

# *Towards Fully Convolutional Panoptic Segmentation*

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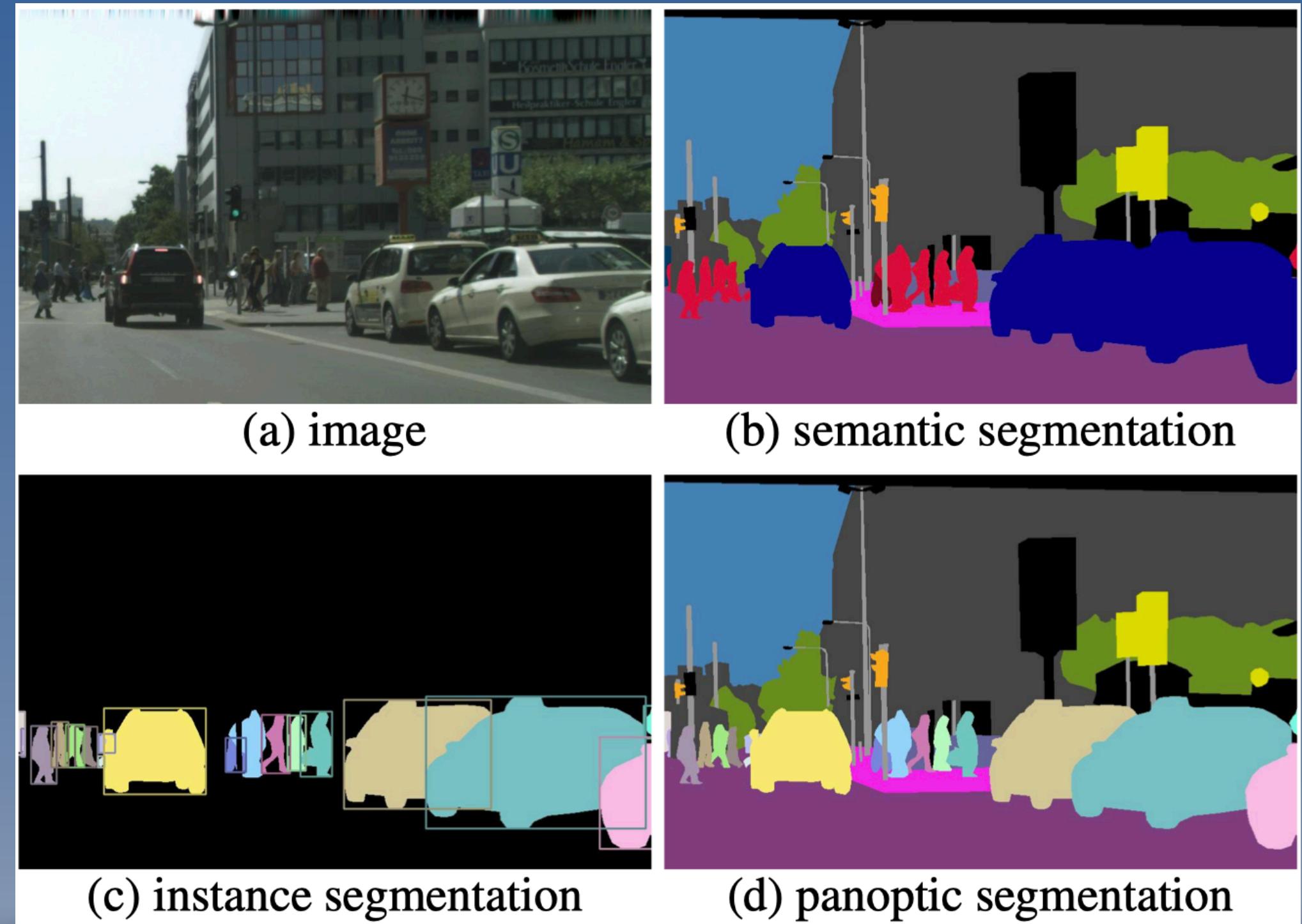
# Introduction

## Definition of Panoptic Segmentation

Assign each pixel with a semantic label and unique identity to Things and Stuff.

## Difficulties in Panoptic Segmentation

- *Conflicting properties of Things and Stuff.*  
Things rely on *instance-aware* features, while  
Stuff need *semantic-consistent* characters.
- How to encode things and stuff in a unified representation?
- How to model the relationship among things, and between things and stuff?

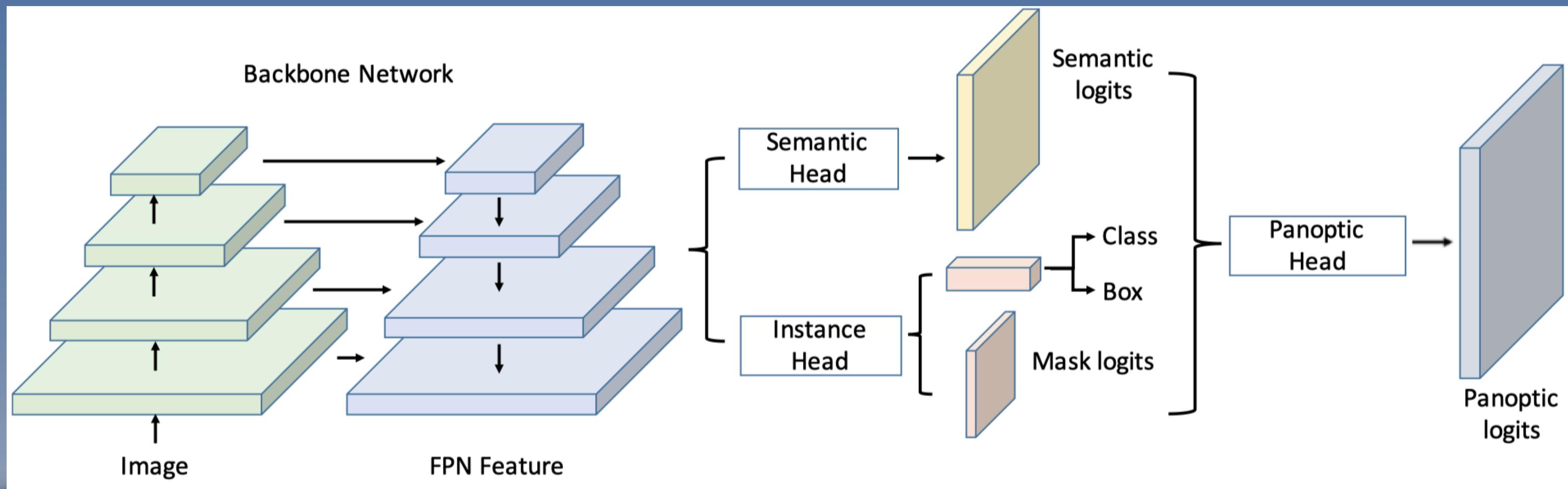


Comparison among tasks. [1]

