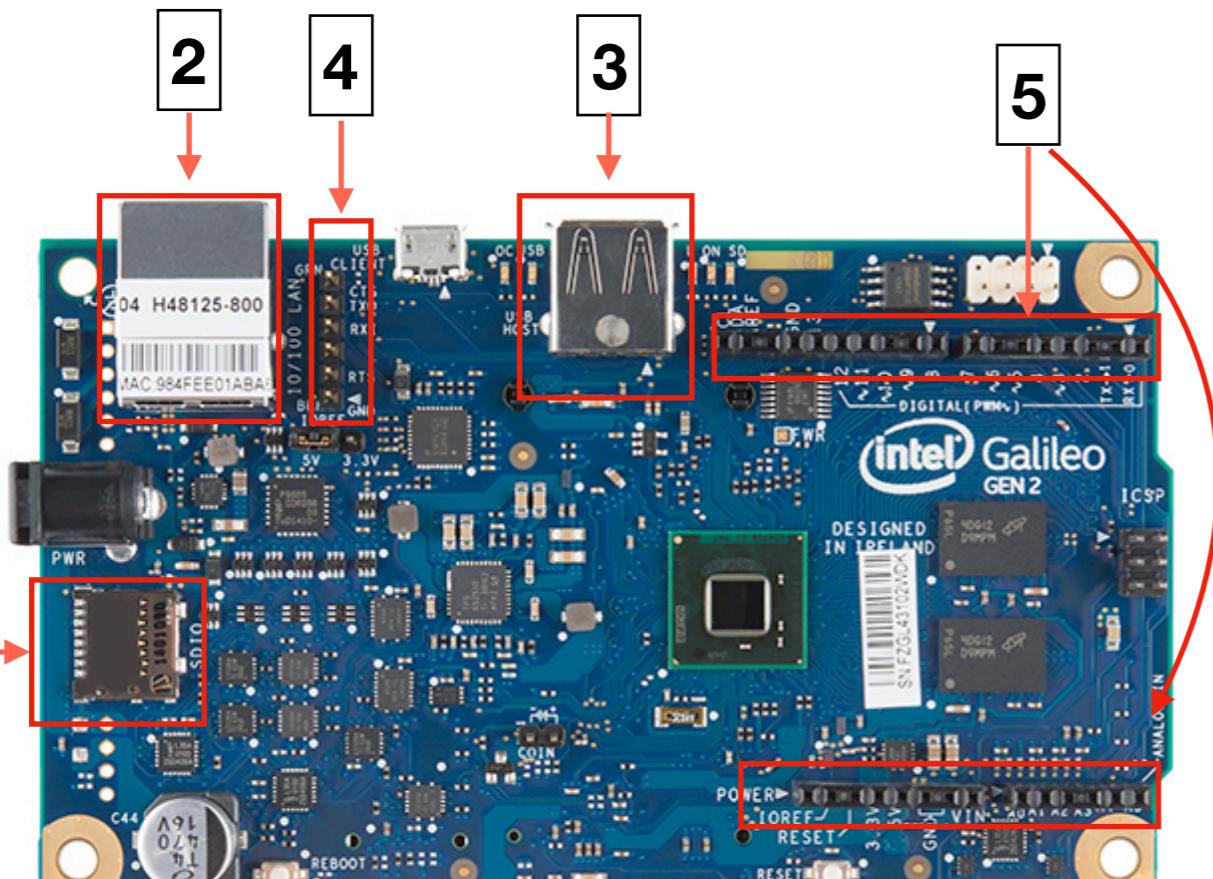
Needed Software: MPLAB X IDE + XC8 compiler

MPLAB X IDE: <http://www.microchip.com/mlab/mlab-x-ide>
XC8 compiler: <http://www.microchip.com/mlab/compilers>



Intel Galileo Projects

- Embedded-linux x86-32bit platform: Yocto OS
- Yocto has **terminal-based** User Interface
- C/C++, Python compilers are already installed
- Package manager is not available



