

# Approximate Bayesian Computation for Parameter Estimation of Complex Stochastic Models

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- Parameter estimation
- Complex stochastic models

## 2 Approximate Bayesian Computation

- Basics
- Efficient sampling
- Challenges

## 3 Applications

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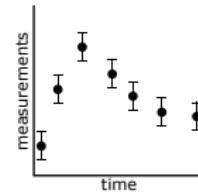
# Parameter estimation

biological system



# Parameter estimation

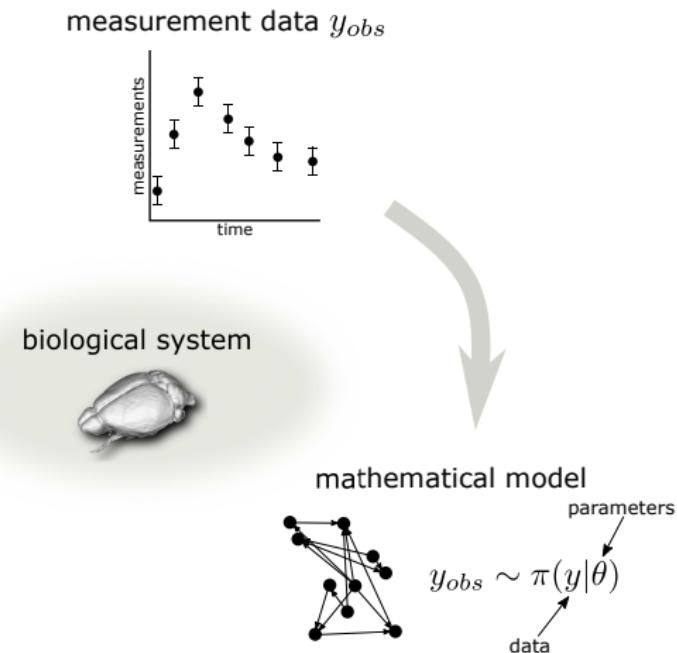
measurement data  $y_{obs}$



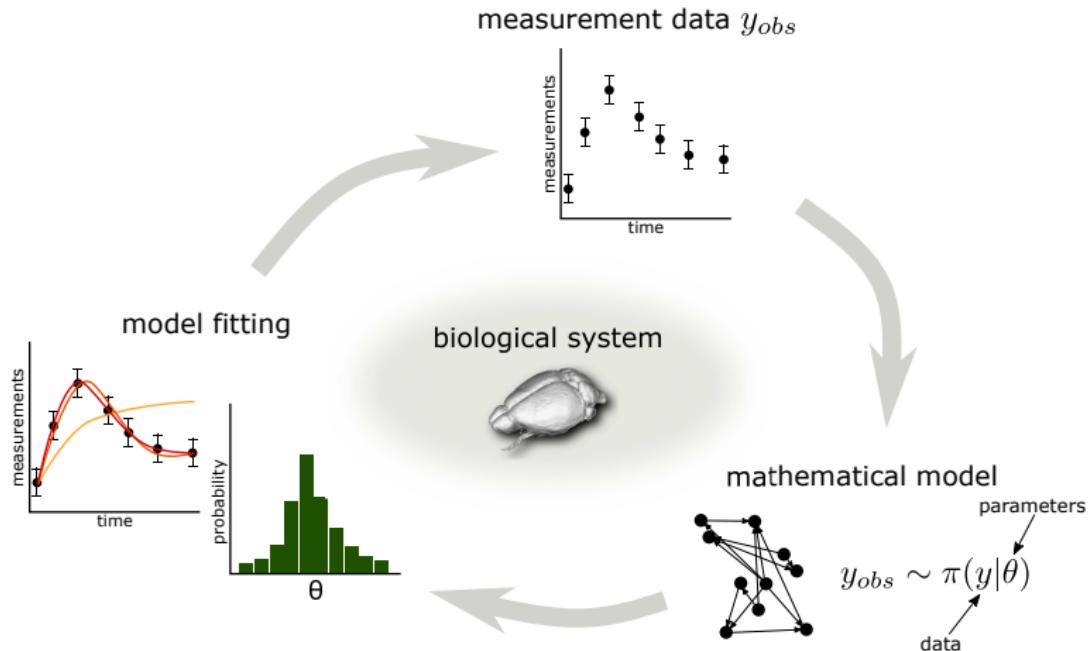
biological system



# Parameter estimation



# Parameter estimation



# Bayesian inference

$$\pi(\theta|y_{obs}) = \frac{\pi(y_{obs}|\theta)\pi(\theta)}{\pi(y_{obs})}$$

Diagram illustrating the Bayesian formula:

- posterior:  $\pi(\theta|y_{obs})$
- likelihood:  $\pi(y_{obs}|\theta)$
- prior:  $\pi(\theta)$
- evidence:  $\pi(y_{obs})$

```
graph TD; Posterior["posterior"] --> Product["\pi(\theta|y_{obs})"]; Product == " \pi(y_{obs}|\theta)\pi(\theta) / \pi(y_{obs})"; Likelihood["likelihood"] --> Product; Prior["prior"] --> Product; Evidence["evidence"] --> Product;
```

- ▶ goal: infer parameters  $\theta$  given data  $y_{obs}$ , i.e. analyze the posterior distribution

# Bayesian inference

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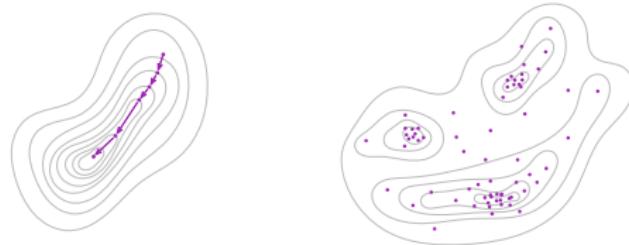
posterior

likelihood

prior

evidence

- ▶ goal: infer parameters  $\theta$  given data  $y_{obs}$ , i.e. analyze the posterior distribution
- ▶ optimization and sampling methods like MCMC commonly require evaluating the (unnormalized) likelihood



# Likelihood-free Bayesian inference

$$\pi(\theta|y_{obs}) = \frac{\pi(y_{obs}|\theta)\pi(\theta)}{\pi(y_{obs})}$$

Diagram illustrating the components of the posterior distribution:

- posterior (arrow pointing to the left)
- likelihood (arrow pointing down to the term  $\pi(y_{obs}|\theta)$ )
- prior (arrow pointing left to the term  $\pi(\theta)$ )
- evidence (arrow pointing up to the term  $\pi(y_{obs})$ )

- ▶ can happen: numerical evaluation of likelihood infeasible

# Likelihood-free Bayesian inference

$$\pi(\theta|y_{obs}) = \frac{\pi(y_{obs}|\theta)\pi(\theta)}{\pi(y_{obs})}$$

Diagram illustrating the components of the posterior distribution:

- posterior**: points to the left side of the equation.
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- evidence**: points to the term  $\pi(y_{obs})$ .

- ▶ **can happen**: numerical evaluation of likelihood infeasible
- ▶ but possible to simulate data  $y \sim \pi(y|\theta)$

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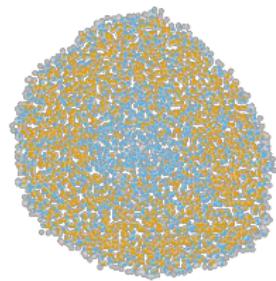
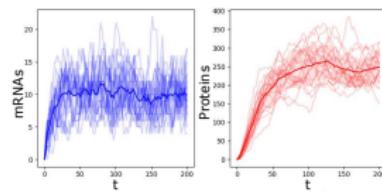
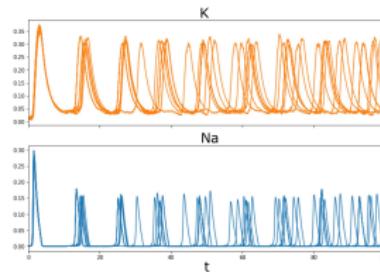
posterior

prior

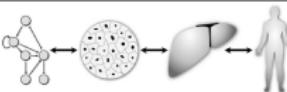
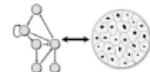
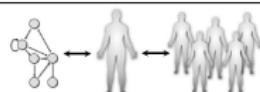
likelihood

evidence

- ▶ can happen: numerical evaluation of likelihood infeasible
  - ▶ but possible to simulate data  $y \sim \pi(y|\theta)$
  - ▶ often the case for complex stochastic models

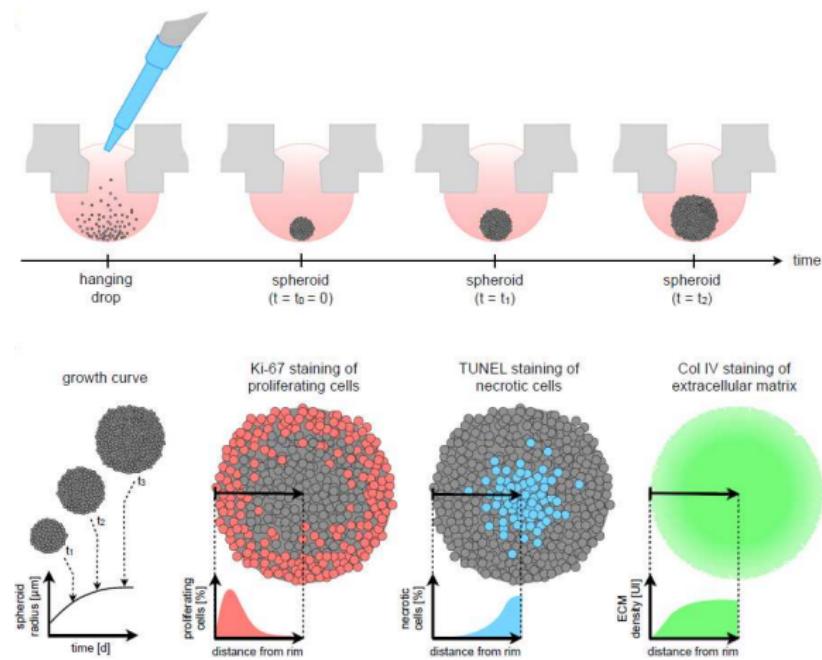


# Multi-scale models

	Boolean / Petri net models	Constraint-based models	Markov chain models	SDE models	ODE models	PDE models	Agent-based models
whole-heart (tissue and fluid mechanics, signaling)							Hunter and Borg, <i>Nature Reviews Molecular Cell Biology</i> , 4(3):237-243, 2003
cancer growth (signaling, cell division and death, angiogenesis, tissue remodeling)							Anderson and Quaranta, <i>Nature Reviews Cancer</i> , 8(3):227-234, 2008
liver lobule (cell division and cell death, tissue mechanics)							Hoehme et al., <i>PNAS</i> , 107(23):10371-10376, 2010
glucose-insulin-glucagon regulation (blood and interstitial flow, organ uptake, signaling)							Schaller et al., <i>CPT: Pharmacometrics and Systems Pharmacology</i> , 2:e65, 2013
whole-cell (transcription, translation, DNA replication, metabolism, replication)							Karr et al., <i>Cell</i> , 150(2):389-401, 2012

