

# 35241 OQM

## Lecture Note – Part 4

### Big- $M$ Method and Two-Phase Simplex Method

#### 1 Initial Basic Feasible Solution

Recall that performing the Simplex algorithm requires an initial basic feasible solution (bfs). All the LP problems we have solved so far are those with  $\leq$  constraints and  $\mathbf{b} \geq \mathbf{0}$ , and hence we have found an initial bfs easily by using the slack variables as the initial basic variables. In other words, an initial bfs is obvious in the considered LP in standard form. Provided that we are faced with LPs involving any  $\geq$  or equality constraint in general form, however, an initial bfs may not be readily apparent in standard form. The examples demonstrated in the following sections will illustrate that an initial bfs may be difficult to find. When a starting bfs is by no means obvious, the Big- $M$  method or the two-phase Simplex method could be exploited to solve the problem.

#### 2 The Big- $M$ Method<sup>1</sup>

In this section, we discuss the Big- $M$  method, a version of the Simplex algorithm that first finds an initial bfs by introducing dummy variables into the LP involving the  $\geq$  or equality constraint(s) in general form. The objective function of the original LP must, of course, be modified to ensure that the dummy variables are all equal to 0 at the conclusion of the Simplex algorithm. The following example illustrates the Big- $M$  method.

---

<sup>1</sup>Section 4.12 in the reference book “Operations Research: Applications and Algorithms” (Winston, 2004)

### Example 1

$$\begin{aligned}\min z = & 2x_1 + 3x_2 \\ \text{s.t. } & \frac{1}{2}x_1 + \frac{1}{4}x_2 \leq 4 \\ & x_1 + 3x_2 \geq 20 \\ & x_1 + x_2 = 10 \\ & x_1, x_2 \geq 0.\end{aligned}$$

To put the general form into standard form, we add a slack variable  $s_1$  to the first constraint and subtract an excess/surplus variable  $e_2$  from the second constraint.

$$\begin{aligned}\min z = & 2x_1 + 3x_2 \\ \text{s.t. } & \frac{1}{2}x_1 + \frac{1}{4}x_2 + s_1 = 4 \\ & x_1 + 3x_2 - e_2 = 20 \\ & x_1 + x_2 = 10 \\ & x_1, x_2, s_1, e_2 \geq 0.\end{aligned}\tag{1}$$

In searching for an initial bfs, we see that  $s_1 = 4$  could be used as a basic (and feasible) variable for the row-1 equation. If we multiply row 2 by  $-1$ , we see that  $e_2 = -20$  could be used as a basic variable for row 2. Unfortunately,  $e_2 = -20$  violates the sign restriction  $e_2 \geq 0$ . Finally, in row 3 there is no readily apparent basic variable.<sup>2</sup> Thus, in order to use the Simplex method, each of rows 2 and 3 needs a basic variable which is feasible. To remedy this problem, we simply “invent” a basic feasible variable for each equation that needs one. Since these variables are created and are not real variables existing in the standard form of the original LP, we call them *artificial variables*. If an artificial variable is added to row  $i$ , we label it  $a_i$ . In the considered LP, we need to add an artificial variable  $a_2$  to row 2 and an artificial variable  $a_3$  to row 3. The resulting canonical form is

$$\begin{aligned}\min z = & 2x_1 + 3x_2 \\ \text{s.t. } & \frac{1}{2}x_1 + \frac{1}{4}x_2 + s_1 = 4 \\ & x_1 + 3x_2 - e_2 + a_2 = 20 \\ & x_1 + x_2 + a_3 = 10 \\ & x_1, x_2, s_1, e_2, a_2, a_3 \geq 0.\end{aligned}\tag{2}$$

We now have a bfs:  $s_1 = 4, a_2 = 20, a_3 = 10$ . Unfortunately, there is no guarantee that the optimal solution to (2) will be the same as the optimal

---

<sup>2</sup>Notice that row 3 does not satisfy the requirement of the canonical form.

solution to (1). In solving (2), we might obtain an optimal solution in which one or more artificial variables are positive. Such a solution may not be feasible in (1). For example, in solving (2), the optimal solution may easily be shown to be  $s_1 = 4, a_2 = 20, a_3 = 10, x_1 = x_2 = e_2 = 0$ . This “solution” obviously cannot possibly solve our original LP problem! To guarantee that the optimal solution to (2) is to solve (1), we must make sure that the optimal solution to (2) sets all artificial variables equal to zero. In a minimisation problem, we can ensure that all the artificial variables will be zero by adding a term  $Ma_i$  to the objective function for each artificial variable  $a_i$ . (In a maximisation problem, add a term  $-Ma_i$  to the objective function.) Here  $M$  represents a “very large” positive number. Thus, we can amend (2) and have

$$\begin{aligned}
 \min z = & 2x_1 + 3x_2 + Ma_2 + Ma_3 \\
 \text{s.t. } & \frac{1}{2}x_1 + \frac{1}{4}x_2 + s_1 = 4 \\
 & x_1 + 3x_2 - e_2 + a_2 = 20 \\
 & x_1 + x_2 + a_3 = 10 \\
 & x_1, x_2, s_1, e_2, a_2, a_3 \geq 0.
 \end{aligned} \tag{3}$$

Rectifying the objective function in this way makes it extremely costly for an artificial variable to be positive. With this modified objective function, it seems reasonable that the optimal solution to (3) will have  $a_2 = a_3 = 0$ . In this case, the optimal solution to (3) will solve the original standard form (1). It sometimes happens, however, that in solving (3), some of the artificial variables may assume positive values in the optimal solution. If this occurs, the original problem has no feasible solution. For obvious reasons, the method we have just outlined is often called the Big- $M$  method.