Intel Galileo Board Gen 2

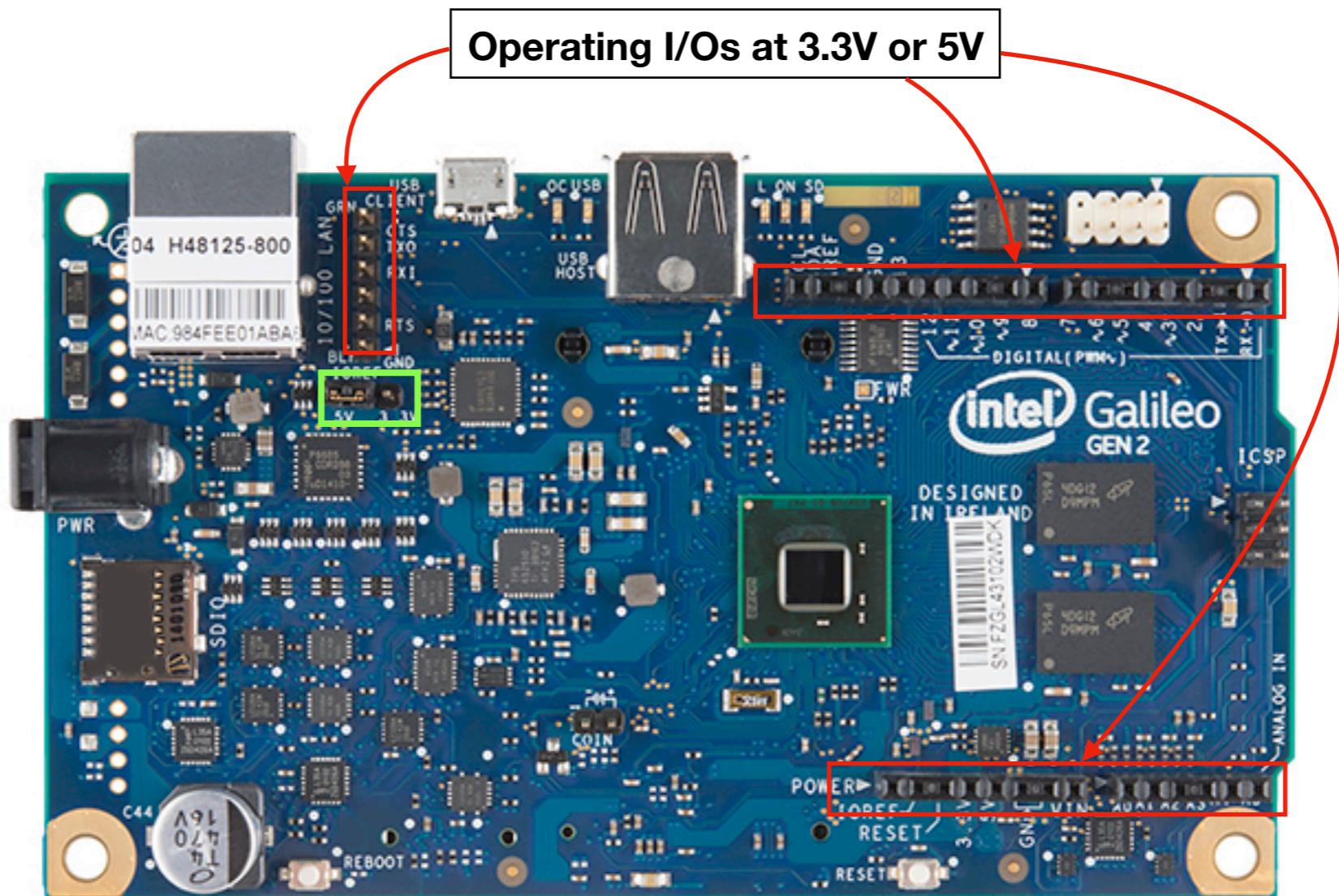
Basic Hardware Features Use:

1. **SD Card:** You should install Yocto OS (***Do not remove SD Card while the board is ON***)
2. **Ethernet Port and Wi-Fi Card installed:** connect the board to the internet and use SSH protocol to exchange files remotely
3. **USB Host Port:** use USB flash drives (**FAT32 formatted**) to transfer files
4. **UART Port:** use the FTDI Cable for console output
5. **GPIO ports:** programmable general purpose I/O pins

Working with Intel Galileo Gen 2

Set up the correct operating voltage:

WARNING: use 3.3V (NOT 5V) for Intel Galileo setting the appropriate jumper



Intel Galileo Board Gen 2

Working with Intel Galileo Gen 2

Working with Yocto OS locally

- It is a command line user interface:

```
telnet 192.168.10.200 — telnet — telnet — 69x12
~ telnet 192.168.10.200
Trying 192.168.10.200...
Connected to 192.168.10.200.
Escape character is '^]'.

Poky 9.0.2 (Yocto Project 1.4 Reference Distro) 1.4.2 clanton
sh-4.2#
```

- Browsing to the file system of Yocto: basic linux commands you can find here <https://diyhacking.com/linux-commands-for-beginners/>
- It includes a text editor “**vi**” and “**nano**” (use to edit your local files)
- Compiling C or C++ application files via “**gcc**” or “**g++**” compilers example:

```
compile: "gcc HelloWorld_application.c -o HelloWorld_executable_filename"
run     : "./HelloWorld_executable_filename"
```

use vi: <https://www.washington.edu/computing/unix/vi.html>

use nano: <https://www.howtogeek.com/howto/42980/the-beginners-guide-to-nano-the-linux-command-line-text-editor/>

compile and run c/c++ applications: <http://pages.cs.wisc.edu/~beechung/ref/gcc-intro.html>

Working with Intel Galileo Gen 2

Working with Yocto OS remotely

Connecting to a remote machine (Galileo Board)

access the machine by executing the `ssh` command in your local shell.

For example, if `1.2.3.4` is the IP address of your remote machine, you can create an SSH connection to it using this command:

```
ssh root@1.2.3.4
```

The first time you connect to the remote machine, `ssh` will ask your permission to put the fingerprint of the remote machine in your local `~/.ssh/known_hosts` file.

```
The authenticity of host '1.2.3.4' can't be established.  
RSA key fingerprint is 12:23:34:56:21:g3:g9:93:86:af:4r:bb:11:5d:f8:h9.  
Are you sure you want to continue connecting (yes/no)? yes  
Warning: Permanently added '1.2.3.4' (RSA) to the list of known hosts.
```

The first time you connect to the server you should type in `yes` to proceed.

Source: <https://semaphoreci.com/community/tutorials/getting-started-with-ssh>

Working with Intel Galileo Gen 2

Working with Yocto OS remotely

- Exchanging files between host machine (*your PC*) and remote machine (*Galileo Board*) via SSH protocol via one command “scp”

```
scp file.txt galileo_username@galileo_ip_address:/some/remote/directory
```

For more options see the link here: http://www.hypexr.org/linux_scp_help.php

Thank you