Hasenauer; Data-driven modeling of biological multi-scale processes; J. Coup. Sys. and Mult. Dyn.; 2015

# Example: Multi-scale model of tumor growth



Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

# Example: Multi-scale model of tumor growth

proliferating cells

- ▶ hybrid discrete-continuous model
- ▶ cells modeled as stochastically interacting agents, dynamics of extracellular substances by reaction-diffusion equations
- ▶ simulate up to  $10^6$  cancer cells
- ▶ 10s - 1h for one forward simulation
- ▶ 7 - 18 parameters

Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

# Example: Multi-scale model of tumor growth

What we tried:

- ▶ multi-start local optimization
  - ▶ deterministic gradient descent
    - ▶ Levenberg-Marquardt
    - ▶ trust-region
    - ▶ interior-point
  - ▶ stochastic gradient descent
  - ▶ Bayesian optimization
- ▶ global optimization
  - ▶ simulated annealing
  - ▶ > 20 particle methods
  - ▶ enhanced scatter search

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**Key problem:** Objective function cannot be evaluated, but only stochastically approximated.

# How to do parameter estimation for complex stochastic models?

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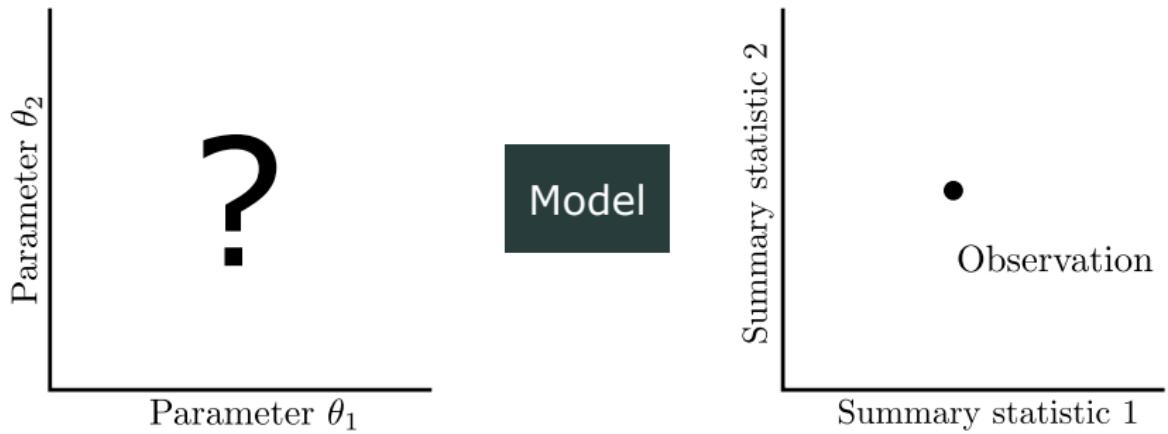
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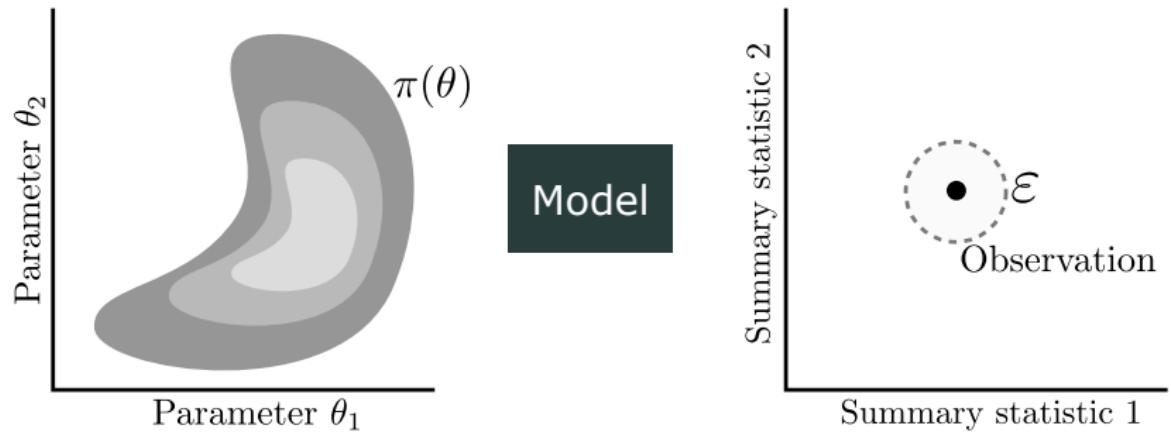
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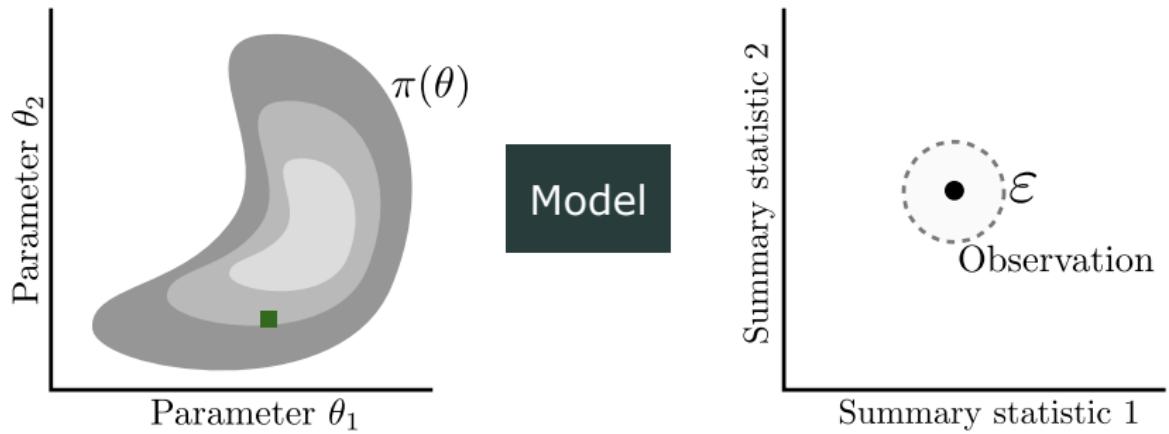
# ABC-Rejection



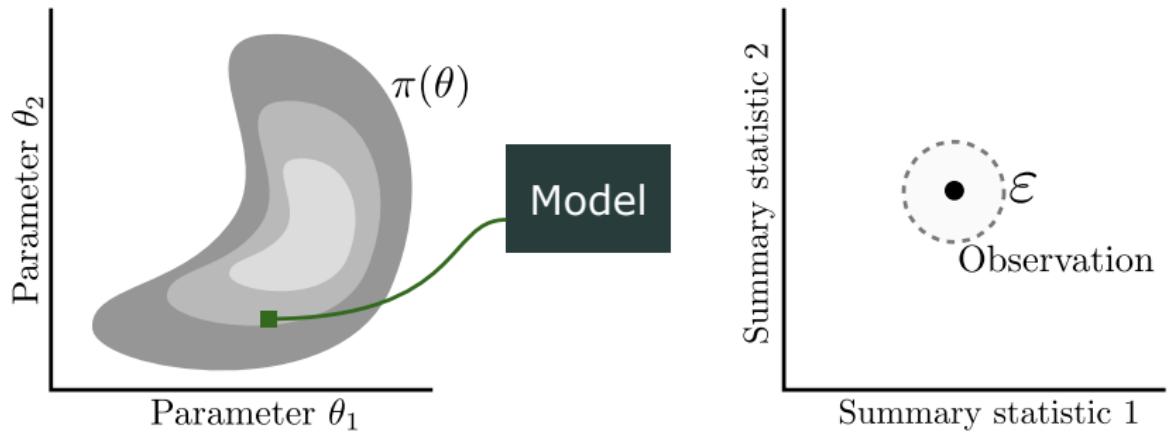
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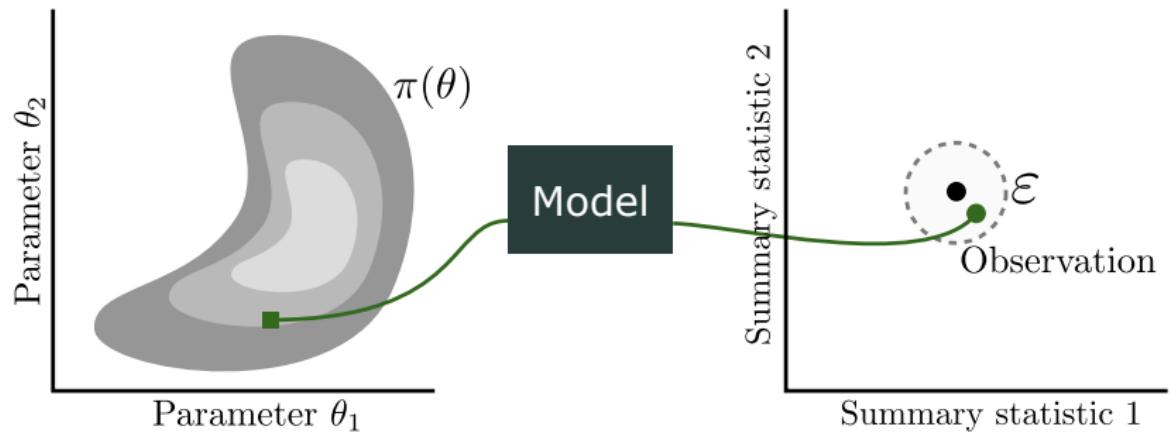
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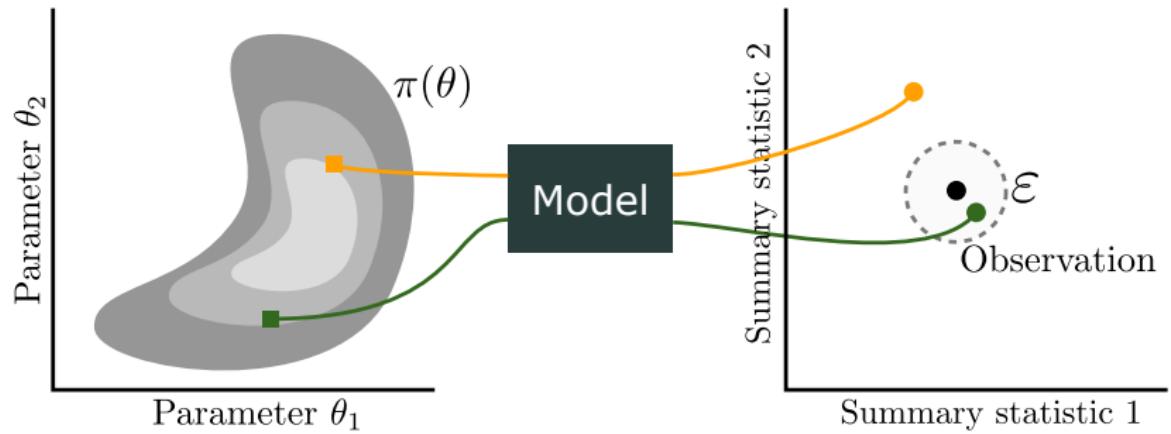
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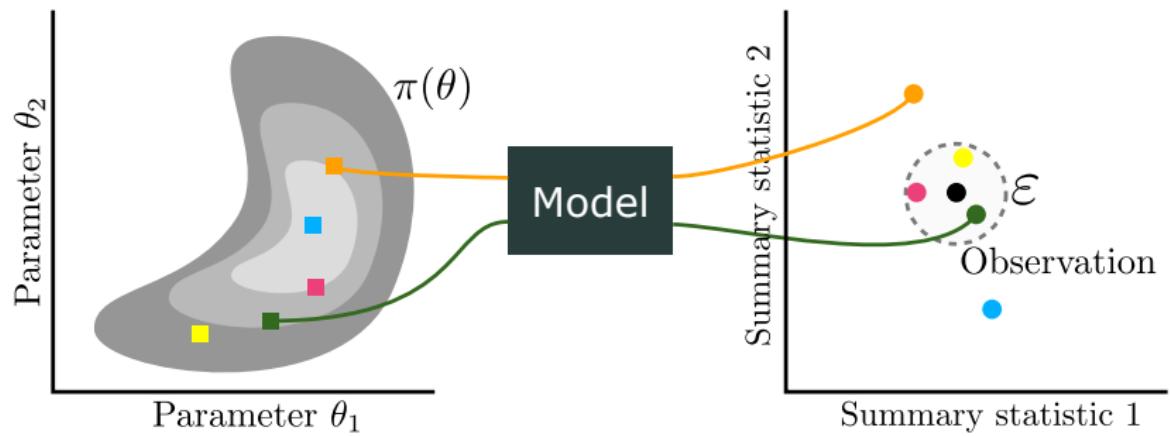
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# ABC-Rejection



