# Weighted Parity-Check Codes for Channels with State and Asymmetric Channels

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 Background: Find practical construction for the Gelfand-Pinsker setting with cost constraint and for the asymmetric channels

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  - Practical
  - Applicable to asymmetric channels (unlike Barron et al. [2003])
  - Having error performance as good as (and sometimes better than) the construction in Barron et al. [2003]

# Query Functions

- Let  $\mathbf{H} \in \mathbb{F}_2^{n \times n}$  be a full-rank matrix, called the *full parity check matrix* 
  - H uniformly chosen random full-rank matrix
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- For a bias vector  $\mathbf{q} = [q_1, \dots, q_n] \in [0, 1]^n$ , define the  $\mathbf{q}$ -weight of a vector  $\mathbf{u} \in \mathbb{F}_2^n$  as

$$w_{\mathbf{q}}(\mathbf{u}) := \prod_{i=1}^n q_i^{u_i} (1-q_i)^{1-u_i} = P_{\mathsf{x}_i \sim \mathrm{Bern}(q_i)}(\mathbf{x} = \mathbf{u})$$

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#### **Definition**

Given the bias vectors  $\mathbf{p}, \mathbf{q} \in [0,1]^n$  (we call  $\mathbf{p}$  the *codeword bias*, and  $\mathbf{q}$  the *parity bias*), the *query function* with respect to  $\mathbf{H}$  is given by

$$f_{\mathsf{H}}(\mathsf{p},\mathsf{q}) := \operatorname{argmax}_{\mathsf{x} \in \mathbb{F}_2^n} w_{\mathsf{p}}(\mathsf{x}) w_{\mathsf{q}}(\mathsf{xH}^T)$$
 (1)

# Weighted Parity-Check Codes (WPC)

#### Definition: Encoder

Given the encoder codeword bias function  $\mathbf{p}_e : \mathbb{F}_2^k \to [0,1]^n$ , which maps a message  $\mathbf{m} \in \mathbb{F}_2^k$  (and other information available at the encoder) to a bias vector  $\mathbf{p}_e(\mathbf{m})$ , and the encoder parity bias function  $\mathbf{q}_e : \mathbb{F}_2^k \to [0,1]^n$ . The encoding function is

$$\mathbf{m} \mapsto \mathbf{x} = f_{\mathsf{H}} \left( \mathbf{p}_{\mathsf{e}}(\mathbf{m}), \, \mathbf{q}_{\mathsf{e}}(\mathbf{m}) \right)$$
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#### Definition: Decoder

Similarly, given the decoder codeword and parity bias functions  $\mathbf{p}_d, \mathbf{q}_d : \mathbb{F}_2^n \to [0,1]^n$ . For a corrupted version  $\mathbf{y}$  of  $\mathbf{x}$ , the decoding function is

$$\mathbf{y} \mapsto \hat{\mathbf{m}} = \left| (\hat{\mathbf{x}} \mathbf{H}^T)_1, \dots, (\hat{\mathbf{x}} \mathbf{H}^T)_k \right|, \tag{3}$$

where

$$\hat{\mathbf{x}} := f_{\mathsf{H}} \left( \mathbf{p}_d(\mathbf{y}), \, \mathbf{q}_d(\mathbf{y}) \right) \tag{4}$$

# Recovering Conventional Linear Codes by WPC

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  $\mathbf{q}_e(\mathbf{m}) = [\mathbf{m}, \mathbf{0}^{n-k}],$   $\mathbf{p}_d(\mathbf{y}) = \beta \mathbf{1}^n + (1 - 2\beta)\mathbf{y},$   $\mathbf{q}_d(\mathbf{y}) = \frac{1}{2} \mathbf{1}^n,$ 

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### Recovering Conventional Linear Codes by WPC

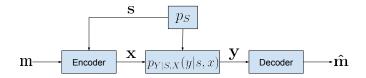
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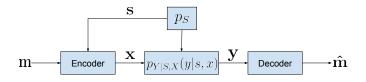
and substitute into Equations (2) and (4)