Now we give the formal description of the Big- $M$  method.

- Step 1. Modify the constraints so that the rhs of each constraint is nonnegative. This requires that each constraint with a negative rhs be multiplied through by  $-1$ .<sup>3</sup>
- Step 2. Convert the system of constraints to standard form, i.e. add a slack variable  $s_i$  in the lhs of each  $\leq$  constraint and subtract an excess variable  $e_i$  from the lhs of each  $\geq$  constraint.

---

<sup>3</sup>Remember that if you multiply an inequality by any negative number, the direction of the inequality is reversed. For example, we would transform the inequality  $x_1 + x_2 \geq -1$  into  $-x_1 - x_2 \leq 1$ . The inequality  $x_1 - x_2 \leq -2$  would be transformed into  $-x_1 + x_2 \geq 2$ .

- Step 3. For each constraint without a slack variable  $s_i$ , add an artificial variable  $a_i$  in the lhs. Also add the sign restriction  $a_i \geq 0$ .
- Step 4. Let  $M$  denote a very large positive number. If the LP is a min problem, add (for each artificial variable)  $Ma_i$  to the objective function. If the LP is a max problem, add (for each artificial variable)  $-Ma_i$  to the objective function.
- Step 5. Because each artificial variable will be in the initial basis, all artificial variables must be eliminated from row 0 to make a canonical form before beginning the Simplex procedure. The choice of the entering variable depends on the multiplier of  $M$  since  $M$  is a very large positive number. For example,  $4M - 2$  is more positive than  $3M + 900$ , and  $-6M + 5$  is more negative than  $-5M - 40$ . Now solve the transformed problem by the Simplex method. If all artificial variables are equal to zero in the optimal solution, then we have found the optimal solution to the original LP. If any artificial variables are positive in the optimal solution, then the original problem is infeasible.<sup>4</sup>

When an artificial variable leaves the basis, its column may be dropped from future tableaux because the purpose of an artificial variable is only to get an initial bfs. Once an artificial variable leaves the basis, we no longer need it.<sup>5</sup>

Now we resume solving the modified LP (3), which actually can be obtained by going through Steps 1–4. Going to Step 5, we first rearrange row 0,

$$z - 2x_1 - 3x_2 - Ma_2 - Ma_3 = 0,$$

to satisfy the canonical form. Because  $a_2$  and  $a_3$  are in the initial bfs, they must be eliminated from row 0. To eliminate  $a_2$  and  $a_3$  from row 0, simply replace row 0 by row 0 +  $M$ (row 2) +  $M$ (row 3). This yields the new row 0:

$$z + (2M - 2)x_1 + (4M - 3)x_2 - Me_2 = 30M.$$

---

<sup>4</sup>We have ignored the possibility that when the modified LP (with the artificial variables) is solved, the final tableau may indicate that the LP is unbounded. If the final tableau indicates the LP is unbounded and all artificial variables in this tableau equal zero, then the original LP is unbounded. If the final tableau indicates that the LP is unbounded and at least one artificial variable is positive, then the original LP is infeasible.

<sup>5</sup>Despite this fact, we will maintain the artificial variables in all tableaux when doing Primal-Dual transformation which will be introduced in the following chapters.

Combining the new row 0 with rows 1–3 yields the initial tableau shown below.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	ratio test
$z$	$2M - 2$	$4M - 3$	0	$-M$	0	0	$30M$	
$s_1$	$\frac{1}{2}$	$\frac{1}{4}$	1	0	0	0	4	$\frac{4}{(\frac{1}{4})} = 16$
$a_2$	1	<span style="border: 1px solid black; padding: 0 2px;">3</span>	0	$-1$	1	0	20	$\frac{20}{3}^*$
$a_3$	1	1	0	0	0	1	10	$\frac{10}{1} = 10$

We are solving a min problem, so the variable with the most positive coefficient in row 0 should enter the basis. Because  $4M > 2M$ , variable  $x_2$  should enter the basis. The ratio test indicates that  $x_2$  should enter the basis in row 2, which means the artificial variable  $a_2$  will leave the current basis. The most difficult part of doing the pivot is eliminating  $x_2$  from row 0. First, replace row 2 by  $\frac{1}{3}(\text{row 2})$ . Thus, the new row 2 is

$$\frac{1}{3}x_1 + x_2 - \frac{1}{3}e_2 + \frac{1}{3}a_2 = \frac{20}{3}.$$

We can now eliminate  $x_2$  from row 0 by adding  $-(4M - 3)(\text{new row 2})$  to row 0. Then we have the new row 0:

$$z + \frac{2M-3}{3}x_1 + \frac{M-3}{3}e_2 + \frac{3-4M}{3}a_2 = \frac{10M+60}{3}.$$