# Idea: Rejection sampling

Background: Want to sample from  $f$ , but can only sample from  $g$  with  $g \gg f$ .

until  $N$  acceptances:

1. sample  $\theta^* \sim g(\theta)$
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Accepted  $\theta^*$  are independent samples from  $f(\theta)$ .

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- ▶ not available for us
- ▶ idea: **circumvent likelihood evaluation** by **simulating data** and matching them to the observed data

# Likelihood-free rejection sampling

until  $N$  acceptances:

1. sample parameter  $\theta^* \sim \pi(\theta)$
2. simulate data  $y^* \sim \pi(y|\theta^*)$
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# Likelihood-free rejection sampling

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Acceptance probability  $\mathbb{P}[y_{obs}]$

- ▶ can be small, in particular 0 for continuous data
- ▶ idea: accept simulations that are “**similar**” to  $y_{obs}$

# ABC-Rejection

With distance  $d$ , and threshold  $\varepsilon > 0$ :

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- ▶ **curse of dimensionality:** if the data are too high-dimensional, the probability of simulating similar data sets is small
- ▶ reduce the dimension using **summary statistics**

# ABC-Rejection

With distance  $d$ , threshold  $\varepsilon > 0$ , and summary statistics  $s$ :

until  $N$  acceptances:

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# Example

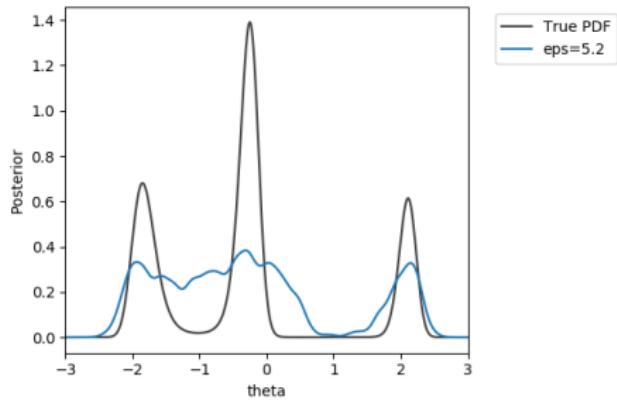
$$y \sim \mathcal{N}(2(\theta - 2)\theta(\theta + 2), 1 + \theta^2),$$

$$\theta \sim U[-3, 3],$$

$$d = \|\cdot\|_1,$$

$$y_{obs} = 2,$$

$N = 1000$  acceptances



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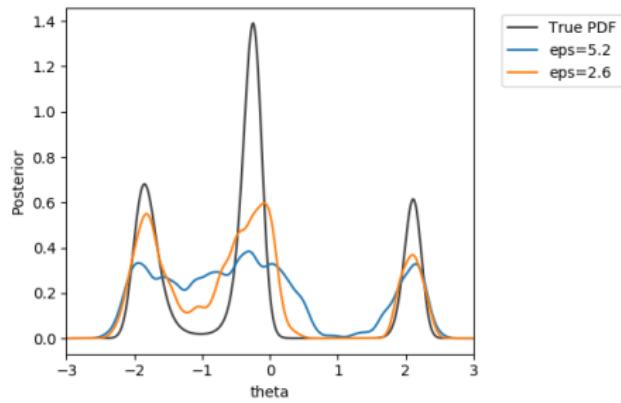
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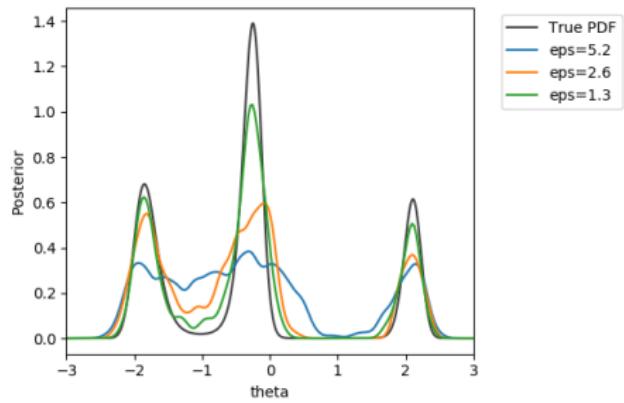
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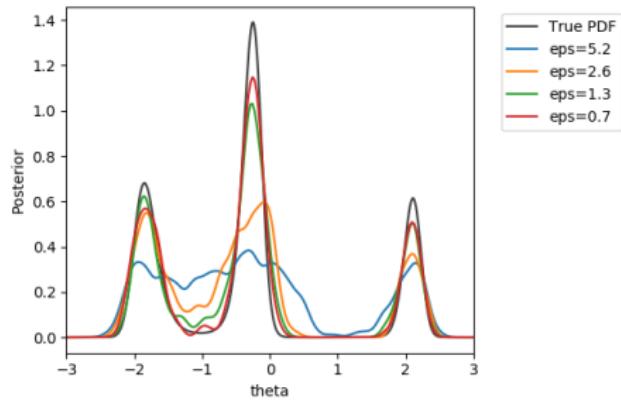
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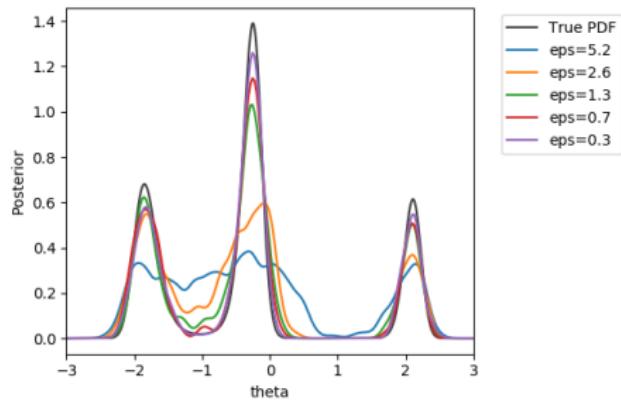
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Will the approximation always converge to the true posterior?

# Formally

We want:

$$\pi(\theta|y_{obs}) \propto \pi(y_{obs}|\theta)\pi(\theta)$$

We get:

$$\pi_{ABC}(\theta|s_{obs}) \propto \int I(\{d(s, s_{obs}) \leq \varepsilon\})\pi(s|\theta)\pi(\theta)ds \approx \frac{1}{N} \sum_{i=1}^N \delta_{\theta^{(i)}}(\theta)$$

## Theorem

Under certain assumptions it holds that

- ▶  $\frac{1}{N} \sum_{i=1}^N \delta_{\theta^{(i)}}(\theta) \xrightarrow{w} \pi_{ABC}(\theta|s_{obs})$  for  $N \rightarrow \infty$ ,
- ▶  $\pi_{ABC}(\theta|s_{obs}) \xrightarrow{w} \pi(\theta|s_{obs})$  for  $\varepsilon \rightarrow 0$ .

# Sources of approximation errors in ABC

- ▶ model error (as for every model of reality)
- ▶ Monte-Carlo error (as for sampling in general)
- ▶ summary statistics
- ▶ epsilon threshold

## John Tukey 1962

“Far better an approximate answer to the right question, which is often vague, than an exact answer to the wrong question, which can always be made precise.”

## Gelman and Rubin 1996

[...] one of the great scientific advantages of simulation analysis of Bayesian methods is the freedom it gives the researcher to formulate appropriate models rather than be overly interested in analytically neat but scientifically inappropriate models.”

