## HW6-1

## November 17, 2023

```
[1]: import argparse
     import os
     import time
     import shutil
     import torch
     import torch.nn as nn
     import torch.optim as optim
     import torch.nn.functional as F
     import torch.backends.cudnn as cudnn
     import torchvision
     import torchvision.transforms as transforms
     from models import *
     global best_prec
     use_gpu = torch.cuda.is_available()
     print('=> Building model...')
     batch_size = 128
     model_name = "VGG16_quant"
     model = VGG16_quant()
     print(model)
     normalize = transforms.Normalize(mean=[0.491, 0.482, 0.447], std=[0.247, 0.243,__
      →0.262])
     train_dataset = torchvision.datasets.CIFAR10(
         root='./data',
         train=True,
         download=True,
         transform=transforms.Compose([
             transforms.RandomCrop(32, padding=4),
             transforms.RandomHorizontalFlip(),
```

```
transforms.ToTensor(),
        normalize,
    1))
trainloader = torch.utils.data.DataLoader(train_dataset, batch_size=batch_size,_
 ⇒shuffle=True, num_workers=2)
test_dataset = torchvision.datasets.CIFAR10(
    root='./data',
    train=False,
    download=True,
    transform=transforms.Compose([
        transforms.ToTensor(),
        normalize,
    ]))
testloader = torch.utils.data.DataLoader(test_dataset, batch_size=batch_size,_u
 ⇒shuffle=False, num_workers=2)
print_freq = 100 # every 100 batches, accuracy printed. Here, each batch ∪
 →includes "batch_size" data points
# CIFAR10 has 50,000 training data, and 10,000 validation data.
def train(trainloader, model, criterion, optimizer, epoch):
    batch_time = AverageMeter()
    data_time = AverageMeter()
    losses = AverageMeter()
    top1 = AverageMeter()
    model.train()
    end = time.time()
    for i, (input, target) in enumerate(trainloader):
        # measure data loading time
        data_time.update(time.time() - end)
        input, target = input.cuda(), target.cuda()
        # compute output
        output = model(input)
        loss = criterion(output, target)
        # measure accuracy and record loss
        prec = accuracy(output, target)[0]
        losses.update(loss.item(), input.size(0))
        top1.update(prec.item(), input.size(0))
```

```
# compute gradient and do SGD step
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        # measure elapsed time
        batch_time.update(time.time() - end)
        end = time.time()
        if i % print_freq == 0:
            print('Epoch: [{0}][{1}/{2}]\t'
                  'Time {batch_time.val:.3f} ({batch_time.avg:.3f})\t'
                  'Data {data_time.val:.3f} ({data_time.avg:.3f})\t'
                  'Loss {loss.val:.4f} ({loss.avg:.4f})\t'
                  'Prec {top1.val:.3f}% ({top1.avg:.3f}%)'.format(
                   epoch, i, len(trainloader), batch_time=batch_time,
                   data_time=data_time, loss=losses, top1=top1))
def validate(val_loader, model, criterion ):
    batch_time = AverageMeter()
    losses = AverageMeter()
    top1 = AverageMeter()
    # switch to evaluate mode
    model.eval()
    end = time.time()
    with torch.no_grad():
        for i, (input, target) in enumerate(val_loader):
            input, target = input.cuda(), target.cuda()
            # compute output
            output = model(input)
            loss = criterion(output, target)
            # measure accuracy and record loss
            prec = accuracy(output, target)[0]
            losses.update(loss.item(), input.size(0))
            top1.update(prec.item(), input.size(0))
            # measure elapsed time
            batch_time.update(time.time() - end)
```

```
end = time.time()
            if i % print_freq == 0: # This line shows how frequently print out_
 \hookrightarrow the status. e.g., i%5 => every 5 batch, prints out
                print('Test: [{0}/{1}]\t'
                  'Time {batch time.val:.3f} ({batch time.avg:.3f})\t'
                  'Loss {loss.val:.4f} ({loss.avg:.4f})\t'
                  'Prec {top1.val:.3f}% ({top1.avg:.3f}%)'.format(
                   i, len(val_loader), batch_time=batch_time, loss=losses,
