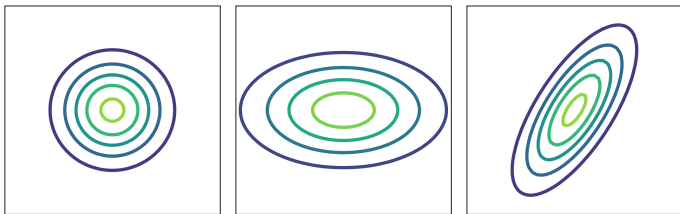


Gaussian Mixture Models

The Gaussian distribution re-visited

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu)^2\right)$$

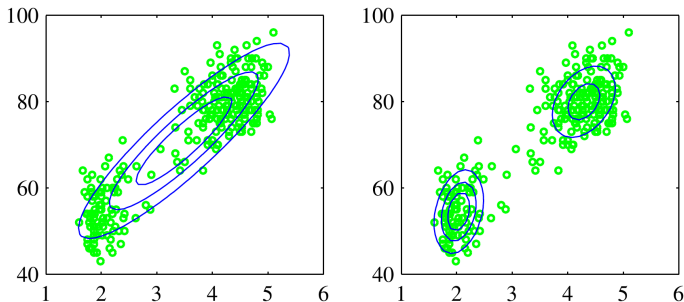
$$\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$$



$$\boldsymbol{\Sigma} = \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix} \quad \boldsymbol{\Sigma} = \begin{pmatrix} \sigma_{11}^2 & 0 \\ 0 & \sigma_{22}^2 \end{pmatrix} \quad \boldsymbol{\Sigma} = \begin{pmatrix} \sigma_{11}^2 & \sigma_{12}^2 \\ \sigma_{21}^2 & \sigma_{22}^2 \end{pmatrix}$$

“Downside” of Gaussians

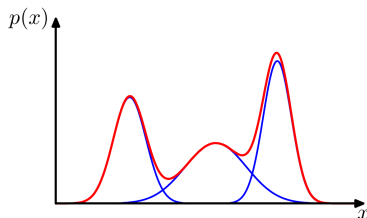
- How to model real-world data?



- What if we could have more than one Gaussian?

Gaussian mixtures

- **Idea:** Create mixture distributions
- Superposition of K Gaussians

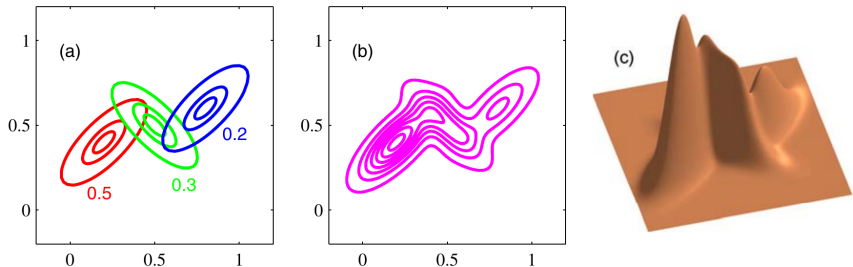


$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x} | \mu_k, \Sigma_k)$$

- Mixing coefficients $0 \leq \pi_k \leq 1$

$$\sum_{k=1}^K \pi_k = 1$$

Example: Mixture of 3 Gaussians



Properties of GMMs

- Marginal density

$$p(\mathbf{x}) = \sum_{k=1}^K p(k)p(\mathbf{x}|k)$$

- responsibilities (posterior prob.) $\gamma_k(\mathbf{x}) = p(k|\mathbf{x})$

$$\begin{aligned}\gamma_k(\mathbf{x}) &= \frac{p(k)p(\mathbf{x}|k)}{\sum_m p(m)p(\mathbf{x}|m)} \\ &= \frac{\pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_m \pi_m \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m)}\end{aligned}$$

GMM Maximum Likelihood Estimation

- Recall the likelihood function

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

- How to find parameters $\boldsymbol{\pi} = \{\pi_1, \dots, \pi_K\}$,
 $\boldsymbol{\mu} = \{\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K\}$ and $\boldsymbol{\Sigma} = \{\boldsymbol{\Sigma}_1, \dots, \boldsymbol{\Sigma}_K\}$?