# Efficient samplers

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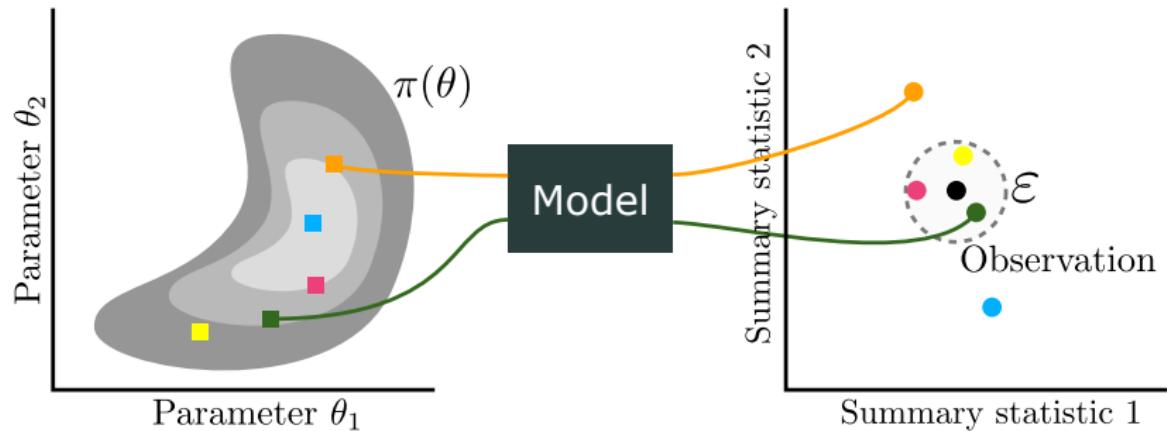
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- ▶ many (likelihood-based) Monte-Carlo sampling algorithms like IS, MCMC, Gibbs, SMC, today have **ABC-fied** versions
  
- ▶ here: focus on **ABC-SMC**

# ABC-SMC

Combine with a Sequential Monte-Carlo Scheme

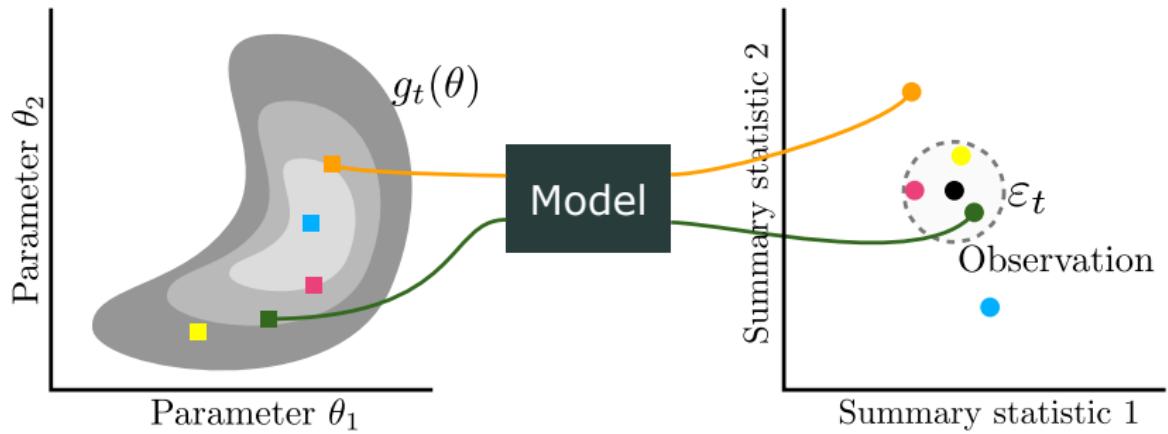


- ▶ idea: decrease  $\varepsilon = \varepsilon_t$  while sampling from an increasingly better approximation of the posterior

Sisson et al. 2007, Toni et al. 2008, Beaumont et al. 2009

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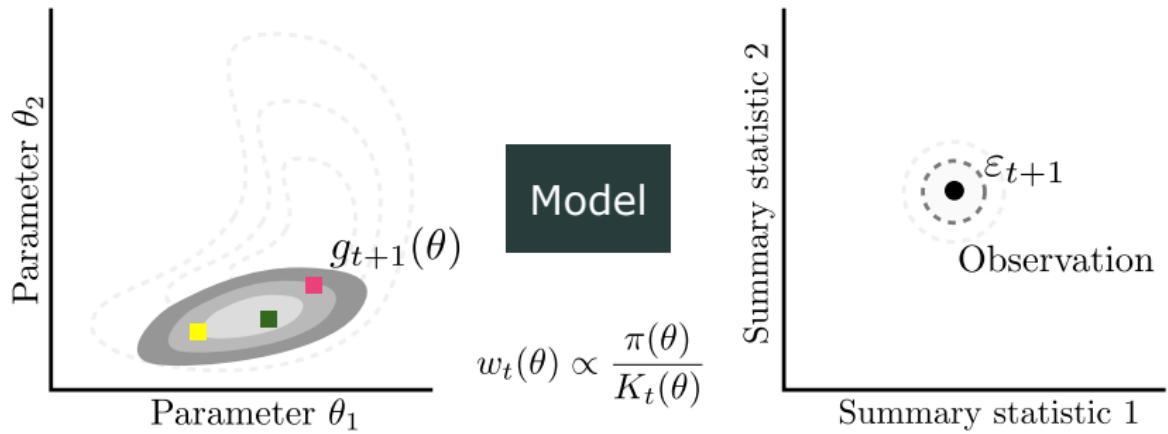


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# ABC-SMC

for  $t = 1, \dots, t_{max}$

1. until  $N$  acceptances

1. sample parameter  $\theta^* \sim g_t(\theta)$
2. simulate data  $y^* \sim \pi(y|\theta^*)$
3. accept  $\theta^*$  if  $d(y^*, y_{obs}) \leq \varepsilon_t$

denote by  $\theta_1^t, \dots, \theta_N^t$  the accepted parameters

2. compute weights  $w_i^t = \frac{\pi(\theta_i^t)}{g_t(\theta_i^t)}$

Here, the proposal distribution is

$$g_t(\theta) = \begin{cases} \pi(\theta) & , t = 1 \\ \sum_{i=1}^N w_i^{t-1} K_t(\theta | \theta_i^{t-1}) / \sum_{i=1}^N w_i^{t-1} & , \text{otherwise} \end{cases}.$$

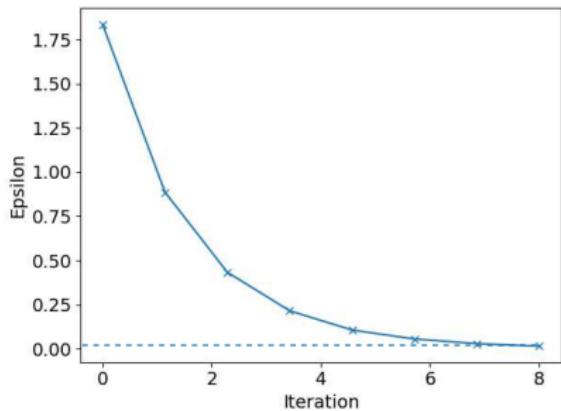
Then,  $\pi_{ABC}(\theta | s_{obs}) \sim \{\theta_i^{t_{max}}, w_i^{t_{max}}\}_{1 \leq i \leq N}$  (importance sampling).

# ABC-SMC

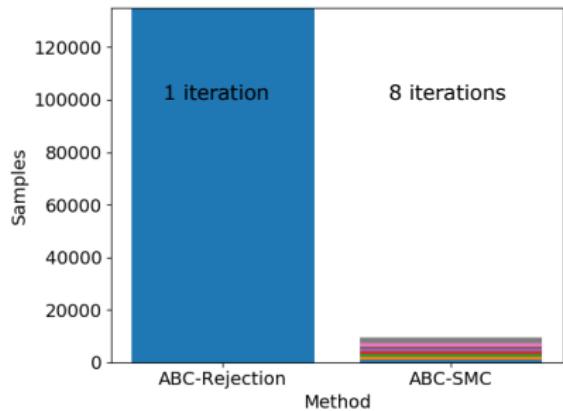
## Example

$y \sim U[-0.05, 0.05]$ ,  $\theta \sim U[-4, 4]$ ,  $d = \|\cdot\|_2$ ,  $y_{obs} = 0$ , same  $\varepsilon$  threshold

ABC-SMC epsilon reduction scheme



Overall number of samples



The SMC scheme significantly reduces the needed number of samples.

# Challenges in ABC-SMC

- ▶ summary statistics
- ▶ distance functions
- ▶ epsilon thresholds
- ▶ population sizes

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$$y \mapsto s(y)$$

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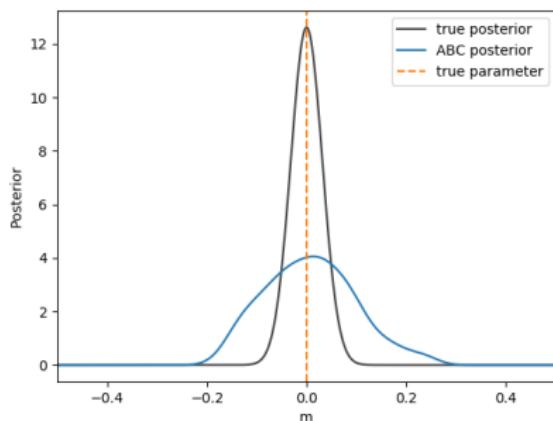
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- ▶ practically: usually not available (essentially only for exponential family models), therefore **trade-off between information loss and performance**
- ▶ **(semi-)automatic selection of summary statistics** (Fearnhead and Prangle 2012, and the review Blum et al. 2013)