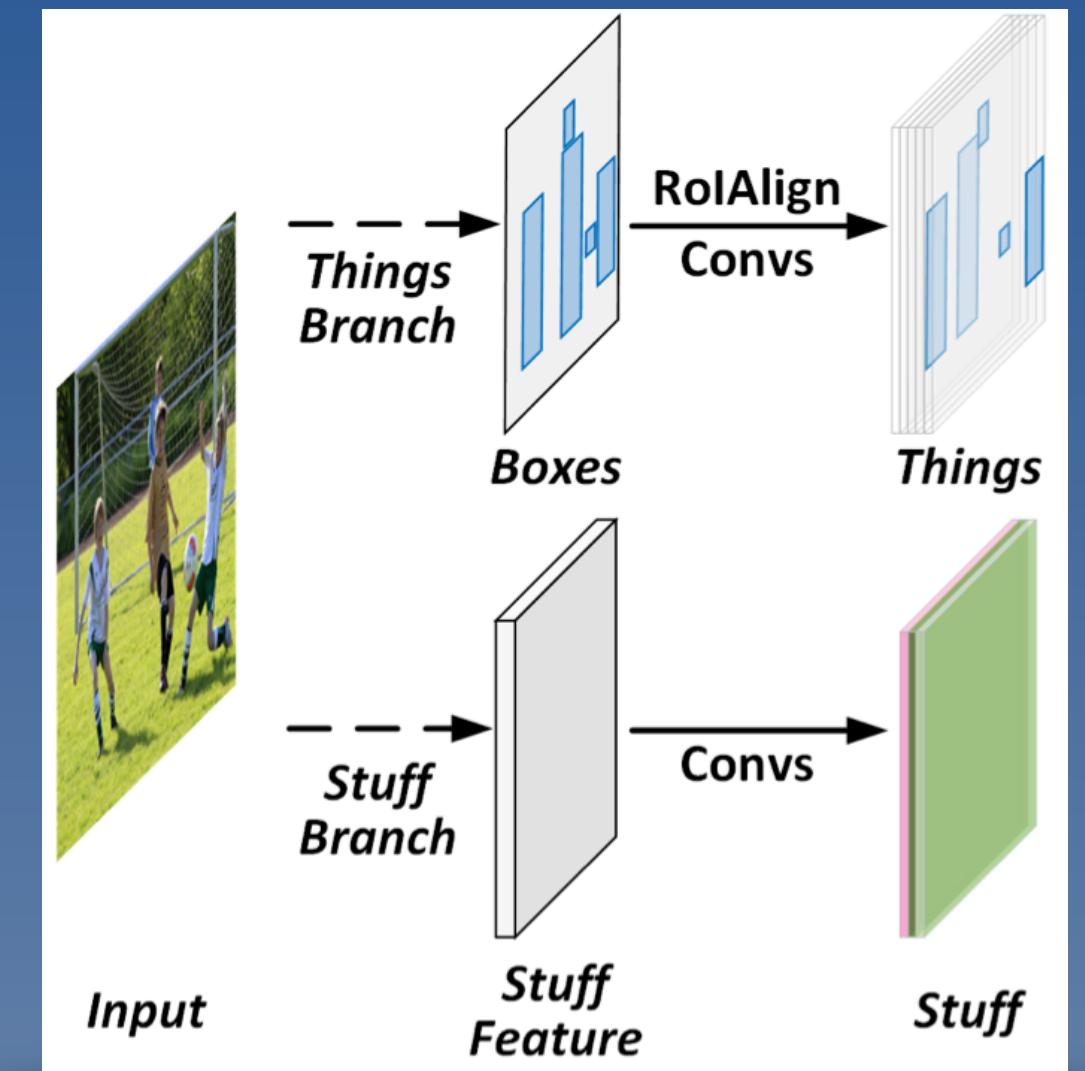
# Introduction

*Previous methods satisfy demands separately*

- *Instance-awareness* for things: box-based [2, 3, 4] or box-free [5, 6] branch.
- *Semantic-consistency* for stuff: FCN-based branch.



Architecture of UPSNet [3].



*Separate representation.*

[2] Alexander Kirillov, Ross Girshick, Kaiming He, and Piotr Dollár. Panoptic feature pyramid networks. In *CVPR*, 2019.

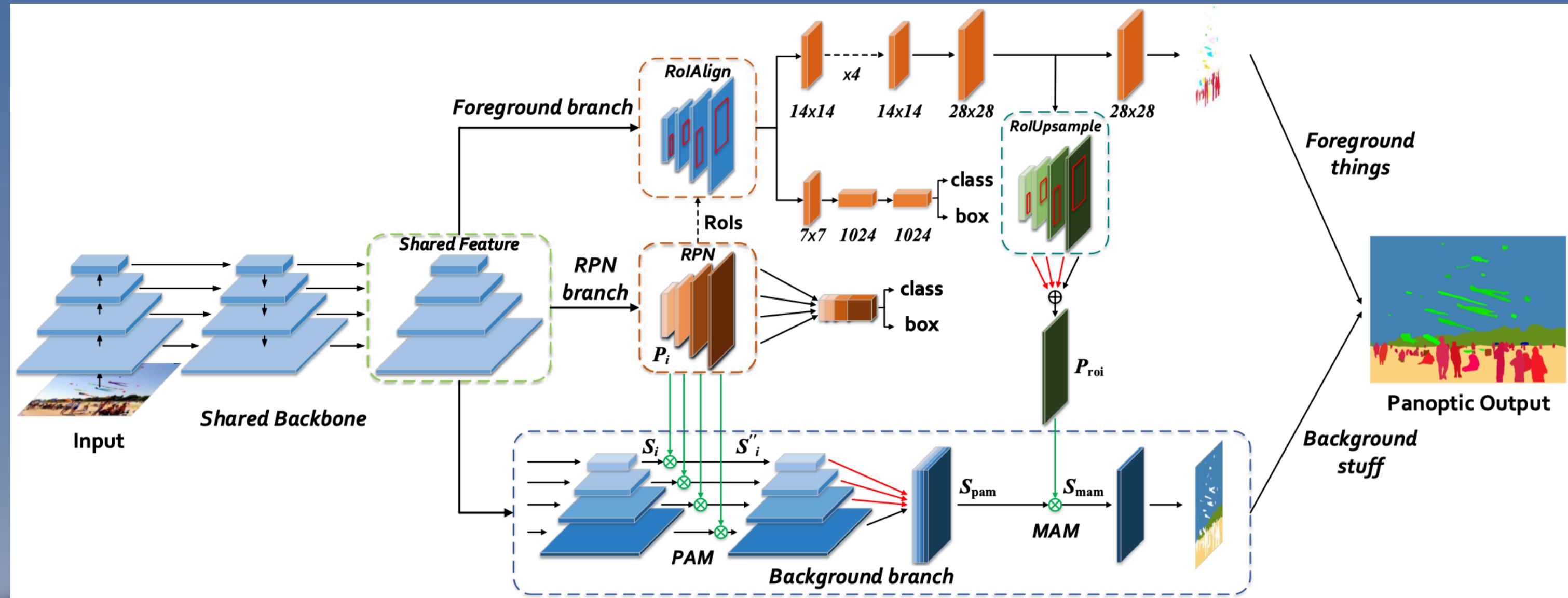
[3] Yuwen Xiong, Renjie Liao, Hengshuang Zhao, Rui Hu, Min Bai, Ersin Yumer, and Raquel Urtasun. Upsnet: A unified panoptic segmentation network. In *CVPR*, 2019.

[4] Yanwei Li, Xinze Chen, Zheng Zhu, Lingxi Xie, Guan Huang, Dalong Du, and Xingang Wang. Attention-guided unified network for panoptic segmentation. In *CVPR*, 2019.

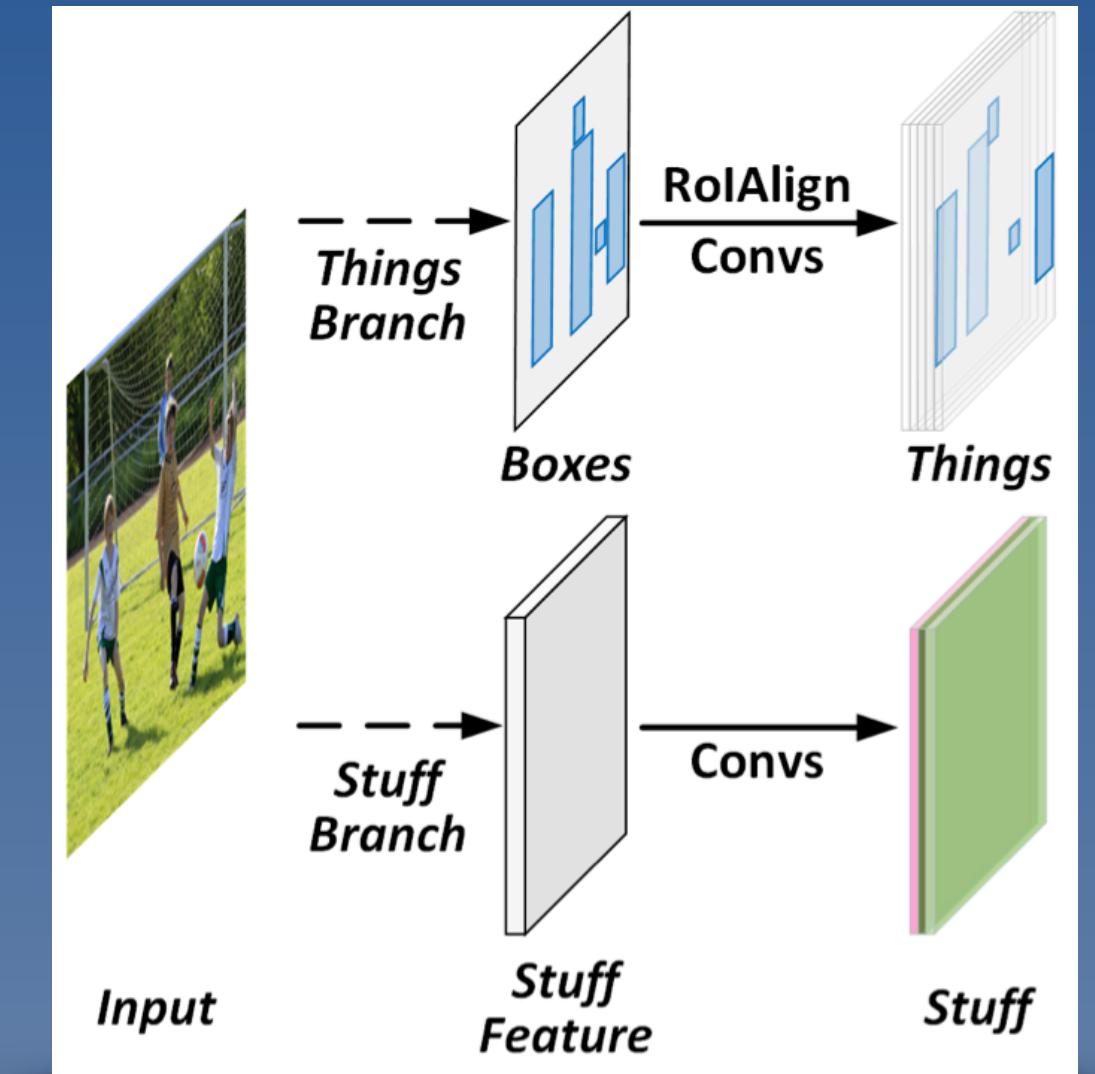
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Architecture of AUNet [4].