                   top1=top1))
    print(' * Prec {top1.avg:.3f}% '.format(top1=top1))
    return top1.avg
def accuracy(output, target, topk=(1,)):
    """Computes the precision@k for the specified values of k"""
    maxk = max(topk)
    batch_size = target.size(0)
    _, pred = output.topk(maxk, 1, True, True)
    pred = pred.t()
    correct = pred.eq(target.view(1, -1).expand_as(pred))
    res = []
    for k in topk:
        correct_k = correct[:k].view(-1).float().sum(0)
        res.append(correct_k.mul_(100.0 / batch_size))
    return res
class AverageMeter(object):
    """Computes and stores the average and current value"""
    def __init__(self):
        self.reset()
    def reset(self):
        self.val = 0
        self.avg = 0
        self.sum = 0
        self.count = 0
    def update(self, val, n=1):
        self.val = val
        self.sum += val * n
        self.count += n
        self.avg = self.sum / self.count
```

```
def save_checkpoint(state, is_best, fdir):
    filepath = os.path.join(fdir, 'checkpoint.pth')
    torch.save(state, filepath)
    if is_best:
        shutil.copyfile(filepath, os.path.join(fdir, 'model_best.pth.tar'))
def adjust_learning_rate(optimizer, epoch):
     """For resnet, the lr starts from 0.1, and is divided by 10 at 80 and 120_{11}
 ⇔epochs"""
    adjust_list = [150, 225]
    if epoch in adjust_list:
        for param_group in optimizer.param_groups:
            param_group['lr'] = param_group['lr'] * 0.1
#model = nn.DataParallel(model).cuda()
#all params = checkpoint['state dict']
#model.load_state_dict(all_params, strict=False)
#criterion = nn.CrossEntropyLoss().cuda()
#validate(testloader, model, criterion)
=> Building model...
VGG quant(
  (features): Sequential(
    (0): QuantConv2d(
      3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (2): ReLU(inplace=True)
    (3): QuantConv2d(
      64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (4): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (5): ReLU(inplace=True)
    (6): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
ceil_mode=False)
    (7): QuantConv2d(
      64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (8): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
```

```
track_running_stats=True)
    (9): ReLU(inplace=True)
    (10): QuantConv2d(
      128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (11): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (12): ReLU(inplace=True)
    (13): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
ceil_mode=False)
    (14): QuantConv2d(
      128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (15): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (16): ReLU(inplace=True)
    (17): QuantConv2d(
      256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (18): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (19): ReLU(inplace=True)
    (20): QuantConv2d(
      256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (21): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (22): ReLU(inplace=True)
    (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
ceil_mode=False)
    (24): QuantConv2d(
      256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (25): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (26): ReLU(inplace=True)
    (27): QuantConv2d(
      512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
      (weight_quant): weight_quantize_fn()
    (28): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (29): ReLU(inplace=True)
```

```
512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
          (weight_quant): weight_quantize_fn()
        (31): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track running stats=True)
        (32): ReLU(inplace=True)
        (33): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
    ceil mode=False)
        (34): QuantConv2d(
          512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
          (weight_quant): weight_quantize_fn()
        (35): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
        (36): ReLU(inplace=True)
        (37): QuantConv2d(
          512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