# Summary statistics

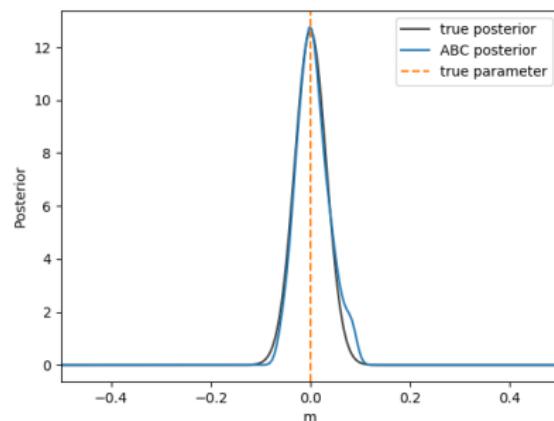
## Example

$y \sim \bigotimes_{i=1}^R \mathcal{N}(\theta, 1)$  for  $R = 10000$ ,  $\theta \sim U[-4, 4]$ ,  $d = \|\cdot\|_2$ ,  
 $y_{obs} = [0, \dots, 0]$



$$s = y$$

time: 107s, samples: 5.2e3



$$s = \bar{y} = \frac{1}{R} \sum_{i=1}^R y_i$$

time: 32s, samples: 1.8e3

# Summary statistics

## Example 2: gk distribution

- ▶ gk distribution  $gk(y|\theta)$  with  $\theta = (A, B, g, k)$  given via quantile transform

$$Q(q|A, B, g, k) = A + B \left[ 1 + c \frac{1 - \exp(-gz(q))}{1 + \exp(-gz(q))} \right] (1 + z(q)^2)^k z(q)$$

for  $B > 0, k > -\frac{1}{2}, c = 0.8$ , where  $z(q) = \Phi^{-1}(q)$  is the quantile transform of  $\mathcal{N}(0, 1)$

- ▶ density function has no closed form

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## Example 2: gk distribution

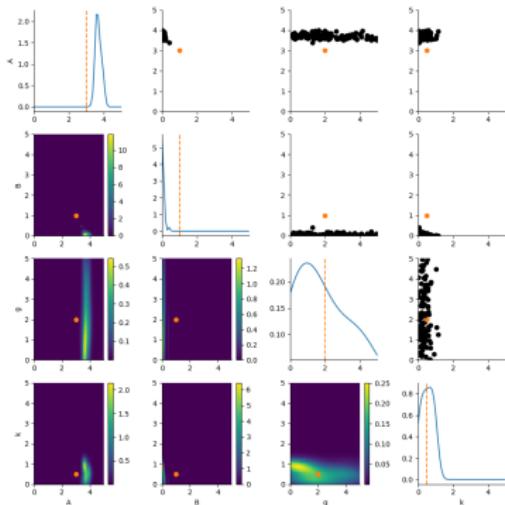
$y \sim \bigotimes_{i=1}^R \text{gk}(y_i|\theta)$  for  $R = 1000$ ,  $\theta \sim U[0, 5]$ ,  $d = \| \cdot \|_2$ ,  $y_{obs}$  sampled from the likelihood with  $\theta = (3.0, 1.0, 2.0, 0.5)$

summary statistics:

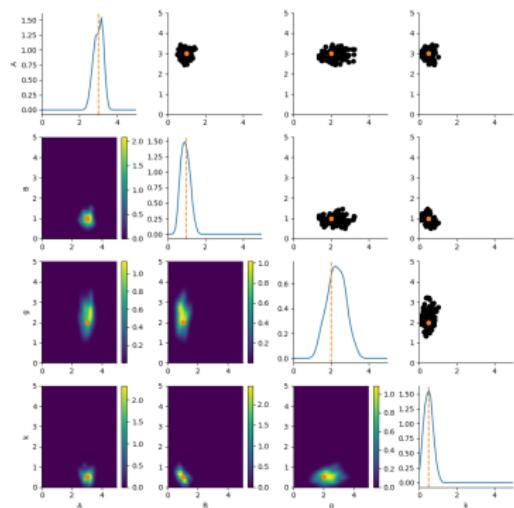
1.  $s = y$
2.  $s = (s_A, s_B, s_g, s_k)$  where  $s_A = E_4$ ,  $s_B = E_6 - E_2$ ,  
 $s_g = (E_6 + E_2 - 2E_4)/s_B$ ,  $s_k = (E_7 - E_5 + E_3 - E_1)/s_B$  where  
 $E_1 \leq \dots \leq E_8$  are the octiles of  $y$  (Drovandi and Pettitt 2011)

# Summary statistics

## Example 2: gk distribution



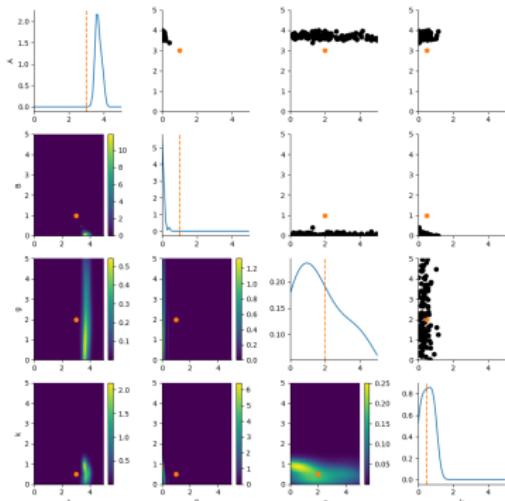
based on full data



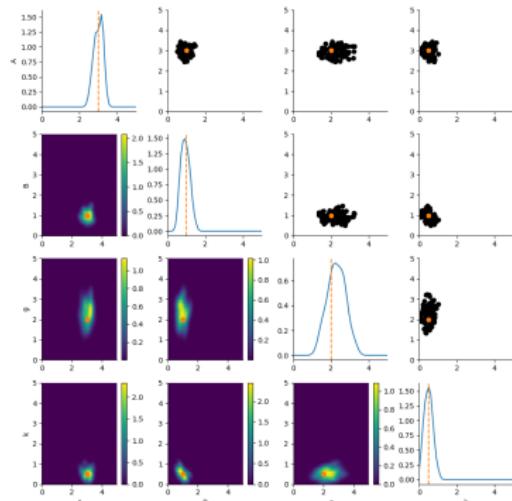
based on order statistics

# Summary statistics

## Example 2: gk distribution



based on full data



based on order statistics

Only the use of proper summary statistics ensures convergence in a reasonable computation time.

# Challenges in ABC-SMC

- ▶ summary statistics
- ▶ **distance functions**
- ▶ epsilon thresholds
- ▶ population sizes

# Distance functions

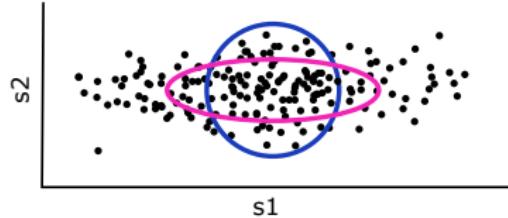
$$d(s(y^*), s(y_{obs}))$$

- ▶ in practice often simply  $p$ -norm distance (e.g. Euclidean distance  $p = 2$ ) used, i.e  $d(x, y) = (\sum_{i=1}^{n_s} |x_i - y_i|^p)^{1/p}$  where  $n_s$  is the summary statistics dimension
- ▶ many other distances possible (McKinley 2009)

# Distance functions

## Weighted distances

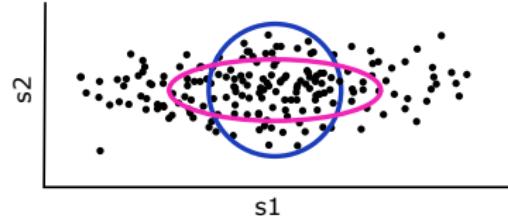
- ▶ problem: summary statistics can vary on **different scales**



# Distance functions

## Weighted distances

- ▶ problem: summary statistics can vary on **different scales**

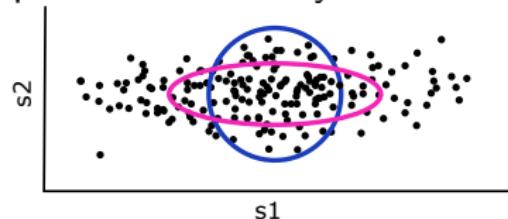


- ▶ therefore: **weighted distance**  $d(x, y) = (\sum_{i=1}^{n_s} \omega_i |x_i - y_i|^p)^{1/p}$
- ▶ usually: pre-calibrate weights

# Distance functions

## Weighted distances

- ▶ problem: summary statistics can vary on **different scales**

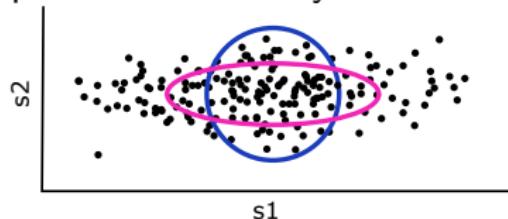


- ▶ therefore: **weighted distance**  $d(x, y) = (\sum_{i=1}^{n_s} \omega_i |x_i - y_i|^p)^{1/p}$
- ▶ usually: pre-calibrate weights
- ▶ requires additional effort, and in iterative methods the proposal distributions can vary over time

# Distance functions

## Weighted distances

- ▶ problem: summary statistics can vary on **different scales**

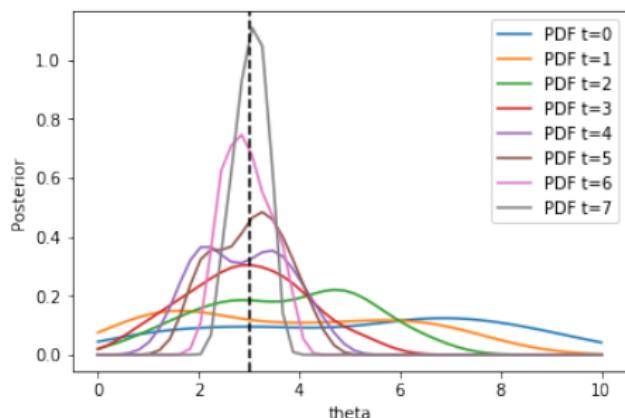


- ▶ therefore: **weighted distance**  $d(x, y) = (\sum_{i=1}^{n_s} \omega_i |x_i - y_i|^p)^{1/p}$
- ▶ usually: pre-calibrate weights
- ▶ requires additional effort, and in iterative methods the proposal distributions can vary over time
- ▶ Prangle 2015: **adapt weights iteratively** based on samples from previous iteration
- ▶ note: assumes equally informative summary statistics

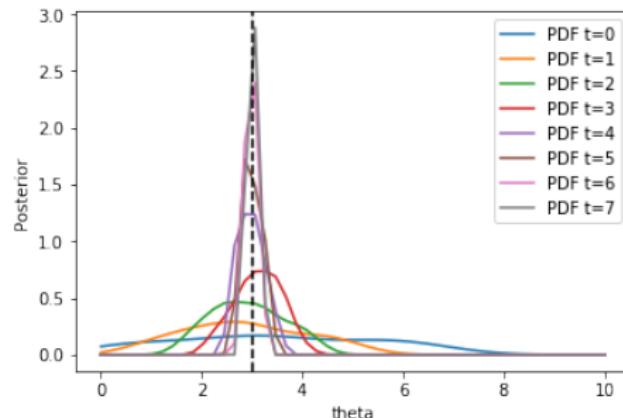
# Distance functions

## Adaptive weights: Example

$s_1 \sim \mathcal{N}(1 + \theta, 0.01)$ ,  $s_2 \sim \mathcal{N}(2, 100)$ ,  $s_{obs} = [4, 2]$  corresponding to  $\theta_{true} = 3$ ,  $\theta \sim U[0, 10]$



$$d = \|\cdot\|_2$$



$$d = \text{adaptively weighted } \|\cdot\|_2$$

Accounting for data heterogeneity improves convergence.