*Separate representation.*

[2] Alexander Kirillov, Ross Girshick, Kaiming He, and Piotr Dollár. Panoptic feature pyramid networks. In *CVPR*, 2019.

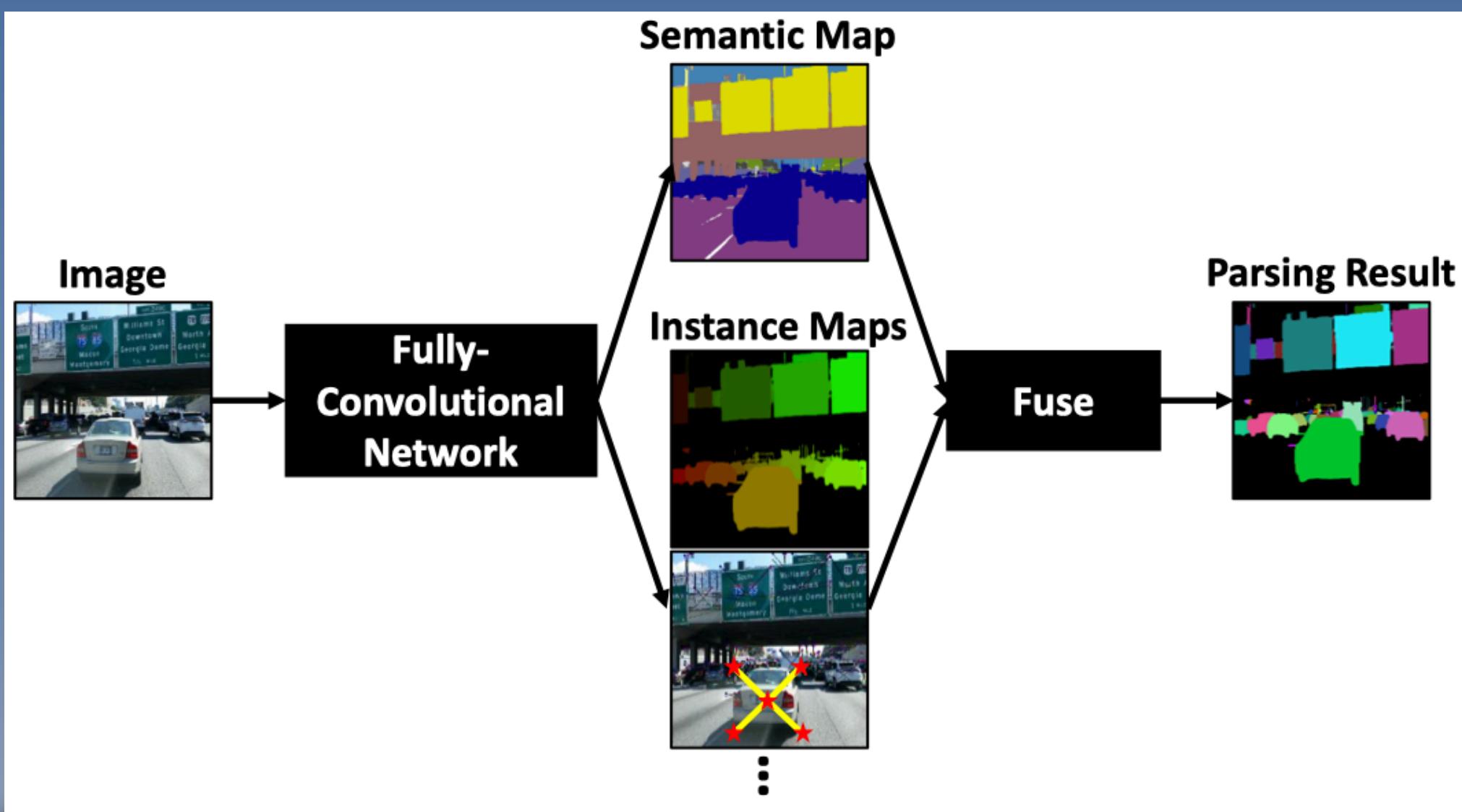
[3] Yuwen Xiong, Renjie Liao, Hengshuang Zhao, Rui Hu, Min Bai, Ersin Yumer, and Raquel Urtasun. Upsnet: A unified panoptic segmentation network. In *CVPR*, 2019.

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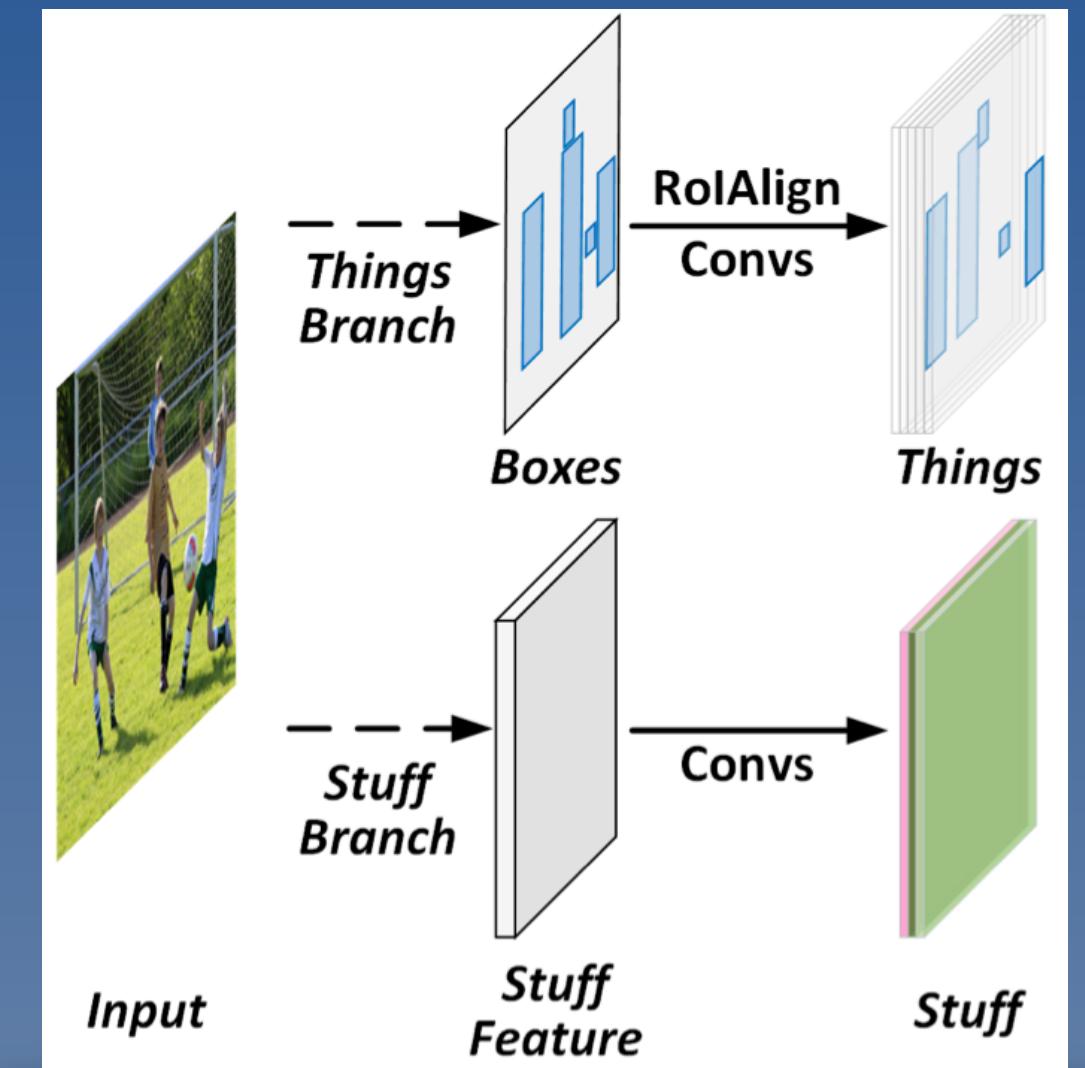
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*Pipeline of DeeperLab [5].*