          (weight_quant): weight_quantize_fn()
        (38): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track running stats=True)
        (39): ReLU(inplace=True)
        (40): QuantConv2d(
          512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False
          (weight_quant): weight_quantize_fn()
        )
        (41): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
        (42): ReLU(inplace=True)
        (43): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
    ceil_mode=False)
        (44): AvgPool2d(kernel_size=1, stride=1, padding=0)
      (classifier): Linear(in features=512, out features=10, bias=True)
    Files already downloaded and verified
    Files already downloaded and verified
[]: | #training
     # This cell won't be given, but students will complete the training
     lr = 4e-2
     weight_decay = 1e-4
     epochs = 60
     best_prec = 0
```

(30): QuantConv2d(

```
#model = nn.DataParallel(model).cuda()
model.cuda()
criterion = nn.CrossEntropyLoss().cuda()
optimizer = torch.optim.SGD(model.parameters(), lr=lr, momentum=0.9, __
 →weight_decay=weight_decay)
#cudnn.benchmark = True
if not os.path.exists('result'):
    os.makedirs('result')
fdir = 'result/'+str(model_name)+"_hw6"
if not os.path.exists(fdir):
    os.makedirs(fdir)
for epoch in range(0, epochs):
    adjust_learning_rate(optimizer, epoch)
    train(trainloader, model, criterion, optimizer, epoch)
    # evaluate on test set
    print("Validation starts")
    prec = validate(testloader, model, criterion)
    # remember best precision and save checkpoint
    is_best = prec > best_prec
    best_prec = max(prec,best_prec)
    print('best acc: {:1f}'.format(best_prec))
    save_checkpoint({
        'epoch': epoch + 1,
        'state_dict': model.state_dict(),
        'best_prec': best_prec,
        'optimizer': optimizer.state_dict(),
    }, is_best, fdir)
```

```
PATH = "result/VGG16_quant_hw6/model_best.pth.tar"
    checkpoint = torch.load(PATH)
    model.load_state_dict(checkpoint['state_dict'])
    device = torch.device("cuda")

model.cuda()
    model.eval()

test_loss = 0
    correct = 0

with torch.no_grad():
    for data, target in testloader:
```

```
data, target = data.to(device), target.to(device) # loading to GPU
  output = model(data)
  pred = output.argmax(dim=1, keepdim=True)
  correct += pred.eq(target.view_as(pred)).sum().item()

test_loss /= len(testloader.dataset)

print('\nTest set: Accuracy: {}/{} ({:.0f}%)\n'.format(
  correct, len(testloader.dataset),
  100. * correct / len(testloader.dataset)))
```

Test set: Accuracy: 8957/10000 (90%)

```
[]:
[]:
[]:
[]:
[3]: class SaveOutput:
        def __init__(self):
           self.outputs = []
        def __call__(self, module, module_in):
           self.outputs.append(module_in)
        def clear(self):
           self.outputs = []
    ####### Save inputs from selected layer ########
    save_output = SaveOutput()
    i = 0
    for layer in model.modules():
        i = i+1
        if isinstance(layer, QuantConv2d):
           print(i,"-th layer prehooked")
           layer.register_forward_pre_hook(save_output)
    dataiter = iter(testloader)
    images, labels = next(dataiter)
    images = images.to(device)
    out = model(images)
```

```
3 -th layer prehooked
    7 -th layer prehooked
    12 -th layer prehooked
    16 -th layer prehooked
    21 -th layer prehooked
    25 -th layer prehooked
    29 -th layer prehooked
    34 -th layer prehooked
    38 -th layer prehooked
    42 -th layer prehooked
    47 -th layer prehooked
    51 -th layer prehooked
    55 -th layer prehooked
[4]: weight_q = model.features[3].weight_q
    w_alpha = model.features[3].weight_quant.wgt_alpha
    w_bit = 4
    weight_int = weight_q / (w_alpha / (2**(w_bit-1)-1))
    print(weight_int)
    tensor([[[[ 0.0000, -1.0000, 1.0000],
              [1.0000, -1.0000, -0.0000],
              [1.0000, 2.0000, 1.0000]],
             [[0.0000, -1.0000, -2.0000],
              [-0.0000, 0.0000, -0.0000],
              [-1.0000, -0.0000, 0.0000]],
             [[-1.0000, 1.0000, 2.0000],
              [-1.0000, 2.0000, 4.0000],