# Challenges in ABC-SMC

- ▶ summary statistics
- ▶ distance functions
- ▶ **epsilon thresholds**
- ▶ population sizes

# Epsilon thresholds

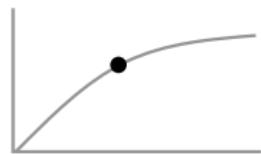
How to choose epsilon?



pre-specified list



quantiles



predict threshold-acceptance rate  
Silk, Filippi, Stumpf 2013

# Epsilon thresholds

## Generalization and re-interpretation

- ▶ generalize  $I(\{d(s(y), s(y_{obs})) \leq \varepsilon\}) \rightsquigarrow K_\varepsilon(s(y) - s(y_{obs}))$  for some **kernel**  $K_\varepsilon$ , i.e.

3.' accept with probability  $\frac{K_\varepsilon(s(y) - s(y_{obs}))}{K_\varepsilon(0)}$

(can represent the previous 0, 1-cutoff by a  $U[-\varepsilon, \varepsilon]$ ) kernel)



# Epsilon thresholds

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- ▶ Wilkinson 2013: ABC gives exact inference under the assumption of measurement noise: it samples from the model  $s \sim \pi(s|\theta) + \delta$  where  $\delta \sim K_\varepsilon$  is an independent error term

# Epsilon thresholds

## Assessing measurement noise

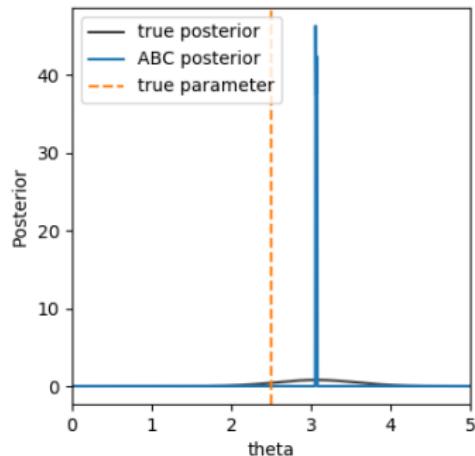
- ▶ if there is **measurement noise**, it **must be accounted for** in ABC
- ▶ ignoring leads to wrong parameter estimates

# Epsilon thresholds

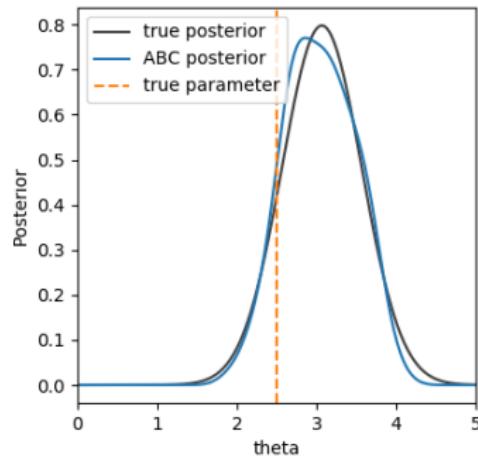
## Assessing measurement noise

- ▶ if there is **measurement noise**, it **must be accounted for** in ABC
- ▶ ignoring leads to wrong parameter estimates

$$\theta \sim U[0, 5], y_{obs} \text{ sampled from } \mathcal{N}(2.5, 0.5^2)$$



$$y = \theta$$



$$y \sim \mathcal{N}(\theta, 0.5^2)$$

# Epsilon thresholds

## Assessing measurement noise

- ▶ if there is **measurement noise**, it **must be accounted for** in ABC
- ▶ ignoring leads to wrong parameter estimates
- ▶ idea: we can use Wilkinson's insight to encode actual measurement noise not in the simulation, but in the **acceptance step**, and perform **exact Bayesian inference**

# Challenges in ABC-SMC

- ▶ summary statistics
- ▶ distance functions
- ▶ epsilon thresholds
- ▶ **population sizes**

# Population sizes

How to choose the population sizes  $N_t$  in ABC-SMC?

# Population sizes

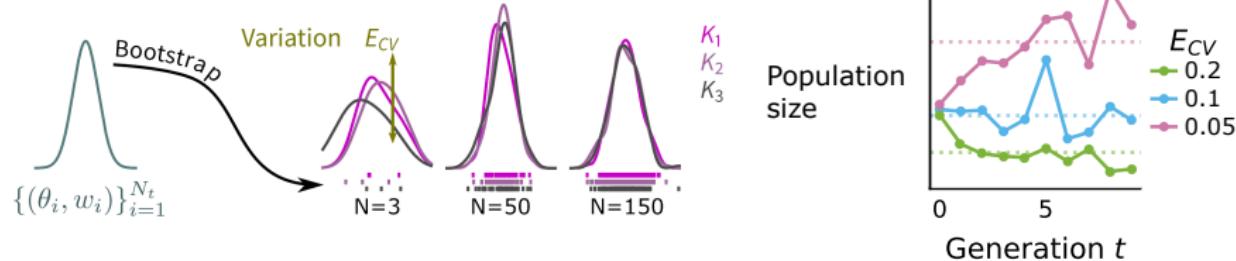
How to choose the population sizes  $N_t$  in ABC-SMC?

- ▶ trade-off accuracy – computational effort

# Population sizes

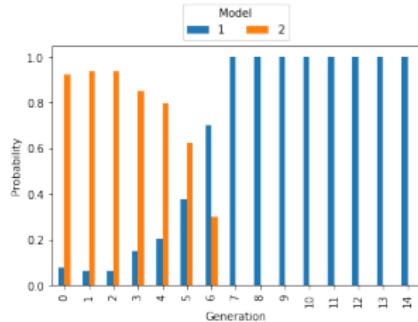
How to choose the population sizes  $N_t$  in ABC-SMC?

- ▶ trade-off accuracy – computational effort
- ▶ idea: **adapt population sizes** trying to **match a specified target accuracy**
- ▶ expressed in terms of the variation associated with kernel density estimates



## Further notes

- ▶ there is a lot more to discuss
- ▶ including adequate proposal distributions, automatic summary statistics selection, threshold schedules, ABC-MCMC, regression ABC, approximate ABC, and many variations of the presented algorithms, ...
- ▶ also model selection possible in ABC by augmenting the parameter space



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# pyABC

<https://github.com/icb-dcm/pyabc>

- ▶ implements an ABC-SMC algorithm
- ▶ HPC scalable using dynamic scheduling
- ▶ analysis, visualization and easy customization
- ▶ adaptive local/global transition kernels, distances, acceptance threshold schedules, population sizes, early rejection, ...



user-friendly



scalable



flexible

# pyABC

Three lines get you started

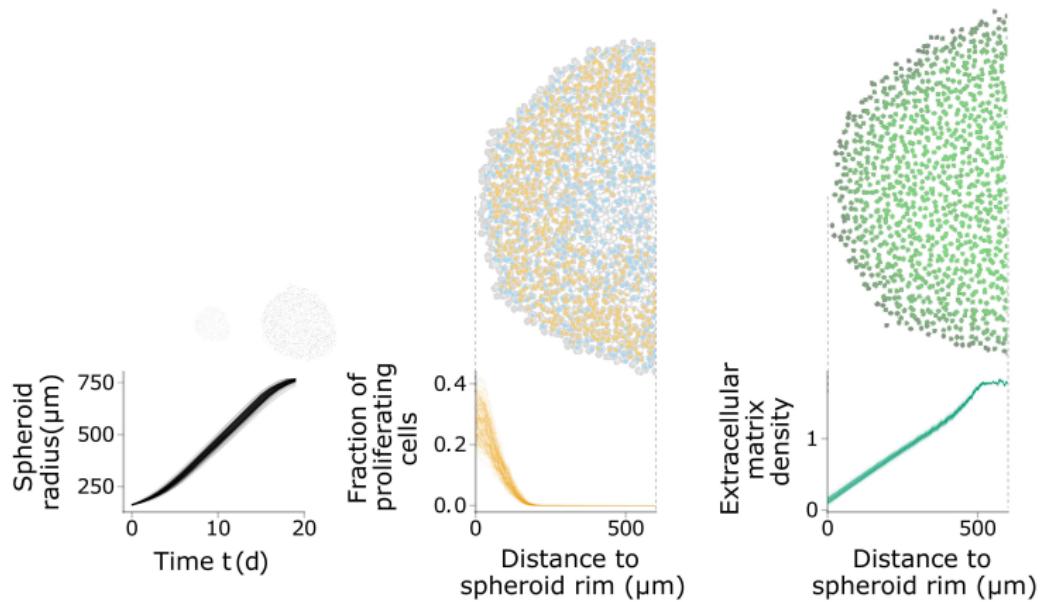
```
# pass model data
abc = pyabc.ABCSMC(model, prior, distance)

# pass observations
abc.new("sqlite:///database.db", observations)

# run it
abc.run(minimum_epsilon=1e-2, max_nr_populations=30)
```

