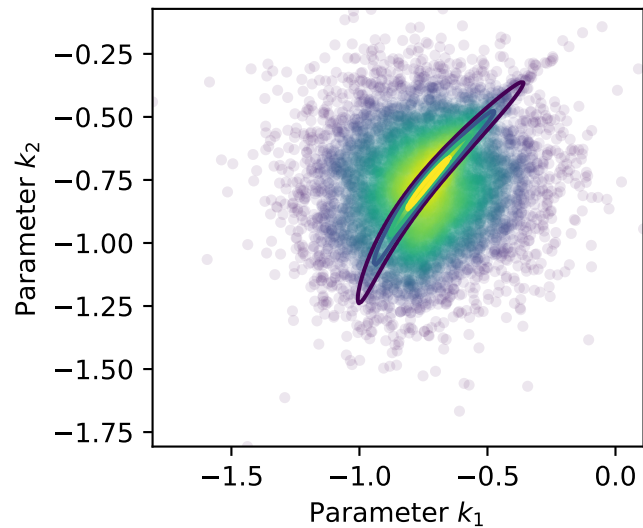
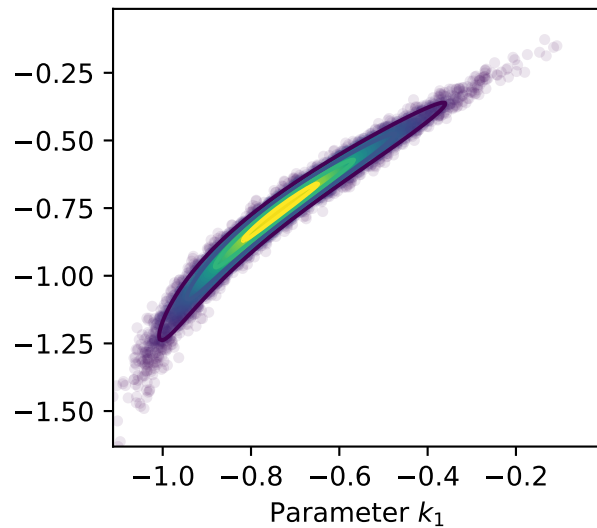
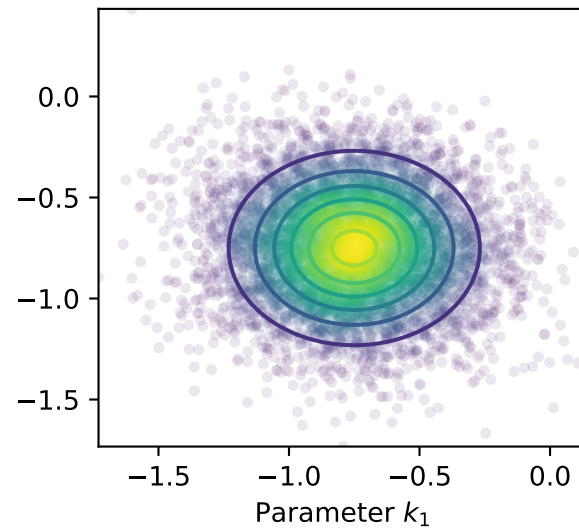


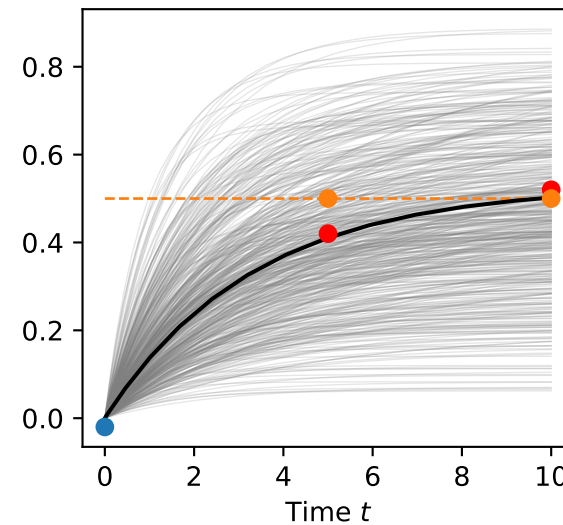
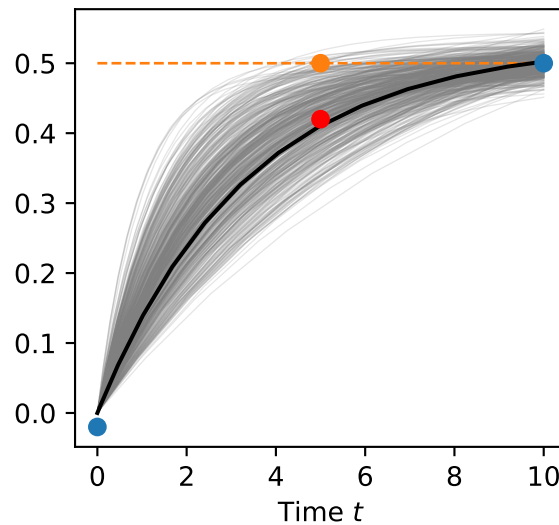
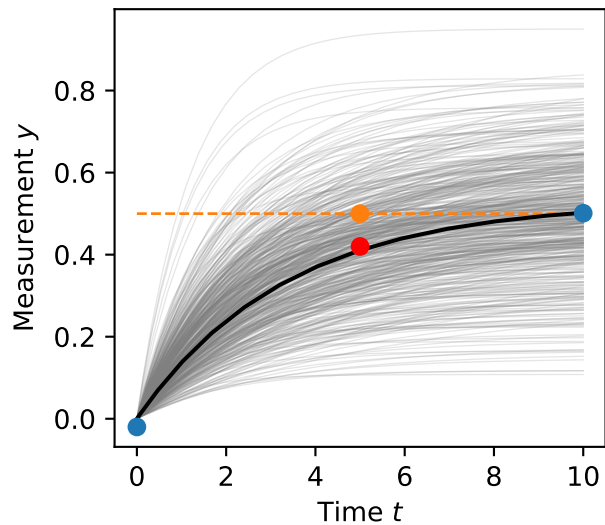
Posterior distribution

Insert 0.5 ✗

Augment by 0/1 ($c = 0.5$) ✓Augment by 0/1 ($c = 0.5$) ✓

— True posterior
● BayesFlow

Posterior predictive check



— True trajectory
● Available data
● Missing data
● Dummy value
— Simulation