*Separate representation.*

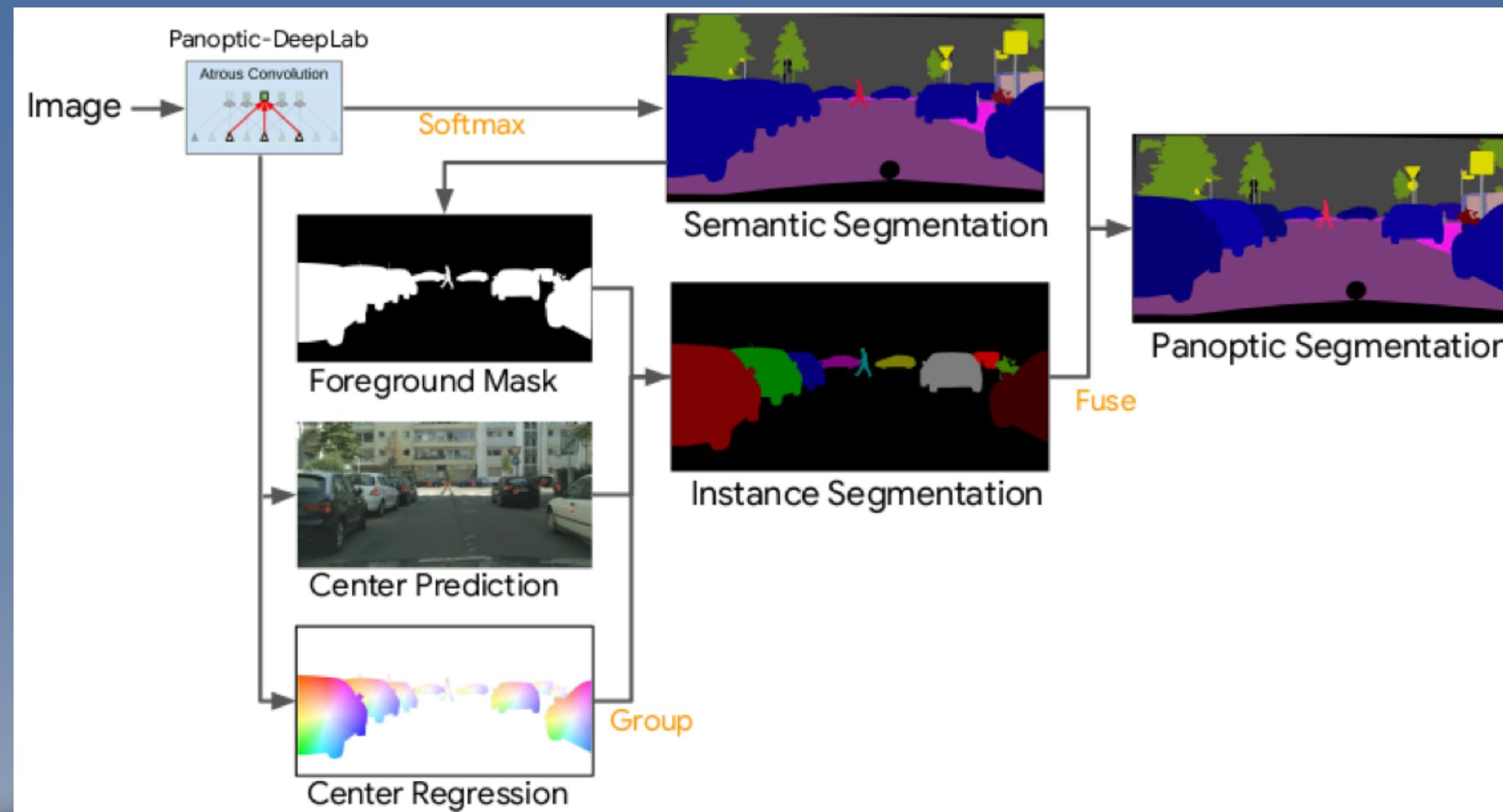
[5] Tien-Ju Yang, Maxwell D Collins, Yukun Zhu, Jyh-Jing Hwang, Ting Liu, Xiao Zhang, Vivienne Sze, George Papandreou, and Liang-Chieh Chen. Deeperlab: Single-shot image parser. *arXiv:1902.05093*, 2019.

[6] Bowen Cheng, Maxwell D Collins, Yukun Zhu, Ting Liu, Thomas S Huang, Hartwig Adam, and Liang-Chieh Chen. Panoptic-deeplab: A simple, strong, and fast baseline for bottom-up panoptic segmentation. In *CVPR*, 2020.

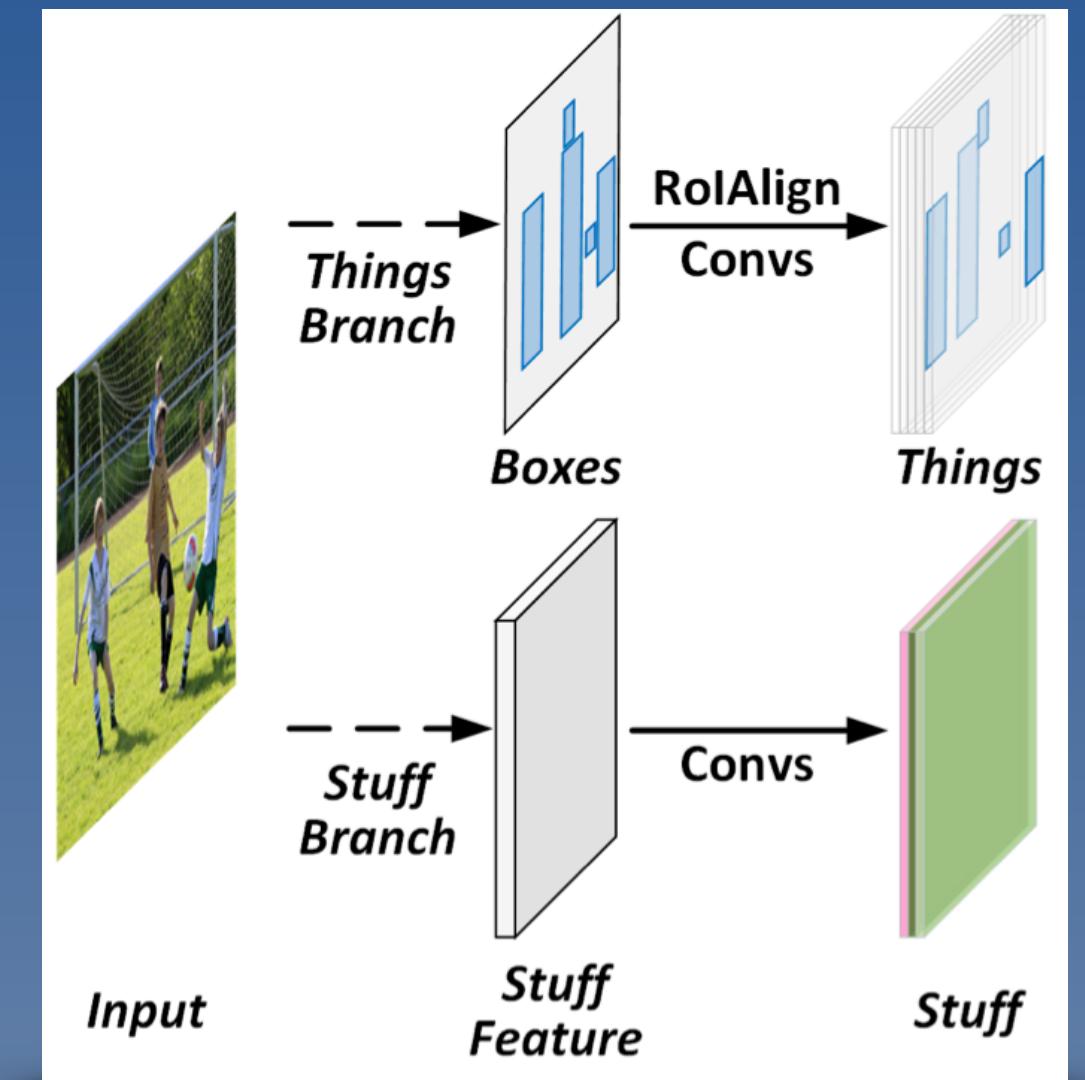
# Introduction

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- *Instance-awareness* for things: box-based [2, 3, 4] or box-free [5, 6] branch.
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*Pipeline of Panoptic-DeepLab [6].*