After using EROs to eliminate  $x_2$  from row 1 and row 3 as well, we obtain the following tableau.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	ratio test
$z$	$\frac{2M-3}{3}$	0	0	$\frac{M-3}{3}$	$\frac{3-4M}{3}$	0	$\frac{10M+60}{3}$	
$s_1$	$\frac{5}{12}$	0	1	$\frac{1}{12}$	$-\frac{1}{12}$	0	$\frac{7}{3}$	$\frac{(\frac{7}{3})}{(\frac{5}{12})} = \frac{28}{5}$
$x_2$	$\frac{1}{3}$	1	0	$-\frac{1}{3}$	$\frac{1}{3}$	0	$\frac{20}{3}$	$\frac{(\frac{20}{3})}{(\frac{1}{3})} = 20$
$a_3$	<span style="border: 1px solid black; padding: 0 2px;"><math>\frac{2}{3}</math></span>	0	0	$\frac{1}{3}$	$-\frac{1}{3}$	1	$\frac{10}{3}$	$\frac{(\frac{10}{3})}{(\frac{2}{3})} = 5^*$

Because  $\frac{2M}{3} > \frac{M}{3}$ , we next enter  $x_1$  into the basis. The ratio test indicates that  $a_3$  in the third row shall leave the current basis. Then our next tableau will have  $a_2 = a_3 = 0$ . After the similar EROs, we have the following new tableau.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs
$z$	0	0	0	$-\frac{1}{2}$	$\frac{1-2M}{2}$	$\frac{3-2M}{2}$	25
$s_1$	0	0	1	$-\frac{1}{8}$	$\frac{1}{8}$	$-\frac{5}{8}$	$\frac{1}{4}$
$x_2$	0	1	0	$-\frac{1}{2}$	$\frac{1}{2}$	$-\frac{1}{2}$	5
$x_1$	1	0	0	$\frac{1}{2}$	$-\frac{1}{2}$	$\frac{3}{2}$	5

Because all variables in row 0 have nonpositive coefficients, this is an optimal tableau; all artificial variables are equal to zero in this tableau, so we have found the optimal solution to the original LP problem:  $x_1 = 5, x_2 = 5, s_1 = \frac{1}{4}, e_2 = 0$  with  $z_{\min} = 25$ . Note that to obtain this optimal solution the  $a_2$  column could have been dropped after  $a_2$  left the basis (at the conclusion of the first pivot), and the  $a_3$  column could have been dropped after  $a_3$  left the basis (at the conclusion of the second pivot).

Now let's consider another example, which is obtained by modifying Example 1.

### **Example 2**

$$\begin{aligned}
\min z = & 2x_1 + 3x_2 \\
s.t. & \frac{1}{2}x_1 + \frac{1}{4}x_2 \leq 4 \\
& x_1 + 3x_2 \geq 36 \\
& x_1 + x_2 = 10 \\
& x_1, x_2 \geq 0.
\end{aligned}$$

After going through Steps 1–5 of the Big- $M$  method, we obtain the initial tableau below.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	ratio test
$z$	$2M - 2$	$4M - 3$	0	$-M$	0	0	$46M$	
$s_1$	$\frac{1}{2}$	$\frac{1}{4}$	1	0	0	0	4	$\frac{4}{(\frac{1}{4})} = 16$
$a_2$	1	3	0	$-1$	1	0	36	$\frac{36}{3} = 12$
$a_3$	1	<span style="border: 1px solid black; padding: 2px;">1</span>	0	0	0	1	10	$\frac{10}{1} = 10^*$

Because  $4M \geq 2M$ , we enter  $x_2$  into the basis. The ratio test indicates that  $x_2$  should be entered in row 3, causing  $a_3$  to leave the basis. After entering  $x_2$  into the basis, we obtain the tableau as follows.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs
$z$	$1 - 2M$	0	0	$-M$	0	$3 - 4M$	$6M + 30$
$s_1$	$\frac{1}{4}$	0	1	0	0	$-\frac{1}{4}$	$\frac{3}{2}$
$a_2$	-2	0	0	-1	1	-3	6
$x_2$	1	1	0	0	0	1	10

Because each variable has a nonpositive coefficient in row 0, this is an optimal tableau. The optimal solution indicated by this tableau is  $s_1 = \frac{3}{2}, a_2 = 6, x_2 = 10, a_3 = e_2 = x_1 = 0$  with  $z_{\min} = 6M + 30$ . The artificial variable  $a_2$  is positive in the optimal tableau, so Step 5 shows that the original LP has no feasible solution. In summary, if any artificial variable is positive in the optimal Big- $M$  tableau, then the original LP has no feasible solution. Note that when the Big- $M$  method is used, it is difficult to determine how large  $M$  should be. Generally,  $M$  is chosen to be at least 100 times larger than the largest coefficient in the original objective function. The introduction of such large numbers into the problem can cause round-off errors and other computational difficulties. For this reason, most computer codes solve LPs by using the two-phase Simplex method.