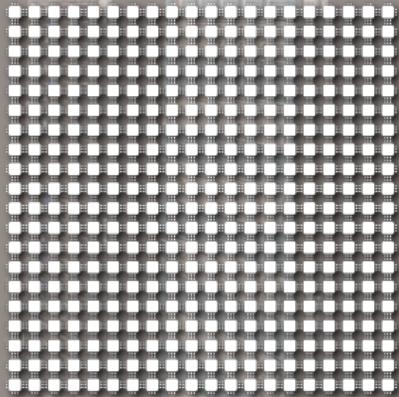
# Multi-scale model of tumor growth

## Summary statistics



Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

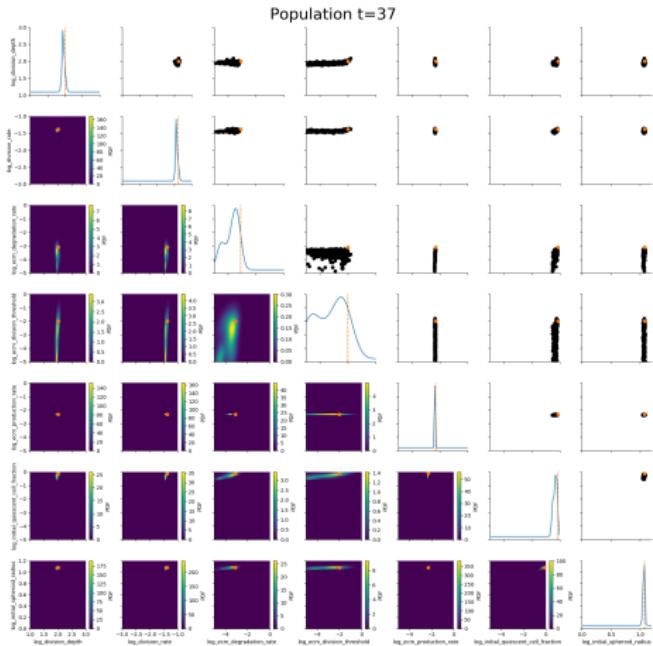
# Multi-scale model of tumor growth



- ▶ 400 cores
- ▶ 3 days
- ▶ 1.8e6 simulations

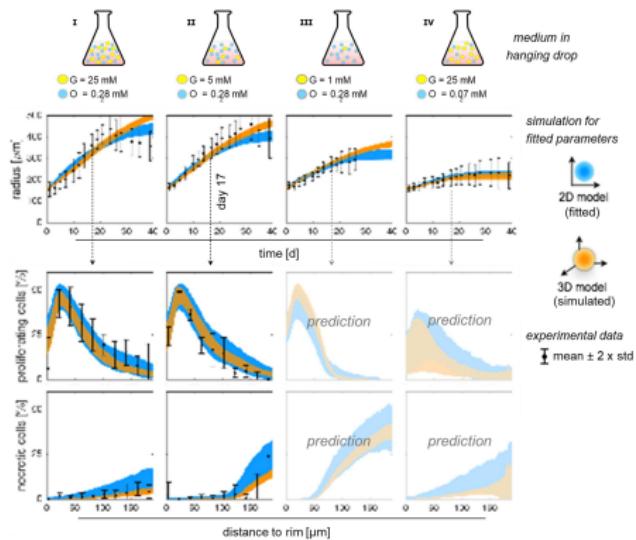
# Multi-scale model of tumor growth

# Multi-scale model of tumor growth



ABC worked where many other methods had failed.

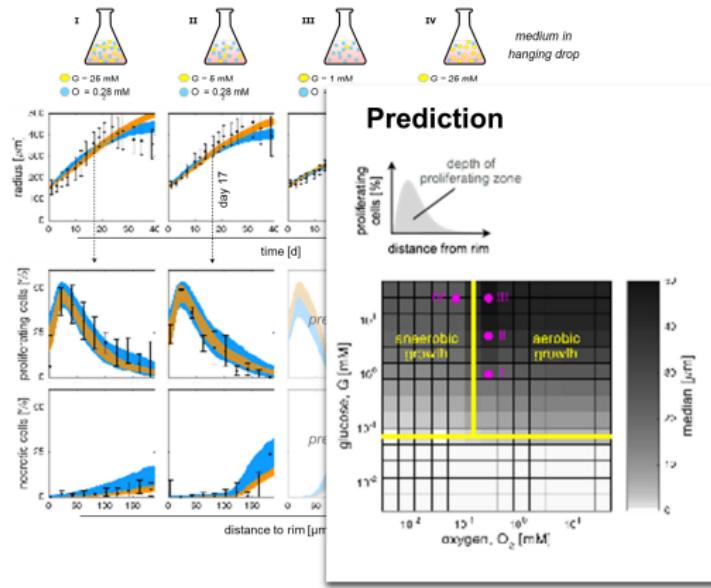
# Multi-scale model of tumor growth



ABC enables automatic multi-experiment data integration.

Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

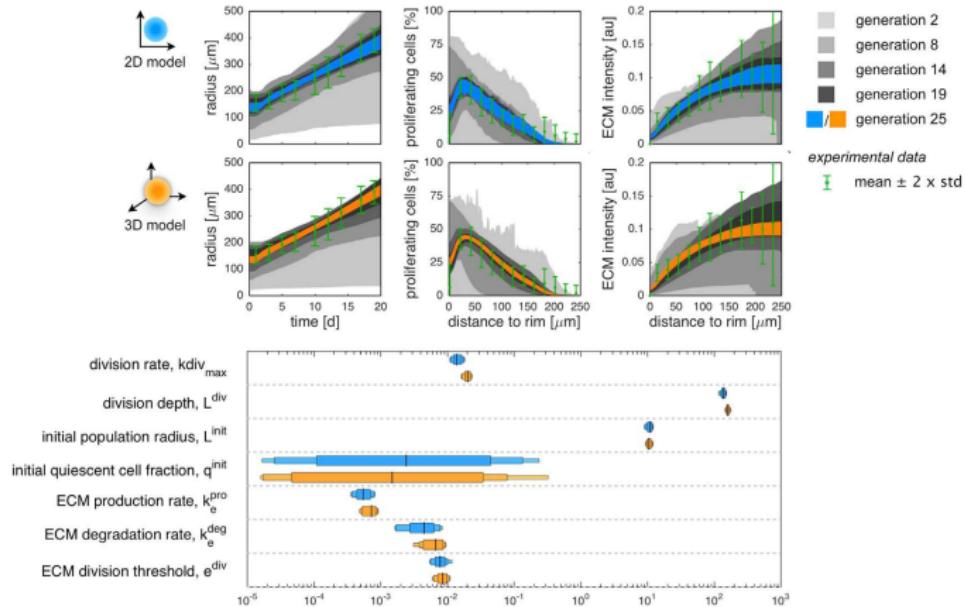
# Multi-scale model of tumor growth



ABC enables uncertainty-aware predictions.

Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

# Multi-scale model of tumor growth

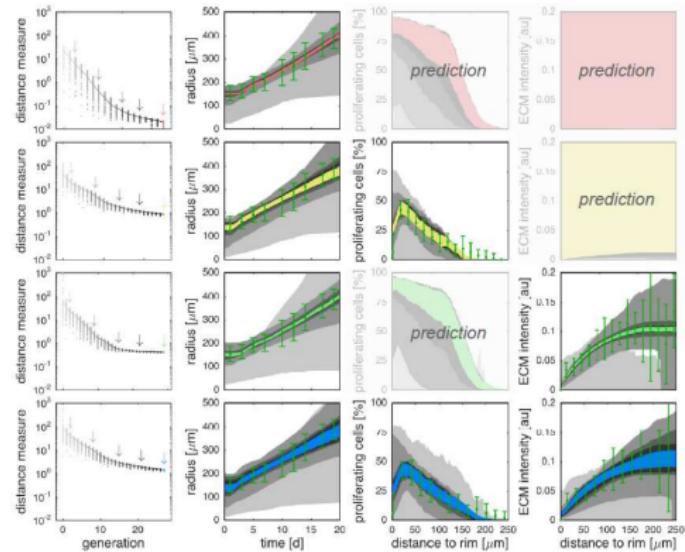


ABC enables hypothesis testing.

Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

# Multi-scale model of tumor growth

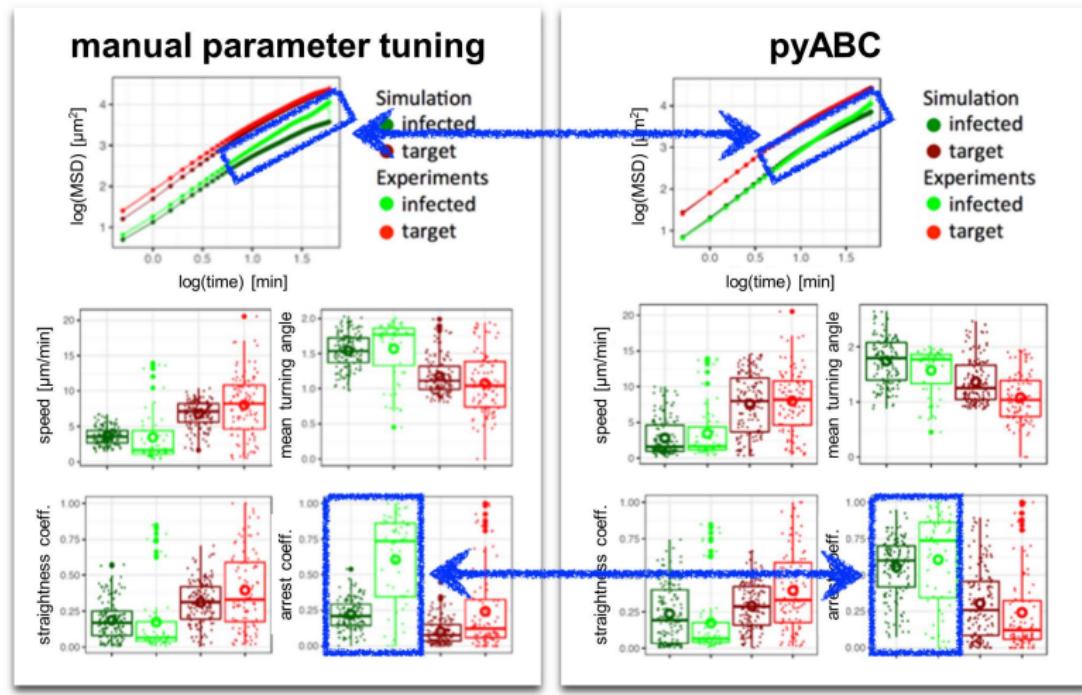
What data do I need?