*Separate representation.*

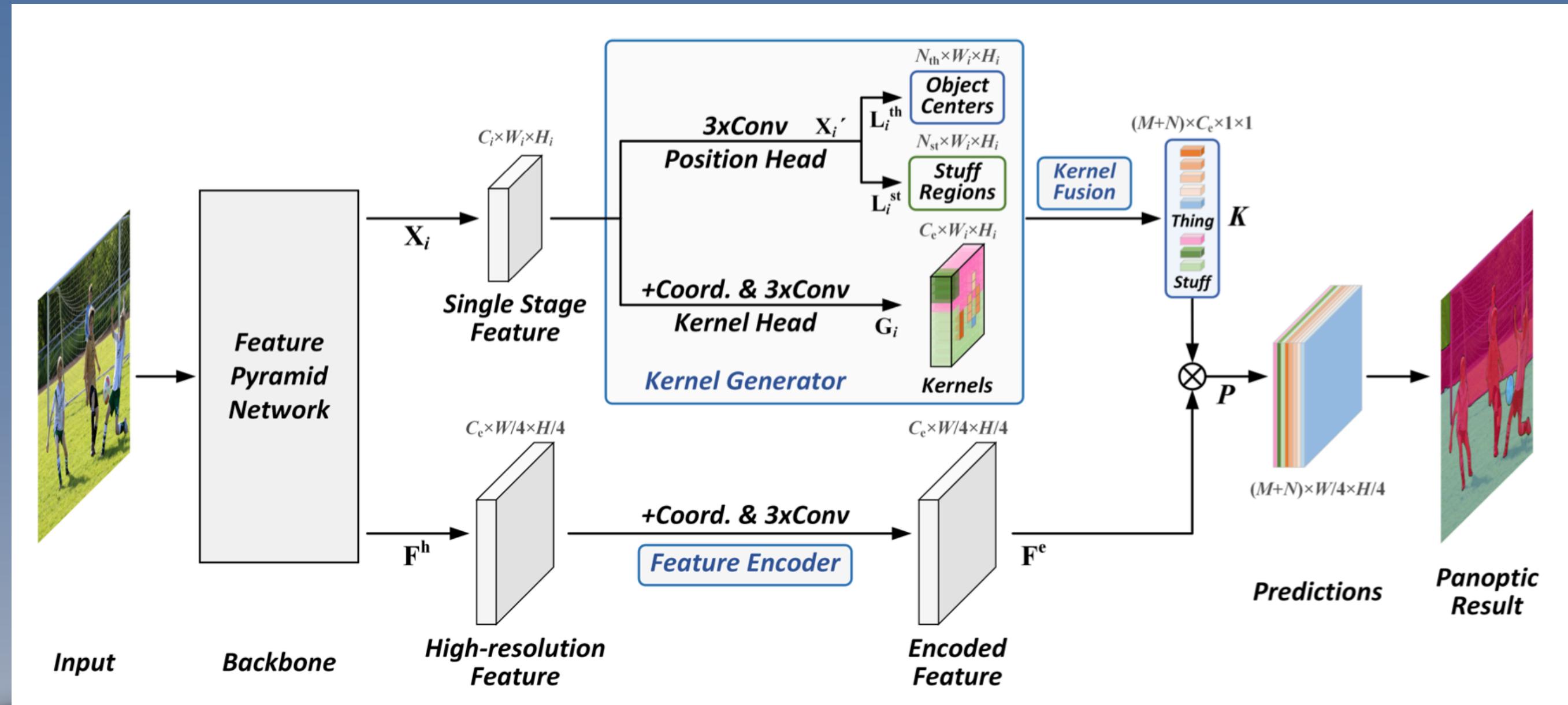
[5] Tien-Ju Yang, Maxwell D Collins, Yukun Zhu, Jyh-Jing Hwang, Ting Liu, Xiao Zhang, Vivienne Sze, George Papandreou, and Liang-Chieh Chen. Deeperlab: Single-shot image parser. *arXiv:1902.05093*, 2019.

[6] Bowen Cheng, Maxwell D Collins, Yukun Zhu, Ting Liu, Thomas S Huang, Hartwig Adam, and Liang-Chieh Chen. Panoptic-deeplab: A simple, strong, and fast baseline for bottom-up panoptic segmentation. In *CVPR*, 2020.

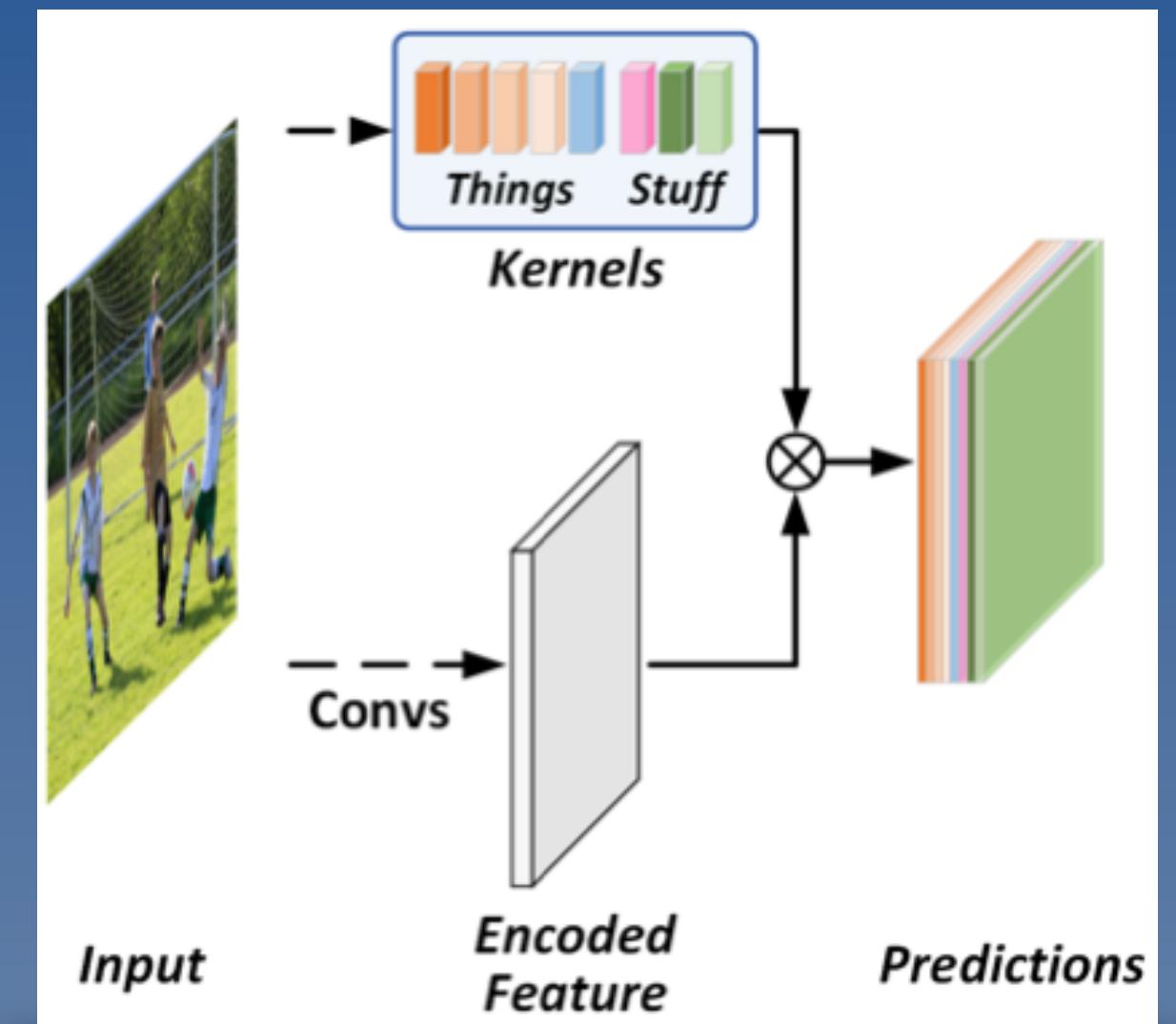
# Panoptic FCN

Panoptic FCN represent them uniformly

- It encodes each *instance* into a specific kernel and generates the prediction by convolutions directly.
- *Instance-awareness* for things: each *thing* has unique kernel.
- *Semantic-consistency* for stuff: identical stuff has same kernel.



Framework of Panoptic FCN [7].



Unified representation.

# Panoptic FCN

## Unified loss function in Panoptic FCN

- Loss function for position localization

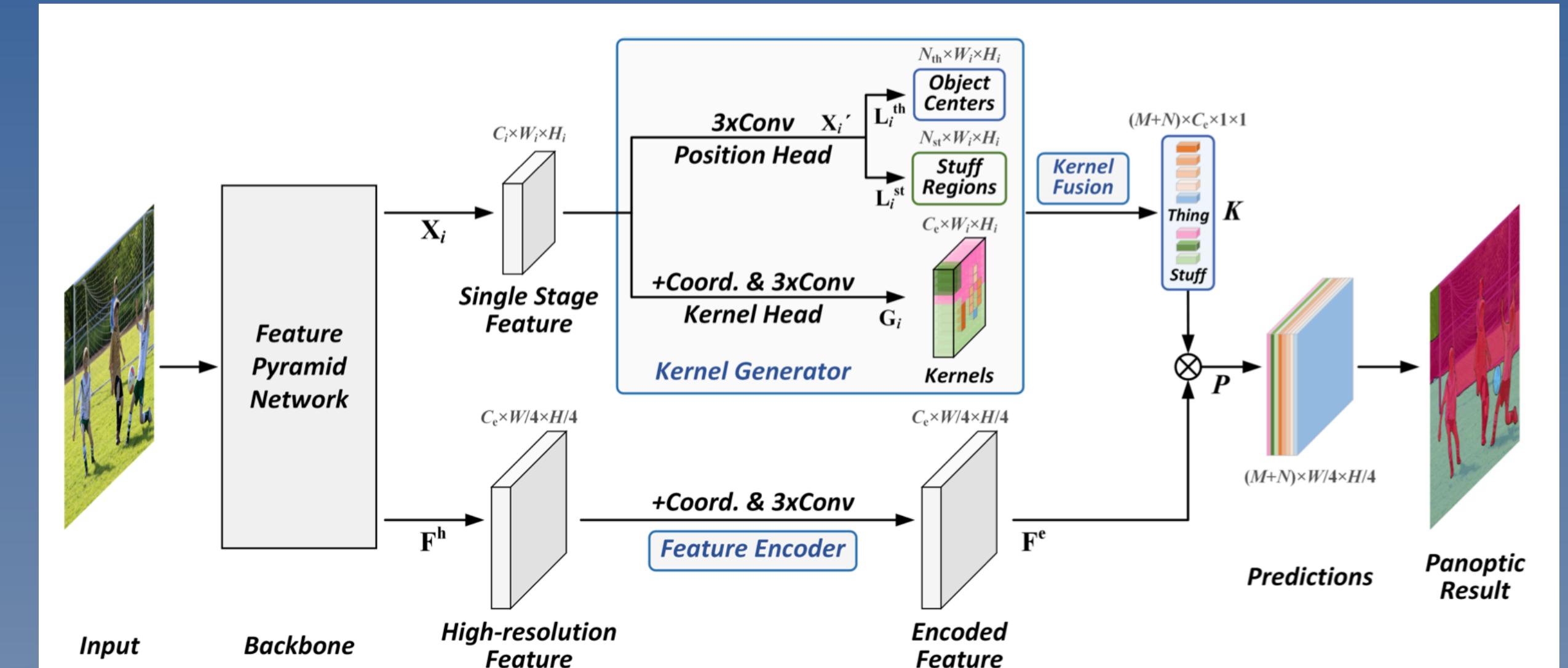
$$\mathcal{L}_{\text{pos}}^{\text{th}} = \sum_i \text{FL}(\mathbf{L}_i^{\text{th}}, \mathbf{Y}_i^{\text{th}}) / N_{\text{th}},$$