              [-2.0000, 1.0000,
                                  2.0000]],
             [[ 0.0000, 1.0000, 0.0000],
              [-0.0000, 0.0000, -1.0000],
              [-1.0000, -1.0000, -1.0000]],
             [[ 1.0000, 1.0000, 0.0000],
              [1.0000, 1.0000, 0.0000],
              [-1.0000, -1.0000, -1.0000]],
             [[ 0.0000, 0.0000, 1.0000],
              [ 0.0000, 0.0000,
                                  1.0000],
              [ 1.0000, 0.0000,
                                  1.0000]]],
```

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[[[-0.0000, -3.0000, 0.0000],
 [5.0000, 6.0000, 7.0000],
 [1.0000, -7.0000, -7.0000]],
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 [1.0000, 1.0000, 0.0000]],
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[[2.0000, 2.0000, -1.0000],
 [-2.0000, -0.0000, -0.0000],
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 [-0.0000, 0.0000, -0.0000]],
[[-1.0000, -2.0000, -1.0000],
 [-2.0000, 0.0000, -0.0000],
 [ 2.0000, 3.0000, 2.0000]]],
[[[4.0000, 7.0000, 7.0000],
 [-3.0000, -6.0000, 0.0000],
 [-4.0000, -2.0000, -0.0000]],
 [[-0.0000, 0.0000, -1.0000],
 [-1.0000, -1.0000, -1.0000],
 [0.0000, 0.0000, 0.0000]],
 [[-1.0000, -3.0000, -1.0000],
 [-1.0000, -2.0000, -2.0000],
 [1.0000, -2.0000, 0.0000]],
...,
[[3.0000, 4.0000, 3.0000],
 [0.0000, 2.0000, 1.0000],
 [-3.0000, -1.0000, -1.0000]],
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 [-3.0000, -1.0000, 0.0000],
 [1.0000, 1.0000, 1.0000]],
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[[-1.0000, 0.0000, -1.0000],
 [-1.0000, -0.0000, -0.0000],
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 [4.0000, 2.0000, -4.0000]],
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 [-1.0000, -2.0000, -2.0000],
 [-0.0000, -2.0000, -1.0000]],
[[7.0000, -1.0000, -2.0000],
 [7.0000, -1.0000, -3.0000],
 [6.0000, -2.0000, -3.0000]],
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 [-1.0000, -4.0000, -3.0000]],
[[0.0000, 2.0000, 0.0000],
 [-2.0000, 1.0000, -1.0000],
 [-2.0000, -0.0000, -0.0000]]],
[[[-3.0000, -7.0000, -6.0000],
 [7.0000, 2.0000, -3.0000],
 [3.0000, 4.0000, 1.0000]],
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 [ 0.0000, -1.0000,
                     0.0000]],
[[ 2.0000, 3.0000,
                     2.0000],
 [-1.0000, 1.0000,
                     2.0000],
 [-0.0000, -2.0000,
                     0.0000]],
```

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[[-0.0000, 1.0000, 1.0000],
              [-0.0000, 1.0000, -1.0000],
              [-1.0000, -1.0000, -1.0000]]
             [[ 1.0000, 2.0000, 1.0000],
              [-1.0000, 1.0000, 3.0000],
              [-4.0000, -3.0000, -2.0000]],
             [[-1.0000, -0.0000, 0.0000],
              [-1.0000, -2.0000, -1.0000],
              [-1.0000, -1.0000, -2.0000]]],
            [[[6.0000, 0.0000, -5.0000],
              [7.0000, -0.0000, -7.0000],
              [6.0000, 1.0000, -7.0000]],
             [[ 2.0000, 0.0000, 1.0000],
              [2.0000, -1.0000, -0.0000],
              [1.0000, -1.0000, -0.0000]],
             [[0.0000, 1.0000, -2.0000],
              [1.0000, 2.0000, -1.0000],
              [0.0000, 3.0000, -0.0000]],
             ...,
             [[-0.0000, -2.0000, -1.0000],
              [-1.0000, -3.0000, -1.0000],
              [-1.0000, -2.0000, 1.0000]],
             [[-3.0000, -3.0000, -3.0000],
              [-3.0000, -4.0000, -4.0000],
              [-2.0000, -1.0000, 0.0000]],
             [[-0.0000, -1.0000, 0.0000],
              [-1.0000, -2.0000, 0.0000],
              [-1.0000, -1.0000, 1.0000]]]], device='cuda:0',
           grad_fn=<DivBackward0>)
[5]: act = save_output.outputs[1][0]
    act_alpha = model.features[3].act_alpha
    act_bit = 4
    act_quant_fn = act_quantization(act_bit)
```

...,

```
act_q = act_quant_fn(act, act_alpha)
act_int = act_q / (act_alpha / (2**act_bit-1))
print(act_int)
tensor([[[[ 0.0000,
                       0.0000,
                                 0.0000,
                                               0.0000,
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                                                                   0.0000],