### 3 The Two-Phase Simplex Method<sup>6</sup>

When a bfs is not readily available, the two-phase Simplex method can be used as an alternative to the Big- $M$  method. The idea of this method is to solve an auxiliary LP to get an initial bfs for the original LP in Phase I, and then switch back to the original LP in Phase II. In the two-phase Simplex method, we add artificial variables to the same constraints as we did in the Big- $M$  method. Then we find a bfs to the original LP by solving the Phase-I auxiliary LP. In the Phase-I LP, the objective function is to minimise the sum

---

<sup>6</sup>Section 4.13 in the reference book “Operations Research: Applications and Algorithms” (Winston, 2004)

of all artificial variables. At the completion of Phase I, we reintroduce the original LP's objective function and determine the optimal solution to the original LP in Phase II. The following steps describe the two-phase Simplex method. Note that steps 1–3 for the two-phase Simplex are identical to those for the Big- $M$  method.

- Step 1. Modify the constraints so that the rhs of each constraint is nonnegative. This requires that each constraint with a negative rhs be multiplied through by  $-1$ .
- Step 2. Convert the system of constraints to standard form, i.e. add a slack variable  $s_i$  in the lhs of each  $\leq$  constraint and subtract an excess variable  $e_i$  from the lhs of each  $\geq$  constraint.
- Step 3. For each constraint without a slack variable  $s_i$ , add an artificial variable  $a_i$  in the lhs. Also add the sign restriction  $a_i \geq 0$ .
- Step 4. For now, ignore the original LP's objective function. Instead solve an LP with an objective function “min  $w =$  (sum of all the artificial variables)”. This is called the *Phase-I LP*. The act of solving the Phase-I LP will force the artificial variables to be zero. Because each  $a_i \geq 0$ , solving the Phase-I LP will result in one of the following three cases:

- Case 1. The optimal objective value  $w_{\min} > 0$ :  
In this case, the original LP has no feasible solution.
- Case 2. The optimal objective value  $w_{\min} = 0$  and no artificial variables existing in the optimal Phase-I basis<sup>7</sup>:  
In this case, we drop all columns in the optimal Phase-I tableau that correspond to the artificial variables.<sup>8</sup> Then combine the original objective function with the constraints from the modified optimal Phase-I tableau. This yields the *Phase II-LP*. An optimal solution to the Phase-II LP is an optimal solution to the original LP.

---

<sup>7</sup>Actually, if no artificial variables exist in the Phase-I basis  $\mathbf{x}_B$ , we certainly have the corresponding objective value  $w_{\min} = 0$  due to the row-0 rhs  $\mathbf{c}_B^T \mathbf{B}^{-1} \mathbf{b}$ .

<sup>8</sup>All the artificial variables have completed their missions.



Case 3. The optimal objective value  $w_{\min} = 0$  and at least one artificial variable remaining in the optimal Phase-I basis<sup>9</sup>:

In this case, we can find an optimal solution to the original LP by dropping from the optimal Phase-I tableau the columns corresponding to the nonbasic artificial variables and the non-artificial variables that have negative coefficients in row 0 (i.e. by eliminating all the columns corresponding to nonbasic artificial variables<sup>10</sup> or having negative reduced costs), and reintroducing the original objective function to form the Phase II-LP.

In Phase I, we deal with a relaxed problem where the artificial variables are allowed to be “ $\geq 0$ ” instead of requiring them to be 0. We will find it easy to get a bfs of the relaxed problem. But what we actually want is to get a bfs of the original LP. In any feasible solution of the Phase-I relaxed problem, the objective function value  $w \geq 0$ . If we can make  $w = 0$ , the artificial variables will be 0 and the solution will be feasible for the original LP. So in Phase I we have the objective to minimise  $w$ .

An interesting point is “Why can we eliminate all the columns corresponding to the non-artificial variables with negative reduced costs in Case 3?”. Then “why not do the same elimination in Case 2 as well?” The explanation will be given in the following examples. Now we consider the first example in the previous section.

### Example 1

$$\begin{aligned} \min z = & 2x_1 + 3x_2 \\ \text{s.t.} \quad & \frac{1}{2}x_1 + \frac{1}{4}x_2 \leq 4 \\ & x_1 + 3x_2 \geq 20 \\ & x_1 + x_2 = 10 \\ & x_1, x_2 \geq 0 \end{aligned}$$

As in the Big- $M$  method, Steps 1–3 transform the constraints into

$$\begin{aligned} \frac{1}{2}x_1 + \frac{1}{4}x_2 + s_1 &= 4 \\ x_1 + 3x_2 - e_2 + a_2 &= 20 \\ x_1 + x_2 + a_3 &= 10 \\ x_1, x_2, s_1, e_2, a_2, a_3 &\geq 0. \end{aligned}$$

---

<sup>9</sup>But the artificial variable(s) remaining in the Phase-I basis are certainly equal to zeros since  $w =$  (sum of all the artificial variables).