$$\mathcal{L}_{\text{pos}}^{\text{st}} = \sum_i \text{FL}(\mathbf{L}_i^{\text{st}}, \mathbf{Y}_i^{\text{st}}) / W_i H_i,$$

- Loss function for segmentation

$$\text{WDice}(\mathbf{P}_j, \mathbf{Y}_j^{\text{seg}}) = \sum_k w_k \text{Dice}(\mathbf{P}_{j,k}, \mathbf{Y}_{j,k}^{\text{seg}}),$$

$$\mathcal{L}_{\text{seg}} = \sum_j \text{WDice}(\mathbf{P}_j, \mathbf{Y}_j^{\text{seg}}) / (M + N),$$



Framework of Panoptic FCN [7].

# Results & Analysis

## Component-wise Analysis in Panoptic FCN

### Ablation studies on kernel generator and feature encoder.

Table 1. Comparisons among different settings of the kernel generator on the COCO *val* set. *deform* and *conv num* respectively denote deformable convolutions for position head and number of convolutions in both heads of the kernel generator.

<i>deform</i>	<i>conv num</i>	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>	AP	mIoU
✗	1	38.4	43.4	31.0	28.3	39.9
✗	2	38.9	44.1	31.1	28.9	40.1
✗	3	39.2	44.7	31.0	29.6	40.2
✗	4	39.2	44.9	30.8	29.4	39.9
✓	3	<b>39.9</b>	<b>45.0</b>	<b>32.4</b>	<b>29.9</b>	<b>41.2</b>

Table 2. Comparisons among different positional settings on the COCO *val* set. *coord<sub>w</sub>* and *coord<sub>f</sub>* denote combining coordinates for the kernel head, and feature encoder, respectively.

<i>coord<sub>w</sub></i>	<i>coord<sub>f</sub></i>	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>	AP	mIoU
✗	✗	39.9	45.0	32.4	29.9	41.2
✓	✗	39.9	45.0	32.2	30.0	41.1
✗	✓	40.2	45.3	32.5	30.4	41.6
✓	✓	<b>41.3</b>	<b>46.9</b>	<b>32.9</b>	<b>32.1</b>	<b>41.7</b>

Table 3. Comparisons among different similarity thresholds of kernel fusion on the COCO *val* set. *class-aware* denotes only merging kernel weights with the same predicted class *c*. And *thres* indicates the cosine similarity threshold *thres* for kernel fusion in Sec. 3.2.

<i>class-aware</i>	<i>thres</i>	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>	AP	mIoU
✓	0.80	39.7	44.3	32.9	29.9	41.7
✓	0.85	40.8	46.1	32.9	31.5	41.7
✓	0.90	<b>41.3</b>	46.9	<b>32.9</b>	<b>32.1</b>	<b>41.7</b>
✓	0.95	41.3	<b>47.0</b>	32.9	31.1	41.7
✗	0.90	41.2	46.7	32.9	30.9	41.7

Table 4. Comparisons among different channel numbers of the feature encoder on the COCO *val* set. *channel num* represents the channel number *C<sub>e</sub>* of the feature encoder.

<i>channel num</i>	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>	AP	mIoU
16	39.9	45.0	32.1	30.8	41.3
32	40.8	46.3	32.5	31.7	41.6
64	<b>41.3</b>	46.9	<b>32.9</b>	32.1	<b>41.7</b>
128	41.3	<b>47.0</b>	32.6	<b>32.6</b>	41.7

# Results & Analysis

## Component-wise Analysis in Panoptic FCN Ablation studies on loss function and feature encoder.

Table 5. Comparisons among different feature types for the feature encoder on the COCO *val* set. *feature type* denotes the method to generate high-resolution feature  $\mathbf{F}^h$  in Sec. 3.3.

<i>feature type</i>	PQ	$\text{PQ}^{\text{th}}$	$\text{PQ}^{\text{st}}$	AP	mIoU
FPN-P2	40.6	46.0	32.4	31.6	41.3
FPN-Summed	40.5	46.0	32.1	31.7	41.1
Semantic FPN [17]	<b>41.3</b>	<b>46.9</b>	<b>32.9</b>	<b>32.1</b>	<b>41.7</b>

Table 7. Comparisons among different training schedules on the COCO *val* set.  $1\times$ ,  $2\times$ , and  $3\times$  *schedule* denote the 90K, 180K, and 270K training iterations in Detectron2 [47], respectively.

<i>schedule</i>	PQ	$\text{PQ}^{\text{th}}$	$\text{PQ}^{\text{st}}$	AP	mIoU
$1\times$	41.3	46.9	32.9	32.1	41.7
$2\times$	43.2	48.8	34.7	34.3	43.4
$3\times$	<b>43.6</b>	<b>49.3</b>	<b>35.0</b>	<b>34.5</b>	<b>43.8</b>

Table 6. Comparisons among different settings of weighted dice loss on the COCO *val* set. *weighted* and *k* denote weighted dice loss and the number of sampled points in Sec. 3.4, respectively.

<i>weighted</i>	<i>k</i>	PQ	$\text{PQ}^{\text{th}}$	$\text{PQ}^{\text{st}}$	AP	mIoU
✗	-	40.2	45.5	32.4	31.0	41.3
✓	1	40.0	45.1	32.4	30.9	41.4
✓	3	41.0	46.4	32.7	31.6	41.4
✓	5	41.0	46.5	32.9	32.1	41.7
✓	7	<b>41.3</b>	<b>46.9</b>	<b>32.9</b>	<b>32.1</b>	41.7
✓	9	41.3	46.8	32.9	32.1	<b>41.8</b>

Table 8. Comparisons among different settings of the feature encoder on the COCO *val* set. *deform* and *channel num* represent deformable convolutions and the channel number  $C_e$ , respectively.

<i>deform</i>	<i>channel num</i>	PQ	$\text{PQ}^{\text{th}}$	$\text{PQ}^{\text{st}}$	AP	mIoU
✗	64	43.6	49.3	35.0	34.5	43.8
✓	256	<b>44.3</b>	<b>50.0</b>	<b>35.6</b>	<b>35.5</b>	<b>44.0</b>

# Results & Analysis

## Component-wise Analysis in Panoptic FCN Ablation studies on loss function and speed-accuracy.

gt position	gt class	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>	AP	mIoU
✗	✗	43.6	49.3	35.0	34.5	43.8
✓	✗	49.8	52.2	46.1	38.2	54.6
✓	✓	<b>65.9</b>	<b>64.1</b>	<b>68.7</b>	<b>45.5</b>	<b>86.6</b>
		+22.3	+14.8	+33.7	+11.0	+42.8