           [4.0000,
                       5.0000,
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           [ 3.0000,
                       4.0000,
                                 6.0000,
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           [10.0000,
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7.0000, ..., 14.0000, 15.0000, [[ 6.0000, 7.0000, 8.0000], 0.0000, ..., 0.0000, 0.0000, [ 1.0000, 0.0000, 0.0000], [ 2.0000, 1.0000, 1.0000, ..., 0.0000, 0.0000, 0.0000],[ 2.0000, 4.0000, 3.0000, ..., 1.0000, 0.0000, 0.0000],[ 1.0000, 2.0000, 2.0000, ..., 1.0000, 0.0000, 0.0000], [ 1.0000, 3.0000, 4.0000, ..., 0.0000, 0.0000, 0.0000]], [[ 0.0000, 0.0000, 0.0000, 0.0000, 0.0000, 0.0000],1.0000], [ 1.0000, 0.0000, 0.0000, ..., 2.0000, 2.0000, 0.0000, 2.0000, [ 1.0000, 0.0000, 1.0000, 1.0000], [ 0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 1.0000], [0.0000, 0.0000,0.0000, ..., 1.0000, 1.0000, 1.0000], [ 0.0000, 0.0000, 0.0000, ..., 13.0000, 14.0000, 11.0000]], [[ 0.0000, 2.0000, 2.0000, ..., 5.0000, 5.0000, 3.0000], [0.0000, 0.0000,0.0000, ..., 1.0000, 2.0000, 1.0000], [0.0000, 0.0000,1.0000, ..., 1.0000, 2.0000, 1.0000], ... , 0.0000, ..., 2.0000, [ 2.0000, 0.0000, 2.0000, 1.0000], 0.0000, ..., 2.0000, [ 1.0000, 0.0000, 2.0000, 1.0000], [ 1.0000, 1.0000, 1.0000, ..., 0.0000, 0.0000, 0.0000]]]], device='cuda:0', grad\_fn=<DivBackward0>) [6]: conv\_int = torch.nn.Conv2d(in\_channels = 64, out\_channels=64, kernel\_size = 3,\_\_ →padding=1) conv int.weight = torch.nn.parameter.Parameter(weight int) conv\_int.bias = model.features[3].bias output int = conv int(act int) output\_recovered = output\_int \* (act\_alpha / (2\*\*act\_bit-1)) \* (w\_alpha / \_\_  $\hookrightarrow$  (2\*\*(w bit-1)-1)) print(output\_recovered) tensor([[[-2.1890e+00, 2.0640e+01, 9.5693e+00, ..., 1.1258e+01, 2.0389e+01, 5.2537e+00], 3.1710e+01, [-9.9445e+00, 2.3704e+01, ..., 3.0834e+01,4.5845e+01, 2.3517e+01], 2.4830e+01, [-1.4385e+01, 2.2328e+01, ..., 2.9146e+01, 4.6158e+01, 2.2141e+01], [ 2.9271e+01, -7.4428e+00, 1.3697e+01, ..., 2.3141e+00, -2.2453e+01, -9.4442e+00], [2.2391e+01, -1.4010e+01, 8.6936e+00, ..., -3.8777e+00,-3.0772e+01, -1.5011e+01], [ 2.6394e+01, 8.0682e+00, 2.3204e+01, ..., 1.7450e+01,

...,

```
-6.1919e+00, 1.2509e-01]],
[[-2.2766e+01, -3.6338e+01, -4.0466e+01, ..., -5.1036e+01,
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...,
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 [-6.3170e+00, 4.7471e+01, -7.2551e+00, ..., 5.2537e+00,
   2.3517e+01, -5.0661e+00]],
[[ 1.0633e+00, 3.8152e+00, -2.5017e-01, ..., -8.9438e+00,
  -1.2321e+01, -1.9514e+01],
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  -3.4462e+01, -3.1460e+01],
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   9.6318e+00, -7.6304e+00]],
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   4.7784e+01, 8.0057e+00],
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   4.4031e+01, 1.2884e+01],
 [-1.6637e+01, 2.5330e+01, 1.3635e+01, ..., 4.0654e+01,
   5.2099e+01, -2.2578e+01,
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   1.1258e+01, 1.4886e+01]]],
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   3.0647e+00, -2.9396e+00],
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  -3.0647e+00, -5.9417e+00],
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 [[3.0146e+01, 7.2426e+01, 6.7298e+01, ..., 6.7298e+01,
   6.1418e+01, 4.2092e+01],
 [-5.8479e+01, -8.3622e+01, -9.7506e+01, ..., -9.8820e+01,
  -1.0426e+02, -7.6429e+01],
 [-3.5025e+01, -3.4337e+01, -3.7464e+01, ..., -3.5525e+01,
  -4.3468e+01, -4.0341e+01],
 ...,
```

```
[-2.9646e+01, -4.8409e+01, -4.1217e+01, ..., -1.2696e+01,
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  6.1293e+00, 1.0007e+01],
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 -2.6894e+00, 3.8152e+00],
 [ 1.6887e+00, 7.7555e+00, 1.1070e+01, ..., 1.5636e+00,
  1.5011e+00, 7.5053e-01],
```

```
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  -8.1307e+00, 6.0042e+00]],
 [[-3.4337e+01, 5.8166e+00, -3.4399e+00, ..., -1.1258e+00,
  -3.1272e+01, 7.0675e+00].