<sup>10</sup>The basic artificial variable(s) cannot be removed since they will be part of the initial basis in the Phase II-LP, i.e. they have not accomplished their missions yet.

Then Step 4 yields the following Phase-I LP:

$$\begin{array}{llllll} \min w = & & & & a_2 & + & a_3 \\ s.t. & \frac{1}{2}x_1 & + & \frac{1}{4}x_2 & + & s_1 & = & 4 \\ & x_1 & + & 3x_2 & & - & e_2 & + & a_2 & = & 20 \\ & x_1 & + & x_2 & & & & & + & a_3 & = & 10 \\ & x_1, x_2, s_1, e_2, a_2, a_3 \geq 0. & & & & & & & & & \end{array}$$

We have an obvious initial bfs ( $s_1 = 4, a_2 = 20, a_3 = 10$ ) for Phase I and thus can generate the initial tableau.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs
$w$	0	0	0	0	-1	-1	0
$s_1$	$\frac{1}{2}$	$\frac{1}{4}$	1	0	0	0	4
$a_2$	1	3	0	-1	1	0	20
$a_3$	1	1	0	0	0	1	10

Note, however, that we still need to eliminate  $a_2$  and  $a_3$  in row 0 to satisfy the canonical form. So the first step in Phase I is always to get rid of the coefficients  $-1$  in row 0 (above the artificial variables) by adding all rows corresponding to artificial variables, which are row 2 and row 3 in this case, to row 0. Then We obtain the following new tableau.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	
$w$	2	4	0	-1	0	0	30	$R'_0 \leftarrow R_0 + R_2 + R_3$
$s_1$	$\frac{1}{2}$	$\frac{1}{4}$	1	0	0	0	4	
$a_2$	1	3	0	-1	1	0	20	
$a_3$	1	1	0	0	0	1	10	

The obtained tableau satisfies the conditions: There exists the identity matrix with all corresponding reduced costs being zeros, and the rhs vector is nonnegative.

Now we can proceed with Simplex procedure. Since Phase-I LP is always a minimisation problem, we choose the entering variable by looking for the

nonbasic variable with the most positive reduced cost. So  $x_2$  will be entered into the new basis. By the ratio test, the second component of the basic,  $a_2$ , is leaving.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	ratio test
$w$	2	4	0	-1	0	0	30	
$s_1$	$\frac{1}{2}$	$\frac{1}{4}$	1	0	0	0	4	$\frac{4}{(\frac{1}{4})} = 16$
$a_2$	1	<span style="border: 1px solid black; padding: 0 2px;">3</span>	0	-1	1	0	20	$\frac{20}{3}^*$
$a_3$	1	1	0	0	0	1	10	$\frac{10}{1} = 10$

Then the pivoting process leads to the following new tableau.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	
$w$	$\frac{2}{3}$	0	0	$\frac{1}{3}$	$-\frac{4}{3}$	0	$\frac{10}{3}$	$R_0'' \leftarrow R_0' - 4R_2''$
$s_1$	$\frac{5}{12}$	0	1	$\frac{1}{12}$	$-\frac{1}{12}$	0	$\frac{7}{3}$	$R_1'' \leftarrow R_1' - \frac{1}{4}R_2''$
$x_2$	$\frac{1}{3}$	1	0	$-\frac{1}{3}$	$\frac{1}{3}$	0	$\frac{20}{3}$	$R_2'' \leftarrow \frac{1}{3}R_2'$
$a_3$	$\frac{2}{3}$	0	0	$\frac{1}{3}$	$-\frac{1}{3}$	1	$\frac{10}{3}$	$R_3'' \leftarrow R_3' - R_2''$

There still exist some positive reduced costs in the current tableau, so the Simplex procedure must be continued.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs	ratio test
$w$	$\frac{2}{3}$	0	0	$\frac{1}{3}$	$-\frac{4}{3}$	0	$\frac{10}{3}$	
$s_1$	$\frac{5}{12}$	0	1	$\frac{1}{12}$	$-\frac{1}{12}$	0	$\frac{7}{3}$	$\frac{28}{5}$
$x_2$	$\frac{1}{3}$	1	0	$-\frac{1}{3}$	$\frac{1}{3}$	0	$\frac{20}{3}$	20
$a_3$	<span style="border: 1px solid black; padding: 0 2px;"><math>\frac{2}{3}</math></span>	0	0	$\frac{1}{3}$	$-\frac{1}{3}$	1	$\frac{10}{3}$	$5^*$

Again, we need to enter  $x_1$  and leave  $a_3$ , and do the pivoting. Then the following Simplex tableau is yielded.