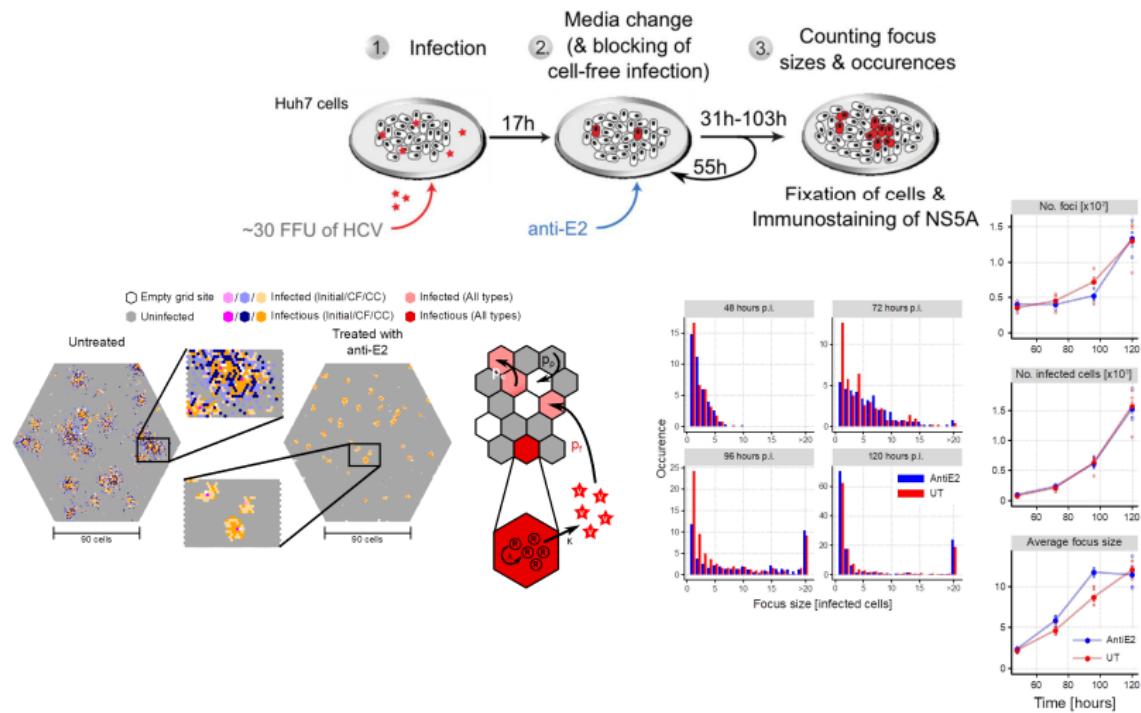
ABC enables experimental design.

Jagiella et al.; Parallelization and high-performance computing enables automated statistical inference of multi-scale models; Cell Systems; 2017

# Analysis of HIV infection dynamics



# Comparing HCV transmission modes



with Elba Raimández-Álvarez, Peter Kumberger

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# Conclusion

- ▶ parameter estimation when we cannot evaluate the likelihood is challenging
- ▶ ABC enables reliable statistical inference with uncertainty information
- ▶ samples from an approximation of the true posterior
- ▶ broadly applicable
- ▶ scalable
- ▶ increasingly popular in many research areas
- ▶ not a silver bullet – if possible, use (sufficiently good approximations of) likelihoods

# Conclusion

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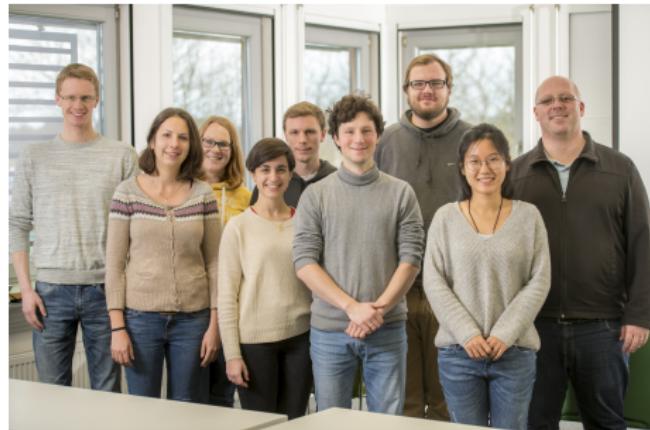


Not everything is a nail.

# Acknowledgments

Thanks to:

- ▶ Elba Raimúndez Álvarez
- ▶ Emmanuel Klinger
- ▶ Dennis Rickert
- ▶ Jan Hasenauer
- ▶ Rest of the ICB-DCM group



## Further reading

-  Sisson, Scott A. and Fan, Yanan and Beaumont, Mark  
*Handbook of Approximate Bayesian Computation.*  
CRC Press, 2018.
-  Beaumont, Mark A.  
Approximate Bayesian Computation in Evolution and Ecology.  
*Annual Review of Ecology, Evolution, and Systematics*,  
41(1):379–406, 2010.
-  Blum M. G.  
Choosing the Summary Statistics and the Acceptance Rate in  
Approximate Bayesian Computation.  
*Proceedings of COMPSTAT, Physica*, 2010.

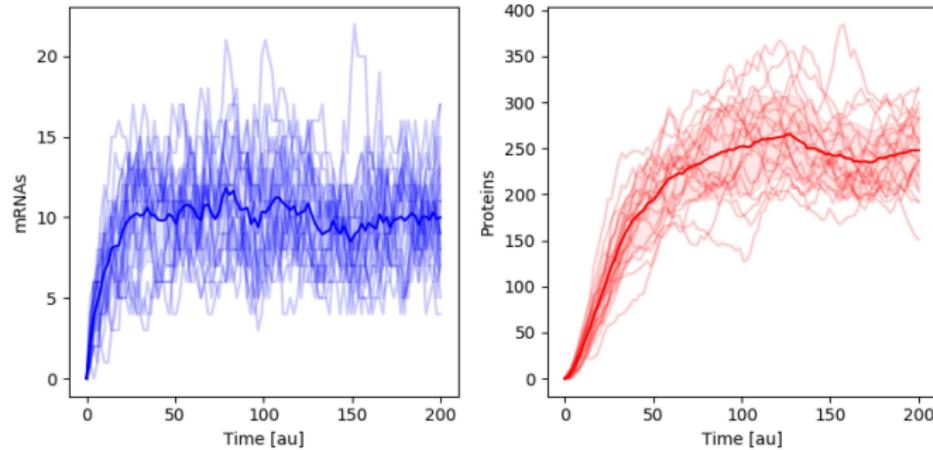
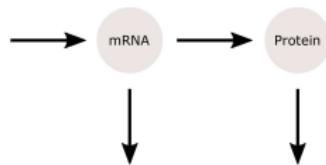
# ABC-MCMC

Combine with a Markov-Chain Monte-Carlo Scheme

initialize some  $\theta_0$  and simulate  $y_0 \sim \pi(y|\theta_0)$   
until enough acceptances

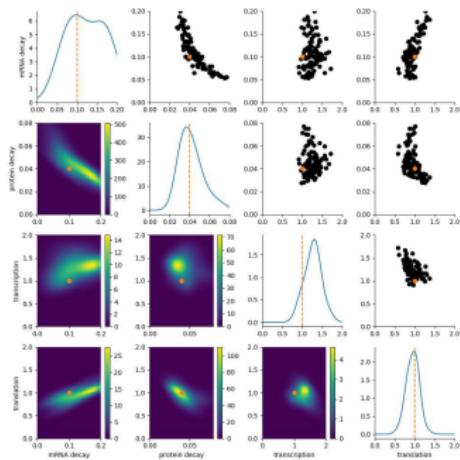
1. sample  $\theta^* \sim g(\theta|\theta_{n-1})$
2. simulate  $y^* \sim \pi(y|\theta^*)$
3. calculate  $\alpha = \min \left[ 1, \frac{\pi(\theta^*)g(\theta^*|\theta_{n-1})I(\{d(s(y^*), s(y_{obs})) \leq \varepsilon\})}{\pi(\theta_{n-1})g(\theta_{n-1}|\theta^*)I(\{d(s(y_{n-1}), s(y_{obs})) \leq \varepsilon\})} \right]$
4. accept with probability  $\alpha$  and update  $\theta_n = \theta^*, y_n = y^*$

## Example: Gene expression

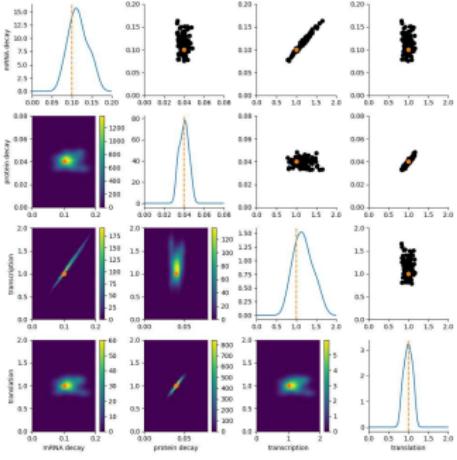


# Example: Gene expression

only protein counts

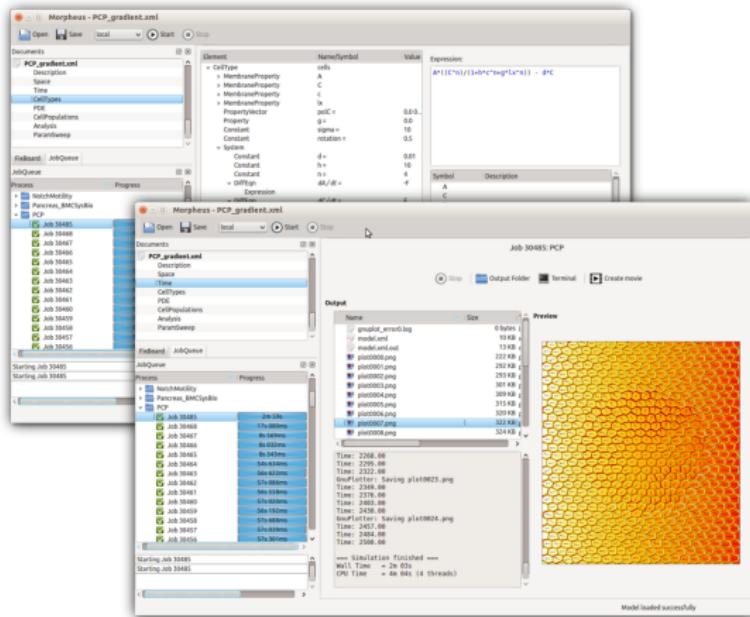


mRNA and protein counts



# Model construction using Morpheus

<https://morpheus.gitlab.io>



Staruss et al.; Morpheus: a user-friendly modeling environment for multiscale and multicellular systems biology; Bioinformatics; 2014