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   3.5650e+00, -1.2509e+00],
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   1.7512e+00, -2.4392e+00],
 ...,
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  -4.6595e+01, -3.6276e+01],
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```
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  5.5664e+00, -5.7541e+00]],
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   4.2467e+01, 3.2523e+00],
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    3.4837e+01, 1.9389e+00],
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  -6.0918e+01, -2.8082e+01],
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  -1.7950e+01, -1.6949e+01]],
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```

```
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  3.8152e+01, 7.5303e+01],
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  4.0966e+01, 7.1676e+01],
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  1.1008e+01, -2.4392e+00],
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  1.9764e+01, 5.0661e+00]],
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  7.9744e+01, 1.9201e+01],
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  -5.3788e+00, -7.9431e+00],
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  -4.2530e+00, -6.3170e+00],
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   2.1890e+00, 1.8138e+00],
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  -2.4893e+01, -3.3836e+01],
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  -3.6713e+01, -3.2210e+01],
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  -2.0952e+01, -3.0709e+01],
 [-2.9834e+01, -3.8902e+01, -3.6025e+01, ..., -1.5636e+01,
  -2.3266e+01, -2.5643e+01]],
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   5.9417e+00, 2.6269e+00]],
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  -3.5650e+00, 8.7562e-01],
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   1.1258e+00, -9.0689e+00]],
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   3.3148e+01, -8.1307e+00],
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   1.3635e+01, -1.2134e+01]]],
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   1.7137e+01, 1.0320e+01],
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  1.3384e+01, 1.2384e+01],
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  8.1933e+00, 7.9431e+00],
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                3.3148e+01, 3.6276e+00],
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                5.0661e+00, -7.8180e+00],
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               -2.1890e+00, -9.9445e+00],
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                1.1633e+01, -4.8784e+00]],
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                5.7541e+01, -8.9438e+00],
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                6.6047e+01, 2.4392e+00],
              [-3.2523e+01, -9.5693e+00, -1.4010e+01, ..., 4.1029e+01,
                5.9479e+01, 6.8799e+00],
              [-1.9326e+01, 3.1272e+00, -1.6449e+01, ..., 2.8895e+01,
                4.5970e+01, 2.6269e+00],
              [-1.3572e+01, 4.7534e+00, -1.8638e+01, ..., -1.1258e+00,
                1.5261e+01, -8.0057e+00]]]], device='cuda:0',
           grad_fn=<MulBackward0>)
[7]: conv_ref = torch.nn.Conv2d(in_channels = 64, out_channels=64, kernel_size = 3,
     →padding=1)
     conv ref.weight = model.features[3].weight q
     conv_ref.bias = model.features[3].bias
     output_ref = conv_ref(act)
     print(output_ref)
    tensor([[[[-3.3602e+00, 2.0532e+01, 9.7798e+00, ..., 1.0963e+01,
                2.2540e+01, 5.5590e+00],
              [-1.0819e+01, 3.1853e+01, 2.4546e+01, ..., 3.1208e+01,
                4.9200e+01, 2.5180e+01],
              [-1.4340e+01, 2.5186e+01, 2.2635e+01, ..., 2.9151e+01,
                4.9394e+01, 2.3629e+01],
              [ 3.8949e+01, -1.7879e+01, 1.3632e+01, ..., 2.4148e+00,