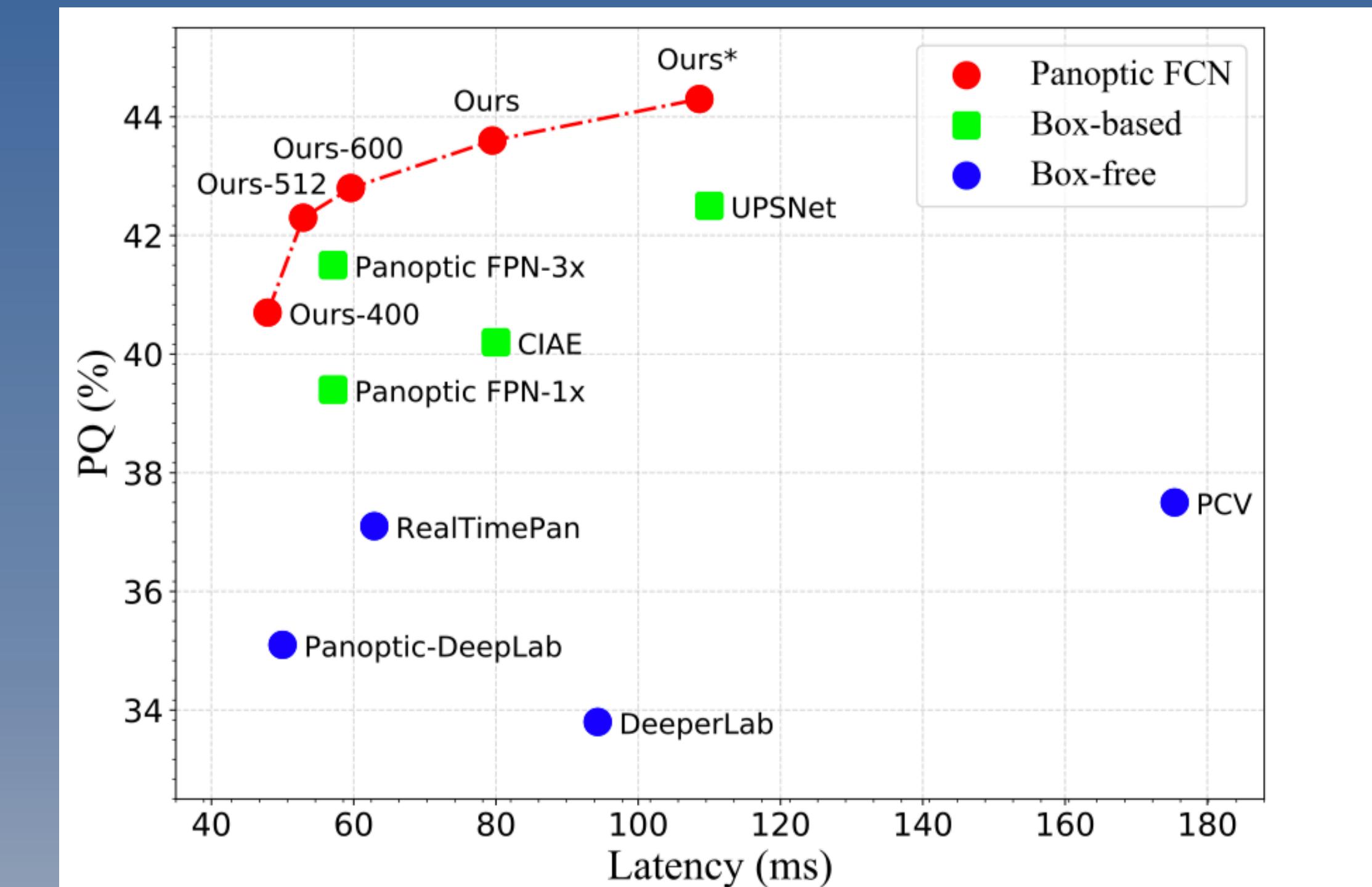


Figure 3. Speed-Accuracy trade-off curve on the COCO *val* set. All the results are compared with Res50 except DeeperLab [49] based on Xception-71 [7]. The latency is measured *end-to-end* from single input to panoptic result. Details are given in Table 10.

# Results & Analysis

## Results of Panoptic FCN It surpasses previous box-based and box-free methods with efficiency.

Table 10. Comparisons with previous methods on the COCO *val* set. Panoptic FCN-400, 512, and 600 denotes utilizing smaller input instead of the default setting. All of our results are achieved on the same device with single input and no flipping. FPS is measured *end-to-end* from single input to panoptic result with an average speed over 1,000 images, which could be further improved with more optimizations. The simple enhanced version is marked with \*. The model testing by ourselves according to released codes is denoted as †.

Method	Backbone	PQ	SQ	RQ	PQ <sup>th</sup>	SQ <sup>th</sup>	RQ <sup>th</sup>	PQ <sup>st</sup>	SQ <sup>st</sup>	RQ <sup>st</sup>	Device	FPS
<i>box-based</i>												
Panoptic FPN [17]	Res50-FPN	39.0	-	-	45.9	-	-	28.7	-	-	-	-
Panoptic FPN <sup>†</sup> -1×	Res50-FPN	39.4	77.8	48.3	45.9	80.9	55.3	29.6	73.3	37.7	V100	17.5
Panoptic FPN <sup>†</sup> -3×	Res50-FPN	41.5	79.1	50.5	48.3	82.2	57.9	31.2	74.4	39.5	V100	17.5
AUNet [24]	Res50-FPN	39.6	-	-	49.1	-	-	25.2	-	-	-	-
CIAE [11]	Res50-FPN	40.2	-	-	45.3	-	-	32.3	-	-	2080Ti	12.5
UPSNet <sup>†</sup> [48]	Res50-FPN	42.5	78.0	52.5	48.6	79.4	<b>59.6</b>	33.4	75.9	41.7	V100	9.1
Unifying [23]	Res50-FPN	43.4	79.6	53.0	48.6	-	-	35.5	-	-	-	-
<i>box-free</i>												
DeeperLab [49]	Xception-71	33.8	-	-	-	-	-	-	-	-	V100	10.6
Panoptic-DeepLab [6]	Res50	35.1	-	-	-	-	-	-	-	-	V100	20.0
AdaptIS [40]	Res50	35.9	-	-	40.3	-	-	29.3	-	-	-	-
RealTimePan [14]	Res50-FPN	37.1	-	-	41.0	-	-	31.3	-	-	V100	15.9
PCV [42]	Res50-FPN	37.5	77.7	47.2	40.0	78.4	50.0	33.7	76.5	42.9	1080Ti	5.7
SOLO V2 [45]	Res50-FPN	42.1	-	-	49.6	-	-	30.7	-	-	-	-
Panoptic FCN-400	Res50-FPN	40.7	80.5	49.3	44.9	82.0	54.0	34.3	78.1	42.1	V100	<b>20.9</b>
Panoptic FCN-512	Res50-FPN	42.3	80.9	51.2	47.4	82.1	56.9	34.7	79.1	42.7	V100	18.9
Panoptic FCN-600	Res50-FPN	42.8	80.6	51.6	47.9	82.6	57.2	35.1	77.4	43.1	V100	16.8
Panoptic FCN	Res50-FPN	43.6	80.6	52.6	49.3	82.6	58.9	35.0	<b>77.6</b>	42.9	V100	12.5
Panoptic FCN*	Res50-FPN	<b>44.3</b>	<b>80.7</b>	<b>53.0</b>	<b>50.0</b>	<b>83.4</b>	59.3	<b>35.6</b>	76.7	<b>43.5</b>	V100	9.2

# Results & Analysis

## Results of Panoptic FCN It surpasses previous box-based and box-free methods with efficiency.

Table 11. Experiments on the COCO *test-dev* set. All of our results are achieved with single scale input and no flipping. The simple enhanced version and *val* set for training are marked with \* and ‡.

Method	Backbone	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>
<i>box-based</i>				
Panoptic FPN [17]	Res101-FPN	40.9	48.3	29.7
CIAE [11]	DCN101-FPN	44.5	49.7	36.8
AUNet [24]	ResNeXt152-FPN	46.5	<b>55.8</b>	32.5
UPSNet [48]	DCN101-FPN	46.6	53.2	36.7
Unifying‡ [23]	DCN101-FPN	47.2	53.5	37.7
<i>box-free</i>				
DeeperLab [49]	Xception-71	34.3	37.5	29.6
SSAP [10]	Res101-FPN	36.9	40.1	32.0
PCV [42]	Res50-FPN	37.7	40.7	33.1
Panoptic-DeepLab [6]	Xception-71	39.7	43.9	33.2
AdaptIS [40]	ResNeXt-101	42.8	53.2	36.7
Axial-DeepLab [43]	Axial-ResNet-L	43.6	48.9	35.6
Panoptic FCN	Res101-FPN	45.5	51.4	36.4
Panoptic FCN	DCN101-FPN	47.0	53.0	37.8
Panoptic FCN*	DCN101-FPN	47.1	53.2	37.8
Panoptic FCN*‡	DCN101-FPN	<b>47.5</b>	53.7	<b>38.2</b>

Table 12. Experiments on the Cityscape *val* set. All of our results are achieved with single scale input and no flipping. The simple enhanced version is marked with \*.