basis	$x_1$	$x_2$	$s_1$	$e_2$	$a_2$	$a_3$	rhs
$w$	0	0	0	0	-1	-1	0
$s_1$	0	0	1	$-\frac{1}{8}$	$\frac{1}{8}$	$-\frac{5}{8}$	$\frac{1}{4}$
$x_2$	0	1	0	$-\frac{1}{2}$	$\frac{1}{2}$	$-\frac{1}{2}$	5
$x_1$	1	0	0	$\frac{1}{2}$	$-\frac{1}{2}$	$\frac{3}{2}$	5

Now all reduced costs are nonpositive, so it is the final optimal Phase-I tableau. Since we have  $w_{\min} = 0$  and the optimal basis  $(s_1, x_2, x_1) = (\frac{1}{4}, 5, 5)$ , i.e. no artificial variables are in the optimal Phase-I basis, the problem is an example of Case 2. We now drop the columns for the artificial variables  $a_2$  and  $a_3$  (we no longer need them) and reintroduce the original objective “ $\min z = 2x_1 + 3x_2$ ” to generate the Phase-II tableau as follows.

basis	$x_1$	$x_2$	$s_1$	$e_2$	rhs
$z$	-2	-3	0	0	0
$s_1$	0	0	1	$-\frac{1}{8}$	$\frac{1}{4}$
$x_2$	0	1	0	$-\frac{1}{2}$	5
$x_1$	1	0	0	$\frac{1}{2}$	5

Again, before performing Simplex procedure we need to do some EROs for row 0 to make the canonical form as follows.

basis	$x_1$	$x_2$	$s_1$	$e_2$	rhs	
$z$	0	0	0	$-\frac{1}{2}$	25	$R'_0 \leftarrow R_0 + 3R_2 + 2R_3$
$s_1$	0	0	1	$-\frac{1}{8}$	$\frac{1}{4}$	
$x_2$	0	1	0	$-\frac{1}{2}$	5	
$x_1$	1	0	0	$\frac{1}{2}$	5	

Since none of the reduced costs is positive, this Simplex tableau is the final one. So the optimal solution of the original LP in standard form is

$$(x_1, x_2, s_1, e_2) = (5, 5, \frac{1}{4}, 0)$$

with  $z_{\min} = 25$ .

### Example 2

$$\begin{array}{ll} \max z = & 4x_1 + 5x_2 \\ \text{s.t.} & 2x_1 + 3x_2 \leq 6 \\ & 3x_1 + x_2 \geq 3 \\ & x_1, x_2 \geq 0 \end{array}$$

We first convert the general form to standard form<sup>11</sup>:

$$\begin{array}{llll} \max z = & 4x_1 + 5x_2 & & \\ \text{s.t.} & 2x_1 + 3x_2 + x_3 & = & 6 \\ & 3x_1 + x_2 & - x_4 & = 3 \\ & x_1, x_2, x_3, x_4 & \geq & 0 \end{array}$$

Then for the second constraint, we need to introduce an artificial variable  $a_1$  since  $x_4$  cannot be a part of the initial bfs.

The Phase-I LP is shown as follows:

$$\begin{array}{llll} \min w = & & & a_1 \\ \text{s.t.} & 2x_1 + 3x_2 + x_3 & = & 6 \\ & 3x_1 + x_2 & - x_4 + a_1 & = 3 \\ & x_1, x_2, x_3, x_4, a_1 & \geq & 0 \end{array}$$

Choose  $(x_3, a_1) = (6, 3)$  as the initial basis and draw up the following tableau:

basis	$x_1$	$x_2$	$x_3$	$x_4$	$a_1$	rhs
$w$	0	0	0	0	-1	0
$x_3$	2	3	1	0	0	6
$a_1$	3	1	0	-1	1	3

Get rid of the coefficients  $-1$  in row 0 above  $a_1$  by adding row 2 to row 0.

---

<sup>11</sup>Notice that the notation used for slack or excess variables is flexible.

basis	$x_1$	$x_2$	$x_3$	$x_4$	$a_1$	rhs	
$w$	3	1	0	-1	0	3	$R'_0 \leftarrow R_0 + R_2$
$x_3$	2	3	1	0	0	6	
$a_1$	3	1	0	-1	1	3	

Now we can progress with the Simplex method. Choose the most positive reduced cost to determine the entering variable, and find the leaving variable using the ratio test as follows.

basis	$x_1$	$x_2$	$x_3$	$x_4$	$a_1$	rhs	ratio test
$w$	3	1	0	-1	0	3	
$x_3$	2	3	1	0	0	6	$\frac{6}{2} = 3$
$a_1$	<span style="border: 1px solid black;">3</span>	1	0	-1	1	3	$\frac{3}{3} = 1^*$

Entering  $x_1$  and leaving  $a_1$ , we do the pivoting and have the following new tableau.

basis	$x_1$	$x_2$	$x_3$	$x_4$	$a_1$	rhs
$w$	0	0	0	0	-1	0
$x_3$	0	$\frac{7}{3}$	1	$\frac{2}{3}$	$-\frac{2}{3}$	4
$x_1$	1	$\frac{1}{3}$	0	$-\frac{1}{3}$	$\frac{1}{3}$	1