• Note that  $w_{\mathbf{p}_d(\mathbf{y})}(\mathbf{x}) = P(\mathbf{x}|\mathbf{y})$  is the posterior distribution of  $\mathbf{x}$ 

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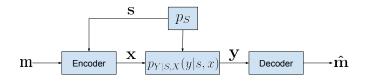


- We construct the weighted parity-check codes with state as follows
- Encoder: after observing m and s, takes

$$\mathbf{p}_e(\mathbf{m},\mathbf{s}) = [p_e(s_1),\ldots,p_e(s_n)], \quad \mathbf{q}_e(\mathbf{m},\mathbf{s}) = [\mathbf{m},\mathbf{q}], \quad (5)$$

where we choose  $p_e(s) = P_{X|S}(1|s)$  so  ${\bf x}$  approximately follows  $P_{X|S}$ 

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• Decoder: after observing y, takes

$$\mathbf{p}_d(\mathbf{y}) = [p_d(y_1), \dots, p_d(y_n)], \quad \mathbf{q}_d(\mathbf{y}) = [\frac{1}{2}\mathbf{1}^k, \mathbf{q}], \tag{6}$$

and outputs  $\hat{\mathbf{m}} = [(\hat{\mathbf{x}}\mathbf{H}^T)_1, \dots, (\hat{\mathbf{x}}\mathbf{H}^T)_k]$ , where  $p_d(y) = P_{X \mid Y}(1 \mid y)$ 

We first state our main result as follows:

#### Theorem 1

• Assume  $\mathbf{q} \sim P_Q$  i.i.d., where  $P_Q$  is a discrete distribution over [0,1] with finite support satisfying

$$\mathbf{E}[H_b(Q)] = \frac{1 - H(X|S)}{1 - R},\tag{7}$$

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- Proof uses Sanov's theorem and robust typicality

• To achieve capacity, we need  $\mathbf{E}[H_b(Q)] = \frac{1 - H(X|S)}{1 - R}$ 

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- (Linear) Take  $P_Q$  to be the uniform distribution  $\mathrm{Unif}[0,1]$ 
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  - $\mathbf{E}[H_b(Q)] = \frac{1 H(X|S)}{1 R}$  may not hold, not capacity achieving
- (Threshold linear) Construct  $P_Q$  using the cdf

$$F_{Q}(t) := \begin{cases} 0 & \text{if } t < 0 \\ \max\{\theta/2, 0\} & \text{if } 0 \le t < |\theta|/2 \\ t & \text{if } |\theta|/2 \le t < 1 - |\theta|/2 \\ 1 - \max\{\theta/2, 0\} & \text{if } 1 - |\theta|/2 \le t < 1 \\ 1 & \text{if } t \ge 1 \end{cases}$$
 (8)

where  $\theta \in [-1,1]$  is chosen s.t.  $\mathbf{E}[H_b(Q)] = \frac{1-H(X|S)}{1-R}$ 

• Combines the linear method for t close to 1/2, and the threshold method for smaller and larger t's

### Simulation Result

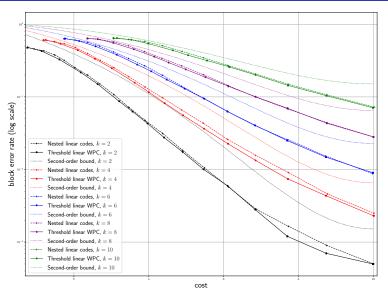


Figure: Performance evaluation with  $n=20, \beta=0.05$ 

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- Simulation results show that WPC achieves a smaller error probability compared to nested linear codes
- In the full paper [Ling et al., 2022], we show that our weighted construction also applies to the Wyner-Ziv setting [Wyner and Ziv, 1976]
- The code can be made more practical by considering a sparse parity-check matrix, though this is left for future work

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