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-4.3042e-08, -1.3134e+01,

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  2.7352e+01, -2.2258e+01],
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 [ 1.9961e+01, -1.3177e+01, -2.4490e+01, ..., 1.0173e+01,
  -2.0147e+01, -2.6611e+01],
 [1.1920e+00, -2.5519e+01, -3.3356e+01, ..., -3.3124e+01,
  -3.6023e+01, -3.3838e+01],
 [ 3.0828e+01, 1.7732e+01, 1.7058e+01, ..., 3.5045e+00,
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   6.0804e+00, 1.9082e+00]],
 [[ 4.8498e+01, 1.0288e+02, 9.4974e+01, ..., 9.5835e+01,
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  1.0601e+01, 5.4281e-01]],
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...,
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  -9.3152e+01, 1.0063e+01],
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   1.1129e+01, 8.4305e+00]],
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  -5.8926e+01, -5.5828e+01],
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   8.4813e+00, -1.1796e+01]],
[[-4.8805e+01, 8.7325e-01, 4.1364e+01, ..., 1.2062e+00,
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   8.1682e+01, 1.2654e+00],
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   4.5864e+01, -4.5907e+00],
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  -6.2296e+00, -3.5357e+00],
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  -1.7725e+01, 8.7558e-01],
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  -6.9013e+01, -2.7821e+01],
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  -1.6903e+01, -1.7600e+01]],
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  -4.2517e+01, -2.7118e+01],
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  -7.7278e+01, -4.9366e+01,
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   8.9614e+01, 3.0625e+01,
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  8.6787e+01, 2.4046e+01],
 [-2.0580e+01, -5.1761e+01, -4.0636e+01, ..., 6.8802e+00,
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  -6.4196e+00, -9.6600e+00],
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  -3.1342e+01, -3.3527e+01],
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  -2.1117e+01, -3.8666e+01],
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  -3.6946e+01, -3.1187e+01],
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...,

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   5.8364e+00, 1.8172e+00]],
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   1.1750e+01, -1.1379e+01]]],
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 -8.8599e+00, -3.8871e+01]],
[[-2.8390e+01, -7.2303e+00, -1.8860e+01, ..., -1.8477e+01,
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[-2.9048e+01, -4.7285e+00, -5.2490e+00, ..., -1.3814e-01,
  1.4298e+01, 3.1702e+00],
```

```
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   [-5.3776e+00, -2.3309e+01, -1.5093e+00, ..., -1.2986e+01,
    7.8112e+00, -2.0553e+01,
   [ 5.4829e+00, -1.1023e+00, 1.4891e+00, ..., -5.7294e+00,
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  [[-1.1548e+01, -8.8188e+00, -1.3786e+01, ..., -3.8128e+01,
   -5.2170e+01, -3.8860e+01],
   [ 3.1793e+01, 4.7593e+01, 5.2851e+01, ..., 6.0211e+01,
     3.6815e+01, 4.7683e+00],
   [-6.3659e-02, -4.2025e+00, -9.3852e+00, ..., 1.6154e+01,
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   [8.5889e+00, 1.4089e+01, -2.7157e+00, ..., 1.2957e+01,
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  [[-2.5304e+00, -1.0193e+01, -8.0289e+00, ..., -5.0835e+00,
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   [ 1.8456e+01, 1.5262e+01, 5.0764e+00, ..., 2.6703e+01,
     7.3676e+01, -5.7064e+00],
   [ 1.3624e+01, 2.6040e+01, -3.8575e+00, ..., 3.5317e+01,
    8.2580e+01, 2.7106e+00],
   [-3.2110e+01, -8.5863e+00, -1.4313e+01, ..., 4.1767e+01,
    7.5013e+01, 6.0838e+00],
   [-1.9167e+01, 2.8595e+00, -1.5935e+01, ..., 2.9167e+01,
     6.4185e+01, 9.8547e-01],
   [-1.3637e+01, 5.0763e+00, -1.7887e+01, ..., -8.2019e-01,
     3.1124e+01, -1.0624e+01]]]], device='cuda:0',
