# Demonstrating State-of-the-Art Real-Time Semantic Segmentation

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#### **Semantic Segmentation**



- Assign each pixel in an image a corresponding label.
- Applications: Autonomous Driving, Video Surveillance, Robot Sensing
- Challenge: Respect object boundaries.



#### **Real-Time Semantic Segmentation**



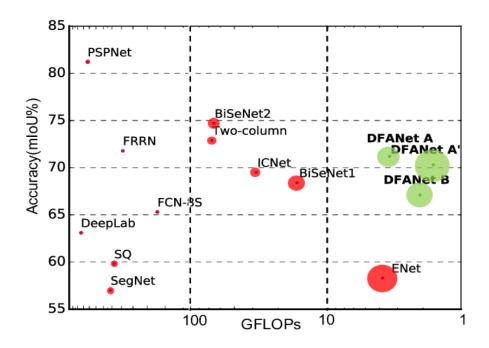
- Perform semantic segmentation in real-time, e.g. for 60 FPS.
- Trade-off between computation time and accuracy.



### **Deep Feature Aggregation Network (DFANet)**



- Deep Feature Aggregation for Real-Time Semantic Segmentation
- IEEE Conference on Computer Vision and Pattern Recognition 2019
- Promises to handle trade-off better than other common approaches.

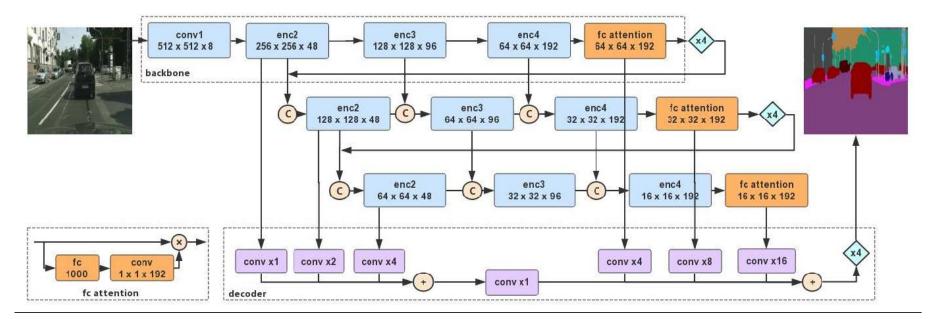


Problem: No working, publicly available implementation exists for reproducing results.

#### **Deep Feature Aggregation Network (DFANet)**



- Network has an encoder-decoder structure.
- Focus on re-using features from multiple (earlier) stages, i.e. lower level features (e.g. edges or object parts).
- Predominantely uses depthwise separable convolutions (for efficiency).



#### **Project Outline**

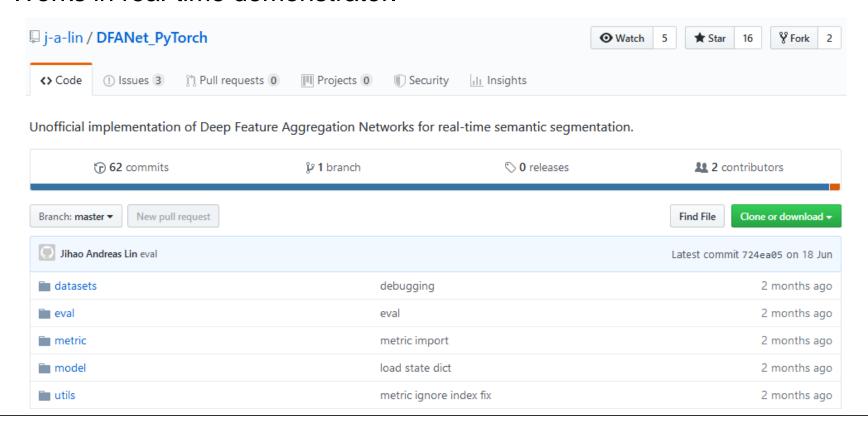


- 1. Familiarize with DFANet, PyTorch,...
- 2. Implement backbone (lightweight Inception module called Xception) and pretrain on ImageNet.
- 3. Implement DFANet, transfer learning using pretrained backbone.
- Integrate into real-time interactive live stream demonstrator for visualization of results.

#### Results



- Achieved 64% mIoU on the training data (comparable to paper results).
- Works in real-time demonstrator.



## **Example Output (Train)**





## **Example Output (Val)**





## **Example Output (Test)**