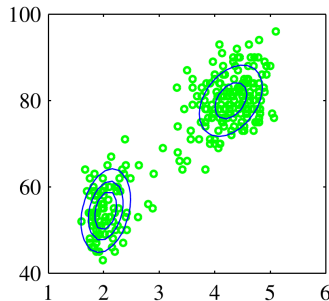
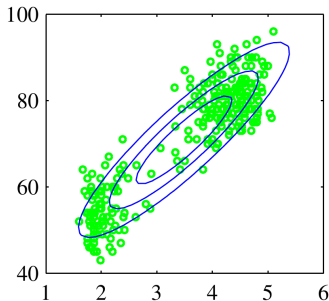
$$\ln p(\mathbf{X} | \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right)$$

Latent variable models

- Some models have latent (hidden) variables never observed in training data
- Assume that observed variables arise from a hidden common “cause”
- + fewer parameters
- harder to fit
- + compute a compressed representation of the data (bottleneck)

Latent variable: cluster label

- How to model real-world data?



EM for Gaussian mixtures

Recall the log-likelihood function

$$\mathcal{L} = \ln p(\mathbf{X}|\pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \right)$$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{1}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial \left(\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m) \right)}{\partial \mu_m}$$

$$\text{Trick: } \partial \ln x = \frac{1}{x} \Rightarrow 1 = x \partial \ln x$$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial (\ln(\pi_k) + \ln(\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)))}{\partial \mu_k}$$

EM for Gaussian mixtures

Recall the log-likelihood function

$$\mathcal{L} = \ln p(\mathbf{X}|\pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \right)$$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{1}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial \left(\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m) \right)}{\partial \mu_m}$$

Trick: $\partial \ln x = \frac{1}{x} \Rightarrow 1 = x \partial \ln x$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial (\ln(\pi_k) + \ln(\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)))}{\partial \mu_k}$$

EM for Gaussian mixtures

Recall the log-likelihood function

$$\mathcal{L} = \ln p(\mathbf{X}|\pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \right)$$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{1}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial \left(\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m) \right)}{\partial \mu_m}$$

Trick: $\partial \ln x = \frac{1}{x} \Rightarrow 1 = x \partial \ln x$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial (\ln(\pi_k) + \ln(\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)))}{\partial \mu_k}$$

EM for Gaussian mixtures

Recall the log-likelihood function

$$\mathcal{L} = \ln p(\mathbf{X}|\pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \right)$$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{1}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial \left(\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m) \right)}{\partial \mu_m}$$

Trick: $\partial \ln x = \frac{1}{x} \Rightarrow 1 = x \partial \ln x$

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \frac{\partial (\ln(\pi_k) + \ln(\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)))}{\partial \mu_k}$$

Derivation for mean μ_k

$$\frac{\mathcal{L}}{\partial \mu_k} = \sum_{n=1}^N \underbrace{\left[\frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{m=1}^K \pi_m \mathcal{N}(\mathbf{x}_n | \mu_m, \Sigma_m)} \right]}_{\text{posterior prob. } \gamma_k(\mathbf{x})} \frac{\partial (\ln(\pi_k) + \ln(\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)))}{\partial \mu_k}$$

$$\mathcal{N}(\mathbf{x} | \mu, \Sigma) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp \left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right)$$

$$\frac{\partial \ln(\mathcal{N}(\mathbf{x} | \mu, \Sigma))}{\partial \mu} = -\frac{1}{2} \left(\Sigma^{-1} + (\Sigma^{-1})^T \right) (\mathbf{x} - \mu) = -\Sigma^{-1} (\mathbf{x} - \mu)$$

$$\frac{\mathcal{L}}{\partial \mu_k} = - \sum_{n=1}^N \gamma_k(\mathbf{x}) \Sigma_k^{-1} (\mathbf{x} - \mu_k)$$

Derivation for mean μ_k

$$\frac{\mathcal{L}}{\partial \mu_k} = - \sum_{n=1}^N \gamma_k(\mathbf{x}) \Sigma_k^{-1} (\mathbf{x} - \mu_k)$$

$$0 \stackrel{!}{=} - \sum_{n=1}^N \gamma_k(\mathbf{x}) (\mathbf{x} - \mu_k)$$

$$\mu_k \sum_{n=1}^N \gamma_k(\mathbf{x}) = \sum_{n=1}^N \gamma_k(\mathbf{x}) \mathbf{x}_n$$

$$\mu_k = \frac{\sum_{n=1}^N \gamma_k(\mathbf{x}) \mathbf{x}_n}{\sum_{n=1}^N \gamma_k(\mathbf{x})}$$