grad fn=<ConvolutionBackward0>)
```

## []:

## 0.0.1 Tiling

```
[8]: import torch
import math
import torch.nn as nn

a_int = act_int[0, :, :, :]
```

```
nis = a_int.size(1)
njs = a_int.size(2)
w_int = torch.reshape(weight_int, (weight_int.size(0), weight_int.size(1), -1))__
  → # merge ki, kj index to kij
padding = 1
stride = 1
array_size = 16 # change to 16 for hw6
oc = w_int.size(0)
ic = w_int.size(1)
w_int_tile = torch.reshape(w_int, (4, array_size, 4, array_size, -1))
a_int_tile = torch.reshape(a_int, (4, array_size, nis, njs))
nig = range(a_int.size(1)) # ni group [0, 1, ..., 31]
njg = range(a_int.size(2)) # nj group
icg = range(int(w_int.size(1))) # input channel [0, ..., 63]
ocg = range(int(w_int.size(0))) # output channel
kijg = range(w_int.size(2)) # [0, .. 8]
ki_dim = int(math.sqrt(w_int.size(2))) # Kernel's 1 dim size
####### Padding before Convolution ######
# a pad = torch.zeros(len(icq), len(niq)+padding*2, len(njq)+padding*2).cuda()
# # a_pad.size() = [64, 32+2pad, 32+2pad]
# a_pad[:, padding:padding+len(nig), padding:padding+len(njg)] = a_int.cuda()
# a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad, (a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## mergin ni and nj index_\(\begin{align*} \text{ + a pad = torch.reshape(a_pad.size(0), -1)) ## merg
 ⇒into nij
# # a_pad.size() = [64, (32+2pad)*(32+2pad)]
# Padding
a_pad_tile = torch.zeros(a_int_tile.size(0), a_int_tile.size(1), nis + padding_
  \Rightarrow 2, njs + padding * 2).cuda()
a_pad_tile[:, :, padding:padding + len(nig), padding:padding + len(njg)] = ___
  →a_int_tile.cuda()
a_pad_tile = torch.reshape(a_pad_tile, (a_pad_tile.size(0), a_pad_tile.size(1),_
 -1))
# Matrix Mult
p_nijg = range(a_pad_tile.size(-1))
psum_tile = torch.zeros(4, array_size, 4, len(p_nijg), len(kijg)).cuda()
for kij in kijg:
        for out_tile in range(4):
                 for in_tile in range(4):
                          for nij in p_nijg:
```

```
m_tile = nn.Linear(array_size, array_size, bias=False)
                      m_tile.weight = torch.nn.Parameter(w_int_tile[out_tile, :,__
       →in_tile, :, kij])
                      psum_tile[out_tile, :, in_tile, nij, kij] = ___
       m_tile(a_pad_tile[in_tile, :, nij]).cuda()
      psum = torch.reshape(psum_tile, (oc, 4, len(p_nijg), len(kijg)))
      # Output dimension
      a_pad_ni_dim = int(math.sqrt(len(p_nijg)))
      o_ni_dim = int((a_pad_ni_dim - (ki_dim - 1) - 1) / stride + 1)
      o nijg = range(o ni dim**2)
      out = torch.zeros(oc, len(o_nijg)).cuda()
      # SFP Acc
      for o_nij in o_nijg:
          for in_tile in range(4):
              for kij in kijg:
                  nij_ = int(o_nij / o_ni_dim) * a_pad_ni_dim + o_nij % o_ni_dim +
       →int(kij / ki_dim) * a_pad_ni_dim + kij % ki_dim
                  out[:, o_nij] = out[:, o_nij] + psum[:, in_tile, nij_, kij]
 [9]: out_2D = torch.reshape(out, (out.size(0), o_ni_dim, -1)) # nij -> ni & nj
      difference = (out_2D - output_int[0,:,:,:])
      print(difference.abs().sum())
      print(difference.sum())
     tensor(3.6061, device='cuda:0', grad_fn=<SumBackward0>)
     tensor(-0.1326, device='cuda:0', grad_fn=<SumBackward0>)
[10]: output_int[0,:,:,:]
[10]: tensor([[[ -35.0000,
                              330.0000,
                                          153.0001, ...,
                                                          180.0000,
                  326.0000,
                               84.0000],
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                              507.0000,
                                          379.0000, ...,
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                                                          -62.0000,
                 -492.0000, -240.0000],
                                          371.0000, ...,
               [ 422.0000,
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```

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   180.0000,
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```