Method	Backbone	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>
<i>box-based</i>				
Panoptic FPN [17]	Res101-FPN	58.1	52.0	62.5
AUNet [24]	Res101-FPN	59.0	54.8	62.1
UPSNet [48]	Res50-FPN	59.3	54.6	62.7
Seamless [36]	Res50-FPN	60.2	55.6	63.6
Unifying [23]	Res50-FPN	61.4	54.7	66.3
<i>box-free</i>				
PCV [42]	Res50-FPN	54.2	47.8	58.9
DeeperLab [49]	Xception-71	56.5	-	-
SSAP [10]	Res50-FPN	58.4	50.6	-
AdaptIS [40]	Res50	59.0	<b>55.8</b>	61.3
Panoptic-DeepLab [6]	Res50	59.7	-	-
Panoptic FCN	Res50-FPN	59.6	52.1	65.1
Panoptic FCN*	Res50-FPN	<b>61.4</b>	54.8	<b>66.6</b>

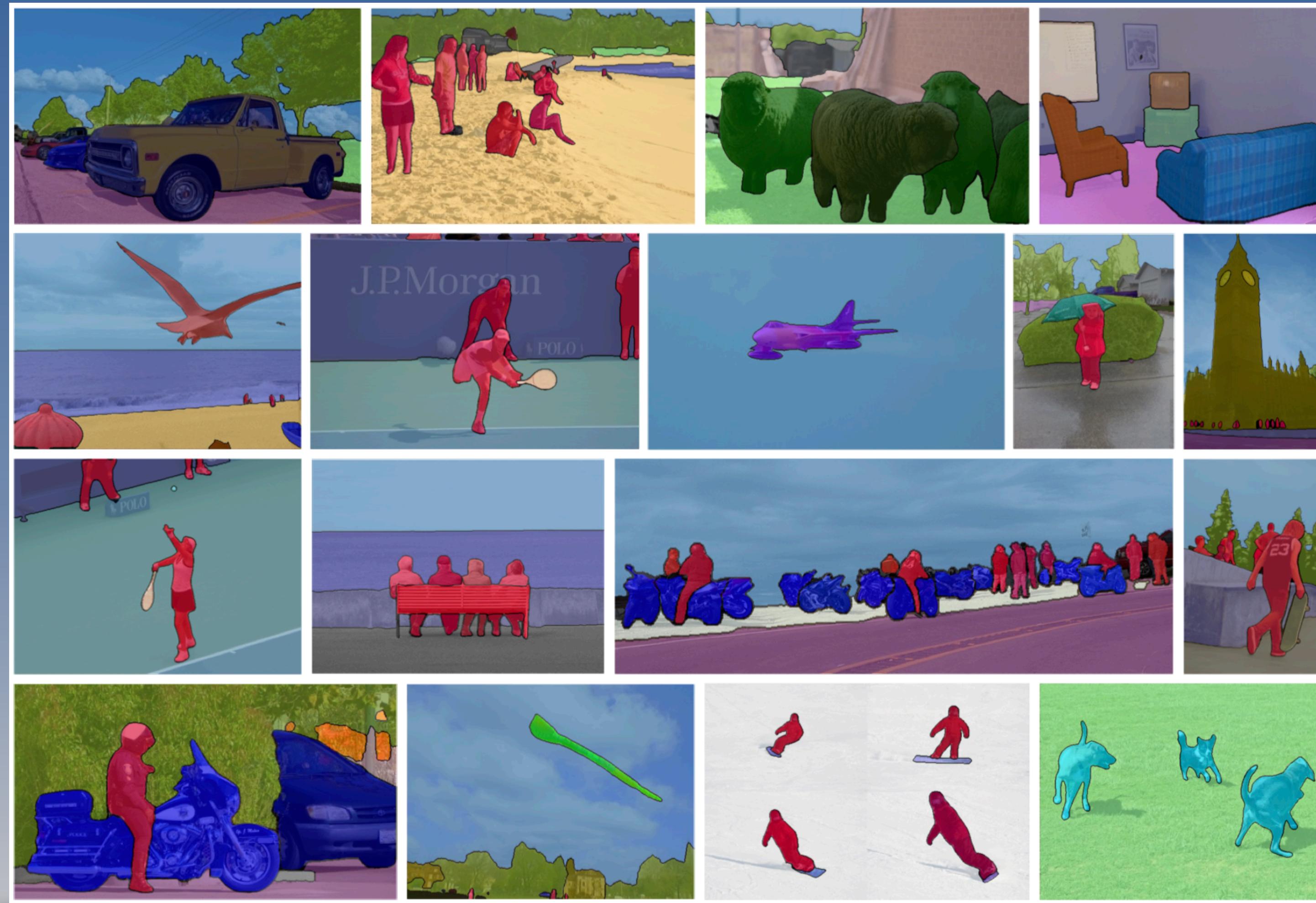
Table 13. Experiments on the Mapillary Vistas *val* set. All of our results are achieved with single scale input and no flipping. The simple enhanced version is marked with \*.

Method	Backbone	PQ	PQ <sup>th</sup>	PQ <sup>st</sup>
<i>box-based</i>				
TASCNet [21]	Res50-FPN	32.6	31.1	34.4
Seamless [36]	Res50-FPN	36.2	<b>33.6</b>	40.0
<i>box-free</i>				
DeeperLab [49]	Xception-71	32.0	-	-
AdaptIS [40]	Res50	32.0	26.6	39.1
Panoptic-DeepLab [6]	Res50	33.3	-	-
Panoptic FCN	Res50-FPN	34.8	30.6	40.5
Panoptic FCN*	Res50-FPN	<b>36.9</b>	32.9	<b>42.3</b>

# Results & Analysis

## Visualization of Panoptic FCN

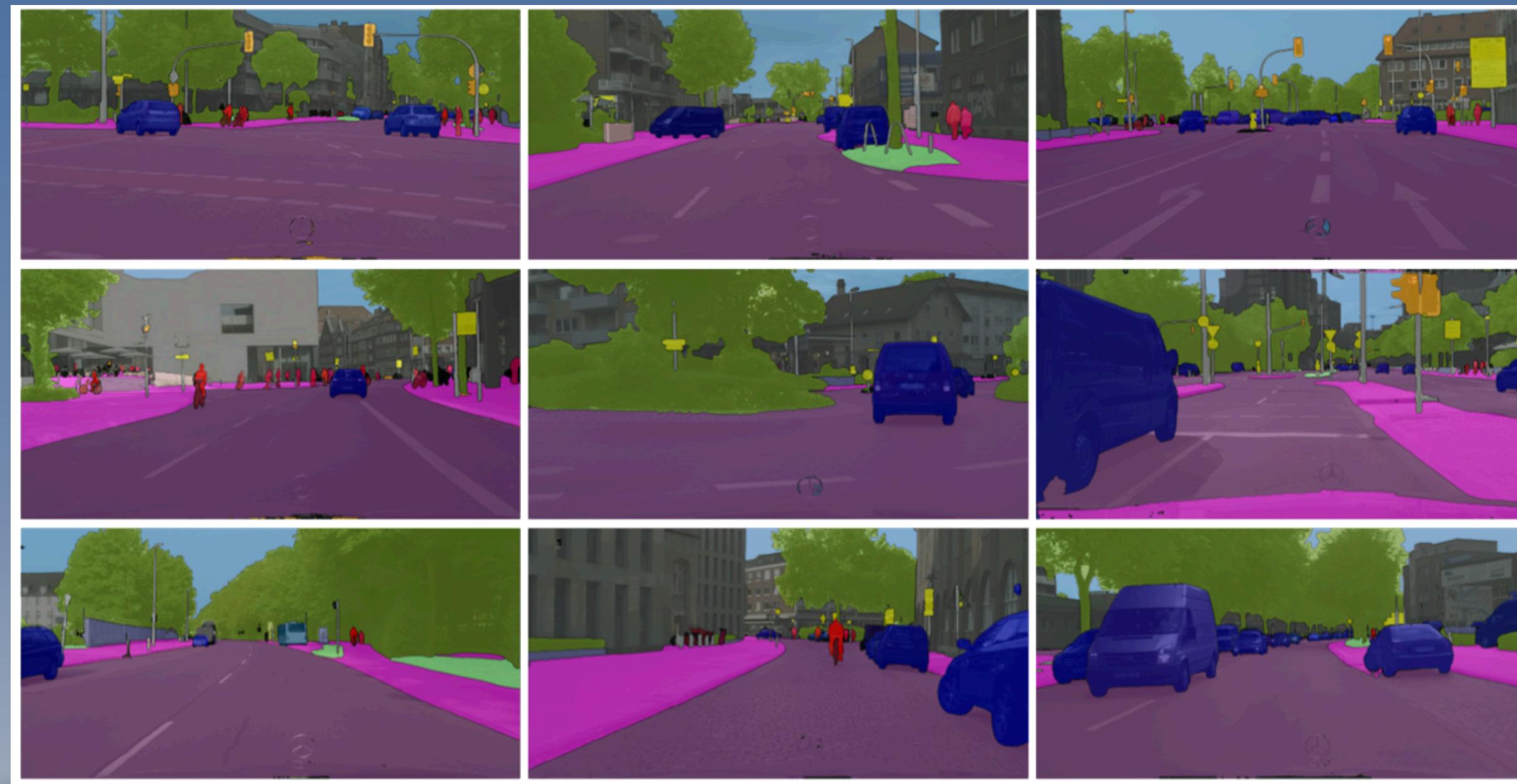
It achieve fine results on common context and traffic-related scenarios.



# Results & Analysis

## Visualization of Panoptic FCN

It achieve fine results on common context and traffic-related scenarios.



# Thanks

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