Since no positive reduced cost exists, this is the final tableau. The optimal objective value is  $w_{\min} = 0$ , and  $a_1$  is not in the optimal Phase-I basis. This is another example of Case 2.<sup>12</sup> Hence we can generate Phase-II initial

---

<sup>12</sup>Now we can discuss the question “Why not eliminate all the columns corresponding to the non-artificial variables with negative reduced costs in Case 2?”. Recall that only nonbasic variables have non-zero reduced costs. Notice that in the previous Example 1 (also of Case 2) the only nonbasic non-artificial variable in the optimal Phase-I tableau is  $e_2$  whose reduced cost is 0. In Example 2, the nonbasic non-artificial variables are  $x_2$  and  $x_4$  whose reduced costs are both 0 again. Actually, this is not a coincidence. In Case 2, each nonbasic non-artificial variable  $x_j$  has a reduced cost  $\mathbf{c}_B^T \mathbf{B}^{-1} \mathbf{A}_j - c_j = 0$  since  $\mathbf{c}_B = \mathbf{0}$  and  $c_j = 0$  in the Phase-I LP of standard form.

tableau by combining the original objective function with the constraints from the optimal Phase-I tableau. In other words, the Phase-I optimal basis  $(x_3, x_1) = (4, 1)$  is exactly the initial feasible basis of the Phase-II LP.

Dropping the column of artificial variable  $a_1$  and reintroducing the original objective “ $\max z = 4x_1 + 5x_2$ ”, we have the Phase-II tableau as follows.

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs
$z$	-4	-5	0	0	0
$x_3$	0	$\frac{7}{3}$	1	$\frac{2}{3}$	4
$x_1$	1	$\frac{1}{3}$	0	$-\frac{1}{3}$	1

Again, some EROs in row 0 are needed to make the canonical form.

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs	
$z$	0	$-\frac{11}{3}$	0	$-\frac{4}{3}$	4	$R'_0 \leftarrow R_0 + 4R_2$
$x_3$	0	$\frac{7}{3}$	1	$\frac{2}{3}$	4	
$x_1$	1	$\frac{1}{3}$	0	$-\frac{1}{3}$	1	

Now we can proceed with the Simplex method. Choose the most negative reduced cost to determine the entering variable, and find the leaving variable using the ratio test.

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs	ratio test
$z$	0	$-\frac{11}{3}$	0	$-\frac{4}{3}$	4	
$x_3$	0	$\frac{7}{3}$	1	$\frac{2}{3}$	4	$\frac{4}{(\frac{7}{3})} = \frac{12}{7}^*$
$x_1$	1	$\frac{1}{3}$	0	$-\frac{1}{3}$	1	$\frac{1}{(\frac{1}{3})} = 3$

Entering  $x_2$  and leaving  $x_3$ , we do the pivoting and have the following new tableau.

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs	
$z$	0	0	$\frac{11}{7}$	$-\frac{2}{7}$	$\frac{72}{7}$	$R_0'' \leftarrow R_0' + \frac{11}{3}R_1''$
$x_2$	0	1	$\frac{3}{7}$	$\frac{2}{7}$	$\frac{12}{7}$	$R_1'' \leftarrow \frac{3}{7}R_1'$ (go first)
$x_1$	1	0	$-\frac{1}{7}$	$-\frac{3}{7}$	$\frac{3}{7}$	$R_2'' \leftarrow R_2' - \frac{1}{3}R_1''$

Another Simplex iteration starts with

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs	ratio test
$z$	0	0	$\frac{11}{7}$	$-\frac{2}{7}$	$\frac{72}{7}$	
$x_2$	0	1	$\frac{3}{7}$	$\frac{2}{7}$	$\frac{12}{7}$	$\frac{(\frac{12}{7})}{\frac{2}{7}} = 6^*$
$x_1$	0	0	$-\frac{1}{7}$	$-\frac{3}{7}$	$\frac{3}{7}$	null

Entering  $x_4$  and leaving  $x_2$ , we do the pivoting and have the following new tableau.

basis	$x_1$	$x_2$	$x_3$	$x_4$	rhs	
$z$	0	1	2	0	12	$R_0''' \leftarrow R_0'' + R_1''$
$x_4$	0	$\frac{7}{2}$	$\frac{3}{2}$	1	6	$R_1''' \leftarrow \frac{7}{2}R_1''$ (go first)
$x_1$	1	$\frac{3}{2}$	$\frac{1}{2}$	0	3	$R_2''' \leftarrow R_2'' + \frac{3}{7}R_1'''$

Since none of the reduced costs is negative, this is the final Phase-II tableau. The optimal solution to the original LP is  $(x_1, x_2) = (3, 0)$  with  $z_{\max} = 12$ .

### Example 3

$$\begin{aligned}
\min \quad & z = 2x_1 + 3x_2 \\
s.t. \quad & \frac{1}{2}x_1 + \frac{1}{4}x_2 \leq 4 \\
& x_1 + 3x_2 \geq 36 \\
& x_1 + x_2 = 10 \\
& x_1, x_2 \geq 0
\end{aligned}$$

The Phase-I LP is



$$\begin{array}{rcll}
\min w = & & a_1 + a_2 & \\
s.t. & \frac{1}{2}x_1 + \frac{1}{4}x_2 + x_3 & = & 4 \\
& x_1 + 3x_2 - x_4 + a_1 & = & 36 \\
& x_1 + x_2 + a_2 & = & 10 \\
& x_1, x_2, x_3, x_4, a_1, a_2 & \geq & 0
\end{array}$$

After one Simplex iteration, we obtain the final Phase-I tableau below.

basis	$x_1$	$x_2$	$x_3$	$x_4$	$a_1$	$a_2$	rhs
$w$	-2	0	0	-1	0	-4	6
$x_3$	$\frac{1}{4}$	0	1	0	0	$-\frac{1}{4}$	$\frac{3}{2}$
$a_1$	-2	0	0	-1	1	-3	6
$x_2$	1	1	0	1	0	1	10

Since  $w_{min} = 6 > 0$  (Case 1), the original LP is infeasible.

#### **Example 4**

$$\begin{array}{rcll}
\max z = & 40x_1 + 10x_2 & + 7x_5 + 14x_6 & \\
s.t. & x_1 - x_2 & + 2x_5 & = 0 \\
& -2x_1 + x_2 & - 2x_5 & = 0 \\
& x_1 + x_3 + x_5 - x_6 & = & 3 \\
& x_2 + x_3 + x_4 + 2x_5 + x_6 & = & 4 \\
& x_1, x_2, x_3, x_4, x_5, x_6 & \geq & 0
\end{array}$$

Notice that we can use  $x_4$  as a basic variable for the fourth constraint. So we use artificial variables  $a_1, a_2, a_3$  as basic variables for the first three constraints. The Phase-I objective is “ $\min w = a_1 + a_2 + a_3$ ”. After one Simplex iteration, we can get the final Phase-I tableau below.

basis	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$a_1$	$a_2$	$a_3$	rhs
$w$	-1	0	0	0	0	0	0	0	-1	0
$a_1$	1	-1	0	0	2	0	1	0	0	0
$a_2$	-2	1	0	0	-2	0	0	1	0	0
$x_3$	1	0	1	0	1	-1	0	0	1	3
$x_4$	-1	2	0	1	1	2	0	0	-1	1

Notice that we have  $w_{\min} = 0$  and two artificial variables,  $a_1$  and  $a_2$ , remain in the optimal Phase-I basis (of course, at a zero level). This is an example of Case 3. To set up the initial Phase-II tableau, we drop the columns of the nonbasic artificial variable(s), which is  $a_3$  in this example, and of the original variables with a negative coefficient in the optimal Phase-I tableau. In this instance, there is only one such variable, which is  $x_1$ .<sup>13</sup> So, the initial tableau for Phase II is shown below.

basis	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$a_1$	$a_2$	rhs
$z$	-10	0	0	-7	-14	0	0	0
$a_1$	-1	0	0	2	0	1	0	0
$a_2$	1	0	0	-2	0	0	1	0
$x_3$	0	1	0	1	-1	0	0	3
$x_4$	2	0	1	1	2	0	0	1

Since the row-0 coefficients, i.e. reduced costs, of all the basic variables are zero, this is a canonical form. Then we commence the first Simplex iteration by entering  $x_6$  and leaving  $x_4$ . After the pivoting procedure, we have the following tableau.

---

<sup>13</sup>Here we discuss the question “Why can we eliminate all the columns corresponding to the non-artificial variables with negative reduced costs in Case 3?”. In this example, we have from the optimal Phase-I tableau an objective equality  $w = x_1 + a_3$ . Even proceeding to Phase-II procedure, we still need to keep  $a_3 = 0$  satisfied, which means  $x_1$  must be zero all the way. In other words,  $x_1$  is not permitted to enter the basis in Phase-II procedure and shall be eliminated after Phase-I procedure.

basis	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$a_1$	$a_2$	rhs
$z$	4	0	7	0	0	0	0	7
$a_1$	-1	0	0	2	0	1	0	0
$a_2$	1	0	0	-2	0	0	1	0
$x_3$	1	1	$\frac{1}{2}$	$\frac{3}{2}$	0	0	0	$\frac{7}{2}$
$x_6$	1	0	$\frac{1}{2}$	$\frac{1}{2}$	1	0	0	$\frac{1}{2}$

Since all reduced costs are nonnegative, this is the optimal Phase-II tableau. The optimal solution to the original LP is

$$(x_1, x_2, x_3, x_4, x_5, x_6) = (0, 0, \frac{7}{2}, 0, 0, \frac{1}{2})$$

with the optimal objective value  $z_{\max} = 7$ .

---

Further reading: Section 4.12 and 4.13 in the reference book “Operations Research: Applications and Algorithms” (Winston, 2004)